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Research article Singular elliptic equations with directional diffusion[†]

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Abstract: We investigate conditions for the existence and uniqueness of viscosity solutions of the Dirichlet problem for a degenerate elliptic equation describing a stationary diffusion, which may take place in a partial number of spatial directions, with a possibly singular reaction term.

Keywords: degenerate elliptic operators; singular equations; Dirichlet problem; viscosity solutions

To Italo with great esteem and friendship.

1. Introduction and main results

In this paper we are interested to the Dirichlet problem

$$\begin{cases} \mathcal{D}_k(D^2u) + f(u) = 0 & \text{in } \Omega\\ u > 0 & \text{in } \Omega\\ u = 0 & \text{on } \partial\Omega, \end{cases}$$
(1.1)

in a bounded domain of \mathbb{R}^n , for an integer $k \in \{1, ..., n\}$, where

$$\mathcal{D}_k(D^2 u) = \sum_{i=1}^k \frac{\partial^2 u}{\partial x_i^2}$$
(1.2)

and f(u) is a positive nonlinearity on $(0, \infty)$, which can go to infinity as $u \to 0$.

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The above problem has a positive solution for uniformly elliptic equations (k = n) with a positive polynomial nonlinearity with negative exponent:

$$\Delta u + p u^{-\gamma} = 0 \tag{1.3}$$

See for instance Lazer-McKenna [31] and Crandall-Rabinowitz-Tartar [24]. For n = 1 equations of this kind arise in the theory of pseudoplastic fluids, appearing as generalized Emden-Fowler equations with negative exponent. See Nachman-Callegari [32].

Existence and uniqueness results results have also been obtained for equations with advection terms. See Giarrusso-Porru [27] and Porru-Vitolo [34].

Partial diffusion operators have been considered with respect to the maximum principle in cylindrical domains in [19–21], which had been previously investigated for linear and fully nonlinear uniformly elliptic equations in [4,9,10,16,19,37–39].

In the present paper, we will show that similar results hold in the case of degenerate, not uniform ellipticity (k < n). For nonlinearities as in equation (1.3) in degenerate elliptic cases see also [5].

We need in our case a geometric condition (G) introduced by Blanc and Rossi [8], which says for the present use that Ω is a strictly convex domain. See Section 4.

Theorem 1.1. Let Ω be a bounded domain of \mathbb{R}^n satisfying condition (**G**). Let $f : (0, \infty) \to (0, \infty)$ be a continuous non-increasing function. Then there exists an unique solution, positive in Ω , of the Dirichlet problem (1.1).

It is plain that Theorem 1.1 holds more generally in the case of the Dirichlet problem

$$\begin{cases} \mathcal{D}_{k,\delta}(D^2u) + f(u) = 0 & \text{in } \Omega\\ u > 0 & \text{in } \Omega\\ u = 0 & \text{on } \partial\Omega, \end{cases}$$
(1.4)

for anisotropic partial diffusion operators

$$\mathcal{D}_{k,\delta}(D^2 u) = \sum_{i=1}^k \delta_i \frac{\partial^2 u}{\partial x_i^2}$$
(1.5)

with $\delta_i > 0, i = 1, ..., k$.

The paper is organized as follows. In Section 2 we introduce the different notions of ellipticity and the viscosity solutions, then we establish comparison principles and recall existence, uniqueness and regularity results. In Section 3 we study an associate ODE and construct radial solutions of partial Laplace equations with positive non-increasing reaction terms. In Section 4 we prove the existence of Dirichlet problems for the smallest and the largest Hessian eigenvalue equation with positive non-increasing reaction terms. In Section 5 we finally prove Theorem 1.1.

2. Definitions and auxiliary results

Let \mathcal{F} be a mapping from $\Omega \times \mathbb{R} \times \mathbb{R}^n \times S^n$ to \mathbb{R} , where Ω is an open connected set of \mathbb{R}^n and S^n the vector space of real $n \times n$ symmetric matrices. The fully nonlinear operator \mathcal{F} acts on $u \in C^2(\Omega)$ as follows:

$$\mathcal{F}[u](x) = \mathcal{F}(x, u(x), Du(x), D^2u(x)), \quad x \in \Omega,$$
(2.1)

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where Du is the gradient and D^2u the Hessian matrix of the function u.

As usual, S^n is endowed with the partial order relationship: $X \le Y$ if and only if X - Y is semidefinite positive. Moreover, if \mathcal{F} is constant with respect to a variable, we omit such a variable.

For instance, the operator considered in Eq (1.1) can be represented as

$$\mathcal{F}[u] = \mathcal{F}(u, D^2 u), \tag{2.2}$$

where

$$\mathcal{F}(t,X) = \sum_{i=1}^{k} X_{ii} + f(t).$$
(2.3)

Definition 1. We say that \mathcal{F} is degenerate elliptic in Ω if and only if

$$\mathcal{F}(x,t,\xi,X) \le \mathcal{F}(x,t,\xi,Y) \tag{2.4}$$

for all $X, Y \in S^n$ such that $X \leq Y$ and $(x, t, \xi) \in \Omega \times \mathbb{R} \times \mathbb{R}^n$.

Therefore the operator (2.3) under consideration is degenerate elliptic for all k = 1, ..., n. Furthermore, let

$$\Pi_k = \sum_{i=1}^k e_i \otimes e_i \tag{2.5}$$

be the projection matrix on the vector subspace generated by the first k vectors e_1, \ldots, e_k of the canonical basis of \mathbb{R}^n , so that in particular $\Pi_n = I$, the $n \times n$ identity matrix. Setting

$$\mathcal{D}_k(X) = \sum_{i=1}^k X_{ii} = \operatorname{Tr}(\Pi_k X), \qquad (2.6)$$

then

$$\mathcal{F}(t,X) = \mathcal{D}_k(X) + f(t). \tag{2.7}$$

Definition 2. We say that \mathcal{F} is proper in Ω if and only if it is degenerate elliptic and

$$\mathcal{F}(x,t,\xi,X) \le \mathcal{F}(x,s,\xi,Y) \tag{2.8}$$

for all $s, t \in \mathbb{R}$ such that $s \leq t$ and $(x, \xi) \in \Omega \times \mathbb{R}^n \times S^n$.

Assuming that *f* is a non-increasing function, the operator (2.7) is proper. Under the same condition on *f*, the operator (2.7) is proper when considering any matrix $A \ge 0$ instead of Π_k .

Definition 3. Let λ and Λ be positive constants such that $\lambda \leq \Lambda$. We say that \mathcal{F} is uniformly elliptic in Ω with ellipticity constants λ and Λ if and only if

$$\mathcal{F}(x,t,\xi,Y) - \Lambda \operatorname{Tr}(Y-X) \le \mathcal{F}(x,t,\xi,X) \le \mathcal{F}(x,t,\xi,Y) - \lambda \operatorname{Tr}(Y-X)$$
(2.9)

for all $X, Y \in S^n$ such that $X \leq Y$ and $(x, t, \xi) \in \Omega \times \mathbb{R} \times \mathbb{R}^n$.

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It is plain that the uniform ellipticity is stronger than the degenerate ellipticity. Moreover, let $\mathcal{M}_{\lambda,\Lambda}^{\pm}(X), X \in S^n$, be the extremal Pucci operators:

$$\mathcal{M}^{+}_{\lambda,\Lambda}(X) = \Lambda \operatorname{Tr}(X^{+}) - \lambda \operatorname{Tr}(X^{-}) = \sup_{\lambda I \le A \le \Lambda I} \operatorname{Tr}(AX)$$

$$\mathcal{M}^{-}_{\lambda,\Lambda}(X) = \lambda \operatorname{Tr}(X^{+}) - \Lambda \operatorname{Tr}(X^{-}) = \inf_{\lambda I \le A \le \Lambda I} \operatorname{Tr}(AX).$$

(2.10)

Then $\mathcal{M}^{\pm}_{\lambda,\Lambda}$ are uniformly elliptic and (2.10) can be restated as

$$\mathcal{M}^{-}_{\lambda,\Lambda}(Y-X) \leq \mathcal{F}(x,t,\xi,Y) - \mathcal{F}(x,t,\xi,X) \leq \mathcal{M}^{+}_{\lambda,\Lambda}(Y-X).$$
(2.11)

It is easy to check that the operators (2.7) are uniform elliptic only for k = n, when the second-order part is the Laplace operator Δu .

For k < n (directional diffusion) the operators (2.6) are degenerate elliptic (proper if f is non-increasing), but not uniformly elliptic. See [41].

Even though a degenerate elliptic fully nonlinear operator $\mathcal{F}[u]$ is defined in the classical sense only when *u* is twice differentiable, nonetheless the equation $\mathcal{F}[u] = 0$ makes (a weaker) sense also when *u* is less regular.

Here we will consider the viscosity sense. Let *D* be a locally compact subset of \mathbb{R}^n , the spaces of upper and lower semicontinuous functions in *D* will be indicated with usc(*D*) and lsc(*D*), respectively.

Let $x_0 \in D$ and $u : D \to \mathbb{R}$. We denote by $J_D^{2,\pm}u(x_0)$ the second order superjet and subjet of u at x_0 :

$$J_{D}^{2,+}u(x_{0}) = \{(\xi, X) \in \mathbb{R}^{n} \times S^{n} : u(x_{0} + h) \leq u(x_{0}) + \langle \xi, h \rangle + \frac{1}{2} \langle Xh, h \rangle + o(|h|^{2}) \text{ as } h \to 0 \};$$

$$J_{D}^{2,-}u(x_{0}) = \{(\xi, X) \in \mathbb{R}^{n} \times S^{n} : u(x_{0} + h) \geq u(x_{0}) + \langle \xi, h \rangle + \frac{1}{2} \langle Xh, h \rangle + o(|h|^{2}) \text{ as } h \to 0 \}.$$
(2.12)

Definition 4. Let u be in usc(D), resp. in lsc(D). We say that u is a viscosity subsolution, resp. supersolution, in Ω of the equation $\mathcal{F}[u] = 0$ if and only if for all $x_0 \in D$

$$\mathcal{F}(x_0, u(x_0), \xi, X) \ge 0 \quad \forall (\xi, X) \in J_O^{2,+} u(x_0),$$
(2.13)

resp.

$$\mathcal{F}(x_0, u(x_0), \xi, X) \le 0 \quad \forall (\xi, X) \in J_O^{2,-}u(x_0),$$
(2.14)

A function $u \in C(D)$, which is both a subsolution and a supersolution of the equation $\mathcal{F}[u] = 0$ is called a viscosity solution of such equation.

We will also use the notations $\mathcal{F}[u] \ge 0$, resp. $\mathcal{F}[u] \ge 0$, to say that u is a subsolution u, resp. a supersolution, of the equation $\mathcal{F}[u] = 0$.

For more properties of viscosity solutions we refer to [12, 22, 23, 30].

An important role is played by the maximum principle for subsolutions and, more generally, the comparison principle between upper semicontinuous subsolutions and lower semicontinuous supersolutions. See [23, 25, 41].

The comparison principle for the operators considered in this paper depends on the non-totally degenerate ellipticity, which is intermediate between the degenerate and the uniform ellipticity. See [3,41].

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Definition 5. Let \mathcal{F} be a degenerate elliptic fully nonlinear operator. We say that \mathcal{F} is non-totally degenerate elliptic in Ω if and only if there exists a continuous function $\lambda(x) > 0$ such that

$$\mathcal{F}(x,t,\xi,X+\varepsilon I) - \mathcal{F}(x,t,\xi,X) \ge \lambda(x)\varepsilon$$
(2.15)

for all $\varepsilon > 0$ and $(x, t, \xi, X) \in \Omega \times \mathbb{R} \times \mathbb{R}^n \times S^n$.

It is easy to check, by linearity, that the operators (2.5) are non-totally degenerate elliptic with $\lambda(x) = k$: in fact,

$$\sum_{i=1}^{k} (X + \varepsilon I)_{ii} = \sum_{i=1}^{k} X_{ii} + \varepsilon k$$
(2.16)

We will also consider below other non-totally degenerate elliptic operators, the partial traces

$$\mathcal{P}_k^-(X) = \sum_{i=1}^k \lambda_i(X), \qquad (2.17)$$

where $\lambda_1(X) \leq \cdots \leq \lambda_n(X)$ are the eigenvalues of the matrix $X \in S^n$, and the dual partial trace operators

$$\mathcal{P}_{k}^{+}(X) = -\mathcal{P}_{k}^{-}(-X) = \sum_{i=n-k+1}^{n} \lambda_{i}(X).$$
(2.18)

Such operators arise for geometric problems of partial mean curvature [35, 36, 42] and in stochastic differential games [7,8]. They have been firstly investigated by Harvey-Lawson [28] and Caffarelli-Li-Nireneberg [13–15], and then in subsequent papers among which for instance [1,6–8,25,26,40].

Is is also easy to check as well that the operators (2.17) and (2.18) are non-totally degenerate elliptic with $\lambda(x) = k$. For instance

$$\sum_{i=1}^{k} \lambda_i (X + \varepsilon I) = \sum_{i=1}^{k} \lambda_i (X) + \varepsilon k$$
(2.19)

Note also that all operators \mathcal{D}_k and \mathcal{P}_k^{\pm} coincide with the Laplace operator when k = n. Only in this case such operators are uniformly elliptic.

Lemma 2.1. Let $\mathcal{F}(t, X) = \mathcal{M}(X) + f(t)$ be a degenerate elliptic operator, where f is a continuous and non-increasing positive function in $(0, \infty)$.

Let $u \in usc(\overline{\Omega})$ and $v \in lsc(\overline{\Omega})$ be non-negative functions such that $\mathcal{F}[u] \ge 0$ and $\mathcal{F}[v] \le 0$ in a bounded domain Ω . If $u \le v$ on $\partial\Omega$, then $u \le v$ in Ω .

Proof. Since the function u - v is upper semicontinuous, then u - v has a maximum at a point $\hat{x} \in \Omega$. We have to prove that, $u \le v$ on $\partial\Omega$, then $u(\hat{x}) \le v(\hat{x})$.

Suppose, by contradiction, that $\max_{\overline{\Omega}}(u - v) = \delta > 0$., namely

$$u(\hat{x}) - v(\hat{x}) = \delta > 0, \tag{2.20}$$

Let B_d a ball centered at the origin such that $\overline{\Omega} \subset B_d$, and where $0 < \varepsilon < \frac{\delta}{d^2}$. Then set

$$u_{\varepsilon}(x) = u(x) + \frac{\varepsilon}{2} |x - \hat{x}|^2,$$
 (2.21)

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By the choice of ε , we have for $x \in \partial \Omega$:

$$u_{\varepsilon}(x) - v(x) + \frac{\delta}{2} \leq \frac{\varepsilon}{2} |x - \hat{x}|^2 + \frac{\delta}{2}$$

$$\leq \frac{\varepsilon}{2} d^2 + \frac{\delta}{2}$$

$$\leq \delta = u_{\varepsilon}(\hat{x}) - v(\hat{x}),$$

(2.22)

so that the usc function $u_{\varepsilon} - v$ has a positive maximum at <u>a</u> point of Ω .

Following the proof of [23, Theorem 3.3], let $x_{\alpha}, y_{\alpha} \in \overline{\Omega}$ be such that

$$M_{\alpha} = \max_{\overline{\Omega} \times \overline{\Omega}} \left(u_{\varepsilon}(x) - v(y) - \frac{\alpha}{2} |x - y|^2 \right)$$

= $u_{\varepsilon}(x_{\alpha}) - v(y_{\alpha}) - \frac{\alpha}{2} |x_{\alpha} - y_{\alpha}|^2.$ (2.23)

Let $\hat{x}_{\varepsilon} \in \overline{\Omega}$ be a limit point of x_{α} . From [23, Lemma 3.1] we have

$$\lim_{\alpha \to \infty} \alpha |x_{\alpha} - y_{\alpha}|^{2} = 0;$$

$$\lim_{\alpha \to \infty} M_{\alpha} = u_{\varepsilon}(\hat{x}_{\varepsilon}) - v(\hat{x}_{\varepsilon}) = \max_{\overline{\Omega}} (u_{\varepsilon}(x) - v(x)).$$
(2.24)

From the above limits:

$$\lim_{\alpha \to \infty} x_{\alpha} = \hat{x}_{\varepsilon} = \lim_{\alpha \to \infty} y_{\alpha};$$

$$\lim_{\alpha \to \infty} (u_{\varepsilon}(x_{\alpha}) - v(y_{\alpha})) = u_{\varepsilon}(\hat{x}_{\varepsilon}) - v(\hat{x}_{\varepsilon}).$$
(2.25)

By the upper semicontinuity of u_{ε} and the lower semicontinuity of v, on a subsequence:

$$\lim_{\alpha \to \infty} u_{\varepsilon}(x_{\alpha}) = u_{\varepsilon}(\hat{x}_{\varepsilon}), \quad \lim_{\alpha \to \infty} v(y_{\alpha}) = v(\hat{x}_{\varepsilon}).$$
(2.26)

By (2.22) we have $\max_{\partial\Omega}(u_{\varepsilon} - v) < u_{\varepsilon}(\hat{x}_{\varepsilon}) - v(\hat{x}_{\varepsilon})$. Therefore $\hat{x}_{\varepsilon} \in \Omega$, and $x_{\alpha}, y_{\alpha} \in \Omega$ for large α , by the upper semicontinuity of $u_{\varepsilon} - v$.

From [23, Theorem 3.2] we deduce that matrices $X_{\alpha}, Y_{\alpha} \in S^n$ such that

$$(\alpha(x_{\alpha} - y_{\alpha}), X_{\alpha}) \in \overline{J}_{\Omega}^{2,+} w(x_{\alpha}),$$

$$(\alpha(x_{\alpha} - y_{\alpha}), Y_{\alpha}) \in \overline{J}_{\Omega}^{2,-} v(y_{\alpha}),$$
(2.27)

and

$$X_{\alpha} \le Y_{\alpha}. \tag{2.28}$$

Since v is a viscosity subsolution, then

$$\mathcal{M}(Y_{\alpha}) + f(v(y_{\alpha})) \le 0. \tag{2.29}$$

On the other hand, by the non-totally degenerate ellipticity, u_{ε} is a viscosity solution of the differential inequality

$$\mathcal{M}(D^2 u_{\varepsilon}(x)) + f\left(u_{\varepsilon}(x) - \frac{\varepsilon}{2} |x - \hat{x}|^2\right) \ge \lambda(x)\varepsilon \text{ in }\Omega$$
(2.30)

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$$\mathcal{M}(X_{\alpha}) + f\left(u_{\varepsilon}(x) - \frac{\varepsilon}{2} |x - \hat{x}|^{2}\right) \ge \lambda(x_{\alpha})\varepsilon.$$
(2.31)

Combining (2.29) and (2.31), by the degenerate ellipticity:

$$\mathcal{M}(X_{\alpha}) + f\left(u_{\varepsilon}(x_{\alpha}) - \frac{\varepsilon}{2} |x_{\alpha} - \hat{x}|^{2}\right) \ge \mathcal{M}(Y_{\alpha}) + f(v(y_{\alpha})) + \lambda(x_{\alpha})\varepsilon$$

$$\ge \mathcal{M}(X_{\alpha}) + f(v(y_{\alpha})) + \lambda(x_{\alpha})\varepsilon,$$
(2.32)

so that

and therefore

$$f\left(u_{\varepsilon}(x_{\alpha}) - \frac{\varepsilon}{2} |x_{\alpha} - \hat{x}|^{2}\right) \ge f(v(y_{\alpha})) + \lambda(x_{\alpha})\varepsilon.$$
(2.33)

Let $\alpha \to \infty$ using (2.26). Then

$$f((u_{\varepsilon}(\hat{x}_{\varepsilon}) - \frac{\varepsilon}{2} |\hat{x}_{\varepsilon} - \hat{x}|^2) \ge f(v(\hat{x}_{\varepsilon})) + \lambda(\hat{x})\varepsilon.$$
(2.34)

From this, by the non-increasing monotonicity of f we have therefore

$$u_{\varepsilon}(\hat{x}_{\varepsilon}) - v(\hat{x}_{\varepsilon}) \le \frac{\varepsilon}{2} |\hat{x}_{\varepsilon} - \hat{x}|^2.$$
(2.35)

On the other hand, recalling the assumption $u(\hat{x}) - v(\hat{x}) = \delta > 0$, we have:

$$u_{\varepsilon}(\hat{x}_{\varepsilon}) - v(\hat{x}_{\varepsilon}) = \max_{\overline{\Omega}}(u_{\varepsilon} - v) \ge \max_{\overline{\Omega}}(u - v) = \delta,$$
(2.36)

Together with (2.36), this implies $0 < \delta \leq \frac{\varepsilon}{2} |\hat{x}_{\varepsilon} - \hat{x}|^2$, which cannot hold for small $\varepsilon > 0$. So the assumption $u(\hat{x}) > v(\hat{x})$ leads to a contradiction, and it turns abut that $u(\hat{x}) \leq v(\hat{x})$.

The above theorem works for all non-totally degenerate elliptic operators, in particular when \mathcal{M} is the partial diffusion operator \mathcal{D}_k as well as for the partial trace operators \mathcal{P}_k^{\pm} .

We will use in the sequel the interior Lipschitz estimate of [25, Lemma 5.5] for $\mathcal{P}_1^-(X) = \lambda_1(X)$ and the dual operator $\mathcal{P}_1^+(X) = \lambda_n(X)$. See also [6].

Lemma 2.2. Let $u \in usc(B_1)$ be a viscosity subsolution of the equation $\lambda_1(D^2u) = g(x)$ in B_1 , a ball of unit radius. If g is a continuous function, bounded below in B_1 , then u in B_1 is Lipschitz-continuous and the following interior Lipschitz estimate holds:

$$\|Du\|_{L^{\infty}(B_{1/2})} \le C\left(\|u\|_{L^{\infty}(B_{1})} + \|g^{-}\|_{L^{\infty}(B_{1})}\right),\tag{2.37}$$

where $B_{1/2}$ is the ball of radius 1/2 concentric with B_1 and C a positive costant depending on n.

By duality, let $u \in lsc(B_1)$ be a supersolution of the equation $\lambda_n(D^2u) = g(x)$ in B_1 . If g is a continuous function, bounded above in B_1 , then $u \in C^{\alpha}(B_1)$ and the following interior C^{α} estimate holds:

$$\|Du\|_{L^{\infty}(B_{1/2})} \le C\left(\|u\|_{L^{\infty}(B_{1})} + \|g^{+}\|_{L^{\infty}(B_{1})}\right),\tag{2.38}$$

It is also worth to recall a very interesting $C^{1,\alpha}$ regularity result proved in [33] for the highly degenerate elliptic operator λ_1 , if we consider that, also in the uniform elliptic case, we have basically the C^{α} regularity, and this is the best we can have in the general case. For Hölder estimates in the uniform and degenerate elliptic case we refer for instance to [2, 11, 25]. For Lipschitz estimates see [6, 25, 29].

3. On the equation $\lambda_i(D^2u) + f(u) = 0$: radial solutions

In this section we investigate the qualitative properties of the radial solutions of the equation $\lambda_i(D^2u) + f(u) = 0$, where *f* is a continuous and non-increasing positive function in $(0, \infty)$.

Asin the case of entire solutions, we preliminarly discuss an associated ODE with suitable initial conditions. See [17, 18].

In the present case, for j = 1 we consider the Cauchy problem

$$\begin{aligned}
\varphi'' + f(\varphi) &= 0, \quad r > 0, \\
\varphi(0) &= t_0 > 0 \\
\varphi'(0) &= 0.
\end{aligned}$$
(3.1)

and for $j \ge 2$

$$\begin{cases} \varphi' + rf(\varphi) = 0, \quad r > 0, \\ \varphi(0) = t_0 > 0. \end{cases}$$
(3.2)

Here below we state some useful properties of the classical solutions.

Lemma 3.1. Let $f : (0, \infty) \to (0, \infty)$ be a continuous and non-increasing function. Then the local classical solution of problem (3.1) or (3.2) is strictly decreasing and concave.

In case (3.1) the solution φ is C^2 and

$$\varphi''(r) \le \frac{\varphi'(r)}{r}.$$
(3.3)

In case (3.2) the solution φ is C^1 . Assuming in addition that f is C^1 , then φ is C^2 , and (3.3) holds as well.

Proof. For problem (3.1) we refer for instance Lemma 2.1 of [27] and Lemma 3 of [34]. Here we limit the discussion to problem (3.2).

Since *f* is positive and non-increasing, we have:

$$\begin{aligned} \varphi'(0) &= \lim_{r \to 0^+} \varphi'(r) = 0, \ \varphi'(r) = -rf(\varphi(r)) < 0 \ \text{for } r > 0; \\ \varphi'(r_2) - \varphi'(r_1) &= -f(\varphi(r_2)) + f(\varphi(r_1)) \le 0 \ \text{if } r_1 < r_2. \end{aligned}$$
(3.4)

Supposing that φ is C^2 ,

$$\varphi''(r) = -f(\varphi(r)) - rf'(\varphi(r))\varphi'(r) \le -f(\varphi(r)) = \frac{\varphi'(r)}{r}.$$
(3.5)

Lemma 3.2. Let $f : (0, \infty) \to (0, \infty)$ be a non-increasing function. Let [0, R) be the maximal positivity interval of the classical solution φ of problem (3.1) or (3.2). Then $R_f(t_0) = R$ is finite. Moreover

- (i) $t_1 < t_2 \Rightarrow R_f(t_1) < R_f(t_2);$
- (*ii*) $\lim_{t_0 \to 0^+} R_f(t_0) = 0;$
- (iii) if $g: (0, \infty) \to (0, \infty)$, then $f \leq g \Rightarrow R_g(t_0) \leq R_f(t_0)$.

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Proof. We discuss the case of problem (3.2), referring to [27] and [34] for (3.1). Since $\varphi'(0) = 0$ and $\varphi(r)$ is concave, then $R_f(t_0) < \infty$.

The remaining properties (i), (ii) and (iii) can be deduced observing that:

$$R_f(t_0) = \left(2\int_0^{t_0} \frac{dt}{f(t)}\right)^{1/2}.$$
(3.6)

4. On the equation $\lambda_j(D^2u) + f(u) = 0$: the Dirichlet problem

In this section we investigate the Dirichlet problem

$$\begin{cases} \lambda_j(D^2u) + f(u) = 0 & \text{in } \Omega\\ u > 0 & \text{in } \Omega\\ u = 0 & \text{on } \Omega \end{cases}$$
(4.1)

with f strictly decreasing in $(0, \infty)$.

We start solving by the Perron's method the approximate problems

$$\begin{cases} \lambda_j(D^2u) + f(u) = 0 & \text{in } \Omega\\ u = \varepsilon & \text{on } \Omega \end{cases}$$
(4.2)

with $\varepsilon > 0$.

In order to do this, we need some geometric property of the boundary $\partial \Omega$. Consider the Dirichlet problem

$$\begin{cases} \lambda_j(D^2 u) = 0 & \text{in } \Omega\\ u = g & \text{on } \Omega \end{cases}$$
(4.3)

Definition 6. (condition (G)). *Given* $y \in \partial \Omega$, *for every* r > 0 *there exists* $\delta > 0$ *such that*

$$(x + \mathbb{R}v) \cap B_r(y) \cap \partial\Omega \neq \emptyset \tag{4.4}$$

for every $x \in B_{\delta}(y)$ and direction $v \in \mathbb{R}^n$ (|v| = 1).

This is a necessary and sufficient to solve the Dirichlet problem (4.3) for all j = 1, ..., n and all continuous boundary data g.

Such condition can be weakened to require that (4.4) holds for only one direction v in each subspace of dimension j and n - j to solve (4.3) for a singole j such that 1 < j < n. See Blanc and Rossi [8, Theorem 1].

Lemma 4.1. Let Ω be a bounded open set satisfying the geometric condition (**G**), and $f: (0, \infty) \to (0, \infty)$ be a continuous and strictly decreasing function. For every $\varepsilon > 0$ there exists an unique continuous viscosity solution of problem (4.2) such that $u(x) \ge \varepsilon$.

Proof. As announced before, we use the Perron's method [23, Theorem 4.1].

The comparison principle is provided by Lemma 2.1. We need to find a subsolution \underline{u} and a supersolution \overline{u} such that $u = \varepsilon = \overline{u}$ on $\partial \Omega$.

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The function $\underline{u} \equiv \varepsilon$ is plainly a subsolution. To find a supersolution we solve the problem

$$\begin{cases} \lambda_1(D^2 v) = 0 & \text{in } \Omega\\ v(x) = -\varepsilon - \frac{1}{2} f(\varepsilon) |x|^2 & \text{on } \partial \Omega \end{cases}$$
(4.5)

See for instance [8,28,40]. By duality $\overline{u}(x) = -v(x) - \frac{1}{2} f(\varepsilon) |x|^2$ is a viscosity solution of the problem

$$\begin{cases} \lambda_n (D^2 \overline{u}) + f(\varepsilon) = 0 & \text{in } \Omega\\ \overline{u}(x) = \varepsilon & \text{on } \partial \Omega. \end{cases}$$
(4.6)

Since $\lambda_n(D^2\overline{u}) \leq 0$ in Ω and $\overline{u} \geq \varepsilon$ on $\partial\Omega$, by the maximum principle [1,26,28] we have $\overline{u} \geq \varepsilon$ in Ω . By the non-increasing monotonicity of f, then $f(\overline{u}) \leq f(\varepsilon)$. On the other hand $\lambda_j \leq \lambda_n$, so that \overline{u} can be chosen as the supersolution we are searching for:

$$\begin{cases} \lambda_j(D^2\overline{u}) + f(\overline{u}) \le 0 & \text{in } \Omega\\ \overline{u}(x) = \varepsilon & \text{on } \partial\Omega. \end{cases}$$
(4.7)

By [23, Theorem 4.1] we conclude that there exists an unique continuous viscosity solution of problem (4.2).

Furthermore, by the comparison principle, being $u \equiv \varepsilon$ a subsolution, we have $u \ge \varepsilon$ in Ω .

From the solutions of problems (4.2), we obtain as limit the solution of problem (4.1) for j = 1 and j = n.

Firstly we show that such limit is a positive function.

Lemma 4.2. Let Ω be a bounded open set satisfying the geometric condition (**G**), and $f : (0, \infty) \rightarrow (0, \infty)$ be a continuous non-increasing function.

For $h \in \mathbb{N}$, let u_h be the solutions of problems (4.2) with $\varepsilon = \frac{1}{h}$ for j = 1. Then for every compact subset K of Ω there exists a number $t_K > 0$ such that

$$u_h(x) \ge t_K \ \forall x \in K \ and \ \forall h \in \mathbb{N}$$

$$(4.8)$$

Suppose in addition that f is C^1 . Then the same holds for the solutions of problems (4.2) with $\varepsilon = \frac{1}{h}$ for j = 2, ..., n.

Proof. Let *K* be a compact subset of Ω .

In the case j = 1, we consider a maximal positive solution φ of the Cauchy problem (3.1). We choose an initial condition $\varphi(0) = t_0 > 0$ such that the maximal positivity radius *R* is small enough (see Lemma 3.2), say $0 < R \le \frac{1}{2} \operatorname{dist}(K, \partial \Omega)$.

For any $x_0 \in K$, let $\phi(x) = \varphi(|x - x_0|)$. Then ϕ is C^2 , and by (3.3) :

$$\lambda_1(D^2\phi(x)) = \varphi''(|x - x_0|). \tag{4.9}$$

Thus ϕ is a classical solution of the Dirichlet problem:

$$\begin{cases} \lambda_1(D^2\phi) + f(\phi) = 0 & \text{in } B_R(x_0) \\ \phi = 0 & \text{on } \partial B_R(x_0). \end{cases}$$
(4.10)

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For $j \ge 2$, we consider a maximal positive solution φ of the Cauchy problem (3.2), and choose the initial condition $\varphi(0) = t_0 > 0$ as before, depending on the maximal positivity radius *R*.

In this case, we need to assume that *f* is C^1 in order that the radial function $\phi(x) = \varphi(|x - x_0|)$ is C^2 , according to Lemma 3.1, and by (3.3) :

$$\lambda_j(D^2\phi(x)) = \varphi'(|x - x_0|)/|x - x_0|.$$
(4.11)

Thus we have found as well a classical solution ϕ of the Dirichlet problem:

$$\begin{cases} \lambda_j(D^2\phi) + f(\phi) = 0 & \text{in } B_R(x_0) \\ \phi = 0 & \text{on } \partial B_R(x_0). \end{cases}$$
(4.12)

From now on, we can proceed with the same argument for all j = 1, ..., n.

We note that $u_h \ge 1/h > 0 = \phi$ on $\partial B_R(x_0)$, for every $h \in \mathbb{N}$. Comparing the solutions ϕ and u_h we have $u_h(x) \ge \phi(x) = \varphi(|x - x_0|)$ in $B_R(x_0)$.

In particular $u_h(x_0) \ge \varphi(0) = t_0$, which proves the assert with $t_K = t_0$.

Theorem 4.3. Let Ω be a bounded open set satisfying the geometric condition (**G**), and $f : (0, \infty) \rightarrow (0, \infty)$ be a continuous non-increasing function. Then for j = 1 there exists an unique continuous positive viscosity solution of problem (4.1).

Proof. For $h \in \mathbb{N}$, let u_h be the solutions of the Dirichlet problems (4.2) with $\varepsilon = \frac{1}{h}$ for j = 1. By the comparison principle, this is a non-increasing sequence. Therefore the u_h converge pointwise, as $h \to \infty$, to a function u in Ω such that u = 0 on $\partial \Omega$.

From Lemma 4.2 the function *u* has a positive lower bound every compact subset *K* of Ω , namely $u(x) \ge t_K > 0$ for all $x \in K$.

We will show that the u_h converge locally uniformly in Ω . Thus, by the stability theorems for viscosity solutions [12, 23], u is a solution of problem (4.1), which is unique by the comparison principle.

We are left therefore with proving the local uniform convergence of the u_h .

To this end, we firstly observe that, being $u_1 \ge u_h > 0$ on Ω for all $h \in \mathbb{N}$, the u_h are equi-bounded in Ω : setting $M = \max_{\Omega} u_1$,

$$0 \le u_h(x) \le M. \tag{4.13}$$

Next, let us fix a compact subset *K* of Ω , and consider a finite covering of *K* with balls of type $B_{R/4}(x_0)$, where $x_0 \in K$ and $0 < R \le \frac{1}{2} \operatorname{dist}(K, \partial \Omega)$.

As in the proof of Lemma 4.2, we choose $t_0 > 0$ be such that *R* is the maximal positivity radius of Cauchy problem (3.1). Letting φ be the maximal positive solution, we obtain a radial function $\phi(x) = \varphi(|x - x_0|)$, which is a classical solution of the Dirichlet problem (4.12).

By the comparison principle $u_h(x) \ge \phi(x)$ in $B_R(x_i)$. In particular, setting $t_K^* = \varphi(R/2)$, and using the decreasing monotonicity of φ , we have:

$$u_h(x) \ge \varphi(R/2) = t_K^* \text{ in } B_{R/2}(x_0), \quad \forall h \in \mathbb{N}.$$

$$(4.14)$$

As a consequence:

$$f(u_h(x)) \le f(t_K^*) \equiv M_K \quad \forall x \in B_{R/2}(x_0), \quad \forall h \in \mathbb{N}.$$

$$(4.15)$$

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Then, for all $x_0 \in K$:

$$\lambda_1(D^2 u_h) \ge -M_K \text{ in } B_{R/2}(x_0)$$
 (4.16)

Therefore, by (4.16), (2.37) and (4.13):

$$\|Du_h\|_{L^{\infty}(B_{R/4}(x_0))} \le C \left(M + M_K\right).$$
(4.17)

This inequality, together with (4.13), shows that the u_h are equi-continuous and equi-bounded on K. By Ascoli-Arzelà therefore $u_h \rightarrow u$ as $h \rightarrow \infty$ uniformly on K, as it was to be proved.

We prove the same result for the Dirichlet problem (4.1) with j = n. We follow the same lines of the proof of Theorem 4.3 but an additional approximation argument is needed since φ is C^2 provided f is C^1 , and we want to show the result under the weaker assumption that f is C^0 .

Theorem 4.4. Let Ω be a bounded open set satisfying the geometric condition (**G**), and $f : (0, \infty) \rightarrow (0, \infty)$ be a continuous non-increasing function. Then for j = n there exists an unique continuous positive viscosity solution of problem (4.1).

Proof. Case 1: f is C^1 non-increasing

We can repeat step by step the proof of Theorem 4.3 if we assume that f is C^1 , referring to (4.2) for j = n instead of j = 1. We construct as there a non-increasing sequence u_h , converging to a function u in Ω .

The sequence u_h is equi-bounded as (4.13) in Ω . We obtain easier way for all $x_0 \in \Omega$ the inequality

$$\lambda_n(D^2 u_h) \le 0 \text{ in } B_{R/2}(x_0), \tag{4.18}$$

Let *K* be a compact subset of Ω , and choose *R* as in the proof of Theorem 4.3. From (4.18), by (2.38) and (4.13), we deduce for all $x_0 \in K$:

$$\|Du_h\|_{L^{\infty}(B_{R/4}(x_0))} \le CM.$$
(4.19)

We conclude as before that the u_h are equi-bounded and equi-continuous on K, so that u is a continuous positive solution of problem (4.4) in this case.

Case 2: f is continuous non-increasing

We approximate f with a sequence f_i of C^1 non-increasing functions such that $f_i \to f$ as $i \to \infty$ locally uniformly in $(0, \infty)$ and $f_{i+1} \leq f_i$ for all $i \in \mathbb{N}$.

Then we solve, by Case 1, the following Dirichlet problems:

$$\begin{cases} \lambda_n (D^2 u_i) + f_i(u_i) = 0 & \text{in } \Omega\\ u_i(x) = 0 & \text{on } \partial \Omega. \end{cases}$$
(4.20)

Recall that the viscosity solutions u_i are positive in Ω , for $i \in \mathbb{N}$.

Since $f_{i+1} \leq f_i$, then $\lambda_n(D^2 u_{i+1}) + f_i(u_{i+1}) \geq \lambda_n(D^2 u_{i+1}) + f_{i+1}(u_{i+1}) = 0$, so that by comparison $u_i \geq u_{i+1}$.

Then the u_i converge to a function u in Ω such that u = 0 on $\partial \Omega$.

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The u_i are equi-bounded in Ω . In fact

$$0 \le u_i(x) \le M,\tag{4.21}$$

where $M = \max_{\Omega} u_1$.

Let *K* be a compact subset of Ω .

Since $\lambda_n(D^2u_i) \leq 0$ in $B_R(x_0)$, then (2.38) and (4.21) imply, as in the proof of Case 1,

$$\|Du_i\|_{L^{\infty}(B_{R/4}(x_0))} \le CM. \tag{4.22}$$

Therefore the u_i are equi-bounded and equi-continuous on K, and by Ascoli-Arzelà the u_h converge uniformly to u.

Next, choose $t_0 > 0$ such that the maximal positive radius $R = R_f(t_0)$ of the Cauchy problem (3.2) is small enough, in order that $0 < R < \frac{1}{2} \operatorname{dist}(K, \partial \Omega)$.

Let φ be the maximal positive solution, and let φ_i be the maximal positive solutions of the following Cauchy problems

$$\begin{cases} \varphi_i'(r) + f_i(\varphi_i(r)) = 0 & \text{in } \Omega\\ \varphi_i(0) = t_0 & \text{on } \partial\Omega. \end{cases}$$
(4.23)

Since $f \le f_i \le f_1$, then $R_1 \le R_i \equiv R_{f_i}(t_0) \le R$ and $\varphi_1 \le \varphi_i \le \varphi$ in $[0, R_1]$. For $x_0 \in K$, then $\phi_i(x) = \varphi_i(|x - x_0|)$ is a classical radial solution of the Dirichlet problem

$$\begin{cases} \lambda_n (D^2 \phi_i) + f_i(\phi_i) = 0 & \text{in } B_R(x_0) \\ \phi_i(x) = 0 & \text{on } \partial B_{R_i}(x_0), \end{cases}$$
(4.24)

Since $u_i > 0$ in Ω , comparing u_i and ϕ_i on $B_{R_i}(x_0)$, we get $u_i \ge \phi_i$ in $B_{R_i}(x_0)$. In particular, recalling that the φ_i are decreasing, we get

$$u_i(x) \ge \varphi_i(R_1/2) \ge \varphi_1(R_1/2) \equiv t'_K > 0 \text{ in } B_{R_1/2}(x_0).$$
 (4.25)

Therefore the f_i uniformly converge to f in $\{u_i(x) : x \in K, i \in \mathbb{N}\} \subset [t'_K, M]$. We have already shown that the u_i converge uniformly on K.

By the aforementioned stability results for viscosity solutions, then *u* is a viscosity solution of the Dirichlet problem (4.2) with j = n, positive in Ω by (4.25).

5. Proof of Theorem 1.1

We have to solve problem (1.1) with f positive and non-increasing in $(0, \infty)$.

Thanks to the results of the previous section, we will use once again the Perron's method of [23, Theorem 4.1].

The comparison principle is provided by Lemma 2.1, recalling that \mathcal{D}_k is non-totally degenerate elliptic.

Next we solve with Theorems 4.3 and 4.4 the following Dirichlet problems:

$$\begin{cases} \lambda_1(D^2\underline{u}) + \frac{1}{k}f(\underline{u}) = 0 & \text{in } \Omega\\ \underline{u}(x) = 0 & \text{on } \partial\Omega. \end{cases}$$
(5.1)

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and

$$\begin{cases} \lambda_n(D^2\overline{u}) + \frac{1}{k}f(\overline{u}) = 0 & \text{in } \Omega\\ \overline{u}(x) = 0 & \text{on } \partial\Omega. \end{cases}$$
(5.2)

Observe that

$$k\lambda_1(X) \le \sum_{i=1}^k X_{ii} \le k\lambda_n(X), \tag{5.3}$$

Then \underline{u} and \overline{u} are continuous viscosity subsolution and supersolution, respectively, positive on Ω , of the equation

$$\mathcal{D}_k(D^2 u) + f(u) \equiv \sum_{i=1}^k \frac{\partial^2 u}{\partial x_i^2} + f(u) = 0 \text{ in } \Omega$$
(5.4)

such that $\underline{u} = 0 = \overline{u}$ on $\partial \Omega$.

Theorem 4.1 of [23] implies therefore that there exists an unique positive viscosity solution of the problem

$$\begin{cases} \sum_{i=1}^{k} \frac{\partial^2 u}{\partial x_i^2} + f(u) = 0 & \text{in } \Omega\\ u(x) = 0 & \text{on } \partial\Omega, \end{cases}$$
(5.5)

as wanted.

Conflict of interest

The authors declare no conflict of interest.

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