



Research article

Taylor approximation of the solution of age-dependent stochastic delay population equations with Ornstein-Uhlenbeck process and Poisson jumps

Wenrui Li¹, Qimin Zhang^{1,*}, Meyer-Baese Anke², Ming Ye³ and Yan Li¹

¹ School of Mathematics and Statistics, Ningxia University, Yinchuan 750021, China

² Department of Scientific Computing, Florida State University, Tallahassee FL 32306-4120, USA

³ Department of Earth, Ocean, and Atmospheric Science and Department of Scientific Computing, Florida State University, Tallahassee FL 32306, USA

* **Correspondence:** Email: zhangqimin@nxu.edu.cn; Tel: +8613995212327.

Abstract: Numerical approximation is a vital method to investigate the properties of stochastic age-dependent population systems, since most stochastic age-dependent population systems cannot be solved explicitly. In this paper, a Taylor approximation scheme for a class of age-dependent stochastic delay population equations with mean-reverting Ornstein-Uhlenbeck (OU) process and Poisson jumps is presented. In case that the coefficients of drift and diffusion are Taylor approximations, we prove that the numerical solutions converge to the exact solutions for these equations. Moreover, the convergence order of the numerical scheme is given. Finally, some numerical simulations are discussed to illustrate the theoretical results.

Keywords: stochastic age-dependent population equations; time delay; ornstein-uhlenbeck process; taylor approximation

1. Introduction

Stochastic age-dependent population system has an increasingly important status in biomathematics, being the main research direction in biology and ecology in recent years. Especially, one of the most striking and meaningful problems in the study of stochastic age-dependent population system is its numerical scheme because of its nonlinear structure and non-existent explicit solutions. In [1], Li et al. first introduced Poisson jumps into stochastic age-dependent population system and proposed the following model:

$$\begin{cases} d_t P_t = \left[-\frac{\partial P_t}{\partial a} - \mu(t, a)P_t + f(t, P_t) \right] dt + g_1(t, P_t)dB_t + h(t, P_t)dN_t, & (t, a) \in Q, \\ P(0, a) = P_0(a), & a \in [0, A], \\ P(t, 0) = \int_0^A \beta(t, a)P(t, a)da, & t \in [0, T], \end{cases} \quad (1.1)$$

where $T > 0$, A is the maximal age of the population species and $A > 0$, $Q = (0, T) \times (0, A)$. $d_t P_t$ is the differential of P_t relative to t , i.e., $d_t P_t = \frac{\partial P_t}{\partial t} dt$. $P_t = P(t, a)$ denotes the population density of age a at time t , $\mu(t, a)$ denotes the mortality rate of age a at time t , $\beta(t, a)$ denotes the fertility rate of females of a at time t , $f(t, P_t)$ denotes effects of external environment for population system, $g_1(t, P_t)$ is a diffusion coefficient, $h(t, P_t)$ is a jump coefficient (it represents the size of the population systems increases or decreases drastically because brusque variations from earthquakes, floods, immigrants and so on), B_t is a Brownian motion, N_t is a Poisson process with intensity $\lambda > 0$. Then, they investigated the convergence of Euler method for model (1.1). Since then, an increasing number of authors have analyzed stochastic age-dependent population models with Poisson jumps, and many significant results have been obtained (see e.g., [2–11]). For example, Wang and Wang [3] established the semi-implicit Euler method for stochastic age-dependent population models with Poisson jumps and discussed the convergence order of numerical solutions. Tan et al. [5] presented a split-step θ (SS θ) method of stochastic age-dependent population models with Poisson jumps, and the exponential stability of the model was established. Pei et al. [8] constructed two types of numerical methods for stochastic age-dependent population models with Poisson jumps, which are compensated and non-compensated. Then the asymptotic mean-square boundedness is discussed for numerical scheme.

In the above-mentioned model (1.1), we can easily see that the effects of randomly environmental variations of parameter μ are described as a linear function of Gaussian white noise [12, 13], that is $\mu dt \rightarrow \mu dt + \sigma dB_t$ (where σ^2 represents the intensity of B_t). Obviously, it is unreasonable to use linear function of Gaussian white noise to simulate parameters perturbation in a randomly varying environment. In [14], Duffie proposed to use a mean-reverting Ornstein-Uhlenbeck process to describe parameters which fluctuate around an average value. Up until now, the mean-reverting OU process have been extensively discussed in [15–18]. Zhao et al. [16] analyzed stationary distribution for stochastic competitive model incorporating the OU process. Wang et al. [17] introduced the OU process into the Susceptible-Infected-Susceptible (SIS) epidemic model and investigated its threshold. However, to the authors' knowledge, there is no literature to consider the OU process into the stochastic age-dependent population system with Poisson jumps. On the other hand, we find that the influence of time delay are not considered in the above papers [1–9, 11]. There are very few papers in the literature that take time delay into account in the stochastic age-dependent population system so far (see e.g., [19, 20]). Therefore, based on the above analysis, studying stochastic age-dependent delay population jumps equations, coupled with mean-reverting OU process have more practical significance.

Obviously, the age-dependent stochastic delay population equations with mean-reverting OU process and Poisson jumps have no explicit solution. Thus, numerical approximation schemes should be developed as a essential and powerful tool to explore its properties. The numerical schemes of stochastic age-dependent population system have been extensively researched by many scholars, for example, [1, 3–5, 8, 9, 19, 21–23]. However, due to the fact that the coefficients f , g_1 and h of model (1.1) are particularly complex functions, so using the existing numerical methods to approximate the

age-dependent stochastic delay population equations with mean-reverting OU process and Poisson jumps will result in slow convergence and very high computational cost. Recently, Jankovic and Ilic [24] introduced a Taylor approximation method for stochastic differential equations and proved that its convergence rate and computational cost is better than other numerical methods such as the Euler method, the semi-implicit Euler method and $SS\theta$ method mentioned in [1–9, 11]. Motivated by Jankovic et al., we construct a Taylor approximation scheme for the age-dependent stochastic delay population equations with mean-reverting OU process and Poisson jumps in this paper. Furthermore, the convergence between the exact solutions and numerical solutions is investigated.

The highlights of the present paper are summarized as follows:

- Age-dependent stochastic delay population equations with mean-reverting OU process and Poisson jumps are given.
- To improve the convergence speed and reduce cost, the Taylor approximation scheme for the age-dependent stochastic delay population equations with mean-reverting OU process and Poisson jumps is developed.
- The convergence and convergence order of Taylor approximation scheme are discussed.

The arrangement of this paper is as follows. In section 2, we establish the age-dependent stochastic delay population equations with mean-reverting OU process and Poisson jumps, as well as introduce some notations and preliminaries. Then, the p th moments boundedness of exact solutions for age-dependent stochastic delay population equations with mean-reverting OU process and Poisson jumps are presented. In section 3, we propose a Taylor approximation scheme for a age-dependent stochastic delay population equations with mean-reverting OU process and Poisson jumps, and the convergence theory for the numerical method is proved. In section 4, we present some numerical simulations to demonstrate our theoretical results. Section 5 presents the conclusions of our research.

2. Model formulation and preliminaries

2.1. Model formulation

In the above model (1.1), the authors took advantage of a traditional parameter perturbation method to reflect the effect of environmental noise, $(-\mu(t, a)P_t + f(t, P_t))dt$ when it is stochastically perturbed with $(-\mu(t, a)P_t + f(t, P_t))dt + g_1(t, P_t)dB_t$. It is worth mentioning that Cai et al. [18] pointed out that due to environmental continuous fluctuations, the mortality rate $\mu(t, a)$ can not be described by a linear function of Gaussian white noise. In order to model the randomly varying environmental fluctuations in $\mu(t, a)$, we introduce the following mean-reverting Ornstein-Uhlenbeck process for $\mu(t, a)$ inspired by [16]:

$$\begin{cases} \mu(t, a) = \mu_1(t)\mu_2(a) \\ d\mu_1(t) = \eta(\mu_e - \mu_1(t))dt + \xi dB_t \end{cases} \quad (2.1)$$

where we assume that $\mu_1(t)$ represents the mortality rate at time t and $\mu_2(a)$ represents the mortality rate at age a . All parameters η , μ_e and ξ are positive constants. η is the reversion rate, μ_e is the mean reversion level or long-run equilibrium of growth rate $\mu_1(t)$, ξ is the intensity of volatility.

For (2.1), applying the stochastic integral format, we obtain the explicit form of the solution as:

$$\mu_1(t) = \mu_e + (\mu_1^0 - \mu_e)e^{-\eta t} + \xi \int_0^t e^{-\eta(t-s)} dB_s \quad (2.2)$$

where $(\mu_1^0 := \mu_1(0))$. It is not difficult to see that the expected value of $\mu_1(t)$ is

$$\mathbb{E}[\mu_1(t)] = \mu_e + (\mu_1^0 - \mu_e)e^{-\eta t} \quad (2.3)$$

and variance value of $\mu_1(t)$ is

$$\text{Var}[\mu_1(t)] = \frac{\xi^2}{2\eta}(1 - e^{-2\eta t}). \quad (2.4)$$

Combining (2.2), (2.3) and (2.4), we easily have that the term $\xi \int_0^t e^{-\eta(t-s)} dB_t$ satisfies the normal distribution $\mathbb{E}\left(0, \frac{\xi^2}{2\eta}(1 - e^{-2\eta t})\right)$. Then we obtain $\xi \int_0^t e^{-\eta(t-s)} dB(t)$ being equal to $\frac{\xi}{\sqrt{2\eta}} \sqrt{1 - e^{-2\eta t}} \frac{dB_t}{dt}$ a.e..

Therefore, we can rewrite (2.2) in the following form [17, 18]

$$\mu_1(t) = \mu_e + (\mu_1^0 - \mu_e)e^{-\eta t} + \sigma(t) \frac{dB_t}{dt}, \quad (2.5)$$

where $\sigma(t) = \frac{\xi}{\sqrt{2\eta}} \sqrt{1 - e^{-2\eta t}}$. A conceptual problem immediately occurs in that $\frac{dB_t}{dt}$ is not defined except in a generalized sense.

Replacing $\mu(t, a)$ in model (1.1) with (2.2) and (2.5) and rearranging leads to the following stochastic age-dependent population equation:

$$\begin{cases} d_t P_t = \left[\frac{\partial P_t}{\partial a} - (\mu_e + (\mu_1^0 - \mu_e)e^{-\eta t})\mu_2(a)P_t + f(t, P_t) \right] dt \\ \quad + g(t, P_t)dB_t + h(t, P_t)dN_t & (t, a) \in (0, T) \times (0, A), \\ P(0, a) = P_0(a), & a \in [0, A], \\ P(t, 0) = \int_0^A \beta(t, a)P(t, a)da, & t \in [0, T], \end{cases} \quad (2.6)$$

where $g(t, P_t)dB_t$ contains $g_1(t, P_t)dB_t$ and $-\sigma(t)\mu_2(a)P_t dB_t$.

On the other hand, due to the time delay is unavoidable in a real world. Motivated by [19] and [25], we derive the following system:

$$\begin{cases} d_t P_t = \left[-\frac{\partial P_t}{\partial a} - (\mu_e + (\mu_1^0 - \mu_e)e^{-\eta t})\mu_2(a)P_t + f(t, P_t, P_{t-\tau}) \right] dt \\ \quad + g(t, P_t, P_{t-\tau})dB_t + h(t, P_t, P_{t-\tau})dN_t, & (t, a) \in (0, T) \times (0, A), \\ P(t, a) = \phi(t, a), & (t, a) \in [-\tau, 0] \times [0, A], \\ P(t, 0) = \int_0^A \beta(t, a)P(t, a)da, & t \in [0, T], \end{cases} \quad (2.7)$$

where $P_t = P(t, a)$ denotes the population density of age a at time t , $P_{t-\tau} = P(t - \tau, a)$ denotes the population density of age a at time $t - \tau$, τ is time delay and $\tau > 0$. $f(t, P_t, P_{t-\tau})$ denotes the effects of external environment for the population system, $g(t, P_t, P_{t-\tau})$ is a diffusion coefficient, $h(t, P_t, P_{t-\tau})$ is a jump coefficient, $\phi_t = \phi(t, a)$ denotes the histories of the population density of age a at time t , $\beta(t, a)$ denotes the fertility rate of females of age a at time t . A is the maximal age of the population species, so $P(t, a) = 0, \forall a \geq A$. N_t is a Poisson process with intensity $\lambda > 0$. The explanation of the other symbols was given under Eq (2.1). In the following section, we concentrate on studying model (2.7).

2.2. Preliminary results

Let $V = D^1([0, A]) \equiv \{\varphi | \varphi \in L^2([0, A]), \text{ where } \frac{\partial \varphi}{\partial a} \text{ represent the generalized partial derivatives}\}$, V be a Sobolev space. $D = L^2[0, A]$ such that $V \hookrightarrow D \equiv D' \hookrightarrow V'$. V' is the dual space of V . We denote by $\|\cdot\|$, $|\cdot|$ and $\|\cdot\|_*$ the norms in V, D and V' respectively; by $\langle \cdot, \cdot \rangle$ the duality product between V and V' , and by (\cdot, \cdot) the scalar product in D .

For simplicity, we introduce some notations. Throughout this paper, unless otherwise, let $(\Omega, \mathcal{F}, \mathbb{P})$ be a complete probability space with filtration $\{\mathcal{F}_t\}_{t \geq 0}$ satisfying the usual conditions (i.e. it is increasing and right continuous while \mathcal{F}_0 contains all \mathbb{P} -null sets), and let \mathbb{E} signify the expectation corresponding to \mathbb{P} . For an operator $H \in L(M, D)$ on the space of all bounded linear operators from M into D , we denote by $\|H\|_2$ the Hilbert-Schmidt norm, i.e., $\|B\|_2 = \text{tr}(HWH)^T$.

Let $\tau > 0$ and $C = C([- \tau, 0]; D)$ be the space of all continuous function from $[0, T]$ into H with sup-norm $\|\psi\|_C = \sup_{-\tau \leq s \leq 0} |\psi(s)|$, $L_V^p = L^p([0, T]; V)$ and $L_D^p = L^p([0, T]; D)$. Moreover, let \mathcal{F}_0 -measurable, $C_{\mathcal{F}_0}^b([- \tau, 0]; D)$ denote the family of all almost surely bounded, \mathcal{F}_0 -measurable $C = C([- \tau, 0]; D)$ - value random variables. For a pair of real numbers a and b , we use $a \vee b = \max(a, b)$. If G is a set, its indicator function by 1_G , namely $1_G(x) = 1$ if $x \in G$ and 0 otherwise.

The integer version of Eq (2.7) is given by

$$P_t = P_0 - \int_0^t \frac{\partial P_s}{\partial a} ds - \int_0^t [\mu_e + (\mu_1^0 - \mu_e)e^{-\eta s}] \mu_2(a) P_s ds + \int_0^t f(s, P_s, P_{s-\tau}) ds + \int_0^t g(s, P_s, P_{s-\tau}) dB_s + \int_0^t h(s, P_s, P_{s-\tau}) dN_s. \quad (2.8)$$

For the existence and uniqueness of the solution, we assume that the following assumptions are satisfied:

(A1) $\mu(t, a)$ and $\beta(t, a)$ are nonnegative measurable, such that

$$\begin{cases} 0 \leq \underline{\mu} \leq \mu_2(a) < \bar{\mu} < \infty, \\ 0 \leq \beta(t, a) \leq \bar{\beta} < \infty. \end{cases}$$

(A2) $f(t, 0, 0) = g(t, 0, 0) = h(t, 0, 0) = 0$.

(A3) The Lipschitz and linear growth conditions: there exists a positive constant K such that

$$\begin{aligned} & |f(t, x_1, y_1) - f(t, x_2, y_2)| \vee \|g(t, x_1, y_1) - g(t, x_2, y_2)\|_2 \vee |h(t, x_1, y_1) - h(t, x_2, y_2)| \\ & \leq K(\|x_1 - x_2\|_C + \|y_1 - y_2\|_C), \\ & |f(t, x, y)|^2 \vee \|g(t, x, y)\|_2^2 \vee |h(t, x, y)|^2 \leq 2K^2(\|x\|_C^2 + \|y\|_C^2) \end{aligned}$$

for $\forall x, y, x_1, x_2, y_1, y_2 \in C$.

(A4) There exists constants $\tilde{K}, \bar{K} > 0$ and $\gamma \in (0, 1]$ such that for $-\tau \leq s \leq 0, 0 \leq a \leq A$ and $r \geq 2$

$$\mathbb{E}|\phi_t - \phi_s|^r \leq \tilde{K}(t - s)^\gamma.$$

Consequently,

$$\mathbb{E}|\phi_t|^r < \infty.$$

(A5) f, g and h have Taylor approximations in the second argument, up to α_1 th, α_2 th and α_3 th derivatives, denoted as $f_x^{(\alpha_1)}(t, x, y)$, $g_x^{(\alpha_2)}(t, x, y)$ and $h_x^{(\alpha_3)}(t, x, y)$, respectively.

(A6) $f_{P_t}^{(\alpha_1+1)}(t, P_t, P_{t-\tau})$, $g_{P_t}^{(\alpha_2+1)}(t, P_t, P_{t-\tau})$ and $h_{P_t}^{(\alpha_3+1)}(t, P_t, P_{t-\tau})$ are uniformly bounded, i.e. there

exist positive constants K_1 , K_2 and K_3 satisfying

$$\begin{cases} \sup_{[0,T] \times [0,A]} |f_{P_t}^{(\alpha_1+1)}(t, P_t, P_{t-\tau})| \leq K_1, \\ \sup_{[0,T] \times [0,A]} |g_{P_t}^{(\alpha_2+1)}(t, P_t, P_{t-\tau})| \leq K_2, \\ \sup_{[0,T] \times [0,A]} |h_{P_t}^{(\alpha_3+1)}(t, P_t, P_{t-\tau})| \leq K_3. \end{cases}$$

Throughout the following analysis, for the purpose of simplicity, we will use C, C_1, C_2, \dots to stand for generic constants that depend upon K and T , but not upon Δ . The precise value of these constants may be determined via the proof. Our first theorem shows the existence and uniqueness of the strong solution for the model (2.7).

Theorem 2.1. *Under the assumptions (A1) – (A4), for $t \in [0, T]$, Eq (2.7) has a unique strong solution.*

Proof. The proof of this theorem is standard (see Zhang et al. [26]) and hence is omitted.

Moreover, the p th moment boundedness of the true solution P_t of the model (2.7) is proved in the following theorem.

Theorem 2.2. *Under the assumptions (A1) – (A4), for each $q \geq 2$, there exists a constant C such that*

$$\mathbb{E} \left[\sup_{-\tau \leq t \leq T} |P_t|^q \right] \leq C. \quad (2.9)$$

Proof. Form (2.8), applying Itô's formula [25] to $|P_t|^q$ yields

$$\begin{aligned} |P_t|^q &= |P_0|^q + \int_0^t q|P_s|^{q-2} \left\langle -\frac{\partial P_s}{\partial a} - (\mu_e + (\mu_1^0 - \mu_e)e^{-\eta s})\mu_2(a)P_s, P_s \right\rangle ds \\ &\quad + \int_0^t q|P_s|^{q-2} (f(s, P_s, P_{s-\tau}), P_s) ds + \int_0^t \frac{q(q-1)}{2} |P_s|^{q-2} \|g(s, P_s, P_{s-\tau})\|_2^2 ds \\ &\quad + \int_0^t q|P_s|^{q-2} (P_s, g(s, P_s, P_{s-\tau})) dB_s + \int_0^t q|P_s|^{q-2} (P_s, h(s, P_s, P_{s-\tau})) dN_s \\ &\quad + \int_0^t \frac{q(q-1)}{2} |P_s|^{q-2} \|h(s, P_s, P_{s-\tau})\|_2^2 dN_s \\ &= |P_0|^q + \int_0^t q|P_s|^{q-2} \left\langle -\frac{\partial P_s}{\partial a} - (\mu_e + (\mu_1^0 - \mu_e)e^{-\eta s})\mu_2(a)P_s, P_s \right\rangle ds \\ &\quad + \int_0^t q|P_s|^{q-2} (f(s, P_s, P_{s-\tau}), P_s) ds + \int_0^t \frac{q(q-1)}{2} |P_s|^{q-2} \|g(s, P_s, P_{s-\tau})\|_2^2 ds \\ &\quad + \int_0^t q|P_s|^{q-2} (P_s, g(s, P_s, P_{s-\tau})) dB_s + \int_0^t q|P_s|^{q-2} (P_s, h(s, P_s, P_{s-\tau})) d\bar{N}_s \\ &\quad + \lambda \int_0^t q|P_s|^{q-2} (P_s, h(s, P_s, P_{s-\tau})) ds + \int_0^t \frac{q(q-1)}{2} |P_s|^{q-2} |h(s, P_s, P_{s-\tau})|^2 d\bar{N}_s \\ &\quad + \lambda \int_0^t \frac{q(q-1)}{2} |P_s|^{q-2} |h(s, P_s, P_{s-\tau})|^2 ds, \end{aligned} \quad (2.10)$$

where $\bar{N}_s = N_s - \lambda s$ is a compensated Poisson process.

Since

$$\begin{aligned}
 -\left\langle \frac{\partial P_s}{\partial a}, P_s \right\rangle &= -\int_0^A P_s d_a(P_s) = \frac{1}{2} \left(\int_0^A \beta(t, a) P_s da \right)^2 \\
 &\leq \frac{1}{2} \int_0^A \beta^2(t, a) da \int_0^A P_s^2 da \\
 &\leq \frac{1}{2} \bar{\beta}^2 A^2 |P_s|^2,
 \end{aligned} \tag{2.11}$$

by the assumptions (A1)-(A3), we get that

$$\begin{aligned}
 |P_t|^q &\leq |P_0|^q + q \left(\frac{\bar{\beta}^2 A^2}{2} + \mu_1^0 \bar{\mu} \right) \int_0^t |P_s|^q ds + q(q-1)K^2 \int_0^t |P_s|^{q-2} (\|P_s\|_C^2 + \|P_{s-\tau}\|_C^2) ds \\
 &\quad + Kq \int_0^t |P_s|^{q-1} (\|P_s\|_C + \|P_{s-\tau}\|_C) ds + q \int_0^t |P_s|^{q-2} (P_s, g(s, P_s, P_{s-\tau})) dB_s \\
 &\quad + q \int_0^t |P_s|^{q-2} (P_s, h(s, P_s, P_{s-\tau})) d\bar{N}_s + \frac{q(q-1)}{2} \int_0^t |P_s|^{q-2} |h(s, P_s, P_{s-\tau})|^2 d\bar{N}_s \\
 &\quad + \lambda q K \int_0^t |P_s|^{q-1} (\|P_s\|_C + \|P_{s-\tau}\|_C) ds + \lambda q(q-1)K^2 \int_0^t |P_s|^{q-2} (\|P_s\|_C^2 + \|P_{s-\tau}\|_C^2) ds \\
 &\leq |P_0|^q + q \left(\frac{\bar{\beta}^2 A^2}{2} + \mu_1^0 \bar{\mu} \right) \int_0^t |P_s|^q ds + 2q(q-1)K^2 \int_0^t \sup_{-\tau \leq u \leq s} |P_u|^q ds \\
 &\quad + 2Kq \int_0^t \sup_{-\tau \leq u \leq s} |P_u|^q ds + q \int_0^t |P_s|^{q-2} (P_s, g(s, P_s, P_{s-\tau})) dB_s \\
 &\quad + q \int_0^t |P_s|^{q-2} (P_s, h(s, P_s, P_{s-\tau})) d\bar{N}_s + 2Kq\lambda \int_0^t \sup_{-\tau \leq u \leq s} |P_u|^q ds \\
 &\quad + \frac{q(q-1)}{2} \int_0^t |P_s|^{q-2} |h(s, P_s, P_{s-\tau})|^2 d\bar{N}_s + 2\lambda q(q-1)K^2 \int_0^t \sup_{-\tau \leq u \leq s} |P_u|^q ds \\
 &\leq |P_0|^q + q \left[\left(\frac{\bar{\beta}^2 A^2}{2} + \mu_1^0 \bar{\mu} \right) + 2K + 2(q-1)K^2 + 2K\lambda + 2\lambda K^2(q-1) \right] \int_0^t \sup_{-\tau \leq u \leq s} |P_u|^q ds \\
 &\quad + q \int_0^t |P_s|^{q-2} (P_s, g(s, P_s, P_{s-\tau})) dB_s + q \int_0^t |P_s|^{q-2} (P_s, h(s, P_s, P_{s-\tau})) d\bar{N}_s \\
 &\quad + \frac{q(q-1)}{2} \int_0^t |P_s|^{q-2} |h(s, P_s, P_{s-\tau})|^2 d\bar{N}_s.
 \end{aligned} \tag{2.12}$$

Note that for any $t \in [0, T]$,

$$\mathbb{E} \left[\sup_{-\tau \leq u \leq t} |P_u|^q \right] = \mathbb{E} \left[\sup_{-\tau \leq u \leq 0} |P_u|^q \right] \vee \mathbb{E} \left[\sup_{0 \leq u \leq t} |P_u|^q \right]. \tag{2.13}$$

Hence, we have

$$\begin{aligned}
& \mathbb{E} \left[\sup_{-\tau \leq u \leq t} |P_u|^q \right] \\
& \leq \mathbb{E} \left[\sup_{-\tau \leq u \leq 0} |\phi_u|^q \right] + C_1 \int_0^t \mathbb{E} \left[\sup_{-\tau \leq u \leq s} |P_u|^q \right] ds \\
& \quad + q \mathbb{E} \left[\sup_{0 \leq s \leq t} \int_0^s |P_s|^{q-2} (P_s, g(s, P_s, P_{s-\tau})) dB_s \right] \\
& \quad + q \mathbb{E} \left[\sup_{0 \leq s \leq t} \int_0^s |P_s|^{q-2} (P_s, h(s, P_s, P_{s-\tau})) d\bar{N}_s \right] \\
& \quad + \frac{q(q-1)}{2} \mathbb{E} \left[\sup_{0 \leq s \leq t} \int_0^s |P_s|^{q-2} |h(s, P_s, P_{s-\tau})|^2 d\bar{N}_s \right],
\end{aligned} \tag{2.14}$$

where $C_1 = q \left[\left(\frac{\bar{\beta}^2 A^2}{2} + \mu_1^0 \bar{\mu} \right) + 2K + 2(q-1)K^2 + 2K\lambda + 2\lambda K^2(q-1) \right]$.

Using the Burkholder-Davis-Gundy's inequality, we derive that

$$\begin{aligned}
& \mathbb{E} \left[\sup_{0 \leq s \leq t} \int_0^s |P_s|^{q-2} (P_s, g(s, P_s, P_{s-\tau})) dB_s \right] \\
& = \mathbb{E} \left[\sup_{0 \leq s \leq t} \int_0^s |P_s|^{\frac{q}{2}} (P_s^{\frac{q-2}{2}}, g(s, P_s, P_{s-\tau})) dB_s \right] \\
& \leq \mathbb{E} \left[\sup_{-\tau \leq u \leq t} |P_u|^{\frac{q}{2}} \left(\int_0^t (P_s^{\frac{q-2}{2}}, g(s, P_s, P_{s-\tau})) dB_s \right) \right] \\
& \leq 3 \mathbb{E} \left[\sup_{-\tau \leq u \leq t} |P_u|^{\frac{q}{2}} \left(\int_0^t |P_s|^{q-2} \|g(s, P_s, P_{s-\tau})\|_2^2 ds \right)^{\frac{1}{2}} \right] \\
& \leq \frac{1}{6q} \mathbb{E} \left[\sup_{-\tau \leq u \leq t} |P_u|^q \right] + C_2 \mathbb{E} \left(\int_0^t |P_s|^{q-2} \|g(s, P_s, P_{s-\tau})\|_2^2 ds \right) \\
& \leq \frac{1}{6q} \mathbb{E} \left[\sup_{-\tau \leq u \leq t} |P_u|^q \right] + 4C_2 K^2 \left(\int_0^t \mathbb{E} \sup_{-\tau \leq u \leq s} |P_u|^q ds \right).
\end{aligned} \tag{2.15}$$

Similarly, we can obtain that

$$\begin{aligned}
& \mathbb{E} \left[\sup_{0 \leq s \leq t} \int_0^s |P_s|^{q-2} (P_s, h(s, P_s, P_{s-\tau})) d\bar{N}_s \right] \\
& \leq \frac{1}{6q} \mathbb{E} \left[\sup_{-\tau \leq u \leq t} |P_u|^q \right] + 4C_3 K^2 \left(\int_0^t \mathbb{E} \sup_{-\tau \leq u \leq s} |P_u|^q ds \right)
\end{aligned} \tag{2.16}$$

and

$$\begin{aligned}
& \mathbb{E} \left[\sup_{0 \leq s \leq t} \int_0^s |P_s|^{q-2} |h(s, P_s, P_{s-\tau})|_2^2 d\bar{N}_s \right] \\
& \leq \frac{1}{3q(q-1)} \mathbb{E} \left[\sup_{-\tau \leq u \leq t} |P_u|^q \right] + 16C_4 K^4 \left(\int_0^t \mathbb{E} \sup_{-\tau \leq u \leq s} |P_u|^q ds \right).
\end{aligned} \tag{2.17}$$

Substituting (2.15), (2.16) and (2.17) into (2.14) yields

$$\begin{aligned} \mathbb{E}\left[\sup_{-\tau \leq u \leq t} |P_u|^q\right] &\leq \mathbb{E}\left[\sup_{-\tau \leq u \leq 0} |\phi_u|^q\right] + \frac{1}{2}\mathbb{E}\left[\sup_{-\tau \leq u \leq t} |P_u|^q\right] \\ &+ (C_1 + 4qC_2K^2 + 4qC_3K^2 + 8q(q-1)C_4K^4)\left(\int_0^t \mathbb{E} \sup_{-\tau \leq u \leq s} |P_u|^q ds\right). \end{aligned} \quad (2.18)$$

Thus, the well-known Gronwall inequality obviously implies the desired equality (2.9).

3. Taylor approximation scheme and convergence

In this section, we will establish the Taylor approximation scheme for the stochastic age-dependent population Eq (2.7) and investigate the strong convergence between the true solutions and the numerical solutions derived from the Taylor approximation scheme.

3.1. Taylor approximation

Let τ_j denote the j th jump of N_s occurrence time. For example, assume that jumps arrive at distinct, ordered times $\tau_1 < \tau_2 < \dots$, let t_1, t_2, \dots, t_m be the deterministic grid points of $[0, T]$. We establish approximate solutions to (2.7) at a discrete set of times $\{\tau_j\} (j = 1, 2, \dots)$. This set is the superposition of the random jump times of the Poisson process on $[0, T]$ and a deterministic grid t_1, t_2, \dots, t_m and satisfy $\max\{|\tau_{i+1} - \tau_i|\} < \Delta t$ (for the sake of simplicity, we denote Δt as Δ). It is quite clear that the random Poisson jump times can be computed without any knowledge of the realized path of (2.7).

Next, we propose a Taylor approximation of the solutions of Eq (2.7). Without loss of any generality, given a step size $\Delta \in (0, 1)$, we let $t_k = k\Delta$ for $k = 0, 1, 2, 3, \dots, [\frac{T}{\Delta}]$, here $[\frac{T}{\Delta}]$ is the integer part of $\frac{T}{\Delta}$. The continuous time Taylor approximate solution $Q_t = Q(t, a)$ to the stochastic age-dependent population Eq (2.7) can be defined by setting $Q_0 = P_0(a) = \phi(0, a)$ and $Q(t, 0) = \int_0^A \beta(t, a)Q_t da$ and forming

$$\begin{cases} Q_t = Q_0 - \int_0^t \frac{\partial Q_s}{\partial a} ds - \int_0^t (\mu_e + (\mu_1^0 - \mu_e)e^{-\eta s})\mu_2(a)Q_s ds + \int_0^t \sum_{j=0}^{\alpha_1} \frac{f_{Z_{1s}}^{(j)}(s, Z_{1s}, Z_{2s})}{j!} (Q_s - Z_{1s})^j ds \\ \quad + \int_0^t \sum_{j=0}^{\alpha_2} \frac{g_{Z_{1s}}^{(j)}(s, Z_{1s}, Z_{2s})}{j!} (Q_s - Z_{1s})^j dB_s \\ \quad + \int_0^t \sum_{j=0}^{\alpha_3} \frac{h_{Z_{1s}}^{(j)}(s, Z_{1s}, Z_{2s})}{j!} (Q_s - Z_{1s})^j dN_s, & 0 \leq t \leq T, \\ Q_t = \phi(t, a), & -\tau \leq t \leq 0, \end{cases} \quad (3.1)$$

where $Z_{1t} = Z_1(t, a) = \sum_{k=0}^{[\frac{t}{\Delta}]} Q_{t_k} 1_{[t_k, t_{k+1})}(t)$ and $Z_{2t} = Z_2(t, a) = \sum_{k=0}^{[\frac{t}{\Delta}]} Q_{t_k - \tau} 1_{[t_k, t_{k+1})}(t)$ are step processes. That is, $Z_{1t} = Q_{t_k}$ and $Z_{2t} = Q_{t_k - \tau}$ for $t \in [t_k, t_{k+1})$ when $k=0, 1, 2, 3, \dots, [\frac{t}{\Delta}]$.

3.2. Convergence of the Taylor approximate solutions

In this subsection, let us investigate the convergence of the Taylor approximate solutions of the stochastic age-dependent population Eq (2.7).

In the following three lemmas we will show that Q_t and $Q_{t-\tau}$ are close to Z_{1t} and Z_{2t} based on L' , respectively.

Lemma 3.1. For any $q \geq 2$, there exists a positive constant K_4 such that

$$\mathbb{E} \sup_{t \in [-\tau, T]} |Q_t|^{(\alpha+1)^2 q} \leq K_4, \quad (3.2)$$

where $\alpha = \max\{\alpha_1, \alpha_2, \alpha_3\}$.

Proof. This proof is completed in **Appendix A**.

Remark 3.1. If $\alpha_1 = \alpha_2 = \alpha_3 = 0$, then (A3) shows that the Taylor approximation solutions Q_t admit finite moments (see, [27, 28]).

Lemma 3.2. Under the assumptions (A1), (A3), (A5), (A6), Lemma 3.1 and $\mathbb{E} \left| \frac{\partial Q_s}{\partial a} \right|^r < K_5$ hold, K_5 is a positive constant. For $2 \leq r \leq (\alpha + 1)q$, we have

$$\mathbb{E}|Q_t - Z_{1t}|^r \leq C\Delta^{\frac{r}{2}}. \quad (3.3)$$

Proof. For any $t \geq 0$, there exists an integer $k \geq 0$ such that $t \in [t_k, t_{k+1})$, we have

$$\begin{aligned} Q_t - Z_{1t} &= Q_t - Q_{t_k} = - \int_{t_k}^t \frac{\partial Q_s}{\partial a} ds - \int_{t_k}^t (\mu_e + (\mu_1^0 - \mu_e)e^{-\eta s}) \mu_2(a) Q_s ds + \int_{t_k}^t X_1(s, Q_s, Z_{1s}, Z_{2s}) ds \\ &\quad + \int_{t_k}^t X_2(s, Q_s, Z_{1s}, Z_{2s}) dB_s + \int_{t_k}^t X_3(s, Q_s, Z_{1s}, Z_{2s}) dN_s, \end{aligned}$$

where

$$\begin{aligned} X_1(t, Q_t, Z_{1t}, Z_{2t}) &= \sum_{j=0}^{\alpha_1} \frac{f_{Z_{1t}}^{(j)}(t, Z_{1t}, Z_{2t})}{j!} (Q_t - Z_{1t})^j, \\ X_2(t, Q_t, Z_{1t}, Z_{2t}) &= \sum_{j=0}^{\alpha_2} \frac{g_{Z_{1t}}^{(j)}(t, Z_{1t}, Z_{2t})}{j!} (Q_t - Z_{1t})^j, \\ X_3(t, Q_t, Z_{1t}, Z_{2t}) &= \sum_{j=0}^{\alpha_3} \frac{h_{Z_{1t}}^{(j)}(t, Z_{1t}, Z_{2t})}{j!} (Q_t - Z_{1t})^j. \end{aligned}$$

By the elementary inequality, we further have

$$\begin{aligned} \mathbb{E}|Q_t - Z_{1t}|^r &\leq 5^{r-1} \left[\mathbb{E} \left| \int_{t_k}^t \frac{\partial Q_s}{\partial a} ds \right|^r + \mathbb{E} \left| \int_{t_k}^t (\mu_e + (\mu_1^0 - \mu_e)e^{-\eta s}) \mu_2(a) Q_s ds \right|^r + \mathbb{E} \left| \int_{t_k}^t X_1(s, Q_s, Z_{1s}, Z_{2s}) \right|^r \right. \\ &\quad \left. + \mathbb{E} \left| \int_{t_k}^t X_2(s, Q_s, Z_{1s}, Z_{2s}) dB_s \right|^r + \mathbb{E} \left| \int_{t_k}^t X_3(s, Q_s, Z_{1s}, Z_{2s}) dN_s \right|^r \right]. \end{aligned}$$

Applying the Hölder inequality and moment inequality, we obtain

$$\begin{aligned} \mathbb{E}|Q_t - Z_{1t}|^r &\leq 5^{r-1} \left[\Delta^{r-1} \int_{t_k}^t \mathbb{E} \left| \frac{\partial Q_s}{\partial a} \right|^r ds + (\mu_1^0 \bar{\mu})^r \Delta^{r-1} \int_{t_k}^t \mathbb{E}|Q_s|^r ds + \Delta^{r-1} \int_{t_k}^t \mathbb{E}|X_1(s, Q_s, Z_{1s}, Z_{2s})|^r ds \right. \\ &\quad \left. + C_1 \Delta^{\frac{r}{2}-1} \int_{t_k}^t \mathbb{E} \|X_2(s, Q_s, Z_{1s}, Z_{2s})\|_2^r dB_s + \mathbb{E} \left| \int_{t_k}^t X_3(s, Q_s, Z_{1s}, Z_{2s}) dN_s \right|^r \right]. \end{aligned} \quad (3.4)$$

For the jump integer, by virtue of the elementary inequality and Doob's inequality, we derive

$$\begin{aligned}
 & \mathbb{E} \left| \int_{t_k}^t X_3(s, Q_s, Z_{1s}, Z_{2s}) dN_s \right|^r \\
 &= \mathbb{E} \left| \int_{t_k}^t X_3(s, Q_s, Z_{1s}, Z_{2s}) d\bar{N}_s + \lambda \int_{t_k}^t X_3(s, Q_s, Z_{1s}, Z_{2s}) ds \right|^r \\
 &\leq 2^{r-1} \mathbb{E} \left| \int_{t_k}^t X_3(s, Q_s, Z_{1s}, Z_{2s}) d\bar{N}_s \right|^r + 2^{r-1} \mathbb{E} \left| \lambda \int_{t_k}^t X_3(s, Q_s, Z_{1s}, Z_{2s}) ds \right|^r \\
 &\leq C_2 2^{r-1} \Delta^{\frac{r}{2}-1} \int_{t_k}^t \mathbb{E} |X_3(s, Q_s, Z_{1s}, Z_{2s})|^r ds + 2^{r-1} \lambda^r \Delta^{r-1} \int_{t_k}^t \mathbb{E} |X_3(s, Q_s, Z_{1s}, Z_{2s})|^r ds.
 \end{aligned} \tag{3.5}$$

Moreover, by the well-known mean value theorem, we observe that there exists a $\theta \in (0, 1)$ such that

$$\begin{aligned}
 & \int_{t_k}^t \mathbb{E} |X_1(s, Q_s, Z_{1s}, Z_{2s})|^r ds \\
 &= \int_{t_k}^t \mathbb{E} |f(s, Q_s, Z_{2s}) - [f(s, Q_s, Z_{2s}) - X_1(s, Q_s, Z_{1s}, Z_{2s})]|^r ds \\
 &= \int_{t_k}^t \mathbb{E} \left| f(s, Q_s, Z_{2s}) - \frac{f_P^{(\alpha_1+1)}(s, Z_{1s} + \theta(Q_s - Z_{1s}), Z_{2s})}{(\alpha_1 + 1)!} (Q_s - Z_{1s})^{\alpha_1+1} \right|^r ds.
 \end{aligned}$$

Then, by the assumptions (A1), (A3), (A5), (A6) and Lemma 3.1, we obtain

$$\begin{aligned}
 & \int_{t_k}^t \mathbb{E} |X_1(s, Q_s, Z_{1s}, Z_{2s})|^r ds \\
 &\leq 2^{r-1} \int_{t_k}^t \left[\mathbb{E} (|f(s, Q_s, Z_{2s})|^2)^{\frac{r}{2}} + \frac{K_1^r}{[(\alpha_1 + 1)!]^r} \mathbb{E} |Q_s - Z_{1s}|^{(\alpha_1+1)r} \right] ds \\
 &\leq 2^{r-1} \int_{t_k}^t \left[2^{r-1} K^r \mathbb{E} (|Q_s|^r + |Z_{2s}|^r) + \frac{K_1^r 2^{(\alpha_1+1)r-1}}{[(\alpha_1 + 1)!]^r} (\mathbb{E} |Q_s|^{(\alpha_1+1)r} + |Z_{1s}|^{(\alpha_1+1)r}) \right] ds \\
 &\leq 2^{r-1} \int_{t_k}^t \left[2^r K^r K_4 + \frac{K_1^r 2^{(\alpha_1+1)r}}{[(\alpha_1 + 1)!]^r} K_4 \right] ds \\
 &\leq C_2 \Delta.
 \end{aligned} \tag{3.6}$$

In the same way as (3.6) was derived, we can show that

$$\int_{t_k}^t \mathbb{E} \|X_2(s, Q_s, Z_{1s}, Z_{2s})\|_2^r ds \leq C_3 \Delta \tag{3.7}$$

and

$$\int_{t_k}^t \mathbb{E} |X_3(s, Q_s, Z_{1s}, Z_{2s})|^r ds \leq C_4 \Delta. \tag{3.8}$$

Substituting (3.5),(3.6),(3.7) and (3.8) into (3.4) yields

$$\begin{aligned}\mathbb{E}|Q_t - Z_t|^r &\leq 5^{r-1}[K_5\Delta^r + K_4(\mu_1^0\bar{\mu})^r\Delta^r + C_2\Delta^r + C_3\Delta^{\frac{r}{2}} + C_2C_42^{r-1}\Delta^{\frac{r}{2}} + C_42^{r-1}\lambda^r\Delta^r] \\ &\leq C\Delta^{\frac{r}{2}},\end{aligned}$$

which is the required inequality (3.3).

Lemma 3.3. *Under the assumptions (A1)-(A6), Lemma 3.1 and $\mathbb{E}\left|\frac{\partial Q_s}{\partial a}\right|^r < K_5$ holds. For $2 \leq r \leq (\alpha + 1)q$, there exists a $\gamma \in (0, 1]$ such that*

$$\mathbb{E}|Q_{t-\tau} - Z_{2t}|^r \leq C\Delta^\gamma, \quad t \geq 0. \quad (3.9)$$

Proof. For any $t \geq 0$, there exists an integer $k \geq 0$ such that $t \in [t_k, t_{k+1})$. We divide the whole proof into the following three cases.

- If $-\tau \leq t_k - \tau \leq t - \tau \leq 0$. Then, by the assumption (A4), we have

$$\mathbb{E}|Q_{t-\tau} - Z_{2t}|^r = \mathbb{E}|Q_{t-\tau} - Q_{t_k-\tau}|^r = \mathbb{E}|\phi_{t-\tau} - \phi_{t_k-\tau}|^r \leq \tilde{K}\Delta^\gamma. \quad (3.10)$$

- If $0 \leq t_k - \tau \leq t - \tau$. Then, by Lemma 3.2, we have

$$\mathbb{E}|Q_{t-\tau} - Z_{2t}|^r \leq C\Delta^{\frac{r}{2}}. \quad (3.11)$$

- If $-\tau \leq t_k - \tau \leq 0 \leq t - \tau$. Then, we have

$$\mathbb{E}|Q_{t-\tau} - Z_{2t}|^r \leq 2^{r-1}\mathbb{E}|Q_{t-\tau} - \phi_0|^r + 2^{r-1}\mathbb{E}|Q_{t_k-\tau} - \phi_0|^r. \quad (3.12)$$

Then together with (3.10) and (3.11), we have the following results immediately,

$$\mathbb{E}|Q_{t-\tau} - Z_{2t}|^r \leq C(\Delta^{\frac{r}{2}} + \Delta^\gamma). \quad (3.13)$$

Summarizing the above three cases, we therefore derive that

$$\mathbb{E}|Q_{t-\tau} - Z_{2t}|^r \leq C\Delta^\gamma$$

for $2 \leq r \leq (\alpha + 1)q$ and $\gamma \in (0, 1]$, which is the desired inequality (3.9).

We can now begin to prove the following theorem which reveals the convergence of the Taylor approximate solutions to the true solutions.

Theorem 3.1. *, Let the assumptions (A₁)–(A₆) and Lemma 3.1 hold. Then for any $q \geq 2$ and $\gamma \in (0, 1]$,*

$$\mathbb{E} \sup_{0 \leq t \leq T} |P_t - Q_t|^q \leq C\Delta^\gamma. \quad (3.14)$$

Consequently

$$\lim_{\Delta \rightarrow 0} \mathbb{E}[\sup_{0 \leq t \leq T} |P_t - Q_t|^q] = 0. \quad (3.15)$$

Proof. By the (2.2) and (3.1), it is not difficult to show that

$$\begin{aligned}
 P_t - Q_t = & - \int_0^t \frac{\partial(P_s - Q_s)}{\partial a} ds - \int_0^t (\mu_e + (\mu_1^0 - \mu_e)e^{-\eta s})\mu_2(a)(P_s - Q_s)ds \\
 & + \int_{t_k}^t (f(s, P_s, P_{s-\tau}) - X_1(s, Q_s, Z_{1s}, Z_{2s}))ds \\
 & + \int_{t_k}^t (g(s, P_s, P_{s-\tau}) - X_2(s, Q_s, Z_s, Z_{2s}))dB_s \\
 & + \int_{t_k}^t (h(s, P_s, P_{s-\tau}) - X_3(s, Q_s, Z_s, Z_{2s}))dN_s.
 \end{aligned}$$

We write

$$\begin{aligned}
 e(t) &= P_t - Q_t, \\
 I_1(s) &= f(s, P_s, P_{s-\tau}) - X_1(s, Q_s, Z_{1s}, Z_{2s}), \\
 I_2(s) &= g(s, P_s, P_{s-\tau}) - X_2(s, Q_s, Z_{1s}, Z_{2s}), \\
 I_3(s) &= h(s, P_s, P_{s-\tau}) - X_3(s, Q_s, Z_{1s}, Z_{2s})
 \end{aligned}$$

for simplicity. For all $t \in [0, T]$, using Itô's formula to $|e(t)|^q$ and copying the analysis of (2.11) to (2.13), we have

$$\begin{aligned}
 |e(t)|^q \leq & \frac{(q\bar{\beta}^2 A^2 + 2\mu_1^0 \bar{\mu} q)}{2} \int_0^t |e(s)|^q ds + \int_0^t q|e(s)|^{q-1}|I_1(s)|ds \\
 & + \frac{q(q-1)}{2} \int_0^t |e(s)|^{q-2} \|I_2(s)\|_2^2 ds + \int_0^t q|e(s)|^{q-1}|I_2(s)|dB_s \\
 & + \int_0^t q|e(s)|^{q-1}|I_3(s)|d\bar{N}_s + \frac{q(q-1)}{2} \int_0^t |e(s)|^{q-2}|I_3(s)|^2 d\bar{N}_s \\
 & + \lambda q \int_0^t |e(s)|^{q-1}|I_3(s)|ds + \frac{\lambda q(q-1)}{2} \int_0^t |e(s)|^{q-2}|I_3(s)|^2 ds.
 \end{aligned}$$

The Young inequality yields

$$|a|^c |b|^d \leq |a|^{c+d} + \frac{d}{c+d} \left[\frac{c}{\varepsilon(c+d)} \right]^{\frac{c}{d}} |b|^{c+d} \quad (3.16)$$

for $\forall a, b \in R$ and $\forall c, d, \varepsilon > 0$. We hence have

$$\begin{aligned}
 & \mathbb{E} \sup_{0 \leq t \leq T} |e(t)|^q \\
 & \leq K_6 \mathbb{E} \sup_{0 \leq t \leq T} \int_0^t |e(s)|^q ds + \mathbb{E} \sup_{0 \leq t \leq T} \int_0^t q(|e(s)|^q + K_7 |I_1(s)|^q) ds \\
 & \quad + \frac{q(q-1)}{2} \mathbb{E} \sup_{0 \leq t \leq T} \int_0^t (|e(s)|^q + K_8 \|I_2(s)\|_2^q) ds \\
 & \quad + \frac{\lambda q(q-1)}{2} \mathbb{E} \sup_{0 \leq t \leq T} \int_0^t (|e(s)|^q + K_8 |I_3(s)|^q) ds. \\
 & \quad + \lambda q \mathbb{E} \sup_{0 \leq t \leq T} \int_0^t (|e(s)|^q + K_7 |I_3(s)|^q) ds \\
 & \quad + \frac{q(q-1)}{2} \mathbb{E} \sup_{0 \leq t \leq T} \int_0^t |e(s)|^{q-2} |I_3(s)|^2 d\bar{N}_s \\
 & \quad + \mathbb{E} \sup_{0 \leq t \leq T} \int_0^t q |e(s)|^{q-2} (e(s), I_2(s)) dB_s \\
 & \quad + \mathbb{E} \sup_{0 \leq t \leq T} \int_0^t q |e(s)|^{q-2} (e(s), I_3(s)) d\bar{N}_s,
 \end{aligned} \tag{3.17}$$

where $K_6 = \frac{(q\bar{\beta}^2 A^2 + 2\mu_0^0 \bar{\mu} q)}{2}$, $K_7 = \frac{1}{q} \left[\frac{q-1}{\varepsilon q} \right]^{q-1}$ and $K_8 = \frac{2}{q} \left[\frac{q-2}{\varepsilon q} \right]^{\frac{q-2}{2}}$.

Applying the Burkholder-Davis-Gundy's inequality [29] and Young inequality, we obtain that

$$\begin{aligned}
 & \mathbb{E} \sup_{0 \leq t \leq T} \int_0^t |e(s)|^{q-2} (e(s), I_2(s)) dB_s \\
 & \leq \frac{1}{6q} \mathbb{E} \left[\sup_{0 \leq t \leq T} |e(t)|^q \right] + C_1 \mathbb{E} \left(\int_0^t |e(s)|^{q-2} \|I_2(s)\|_2^2 ds \right) \\
 & \leq \frac{1}{6q} \mathbb{E} \left[\sup_{0 \leq t \leq T} |e(t)|^q \right] + C_1 \mathbb{E} \sup_{0 \leq t \leq T} \int_0^t (|e(s)|^q + K_8 \|I_2(s)\|_2^q) ds.
 \end{aligned} \tag{3.18}$$

Continuing this approach, we have

$$\begin{aligned}
 & \mathbb{E} \sup_{0 \leq t \leq T} \int_0^t |e(s)|^{q-2} (e(s), I_3(s)) d\bar{N}_s \\
 & \leq \frac{1}{6q} \mathbb{E} \left[\sup_{0 \leq t \leq T} |e(t)|^q \right] + C_2 \mathbb{E} \sup_{0 \leq t \leq T} \int_0^t (|e(s)|^q + K_8 |I_3(s)|^q) ds
 \end{aligned} \tag{3.19}$$

and

$$\begin{aligned}
 & \mathbb{E} \sup_{0 \leq t \leq T} \int_0^t |e(s)|^{q-2} |I_3(s)|^2 d\bar{N}_s \\
 & \leq \frac{1}{3q(q-1)} \mathbb{E} \left[\sup_{0 \leq t \leq T} |e(t)|^q \right] + C_3 \mathbb{E} \sup_{0 \leq t \leq T} \int_0^t (|e(s)|^q + K_9 |I_3(s)|^q) ds,
 \end{aligned} \tag{3.20}$$

where $K_9 = \frac{4}{q} \left[\frac{q-4}{\varepsilon q} \right]^{\frac{q-4}{4}}$.

Next, under the assumptions (A_3) , (A_6) , Lemma 3.2 and Lemma 3.3, we then compute

$$\begin{aligned}
 & \mathbb{E} \sup_{0 \leq t \leq T} \int_0^t |I_1(s)|^q ds \\
 &= \mathbb{E} \sup_{0 \leq t \leq T} \int_0^t |f(s, P_s, P_{s-\tau}) - X_1(s, Q_s, Z_{1s}, Z_{2s})|^q ds \\
 &= \mathbb{E} \sup_{0 \leq t \leq T} \int_0^t |f(s, P_s, P_{s-\tau}) - f(s, Q_s, Z_{2s}) + f(s, Q_s, Z_{2s}) - X_1(s, Q_s, Z_{1s}, Z_{2s})|^q ds \\
 &\leq 2^{q-1} \mathbb{E} \left[\int_0^T (|f(s, P_s, P_{s-\tau}) - f(s, Q_s, Z_{2s})|^q + |f(s, Q_s, Z_{2s}) - X_1(s, Q_s, Z_{1s}, Z_{2s})|^q) ds \right] \quad (3.21) \\
 &\leq 2^{q-1} \left[2^{2q-2} K^q \int_0^T \mathbb{E} (|P_s - Q_s|^q + |P_{s-\tau} - Q_{s-\tau}|^q + |Q_{s-\tau} - Z_{2s}|^q) ds \right. \\
 &\quad \left. + \int_0^T \mathbb{E} \left| \frac{f_P^{(\alpha_1+1)}(s, Z_{1s} + \theta(Q_s - Z_{1s}), Z_{2s})}{(\alpha_1 + 1)!} (Q_s - Z_{1s})^{\alpha_1+1} \right|^q ds \right] \\
 &\leq 2^{3q-2} K^q \left[\int_0^T \mathbb{E} \sup_{0 \leq u \leq s} |e(u)|^q ds \right] + 2^{3q-3} K^q TC \Delta^\gamma + \frac{2^{q-1} K_1^q TC}{[(\alpha_1 + 1)!]^q} \Delta^{\frac{(\alpha_1+1)q}{2}}.
 \end{aligned}$$

Moreover, we can similarly compute

$$\begin{aligned}
 & \mathbb{E} \sup_{0 \leq t \leq T} \int_0^t |I_2(s)|^q ds \\
 &= \mathbb{E} \sup_{0 \leq t \leq T} \int_0^t \|(g(s, P_s, P_{s-\tau}) - X_2(s, Q_s, Z_{1s}, Z_{2s}))\|_2^q ds \quad (3.22) \\
 &\leq 2^{3q-2} K^q \left[\int_0^T \mathbb{E} \sup_{0 \leq u \leq s} |e(u)|^q ds \right] + 2^{3q-3} K^q TC \Delta^\gamma + \frac{2^{q-1} K_2^q TC}{[(\alpha_2 + 1)!]^q} \Delta^{\frac{(\alpha_2+1)q}{2}}
 \end{aligned}$$

and

$$\begin{aligned}
 & \mathbb{E} \sup_{0 \leq t \leq T} \int_0^t |I_3(s)|^q ds \\
 &= \mathbb{E} \sup_{0 \leq t \leq T} \int_0^t |h(s, P_s, P_{s-\tau}) - X_3(s, Q_s, Z_{1s}, Z_{2s})|^q ds \quad (3.23) \\
 &\leq 2^{3q-2} K^q \left[\int_0^T \mathbb{E} \sup_{0 \leq u \leq s} |e(u)|^q ds \right] + 2^{3q-3} K^q TC \Delta^\gamma + \frac{2^{q-1} K_3^q TC}{[(\alpha_3 + 1)!]^q} \Delta^{\frac{(\alpha_3+1)q}{2}}.
 \end{aligned}$$

Substituting (3.18) to (3.23) into (3.17) we obtain that

$$\mathbb{E} \sup_{0 \leq t \leq T} |e(t)|^q \leq C \Delta^{\frac{(\alpha+1)q}{2}} + C \Delta^\gamma + C \int_0^t \mathbb{E} \sup_{0 \leq u \leq s} |e(u)|^q ds$$

and the required result (3.14) and (3.15) follows from the Gronwall inequality.

4. Numerical simulation

In this section, we present some numerical experiments to demonstrate the theoretical result. Let us consider the following age-dependent stochastic delay population equations with OU process and Poisson jumps:

$$\begin{cases} d_t P_t = \left[-\frac{\partial P_t}{\partial a} - (0.65 + (0.5 - 0.65)e^{-0.75t})\frac{1}{1-a}P_t + f(t, P_t, P_{t-1}) \right] dt \\ \quad + g(t, P_t, P_{t-1})dB_t + h(t, P_t, P_{t-1})dN_t, & (t, a) \in (0, 1) \times (0, 1), \\ P(t, a) = \exp\left(\frac{-1}{1-a}\right), & (t, a) \in [-1, 0] \times [0, 1], \\ P(t, 0) = \int_0^A \frac{1}{(1-a)^2} P(t, a) da, & t \in [0, 1], \end{cases} \quad (4.1)$$

where $A = 1$, $T = 1$, $\tau = 1$, $\mu_e = 0.65$, $\mu_1^0 = 0.5$, $\eta = 0.75$, $\mu_2(a) = \frac{1}{1-a}$, B_t is a scalar Brownian motion, N_t is a Poisson process with intensity $\lambda = 1$, $\phi(t, a) = \exp\left(\frac{-1}{1-a}\right)$ and $\beta(t, a) = \frac{1}{(1-a)^2}$.

Now, we employ MATLAB for numerical simulations. First, we compare the convergence speed of the Taylor approximation scheme and backward Euler methods (BEM) mentioned in [30]. Let $T = 1$, $\Delta t = 5 \times 10^{-4}$ and $\Delta a = 0.05$. For f , g and h of model (4.1), we choose three different groups of functions as examples. Obviously, it is easy to verify that assumptions (A1) – (A6) are satisfied. By averaging over all of the 500 samples, on the computer running at Intel Core i5-4570 CPU 3.20 GHz, the runtimes of the Taylor approximation scheme (where f , g and h are approximated up to the 5th order) and the backward Euler methods for model (4.1) are given in Table 1.

Table 1. Runtimes for the Taylor approximation scheme and backward Euler method.

$f(t, P_t, P_{t-\tau})$	$g(t, P_t, P_{t-\tau})$	$h(t, P_t, P_{t-\tau})$	Taylor approximation	BEM
$\sin 2P_t + \frac{1}{4} \sin 4P_{t-1}$	$\sqrt{P_t^2 + 1} + P_{t-1}$	$\sin P_t - P_{t-1}$	17.561282	29.227642
$\exp P_t + \sqrt{P_{t-1}^2 - 1}$	$(\ln P_t)^{-1} - P_{t-1}^2$	$\cos P_t + \sin^2 P_{t-1}$	19.325948	31.497162
$-2P_t \ln P_t + P_{t-1}^2$	$\sin^3 P_t \cos P_t + P_{t-1}$	$-2P_t \sqrt{-\ln P_t} + 1$	25.367845	34.894251

Form the fist group f , g and h functions in Table 1, we observe that the runtime of the Taylor approximation scheme (3.1) is about 17.561282 seconds while the runtime of backward Euler method is about 29.227642 seconds on the same computer, and conclude that the convergence speed of the Taylor approximation scheme is 1.664 times faster than that of the backward Euler methods. As the theoretical results, Table 1 reveals that the rate of convergence for the Taylor approximation scheme is faster than the backward Euler methods.

Next, we explore the convergence of the Taylor approximation scheme (3.1). By Theorem 3.1, we obtain that the numerical solution of the Taylor approximation scheme will converge to the exact solution with $\frac{\gamma}{q}$, where $\gamma \in (0, 1]$ and $q \geq 2$. Since the age-dependent stochastic delay population equations with OU process and Poisson jumps (4.1) cannot be solved analytically, we use more precise numerical solutions to obtain the exact solution. We take $T = 1$, $\Delta t = 0.005$, $\Delta a = 0.05$, $f(t, P_t, P_{t-\tau}) = \sin 2P_t + \frac{1}{4} \sin 4P_{t-1}$, $g(t, P_t, P_{t-\tau}) = \sqrt{P_t^2 + 1} + P_{t-1}$ and $h(t, P_t, P_{t-\tau}) = \sin P_t - P_{t-1}$. Based on [5], the “explicit solutions” $P(t, a)$ to model (4.1) can be given by the numerical solution of the $SS\theta$ method with $\theta = 0.2$.

Table 2. Error simulation between $P(t, a)$ and $Q(t, a)$ at different values of Δa , x , and Δt .

(a) $x = 10, \Delta t = 0.005$					
Δa	0.04	0.05	0.2	0.25	0.5
$(P(t, a) - Q(t, a))^2$	0.03	0.04	0.07	0.08	0.2
(b) $\Delta t = 0.005, \Delta a = 0.05$					
x	5	8	10	20	50
$(P(t, a) - Q(t, a))^2$	0.08	0.07	0.04	0.01	0.005
(c) $x = 10, \Delta a = 0.05$					
Δt	0.005	0.001	0.0005	0.0001	0.00005
$(P(t, a) - Q(t, a))^2$	0.04	0.04	0.03	0.02	0.01

In Figure 1, we show the paths of the “explicit solutions” $P(t, a)$, the numerical solution $Q(t, a)$ of the Taylor approximation scheme (where f , g and h approximated up to the 10th order) and error simulations between them. In Figure 2, the relative difference between “explicit solutions” $P(t, a)$ and numerical solutions $Q(t, a)$ is presented. Moreover, we can see that the maximum value of the error square is less than 0.04 from Figure 1 and the maximum value of the the relative difference is less than 0.2 from Figure 2. Clearly the numerical solution $Q(t, a)$ converge to exact solution in the mean sense.

To further demonstrate the convergence of the Taylor approximation scheme, we show the errors between the “explicit solutions” $P(t, a)$ and numerical solutions $Q(t, a)$ at different values of time step Δt , expansion order x and age step Δa in Table 2. Table 2(a) shows that for fixed expansion order $x = 10$ and time step $\Delta t = 0.005$, the corresponding value of $(P(t, a) - Q(t, a))^2$ when Δa take 0.04, 0.05, 0.2, 0.25 and 0.5, separately. In Table 2(b), for Taylor approximations of the coefficients f , g and h , we choose the expansion order to take 5, 8, 10, 15 and 20, separately. Then the values of $(P(t, a) - Q(t, a))^2$ are given. In Table 2(c), for fixed expansion order $x = 10$ and age step $\Delta a = 0.05$, we give the corresponding value of $(P(t, a) - Q(t, a))^2$ when Δt take 0.005, 0.001, 0.0005, 0.0001 and 0.00005, separately. To illustrate our results more succinctly and forcefully, we use log-log plot Figure 3(a)–(c) to simulate the data of Table 2(a)–(c), respectively. In Figure 3(a), when expansion order $x = 10$ and time step $\Delta t = 0.005$, as the value of age step Δa increases, the value of $(P(t, a) - Q(t, a))^2$ increases. In Figure 3(b), as one would expect, as the expansion order increases, the value of $(P(t, a) - Q(t, a))^2$ is getting smaller with time step $\Delta t = 0.005$, age step $\Delta a = 0.05$. From Figure 3(c), it clearly reveals the fact that for fixed expansion order $x = 10$ and age step $\Delta a = 0.05$, the value of $(P(t, a) - Q(t, a))^2$ will tend to decrease when the increments of time Δt smaller. Thus, based on the above numerical analysis, we conclude that the Taylor approximation scheme is a simple and efficient numerical method for the age-dependent stochastic delay population equations with OU process and Poisson jumps.

5. Concluding remarks

This paper discuss a Taylor approximation scheme for a class of stochastic age-dependent population equations. In order to obtain a more realistic and improved model compared to those in the literature [1–9, 11], we introduce the mean-reverting Ornstein-Uhlenbeck (OU) process, time delay

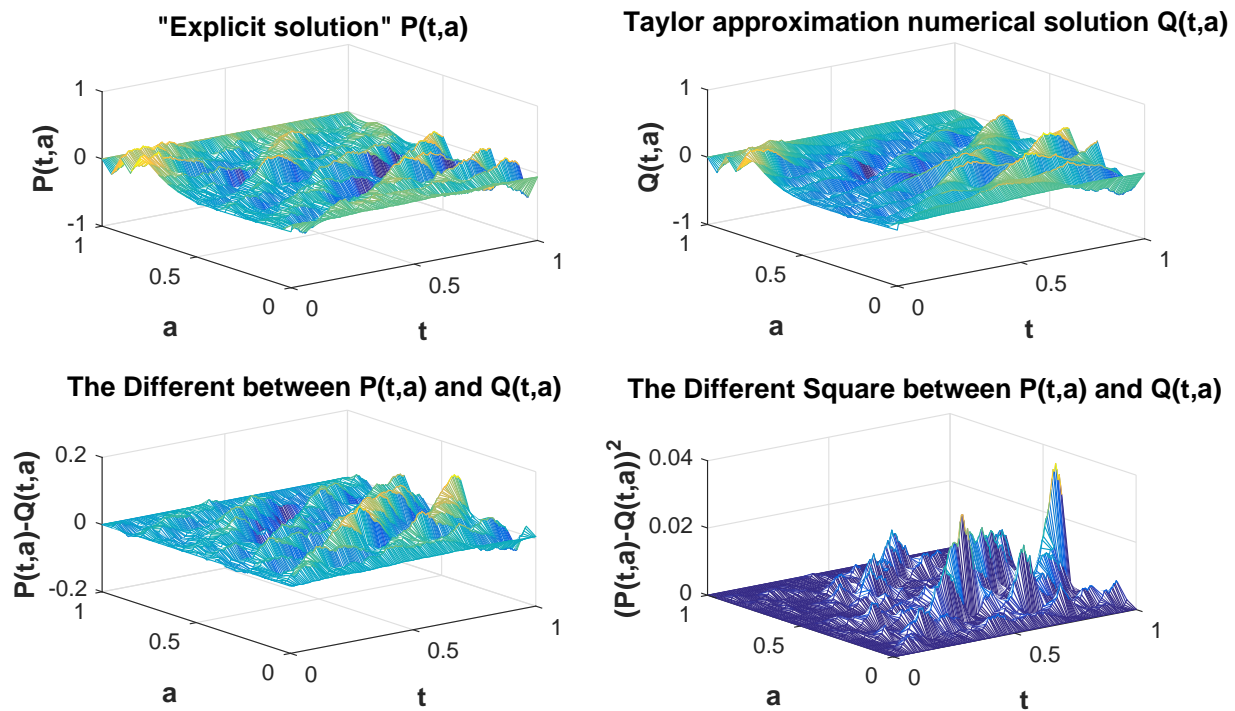


Figure 1. The upper left corner shows the path of the “explicit solutions” $P(t,a)$. The upper right corner displays the path of the Taylor approximation of solution of $Q(t,a)$. The lower left and lower right diagrams represent mean and mean-square error simulations between “explicit solutions” $P(t,a)$ and numerical solutions $Q(t,a)$ based on the Taylor approximation, respectively.

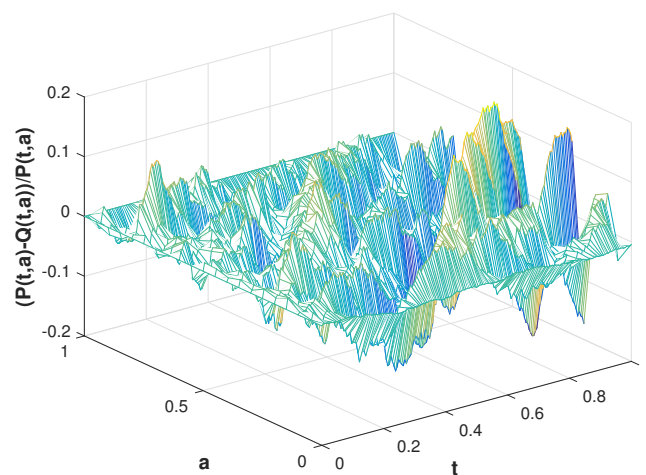


Figure 2. The relative difference between “explicit solutions” $P(t,a)$ and numerical solutions $Q(t,a)$.

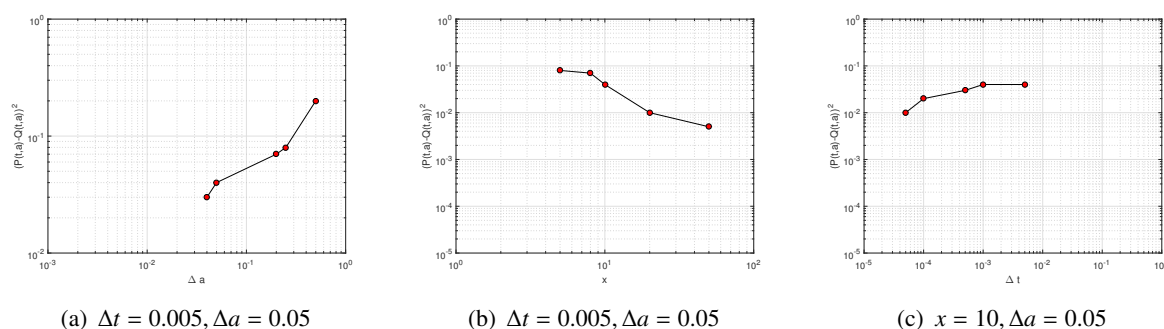


Figure 3. Error simulation between $P(t, a)$ and $Q(t, a)$ at different values of order Δa , x , and Δt .

and Poisson jumps into equation and form a new system (2.7). We investigate the p th moments boundedness of exact solutions of age-dependent stochastic delay population equations with mean-reverting OU process and Poisson jumps (2.7). When the drift and diffusion coefficients satisfies Taylor approximations, we construct a Taylor approximation scheme for Eq (2.7) and reveal that the Taylor approximation solutions converge to the exact solutions for the equations. Furthermore, we estimate the order of the convergence. We also utilize a numerical example to confirm our theoretical results. In our future work, we will consider the effect of variable delay for stochastic age-dependent population equations and investigate the convergence of numerical methods for stochastic age-dependent population equations with OU process and variable delay.

Acknowledgements

The authors are very grateful to the anonymous reviewers for their insightful comments and helpful suggestions. This research was funded by the “Major Innovation Projects for Building First-class Universities in China’s Western Region” (ZKZD2017009).

Conflict of interest

All authors declare no conflicts of interest in this paper.

References

1. R. Li, W. Pang, Q. Wang, Numerical analysis for stochastic age-dependent population equations with Poisson jumps, *J. Math. Anal. Appl.*, **327** (2007), 1214–1224.
2. W. Ma, Q. Zhang, J. Gao, The existence and uniqueness of solutions to stochastic age-dependent population equations with jumps, *Chin. J. Appl. Probab. Stat.*, **32** (2016), 441–451.
3. L. Wang, X. Wang, Convergence of the semi-implicit Euler method for stochastic age-dependent population equations with Poisson jumps, *Appl. Math. Model.*, **34** (2010), 2034–2043.
4. A. Rathinasamy, B. Yin, B. Yasodha, Numerical analysis for stochastic age-dependent population equations with Poisson jump and phase semi-Markovian switching, *Commun. Nonlinear Sci. Numer. Simul.*, **16** (2011), 350–362.

5. J. Tan, A. Rathinasamy, Y. Pei, Convergence of the split-step method for stochastic age-dependent population equations with Poisson jumps, *Appl. Math. Comput.*, **254** (2015), 305–317.
6. H. Chen, Existence and uniqueness, attraction for stochastic age-structured population systems with diffusion and Poisson jump, *J. Math. Phys.*, **54** (2013), 082701.
7. M. Wei, Exponential stability of numerical solutions to stochastic age-dependent population equations with Poisson jumps, *Engin. Tech.*, **55** (2011), 1103–1108.
8. Y. Pei, H. Yang, Q. Zhang, F. Shen, Asymptotic mean-square boundedness of the numerical solutions of stochastic age-dependent population equations with Poisson jumps, *Appl. Math. Comput.*, **320** (2018), 524–534.
9. W. Ma, Q. Zhang, Convergence of numerical solutions to stochastic age-dependent population equations with Poisson jumps and Markovian switching, *J. Shanxi Univ.*, **2011** (2011).
10. S. Zhao, S. Yuan, H. Wang, Threshold behavior in a stochastic algal growth model with stoichiometric constraints and seasonal variation, *J. Differ. Equ.*, **2019** (2019).
11. B. Wang, J. Sun, B. Huang, The model analysis for stochastic age-dependent population with Poisson Jumps, *Int. Inst. Appl. Stat. Stud.*, **2008** (2008).
12. W. Li, Q. Zhang, Construction of positivity-preserving numerical method for stochastic SIVS epidemic model, *Adv. Differ. Equ.*, **2019** (2019).
13. Y. Li, M. Ye, Q. Zhang, Strong convergence of the partially truncated Euler Maruyama scheme for a stochastic age-structured SIR epidemic model, *Appl. Math. Comput.*, **362** (2019), 124519.
14. D. Duffie, *Dynamic asset pricing theory*, Princeton University Press, (2010.)
15. E. Allen, Environmental variability and mean-reverting processes, *Discrete Contin. Dyn. Syst. Ser. B*, **21** (2016), 2073.
16. Y. Zhao, S. Yuan, J. Ma, Survival and stationary distribution analysis of a stochastic competitive model of three species in a polluted environment, *Bull. Math. Biol.*, **77** (2015), 1285–1326.
17. W. Wang, Y. Cai, Z. Ding, Z. Gui, A stochastic differential equation SIS epidemic model incorporating Ornstein-Uhlenbeck process, *Phys. A*, **509** (2018), 921–936.
18. Y. Cai, J. Jiao, Z. Gui, Y. Liu, W. Wang, Environmental variability in a stochastic epidemic model, *Appl. Math. Comput.*, **329** (2018), 210–226.
19. S. Deng, W. Fei, Y. Liang, X. Mao, Convergence of the split-step-method for stochastic age-dependent population equations with Markovian switching and variable delay, *Appl. Numer. Math.*, **139** (2019), 15–37.
20. Q. Li, Q. Zhang, B. Cao, Mean-square stability of stochastic age-dependent delay population systems with jumps, *Acta Math. Appl. Sin.*, **34** (2018), 145–154.
21. J. Tan, W. Men, Y. Pei, Y. Guo, Construction of positivity preserving numerical method for stochastic age-dependent population equations, *Appl. Math. Comput.*, **293** (2017), 57–64.
22. F. Jiang, Y. Shen, L. Liu, Taylor approximation of the solutions of stochastic differential delay equations with Poisson jump, *Commun. Nonlinear Sci. Numer. Simul.*, **16** (2011), 798–804.
23. X. Yu, S. Yuan, T. Zhang, Asymptotic properties of stochastic nutrient-plankton food chain models with nutrient recycling, *Nonlinear Anal. Hybrid Syst.*, **34** (2019), 209–225.

24. S. Jankovic, D. Ilic, An analytic approximation of solutions of stochastic differential equations, *Comput. Math. Appl.*, **47** (2004), 903–912.
25. A. Ivanov, Y. Kazmerchuk, A. Swishchuk, Theory, stochastic stability and applications of stochastic delay differential equations: A survey of results, *Differ. Equ. Dyna. Syst.*, **11** (2003), 55–115.
26. Q. Zhang, W. Liu, Z. Nie, Existence, uniqueness and exponential stability for stochastic age-dependent population, *Appl. Math. Comput.*, **154** (2004), 183–201.
27. R. Li, H. Meng, Y. Dai, Convergence of numerical solutions to stochastic delay differential equations with jumps, *Appl. Math. Comput.*, **172** (2006), 584–602.
28. L. Wang, C. Mei, H. Xue, The semi-implicit Euler method for stochastic differential delay equation with jumps, *Appl. Math. Comput.*, **192** (2007), 567–578.
29. S. Anita, *Analysis and control of age-dependent population dynamics*, Springer Science & Business Media, (2000).
30. D. Higham, P. Kloeden, Strong convergence rates for backward Euler on a class of nonlinear jump-diffusion problems, *J. Comput. Appl. Math.*, **205** (2007), 949–956.
31. I. Bihari, A generalization of a lemma of Bellman and its application to uniqueness problems of differential equations, *Acta Math. Hungarica*, **7** (1956), 81–94.

Appendix A

Proof of Lemma 3.1. For the purpose of simplification, let $l = (\alpha + 1)^2q$. Applying Itô's formula to $|Q_t|^l$, we have

$$\begin{aligned}
|Q_t|^l &= |Q_0|^l + \int_0^t l|Q_s|^{l-2} \left\langle -\frac{\partial Q_s}{\partial a} - (\mu_e + (\mu_1^0 - \mu_e)e^{-\eta s})\mu_2(a)Q_s, Q_s \right\rangle ds \\
&\quad + \int_0^t l|Q_s|^{l-2} \left(\sum_{j=0}^{\alpha_1} \frac{f_{Z_{1s}}^{(j)}(s, Z_{1s}, Z_{2s})}{j!} (Q_s - Z_{1s})^j, Q_s \right) ds \\
&\quad + \int_0^t \frac{l(l-1)}{2} |Q_s|^{l-2} \left\| \sum_{j=0}^{\alpha_2} \frac{g_{Z_{1s}}^{(j)}(s, Z_{1s}, Z_{2s})}{j!} (Q_s - Z_{1s})^j \right\|_2^2 ds \\
&\quad + \int_0^t l|Q_s|^{l-2} \left(Q_s, \sum_{j=0}^{\alpha_2} \frac{g_{Z_{1s}}^{(j)}(s, Z_{1s}, Z_{2s})}{j!} (Q_s - Z_{1s})^j \right) dB_s \\
&\quad + \int_0^t l|Q_s|^{l-2} \left(Q_s, \sum_{j=0}^{\alpha_3} \frac{h_{Z_{1s}}^{(j)}(s, Z_{1s}, Z_{2s})}{j!} (Q_s - Z_{1s})^j \right) dN_s \\
&\quad + \int_0^t \frac{l(l-1)}{2} |Q_s|^{l-2} \left\| \sum_{j=0}^{\alpha_3} \frac{h_{Z_{1s}}^{(j)}(s, Z_{1s}, Z_{2s})}{j!} (Q_s - Z_{1s})^j \right\|_2^2 dN_s \\
&= |Q_0|^l + \int_0^t l|Q_s|^{l-2} \left\langle -\frac{\partial Q_s}{\partial a} - (\mu_e + (\mu_1^0 - \mu_e)e^{-\eta s})\mu_2(a)Q_s, Q_s \right\rangle ds \\
&\quad + \int_0^t l|Q_s|^{l-2} \left(\sum_{j=0}^{\alpha_1} \frac{f_{Z_{1s}}^{(j)}(s, Z_{1s}, Z_{2s})}{j!} (Q_s - Z_{1s})^j, Q_s \right) ds \\
&\quad + \int_0^t \frac{l(l-1)}{2} |Q_s|^{l-2} \left\| \sum_{j=0}^{\alpha_2} \frac{g_{Z_{1s}}^{(j)}(s, Z_{1s}, Z_{2s})}{j!} (Q_s - Z_{1s})^j \right\|_2^2 ds \\
&\quad + \int_0^t l|Q_s|^{l-2} \left(Q_s, \sum_{j=0}^{\alpha_2} \frac{g_{Z_{1s}}^{(j)}(s, Z_{1s}, Z_{2s})}{j!} (Q_s - Z_{1s})^j \right) dB_s \\
&\quad + \int_0^t l|Q_s|^{l-2} \left(Q_s, \sum_{j=0}^{\alpha_3} \frac{h_{Z_{1s}}^{(j)}(s, Z_{1s}, Z_{2s})}{j!} (Q_s - Z_{1s})^j \right) d\bar{N}_s \\
&\quad + \lambda \int_0^t l|Q_s|^{l-2} \left(Q_s, \sum_{j=0}^{\alpha_3} \frac{h_{Z_{1s}}^{(j)}(s, Z_{1s}, Z_{2s})}{j!} (Q_s - Z_{1s})^j \right) ds \\
&\quad + \int_0^t \frac{l(l-1)}{2} |Q_s|^{l-2} \left\| \sum_{j=0}^{\alpha_3} \frac{h_{Z_{1s}}^{(j)}(s, Z_{1s}, Z_{2s})}{j!} (Q_s - Z_{1s})^j \right\|_2^2 d\bar{N}_s \\
&\quad + \lambda \int_0^t \frac{l(l-1)}{2} |Q_s|^{l-2} \left\| \sum_{j=0}^{\alpha_3} \frac{h_{Z_{1s}}^{(j)}(s, Z_{1s}, Z_{2s})}{j!} (Q_s - Z_{1s})^j \right\|_2^2 ds,
\end{aligned} \tag{5.1}$$

where $\bar{N}_s = N_s - \lambda s$ is a compensated Poisson process. Since

$$\begin{aligned} -\left\langle \frac{\partial Q_s}{\partial a}, Q_s \right\rangle &= -\int_0^A Q_s d_a(Q_s) = \frac{1}{2} \left(\int_0^A \beta(t, a) Q_s da \right)^2 \\ &\leq \frac{1}{2} \int_0^A \beta^2(t, a) da \int_0^A Q_s^2 da \\ &\leq \frac{1}{2} \bar{\beta}^2 A^2 |Q_s|^2, \end{aligned} \quad (5.2)$$

by the assumptions (A1)-(A3), we get that

$$\begin{aligned} |Q_t|^l &\leq |Q_0|^l + l \left(\frac{\bar{\beta}^2 A^2}{2} + \mu_1^0 \bar{\mu} \right) \int_0^t |Q_s|^l ds \\ &\quad + \int_0^t l |Q_s|^{l-2} \left(\sum_{j=0}^{\alpha_1} \frac{f_{Z_{1s}}^{(j)}(s, Z_{1s}, Z_{2s})}{j!} (Q_s - Z_{1s})^j, Q_s \right) ds \\ &\quad + \int_0^t \frac{l(l-1)}{2} |Q_s|^{l-2} \left\| \sum_{j=0}^{\alpha_2} \frac{g_{Z_{1s}}^{(j)}(s, Z_{1s}, Z_{2s})}{j!} (Q_s - Z_{1s})^j \right\|_2^2 ds \\ &\quad + \int_0^t l |Q_s|^{l-2} (Q_s, \sum_{j=0}^{\alpha_2} \frac{g_{Z_{1s}}^{(j)}(s, Z_{1s}, Z_{2s})}{j!} (Q_s - Z_{1s})^j) dB_s \\ &\quad + \int_0^t l |Q_s|^{l-2} (Q_s, \sum_{j=0}^{\alpha_3} \frac{h_{Z_{1s}}^{(j)}(s, Z_{1s}, Z_{2s})}{j!} (Q_s - Z_{1s})^j) d\bar{N}_s \\ &\quad + \lambda \int_0^t l |Q_s|^{l-2} (Q_s, \sum_{j=0}^{\alpha_3} \frac{h_{Z_{1s}}^{(j)}(s, Z_{1s}, Z_{2s})}{j!} (Q_s - Z_{1s})^j) ds \\ &\quad + \int_0^t \frac{l(l-1)}{2} |Q_s|^{l-2} \left| \sum_{j=0}^{\alpha_3} \frac{h_{Z_{1s}}^{(j)}(s, Z_{1s}, Z_{2s})}{j!} (Q_s - Z_{1s})^j \right|^2 d\bar{N}_s \\ &\quad + \lambda \int_0^t \frac{l(l-1)}{2} |Q_s|^{l-2} \left| \sum_{j=0}^{\alpha_3} \frac{h_{Z_{1s}}^{(j)}(s, Z_{1s}, Z_{2s})}{j!} (Q_s - Z_{1s})^j \right|^2 ds. \end{aligned} \quad (5.3)$$

Using the well-known mean value theorem, we derive that there exists a $\theta \in (0, 1)$ such that

$$\begin{aligned} &|Q_t|^l \\ &\leq |Q_0|^l + l \left(\frac{\bar{\beta}^2 A^2}{2} + \mu_1^0 \bar{\mu} \right) \int_0^t |Q_s|^l ds + \int_0^t l |Q_s|^{l-2} (f(s, Q_s, Z_{2s}) \\ &\quad - \frac{f_{Z_{1s}}^{(\alpha_1+1)}(s, Z_{1s} + \theta(Q_s - Z_{1s}), Z_{2s})}{(\alpha_1 + 1)!} (Q_s - Z_{1s})^{\alpha_1+1}, Q_s) ds \\ &\quad + \int_0^t \frac{l(l-1)}{2} |Q_s|^{l-2} \left\| g(s, Q_s, Z_{2s}) - \frac{g_{Z_{1s}}^{(\alpha_2+1)}(s, Z_{1s} + \theta(Q_s - Z_{1s}), Z_{2s})}{(\alpha_2 + 1)!} (Q_s - Z_{1s})^{\alpha_2+1} \right\|_2^2 ds \end{aligned}$$

$$\begin{aligned}
& + \int_0^t l|Q_s|^{l-2} (Q_s, g(s, Q_s, Z_{2s}) - \frac{g_{Z_{1s}}^{(\alpha_2+1)}(s, Z_{1s} + \theta(Q_s - Z_{1s}), Z_{2s})}{(\alpha_2 + 1)!} (Q_s - Z_{1s})^{\alpha_2+1}) dB_s \\
& + \int_0^t l|Q_s|^{l-2} (Q_s, h(s, Q_s, Z_{2s}) - \frac{h_{Z_{1s}}^{(\alpha_3+1)}(s, Z_{1s} + \theta(Q_s - Z_{1s}), Z_{2s})}{(\alpha_3 + 1)!} (Q_s - Z_{1s})^{\alpha_3+1}) d\bar{N}_s \\
& + \lambda \int_0^t l|Q_s|^{l-2} (Q_s, h(s, Q_s, Z_{2s}) - \frac{h_{Z_{1s}}^{(\alpha_3+1)}(s, Z_{1s} + \theta(Q_s - Z_{1s}), Z_{2s})}{(\alpha_3 + 1)!} (Q_s - Z_{1s})^{\alpha_3+1}) ds \\
& + \int_0^t \frac{l(l-1)}{2} |Q_s|^{l-2} |h(s, Q_s, Z_{2s}) - \frac{h_{Z_{1s}}^{(\alpha_3+1)}(s, Z_{1s} + \theta(Q_s - Z_{1s}), Z_{2s})}{(\alpha_3 + 1)!} (Q_s - Z_{1s})^{\alpha_3+1}|^2 d\bar{N}_s \\
& + \lambda \int_0^t \frac{l(l-1)}{2} |Q_s|^{l-2} |h(s, Q_s, Z_{2s}) - \frac{h_{Z_{1s}}^{(\alpha_3+1)}(s, Z_{1s} + \theta(Q_s - Z_{1s}), Z_{2s})}{(\alpha_3 + 1)!} (Q_s - Z_{1s})^{\alpha_3+1}|^2 ds.
\end{aligned} \tag{5.4}$$

Denotes

$$\begin{aligned}
H_1(s, Q_s, Z_{1s}, Z_{2s}) &= f_{Z_{1s}}^{(\alpha_1+1)}(s, Z_{1s} + \theta(Q_s - Z_{1s}), Z_{2s}), \\
H_2(s, Q_s, Z_{1s}, Z_{2s}) &= g_{Z_{1s}}^{(\alpha_2+1)}(s, Z_{1s} + \theta(Q_s - Z_{1s}), Z_{2s}), \\
H_3(s, Q_s, Z_{1s}, Z_{2s}) &= h_{Z_{1s}}^{(\alpha_3+1)}(s, Z_{1s} + \theta(Q_s - Z_{1s}), Z_{2s}).
\end{aligned}$$

Therefore, we obtain that

$$\begin{aligned}
& \int_0^t l|Q_s|^{l-2} (f(s, Q_s, Z_{2s}) - \frac{H_1(s, Q_s, Z_{1s}, Z_{2s})}{(\alpha_1 + 1)!} (Q_s - Z_{1s})^{\alpha_1+1}, Q_s) ds \\
& + \int_0^t \frac{l(l-1)}{2} |Q_s|^{l-2} \|g(s, Q_s, Z_{2s}) - \frac{H_2(s, Q_s, Z_{1s}, Z_{2s})}{(\alpha_2 + 1)!} (Q_s - Z_{1s})^{\alpha_2+1}\|_2^2 ds \\
& + \lambda \int_0^t l|Q_s|^{l-2} (Q_s, h(s, Q_s, Z_{2s}) - \frac{H_3(s, Q_s, Z_{1s}, Z_{2s})}{(\alpha_3 + 1)!} (Q_s - Z_{1s})^{\alpha_3+1}) ds \\
& + \lambda \int_0^t \frac{l(l-1)}{2} |Q_s|^{l-2} |h(s, Q_s, Z_{2s}) - \frac{H_3(s, Q_s, Z_{1s}, Z_{2s})}{(\alpha_3 + 1)!} (Q_s - Z_{1s})^{\alpha_3+1}|^2 ds \\
& \leq \int_0^t l|Q_s|^{l-2} (K(\|Q_s\| + \|Z_{2s}\|) + \frac{K_1}{(\alpha_1 + 1)!} \|2Q_s\|^{\alpha_1+1}, Q_s) ds \\
& + \int_0^t l(l-1)|Q_s|^{l-2} (2K^2\|Q_s\|^2 + (\frac{K_2}{(\alpha_2 + 1)!} 2^{\alpha_2+1})^2 \|Q_s\|^{2\alpha_2+2}) ds \\
& + \lambda \int_0^t l(l-1)|Q_s|^{l-2} (2K^2\|Q_s\|^2 + (\frac{K_3}{(\alpha_3 + 1)!} 2^{\alpha_3+1})^2 \|Q_s\|^{2\alpha_3+2}) ds \\
& + \lambda \int_0^t l|Q_s|^{l-2} (K(\|Q_s\| + \|Z_{2s}\|) + \frac{K_3}{(\alpha_3 + 1)!} \|2Q_s\|^{\alpha_3+1}, Q_s) ds \\
& \leq (1 + \lambda) \int_0^t l|Q_s|^{l-2} (2K\|Q_s\|^2 + \frac{K_1}{(\alpha_1 + 1)!} 2^{\alpha_1+1} \|Q_s\|^{\alpha_1+2}) ds \\
& + (1 + \lambda) \int_0^t (2l(l-1)K^2|Q_s|^l + l(l-1)(\frac{C}{(\bar{\alpha} + 1)!} 2^{\alpha_1+1})^2 \|Q_s\|^{l+2\alpha}) ds \\
& \leq (1 + \lambda) \int_0^t ((2lK + 2l(l-1)K^2)|Q_s|^l + (\frac{lK_1}{(\alpha_1 + 1)!} 2^{\alpha_1+1} \\
& + l(l-1)(\frac{C}{(\bar{\alpha} + 1)!} 2^{\alpha_1+1})^2) \|Q_s\|^{l+2\alpha}) ds,
\end{aligned} \tag{5.5}$$

where $\bar{\alpha} = \min\{\alpha_1, \alpha_2, \alpha_3\}$.

By the Burkholder-Davis-Gundy's inequality, we then have

$$\begin{aligned}
& \mathbb{E} \left[\sup_{0 \leq s \leq t} \int_0^s |Q_s|^{l-2} \left(Q_s, g(s, Q_s, Z_{2s}) - \frac{H_2(s, Q_s, Z_{1s}, Z_{2s})}{(\alpha_2 + 1)!} (Q_s - Z_{1s})^{\alpha_2+1} \right) dB_s \right] \\
& + \mathbb{E} \left[\sup_{0 \leq s \leq t} \int_0^s |Q_s|^{l-2} \left(Q_s, h(s, Q_s, Z_{2s}) - \frac{H_3(s, Q_s, Z_{1s}, Z_{2s})}{(\alpha_3 + 1)!} (Q_s - Z_{1s})^{\alpha_3+1} \right) d\bar{N}_s \right] \\
& + \mathbb{E} \left[\sup_{0 \leq s \leq t} \int_0^s \frac{l(l-1)}{2} |Q_s|^{l-2} \left| h(s, Q_s, Z_{2s}) - \frac{H_3(s, Q_s, Z_{1s}, Z_{2s})}{(\alpha_3 + 1)!} (Q_s - Z_{1s})^{\alpha_3+1} \right|^2 d\bar{N}_s \right] \\
\leq & \mathbb{E} \left[\sup_{0 \leq s \leq t} \int_0^s |Q_s|^{\frac{l-2}{2}} \left(Q_s^{\frac{l-2}{2}}, g(s, Q_s, Z_{2s}) - \frac{H_2(s, Q_s, Z_{1s}, Z_{2s})}{(\alpha_2 + 1)!} (Q_s - Z_{1s})^{\alpha_2+1} \right) dB_s \right] \\
& + \mathbb{E} \left[\sup_{0 \leq s \leq t} \int_0^s |Q_s|^{\frac{l-2}{2}} \left(Q_s^{\frac{l-2}{2}}, h(s, Q_s, Z_{2s}) - \frac{H_3(s, Q_s, Z_{1s}, Z_{2s})}{(\alpha_3 + 1)!} (Q_s - Z_{1s})^{\alpha_3+1} \right) d\bar{N}_s \right] \\
& + \mathbb{E} \left[\sup_{0 \leq s \leq t} \int_0^s \frac{l(l-1)}{2} |Q_s|^{l-2} \left| h(s, Q_s, Z_{2s}) - \frac{H_3(s, Q_s, Z_{1s}, Z_{2s})}{(\alpha_3 + 1)!} (Q_s - Z_{1s})^{\alpha_3+1} \right|^2 d\bar{N}_s \right] \\
\leq & \mathbb{E} \left[\sup_{-\tau \leq u \leq t} |Q_u|^{\frac{l}{2}} \left(\int_0^t (Q_s^{\frac{l-2}{2}}, g(s, Q_s, Z_{2s}) - \frac{H_2(s, Q_s, Z_{1s}, Z_{2s})}{(\alpha_2 + 1)!} (Q_s - Z_{1s})^{\alpha_2+1}) dB_s \right) \right] \\
& + \mathbb{E} \left[\sup_{-\tau \leq u \leq t} |Q_u|^{\frac{l}{2}} \left(\int_0^t (Q_s^{\frac{l-2}{2}}, h(s, Q_s, Z_{2s}) - \frac{H_3(s, Q_s, Z_{1s}, Z_{2s})}{(\alpha_3 + 1)!} (Q_s - Z_{1s})^{\alpha_3+1}) d\bar{N}_s \right) \right] \\
& + \mathbb{E} \left[\sup_{0 \leq s \leq t} \int_0^s \frac{l(l-1)}{2} |Q_s|^{l-2} \left| h(s, Q_s, Z_{2s}) - \frac{H_3(s, Q_s, Z_{1s}, Z_{2s})}{(\alpha_3 + 1)!} (Q_s - Z_{1s})^{\alpha_3+1} \right|^2 d\bar{N}_s \right] \\
\leq & 3\mathbb{E} \left[\sup_{-\tau \leq u \leq t} |Q_u|^{\frac{l}{2}} \left(\int_0^t |Q_s|^{l-2} \left\| g(s, Q_s, Z_{2s}) - \frac{H_2(s, Q_s, Z_{1s}, Z_{2s})}{(\alpha_2 + 1)!} (Q_s - Z_{1s})^{\alpha_2+1} \right\|_2^2 ds \right)^{\frac{1}{2}} \right] \quad (5.6) \\
& + 3\mathbb{E} \left[\sup_{-\tau \leq u \leq t} |Q_u|^{\frac{l}{2}} \left(\int_0^t |Q_s|^{l-2} \left\| h(s, Q_s, Z_{2s}) - \frac{H_3(s, Q_s, Z_{1s}, Z_{2s})}{(\alpha_3 + 1)!} (Q_s - Z_{1s})^{\alpha_3+1} \right\|_2^2 ds \right)^{\frac{1}{2}} \right] \\
& + \mathbb{E} \left[\sup_{0 \leq s \leq t} \int_0^s \frac{l(l-1)}{2} |Q_s|^{l-2} \left| h(s, Q_s, Z_{2s}) - \frac{H_3(s, Q_s, Z_{1s}, Z_{2s})}{(\alpha_3 + 1)!} (Q_s - Z_{1s})^{\alpha_3+1} \right|^2 d\bar{N}_s \right] \\
\leq & 3\mathbb{E} \left[\sup_{-\tau \leq u \leq t} |Q_u|^{\frac{l}{2}} \left(\int_0^t |Q_s|^{l-2} (2K^2 \|Q_s\|^2 + (\frac{K_2}{(\alpha_2 + 1)!} 2^{\alpha_2+1})^2 \|Q_s\|^{2\alpha_2+2}) ds \right)^{\frac{1}{2}} \right] \\
& + 3\mathbb{E} \left[\sup_{-\tau \leq u \leq t} |Q_u|^{\frac{l}{2}} \left(\int_0^t |Q_s|^{l-2} (2K^2 \|Q_s\|^2 + (\frac{K_3}{(\alpha_3 + 1)!} 2^{\alpha_3+1})^2 \|Q_s\|^{2\alpha_3+2}) ds \right)^{\frac{1}{2}} \right] \\
& + \mathbb{E} \left[\sup_{0 \leq s \leq t} \int_0^s \frac{l(l-1)}{2} |Q_s|^{l-2} \left| h(s, Q_s, Z_{2s}) - \frac{H_3(s, Q_s, Z_{1s}, Z_{2s})}{(\alpha_3 + 1)!} (Q_s - Z_{1s})^{\alpha_3+1} \right|^2 d\bar{N}_s \right] \\
\leq & \frac{1}{6} \mathbb{E} \left[\sup_{-\tau \leq u \leq t} |Q_u|^l \right] + C\mathbb{E} \left(\int_0^t |Q_s|^{l-2} (2K^2 \|Q_s\|^2 + (\frac{K_2}{(\alpha_2 + 1)!} 2^{\alpha_2+1})^2 \|Q_s\|^{2\alpha_2+2}) ds \right) \\
& + \frac{1}{6} \mathbb{E} \left[\sup_{-\tau \leq u \leq t} |Q_u|^l \right] + C\mathbb{E} \left(\int_0^t |Q_s|^{l-2} (2K^2 \|Q_s\|^2 + (\frac{K_3}{(\alpha_3 + 1)!} 2^{\alpha_3+1})^2 \|Q_s\|^{2\alpha_3+2}) ds \right) \\
& + \frac{1}{6} \mathbb{E} \left[\sup_{-\tau \leq u \leq t} |Q_u|^l \right] + C\mathbb{E} \left(\int_0^t |Q_s|^{l-2} (2K^2 \|Q_s\|^2 + (\frac{K_3}{(\alpha_3 + 1)!} 2^{\alpha_3+1})^2 \|Q_s\|^{2\alpha_3+2}) ds \right) \\
\leq & \frac{1}{2} \mathbb{E} \left[\sup_{-\tau \leq u \leq t} |Q_u|^l \right] + C\mathbb{E} \left(\int_0^t (|Q_s|^l + \|Q_s\|^{2\alpha+l}) ds \right).
\end{aligned}$$

Note that for any $t \in [0, T]$,

$$\mathbb{E}\left[\sup_{-\tau \leq u \leq t} |Q_u|^l\right] = \mathbb{E}\left[\sup_{-\tau \leq u \leq 0} |Q_u|^l\right] \vee \mathbb{E}\left[\sup_{0 \leq u \leq t} |Q_u|^l\right].$$

Combining (5.4), (5.5) and (5.6), we can show that

$$\begin{aligned} & \mathbb{E}\left[\sup_{-\tau \leq u \leq t} |Q_u|^l\right] \\ & \leq \mathbb{E}\left[\sup_{-\tau \leq u \leq 0} |\phi_u|^l\right] + l\left(\frac{\bar{\beta}^2 A^2}{2} + \mu_1^0 \bar{\mu} + (1 + \lambda)(2K + 2(l-1)K^2)\right) \int_0^t \mathbb{E} \sup_{-\tau \leq u \leq s} |Q_u|^l ds \\ & \quad + (1 + \lambda)\left(\frac{lK_1}{(\alpha_1 + 1)!} 2^{\alpha+1} + l(l-1)\left(\frac{C}{(\bar{\alpha} + 1)!} 2^{\alpha+1}\right)^2\right) \int_0^t \mathbb{E} \sup_{-\tau \leq u \leq s} \|Q_u\|^{l+2\alpha} ds \\ & \quad + \frac{1}{2} \mathbb{E}\left[\sup_{-\tau \leq u \leq t} |Q_u|^l\right] + C\left(\int_0^t (\mathbb{E} \sup_{-\tau \leq u \leq s} |Q_u|^l + \mathbb{E} \sup_{-\tau \leq u \leq s} \|Q_u\|^{2\alpha+l}) ds\right) \\ & \leq \mathbb{E}\left[\sup_{-\tau \leq u \leq 0} |\phi_u|^l\right] + C \int_0^t \mathbb{E} \sup_{-\tau \leq u \leq s} |Q_u|^l ds + C \int_0^t (\mathbb{E} \sup_{-\tau \leq u \leq s} \|Q_u\|^{2\alpha+l}) ds \\ & \leq \mathbb{E}\left[\sup_{-\tau \leq u \leq 0} |\phi_u|^l\right] + C \int_0^t (\mathbb{E} \sup_{-\tau \leq u \leq s} \|Q_u\|^{2l}) ds. \end{aligned}$$

Finally, by Generalization of the Bellman lemma [31], we obtain the desired result (3.2).



AIMS Press

©2020 the Author(s), licensee AIMS Press. This is an open access article distributed under the terms of the Creative Commons Attribution License (<http://creativecommons.org/licenses/by/4.0>)