

AIMS Mathematics, 9(8): 23128–23141. DOI:10.3934/math.20241124 Received: 07 May 2024 Revised: 09 July 2024 Accepted: 22 July 2024 Published: 29 July 2024

https://www.aimspress.com/journal/Math

Research article

Iterative oscillation criteria of third-order nonlinear damped neutral differential equations

Taher S. Hassan^{1,2,3}, Emad R. Attia^{4,5} and Bassant M. El-Matary^{5,6,*}

- ¹ Department of Mathematics, College of Science, University of Hail, Hail 2440, Saudi Arabia
- ² Department of Mathematics, Faculty of Science, Mansoura University, Mansoura 35516, Egypt
- ³ Section of Mathematics, International Telematic University Uninettuno, Corso Vittorio Emanuele II, 39, 00186 Roma, Italy
- ⁴ Department of Mathematics, College of Sciences and Humanities, Prince Sattam Bin Abdulaziz University, Alkharj 11942, Saudi Arabia
- ⁵ Department of Mathematics, College of Science, Qassim University, Buraydah, 51452, Saudi Arabia
- ⁶ Department of Mathematics, Faculty of Science, Damietta University, New Damietta 34517, Egypt
- * **Correspondence:** Email: bassantmarof@yahoo.com, b.elmatary@qu.edu.sa.

Abstract: Using comparison principles, we examine the asymptotic characteristics of a thirdorder nonlinear damped neutral differential equation. Our results substantially generalize numerous previously established results as well as drastically improving them. To illustrate the relevance and effectiveness of our results, we use numerical examples.

Keywords: differential equations; third-order; oscillation; asymptotic behavior; damped **Mathematics Subject Classification:** 34K11, 39A10, 39A99

1. Introduction

A neutral delay differential equation contains the highest-order derivative of the unknown function both with and without delays. Because of this, the theory of neutral delay differential equations is more difficult to understand than the theory of non-neutral equations. There has been an increase in interest in the theory of neutral differential equations in recent years. Studying these equations is essential for both theory and applications, as neutral equations are used to explain a wide range of real-world phenomena, including the motion of radiating electrons, population growth, the spread of epidemics, networks incorporating lossless transmission lines, etc., see [2, 17, 19, 20]. Researchers have focused a great deal of attention on the oscillation problem of functional differential equations in the recent few decades; see, for example, [1–40]. For third-order delay equations, see [1–7, 12, 25, 26, 29]. For neutral equations, see [21,22,32–34] and [8,15,24,35,39] for the equations with damping. Using a generalized Riccati transformation and an integral averaging technique the authors [38] obtained certain necessary conditions for oscillation for the third-order nonlinear differential equation

$$[m_2(s)\{m_1(s)x'(s)\}']' + p(s)x'(s) + q(s)f(x(\rho(s))) = 0,$$

where $\rho'(s) > 0$ and $\frac{f(u)}{u} \ge k > 0$, for all $u \ne 0$. Also, [11] improves and unifies the results of [38], reducing the third-order equations to the first and second ones. In this work, we focus our attention on the oscillation of the third-order nonlinear neutral differential equation with the form

$$\left\{m_2(s)\varphi_{\eta_2}\left(\left[m_1(s)\varphi_{\eta_1}\left(z'(s)\right)\right]'\right)\right\}' + m_3(s)\varphi_{\eta_2}\left(\left[m_1(s)\varphi_{\eta_1}\left(z'(s)\right)\right]'\right) + q(s)f(x(\rho(s))) = 0,$$
(1.1)

where $s \ge s_0 \ge 0$, $z(s) := x(s) + p(s)x(\mu(s))$, $\varphi_{\beta}(u) := |u|^{\beta-1}u$, $\beta > 0$; $\eta_1, \eta_2 > 0$, and $m_i, p, q, \rho, \mu \in Q$ $C([s_0,\infty),\mathbb{R}), i = 1, 2, 3$. It should be noted that the oscillation of many special cases of Eq (1.1) has been studied by many authors; see, for examples, [9–12, 15, 16].

In this paper, we suppose that

- (i) $0 \le p(s) , <math>q(s) \ge 0$, $m_i(s) > 0$, i = 1, 2 and $m_3(s) \ge 0$;
- (ii) $f \in C(\mathbb{R}, \mathbb{R})$ such that xf(x) > 0 and $\frac{f(x)}{\varphi_{\eta}(x)} \ge k > 0$, for all $x \neq 0, \eta := \eta_1 \eta_2$; (iii) $\rho(s) \le s, \mu(s) \le s$, and $\lim_{s \to \infty} \rho(s) = \lim_{s \to \infty} \mu(s) = \infty$;

(iv)
$$\int_{\mathcal{S}}^{\infty} \left(\frac{1}{m_1(t)}\right)^{1/\eta_1} dt = \infty$$
 and $\int_{\mathcal{S}}^{\infty} \left(\frac{1}{M(t)}\right)^{1/\eta_2} dt = \infty$,
where $M(s) := m_2(s) \exp\left(\int_{\mathcal{S}}^{s} \frac{m_3(r)}{m_2(r)} dr\right), \mathcal{S} \in [s_0, \infty)$

A function x(s) is a solution of (1.1) if it satisfies Eq (1.1) for all $s \in [s_x, \infty)$ and satisfying sup{|x(s)|: $s \geq S$ > 0 for any $S \geq s_x$ with $x(s), m_1(s)\varphi_{\eta_1}(z'(s))$, and $m_2(s)\varphi_{\eta_2}(|m_1(s)\varphi_{\eta_1}(z'(s))|')$ are continuously differentiable for all $s \in [s_x, \infty)$. The solution on $[s_x, \infty)$ with arbitrary large zeros is said to be an oscillatory solution. In this paper, we investigate the oscillatory and asymptotic behavior of Eq (1.1)by a reduction in order and comparison with the oscillation of first-order delay differential equations.

2. Main results

Throughout this paper, we define

$$\mathcal{L}_{1}(z(s)) := \varphi_{\eta_{1}}(z'(s)), \ \mathcal{L}_{2}(z(s)) := \varphi_{\eta_{2}}((m_{1}(s)\mathcal{L}_{1}(z(s)))').$$

Also, the sequences $\{P_n(s)\}_{n=1}^{\infty}$ and $\{Q_n(s,t)\}_{n=1}^{\infty}$ are defined as follows:

$$P_{n}(s) = \int_{\mathcal{S}}^{s} \left[\frac{1}{m_{1}(u)} \int_{\mathcal{S}}^{u} \left(\frac{1}{M(t)} \exp\left(\int_{t}^{u} \overline{q}(w) P_{n-1}^{\eta}(\rho(w)) \, \mathrm{d}w \right) \right)^{1/\eta_{2}} \, \mathrm{d}t \right]^{1/\eta_{1}} \, \mathrm{d}u, \tag{2.1}$$

for $S \in [s_0, \infty)$ and $s \in [S, \infty)$, with

$$P_0(s) = 0 \quad \text{and} \quad \overline{q}(s) := kq(s) \left(1 - p\left(\rho\left(s\right)\right)\right)^\eta \exp\left(\int_{\mathcal{S}}^s \frac{m_3(r)}{m_2(r)} \, \mathrm{d}r\right),$$

AIMS Mathematics

and

$$Q_n(s,t) := \int_t^s \left[\frac{1}{m_1(v)} \int_v^s \left(\frac{1}{M(u)} \exp\left(\int_u^s \bar{q}_*(w) Q_{n-1}^{\eta}(w,\rho(w)) \, \mathrm{d}w \right) \right)^{1/\eta_2} \, \mathrm{d}u \right]^{1/\eta_1} \, \mathrm{d}v,$$

for $s \in [t, \infty) \subseteq [S, \infty)$, with

$$Q_0(s,t) = 0 \text{ and } \bar{q}_*(s) := kN^\eta q(s) \exp\left(\int_{\mathcal{S}}^s \frac{m_3(r)}{m_2(r)} \, \mathrm{d}r\right),$$

for some N > 0 and $S \in [s_0, \infty)$.

The subsequent lemmas will be introduced and utilized in the main result.

Lemma 2.1. Assume that x is an eventually positive solution of Eq (1.1). Then there exists $S \ge s_0$ such that either

(*I*)
$$\mathcal{L}_1(z(s)) > 0$$
, $\mathcal{L}_2(z(s)) > 0$,

or

(II)
$$\mathcal{L}_1(z(s)) < 0, \ \mathcal{L}_2(z(s)) > 0,$$

for all $s \geq S$.

Proof. Since *x* is a positive solution of Eq (1.1) on $[s_1, \infty)$, $s_1 \ge s_0$ such that $x(\rho(s)) > 0$ and $x(\mu(s)) > 0$ for $s \ge s_1$. From Eq (1.1), we have for all $s \ge s_1$,

$$(m_2(s) \mathcal{L}_2(z(s)))' + m_3(s) \mathcal{L}_2(z(s)) \le 0,$$

which implies that

$$\left(M\left(s\right)\mathcal{L}_{2}(z(s))\right)'\leq0,$$

where $M(s) = m_2(s) \exp\left(\int_{s_1}^s \frac{m_3(r)}{m_2(r)} dr\right)$. That demonstrates that $\mathcal{L}_1(z(s))$ and $\mathcal{L}_2(z(s))$ are of one sign eventually. We claim that

 $\mathcal{L}_2(z(s)) > 0$ eventually.

If not, consider the following two cases:

Case 1. There exists $s_2 \ge s_1$, sufficiently large, such that

$$\mathcal{L}_1(z(s)) > 0$$
 and $\mathcal{L}_2(z(s)) < 0$ for $s \ge s_2$.

Since $(M(s) \mathcal{L}_2(z(s)))' \leq 0$, then there exists a negative constant \mathcal{M} such that

$$M(s)\varphi_{\eta_2}\left((m_1(s)\mathcal{L}_1(z(s)))'\right) \leq \mathcal{M} \quad \text{for } s \geq s_2.$$

It follows that

$$(m_1(s)\mathcal{L}_1(z(s)))' \le \varphi_{\eta_2}^{-1}(\mathcal{M})^{1/\eta_2} \left(\frac{1}{M(s)}\right)^{1/\eta_2} \text{ for } s \ge s_2.$$

Integrating from s_2 to s, we obtain

$$m_1(s)\mathcal{L}_1(z(s)) \le m_1(s_2)\mathcal{L}_1(z(s_2)) + \varphi_{\eta_2}^{-1}(\mathcal{M})^{1/\eta_2} \int_{s_2}^s \left(\frac{1}{M(t)}\right)^{1/\eta_2} dt$$

AIMS Mathematics

Letting $s \to \infty$ and using (iv), then $\mathcal{L}_1(z(s)) \to -\infty$, which contradicts that $\mathcal{L}_1(z(s)) > 0$. **Case 2.** There exists $s_2 \ge s_1$, sufficiently large, such that

 $\mathcal{L}_1(z(s)) < 0$ and $\mathcal{L}_2(z(s)) < 0$ for $s \ge s_2$,

which implies that $(m_1(s)\mathcal{L}_1(z(s)))' < 0$ and therefore,

$$m_1(s)\mathcal{L}_1(z(s)) \le m_1(s_2)\mathcal{L}_1(z(s_2)) = \bar{k} < 0.$$

Dividing by $m_1(s)$ and integrating from s_2 to s, we obtain

$$z(s) \le z(s_2) + \varphi_{\eta_1}^{-1}(\bar{k}) \int_{s_2}^{s} \left(\frac{1}{m_1(t)}\right)^{1/\eta_1} \mathrm{d}t.$$

Letting $s \to \infty$, then (iv) yields $z(s) \to -\infty$, which contradicts the fact that z(s) > 0. This completes the proof.

Lemma 2.2. Assume that x is a positive solution of Eq (1.1) and the corresponding function z satisfies (I) of Lemma 2.1. Then

$$(M(s) \mathcal{L}_2(z(s)))' + \bar{q}(s) z^{\eta}(\rho(s)) \le 0.$$
(2.2)

Proof. Since x is a positive solution of Eq (1.1) on $[s_1, \infty)$, then there exists $s_2 \ge s_1$ such that the corresponding function z satisfies (I) of Lemma 2.1 on $[s_1, \infty)$. It is easy to see that Eq (1.1) can be written in the form

$$(m_2(s)\mathcal{L}_2(z(s)))' + m_3(s)\mathcal{L}_2(z(s)) + q(s)f(x(\rho(s))) = 0,$$

for all $s \ge s_1$. Then

$$(M(s) \mathcal{L}_2(z(s)))' + q(s) \exp\left(\int_{s_1}^s \frac{m_3(r)}{m_2(r)} dr\right) f(x(\rho(s))) = 0.$$

Therefore,

$$(M(s) \mathcal{L}_2(z(s)))' + kq(s) \exp\left(\int_{s_1}^s \frac{m_3(r)}{m_2(r)} \, \mathrm{d}r\right) x^\eta(\rho(s)) \le 0.$$
(2.3)

Also, we have

$$x(s) = z(s) - p(s)x(\mu(s)) \ge z(s) - p(s)z(\mu(s)).$$

Since z' > 0, we get

$$x(s) \ge (1 - p(s))z(s).$$
 (2.4)

Substituting (2.4) into (2.3), we have

 $(M(s)\mathcal{L}_2(z(s)))' + \overline{q}(t)z^{\eta}(\rho(s)) \le 0.$

This completes the proof.

Lemma 2.3. If x is an eventually positive solution of Eq (1.1) and the corresponding function z satisfies *Case (I) of Lemma 2.1, then for* $n \in \mathbb{N}$ *,*

$$z(s) \ge P_n(s) \left(M(s) \mathcal{L}_2(z(s)) \right)^{1/\eta}.$$
(2.5)

AIMS Mathematics

Volume 9, Issue 8, 23128–23141.

Proof. Since x is a positive solution of Eq (1.1) on $[s_1, \infty)$, then there exists $s_2 \ge s_1$ such that the corresponding function z satisfies (I) of Lemma 2.1 on $[s_1, \infty)$. Then

$$m_{1}(s) \mathcal{L}_{1}(z(s)) = \int_{s_{1}}^{s} (m_{1}(t) \mathcal{L}_{1}(z(t)))' dt + m_{1}(s_{1}) \mathcal{L}_{1}(z(s_{1}))$$

$$\geq \int_{s_{1}}^{s} \left(\frac{1}{M(t)}\right)^{1/\eta_{2}} (M(t) \mathcal{L}_{2}(z(t)))^{1/\eta_{2}} dt \qquad (2.6)$$

$$\geq (M(s) \mathcal{L}_{2}(z(s)))^{1/\eta_{2}} \int_{s_{1}}^{s} \left(\frac{1}{M(t)}\right)^{1/\eta_{2}} dt.$$

Then,

$$z'(s) \ge (M(s) \mathcal{L}_2(z(s)))^{1/\eta} \left[\frac{1}{m_1(s)} \int_{s_1}^s \left(\frac{1}{M(t)} \right)^{1/\eta_2} dt \right]^{1/\eta_1}.$$

Integrating the above inequality from s_1 to $s \in [s_1, \infty)$, we obtain

$$z(s) \ge \int_{s_1}^{s} \left\{ (M(u) \mathcal{L}_2(z(u)))^{1/\eta} \left[\frac{1}{m_1(u)} \int_{s_1}^{u} \left(\frac{1}{M(t)} \right)^{1/\eta_2} dt \right]^{1/\eta_1} \right\} du$$

$$\ge (M(s) \mathcal{L}_2(z(s)))^{1/\eta} \int_{s_1}^{s} \left\{ \left[\frac{1}{m_1(u)} \int_{s_1}^{u} \left(\frac{1}{M(t)} \right)^{1/\eta_2} dt \right]^{1/\eta_1} \right\} du$$

$$= (M(s) \mathcal{L}_2(z(s)))^{1/\eta} P_1(s).$$

This shows that (2.5) holds for n = 1. Consequently,

$$z(\rho(s)) \ge (M(\rho(s)) \mathcal{L}_2(z(\rho(s))))^{1/\eta} P_1(\rho(s)).$$
(2.7)

From (2.2) and (2.7), we obtain

$$(M(s)\mathcal{L}_2(z(s)))' + \overline{q}(s)P_1^{\eta}(\rho(s))M(\rho(s))\mathcal{L}_2(z(\rho(s))) \le 0.$$

Using the nonicreasing nature of $M(s) \mathcal{L}_2(z(s))$ and $\rho(s) \leq s$, we obtain

$$(M(s)\mathcal{L}_2(z(s)))' + \overline{q}(s)P_1^{\eta}(\rho(s))M(s)\mathcal{L}_2(z(s)) \le 0.$$

Integrating the above inequality from *t* to $s \in [t, \infty)$ implies that

$$M(t) \mathcal{L}_2(z(t)) \ge M(s) \mathcal{L}_2(z(s)) \exp\left(\int_t^s \overline{q}(w) P_1^{\eta}(\rho(w)) \, \mathrm{d}w\right).$$
(2.8)

Using (2.8) in (2.6), we obtain

$$m_1(s) \mathcal{L}_1(z(s)) \ge (M(s) \mathcal{L}_2(z(s)))^{1/\eta_2} \int_{s_1}^s \left(\frac{1}{M(t)} \exp\left(\int_t^s \overline{q}(w) P_1^{\eta}(\rho(w)) \, \mathrm{d}w \right) \right)^{1/\eta_2} \, \mathrm{d}t.$$

It follows that

$$z'(s) \ge (M(s) \mathcal{L}_2(z(s)))^{1/\eta} \left[\frac{1}{m_1(s)} \int_{s_1}^s \left(\frac{1}{M(t)} \exp\left(\int_t^s \overline{q}(w) P_1^{\eta}(\rho(w)) \, \mathrm{d}w \right) \right)^{1/\eta_2} \, \mathrm{d}t \right]^{1/\eta_1}.$$

AIMS Mathematics

Again, integrating from s_1 to s, we obtain

$$z(s) \geq \int_{s_1}^{s} (M(u) \mathcal{L}_2(z(u)))^{1/\eta} \left[\frac{1}{m_1(u)} \int_{s_1}^{u} \left(\frac{1}{M(t)} \exp\left(\int_{t}^{u} \overline{q}(w) P_1^{\eta}(\rho(w)) \, dw \right) \right)^{1/\eta_2} \, dt \right]^{1/\eta_1} \, du$$

$$\geq (M(s) \mathcal{L}_2(z(s)))^{1/\eta} \int_{s_1}^{s} \left[\frac{1}{m_1(u)} \int_{s_1}^{u} \left(\frac{1}{M(t)} \exp\left(\int_{t}^{u} \overline{q}(w) P_1^{\eta}(\rho(w)) \, dw \right) \right)^{1/\eta_2} \, dt \right]^{1/\eta_1} \, du$$

$$= (M(s) \mathcal{L}_2(z(s)))^{1/\eta} P_2(s).$$

This shows that (2.5) holds for n = 2. If this process is repeated *n* times, we obtain (2.5).

The asymptotic behavior of all solutions to Eq (1.1) is discussed in the results that follow.

Theorem 2.1. Let $n \in \mathbb{N}$. Assume that the first-order delay differential equation

$$w'(s) + \bar{q}(s) P_n^{\eta}(\rho(s)) w(\rho(s)) = 0$$
(2.9)

is oscillatory. If x(s) is a solution of Eq (1.1), then x(s) is either oscillatory or bounded.

Proof. Assume that x(s) is a nonoscillatory solution of Eq (1.1). Without loss of generality, let x(s) > 0, $x(\rho(s)) > 0$, and $x(\mu(s)) > 0$ on $[s_1, \infty)$, $s_1 \ge s_0$. It follows from Lemma 2.1 that there exists $s_2 \ge s_1$ such that either (I) or (II) holds on $[s_2, \infty)$. Assume (I) is valid. From (2.5), we have

$$z(\rho(s)) \ge (M(\rho(s)) \mathcal{L}_2(z(\rho(s))))^{1/\eta} P_n(\rho(s)).$$
(2.10)

Combining (2.2) and (2.10), we obtain

$$w'(s) + \overline{q}(s)P_n^{\eta}(\rho(s))w(\rho(s)) \le 0,$$

where $w(s) := M(s) \mathcal{L}_2(z(s))$. Due to [37, Theorem 1], the associated delay differential equation also has a positive solution. This is a contradiction. Now, to complete the proof, we consider (II) valid. Since z(s) > 0, and z'(s) < 0 then z(s) is bounded, and therefore x(s) is bounded. The proof is complete.

Theorem 2.2. Let $n \in \mathbb{N}$. Assume that the first-order delay differential equation (2.9) is oscillatory and

$$\int_{-\infty}^{\infty} \left[\frac{1}{m_1(v)} \int_{v}^{\infty} \left(\frac{1}{m_2(u)} \int_{u}^{\infty} q(t) \exp\left(\int_{u}^{t} \frac{m_3(r)}{m_2(r)} dr \right) dt \right)^{1/\eta_2} du \right]^{1/\eta_1} dv = \infty.$$
(2.11)

If x(s) is a solution of Eq (1.1), then x(s) is either oscillatory or tends to zero eventually.

Proof. Assume that x(s) is a nonoscillatory solution of Eq (1.1). Without loss of generality, let x(s) > 0, $x(\rho(s)) > 0$, and $x(\mu(s)) > 0$ on $[s_1, \infty)$, $s_1 \ge s_0$. It follows from Lemma 2.1 that there exists $s_2 \ge s_1$ such that either (I) or (II) holds on $[s_2, \infty)$. The proof of Case (I) is identical to the proof of Theorem 2.1, Case (I), and so it has been omitted. Assume (II) is valid. It is obvious that Eq (1.1) can be written as

$$(M(s)\mathcal{L}_2(z(s)))' + kq(s)\exp\left(\int_{s_1}^s \frac{m_3(r)}{m_2(r)} \,\mathrm{d}r\right) x^\eta(\rho(s)) \le 0.$$
(2.12)

AIMS Mathematics

Since z(s) > 0 and z'(s) < 0, there exists a constant $l \ge 0$ such that $\lim_{t\to\infty} z(s) = l$. We claim l = 0. If not, then for sufficiently small $\epsilon > 0$, there exists $s_3 \ge s_2$ such that $l - p(l + \epsilon) > 0$ and $l < z(s) < l + \epsilon$ for all $s > s_3$. Then

$$x(s) = z(s) - p(s)x(\mu(s)) \ge z(s) - pz(\mu(s)) \ge l - p(l + \epsilon) \ge N \ (l + \epsilon) > N \ z(s),$$
(2.13)

 $N := \frac{l-p(l+\epsilon)}{l+\epsilon} > 0$. From (2.12) and (2.13), we obtain

$$(M(s) \mathcal{L}_2(z(s)))' + kN^{\eta}q(s) \exp\left(\int_{s_1}^s \frac{m_3(r)}{m_2(r)} dr\right) z^{\eta}(\rho(s)) \le 0.$$
(2.14)

Then

$$(M(s)\mathcal{L}_2(z(s)))' + Kq(s)\exp\left(\int_{s_1}^s \frac{m_3(r)}{m_2(r)} dr\right) \le 0,$$

where $K := kN^{\eta}l^{\eta} > 0$. Integrating the above inequality from $s \in [s_3, \infty)$ to ∞ , we obtain

$$M(s) \mathcal{L}_2(z(s)) \geq K \int_s^\infty q(t) \exp\left(\int_{s_1}^t \frac{m_3(r)}{m_2(r)} dr\right) dt$$

= $K \exp\left(\int_{s_1}^s \frac{m_3(r)}{m_2(r)} dr\right) \int_s^\infty q(t) \exp\left(\int_s^t \frac{m_3(r)}{m_2(r)} dr\right) dt.$

It follows that

$$(m_1(s) \mathcal{L}_1(z(s)))' \ge K^{1/\eta_2} \left(\frac{1}{m_2(s)} \int_s^\infty q(t) \exp\left(\int_s^t \frac{m_3(r)}{m_2(r)} dr\right) dt\right)^{1/\eta_2},$$

Integrating the above inequality from *s* to ∞ , we obtain

$$-z'(s) \ge K^{1/\eta} \left[\frac{1}{m_1(s)} \int_s^\infty \left(\frac{1}{m_2(u)} \int_u^\infty q(t) \exp\left(\int_u^t \frac{m_3(r)}{m_2(r)} \, \mathrm{d}r \right) \, \mathrm{d}t \right)^{1/\eta_2} \, \mathrm{d}u \right]^{1/\eta_1}$$

Again, integrating the above inequality from s_2 to ∞ , we obtain

$$z(s_2) \ge K^{1/\eta} \int_{s_2}^{\infty} \left[\frac{1}{m_1(v)} \int_{v}^{\infty} \left(\frac{1}{m_2(u)} \int_{u}^{\infty} q(t) \exp\left(\int_{u}^{t} \frac{m_3(r)}{m_2(r)} dr \right) dt \right)^{1/\eta_2} du \right]^{1/\eta_1} dv,$$

which is a contradiction to (2.11), then $\lim_{s\to\infty} z(s) = 0$. Since $0 < x(s) \le z(s)$, then $\lim_{s\to\infty} x(s) = 0$. The proof is complete.

Lemma 2.4. If x is an eventually positive solution of Eq (1.1) and the corresponding function z satisfies Case (II) of Lemma 2.1, then for $n \in \mathbb{N}$ and $s \in [t, \infty)$,

$$z(t) \ge (M(s) \mathcal{L}_2(z(s)))^{1/\eta} Q_n(s,t).$$
(2.15)

Proof. Let *x* be a positive solution of Eq (1.1) such that the Case (II) of Lemma 2.1 is satisfied on $[s_1, \infty)$, for some $s_1 \ge s_0$. Then, for $s \ge v \ge s_1$,

$$-m_1(v) \mathcal{L}_1(z(v)) = \int_v^s (m_1(u) \mathcal{L}_1(z(u)))' \, \mathrm{d}u - m_1(s) \mathcal{L}_1(z(s))$$

AIMS Mathematics

23135

$$\geq \int_{v}^{s} \left(\frac{1}{M(u)}\right)^{1/\eta_{2}} (M(u) \mathcal{L}_{2}(z(u)))^{1/\eta_{2}} du \qquad (2.16)$$

$$\geq (M(s) \mathcal{L}_{2}(z(s)))^{1/\eta_{2}} \int_{v}^{s} \left(\frac{1}{M(u)}\right)^{1/\eta_{2}} du.$$

. .

Then

$$-z'(v) \ge (M(s) \mathcal{L}_2(z(s)))^{1/\eta} \left[\frac{1}{m_1(v)} \int_v^s \left(\frac{1}{M(u)} \right)^{1/\eta_2} du \right]^{1/\eta_1}$$

Integrating the above inequality from *t* to $s \in [t, \infty)$ with respect to *v*, we obtain

$$z(t) \ge (M(s) \mathcal{L}_2(z(s)))^{1/\eta} \int_t^s \left[\frac{1}{m_1(v)} \int_v^s \left(\frac{1}{M(u)} \right)^{1/\eta_2} du \right]^{1/\eta_1} dv$$

$$\ge (M(s) \mathcal{L}_2(z(s)))^{1/\eta} Q_1(s,t).$$

This shows that (2.15) holds for n = 1. Consequently,

$$z(\rho(s)) \ge (M(s) \mathcal{L}_2(z(s)))^{1/\eta} Q_1(s, \rho(s)).$$
(2.17)

From (2.14) and (2.17), we obtain

$$(M(s) \mathcal{L}_2(z(s)))' + \overline{q}_*(s) Q_1^{\eta}(s, \rho(s)) M(s) \mathcal{L}_2(z(s)) \le 0,$$
(2.18)

where $\overline{q}_*(s) = kN^{\eta}q(s) \exp\left(\int_{s_1}^s \frac{m_3(r)}{m_2(r)} dr\right)$. Integrating the latter inequality from *u* to $s \in [u, \infty)$ gives

$$M(u) \mathcal{L}_{2}(z(u) \ge M(s) \mathcal{L}_{2}(z(s)) \exp\left(\int_{u}^{s} \bar{q}_{*}(w) Q_{1}^{\eta}(w, \rho(w)) \, \mathrm{d}w\right).$$
(2.19)

From (2.16) and (2.19), we obtain

$$-m_{1}(v)\mathcal{L}_{1}(z(v)) \geq \int_{v}^{s} \left(\frac{1}{M(u)}\right)^{1/\eta_{2}} (M(u)\mathcal{L}_{2}(z(u)))^{1/\eta_{2}} du$$

$$\geq (M(s)\mathcal{L}_{2}(z(s)))^{1/\eta_{2}} \int_{v}^{s} \left(\frac{1}{M(u)}\exp\left(\int_{u}^{s} \bar{q}_{*}(w)Q_{1}^{\eta}(w,\rho(w)) dw\right)\right)^{1/\eta_{2}} du$$

It follows that

$$-z'(v) \ge (M(s)\mathcal{L}_2(z(s)))^{1/\eta} \left[\frac{1}{m_1(v)} \int_v^s \left(\frac{1}{M(u)} \exp\left(\int_u^s \bar{q}_*(w) Q_1^{\eta}(w, \rho(w)) \, \mathrm{d}w \right) \right)^{1/\eta_2} \, \mathrm{d}u \right]^{1/\eta_1}$$

Therefore,

$$z(s) \ge (M(s) \mathcal{L}_2(z(s)))^{1/\eta} \int_t^s \left[\frac{1}{m_1(v)} \int_v^s \left(\frac{1}{M(u)} \exp\left(\int_u^s \bar{q}_*(w) Q_1^{\eta}(w, \rho(w)) \, \mathrm{d}w \right) \right)^{1/\eta_2} \, \mathrm{d}u \right]^{1/\eta_1} \, \mathrm{d}v.$$

Then,

$$z(s) \geq \left(M(s) \mathcal{L}_2(z(s))\right)^{1/\eta} Q_2(s,t).$$

This shows that (2.15) holds for n = 2. To obtain (2.15) for arbitrary $n \in \mathbb{N}$, this procedure can be done n times.

AIMS Mathematics

Theorem 2.3. Let $\rho(s)$ be nondecreasing on $[s_0, \infty)$. Suppose there exists $n \in \mathbb{N}$ such that one of the following first-order delay differential equations (2.9) is oscillatory and

$$\limsup_{s \to \infty} \int_{\rho(s)}^{s} \bar{q}_{*}(t) Q_{n}^{\eta}(\rho(s), \rho(t)) \, \mathrm{d}t > 1.$$
(2.20)

Then Eq (1.1) is oscillatory.

Proof. Assume that x(s) is a nonoscillatory solution of Eq (1.1). Without loss of generality, let x(s) > 0, $x(\rho(s)) > 0$, and $x(\mu(s)) > 0$ on $[s_1, \infty)$, $s_1 \ge s_0$. It follows from Lemma 2.1 that there exists $s_2 \ge s_1$ such that either (I) or (II) holds on $[s_1, \infty)$. The proof of Case (I) is identical to the proof of Theorem 2.1, Case (I), and so it has been omitted. Assume (II) is valid. As in the proof of Theorem 2.2, Case (II), we have

$$-(M(s)\mathcal{L}_{2}(z(s)))' \ge kN^{\eta}q(s)\exp\left(\int_{s_{1}}^{s}\frac{m_{3}(r)}{m_{2}(r)}\,\mathrm{d}r\right)z^{\eta}(\rho(s)) = \bar{q}_{*}(s)z^{\eta}(\rho(s))\,.$$

Integrating the above inequality from $\rho(s)$ to *s*, we obtain

$$M(\rho(s)) \mathcal{L}_2(z(\rho(s))) \ge \int_{\rho(s)}^s \bar{q}_*(t) z^{\eta}(\rho(t)) \, \mathrm{d}t.$$

In view of the nondecreasing nature of ρ and (2.15), we obtain

$$M(\rho(s)) \mathcal{L}_2(z(\rho(s))) \ge M(\rho(s)) \mathcal{L}_2(z(\rho(s))) \int_{\rho(s)}^s \bar{q}_*(t) Q_n^{\eta}(\rho(s), \rho(t)) dt.$$

This is a contradiction with (2.20). The proof is complete.

Applying the results of [27, 28, 30, 31] in Theorems 2.1–2.3, we get the asymptotic behavior of the solutions to Eq (1.1).

Corollary 2.1. Let $\rho(s)$ be nondecreasing on $[s_0, \infty)$. Suppose there exists $n \in \mathbb{N}$ such that one of the following conditions is satisfied:

- (a) $\liminf_{s\to\infty} \int_{\rho(s)}^{s} \overline{q}(t) P_n^{\eta}(\rho(t)) dt > \frac{1}{e};$ (b) $\limsup_{s\to\infty} \int_{\rho(s)}^{s} \overline{q}(t) P_n^{\eta}(\rho(t)) dt > 1;$
- (c) $\liminf_{s\to\infty} \int_{\rho(s)}^{s} \overline{q}(t) P_n^{\eta}(\rho(t)) dt > \alpha \text{ and } \limsup_{s\to\infty} \int_{\rho(s)}^{s} \overline{q}(t) P_n^{\eta}(\rho(t)) dt > 1 \left(1 \sqrt{1 \alpha}\right)^2.$

If x(s) is a solution of Eq (1.1), then

- (I) x(s) is either oscillatory or bounded;
- (II) x(s) is either oscillatory or tends to zero eventually if (2.11) holds;
- (III) x(s) is oscillatory if (2.20) holds.

Remark 2.1. We note that Theorems 2.2 and 2.3 are reduced to [10, Theorems 1 and 2] when $\eta_1 = \eta_2 = 1$, $m_3(s) = 0$, k = 1, and p(s) = 0.

AIMS Mathematics

Volume 9, Issue 8, 23128-23141.

3. Numerical examples

Examples are provided to demonstrate the significance of our results.

Example 3.1. Consider the third-order nonlinear neutral differential equation with a damping term of the form

$$\begin{cases} \frac{1}{s}\varphi_1\left(\left[(s-1)\varphi_3\left(\left(x(s)+\frac{1}{2}x\left(\frac{s}{2}\right)\right)'\right)\right]'\right)\right)' + \frac{1}{s^2}\varphi_1\left(\left[(s-1)\varphi_3\left(\left(x(s)+\frac{1}{2}x\left(\frac{s}{2}\right)\right)'\right)\right]'\right) + 6sx^3(s-1) \\ = 0, \ s \ge 1, \end{cases}$$
(3.1)

where $m_1(s) = s - 1$, $m_2(s) = \frac{1}{s}$, $m_3(s) = \frac{1}{s^2}$, q(s) = 6s, $\mu(s) = \frac{s}{2}$, $\rho(s) = s - 1$, $p(s) = \frac{1}{2}$, $\eta_1 = 3$, and $\eta_2 = 1$. Using Maple software, we see that condition (iv) holds and $\overline{q}(s) = \frac{3}{4}s^2$.

$$\int_{s_2}^{\infty} \left[\frac{1}{m_1(v)} \int_{v}^{\infty} \left(\frac{1}{m_2(u)} \int_{u}^{\infty} q(t) \exp\left(\int_{u}^{t} \frac{m_3(r)}{m_2(r)} dr \right) dt \right)^{1/\eta_2} du \right]^{1/\eta_1} dv$$
$$= \int_{1}^{\infty} \left[\frac{1}{v-1} \int_{v}^{\infty} \left(u \int_{u}^{\infty} 16t \exp\left(\int_{u}^{t} \frac{1}{r} dr \right) dt \right) du \right]^{\frac{1}{3}} dv = \infty.$$

Also, we have, for n = 1

$$\begin{split} & \liminf_{s \to \infty} \int_{\rho(s)}^{s} \bar{q}(t) P_{n}^{\eta}(\rho(t)) \, \mathrm{d}t \\ &= \liminf_{s \to \infty} \int_{s-1}^{s} \bar{q}(t) P_{1}^{3}(t-1) \, \mathrm{d}t \\ &= \liminf_{s \to \infty} ((1/8)s^{6} - (1/8)(s-1)^{6} - (9/10)s^{5} + (9/10)(s-1)^{5} + (9/4)s^{4} - (9/4)(s-1)^{4} \\ &- 2s^{3} + 2(s-1)^{3}) > \frac{1}{e}. \end{split}$$

Then, according to Corollary 2.1, every solution to Eq (3.1) is either oscillatory or tends to zero as $s \to \infty$.

Example 3.2. Consider the third-order nonlinear neutral differential equation with a damping term of the form

$$\left\{ \frac{1}{s^2} \varphi_1 \left(\left[\frac{1}{9s^2} \varphi_1 \left((x(s) + \frac{1}{3}x(s-1))' \right) \right]' \right) \right\}' + \frac{2}{s^3} \varphi_1 \left(\left[\frac{1}{9s^2} \varphi_1 \left((x(s) + \frac{1}{3}x(s-1)' \right) \right]' \right) + \frac{14}{s^7} x(\frac{s}{2}) \right]$$

= 0, $t \ge 1$, (3.2)

where $m_1(s) = \frac{1}{9s^2}$, $m_2(s) = \frac{1}{s^2}$, $m_3(s) = \frac{2}{s^3}$, $q(s) = \frac{42}{s^7}$, $\mu(s) = s - 1$, $\rho(s) = \frac{s}{2}$, $p(s) = \frac{1}{3}$, $\eta_1 = \eta_2 = 1$, $k = \frac{1}{3}$, and $N = \frac{1}{2}$. Using Maple software, we see that condition (iv) holds and $\overline{q}(s) = \frac{28}{3s^5}$, $q_*(s) = \frac{7}{s^5}$. Also, we have, for n = 1,

$$\liminf_{s\to\infty}\int_{\rho(s)}^{s}\overline{q}(t)P_{n}^{\eta}(\rho(t))\,\mathrm{d}t$$

AIMS Mathematics

$$= \liminf_{s \to \infty} \int_{\frac{s}{2}}^{s} \overline{q}(t) P_{1}(\frac{t}{2}) dt$$

$$= \liminf_{s \to \infty} ((21/16) \ln(2) - 7/(2s) + 105/(4s^{4}))$$

$$= 0.90976 > \frac{1}{e},$$

$$\limsup_{s \to \infty} \int_{\rho(s)}^{s} q_{*}(t) Q_{n}^{\eta}(\rho(s), \rho(t)) dt$$

$$= \limsup_{s \to \infty} \int_{\frac{s}{2}}^{s} q_{*}(t) Q_{1}(\frac{s}{2}, \frac{t}{2}) dt$$

$$= \limsup_{s \to \infty} \int_{\frac{s}{2}}^{s} q_{*}(t) \int_{t/2}^{s/2} \frac{\int_{v}^{s/2} (M(u))^{-1} du}{mI(v)} dv dt$$

$$= \limsup_{s \to \infty} \int_{\frac{s}{2}}^{s} \frac{7}{t^{5}} \frac{(3s^{2} + 6st + 9t^{2})(s - t)^{2}}{64} dt = 0.60029 < 1,$$

 Γ^{s}

$$\limsup_{s \to \infty} \int_{\rho(s)}^{s} q_{*}(t) Q_{n}^{\eta}(\rho(s), \rho(t)) dt$$

=
$$\limsup_{s \to \infty} \int_{\frac{s}{2}}^{s} q_{*}(t) Q_{2}(\frac{s}{2}, \frac{t}{2}) dt$$

=
$$\limsup_{s \to \infty} \int_{\frac{s}{2}}^{s} q_{*}(t) \int_{t/2}^{s/2} \frac{1}{mI(v)} \int_{v}^{s/2} \frac{e^{\int_{u}^{s/2} q_{*}(w)QI(w,w/2) dw}}{M(u)} du dv ds$$

= 1.111 > 1.

Thus, (a) is satisfied for n = 1, and (2.20) is satisfied for n = 2. Then, according to Corollary 2.1, every solution to Eq (3.2) is oscillatory.

Author contributions

Taher S. Hassan: Supervision, Writing-review editing, Software and Investigation; Emad R. Attia: Supervision, Writing-review editing, Software and Investigation; Bassant M. ElMatary: Supervision, Writing-original draft, Writing-review editing, Software and Investigation. All authors have read and agreed to the published version of the manuscript

Use of AI tools declaration

The authors declare they have not used Artificial Intelligence (AI) tools in the creation of this article.

Acknowledgments

The Researchers would like to thank the Deanship of Graduate Studies and Scientific Research at Qassim University for financial support (QU-APC-2024-9/1). This study is supported via funding from

AIMS Mathematics

Prince Sattam bin Abdulaziz University project number (PSAU/2024/R/1445).

Conflict of interest

The authors declare that there are no conflicts of interest regarding the publication of this article.

References

- 1. R. Agarwal, M. Bohner, T. Li, C. Zhang, Oscillation of third-order nonlinear delay differential equations, *Taiwanese J. Math.*, **17** (2013), 545–558. http://dx.doi.org/10.11650/tjm.17.2013.2095
- 2. R. Agarwal, S. Grace, D. O'Regan, Oscillation theory for difference and functional differential equations, Dordrecht: Springer, 2000. http://dx.doi.org/10.1007/978-94-015-9401-1
- R. Agarwal, S. Grace, D. O'Regan, On the oscillation of certain functional differential equations via comparison methods, *J. Math. Anal. Appl.*, 286 (2003), 577–600. http://dx.doi.org/10.1016/S0022-247X(03)00494-3
- R. Agarwal, S. Grace, D. O'Regan, The oscillation of certain higher order functional differential equations, *Math. Comput. Model.*, **37** (2003), 705–728. http://dx.doi.org/10.1016/S0895-7177(03)00079-7
- 5. B. Bacuíková, J. Džurina, Oscillation of third-order functional differential equations, *Electron. J. Qual. Theo.*, **43** (2010), 1–10.
- 6. B. Bacuíková, J. Džurina, Oscillation of third-order nonlinear differential equations, *Appl. Math. Lett.*, **24** (2011), 466–470. http://dx.doi.org/10.1016/j.aml.2010.10.043
- B. Bacuíková, E. Elabbasy, S. Saker, J. Džurina, Oscillation criteria for third-order nonlinear differential equations, *Math. Slovaca*, 58 (2008), 201–220. http://dx.doi.org/10.2478/s12175-008-0068-1
- 8. M. Bohner, S. Grace, I. Sağer, E. Tunç, Oscillation of third-order nonlinear damped delay differential equations, *Appl. Math. Comput.*, **278** (2016), 21–32. http://dx.doi.org/10.1016/j.amc.2015.12.036
- 9. G. Chatzarakis, J. Džurina, I. Jadlovska, Oscillatory and asymptotic properties of third-order quasilinear delay differential equations, *J. Inequal. Appl.*, **2019** (2019), 23. http://dx.doi.org/10.1186/s13660-019-1967-0
- 10. G. Chatzarakis, S. Grace, I. Jadlovská, Oscillation criteria for third-order delay differential equations, *Adv. Differ. Equ.*, **2017** (2017), 330. http://dx.doi.org/10.1186/s13662-017-1384-y
- 11. E. Elabbasy, B. Qaraad, T. Abdeljawad, O. Moaaz, Oscillation criteria for a class of third-order damped neutral differential equations, *Symmetry*, **12** (2020), 1988. http://dx.doi.org/10.3390/sym12121988
- 12. E. Elabbasy, T. Hassan, B. Elmatary, Oscillation criteria for third order delay nonlinear differential equations, *Electron. J. Qual. Theo.*, **5** (2012), 1–11.
- L. Erbe, T. Hassan, A. Peterson, Oscillation of third order nonlinear functional dynamic equations on time scales, *Differ. Equ. Dyn. Syst.*, 18 (2010), 199–227. http://dx.doi.org/10.1007/s12591-010-0005-y

- 14. L. Erbe, Q. Kong, B. Zhang, *Oscillation theory for functional differential equations*, New York: Routledge, 1995. http://dx.doi.org/10.1201/9780203744727
- 15. S. Grace, Oscillation criteria for third order nonlinear delay differential equations with damping, *Opusc. Math.*, **35** (2015), 485–497. http://dx.doi.org/10.7494/OpMath.2015.35.4.485
- S. Grace, R. Agarwal, R. Pavani, E. Thandapani, On the oscilation certain third order nonlinear functional differential equations, *Appl. Math. Comput.*, **202** (2008), 102–112. http://dx.doi.org/10.1016/j.amc.2008.01.025
- 17. K. Gopalsamy, *Stability and oscillation in delay differential equations of population dynamics*, Dordrecht: Springer, 1992. http://dx.doi.org/10.1007/978-94-015-7920-9
- 18. I. Gyori, F. Hartung, Stability of a single neuron model with delay, *J. Comput. Appl. Math.*, **157** (2003), 73–92. http://dx.doi.org/10.1016/S0377-0427(03)00376-5
- 19. I. Gyori, G. Ladas, Oscillation theory of delay differential equations with applications, Oxford: Clarendon Press, 1991. http://dx.doi.org/10.1093/oso/9780198535829.001.0001
- J. Hale, S. Verduyn Lunel, Introduction to functional differential equations, New York: Springer-Verlag, 1993. http://dx.doi.org/10.1007/978-1-4612-4342-7
- T. Hassan, B. El-Matary, Asymptotic behavior and oscillation of third-order nonlinear neutral differential equations with mixed nonlinearities, *Mathematics*, **11** (2023), 424. http://dx.doi.org/10.3390/math11020424
- 22. T. Hassan, B. El-Matary, Oscillation criteria for third order nonlinear neutral differential equation, *PLOMS Math.*, **1** (2021), 00001.
- T. Hassan, L. Erbe, A. Peterson, Forced oscillation of second order functional differential equations with mixed nonlinearities, *Acta Math. Sci.*, **31** (2011), 613–626. http://dx.doi.org/10.1016/S0252-9602(11)60261-0
- 24. T. Hassan, Q. Kong, Interval criteria for forced oscillation of differential equations with p-Laplacian, damping, and mixed nonlinearities, *Dynam. Syst. Appl.*, **20** (2011), 279–294.
- I. Jadlovská, G. Chatzarakis, J. Džurina, S. Grace, On sharp oscillation criteria for general third-order delay differential equations, *Mathematics*, 9 (2021), 1675. http://dx.doi.org/10.3390/math9141675
- 26. Y. Kitamura, Oscillation of functional differential equations with general deviating arguments, *Hiroshima Math. J.*, **15** (1985), 445–491.
- 27. R. Koplatadze, T. Chanturiya, Oscillating and monotone solutions of first-order differential equations with deviating argument, *Differ. Uravn.*, **18** (1982), 1463–1465.
- 28. B. Karpuz, Ö. Öcalan, New oscillation tests and some refinements for first-order delay dynamic equations, *Turk. J. Math.*, **40** (2016), 850–863. http://dx.doi.org/10.3906/mat-1507-98
- G. Ladas, Y. Sficas, I. Stavroulakis, Necessary and sufficient conditions for oscillations of higher order delay differential equations, *Trans. Amer. Math. Soc.*, 285 (1984), 81–90. http://dx.doi.org/10.2307/1999473

- 30. G. Ladas, V. Lakshmikantham, J. Papadakis, Oscillations of higher-order retarded differential equations generated by the retarded argument, In: *Delay and functional differential equations and their applications*, New York: Academic Press, 1972, 219–231. http://dx.doi.org/10.1016/B978-0-12-627250-5.50013-7
- 31. G. Ladas, V. Lakshmikantham, Sharp conditions for oscillations caused by delays, *Appl. Anal.*, **9** (1979), 93–98. http://dx.doi.org/10.1080/00036817908839256
- 32. T. Li, Y. Rogovchenko, On the asymptotic behavior of solutions to a class of thirdorder nonlinear neutral differential equations, *Appl. Math. Lett.*, **105** (2020), 106293. http://dx.doi.org/10.1016/j.aml.2020.106293
- 33. T. Li, C. Zhang, G. Xing, Oscillation of third-order neutral delay differential equations, *Abstr. Appl. Anal.*, **2012** (2012), 569201. http://dx.doi.org/10.1155/2012/569201
- 34. O. Moaaz, I. Dassios, W. Muhsin, A. Muhib, Oscillation theory for non-linear neutral delay differential equations of third order, *Appl. Sci.*, **10** (2020), 4855. http://dx.doi.org/10.3390/app10144855
- 35. O. Moaaz, E. Elabbasy, E. Shaaban, Oscillation criteria for a class of third order damped differential equations, *Arab Journal of Mathematical Sciences*, **24** (2018), 16–30. http://dx.doi.org/10.1016/j.ajmsc.2017.07.001
- 36. S. Padhi, S. Pati, *Theory of third-order differential equations*, New Delhi: Springer, 2014. http://dx.doi.org/10.1007/978-81-322-1614-8
- 37. Ch. Philos, On the existence of nonoscillatory solutions tending to zero at ∞ to differential equations with positive delays, *Arch. Math.*, **36** (1981), 168–178. http://dx.doi.org/10.1007/BF01223686
- 38. A. Tiryaki, M. Aktas, Oscillation criteria of a certain class of third order nonlinear delay differential equations with damping, *J. Math. Anal. Appl.*, **325** (2007), 54–68. http://dx.doi.org/10.1016/j.jmaa.2006.01.001
- M. Wei, C. Jiang, T. Li, Oscillation of third-order neutral differential equations with damping and distributed delay, *Adv. Differ. Equ.*, **2019** (2019), 426. http://dx.doi.org/10.1186/s13662-019-2363-2
- 40. L. Yang, Z. Xu, Oscillation of certain third-order quasilinear neutral differential equations, *Math. Slovaca*, **64** (2014), 85–100. http://dx.doi.org/10.2478/s12175-013-0189-z



© 2024 the Author(s), licensee AIMS Press. This is an open access article distributed under the terms of the Creative Commons Attribution License (https://creativecommons.org/licenses/by/4.0)