



Research article

Separated boundary value problems via quantum Hilfer and Caputo operators

Idris Ahmed^{1,2}, Sotiris K. Ntouyas³ and Jessada Tariboon^{1,*}

¹ Intelligent and Nonlinear Dynamic Innovations Research Center, Department of Mathematics, Faculty of Applied Science, King Mongkut's University of Technology North Bangkok, Bangkok 10800, Thailand

² Department of Mathematics, Faculty of Natural and Applied Sciences, Sule Lamido University, P.M.B 048 Kafin-Hausa, Jigawa State, Nigeria

³ Department of Mathematics, University of Ioannina, 451 10 Ioannina, Greece

* **Correspondence:** Email: jessada.t@sci.kmutnb.ac.th.

Abstract: This paper describes a new class of boundary value fractional-order differential equations of the q -Hilfer and q -Caputo types, with separated boundary conditions. The presented problem is converted to an equivalent integral form, and fixed-point theorems are used to prove the existence and uniqueness of solutions. Moreover, several special cases demonstrate how the proposed problems advance beyond the existing literature. Examples are provided to support the analysis presented.

Keywords: Hilfer fractional derivative; Caputo derivative; separated boundary condition; existence; fixed point theorems

Mathematics Subject Classification: 26A33, 34A12, 34A34, 34D20

1. Introduction

The concepts of fractional calculus have gained widespread recognition as an important area within pure mathematics. The concepts within fractional calculus have been studied by numerous mathematicians, given their significance across various fields of knowledge, see [1–4]. Theoretical aspects of fractional differential equations have attracted considerable interest since the advent of fractional calculus. Owing to the nonlocal nature of fractional-order differential equations, researchers possess the flexibility to choose and apply the most suitable operator, thereby accurately representing complex real-world phenomena. However, there are numerous versions of integrals and derivatives of arbitrary fractional order, employing various types of operators, as detailed in [5–11].

Fixed-point theorems serve as valuable tools for establishing both the existence and uniqueness of solutions to fractional differential equations. The methodology has been extensively studied by numerous mathematicians, and vast results have been published, see [12–18] and references therein. Furthermore, in the physical and life sciences, fractional calculus has widespread applicability across various domains, including image processing, complex systems, traffic flow, etc. Numerous researchers have studied many different kinds of initial and boundary value problems with various types of fractional operators, using techniques based on fixed-point theorems, [19–26].

The concept of sequential fractional derivatives was first introduced in [27]. Since its inception, numerous researchers have made significant contributions to the advancement of this field. As a result, several research articles have been published. For more research insight, we refer to [28–34].

Wang et al. [35], studied the turbulent flow model within the framework of the Caputo-Hadamard fractional derivatives of the form:

$$\begin{cases} {}^{CH}\mathfrak{D}^{\tau_1}\psi_{p(s)}({}^{CH}\mathfrak{D}^{\tau_2}u(s)) + g(u(s), \mathfrak{I}^{\alpha_1, \alpha_2}u(s)) = 0, & s \in [1, \lambda], \\ u'(1) = \alpha u(\lambda), \quad u(1) = u''(1) = 0, \\ {}^{CH}\mathfrak{D}^{\tau_2}u(1) = 0, \\ 2 < \tau_2 < 3, \quad 0 < \tau_1 < 1, \quad \alpha_1, \alpha_2 > 0, \quad \frac{\lambda}{2} < \alpha \leq \frac{2\lambda}{4 - \lambda}. \end{cases} \quad (1.1)$$

In [36], the authors discussed the existence and uniqueness of positive solutions for a class of Caputo fractional differential equations described by:

$$\begin{cases} {}^C\mathfrak{D}^{\alpha_1}\psi_{p(s)}({}^C\mathfrak{D}^{\alpha_2}u(s)) + g(s, u(s)) = 0, & s \in [0, 1], \\ u(0) = k, \quad u(1) = \sum_{n=1}^m \varphi_n {}^{RL}\mathfrak{I}^{\delta_n}u(\beta_n), \quad m \in \mathbb{N}, \quad \varphi_n \geq 0, \quad k > 0, \\ 0 < \beta_1 < \beta_2 < \dots < \beta_m < 1, \quad 0 < \alpha_1, \alpha_2 < 1, \quad \psi_{p(s)} > 2, \quad \delta_n > 0. \end{cases} \quad (1.2)$$

In 2018, Tariboon et al. [37] considered the sequential Caputo and Hadamard fractional nonseparated boundary value problem given by:

$$\begin{cases} {}^C\mathfrak{D}^{\alpha_1}({}^H\mathfrak{D}^{\alpha_2}u)(s) = g(s, u(s)), \quad s \in (a, b), \quad 0 < \alpha_1, \alpha_2 < 1, \\ c_1u(a) + c_2({}^H\mathfrak{D}^{\alpha_2}u)(b) = 0, \quad c_3u(a) + c_4({}^H\mathfrak{D}^{\alpha_2}u)(b) = 0, \\ \text{and} \\ {}^H\mathfrak{D}^{\alpha_2}({}^C\mathfrak{D}^{\alpha_1}u)(s) = g(s, u(s)), \quad s \in (a, b), \\ c_1u(a) + c_2({}^C\mathfrak{D}^{\alpha_1}u)(b) = 0, \quad c_3u(a) + c_4({}^C\mathfrak{D}^{\alpha_1}u)(b) = 0, \quad c_1, c_2, c_3, c_4 \in \mathbb{R}. \end{cases} \quad (1.3)$$

The investigation employed Banach and Krasnoselskii's fixed-point theorems, alongside Leray-Schauder's nonlinear alternative, to establish the existence and uniqueness of the results.

Asawasamrit et al. [38] studied the nonlocal boundary value problem involving the Hilfer fractional derivative of the form:

$$\begin{cases} {}^H\mathcal{D}^{\alpha_1, \alpha_2}u(s) = g(s, u(s)), \quad s \in [a, b], \quad 1 < \alpha_1 < 2, \quad 0 \leq \alpha_2 \leq 1, \\ u(a) = 0, \quad u(b) = \sum_{i=1}^k c_i \mathfrak{I}^{\alpha_3}u(\vartheta_i), \quad c_i \in \mathbb{R}, \quad \alpha_3 \geq 0, \quad \vartheta_i \in [a, b]. \end{cases} \quad (1.4)$$

Jackson [39, 40] initiated the idea of q -difference calculus. For more basic concepts of q -difference calculus, see [41, 42]. Since then, numerous researchers have delved into the theoretical analysis of q -fractional-order differential equations, see [43–48].

Allouch et al. [49] studied the q -difference equation with nonlinear integral boundary conditions of the form:

$$\begin{cases} \mathcal{D}_q^\zeta u(\kappa) = g(\kappa, u(\kappa)), \kappa \in [0, b], 1 < \zeta < 2, 0 < q < 1, b > 0, \\ u(0) - u'(0) = \int_0^b g(\vartheta, u(\vartheta))d\vartheta, u(A) + u'(b) = \int_0^b h(\vartheta, u(\vartheta))d\vartheta. \end{cases} \quad (1.5)$$

Measures of noncompactness and Mönch's fixed point theorems were utilized to derive the results.

Inspired by recent publications, we propose a new type of separated boundary value problems and investigate its theoretical analysis. The problem under consideration takes the form of

$$\begin{cases} {}^H\mathcal{D}_q^{\alpha,\beta}({}^C\mathcal{D}_q^\delta z)(t) = f(t, z(t)), t \in [0, T], \\ z(0) + \lambda_1 {}^C\mathcal{D}_q^{\gamma+\delta-1} z(0) = 0, z(T) + \lambda_2 {}^C\mathcal{D}_q^{\gamma+\delta-1} z(T) = 0, \\ 0 < \alpha, \delta, q < 1, 0 \leq \beta \leq 1, \lambda_1, \lambda_2 \in \mathbb{R}, T > 0, \end{cases} \quad (1.6)$$

where ${}^C\mathcal{D}_q^\delta(\cdot)$ and ${}^H\mathcal{D}_q^{\alpha,\beta}(\cdot)$, respectively, are the Caputo and Hilfer fractional derivatives of orders δ , α , and type β such that $\gamma = \alpha + \beta(1 - \alpha)$ with $\gamma + \delta > 1$, and $f : [0, T] \times \mathbb{R} \rightarrow \mathbb{R}$ is a continuous function.

The existence and uniqueness of solutions to q sequential fractional-order boundary value problems have not been extensively studied. In our study, we introduce a new class of sequential q -Hilfer and q -Caputo fractional differential equations with separated boundary conditions and provide a comprehensive theoretical analysis.

The novelty of our study lies in the fact that we consider a sequential fractional boundary value problem combining q -Hilfer and q -Caputo fractional derivative operators subjected to non-separated boundary conditions. To the best of our knowledge, this is the first paper to appear in the literature. The method used is standard, but its configuration in the Hilfer-Caputo sequential boundary value problem (1.6) is new. The results are new and significantly enrich the existing results in the literature on Hilfer boundary value problems.

The rest of the paper is organized as follows: Section 2 revisits essential definitions, lemmas, and theorems. Section 3 focuses on establishing an integral equivalent form of the proposed problem, which enables us to prove the existence and uniqueness of results. In Section 4, two examples are presented. Section 5 provides the conclusion of the paper.

2. Preliminaries

The section includes prerequisite facts, definitions, and key lemmas that will assist in proving the main results. The space $\mathcal{X} = C([0, T], \mathbb{R})$ constitutes a Banach space comprising all continuous functions over $[0, T]$ with

$$\|z\| = \sup_{t \in [0, T]} |z(t)|.$$

Recall that for $q \in (0, 1)$ and $g, h \in \mathbb{R}$, the following properties hold [42]:

$$[g]_q = \frac{q^g - 1}{q - 1},$$

and

$$(g-h)_q^{(0)} = 1, \quad (g-h)_q^{(k)} = \prod_{n=0}^{k-1} (g-hq^n); \quad k \in \mathbb{N}.$$

Moreover, for $\alpha \in \mathbb{R}$, we have

$$(g-h)_q^{(\alpha)} = g^\alpha \prod_{n=0}^{\infty} \left(\frac{1 - (\frac{h}{g})q^n}{1 - (\frac{h}{g})q^{n+\alpha}} \right).$$

The q analog gamma function is given by

$$\Gamma_q(\alpha) = \frac{(1-q)_q^{(\alpha-1)}}{(1-q)^{\alpha-1}}; \quad \alpha \in \mathbb{R} \setminus \{0, -1, -2, \dots\},$$

such that $\Gamma_q(\alpha + 1) = [\alpha]_q \Gamma_q(\alpha)$.

For $u : [0, T] \rightarrow \mathbb{R}$ and $0 < q < 1$, the q -derivative of u is defined by

$$\mathcal{D}_q u(t) = \frac{u(t) - u(qt)}{(1-q)t}; \quad t \neq 0, \quad \mathcal{D}_q u(0) = \lim_{t \rightarrow 0} \mathcal{D}_q u(t).$$

Moreover, the higher-order q -derivative shows

$$\mathcal{D}_q^0 u(t) = u(t), \quad \mathcal{D}_q^n u(t) = \mathcal{D}_q (\mathcal{D}_q^{n-1} u)(t), \quad n \in \mathbb{N}.$$

For setting $J_t = \{tq^n : n \in \mathbb{N}, t \geq 0\} \cup \{0\}$, the analog q -integral of a function $u : J_t \rightarrow \mathbb{R}$ is of the form:

$$\mathcal{I}_q u(t) = \int_0^t u(v) d_q v = \sum_{n=0}^{\infty} t(1-q)q^n u(tq^n),$$

provided that the right-hand side converges. Note that $\mathcal{D}_q (\mathcal{I}_q u)(t) = u(t)$, and if u is continuous at 0, then

$$\mathcal{I}_q (\mathcal{D}_q u)(t) = u(t) - u(0).$$

Definition 2.1. [45] Let $w : [0, T] \rightarrow \mathbb{R}$, $\vartheta \in [0, T]$, and $\alpha > 0$. The integral operator

$$\mathcal{I}_q^\alpha w(\vartheta) = \frac{1}{\Gamma_q(\alpha)} \int_0^\vartheta (\vartheta - qv)_q^{(\alpha-1)} w(v) d_q v,$$

is called the q -fractional-order integral in the Riemann-Liouville sense of order $\alpha > 0$ for the function w , and $\mathcal{I}_q^0 w(\vartheta) = w(\vartheta)$.

Lemma 2.1. [45] For $0 \leq \alpha < \infty$ and $\sigma \in (-1, +\infty)$. If $w(\vartheta) = (\vartheta - a)^{(\sigma)}$, then

$$\mathcal{I}_q^\alpha w(\vartheta) = \frac{\Gamma_q(\sigma + 1)}{\Gamma_q(\alpha + \sigma + 1)} (\vartheta - a)_q^{(\alpha + \sigma)}; \quad 0 < a < \vartheta < T,$$

also

$$(\mathcal{I}_q^\alpha 1)(\vartheta) = \frac{1}{\Gamma_q(\alpha + 1)} (\vartheta - a)_q^{(\alpha)}.$$

Definition 2.2. [50] Let $w : [0, T] \rightarrow \mathbb{R}$, $\vartheta \in [0, T]$, $0 < \alpha < 1$. The derivative operator

$${}^{RL}\mathcal{D}_q^\alpha w(\vartheta) = \frac{1}{\Gamma_q(1-\alpha)} \mathcal{D}_q \int_0^\vartheta (\vartheta - qv)_q^{(-\alpha)} w(v) d_q v,$$

is called the q -fractional-order derivative in Riemann-Liouville sense of order α for the function w .

Definition 2.3. [50] Let $w \in C_q^1([0, T], \mathbb{R})$, $\vartheta \in [0, T]$, $0 < \alpha < 1$. The derivative operator

$${}^C\mathcal{D}_q^\alpha w(\vartheta) = \frac{1}{\Gamma_q(1-\alpha)} \int_0^\vartheta (\vartheta - qv)_q^{(-\alpha)} \mathcal{D}_q w(v) d_q v, \quad (2.1)$$

is called the q -fractional-order derivative in the Caputo sense of order α .

Lemma 2.2. [50] Let $w : [0, T] \rightarrow \mathbb{R}$ and $\alpha, \sigma \geq 0$. Thus

- (i). $\mathcal{I}_q^\alpha (\mathcal{I}_q^\sigma w)(t) = \mathcal{I}_q^{\alpha+\sigma} w(t)$,
- (ii). ${}^C\mathcal{D}_q^\alpha (\mathcal{I}_q^\alpha w)(t) = w(t)$.

Definition 2.4. [51] Let $w \in C_q^1([0, T], \mathbb{R})$ and $0 < \alpha < 1$, $0 \leq \beta \leq 1$. The operator

$${}^H\mathcal{D}_q^{\alpha,\beta} w(\vartheta) = \mathcal{I}_q^{\beta(1-\alpha)} \left[\mathcal{D}_q \left(\mathcal{I}_q^{(1-\beta)(1-\alpha)} w \right) \right] (\vartheta), \quad (2.2)$$

is called q -Hilfer fractional derivative of order α with a parameter β . Note that ${}^H\mathcal{D}_q^{\alpha,\beta}$ can be written as

$${}^H\mathcal{D}_q^{\alpha,\beta} w = \mathcal{I}_q^{\beta(1-\alpha)} \mathcal{D}_q \left(\mathcal{I}_q^{(1-\beta)(1-\alpha)} w \right) = \mathcal{I}_q^{\beta(1-\alpha)} \mathcal{D}_q \left(\mathcal{I}_q^{1-\gamma} w \right), \quad \gamma = \alpha + \beta(1-\alpha).$$

Lemma 2.3. [50] Suppose that $0 < \alpha < 1$. Then we have

$$\mathcal{I}_q^\alpha \left({}^{RL}\mathcal{D}_q^\alpha w \right) (\vartheta) = w(\vartheta) - \frac{1}{\Gamma_q(\alpha)} \vartheta^{\alpha-1} (\mathcal{I}_q^{1-\alpha} w)(0),$$

and moreover,

$$\mathcal{I}_q^\alpha \left({}^C\mathcal{D}_q^\alpha w \right) (\vartheta) = w(\vartheta) + k, \quad k \in \mathbb{R}.$$

Remark 2.1. Note that if $\beta = 0$, from problem (1.6), we have

$$\begin{cases} {}^{RL}\mathcal{D}_q^\alpha ({}^C\mathcal{D}_q^\delta z)(t) = f(t, z(t)), & t \in [0, T], \\ z(0) + \lambda_1 {}^C\mathcal{D}_q^{\alpha+\delta-1} z(0) = 0, & z(T) + \lambda_2 {}^C\mathcal{D}_q^{\alpha+\delta-1} z(T) = 0, \end{cases}$$

and if $\beta = 1$, we have

$$\begin{cases} {}^C\mathcal{D}_q^\alpha ({}^C\mathcal{D}_q^\delta z)(t) = f(t, z(t)), & t \in [0, T], \\ z(0) + \lambda_1 {}^C\mathcal{D}_q^\delta z(0) = 0, & z(T) + \lambda_2 {}^C\mathcal{D}_q^\delta z(T) = 0, \end{cases}$$

which are the q sequential Riemann-Liouville and Caputo derivatives with separated boundary conditions.

3. Main results

In this part, we begin by employing techniques from Lemma 2.3 to establish an integral equation associated with problem (1.6). To this end, we introduce the lemma, addressing a linear variant of problem (1.6), which serves as the fundamental tool for transforming the problem into a fixed-point problem.

Lemma 3.1. *Let $0 < \alpha, \delta < 1$, $0 \leq \beta \leq 1$, $\gamma = \alpha + \beta(1 - \alpha)$, $\lambda_1, \lambda_2 \in \mathbb{R}$ and $0 < q < 1$ and*

$$Q = T^{(\gamma+\delta-1)} + (\lambda_2 - \lambda_1)\Gamma_q(\gamma + \delta) \neq 0.$$

Suppose $g \in C([0, T], \mathbb{R})$. If $z \in C^2_q([0, T], \mathbb{R})$, then, the linear problem

$$\begin{cases} {}^H\mathcal{D}_q^{\alpha,\beta}({}^C\mathcal{D}_q^\delta z)(t) = g(t), & t \in [0, T], \\ z(0) + \lambda_1 {}^C\mathcal{D}_q^{\gamma+\delta-1}z(0) = 0, & z(T) + \lambda_2 {}^C\mathcal{D}_q^{\gamma+\delta-1}z(T) = 0, \end{cases} \quad (3.1)$$

is equivalent to the integral equation:

$$\begin{aligned} z(t) = & \frac{\lambda_1\Gamma_q(\gamma + \delta) - t^{(\gamma+\delta-1)}}{Q} \left[\frac{1}{\Gamma_q(\alpha + \delta)} \int_0^T (T - qv)_q^{(\alpha+\delta-1)} g(v) d_q v \right. \\ & \left. + \frac{\lambda_2}{\Gamma_q(\alpha - \gamma + 1)} \int_0^T (T - qv)_q^{(\alpha-\gamma)} g(v) d_q v \right] \\ & + \frac{1}{\Gamma_q(\alpha + \delta)} \int_0^t (t - qv)_q^{(\alpha+\delta-1)} g(v) d_q v, \quad t \in [0, T]. \end{aligned} \quad (3.2)$$

Proof. Suppose $z \in C^2_q([0, T], \mathbb{R})$ satisfies problem (3.1), then, we show that z satisfies the integral (3.2). Since

$${}^H\mathcal{D}_q^{\alpha,\beta}(\cdot) = I_q^{\beta(1-\alpha)} \mathcal{D}_q I_q^{(1-\beta)(1-\alpha)}(\cdot) = I_q^{\beta(1-\alpha)} \mathcal{D}_q I_q^{1-\gamma}(\cdot), \quad (3.3)$$

then, make use of Eq (3.3), the first equation of (3.1) can be simplified as

$$I_q^{\beta(1-\alpha)} \mathcal{D}_q I_q^{1-\gamma}({}^C\mathcal{D}_q^\delta z)(t) = g(t). \quad (3.4)$$

Taking I_q^α to both sides of Eq (3.4) and utilize the techniques in Lemma 2.3, yields

$${}^C\mathcal{D}_q^\delta z(t) = \frac{A}{\Gamma_q(\gamma)} t^{(\gamma-1)} + \frac{1}{\Gamma_q(\alpha)} \int_0^t (t - qv)_q^{(\alpha-1)} g(v) d_q v, \quad A \in \mathbb{R}, \quad (A \text{ constant}). \quad (3.5)$$

Also, taking I_q^δ to both sides of Eq (3.5) and utilize the techniques in Lemma 2.3, we get

$$z(t) = B + \frac{A}{\Gamma_q(\gamma + \delta)} t^{(\gamma+\delta-1)} + \frac{1}{\Gamma_q(\alpha + \delta)} \int_0^t (t - qv)_q^{(\alpha+\delta-1)} g(v) d_q v, \quad (3.6)$$

where $B \in \mathbb{R}$ is an arbitrary constant. Applying the operator ${}^C\mathcal{D}_q^{\gamma+\delta-1}$ to both sides of Eq (3.6), yields

$${}^C\mathcal{D}_q^{\gamma+\delta-1}z(t) = A + \frac{1}{\Gamma_q(\alpha - \gamma + 1)} \int_0^t (t - qv)_q^{(\alpha-\gamma)} g(v) d_q v. \quad (3.7)$$

Thus, from the condition $z(0) + \lambda_1 {}^C \mathcal{D}_q^{\gamma+\delta-1} z(0) = 0$, Eqs (3.6) and (3.7), we get

$$z(0) + \lambda_1 {}^C \mathcal{D}_q^{\gamma+\delta-1} z(0) = \lambda_1 A + B = 0 \implies B = -\lambda_1 A. \quad (3.8)$$

From $z(T) + \lambda_2 {}^C \mathcal{D}_q^{\gamma+\delta-1} z(T) = 0$, Eqs (3.6) and (3.7), we obtain

$$\begin{aligned} 0 = & B + \lambda_2 A + \frac{A}{\Gamma_q(\gamma + \delta)} T^{(\gamma+\delta-1)} + \frac{\lambda_2}{\Gamma_q(\alpha - \gamma + 1)} \int_0^T (T - qv)_q^{(\alpha-\gamma)} g(v) d_q v \\ & + \frac{1}{\Gamma_q(\alpha + \delta)} \int_0^T (T - qv)_q^{(\alpha+\delta-1)} g(v) d_q v. \end{aligned} \quad (3.9)$$

Upon simplification and substituting $B = -\lambda_1 A$ in Eq (3.9), we get

$$B = \frac{\lambda_1 \Gamma_q(\gamma + \delta)}{Q} \left[\frac{1}{\Gamma_q(\alpha + \delta)} \int_0^T (T - qv)_q^{(\alpha+\delta-1)} g(v) d_q v + \frac{\lambda_2}{\Gamma_q(\alpha - \gamma + 1)} \int_0^T (T - qv)_q^{(\alpha-\gamma)} g(v) d_q v \right],$$

and

$$A = -\frac{\Gamma_q(\gamma + \delta)}{Q} \left[\frac{1}{\Gamma_q(\alpha + \delta)} \int_0^T (T - qv)_q^{(\alpha+\delta-1)} g(v) d_q v + \frac{\lambda_2}{\Gamma_q(\alpha - \gamma + 1)} \int_0^T (T - qv)_q^{(\alpha-\gamma)} g(v) d_q v \right].$$

□

To explore the numerical behavior of the integral solution of the proposed problem (1.6), we vary the fractional-orders associated with the problem. The following parameters, α, β , and δ , respectively, were considered. The respective graphical analysis are shown in Figures 1 and 2, respectively. Figures 1a–1c illustrate the behavior of the solution of the integral (3.2) when varying the fraction-order α . Moreover, the corresponding 3D plots is displayed in Figures 2a–2c, respectively.

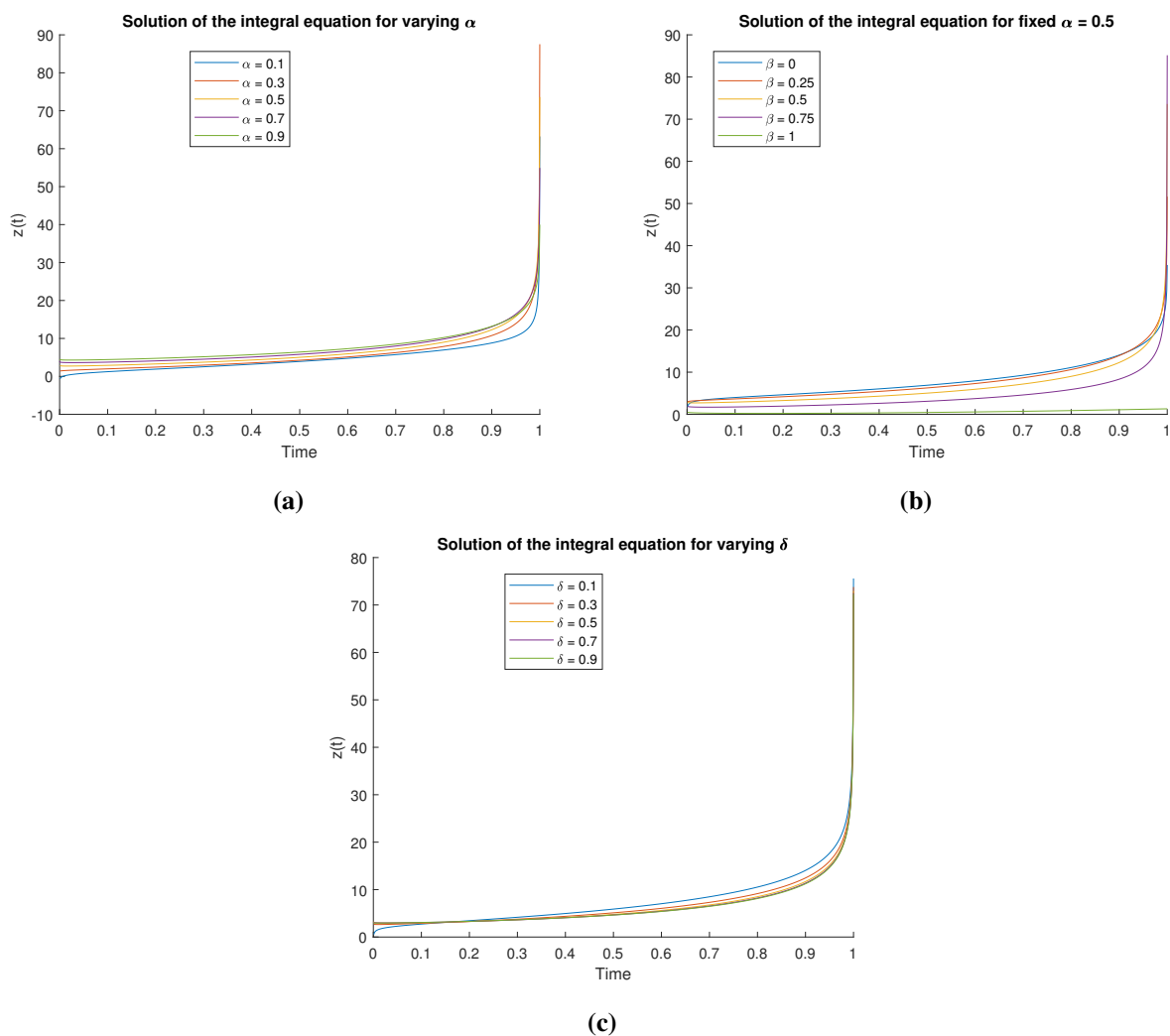


Figure 1. Solution of the integral Eq (3.2) for values of α, β and δ for the function $g(t) = t^2 + 2t + 1$ and $t \in [0, 1]$.

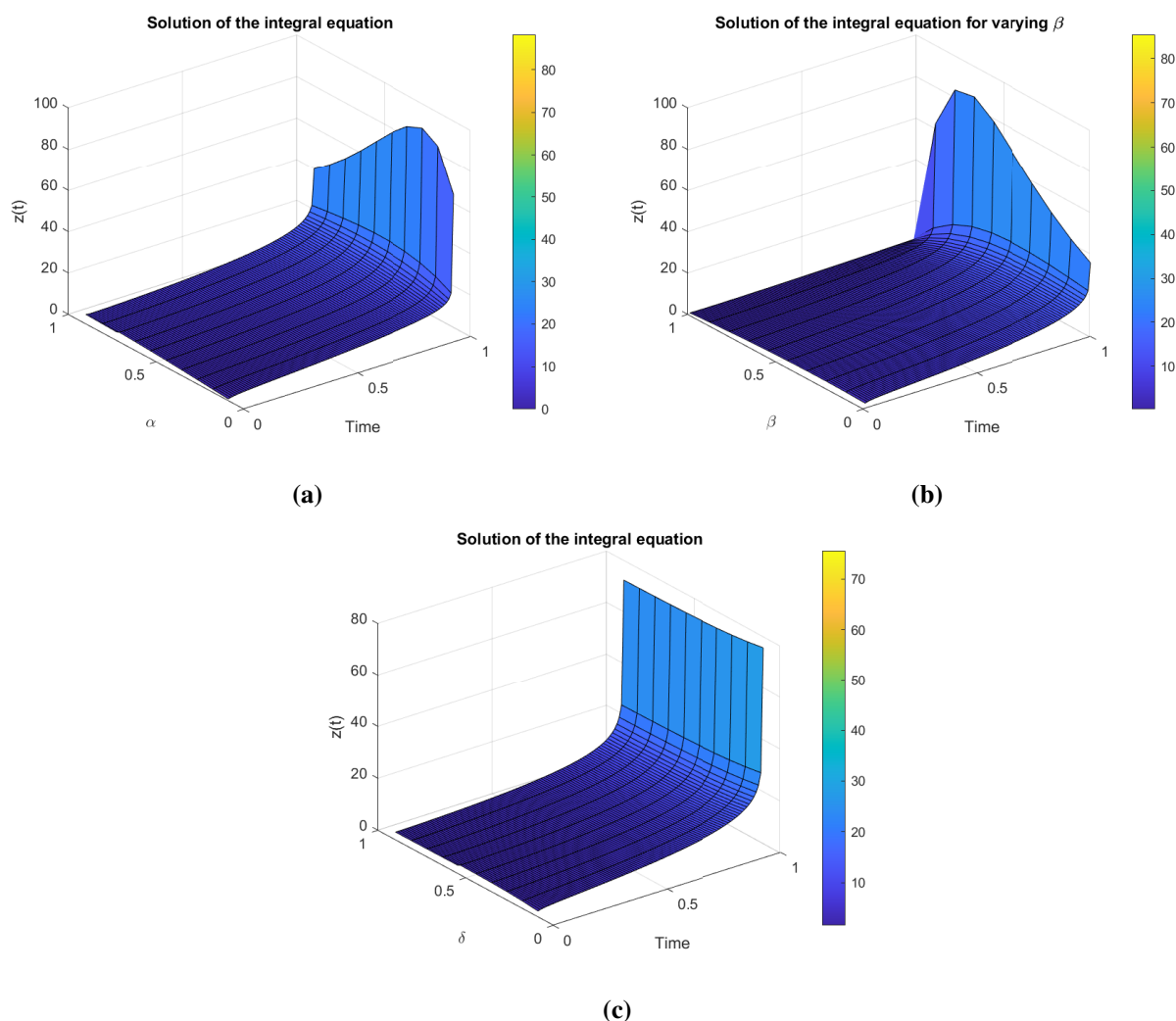


Figure 2. 3D plots for the solution of (3.2) for the function $g(t) = t^2 + 2t + 1$ and $t \in [0, 1]$.

3.1. Existence results

By employing Krasnoselskii's fixed-point theorem and Leray-Schauder's nonlinear alternative, in this subsection, we will present the proof of the existence results of (1.6).

Lemma 3.2. (Krasnoselskii's fixed point theorem) [52] Let $M \subset \mathcal{X}$ be closed, bounded, convex, and nonempty. Suppose $\mathcal{F}_1, \mathcal{F}_2$ be operators such that:

- (i) $\mathcal{F}_1 z + \mathcal{F}_2 z_1 \in M$ whenever $z, z_1 \in M$;
- (ii) \mathcal{F}_2 is a contraction mapping;
- (iii) \mathcal{F}_1 is compact and continuous.

Then there exists $w \in M$ such that $w = \mathcal{F}_1 w + \mathcal{F}_2 w$.

Theorem 3.1. Let $0 < \alpha, \delta < 1$, $0 \leq \beta \leq 1$, and $\gamma = \alpha + \beta(1 - \alpha)$. Suppose that the function $f : [0, T] \times \mathbb{R} \rightarrow \mathbb{R}$ is continuous and satisfies:

(\mathcal{H}_1) There exists $L > 0$, (constant) such that

$$|f(t, z) - f(t, z_1)| \leq L|z - z_1|, \text{ for } t \in [0, T], \text{ and } z, z_1 \in \mathbb{R}.$$

(\mathcal{H}_2) $|f(t, z)| \leq \Psi(t), \forall (t, z) \in [0, T] \times \mathbb{R}$ and $\Psi \in C([0, T], \mathbb{R}^+)$;

Then there exists at least one solution of the quantum Hilfer and Caputo separated boundary value problem (1.6) on $[0, T]$, provided that

$$L\left(\Delta - \frac{T^{(\alpha+\delta)}}{\Gamma_q(\alpha + \delta + 1)}\right) < 1, \quad (3.10)$$

where

$$\Delta = \frac{|\lambda_1|\Gamma_q(\gamma + \delta) + T^{(\gamma+\delta-1)}}{|Q|} \left[\frac{T^{(\alpha+\delta)}}{\Gamma_q(\alpha + \delta + 1)} + |\lambda_2| \frac{T^{(\alpha-\gamma+1)}}{\Gamma_q(\alpha - \gamma + 2)} \right] + \frac{T^{(\alpha+\delta)}}{\Gamma_q(\alpha + \delta + 1)}. \quad (3.11)$$

Proof. Now, from equation 3.2, define $\mathcal{F} : \mathcal{X} \rightarrow \mathcal{X}$ by

$$\begin{aligned} (\mathcal{F}z)(t) &= \frac{\lambda_1\Gamma_q(\gamma + \delta) - t^{(\gamma+\delta-1)}}{Q} \left[\frac{1}{\Gamma_q(\alpha + \delta)} \int_0^T (T - qv)_q^{(\alpha+\delta-1)} f(v, z(v)) d_q v \right. \\ &\quad \left. + \frac{\lambda_2}{\Gamma_q(\alpha - \gamma + 1)} \int_0^T (T - qv)_q^{(\alpha-\gamma)} f(v, z(v)) d_q v \right] \\ &\quad + \frac{1}{\Gamma_q(\alpha + \delta)} \int_0^t (t - qv)_q^{(\alpha+\delta-1)} f(v, z(v)) d_q v, \quad t \in [0, T]. \end{aligned}$$

Suppose $\sup_{t \in [0, T]} \Psi(t) = \|\Psi\|$ and $\sigma \geq \|\Psi\|\Delta$ such that $B_\sigma = \{x \in \mathcal{X} : \|x\| \leq \sigma\}$. Now, we set

$$\mathcal{F}_1 z(t) = \frac{1}{\Gamma_q(\alpha + \delta)} \int_0^t (t - qv)_q^{(\alpha+\delta-1)} f(v, z(v)) d_q v, \quad t \in [0, T],$$

and

$$\begin{aligned} \mathcal{F}_2 z(t) &= \frac{\lambda_1\Gamma_q(\gamma + \delta) - t^{(\gamma+\delta-1)}}{Q} \left[\frac{1}{\Gamma_q(\alpha + \delta)} \int_0^T (T - qv)_q^{(\alpha+\delta-1)} f(v, z(v)) d_q v \right. \\ &\quad \left. + \frac{\lambda_2}{\Gamma_q(\alpha - \gamma + 1)} \int_0^T (T - qv)_q^{(\alpha-\gamma)} f(v, z(v)) d_q v \right], \quad t \in [0, T]. \end{aligned}$$

Then, for any $z, z_1 \in B_\sigma$, we get

$$\begin{aligned} &|(\mathcal{F}_1 z)(t) + (\mathcal{F}_2 z_1)(t)| \\ &\leq \sup_{t \in [0, T]} \left\{ \frac{1}{\Gamma_q(\alpha + \delta)} \int_0^t (t - qv)_q^{(\alpha+\delta-1)} f(v, z(v)) d_q v \right. \\ &\quad \left. + \frac{\lambda_1\Gamma_q(\gamma + \delta) - t^{\gamma+\delta-1}}{Q} \left[\frac{1}{\Gamma_q(\alpha + \delta)} \int_0^T (T - qv)_q^{(\alpha+\delta-1)} f(v, z_1(v)) d_q v \right. \right. \\ &\quad \left. \left. + \frac{\lambda_2}{\Gamma_q(\alpha - \gamma + 1)} \int_0^T (T - qv)_q^{(\alpha-\gamma)} f(v, z_1(v)) d_q v \right] \right\} \end{aligned}$$

$$\begin{aligned} &\leq \|\Psi\| \left(\frac{T^{(\alpha+\delta)}}{\Gamma_q(\alpha+\delta+1)} + \frac{|\lambda_1| \Gamma_q(\gamma+\delta) + T^{(\gamma+\delta-1)}}{|Q|} \left(\frac{T^{(\alpha+\delta)}}{\Gamma_q(\alpha+\delta+1)} + |\lambda_2| \frac{T^{(\alpha-\gamma+1)}}{\Gamma_q(\alpha-\gamma+2)} \right) \right) \\ &\leq \|\Psi\| \Delta \leq \sigma. \end{aligned}$$

Hence $\|\mathcal{F}_1 z + \mathcal{F}_2 z_1\| \leq \sigma$, which shows that $\mathcal{F}_1 z + \mathcal{F}_2 z_1 \in B_\sigma$. Therefore, the condition (i) of Lemma 3.2 is satisfied.

To show condition (ii) of Lemma 3.2, we proceed as follows, for any $z, z_1 \in C([0, T], \mathbb{R})$, gives

$$\begin{aligned} &|(\mathcal{F}_2 z)(t) - (\mathcal{F}_2 z_1)(t)| \\ &\leq \frac{|\lambda_1| \Gamma_q(\gamma+\delta) + t^{(\gamma+\delta-1)}}{|Q|} \left[\frac{1}{\Gamma_q(\alpha+\delta)} \int_0^T (T - qv)^{(\alpha+\delta-1)} |f(v, z(v)) d_q v - f(v, z_1(v)) d_q v| \right. \\ &\quad \left. + \frac{|\lambda_2|}{\Gamma_q(\alpha-\gamma+1)} \int_0^T (T - qv)^{(\alpha-\gamma)} |f(v, z(v)) d_q v - f(v, z_1(v)) d_q v| \right] \\ &\leq L \left(\frac{|\lambda_1| \Gamma_q(\gamma+\delta) + T^{(\gamma+\delta-1)}}{|Q|} \left(\frac{T^{(\alpha+\delta)}}{\Gamma_q(\alpha+\delta+1)} + |\lambda_2| \frac{T^{(\alpha-\gamma+1)}}{\Gamma_q(\alpha-\gamma+2)} \right) \right) \|z - z_1\| \\ &= L \left(\Delta - \frac{T^{(\alpha+\delta)}}{\Gamma_q(\alpha+\delta+1)} \right) \|z - z_1\|. \end{aligned}$$

Consequently, $\|(\mathcal{F}_2 z) - (\mathcal{F}_2 z_1)\| \leq L \left(\Delta - \frac{T^{(\alpha+\delta)}}{\Gamma_q(\alpha+\delta+1)} \right) \|z - z_1\|$, and hence, by (3.10), \mathcal{F}_2 is a contraction. Hence, condition (ii) of Lemma 3.2 is satisfied.

Moreover, since $f \in C([0, T], \mathbb{R})$, the operator \mathcal{F}_1 is continuous and it is uniformly bounded, as

$$\|\mathcal{F}_1 z\| \leq \frac{T^{(\alpha+\delta)}}{\Gamma_q(\alpha+\delta+1)} \|\Psi\|.$$

Set $\sup_{(t,z) \in [0,T] \times \mathcal{B}_\sigma} |f(t, z)| = \hat{f}$. Then

$$\begin{aligned} |(\mathcal{F}_1 z)(t_2) - (\mathcal{F}_1 z)(t_1)| &= \frac{1}{\Gamma_q(\alpha+\delta)} \left| \int_0^{t_1} [(t_2 - qv)^{(\alpha+\delta-1)} - (t_1 - qv)^{(\alpha+\delta-1)}] f(v, z(v)) d_q v \right. \\ &\quad \left. + \int_{t_1}^{t_2} (t_2 - qv)^{(\alpha+\delta-1)} f(v, z(v)) d_q v \right| \\ &\leq \frac{\hat{f}}{\Gamma_q(\alpha+\delta+1)} [2(t_2 - t_1)^{(\alpha+\delta)} + |t_2^{(\alpha+\delta)} - t_1^{(\alpha+\delta)}|], \end{aligned}$$

$\rightarrow 0$. as $t_2 - t_1 \rightarrow 0$, independently of z . Hence, as a consequence of the Arzelá-Ascoli theorem, this shows that \mathcal{F}_1 is compact on \mathcal{B}_σ .

Therefore, since all the assumptions of Lemma 3.2 are satisfied, we conclude that there exists at least one solution of quantum Hilfer and Caputo separated boundary value problem (1.6) on $[0, T]$. \square

The next existence result relies on Leray-Schauder's nonlinear alternative.

Lemma 3.3. (Leray-Schauder's Nonlinear Alternative) [53] Let $C \subset X$ be closed and convex of X , $\mathcal{U} \subset C$ be open, and $0 \in \mathcal{U}$. Suppose $F : \bar{\mathcal{U}} \rightarrow C$ is a continuous and compact map. Then either

- (i) F has a fixed point in $\bar{\mathcal{U}}$ or
- (ii) $\exists z \in \partial \mathcal{U}$ and $\omega \in (0, 1)$ with $z = \omega F(z)$.

Theorem 3.2. Suppose that the function $f : [0, T] \times \mathbb{R} \rightarrow \mathbb{R}$ is continuous and satisfies:

(\mathcal{H}_3) there exists a function $\Lambda : [0, \infty) \rightarrow (0, \infty)$ continuous and nondecreasing and a function $G \in C([0, T], \mathbb{R}_+)$ such that

$$|f(t, z)| \leq G(t)\Lambda(\|z\|) \text{ for each } (t, z) \in [0, T] \times \mathbb{R};$$

(\mathcal{H}_4) There exists $C > 0$ (constant) such that

$$1 < \frac{C}{\Lambda(C)\|G\|\Delta}.$$

Then, there exists at least one solution of problem (1.6) on $[0, T]$.

Proof. Firstly, we show that \mathcal{F} maps a bounded set into bounded sets in \mathcal{X} . For any $k > 0$, let $\mathbb{B}_k = \{z \in \mathcal{X} : \|z\| \leq k\}$ be a bounded set in \mathcal{X} . Then, for $t \in [0, T]$ yields

$$\begin{aligned} |(\mathcal{F}z)(t)| &\leq \sup_{t \in [0, T]} \left\{ \frac{1}{\Gamma_q(\alpha + \delta)} \int_0^t (t - qv)_q^{(\alpha + \delta - 1)} f(v, z(v)) d_q v \right. \\ &\quad + \frac{\lambda_1 \Gamma_q(\gamma + \delta) - t^{\gamma + \delta - 1}}{Q} \left[\frac{1}{\Gamma_q(\alpha + \delta)} \int_0^T (T - qv)_q^{(\alpha + \delta - 1)} f(v, z(v)) d_q v \right. \\ &\quad \left. \left. + \frac{\lambda_2}{\Gamma_q(\alpha - \gamma + 1)} \int_0^T (T - qv)_q^{(\alpha - \gamma)} f(v, z(v)) d_q v \right] \right\} \\ &\leq \Lambda(\|z\|)\|G\| \left\{ \frac{T^{(\alpha + \delta)}}{\Gamma_q(\alpha + \delta + 1)} + \frac{|\lambda_1| \Gamma_q(\gamma + \delta) + T^{(\gamma + \delta - 1)}}{|Q|} \left(\frac{T^{(\alpha + \delta)}}{\Gamma_q(\alpha + \delta + 1)} \right. \right. \\ &\quad \left. \left. + |\lambda_2| \frac{T^{(\alpha - \gamma + 1)}}{\Gamma_q(\alpha - \gamma + 2)} \right) \right\} \\ &\leq \Lambda(\|z\|)\|G\|\Delta, \end{aligned} \tag{3.12}$$

which implies that

$$\|\mathcal{F}z\| \leq \Lambda(\|z\|)\|G\|\Delta.$$

Moreover, for $t_1, t_2 \in [0, T]$ with $t_1 < t_2$ and $z \in \mathbb{B}_k$, we obtain

$$\begin{aligned} &|(\mathcal{F}z)(t_2) - (\mathcal{F}z)(t_1)| \\ &\leq \frac{|t_2^{\gamma + \delta - 1} - t_1^{\gamma + \delta - 1}|}{|Q|} \left[\frac{1}{\Gamma_q(\alpha + \delta)} \int_0^T (T - qv)_q^{(\alpha + \delta - 1)} |f(v, z(v))| d_q v \right. \\ &\quad \left. + \frac{|\lambda_2|}{\Gamma_q(\alpha - \gamma + 1)} \int_0^T (T - qv)_q^{(\alpha - \gamma)} |f(v, z(v))| d_q v \right] \\ &\quad + \frac{1}{\Gamma_q(\alpha + \delta)} \left| \int_0^{t_1} [(t_2 - qv)_q^{(\alpha + \delta - 1)} - (t_1 - qv)_q^{(\alpha + \delta - 1)}] |f(v, z(v))| d_q v \right. \\ &\quad \left. + \int_{t_1}^{t_2} (t_2 - qv)_q^{(\alpha + \delta - 1)} |f(v, z(v))| d_q v \right| \\ &\leq \frac{|t_2^{\gamma + \delta - 1} - t_1^{\gamma + \delta - 1}|}{|Q|} \Lambda(k) \left[\frac{1}{\Gamma_q(\alpha + \delta)} \int_0^T (T - qv)_q^{(\alpha + \delta - 1)} g(v) d_q v \right. \end{aligned}$$

$$\begin{aligned}
& + \frac{|\lambda_2|}{\Gamma_q(\alpha - \gamma + 1)} \int_0^T (T - qv)_q^{(\alpha - \gamma)} g(v) d_q v \\
& + \frac{1}{\Gamma_q(\alpha + \delta)} \Lambda(k) \left| \int_0^{t_1} [(t_2 - qv)_q^{(\alpha + \delta - 1)} - (t_1 - qv)_q^{(\alpha + \delta - 1)}] g(v) d_q v \right. \\
& \left. + \int_{t_1}^{t_2} (t_2 - qv)_q^{(\alpha + \delta - 1)} g(v) d_q v \right| \\
\leq & \frac{\|G\| \Lambda(k) |t_2^{\gamma + \delta - 1} - t_1^{\gamma + \delta - 1}|}{|Q|} \left\{ \frac{T^{(\alpha + \delta)}}{\Gamma_q(\alpha + \delta + 1)} + |\lambda_2| \frac{T^{(\alpha - \gamma + 1)}}{\Gamma_q(\alpha - \gamma + 2)} \right\} \\
& + \frac{\|G\| \Lambda(k)}{\Gamma_q(\alpha + \delta + 1)} [2(t_2 - t_1)_q^{(\alpha + \delta)} + |t_2^{(\alpha + \delta)} - t_1^{(\alpha + \delta)}|], \\
\rightarrow & 0 \text{ as } t_2 - t_1 \rightarrow 0.
\end{aligned}$$

This proves the equicontinuity of the set $\mathcal{F}(\mathbb{B}_k)$, and by the Arzelá-Ascoli theorem, it is relatively compact. Thus, $\mathcal{F} : \mathcal{X} \rightarrow \mathcal{X}$ is completely continuous.

Now, for $t \in [0, T]$, as in step 1, yields

$$|z(t)| \leq \|G\| \Lambda(\|z\|) \Delta,$$

which gives

$$\frac{\|z\|}{\|G\| \Lambda(\|z\|) \Delta} \leq 1.$$

By $(\mathcal{H}_4) \exists C$ such that $C \neq \|z\|$. Let

$$\mathcal{U} = \{z \in \mathcal{X} : \|z\| < C\}.$$

Then, $\mathcal{F} : \bar{\mathcal{U}} \rightarrow C$ is both continuous and completely continuous. From \mathcal{U} , there exists no $z \in \bar{\mathcal{U}}$ such that $z = \omega \mathcal{F}(z)$ for any $\omega \in (0, 1)$. Thus, as a consequence of Lemma 3.3, we conclude that \mathcal{F} has a fixed point $z \in \bar{\mathcal{U}}$ which is a solution of problem (1.6). \square

3.2. Uniqueness result

We proceed to establish the uniqueness of problem (1.6) using the Banach contraction principle [54].

Theorem 3.3. *Let $0 < \alpha, \delta < 1$, $0 \leq \beta \leq 1$, and $\gamma = \alpha + \beta(1 - \alpha)$. Suppose that $f : [0, T] \times \mathbb{R} \rightarrow \mathbb{R}$ fulfills the assumption (\mathcal{H}_1) . If*

$$L\Delta < 1, \tag{3.13}$$

where Δ is defined by (3.11), then, there exists a unique solution of problem (1.6) on $[0, T]$.

Proof. To do so, problem (1.6) can be viewed as a fixed-point problem, $z = \mathcal{F}z$, where \mathcal{F} is defined as in (3.1). Next, we show that \mathcal{F} has a unique fixed point. Indeed, let $\sup_{t \in [0, T]} |f(t, 0)| = \mathcal{K} < \infty$ and

$\frac{\mathcal{K}\Delta}{1 - L\Delta} \leq k$. First, we show that $\mathcal{F}\mathcal{B}_k \subset \mathcal{B}_k$, where $\mathcal{B}_k = \{z \in \mathcal{X} : \|z\| \leq k\}$. Given $z \in \mathcal{B}_k$, gives

$$|(\mathcal{F}z)(t)| \leq \sup_{t \in [0, T]} \left\{ \frac{1}{\Gamma_q(\alpha + \delta)} \int_0^t (t - qv)_q^{(\alpha + \delta - 1)} |f(v, z(v))| d_q v \right.$$

$$\begin{aligned}
& + \frac{\lambda_1 \Gamma_q(\gamma + \delta) - t^{(\gamma + \delta - 1)}}{Q} \left[\frac{1}{\Gamma_q(\alpha + \delta)} \int_0^T (T - qv)_q^{(\alpha + \delta - 1)} |f(v, z(v))| d_q v \right. \\
& \left. + \frac{\lambda_2}{\Gamma_q(\alpha - \gamma + 1)} \int_0^T (T - qv)_q^{(\alpha - \gamma)} |f(v, z(v))| d_q v \right] \Big\} \\
\leq & \frac{1}{\Gamma_q(\alpha + \delta)} \int_0^T (T - qv)_q^{(\alpha + \delta - 1)} (|f(v, z(v)) - f(v, 0)| + |f(v, 0)|) d_q v \\
& + \frac{|\lambda_1| \Gamma_q(\gamma + \delta) + T^{(\gamma + \delta - 1)}}{|Q|} \\
& \times \left[\frac{1}{\Gamma_q(\alpha + \delta)} \int_0^T (T - qv)_q^{(\alpha + \delta - 1)} (|f(v, z(v)) - f(v, 0)| + |f(v, 0)|) f(v, z(v)) d_q v \right. \\
& \left. + \frac{|\lambda_2|}{\Gamma_q(\alpha - \gamma + 1)} \int_0^T (T - qv)_q^{(\alpha - \gamma)} (|f(v, z(v)) - f(v, 0)| + |f(v, 0)|) d_q v \right] \\
\leq & (L\|z\| + \mathcal{K}) \left\{ \frac{1}{\Gamma_q(\alpha + \delta)} \int_0^T (T - qv)_q^{(\alpha + \delta - 1)} d_q v \right. \\
& + \frac{|\lambda_1| \Gamma_q(\gamma + \delta) + T^{(\gamma + \delta - 1)}}{|Q|} \left[\frac{1}{\Gamma_q(\alpha + \delta)} \int_0^T (T - qv)_q^{(\alpha + \delta - 1)} d_q v \right. \\
& \left. + \frac{|\lambda_2|}{\Gamma_q(\alpha - \gamma + 1)} \int_0^T (T - qv)_q^{(\alpha - \gamma)} d_q v \right] \Big\}, \\
\leq & (L\|z\| + \mathcal{K}) \left\{ \frac{T^{(\alpha + \delta)}}{\Gamma_q(\alpha + \delta + 1)} + \frac{|\lambda_1| \Gamma_q(\gamma + \delta) + T^{(\gamma + \delta - 1)}}{|Q|} \left(\frac{T^{(\alpha + \delta)}}{\Gamma_q(\alpha + \delta + 1)} \right. \right. \\
& \left. \left. + |\lambda_2| \frac{T^{(\alpha - \gamma + 1)}}{\Gamma_q(\alpha - \gamma + 2)} \right) \right\} \\
\leq & (Lk + \mathcal{K})\Delta \\
\leq & k,
\end{aligned}$$

and hence $\|(\mathcal{F}z)\| \leq k$, which means that $\mathcal{F}\mathcal{B}_k \subset \mathcal{B}_k$.

Subsequently, for $t \in [0, T]$ and any $z, z_1 \in C([0, T], \mathbb{R})$, we get

$$\begin{aligned}
& |(\mathcal{F}z)(t) - (\mathcal{F}z_1)(t)| \\
\leq & \frac{1}{\Gamma_q(\alpha + \delta)} \int_0^t (t - qv)_q^{(\alpha + \delta - 1)} |f(v, z(v)) - f(v, z_1(v))| d_q v \\
& + \frac{|\lambda_1| \Gamma_q(\gamma + \delta) + t^{(\gamma + \delta - 1)}}{|Q|} \left[\frac{1}{\Gamma_q(\alpha + \delta)} \int_0^T (T - qv)_q^{(\alpha + \delta - 1)} |f(v, z(v)) - f(v, z_1(v))| d_q v \right. \\
& \left. + \frac{|\lambda_2|}{\Gamma_q(\alpha - \gamma + 1)} \int_0^T (T - qv)_q^{(\alpha - \gamma)} |f(v, z(v)) - f(v, z_1(v))| d_q v \right] \\
\leq & L\|z - z_1\| \left(\frac{|\lambda_1| \Gamma_q(\gamma + \delta) + T^{(\gamma + \delta - 1)}}{|Q|} \left[\frac{T^{(\alpha + \delta)}}{\Gamma_q(\alpha + \delta + 1)} \right. \right. \\
& \left. \left. + |\lambda_2| \frac{T^{(\alpha - \gamma + 1)}}{\Gamma_q(\alpha - \gamma + 2)} \right] + \frac{T^{(\alpha + \delta)}}{\Gamma_q(\alpha + \delta + 1)} \right) \\
= & L\Delta \|z - z_1\|.
\end{aligned}$$

Therefore, $\|(\mathcal{F}z) - (\mathcal{F}z_1)\| \leq L\Delta\|z - z_1\|$, and hence, by (3.13), \mathcal{F} is a contraction, and hence, problem (1.6) has a unique solution on $[0, T]$. \square

3.3. Special cases of the proposed problem.

Case I. If $\lambda_1 = \lambda_2 = 0$, problem (1.6) reduces to sequential q -Hilfer problems of the form:

$$\begin{cases} {}^H\mathcal{D}_q^{\alpha,\beta}({}^C\mathcal{D}_q^\delta z)(t) = f(t, z(t)), & t \in [0, T], \\ z(0) = 0, z(T) = 0. \end{cases} \quad (3.14)$$

Corollary 3.1. Let $0 < \alpha, \delta < 1$, $0 \leq \beta \leq 1$, and $\gamma = \alpha + \beta(1 - \alpha)$. Suppose $f : [0, T] \times \mathbb{R} \rightarrow \mathbb{R}$ is a continuous function. If $z \in C_q^2([0, T], \mathbb{R})$, then z satisfies the problem (3.14) if and only if z satisfies the integral equation:

$$\begin{aligned} z(t) = & \frac{1}{\Gamma_q(\alpha + \delta)} \int_0^t (t - qv)_q^{(\alpha+\delta-1)} f(v, z(v)) d_q v \\ & - \frac{t^{(\gamma+\delta-1)}}{T^{(\gamma+\delta-1)}} \frac{1}{\Gamma_q(\alpha + \delta)} \int_0^T (T - qv)_q^{(\alpha+\delta-1)} f(v, z(v)) d_q v. \end{aligned} \quad (3.15)$$

Case II. If $\lambda_1 = \lambda_2 = 1$, problem (1.6) reduces to sequential q -Hilfer problems of the form:

$$\begin{cases} {}^H\mathcal{D}_q^{\alpha,\beta}({}^C\mathcal{D}_q^\delta z)(t) = f(t, z(t)), & t \in [0, T], \\ z(0) + {}^C\mathcal{D}_q^{\gamma+\delta-1} z(0) = 0, z(T) + {}^C\mathcal{D}_q^{\gamma+\delta-1} z(T) = 0. \end{cases} \quad (3.16)$$

Corollary 3.2. Let $0 < \alpha, \delta < 1$, $0 \leq \beta \leq 1$, and $\gamma = \alpha + \beta(1 - \alpha)$. Suppose $f : [0, T] \times \mathbb{R} \rightarrow \mathbb{R}$ is a continuous function. If $z \in C_q^2([0, T], \mathbb{R})$, then z satisfies the problem (3.16) if and only if z satisfies the integral equation:

$$\begin{aligned} z(t) = & \frac{\Gamma_q(\gamma + \delta) - t^{(\gamma+\delta-1)}}{T^{(\gamma+\delta-1)}} \left[\frac{1}{\Gamma_q(\alpha + \delta)} \int_0^T (T - qv)_q^{(\alpha+\delta-1)} f(v, z(v)) d_q v \right. \\ & \left. + \frac{1}{\Gamma_q(\alpha - \gamma + 1)} \int_0^T (T - qv)_q^{(\alpha-\gamma)} f(v, z(v)) d_q v \right] \\ & + \frac{1}{\Gamma_q(\alpha + \delta)} \int_0^t (t - qv)_q^{(\alpha+\delta-1)} f(v, z(v)) d_q v. \end{aligned} \quad (3.17)$$

Case III. Let $\beta = 1$, then $\gamma = 1$, and problem (1.6) reduces to the sequential q -Caputo fractional-order differential equation given by

$$\begin{cases} {}^C\mathcal{D}_q^\alpha({}^C\mathcal{D}_q^\delta z)(t) = f(t, z(t)), & t \in [0, T], \\ z(0) + \lambda_1 {}^C\mathcal{D}_q^\delta z(0) = 0, z(T) + \lambda_2 {}^C\mathcal{D}_q^\delta z(T) = 0. \end{cases} \quad (3.18)$$

Corollary 3.3. Let $0 < \alpha, \delta < 1$ be orders of fractional derivative and $0 < q < 1$ be quantum number. Suppose $f : [0, T] \times \mathbb{R} \rightarrow \mathbb{R}$ is a continuous function. If $z \in C_q^2([0, T], \mathbb{R})$, then z satisfies the

problem (3.18) if and only if z satisfies the integral equation:

$$\begin{aligned} z(t) = & \frac{\lambda_1 \Gamma_q(\delta + 1) - t^\delta}{T^{(\delta)} + (\lambda_2 - \lambda_1) \Gamma_q(\delta + 1)} \left[\frac{1}{\Gamma_q(\alpha + \delta)} \int_0^T (T - qv)_q^{(\alpha + \delta - 1)} f(v, z(v)) d_q v \right. \\ & \left. + \frac{\lambda_2}{\Gamma_q(\alpha)} \int_0^T (T - qv)_q^{(\alpha - 1)} f(v, z(v)) d_q v \right] \\ & + \frac{1}{\Gamma_q(\alpha + \delta)} \int_0^t (t - qv)_q^{(\alpha + \delta - 1)} f(v, z(v)) d_q v. \end{aligned} \quad (3.19)$$

Case IV. Let $\beta = 0$, then $\gamma = \alpha$, and problem (1.6) reduces to the sequential q -Riemann and Caputo fractional-order differential equation given by

$$\begin{cases} {}^{RL} \mathcal{D}_q^\alpha ({}^C \mathcal{D}_q^\delta z)(t) = f(t, z(t)), \quad t \in [0, T], \\ z(0) + \lambda_1 {}^C \mathcal{D}_q^{\alpha + \delta - 1} z(0) = 0, \quad z(T) + \lambda_2 {}^C \mathcal{D}_q^{\alpha + \delta - 1} z(T) = 0. \end{cases} \quad (3.20)$$

Corollary 3.4. Let $0 < \alpha, \delta < 1$, and $f : [0, T] \times \mathbb{R} \rightarrow \mathbb{R}$ is a continuous function. If $z \in C([0, T], \mathbb{R})$, then z satisfies the problem (3.20) if and only if z satisfies the integral equation:

$$\begin{aligned} z(t) = & \frac{\lambda_1 \Gamma_q(\alpha + \delta) - t^{(\alpha + \delta - 1)}}{Q^*} \left[\frac{1}{\Gamma_q(\alpha + \delta)} \int_0^T (T - qv)_q^{(\alpha + \delta - 1)} f(v, z(v)) d_q v \right. \\ & \left. + \lambda_2 \int_0^T f(v, z(v)) d_q v \right] + \frac{1}{\Gamma_q(\alpha + \delta)} \int_0^t (t - qv)_q^{(\alpha + \delta - 1)} f(v, z(v)) d_q v, \end{aligned} \quad (3.21)$$

where $Q^* = T^{(\alpha + \delta - 1)} + (\lambda_2 - \lambda_1) \Gamma_q(\alpha + \delta)$.

Case V. If $q = 1$, then problem (1.6) reduces to the sequential Hilfer and Caputo boundary value problem of the form:

$$\begin{cases} {}^H \mathcal{D}^{\alpha, \beta} ({}^C \mathcal{D}^\delta z)(t) = f(t, z(t)), \quad t \in [0, T], \\ z(0) + \lambda_1 {}^C \mathcal{D}^{\gamma + \delta - 1} z(0) = 0, \quad z(T) + \lambda_2 {}^C \mathcal{D}^{\gamma + \delta - 1} z(T) = 0. \end{cases} \quad (3.22)$$

Corollary 3.5. Let $0 < \alpha, \delta < 1$, $0 \leq \beta \leq 1$, and $\gamma = \alpha + \beta(1 - \alpha)$. Suppose $f : [0, T] \times \mathbb{R} \rightarrow \mathbb{R}$ is a continuous function. If $z \in C^2([0, T], \mathbb{R})$, then z satisfies the problem (3.22) if and only if z satisfies the integral equation:

$$\begin{aligned} z(t) = & \frac{\lambda_1 \Gamma(\gamma + \delta) - t^{\gamma + \delta - 1}}{Q} \left[\frac{1}{\Gamma(\alpha + \delta)} \int_0^T (T - v)^{\alpha + \delta - 1} f(v, z(v)) dv \right. \\ & \left. + \frac{\lambda_2}{\Gamma(\alpha - \gamma + 1)} \int_0^T (T - v)^{\alpha - \gamma} f(v, z(v)) dv \right] \\ & + \frac{1}{\Gamma(\alpha + \delta)} \int_0^t (t - v)^{\alpha + \delta - 1} f(v, z(v)) dv. \end{aligned} \quad (3.23)$$

4. Examples

Example 4.1. Consider the sequential fractional differential equation involving q -Hilfer and q -Caputo fractional derivatives:

$$\begin{cases} {}^H\mathcal{D}_{\frac{1}{2}}^{\frac{3}{5}, \frac{2}{5}} ({}^C\mathcal{D}_{\frac{1}{2}}^{\frac{4}{5}} z)(t) = f(t, z(t)), & t \in [0, \frac{9}{7}], \\ z(0) + \frac{11}{23} {}^C\mathcal{D}_{\frac{1}{2}}^{\frac{14}{25}} z(0) = 0, & z(\frac{9}{7}) + \frac{13}{29} {}^C\mathcal{D}_{\frac{1}{2}}^{\frac{14}{25}} z(\frac{9}{7}) = 0. \end{cases} \quad (4.1)$$

Now, we choose constants as $\alpha = 3/5$, $\beta = 2/5$, $\delta = 4/5$, $q = 1/2$, $T = 9/7$, $\lambda_1 = 11/23$, $\lambda_2 = 13/29$. Then we compute $\gamma = 19/25$, which yields $\gamma + \delta - 1 = 14/25$. These information can be used to find that $Q \approx 1.123420003$, $\Delta \approx 3.821919331$, and $\Delta - (T^{(\alpha+\delta)}/\Gamma_q(\alpha + \delta)) \approx 2.578777897$.

Case (i). Let the nonlinear bounded function $f(t, z)$ be presented by

$$f(t, z) = h(t) + \frac{|z|}{p + |z|}, \quad (4.2)$$

where $h : [0, 9/7] \rightarrow \mathbb{R}$, and p is a positive constant.

Thus,

$$|f(t, z)| \leq |h(t)| + 1 := \Psi(t).$$

and

$$|f(t, z) - f(t, z_1)| \leq \frac{1}{p} |z - z_1|,$$

for all $t \in [0, 9/7]$ and $z, z_1 \in \mathbb{R}$. Therefore, conditions (\mathcal{H}_1) and (\mathcal{H}_2) in Theorem 3.1 are satisfied with $L = 1/p$. Thus, from Theorem 3.1, we say that problem (4.1) with (4.2) has at least one solution on $[0, 9/7]$ if $p > 2.578777897$. In addition, the unique solution of problem (4.1) with (4.2), can be guaranteed if $p > 3.821919331$ by applying the result in Theorem 3.3.

Case (ii). If the nonlinear, unbounded function $f(t, z)$ is expressed as

$$f(t, z) = \frac{1}{2(t^2 + 4)} \left(\frac{z^2 + 2|z|}{1 + |z|} \right) + \frac{3}{4}, \quad (4.3)$$

then it is easy to check that condition (\mathcal{H}_1) is fulfilled by inequality

$$|f(t, z) - f(t, z_1)| \leq \frac{1}{4} |z - z_1|,$$

with $L = 1/4$, which leads to

$$L\Delta \approx 0.9554798328 < 1.$$

Hence, problem (4.1) with (4.3) has a unique solution on $[0, 9/7]$.

Example 4.2. Consider the sequential boundary value differential equations in the frame of q -Hilfer and q -Caputo fractional derivatives given by:

$$\begin{cases} {}^H\mathcal{D}_{\frac{2}{3}}^{\frac{5}{7}, \frac{3}{4}} ({}^C\mathcal{D}_{\frac{2}{3}}^{\frac{6}{7}} z)(t) = \frac{1}{t+2} \left(\frac{z^{2024}(t)}{4(1+z^{2022}(t))} + \frac{1}{\sqrt{t+3}} \right), & t \in [0, \frac{8}{9}], \\ z(0) + \frac{17}{31} {}^C\mathcal{D}_{\frac{2}{3}}^{\frac{11}{14}} z(0) = 0, & z(\frac{8}{9}) + \frac{19}{37} {}^C\mathcal{D}_{\frac{2}{3}}^{\frac{11}{14}} z(\frac{8}{9}) = 0. \end{cases} \quad (4.4)$$

Here $\alpha = 5/7$, $\beta = 3/4$, $\gamma = 13/14$ (by computing), $q = 2/3$, $\delta = 6/7$, $T = 8/9$, $\lambda_1 = 17/31$, $\lambda_2 = 19/37$, and $\gamma + \delta - 1 = 11/14$. From all constants, we have $Q \approx 0.8787426597$ and $\Delta \approx 2.500884518$.

Now, we see that the nonlinear non-Lipschitzian function $f(t, z)$ shown in the right-side of the first equation in (4.4), is bounded by

$$|f(t, z)| = \left| \frac{1}{t+2} \left(\frac{z^{2024}(t)}{4(1+z^{2022}(t))} + \frac{1}{\sqrt{t+3}} \right) \right| \leq \frac{1}{t+2} \left(\frac{1}{4}z^2 + \frac{1}{3} \right).$$

Choosing $G(t) = 1/(t+2)$ and $\Lambda(u) = (1/4)u^2 + (1/3)$, we have $\|G\| = 1/2$, and we can find that $\exists C \in (0.492701921, 2.706166297)$ satisfying (\mathcal{H}_4) . Thus, by applying Theorem 3.2, we say that problem (4.4) has at least one solution on $[0, 8/9]$.

5. Conclusions

Since the appearance of fractional operators, many research articles have been dedicated to improving and generalizing those operators. This paper investigates the existence and uniqueness of the results of a sequential boundary value problem in the setting of q -Hilfer and q -Caputo fractional derivatives with separated boundary conditions. The proposed problem is new and can be visualized as a generalization of Hilfer, q -Caputo, Caputo, q -Riemann-Liouville, and Riemann-Liouville fractional differential equations.

Author contributions

All authors contributed equally and significantly to writing this article. All authors read and approved the final manuscript.

Use of AI tools declaration

The authors declare they have not used Artificial Intelligence (AI) tools in the creation of this article.

Acknowledgments

The first author was supported by King Mongkut's University of Technology North Bangkok with contract no. KMUTNB-Post-67-08. This research budget was allocated by National Science, Research and Innovation Fund (NSRF) and King Mongkut's University of Technology North Bangkok with Contract no. KMUTNB-FF-67-B-02.

Conflicts of interest

The authors declare no conflict of interest.

References

1. A. A. Kilbas, H. M. Srivastava, J. J. Trujillo, *Theory and applications of fractional differential equations*, Elsevier, 2006.
2. S. G. Samko, *Fractional integrals and derivatives*, Theory and Applications, 1993.
3. I. Podlubny, *Fractional differential equations*, 1999.
4. F. Mainardi, *Fractional calculus and waves in linear viscoelasticity: An introduction to mathematical models*, World Scientific, 2010. <https://doi.org/10.1142/9781848163300>
5. D. S. Oliveira, E. C. de Oliveira, Hilfer-Katugampola fractional derivatives, *Comput. Appl. Math.*, **37** (2018), 3672–3690. <https://doi.org/10.1007/s40314-017-0536-8>
6. T. J. Osler, The fractional derivative of a composite function, *SIAM J. Math. Anal.*, **1** (1970), 288–293. <https://doi.org/10.1137/0501026>
7. R. Almeida, A Caputo fractional derivative of a function with respect to another function, *Commun. Nonlinear Sci. Numer. Simul.*, **44** (2017), 460–481. <https://doi.org/10.1016/j.cnsns.2016.09.006>
8. J. V. da C. Sousa, E. C. de Oliveira, On the ψ -Hilfer fractional derivative, *Commun. Nonlinear Sci. Numer. Simul.*, **60** (2018), 72–91. <https://doi.org/10.1016/j.cnsns.2018.01.005>
9. Y. Y., Gambo, F. Jarad, D. Baleanu, T. Abdeljawad, On Caputo modification of the Hadamard fractional derivatives, *Adv. Differ. Equ.*, **2014**, (2014), 10. <https://doi.org/10.1186/1687-1847-2014-10>
10. F. Jarad, T. Abdeljawad, D. Baleanu, Caputo-type modification of the Hadamard fractional derivatives, *Adv. Differ. Equ.*, **2012** (2012), 142. <https://doi.org/10.1186/1687-1847-2012-142>
11. F. Jarad, T. Abdeljawad, D. Baleanu, On the generalized fractional derivatives and their Caputo modification, *J. Nonlinear Sci. Appl.*, **10** (2017), 2607–2619. <https://doi.org/10.22436/jnsa.010.05.27>
12. K. Balachandran, S. Kiruthika, J. Trujillo, Existence of solutions of nonlinear fractional pantograph equations, *Acta Math. Sci.*, **33** (2013), 712–720. [https://doi.org/10.1016/s0252-9602\(13\)60032-6](https://doi.org/10.1016/s0252-9602(13)60032-6)
13. D. Vivek, K. Kanagarajan, S. Sivasundaram, Dynamics and stability of pantograph equations via Hilfer fractional derivative, *Nonlinear Stud.*, **23** (2016), 685–698.
14. D. Vivek, K. Kanagarajan, S. Sivasundaram, Theory and analysis of nonlinear neutral pantograph equations via Hilfer fractional derivative, *Nonlinear Stud.*, **24** (2017), 699–712.
15. A. Anguraj, A. Vinodkumar, K. Malar, Existence and stability results for random impulsive fractional pantograph equations, *Filomat*, **30** (2016), 3839–3854. <https://doi.org/10.2298/fil1614839a>
16. K. Shah, D. Vivek, K. Kanagarajan, Dynamics and stability of ψ -fractional pantograph equations with boundary conditions, *Bol. Soc. Paran. Mat.*, **39** (2021), 43–55. <https://doi.org/10.5269/bspm.41154>
17. H. M. Srivastava, Fractional-order integral and derivative operators and their applications, *Mathematics*, **8** (2020), 1016. <https://doi.org/10.3390/math8061016>

18. A. Lachouri, M. S. Abdo, A. Ardjouni, S. Etemad, S. Rezapour, A generalized neutral-type inclusion problem in the frame of the generalized Caputo fractional derivatives, *Adv. Differ. Equ.*, **2021** (2021), 404. <https://doi.org/10.1186/s13662-021-03559-7>
19. C. Ravichandran, K. Logeswari, F. Jarad, New results on existence in the framework of Atangana-Baleanu derivative for fractional integro-differential equations, *Chaos Soliton. Fract.*, **125** (2019), 194–200. <https://doi.org/10.1016/j.chaos.2019.05.014>
20. M. S. Abdo, S. K. Panchal, Fractional integro-differential equations involving ψ -Hilfer fractional derivative, *Adv. Appl. Math. Mech.*, **11** (2019), 338–359. <https://doi.org/10.4208/aamm.oa-2018-0143>
21. K. Karthikeyan, P. Karthikeyan, N. Patanarapeelert, T. Sitthiwiratham, Mild solutions for impulsive integro-differential equations involving Hilfer fractional derivative with almost sectorial operators, *Axioms*, **10** (2021), 313. <https://doi.org/10.3390/axioms10040313>
22. G. Wang, A. Ghanmi, S. Horrigue, S. Madian, Existence result and uniqueness for some fractional problem, *Mathematics*, **7** (2019), 516. <https://doi.org/10.3390/math7060516>
23. A. Morsy, C. Anusha, K. S. Nisar, C. Ravichandran, Results on generalized neutral fractional impulsive dynamic equation over time scales using nonlocal initial condition, *AIMS Math.*, **9** (2024), 8292–8310. <https://doi.org/10.3934/math.2024403>
24. K. Zhao, J. Liu, X. Lv, A unified approach to solvability and stability of multipoint bvps for Langevin and Sturm-Liouville equations with CH-fractional derivatives and impulses via coincidence theory, *Fractal Fract.*, **8** (2024), 111. <https://doi.org/10.3390/fractalfract8020111>
25. H. Srivastava, A. El-Sayed, F. Gaafar, A class of nonlinear boundary value problems for an arbitrary fractional-order differential equation with the Riemann-Stieltjes functional integral and infinite-point boundary conditions, *Symmetry*, **10** (2018), 508. <https://doi.org/10.3390/sym10100508>
26. M. Alam, A. Zada, T. Abdeljawad, Stability analysis of an implicit fractional integro-differential equation via integral boundary conditions, *Alex. Eng. J.*, **87** (2024), 501–514. <https://doi.org/10.1016/j.aej.2023.12.055>
27. K. S. Miller, B. Ross, *An introduction to the fractional calculus and fractional differential equations*, New York: John Wiley, 1993.
28. B. Ahmad, S. K. Ntouyas, R. P. Agarwal, A. Alsaedi, Existence results for sequential fractional integro-differential equations with nonlocal multi-point and strip conditions, *Bound. Value Probl.*, **2016** (2016), 205. <https://doi.org/10.1186/s13661-016-0713-5>
29. B. Ahmad, S. K. Ntouyas, A. Alsaedi, Sequential fractional differential equations and inclusions with semi-periodic and nonlocal integro-multipoint boundary conditions, *J. King Saud Uni. Sci.*, **31** (2019), 184–193. <https://doi.org/10.1016/j.jksus.2017.09.020>
30. A. Alsaedi, S. K. Ntouyas, R. P. Agarwal, B. Ahmad, On Caputo type sequential fractional differential equations with nonlocal integral boundary conditions, *Adv. Differ. Equ.*, **2015** (2015), 33. <https://doi.org/10.1186/s13662-015-0379-9>
31. B. Ahmad, R. Luca, Existence of solutions for sequential fractional integro-differential equations and inclusions with nonlocal boundary conditions, *Appl. Math. Comput.*, **339** (2018), 516–534. <https://doi.org/10.1016/j.amc.2018.07.025>

32. W. Saengthong, E. Thailert, S. K. Ntouyas, Existence and uniqueness of solutions for system of Hilfer-Hadamard sequential fractional differential equations with two point boundary conditions, *Adv. Differ. Equ.*, **2019** (2019), 525. <https://doi.org/10.1186/s13662-019-2459-8>
33. S. Sitho, S. K. Ntouyas, A. Samadi, J. Tariboon, Boundary value problems for ψ -Hilfer type sequential fractional differential equations and inclusions with integral multi-point boundary conditions, *Mathematics*, **9** (2021), 1001. <https://doi.org/10.3390/math9091001>
34. S. K. Ntouyas, D. Vivek, Existence and uniqueness results for sequential ψ -Hilfer fractional differential equations with multi-point boundary conditions, *Acta Math. Univ. Comenianae*, **90** (2021), 171–185.
35. G. Wang, X. Ren, L. Zhang, B. Ahmad, Explicit iteration and unique positive solution for a Caputo-Hadamard fractional turbulent flow model, *IEEE Access*, **7** (2019), 109833–109839. <https://doi.org/10.1109/access.2019.2933865>
36. P. Borisut, S. Phiangsungnoen, Existence and uniqueness of positive solutions for the fractional differential equation involving the ρ (τ)-Laplacian operator and nonlocal integral condition, *Mathematics*, **11** (2023), 3525. <https://doi.org/10.3390/math11163525>
37. J. Tariboon, A. Cuntavepanit, S. K. Ntouyas, W. Nithiarayaphaks, Separated boundary value problems of sequential Caputo and Hadamard fractional differential equations, *J. Funct. Space.*, **2018** (2018), 6974046. <https://doi.org/10.1155/2018/6974046>
38. S. Asawasamrit, A. Kijjathanakorn, S. K. Ntouyas, J. Tariboon, Nonlocal boundary value problems for Hilfer fractional differential equations, *Bull. Korean Math. Soc.*, **55** (2018), 1639–1657. <https://doi.org/10.4134/BKMS.b170887>
39. F. H. Jackson, On q -definite integrals, *Quart. J. Pure Appl. Math.*, **41** (1910), 193–203.
40. F. H. Jackson, XI.–On q -functions and a certain difference operator, *Earth Env. Sci. T. R. So.*, **46** (1909), 253–281. <https://doi.org/10.1017/S0080456800002751>
41. G. Gasper, M. Rahman, *Basic hypergeometric series*, Cambridge university press, 2009. <https://doi.org/10.1017/cbo9780511526251>
42. V. G. Kac, P. Cheung, *Quantum calculus*, New York: Springer, 2002. <https://doi.org/10.1007/978-1-4613-0071-7>
43. B. Ahmad, S. K. Ntouyas, I. K. Purnaras, Existence results for nonlocal boundary value problems of nonlinear fractional q -difference equations, *Adv. Differ. Equ.*, **2012** (2012), 140. <https://doi.org/10.1186/1687-1847-2012-140>
44. W. A. Al-Salam, Some fractional q -integrals and q -derivatives, *P. Edinburgh Math. Soc.*, **15** (1966), 135–140. <https://doi.org/10.1017/s0013091500011469>
45. R. P. Agarwal, Certain fractional q -integrals and q -derivatives, *Math. Proce. Cambridge*, **66** (1969), 365–370. <https://doi.org/10.1017/s0305004100045060>
46. S. Salahshour, A. Ahmadian, C. S. Chan, Successive approximation method for Caputo q -fractional IVPs, *Commun. Nonlinear Sci. Numer. Simul.*, **24** (2015), 153–158. <https://doi.org/10.1016/j.cnsns.2014.12.014>

47. W. X. Zhou, H. Z. Liu, Existence solutions for boundary value problem of nonlinear fractional q -difference equations, *Adv. Differ. Equ.*, **2013** (2013), 113. <https://doi.org/10.1186/1687-1847-2013-113>
48. S. Abbas, M. Benchohra, N. Laledj, Y. Zhou, Existence and Ulam stability for implicit fractional q -difference equations, *Adv. Differ. Equ.*, **2019** (2019), 480. <https://doi.org/10.1186/s13662-019-2411-y>
49. N. Allouch, J. R. Graef, S. Hamani, Boundary value problem for fractional q -difference equations with integral conditions in banach spaces, *Fractal Fract.*, **6** (2022), 237. <https://doi.org/10.3390/fractalfract6050237>
50. P. Rajkovic, S. Marinkovic, M. Stankovic, On q -analogues of Caputo derivative and Mittag-Leffler function, *Fract. Calc. Appl. Anal.*, **10** (2007), 359–373.
51. N. Limpanukorn, Existence of solution to q -Hilfer fractional difference equation with a time-varying order of operations, *Mathematical Journal by The Mathematical Association of Thailand Under The Patronage of His Majesty The King*, **67** (2022), 1–11.
52. M. A. Krasnosel'skii, Two remarks on the method of successive approximations, *Uspekhi Mat. Nauk*, **10** (1955), 123–127.
53. A. Granas, J. Dugundji, *Fixed point theory*, New York: Springer, 2003. <https://doi.org/10.1007/978-0-387-21593-8>
54. K. Deimling, *Nonlinear functional analysis*, Berlin: Springer, 1985. <https://doi.org/10.1007/978-3-662-00547-7>



AIMS Press

©2024 the Author(s), licensee AIMS Press. This is an open access article distributed under the terms of the Creative Commons Attribution License (<https://creativecommons.org/licenses/by/4.0>)