



---

*Research article*

## Ranking of linear Diophantine fuzzy numbers using circumcenter of centroids

Salma Iqbal and Naveed Yaqoob\*

Department of Mathematics and Statistics, Riphah International University, I-14, Islamabad, Pakistan

\* **Correspondence:** Email: [nayaqoob@ymail.com](mailto:nayaqoob@ymail.com).

**Abstract:** This paper generically introduces a new notion of trapezoidal linear Diophantine fuzzy numbers in general (TrapLDFNs). We begin by introducing the concept of TrapLDFNs. Then, we propose a ranking method for TrapLDFNs relying on the circumcenter of centroids of TrapLDFN membership and non-membership functions.

**Keywords:** linear Diophantine fuzzy sets; linear Diophantine fuzzy numbers; linear Diophantine fuzzy equations

**Mathematics Subject Classification:** 03E72

---

### 1. Introduction

In 1965, Zadeh [56] presented fuzzy set theory. Later, Atanasov [10] generalized the notion of a fuzzy set and added the notion of an intuitionistic fuzzy set. One of the underlying issues of fuzzy arithmetic and fuzzy decision-making is the ranking of fuzzy numbers. Before the decision-maker can act, fuzzy numbers should be ranked. Real numbers can be ordered linearly by the connection  $\leq$  or  $\geq$ , however, and fuzzy numbers do not have this type of disparity. Because a probable distribution depicts fuzzy numbers, they could also overlap, making it challenging to determine whether one fuzzy number is either larger or smaller than another. A ranking component, which outlines each fuzzy number further into a real line in which a natural order persists, is an efficient method to order the fuzzy numbers. Ramesh [49] compares the notion of ranking function for making comparisons of normal fuzzy numbers.

Abbasbandy and Hajjari [1] developed an innovative method for classifying trapezoidal fuzzy numbers. Wang and Kerre [52] proposed ordering features for fuzzy quantities. Angelov [8] adhered the Bellman and Zadeh [12] fuzzy optimization approach to intuitionistic fuzzy optimization. Numerous authors, including Jana and Roy [30], Mahapatra et al. [35], Dubey et al. [20], Mukherjee and Basu [39] have investigated the issue of optimization in an intuitionistic fuzzy background. One

initiative to model the decision-making challenge with ambiguous quantities is to treat such imprecise quantities as intuitionistic fuzzy numbers. Consequently, the analogy of fuzzy numbers is required in the intuitionistic fuzzy optimisation problem. To create ranking systems for intuitionistic fuzzy numbers, comparisons of these erroneous numbers are necessary.

Between intuitionistic fuzzy sets, Atanassov identified four fundamental distances: “The Hamming, normalised Hamming, Euclidean, and normalised Euclidean distances”. Szmidt and Kacprzyk [51] added to this principle and suggested a new definition of distance between intuitionistic fuzzy sets. Wang and Xin [53] also investigated the striking similarities and detachments between intuitionistic fuzzy sets by presenting some new axioms. Besides this, Nayagam et al. [41] and Nehi [42] also have investigated the ranking of intuitionistic fuzzy numbers. Li [34] defined and implemented a ratio methodology for triangular intuitionistic fuzzy numbers to MADM. In literature, there are additional ranking techniques that have been developed by authors like Kumar and Kaur [33], Zhang and Yu [57], Esmailzadeh and Esmailzadeh [22] and Papakostas et al. [44]. By adding the valuation and ambiguity indexes of a trapezoidal intuitionistic fuzzy number, De and Das [19] were capable of describing a ranking function.

The centroid approach of ranking intuitionistic fuzzy numbers was introduced by Nishad et al. [43]. Bharati and Singh [13, 14] have explored intuitionistic fuzzy multiple objective programming and implemented it in agricultural planning and control. In a two-stage time-minimizing transportation concern, Bharati and Malhotra [15] used intuitionistic fuzzy sets. A novel algorithm for ranking intuitionistic fuzzy digits using the centroid method was put forth by Prakash et al. [45]. Mitchell [37] introduced some techniques for ranking intuitively fuzzy numbers. To use the intuitionistic fuzzy number’s anticipated interval, Grzegorzewski [26] suggested a ranking and having-to-order method for intuitionistic fuzzy numbers. This is entirely predicated on the possible values for the fuzzy number first presented in Chiao [17]. An approach for ranking fuzzy numbers using the circumcenter of centroids and an indicator of modality was presented by Rao and Shankar [46]. Nasserri et al. [40] introduce an addition to using the circumcenter of centroids to rank fuzzy numbers with the aid of an area method. Roseline and Amirtharaj [50] presented intuitionistic fuzzy numbers using distance methods that rely on the circumcenter of centroids.

Additionally, Yager [54, 55] expanded upon the idea of PFS and introduced a new definition known as a  $q$ -rung orthopair fuzzy set ( $q$ -ROFS). Chen [16] suggested  $m$ -polar FS, while Zhang [57] established bipolar FS and its relationships. Akram [2] investigated the theory, procedures, and applications of  $m$ -polar F graphs in DM. Riaz and Hashmi [47] proposed the cutting-edge idea of a linear Diophantine fuzzy set (LDFS). The research on LDFSs has recently expanded significantly. Jampan et al. [29] researched linear Diophantine fuzzy Einstein aggregation operators, spherical linear Diophantine fuzzy, and linear Diophantine fuzzy relations concerning decision-making issues. Developed a fresh method for the COVID-19  $q$ -linear Diophantine fuzzy emergency decision support system. Algebraic linear Diophantine fuzzy structures were researched by Kamac [31]. Khan et al. [32] use triangular linear Diophantine fuzzy numbers to solve linear and quadratic equations. There are several authors who studied different applications of generalized fuzzy set models, for instance, Ali et al. [3–6], Ashraf et al. [9], Ayub et al. [11], Das and Granados [18], Farid et al. [23], Gupta et al. [27], Hashmi et al. [28], Mahmood et al. [36], Mohammad et al. [38] and Riaz and Farid [48].

The domain principle of intuitionistic fuzzy set (IFS), interval-valued intuitionistic fuzzy set

(IVIFS), Pythagorean fuzzy set (PFS), interval-valued Pythagorean fuzzy set (IVPFS) and q-rung orthopair fuzzy set (q-ROFS) have several actual applications in diverse fields. But researchers found some limitations to apply these concepts in much uncertain problems due to some issues related to membership and non-membership grades. For instance, in all these theories the researchers cannot choose 1 for membership and 1 for no-membership, if someone choose 1 for membership and 1 for no-membership the  $1^q + 1^q > 1$ . In order to remedy the issues, firstly, Riaz and Hashmi introduce the novel idea of linear Diophantine fuzzy set (LDFS). In LDFS concept, they use the reference parameters similar to membership and non-membership grades makes it most accommodating in the direction of modeling uncertainties in actual existence issues. This research proposes a novel circumcenter-based algorithm for ranking LD fuzzy numbers. A trapezoid is initially divided into three segments in a trapezoidal LD fuzzy number, with the first, second, and third parts consecutively being a triangle, a rectangle, and a triangle. Next, the centroids of each of these three components are computed and their circumcenters. To rank LD fuzzy numbers, a ranking algorithm is lastly specified as the circumcenter position plus the original position. The centroid of the trapezoid, which serves as the trapezoid's balance point, is used as a point of reference in most ranking algorithms suggested in the literature. But since all of the centroids' vertices are fairly different from this point, the centroids' circumcenter could be considered a significantly balanced location.

## 2. Preliminaries and basic definitions

This section is dedicated to reviewing some fundamental ideas essential for comprehending the dominant model.

**Definition 2.1.** [56] Consider a non-empty set  $X$  as the universe of discourse. Then a fuzzy set  $\xi$  in  $X$  is defined as follows:

$$\xi = \{(\theta, \mu_\xi(\theta)) | \theta \in X\}, \quad (2.1)$$

where  $\mu_\xi(\theta) : X \rightarrow [0, 1]$  is the membership degree.

**Definition 2.2.** [24] A fuzzy set  $\xi$  defined on the universe set  $X$  is said to be normal iff  $\mu_\xi(\theta) = 1$ .

**Definition 2.3.** [21] A fuzzy set  $\xi$  of universe set  $X$  is said to be convex iff

$$\mu_\xi(\lambda x + (1 - \lambda)y) \geq \min\{\mu_\xi(x), \mu_\xi(y)\} \quad \forall x, y \in X \text{ and } \lambda \in [0, 1]. \quad (2.2)$$

**Definition 2.4.** [21] A fuzzy set  $\xi$  of universe set  $X$  is a fuzzy number iff  $\xi$  is normal and convex on  $X$ .

A real fuzzy number  $\xi$  is described as any fuzzy subset of the real line  $R$  with membership function  $\mu_\xi(\theta)$  possessing the following properties:

- $\mu_\xi$  is a continuous mapping from  $R$  to the closed interval  $[0, 1]$ .
- $\xi$  is normalized : there exist  $t \in R$  such that  $\mu_\xi(t) = 1$ .
- Convexity of  $\xi$  : i.e.,  $u, w \in R$ , if  $t \leq u \leq w$ , then  $\mu_\xi(u) \geq \min\{\mu_\xi(t), \mu_\xi(w)\}$ .
- Boundness of support: i.e.,  $\exists S \in R$  and  $\forall t \in R$ , if  $|t| \geq S$ , then  $\mu_\xi(t) = 0$ .

**Definition 2.5.** [10] An intuitionistic fuzzy set  $\varpi$  in  $X$  defined by

$$\varpi = \{(\theta, \langle \alpha_\varpi(\theta), \beta_\varpi(\theta) \rangle) : \theta \in X\}, \quad (2.3)$$

where  $\alpha_{\varpi} : X \rightarrow [0, 1]$  and  $\beta_{\varpi} : X \rightarrow [0, 1]$  are the membership degree and non-membership degree, respectively, with the condition:

$$0 \leq \alpha_{\varpi}(\theta) + \beta_{\varpi}(\theta) \leq 1. \quad (2.4)$$

The hesitation degree of IFS  $\varpi$  defined in  $X$  is denoted as  $\pi_{\varpi}(\theta)$ . It is determined by the following expression:

$$\pi_{\varpi}(\theta) = 1 - \alpha_{\varpi}(\theta) - \beta_{\varpi}(\theta). \quad (2.5)$$

**Definition 2.6.** [47] Let  $X$  be the universe. A linear Diophantine fuzzy set (LDFS)  $\mathfrak{F}_R$  on  $X$  is defined as follows:

$$\mathfrak{F}_R = \{(\theta, \langle \zeta_R^{\tau}(\theta), \eta_R^{\nu}(\theta) \rangle, \langle \alpha(\theta), \beta(\theta) \rangle) : \theta \in X\}, \quad (2.6)$$

where  $\zeta_R^{\tau}(\theta), \eta_R^{\nu}(\theta), \alpha(\theta), \beta(\theta) \in [0, 1]$  such that

$$\begin{aligned} 0 &\leq \alpha(\theta)\zeta_R^{\tau}(\theta) + \beta(\theta)\eta_R^{\nu}(\theta) \leq 1, \quad \forall \theta \in X, \\ 0 &\leq \alpha(\theta) + \beta(\theta) \leq 1. \end{aligned} \quad (2.7)$$

The hesitation part can be written as

$$\varrho_{\pi_R} = 1 - (\alpha(\theta)\zeta_R^{\tau}(\theta) + \beta(\theta)\eta_R^{\nu}(\theta)), \quad (2.8)$$

where  $\varrho$  is the reference parameter.

**Definition 2.7.** [47] An absolute LDFS on  $X$  can be written as

$${}^1\mathfrak{F}_R = \{(\theta, \langle 1, 0 \rangle, \langle 1, 0 \rangle) : \theta \in X\}, \quad (2.9)$$

and empty or null LDFS can be expressed as

$${}^0\mathfrak{F}_R = \{(\theta, \langle 0, 1 \rangle, \langle 0, 1 \rangle) : \theta \in X\}. \quad (2.10)$$

**Definition 2.8.** [47] Let  $\mathfrak{F}_R = \{(\theta, \langle \zeta_R^{\tau}(\theta), \eta_R^{\nu}(\theta) \rangle, \langle \alpha(\theta), \beta(\theta) \rangle) : \theta \in X\}$  be an LDFS. For any constants  $s, t, u, v \in [0, 1]$  such that  $0 \leq su + tv \leq 1$  with  $0 \leq u + v \leq 1$ , define the  $(\langle s, t \rangle, \langle u, v \rangle)$ -cut of  $\mathfrak{F}_R$  as follows:

$$\mathfrak{F}_{R(u,v)}^{\langle s,t \rangle} = \{\theta \in X : \zeta_R^{\tau}(\theta) \geq s, \eta_R^{\nu}(\theta) \leq t, \alpha(\theta) \geq u, \beta(\theta) \leq v\}. \quad (2.11)$$

**Definition 2.9.** [32] A LDF number  $\mathfrak{F}_R$  is

- a LDF subset of the real line  $R$ ,
- normal, i.e., there is any  $\theta_0 \in R$  such that  $\zeta_R^{\tau}(\theta_0) = 1, \eta_R^{\nu}(\theta_0) = 0, \alpha(\theta_0) = 1, \beta(\theta_0) = 0$ ,
- convex for the membership functions  $\zeta_R^{\tau}$  and  $\alpha$ , i.e.,

$$\begin{aligned} \zeta_R^{\tau}(\lambda\theta_1 + (1 - \lambda)\theta_2) &\geq \min\{\zeta_R^{\tau}(\theta_1), \zeta_R^{\tau}(\theta_2)\} \quad \forall \theta_1, \theta_2 \in R, \lambda \in [0, 1], \\ \alpha(\lambda\theta_1 + (1 - \lambda)\theta_2) &\geq \min\{\alpha(\theta_1), \alpha(\theta_2)\} \quad \forall \theta_1, \theta_2 \in R, \lambda \in [0, 1], \end{aligned} \quad (2.12)$$

- concave for the nonmembership functions  $\eta_R^{\nu}$  and  $\beta$ , i.e.,

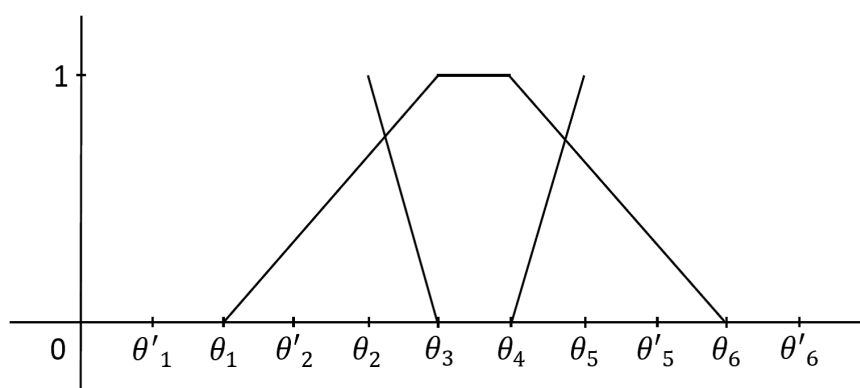
$$\begin{aligned} \eta_R^{\nu}(\lambda\theta_1 + (1 - \lambda)\theta_2) &\leq \max\{\eta_R^{\nu}(\theta_1), \eta_R^{\nu}(\theta_2)\} \quad \forall \theta_1, \theta_2 \in R, \lambda \in [0, 1], \\ \beta(\lambda\theta_1 + (1 - \lambda)\theta_2) &\leq \max\{\beta(\theta_1), \beta(\theta_2)\} \quad \forall \theta_1, \theta_2 \in R, \lambda \in [0, 1]. \end{aligned} \quad (2.13)$$

**Definition 2.10.** Let  $\mathfrak{L}_R$  be a trapezoidal LDFN (TrapLDFN) on  $R$  with the following membership functions ( $\zeta_R^\tau$  and  $\alpha$ ) and non-membership functions ( $\eta_R^\nu$  and  $\beta$ ) :

$$\zeta_R^\tau(x) = \begin{cases} 0 & x < \theta_1 \\ \frac{x-\theta_1}{\theta_3-\theta_1} & \theta_1 \leq x \leq \theta_3 \\ 1 & \theta_3 \leq x \leq \theta_4 \\ \frac{\theta_6-x}{\theta_6-\theta_4} & \theta_4 \leq x \leq \theta_6 \\ 0 & \theta_6 < x, \end{cases} \quad (2.14)$$

$$\eta_R^\nu(x) = \begin{cases} 0 & x < \theta_2 \\ \frac{\theta_3-x}{\theta_3-\theta_2} & \theta_2 \leq x \leq \theta_3 \\ 0 & \theta_3 \leq x \leq \theta_4 \\ \frac{x-\theta_4}{\theta_5-\theta_4} & \theta_4 \leq x \leq \theta_5 \\ 0 & \theta_5 < x, \end{cases} \quad (2.15)$$

where  $\theta_1 \leq \theta_2 \leq \theta_3 \leq \theta_4 \leq \theta_5 \leq \theta_6$  for all  $x \in R$ . The figure of  $(\theta_1, \theta_2, \theta_3, \theta_4, \theta_5, \theta_6)$  is shown in Figure 1.

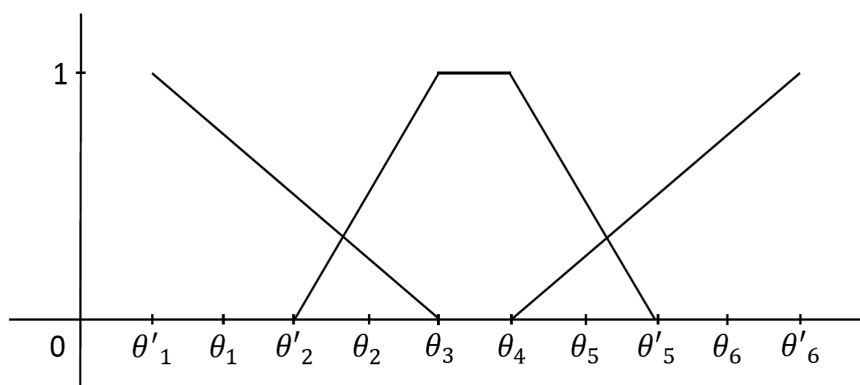


**Figure 1.** The figure of  $(\theta_1, \theta_2, \theta_3, \theta_4, \theta_5, \theta_6)$ .

$$\alpha(x) = \begin{cases} 0 & x < \theta'_2 \\ \frac{x-\theta'_2}{\theta_3-\theta'_2} & \theta'_2 \leq x \leq \theta_3 \\ 1 & \theta_3 \leq x \leq \theta_4 \\ \frac{\theta'_5-x}{\theta'_5-\theta_4} & \theta_4 \leq x \leq \theta'_5 \\ 0 & \theta'_5 < x, \end{cases} \quad (2.16)$$

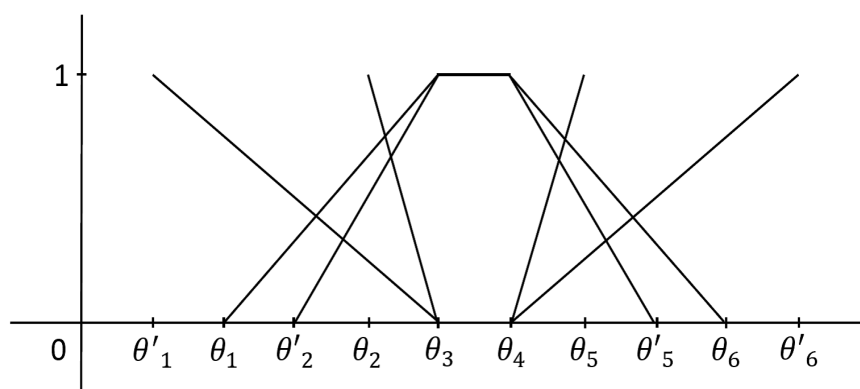
$$\beta(x) = \begin{cases} 0 & x < \theta'_1 \\ \frac{\theta_3-x}{\theta_3-\theta'_1} & \theta'_1 \leq x \leq \theta_3 \\ 0 & \theta_3 \leq x \leq \theta_4 \\ \frac{x-\theta_4}{\theta'_6-\theta_4} & \theta_4 \leq x \leq \theta'_6 \\ 0 & \theta'_6 < x, \end{cases} \quad (2.17)$$

where  $\theta'_1 \leq \theta'_2 \leq \theta_3 \leq \theta_4 \leq \theta'_5 \leq \theta'_6$  for all  $x \in R$ . The figure of  $(\theta'_1, \theta'_2, \theta_3, \theta_4, \theta'_5, \theta'_6)$  is shown in Figure 2.



**Figure 2.** The figure of  $(\theta'_1, \theta'_2, \theta_3, \theta_4, \theta'_5, \theta'_6)$ .

The figure of  $\mathfrak{L}_{\mathfrak{R}TrapLDFN}$  is shown in Figure 3.



**Figure 3.** The figure of  $\mathfrak{L}_{\mathfrak{R}TrapLDFN}$ .

**Definition 2.11.** Consider a TrapLDFN  $\mathfrak{L}_{\mathfrak{R}TrapLDFN} = \left\{ \begin{matrix} (\theta_1, \theta_2, \theta_3, \theta_4, \theta_5, \theta_6) \\ (\theta'_1, \theta'_2, \theta_3, \theta_4, \theta'_5, \theta'_6) \end{matrix} \right\}$ . Then

(i) s-cut set of  $\mathfrak{L}_{\mathfrak{R}TrapLDFN}$  is a crisp subset of  $\mathbb{R}$ , which is defined as follows

$$\begin{aligned} \mathfrak{L}_{\mathfrak{R}TrapLDFN}^s &= \{x \in X : \zeta_{\mathfrak{R}}^T(x) \geq s\} \\ &= [\underline{\zeta_{\mathfrak{R}}^T(s)}, \overline{\zeta_{\mathfrak{R}}^T(s)}] \\ &= [\theta_1 + s(\theta_3 - \theta_1), \theta_6 - s(\theta_6 - \theta_4)], \end{aligned} \quad (2.18)$$

(ii) t-cut set of  $\mathfrak{L}_{\mathfrak{R}TrapLDFN}$  is a crisp subset of  $\mathbb{R}$ , which is defined as follows

$$\begin{aligned} \mathfrak{L}_{\mathfrak{R}TrapLDFN}^t &= \{x \in X : \eta_{\mathfrak{R}}^V(x) \leq t\} \\ &= [\underline{\eta_{\mathfrak{R}}^V(t)}, \overline{\eta_{\mathfrak{R}}^V(t)}] \\ &= [\theta_3 - t(\theta_3 - \theta_2), \theta_4 + t(\theta_5 - \theta_4)], \end{aligned} \quad (2.19)$$

(iii) u-cut set of  $\mathfrak{L}_{\mathfrak{R}TrapLDFN}$  is a crisp subset of  $\mathbb{R}$ , which is defined as follows

$$\mathfrak{L}_{\mathfrak{R}TrapLDFN}^u = \{x \in X : \alpha(x) \geq u\}$$

$$\begin{aligned}
&= [\underline{\alpha(u)}, \overline{\alpha(u)}] \\
&= [\theta'_2 + u(\theta_3 - \theta'_2), \theta'_5 - u(\theta'_5 - \theta_4)], \tag{2.20}
\end{aligned}$$

(iv)  $v$ -cut set of  $\mathfrak{F}_{\mathbb{R}TrapLDFN}$  is a crisp subset of  $\mathbb{R}$ , which is defined as follows

$$\begin{aligned}
\mathfrak{F}_{\mathbb{R}TrapLDFN}^v &= \{x \in X : \beta(x) \leq v\} \\
&= [\underline{\beta(v)}, \overline{\beta(v)}] \\
&= [\theta_3 - v(\theta_3 - \theta'_1), \theta_4 + v(\theta'_6 - \theta_4)]. \tag{2.21}
\end{aligned}$$

We can denote the  $(\langle s, t \rangle, \langle u, v \rangle)$ -cut of  $\mathfrak{F}_{\mathbb{R}TrapLDFN} = \left\{ (\theta_1, \theta_2, \theta_3, \theta_4, \theta_5, \theta_6) \right\}$  by

$$(\mathfrak{F}_{\mathbb{R}TrapLDFN})_{\langle s, t \rangle, \langle u, v \rangle} = \left\{ \left( [\underline{\zeta_R^T(s)}, \overline{\zeta_R^T(s)}], [\underline{\eta_R^V(t)}, \overline{\eta_R^V(t)}] \right), \left( [\underline{\alpha(u)}, \overline{\alpha(u)}], [\underline{\beta(v)}, \overline{\beta(v)}] \right) \right\}.$$

We denote the set of all TrapLDFN on  $\mathbb{R}$  by  $\mathfrak{F}_{\mathbb{R}TrapLDFN}(\mathbb{R})$ .

### 3. Centroid method for ranking of trapezoidal LDFNs

In this part, we determine the centroid location of the trapezoidal linear Diophantine fuzzy number (TrapLDFN). The geometric core of a trapezoidal Linear diophantine fuzzy number is used in the process of ranking TrapLDFNs with a centroid index. Values on the horizontal and vertical axes correlate to the geometric centre.

Consider a TrapLDFN  $\mathfrak{F}_{\mathbb{R}TrapLDFN} = \left\{ (\theta_1, \theta_2, \theta_3, \theta_4, \theta_5, \theta_6) \right\}$ , whose membership function can be defined as follows:

$$\zeta_R^T(x) = \begin{cases} 0 & x < \theta_1 \\ f_A^L(x) & \theta_1 \leq x \leq \theta_3 \\ 1 & \theta_3 \leq x \leq \theta_4 \\ f_A^R(x) & \theta_4 \leq x \leq \theta_6 \\ 0 & \theta_6 \leq x, \end{cases} \tag{3.1}$$

$$\eta_R^V(x) = \begin{cases} 0 & x < \theta_2 \\ g_A^L(x) & \theta_2 \leq x \leq \theta_3 \\ 0 & \theta_3 \leq x \leq \theta_4 \\ g_A^R(x) & \theta_4 \leq x \leq \theta_5 \\ 0 & \theta_5 \leq x, \end{cases} \tag{3.2}$$

$$\alpha(x) = \begin{cases} 0 & x < \theta'_2 \\ f_A'^L(x) & \theta'_2 \leq x \leq \theta_3 \\ 1 & \theta_3 \leq x \leq \theta_4 \\ f_A'^R(x) & \theta_4 \leq x \leq \theta'_5 \\ 0 & \theta'_5 \leq x, \end{cases} \tag{3.3}$$

$$\beta(x) = \begin{cases} 0 & x < \theta'_1 \\ g_A^{\prime L}(x) & \theta'_1 \leq x \leq \theta_3 \\ 0 & \theta_3 \leq x \leq \theta_4 \\ g_A^{\prime R}(x) & \theta_4 \leq x \leq \theta'_6 \\ 0 & \theta'_6 \leq x. \end{cases} \quad (3.4)$$

Where

$$\begin{aligned} f_A^L : R &\longrightarrow [0, 1], & f_A^R : R &\longrightarrow [0, 1], \\ g_A^L : R &\longrightarrow [0, 1], & g_A^R : R &\longrightarrow [0, 1], \\ f_A^{\prime L} : R &\longrightarrow [0, 1], & f_A^{\prime R} : R &\longrightarrow [0, 1], \\ g_A^{\prime L} : R &\longrightarrow [0, 1] \text{ and } g_A^{\prime R} : R &\longrightarrow [0, 1], \end{aligned} \quad (3.5)$$

are called the sides of TrapLDFN, where  $f_A^L, g_A^R, f_A^{\prime L}$  and  $g_A^{\prime R}$  are non-decreasing and  $f_A^R, g_A^L, f_A^{\prime R}$  and  $g_A^{\prime L}$  are non-increasing functions. Therefore the inverse functions of  $f_A^L, f_A^R, g_A^L, g_A^R, f_A^{\prime L}, f_A^{\prime R}, g_A^{\prime L}$  and  $g_A^{\prime R}$  exist which are also of the same nature. Let

$$\begin{aligned} h_A^L : [0, 1] &\longrightarrow R, & h_A^R : [0, 1] &\longrightarrow R, \\ k_A^L : [0, 1] &\longrightarrow R, & k_A^R : [0, 1] &\longrightarrow R, \\ h_A^{\prime L} : [0, 1] &\longrightarrow R, & h_A^{\prime R} : [0, 1] &\longrightarrow R, \\ k_A^{\prime L} : [0, 1] &\longrightarrow R \text{ and } k_A^{\prime R} : [0, 1] &\longrightarrow R, \end{aligned} \quad (3.6)$$

be the inverse functions of  $f_A^L, f_A^R, g_A^L, g_A^R, f_A^{\prime L}, f_A^{\prime R}, g_A^{\prime L}$  and  $g_A^{\prime R}$  respectively. Then,  $h_A^L, h_A^R, k_A^L, k_A^R, h_A^{\prime L}, h_A^{\prime R}, k_A^{\prime L}$  and  $k_A^{\prime R}$  should be integrable on  $R$ . In the case of the above defined TrapLDFN, the above inverse functions can be analytically expressed as follows:

$$\begin{aligned} h_A^L(y) &= \theta_1 + (\theta_3 - \theta_1)y & 0 \leq y \leq 1, \\ h_A^R(y) &= \theta_6 + (\theta_4 - \theta_6)y & 0 \leq y \leq 1, \\ k_A^L(y) &= \theta_3 + (\theta_2 - \theta_3)y & 0 \leq y \leq 1, \\ k_A^R(y) &= \theta_4 + (\theta_5 - \theta_4)y & 0 \leq y \leq 1, \\ h_A^{\prime L}(y) &= \theta'_2 + (\theta_3 - \theta'_2)y & 0 \leq y \leq 1, \\ h_A^{\prime R}(y) &= \theta'_5 + (\theta_4 - \theta'_5)y & 0 \leq y \leq 1, \\ k_A^{\prime L}(y) &= \theta_3 + (\theta'_1 - \theta_3)y & 0 \leq y \leq 1, \\ k_A^{\prime R}(y) &= \theta_4 + (\theta'_6 - \theta_4)y & 0 \leq y \leq 1. \end{aligned} \quad (3.7)$$

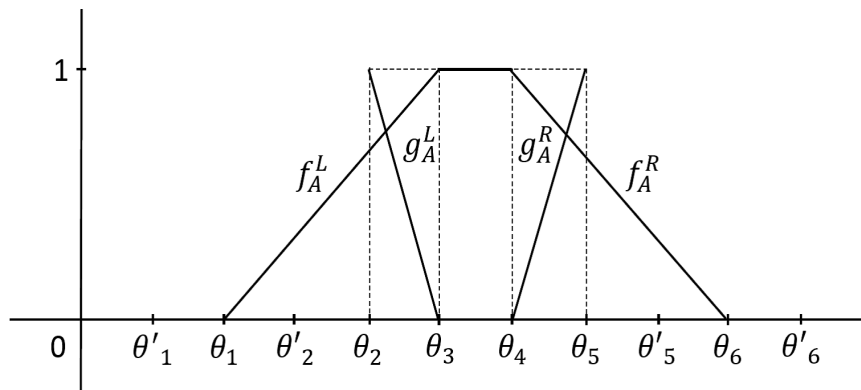
The centroid point of the TrapLDFN is determined as follows. First we find  $\zeta_R^\tau(x)$  and  $\eta_R^u(x)$ , also see the Figure 4.

$$\begin{aligned} \zeta_R^\tau(x) &= \frac{\int_{\theta_1}^{\theta_3} x f_A^L(x) dx + \int_{\theta_3}^{\theta_4} x dx + \int_{\theta_4}^{\theta_6} x f_A^R(x) dx}{\int_{\theta_1}^{\theta_3} f_A^L(x) dx + \int_{\theta_3}^{\theta_4} dx + \int_{\theta_4}^{\theta_6} f_A^R(x) dx}, \\ &= \frac{\int_{\theta_1}^{\theta_3} \frac{x^2 - x\theta_1}{\theta_3 - \theta_1} dx + \int_{\theta_3}^{\theta_4} x dx + \int_{\theta_4}^{\theta_6} \frac{\theta_6 x - x^2}{\theta_6 - \theta_4} dx}{\int_{\theta_1}^{\theta_3} \frac{x - \theta_1}{\theta_3 - \theta_1} dx + \int_{\theta_3}^{\theta_4} dx + \int_{\theta_4}^{\theta_6} \frac{\theta_6 - x}{\theta_6 - \theta_4} dx}, \\ &= \frac{\frac{1}{\theta_3 - \theta_1} \left[ \frac{x^3}{3} - \frac{x^2}{2} \theta_1 \right]_{\theta_1}^{\theta_3} + \left[ \frac{x^2}{2} \right]_{\theta_3}^{\theta_4} + \frac{1}{\theta_6 - \theta_4} \left[ \theta_6 \frac{x^2}{2} - \frac{x^3}{3} \right]_{\theta_4}^{\theta_6}}{\frac{1}{\theta_3 - \theta_1} \left[ \frac{x^2}{2} - \theta_1 x \right]_{\theta_1}^{\theta_3} + [x]_{\theta_3}^{\theta_4} + \frac{1}{\theta_6 - \theta_4} \left[ \theta_6 x - \frac{x^2}{2} \right]_{\theta_4}^{\theta_6}}, \end{aligned}$$



$$\zeta_R^\tau(x) = \frac{1}{3} \left[ \frac{\theta_6^2 + \theta_4^2 - \theta_3^2 - \theta_1^2 - \theta_1\theta_3 + \theta_6\theta_4}{\theta_6 + \theta_4 - \theta_3 - \theta_1} \right], \tag{3.8}$$

$$\begin{aligned} \eta_R^\nu(x) &= \frac{\int_{\theta_2}^{\theta_3} xg_A^L(x)dx + \int_{\theta_3}^{\theta_4} xdx + \int_{\theta_4}^{\theta_5} xg_A^R(x)}{\int_{\theta_2}^{\theta_3} g_A^L(x)dx + \int_{\theta_3}^{\theta_4} dx + \int_{\theta_4}^{\theta_5} g_A^R(x)}, \\ &= \frac{\int_{\theta_2}^{\theta_3} \frac{\theta_3x-x^2}{\theta_3-\theta_2} dx + \int_{\theta_3}^{\theta_4} xdx + \int_{\theta_4}^{\theta_5} \frac{x^2-\theta_4x}{\theta_5-\theta_4} dx}{\int_{\theta_2}^{\theta_3} \frac{\theta_3-x}{\theta_3-\theta_2} + \int_{\theta_3}^{\theta_4} dx + \int_{\theta_4}^{\theta_5} \frac{x-\theta_4}{\theta_5-\theta_4} dx}, \\ &= \frac{\frac{1}{\theta_3-\theta_2} \left[ \theta_3 \frac{x^2}{2} - \frac{x^3}{3} \right]_{\theta_2}^{\theta_3} + \left[ \frac{x^2}{2} \right]_{\theta_3}^{\theta_4} + \frac{1}{\theta_5-\theta_4} \left[ \frac{x^3}{3} - \theta_4 \frac{x^2}{2} \right]_{\theta_4}^{\theta_5}}{\frac{1}{\theta_3-\theta_2} \left[ \theta_3x - \frac{x^2}{2} \right]_{\theta_2}^{\theta_3} + [x]_{\theta_3}^{\theta_4} + \frac{1}{\theta_5-\theta_4} \left[ \frac{x^2}{2} - \theta_4x \right]_{\theta_4}^{\theta_5}}, \\ \eta_R^\nu(x) &= \frac{1}{3} \left[ \frac{2\theta_5^2 + 2\theta_4^2 - 2\theta_3^2 - 2\theta_2^2 + \theta_3\theta_2 - \theta_5\theta_4}{\theta_5 + \theta_4 - \theta_3 - \theta_2} \right]. \end{aligned} \tag{3.9}$$



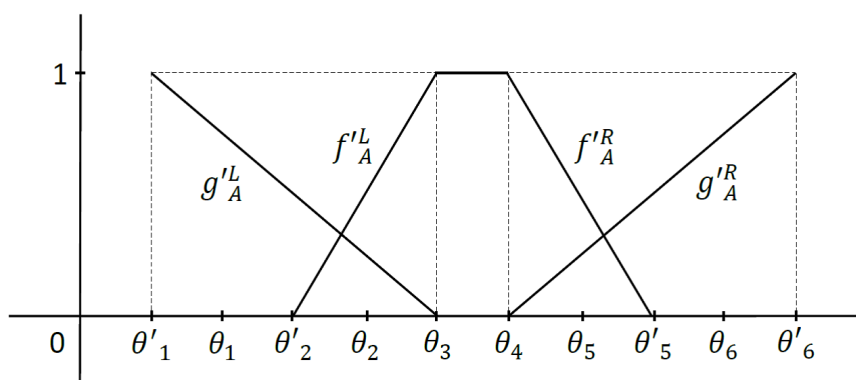
**Figure 4.** The figure of  $(\theta_1, \theta_2, \theta_3, \theta_4, \theta_5, \theta_6)$ .

Similarly, we find  $\alpha(x)$  and  $\beta(x)$ , also see the Figure 5.

$$\begin{aligned} \alpha(x) &= \frac{\int_{\theta'_2}^{\theta_3} xf_A'^L(x)dx + \int_{\theta_3}^{\theta_4} xdx + \int_{\theta_4}^{\theta'_5} xf_A'^R(x)dx}{\int_{\theta'_2}^{\theta_3} f_A'^L(x)dx + \int_{\theta_3}^{\theta_4} dx + \int_{\theta_4}^{\theta'_5} f_A'^R(x)dx}, \\ &= \frac{\int_{\theta'_2}^{\theta_3} \frac{x^2-\theta'_2x}{\theta_3-\theta'_2} dx + \int_{\theta_3}^{\theta_4} xdx + \int_{\theta_4}^{\theta'_5} \frac{\theta'_5x-x^2}{\theta'_5-\theta_4} dx}{\int_{\theta'_2}^{\theta_3} \frac{x-\theta'_2}{\theta_3-\theta'_2} dx + \int_{\theta_3}^{\theta_4} dx + \int_{\theta_4}^{\theta'_5} \frac{\theta'_5-x}{\theta'_5-\theta_4} dx}, \\ &= \frac{\frac{1}{\theta_3-\theta'_2} \left[ \frac{x^3}{3} - \theta'_2 \frac{x^2}{2} \right]_{\theta'_2}^{\theta_3} + \left[ \frac{x^2}{2} \right]_{\theta_3}^{\theta_4} + \frac{1}{\theta'_5-\theta_4} \left[ \theta'_5 \frac{x^2}{2} - \frac{x^3}{3} \right]_{\theta_4}^{\theta'_5}}{\frac{1}{\theta_3-\theta'_2} \left[ \frac{x^2}{2} - \theta'_2x \right]_{\theta'_2}^{\theta_3} + [x]_{\theta_3}^{\theta_4} + \frac{1}{\theta'_5-\theta_4} \left[ \theta'_5x - \frac{x^2}{3} \right]_{\theta_4}^{\theta'_5}}, \end{aligned}$$

$$\alpha(x) = \frac{1}{3} \left[ \frac{\theta_5^2 + \theta_4^2 - \theta_3^2 - \theta_2^2 - \theta_2\theta_3 + \theta_4\theta_5}{\theta_5 + \theta_4 - \theta_3 - \theta_2} \right], \quad (3.10)$$

$$\begin{aligned} \beta(x) &= \frac{\int_{\theta'_1}^{\theta_3} x g_A'^L(x) dx + \int_{\theta_3}^{\theta_4} x dx + \int_{\theta_4}^{\theta'_6} g_A'^R(x) dx}{\int_{\theta'_1}^{\theta_3} g_A'^L(x) dx + \int_{\theta_3}^{\theta_4} dx + \int_{\theta_4}^{\theta'_6} g_A'^R(x) dx}, \\ &= \frac{\int_{\theta'_1}^{\theta_3} \frac{\theta_3 x - x^2}{\theta_3 - \theta'_1} dx + \int_{\theta_3}^{\theta_4} x dx + \int_{\theta_4}^{\theta'_6} \frac{x^2 - \theta_4 x}{\theta'_6 - \theta_4} dx}{\int_{\theta'_1}^{\theta_3} \frac{\theta_3 - x}{\theta_3 - \theta'_1} dx + \int_{\theta_3}^{\theta_4} dx + \int_{\theta_4}^{\theta'_6} \frac{x - \theta_4}{\theta'_6 - \theta_4} dx}, \\ &= \frac{\frac{1}{\theta_3 - \theta'_1} \left[ \theta_3 \frac{x^2}{2} - \frac{x^3}{3} \right]_{\theta'_1}^{\theta_3} + \left[ \frac{x^2}{2} \right]_{\theta_3}^{\theta_4} + \frac{1}{\theta'_6 - \theta_4} \left[ \frac{x^3}{3} - \theta_4 \frac{x^2}{2} \right]_{\theta_4}^{\theta'_6}}{\frac{1}{\theta_3 - \theta'_1} \left[ \theta_3 x - \frac{x^2}{2} \right]_{\theta'_1}^{\theta_3} + [x]_{\theta_3}^{\theta_4} + \frac{1}{\theta'_6 - \theta_4} \left[ \frac{x^2}{2} - \theta_4 x \right]_{\theta_4}^{\theta'_6}}, \\ \beta(x) &= \frac{1}{3} \left[ \frac{2\theta_6^2 + 2\theta_4^2 - 2\theta_3^2 - 2\theta_1^2 + \theta_3\theta'_1 - \theta'_6\theta_4}{\theta'_6 + \theta_4 - \theta_3 - \theta'_1} \right]. \end{aligned} \quad (3.11)$$

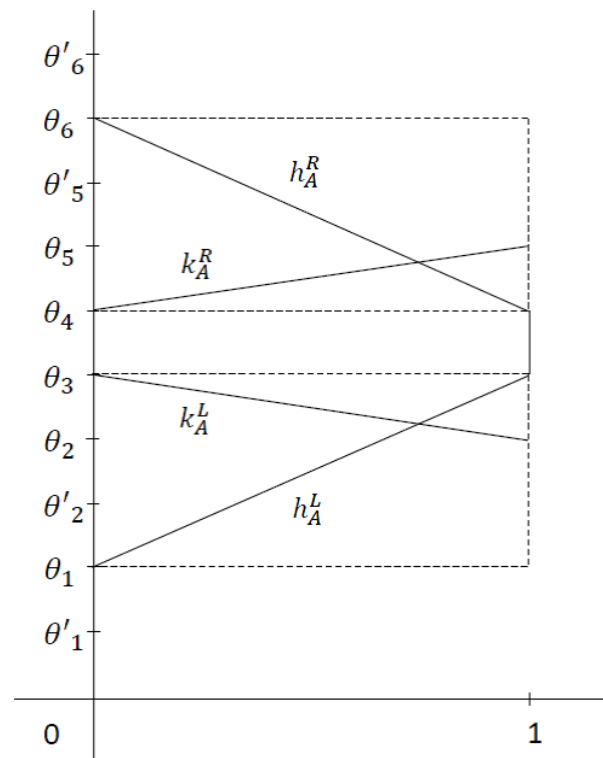


**Figure 5.** The figure of  $(\theta'_1, \theta'_2, \theta_3, \theta_4, \theta'_5, \theta'_6)$ .

Next, we find  $\zeta_R^r(y)$  and  $\eta_R^v(y)$ , also see the Figure 6.

$$\begin{aligned} \zeta_R^r(y) &= \frac{\int_0^1 y h_A^R(y) dy - \int_0^1 y h_A^L(y) dy}{\int_0^1 h_A^R(y) dy - \int_0^1 h_A^L(y) dy} \\ &= \frac{\int_0^1 (\theta_6 y + \theta_4 y^2 - \theta_6 y^2) dy - \int_0^1 (\theta_1 y + \theta_3 y^2 - \theta_1 y^2) dy}{\int_0^1 (\theta_6 + \theta_4 y - \theta_6 y) dy - \int_0^1 (\theta_1 + \theta_3 y - \theta_1 y) dy} \\ &= \frac{1}{3} \left[ \frac{\theta_6 + 2\theta_4 - \theta_1 - 2\theta_3}{\theta_6 + \theta_4 - \theta_1 - \theta_3} \right]. \end{aligned} \quad (3.12)$$

$$\begin{aligned}
 \eta_R^v(y) &= \frac{\int_0^1 y k_A^R dy - \int_0^1 y k_A^L(y) dy}{\int_0^1 k_A^R dy - \int_0^1 k_A^L(y) dy}, \\
 &= \frac{\int_0^1 (\theta_4 y + \theta_5 y^2 - \theta_4 y^2) dy - \int_0^1 (\theta_3 y + \theta_2 y^2 - \theta_3 y^2) dy}{\int_0^1 (\theta_4 + \theta_5 y - \theta_4 y) dy - \int_0^1 (\theta_3 + \theta_2 y - \theta_3 y) dy}, \\
 \eta_R^v(y) &= \frac{1}{3} \left[ \frac{2\theta_5 + \theta_4 - \theta_3 - 2\theta_2}{\theta_5 + \theta_4 - \theta_3 - \theta_2} \right]. \tag{3.13}
 \end{aligned}$$

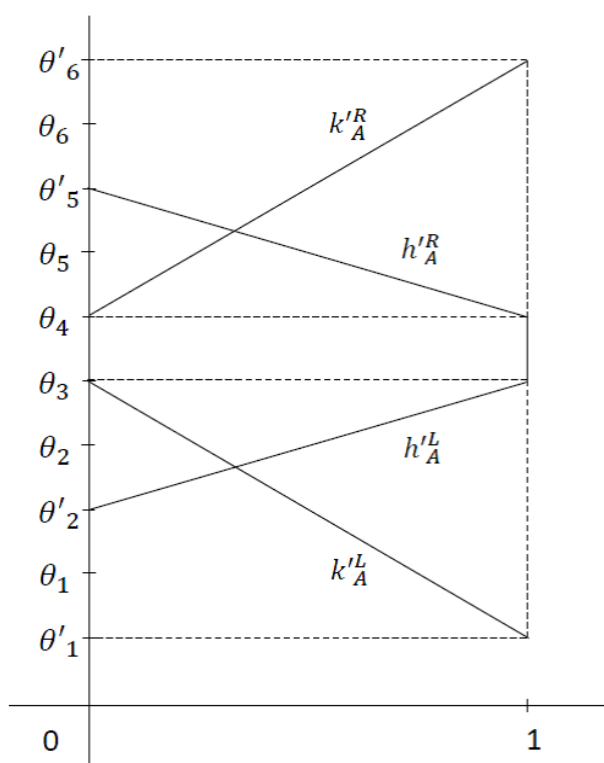


**Figure 6.** The figure of inverse of  $(\theta_1, \theta_2, \theta_3, \theta_4, \theta_5, \theta_6)$ .

Similarly, we find  $\alpha(y)$  and  $\beta(y)$ , also see the Figure 7.

$$\begin{aligned}
 \alpha(y) &= \frac{\int_0^1 y h_A^R(y) dy - \int_0^1 y h_A^L(y) dy}{\int_0^1 h_A^R(y) dy - \int_0^1 h_A^L(y) dy}, \\
 &= \frac{\int_0^1 (\theta'_5 y + \theta_4 y^2 - \theta'_5 y^2) dy - \int_0^1 (\theta'_2 y + \theta_3 y^2 - \theta'_2 y^2) dy}{\int_0^1 (\theta'_5 + \theta_4 y - \theta'_5 y) dy - \int_0^1 (\theta'_2 + \theta_3 y - \theta'_2 y) dy}, \\
 \alpha(y) &= \frac{1}{3} \left[ \frac{\theta'_5 + 2\theta_4 - 2\theta_3 - \theta'_2}{\theta'_5 + \theta_4 - \theta_3 - \theta'_2} \right]. \tag{3.14}
 \end{aligned}$$

$$\begin{aligned}
\beta(y) &= \frac{\int_0^1 y k_A^{\prime R}(y) dy - \int_0^1 y k_A^{\prime L}(y) dy}{\int_0^1 k_A^{\prime R}(y) dy - \int_0^1 k_A^{\prime L}(y) dy}, \\
&= \frac{\int_0^1 (\theta_4 y + \theta_6 y^2 - \theta_4 y^2) dy - \int_0^1 (\theta_3 y + \theta_1 y^2 - \theta_3 y^2) dy}{\int_0^1 (\theta_4 + \theta_6 y - \theta_4 y) dy - \int_0^1 (\theta_3 + \theta_1 y - \theta_3 y) dy}, \\
&= \frac{1}{3} \left[ \frac{2\theta_6 + \theta_4 - \theta_3 - 2\theta_1}{\theta_6 + \theta_4 - \theta_3 - \theta_1} \right]. \tag{3.15}
\end{aligned}$$



**Figure 7.** The figure of inverse of  $(\theta'_1, \theta'_2, \theta_3, \theta_4, \theta'_5, \theta'_6)$ .

Then  $(\langle \zeta_R^{\tau}(x), \zeta_R^{\tau}(y) \rangle, \langle \alpha(x), \alpha(y) \rangle; \langle \eta_R^{\nu}(x), \eta_R^{\nu}(y) \rangle, \langle \beta(x), \beta(y) \rangle)$  gives the centroid of the TrapLDFN.

**Definition 3.1.** The ranking function of the TrapLDFN  $A$  is defined by

$$\mathfrak{R}(A) = \sqrt{[\zeta_R^{\tau}(x) - \zeta_R^{\tau}(y)]^2 + [\alpha(x) - \alpha(y)]^2 + [\eta_R^{\nu}(x) - \eta_R^{\nu}(y)]^2 + [\beta(x) - \beta(y)]^2} \tag{3.16}$$

which is the Eculidean distance.

As a special case, if in a TrapLDFN, we let  $\theta_3 = \theta_4$ , then we will get a triangular LDFN with parameters  $\theta_1 \leq \theta_2 \leq \theta_3 \leq \theta_4 \leq \theta_5 \leq \theta_6$  and  $\theta'_1 \leq \theta'_2 \leq \theta_3 \leq \theta_4 \leq \theta'_5 \leq \theta'_6$ . It is denoted by

$\mathfrak{R}_{TriLDFN} = \left\{ \begin{matrix} (\theta_1, \theta_2, \theta_3, \theta_5, \theta_6) \\ (\theta'_1, \theta'_2, \theta_3, \theta'_5, \theta'_6) \end{matrix} \right\}$ . The centroids of the membership functions and non-membership functions of the triangular LDFN respectively are defined as

$$\begin{aligned}\zeta_R^\tau(x) &= \frac{1}{3} [\theta_1 + \theta_3 + \theta_6], \\ \eta_R^\nu(x) &= \frac{1}{3} [2\theta_2 - \theta_3 + 2\theta_5], \\ \alpha(x) &= \frac{1}{3} [\theta'_2 + \theta_3 + \theta'_5], \\ \beta(x) &= \frac{1}{3} [2\theta'_1 - \theta_3 + 2\theta'_6],\end{aligned}\quad (3.17)$$

and

$$\begin{aligned}\zeta_R^\tau(y) &= \frac{1}{3}, \\ \eta_R^\nu(y) &= \frac{2}{3}, \\ \alpha(y) &= \frac{1}{3}, \\ \beta(y) &= \frac{2}{3}.\end{aligned}\quad (3.18)$$

**Definition 3.2.** The ranking function of the triangular LDFN  $A$  is defined by

$$\mathfrak{R}(A) = \sqrt{[\zeta_R^\tau(x) - \zeta_R^\tau(y)]^2 + [\alpha(x) - \alpha(y)]^2 + [\eta_R^\nu(x) - \eta_R^\nu(y)]^2 + [\beta(x) - \beta(y)]^2}, \quad (3.19)$$

which is the Eculidean distance.

**Example 3.3.** Consider two TriLDFNs  $A = \left\{ \begin{matrix} (3,5,7,8,13) \\ (1,4,7,10,14) \end{matrix} \right\}$  and  $B = \left\{ \begin{matrix} (1,3,9,10,13) \\ (0,4,9,13,15) \end{matrix} \right\}$ . Then using the proposed method we find  $\mathfrak{R}(A)$ ,

$$\zeta_R^\tau(x) = \frac{1}{3} [\theta_1 + \theta_3 + \theta_6] = \frac{1}{3} [3 + 7 + 13] = 7.67 \quad (3.20)$$

$$\eta_R^\nu(x) = \frac{1}{3} [2\theta_2 - \theta_3 + 2\theta_5] = \frac{1}{3} [10 - 7 + 16] = 6.33 \quad (3.21)$$

$$\alpha(x) = \frac{1}{3} [\theta'_2 + \theta_3 + \theta'_5] = \frac{1}{3} [4 + 7 + 10] = 7 \quad (3.22)$$

$$\beta(x) = \frac{1}{3} [2\theta'_1 - \theta_3 + 2\theta'_6] = \frac{1}{3} [2 - 7 + 28] = 7.67. \quad (3.23)$$

Also

$$\zeta_R^\tau(y) = 0.33, \quad \eta_R^\nu(y) = 0.67, \quad \alpha(y) = 0.33, \quad \beta(y) = 0.67. \quad (3.24)$$

Now,

$$\begin{aligned}\mathfrak{R}(A) &= \sqrt{[\zeta_R^\tau(x) - \zeta_R^\tau(y)]^2 + [\alpha(x) - \alpha(y)]^2 + [\eta_R^\nu(x) - \eta_R^\nu(y)]^2 + [\beta(x) - \beta(y)]^2} \\ &= 13.394.\end{aligned}\quad (3.25)$$

Now, by using the proposed method we find  $\mathfrak{R}(B)$ ,

$$\zeta_R^\tau(x) = \frac{1}{3} [\theta_1 + \theta_3 + \theta_6] = \frac{1}{3} [1 + 9 + 13] = 7.67 \quad (3.26)$$

$$\eta_R^\nu(x) = \frac{1}{3} [2\theta_2 - \theta_3 + 2\theta_5] = \frac{1}{3} [6 - 9 + 20] = 5.67 \quad (3.27)$$

$$\alpha(x) = \frac{1}{3} [\theta'_2 + \theta_3 + \theta'_5] = \frac{1}{3} [4 + 9 + 13] = 8.67 \quad (3.28)$$

$$\beta(x) = \frac{1}{3} [2\theta'_1 - \theta_3 + 2\theta'_6] = \frac{1}{3} [0 - 9 + 30] = 7. \quad (3.29)$$

Also

$$\zeta_R^\tau(y) = 0.33, \quad \eta_R^\nu(y) = 0.67, \quad \alpha(y) = 0.33, \quad \beta(y) = 0.67. \quad (3.30)$$

Now,

$$\begin{aligned} \mathfrak{K}(B) &= \sqrt{[\zeta_R^\tau(x) - \zeta_R^\tau(y)]^2 + [\alpha(x) - \alpha(y)]^2 + [\eta_R^\nu(x) - \eta_R^\nu(y)]^2 + [\beta(x) - \beta(y)]^2} \\ &= 13.729. \end{aligned} \quad (3.31)$$

As  $\mathfrak{K}(A) < \mathfrak{K}(B) \implies A < B$ .

#### 4. Ranking of trapezoidal LDFNs using circumcenter of centroids

A trapezoid's centroid is regarded as the shape's equilibrium position. The linear Diophantine fuzzy number's membership function trapezoid is divided into three planar figures. These three plane figures are in order, a triangle, a rectangle, and another triangle. The point of reference for defining the ordering of linear Diophantine fuzzy numbers is the circumcenter of the centroids of these three plane figures. Each centroid point ( $G_1$  of a triangle,  $G_2$  of a rectangle, and  $G_3$  of a triangle) is a balancing point for each unique planar figure, and the circumcenter of these centroid points is equidistant from each vertex, which is why this point was chosen as a point of reference (which are centroids). As a result, this point would serve as a more accurate reference point than the trapezoid's centroid.

Take into consideration the trapezoidal linear Diophantine fuzzy number

$$\mathfrak{L}_{\mathfrak{R}TrapLDFN} = \left\{ \begin{array}{l} (\theta_1, \theta_2, \theta_3, \theta_4, \theta_5, \theta_6) \\ (\theta'_1, \theta'_2, \theta'_3, \theta'_4, \theta'_5, \theta'_6) \end{array} \right\}. \quad (4.1)$$

The centroids of the three plane figures that make up the  $\zeta_R^\tau(x)$  are  $G_1 = (\frac{\theta_1+2\theta_3}{3}, \frac{1}{3})$ ,  $G_2 = (\frac{\theta_3+\theta_4}{2}, \frac{1}{2})$  and  $G_3 = (\frac{2\theta_4+\theta_6}{3}, \frac{1}{3})$  and membership function are  $G_1 = (\frac{\theta_1+2\theta_3}{3}, \frac{1}{3})$ ,  $G_2 = (\frac{\theta_3+\theta_4}{2}, \frac{1}{2})$  and  $G_3 = (\frac{2\theta_4+\theta_6}{3}, \frac{1}{3})$  are non-collinear and form a triangle. Since the equation of line  $G_1G_3$  is  $y = \frac{1}{3}$  and  $G_2$  does not lie on line  $G_1G_3$ . Figure 8 displays the circumcenter of the centroids of  $\zeta_R^\tau(x)$ .

Likewise, the centroids of the three plane figures that make up the membership function of  $\alpha(x)$  are, in a similar manner,  $G'_1 = (\frac{\theta'_2+2\theta_3}{3}, \frac{1}{3})$ ,  $G'_2 = (\frac{\theta_3+\theta_4}{2}, \frac{1}{2})$  and  $G'_3 = (\frac{2\theta_4+\theta'_5}{3}, \frac{1}{3})$ .  $G'_2$  does not fall on the line  $G'_1G'_3$ , and its equation is  $y = \frac{1}{3}$ .  $G'_1$ ,  $G'_2$  and  $G'_3$  are therefore non-collinear and form a triangle. Figure 9 displays the circumcenter of the centroids of  $\alpha(x)$ .

Finding the triangle's circumcenter is our next task. The general equation for a triangle's circumcentre with the coordinates  $(x_1, y_1)$ ,  $(x_2, y_2)$  and  $(x_3, y_3)$  is

$$x = \frac{-(y_1 - y_2)u + (y_1 - y_3)v}{2K}, \quad (4.2)$$

$$y = \frac{(x_1 - x_2)u - (x_1 - x_3)v}{2K}, \quad (4.3)$$

where

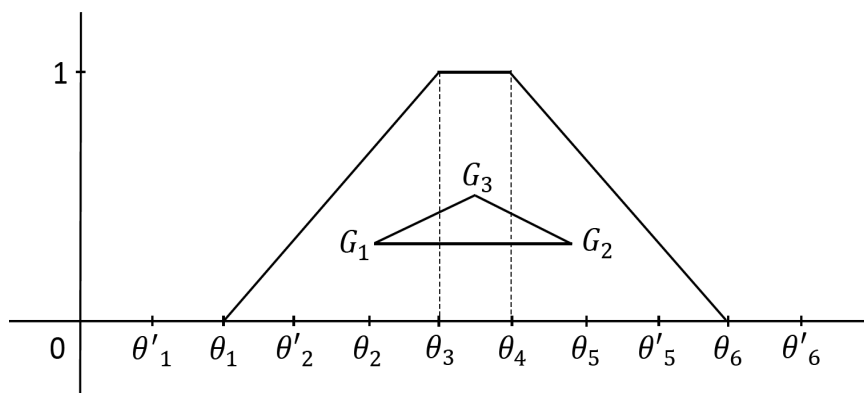
$$v = x_1^2 + y_1^2 - x_2^2 - y_2^2, \tag{4.4}$$

$$u = x_1^2 + y_1^2 - x_3^2 - y_3^2, \tag{4.5}$$

$$K = (x_1 - x_2)(y_1 - y_3) - (x_1 - x_3)(y_1 - y_2). \tag{4.6}$$

The circumcenter  $\hat{S}_{A_{(\zeta_R^i(x))}}(\bar{x}_0, \bar{y}_0)$  of the triangle with vertices  $G_1, G_2$  and  $G_3$  (as shown in Figure 8) of the membership function of the trapezoidal LDFN  $A = \left\{ \begin{matrix} (\theta_1, \theta_2, \theta_3, \theta_4, \theta_5, \theta_6) \\ (\theta'_1, \theta'_2, \theta'_3, \theta'_4, \theta'_5, \theta'_6) \end{matrix} \right\}$  is

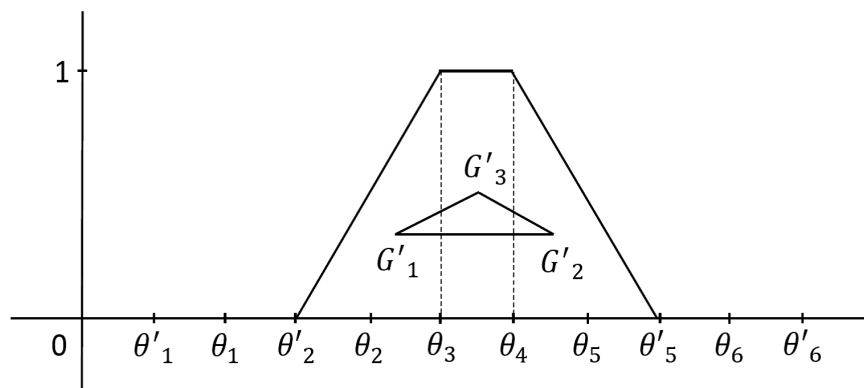
$$\hat{S}_{A_{(\zeta_R^i(x))}}(\bar{x}_0, \bar{y}_0) = \left( \frac{\theta_1 + 2\theta_3 + 2\theta_4 + \theta_6}{6}, \frac{(2\theta_1 + \theta_3 - 3\theta_4)(2\theta_6 + \theta_4 - 3\theta_3) + 5}{12} \right), \tag{4.7}$$



**Figure 8.** Circumcenter of centroids of  $\zeta_R^i(x)$ .

Also, the circumcenter  $\hat{S}_{A_{(\alpha(x))}}(\bar{x}'_0, \bar{y}'_0)$  of the triangle with vertices  $G'_1, G'_2$  and  $G'_3$  (as shown in Figure 9) is

$$\hat{S}_{A_{(\alpha(x))}}(\bar{x}'_0, \bar{y}'_0) = \left( \frac{\theta'_2 + 2\theta_3 + 2\theta_4 + \theta'_5}{6}, \frac{(2\theta'_2 + \theta_3 - 3\theta_4)(2\theta'_5 + \theta_4 - 3\theta_3) + 5}{12} \right). \tag{4.8}$$

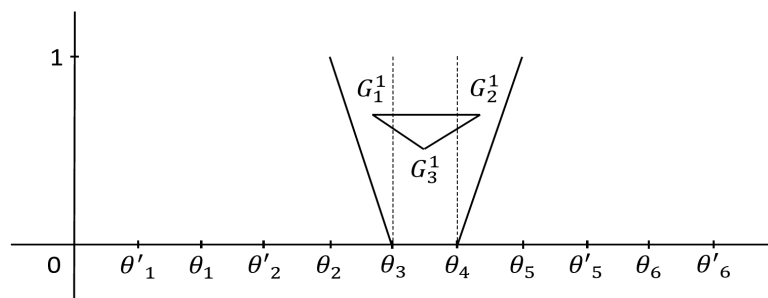


**Figure 9.** Circumcenter of centroids of  $\alpha(x)$ .

Separate the TrapLDFN trapezoid of non-membership functions into three plane figures as well. Again, a triangle, a rectangle, and a triangle successively make up these three plane figures. Additionally, the centroids of the three plane figures that make up the non-membership function  $\eta_{\mathfrak{R}}^v(x)$  are  $G_1^1 = \left(\frac{\theta_2+2\theta_3}{3}, \frac{2}{3}\right)$ ,  $G_2^1 = \left(\frac{(\theta_3+\theta_4)}{2}, \frac{1}{2}\right)$  and  $G_3^1 = \left(\frac{(2\theta_4+\theta_5)}{3}, \frac{2}{3}\right)$  correspondingly. The line  $G_1^1G_3^1$  is has the equation  $y = \frac{2}{3}$ , and  $G_2^1$  does not fall on this line.

$G_1^1, G_2^1$  and  $G_3^1$  are therefore not collinear and form a triangle. Figure 10 displays the circumcenter of the centroids of  $\eta_{\mathfrak{R}}^v(x)$ . And the circumcenter  $\hat{S}_{A_{(\eta_{\mathfrak{R}}^v(x))}}$  of the triangle formed by the vertices  $G_1^1, G_2^1$  and  $G_3^1$  of the non-membership function of the trapezoidal LDFN  $\mathfrak{L}_{\mathfrak{R}TrapLDFN} = \left\{ \begin{matrix} (\theta_1, \theta_2, \theta_3, \theta_4, \theta_5, \theta_6) \\ (\theta'_1, \theta'_2, \theta_3, \theta_4, \theta'_5, \theta'_6) \end{matrix} \right.$  is

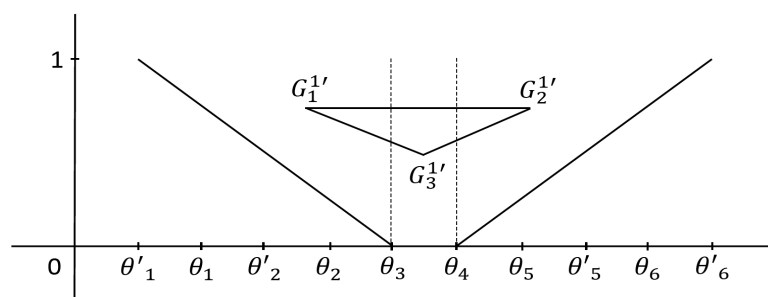
$$\hat{S}_{A_{(\eta_{\mathfrak{R}}^v(x))}}(\bar{x}_1, \bar{y}_1) = \left( \frac{\theta_2 + 2\theta_3 + 2\theta_4 + \theta_5}{6}, \frac{(2\theta_2 + \theta_3 - 3\theta_4)(-2\theta_5 - \theta_4 + 3\theta_3) + 7}{12} \right). \tag{4.9}$$



**Figure 10.** Circumcenter of centroids of  $\eta_{\mathfrak{R}}^v(x)$ .

Similarly, the centroids of the three plane figures of nonmembership function  $\beta(x)$  are  $G_1^{1'} = \left(\frac{\theta'_1+2\theta_3}{3}, \frac{2}{3}\right)$ ,  $G_2^{1'} = \left(\frac{(\theta_3+\theta_4)}{2}, \frac{1}{2}\right)$  and  $G_3^{1'} = \left(\frac{(2\theta_4+\theta'_6)}{3}, \frac{2}{3}\right)$  respectively. Equation of the line  $G_1^{1'}G_3^{1'}$  is  $y = \frac{2}{3}$  and  $G_2^{1'}$  does not lie on the line  $G_1^{1'}G_3^{1'}$ . Therefore  $G_1^{1'}, G_2^{1'}$  and  $G_3^{1'}$  (as shown in Figure 11) are non-collinear and they form a triangle. The circumcenter of centroids of  $\beta(x)$  is

$$\hat{S}_{A_{(\beta(x))}}(\bar{x}'_1, \bar{y}'_1) = \left( \frac{\theta'_1 + 2\theta_3 + 2\theta_4 + \theta'_6}{6}, \frac{(2\theta'_1 + \theta_3 - 3\theta_4)(-2\theta'_6 - \theta_4 + 3\theta_3) + 7}{12} \right). \tag{4.10}$$



**Figure 11.** Circumcenter of centroids of  $\beta(x)$ .

**Definition 4.1.** The ranking function of the trapezoidal LDFN  $A = \left\{ \begin{matrix} (\theta_1, \theta_2, \theta_3, \theta_4, \theta_5, \theta_6) \\ (\theta'_1, \theta'_2, \theta_3, \theta_4, \theta'_5, \theta'_6) \end{matrix} \right.$  for membership function and non-membership function are defined as  $R_{A_{(\xi_{\mathfrak{R}}^v(x))}} = \sqrt{x_0^2 + y_0^2}$ ,  $R_{A_{(\alpha(x))}} = \sqrt{x_0'^2 + y_0'^2}$  and



$R_{A_{(t_{\mathfrak{R}}^y(x))}} = \sqrt{x_1^2 + y_1^2}$ ,  $R_{A_{(\beta(x))}} = \sqrt{x_1'^2 + y_1'^2}$ , then

$$R_A = \frac{1}{4} \left( R_{A_{(\zeta_{\mathfrak{R}}^x(x))}} + R_{A_{(\alpha(x))}} + R_{A_{(t_{\mathfrak{R}}^y(x))}} + R_{A_{(\beta(x))}} \right). \quad (4.11)$$

As an exception, if we allow  $\theta_3 = \theta_4$  in a TrapLDFN, we will obtain a triangular LDFN with the parameters  $\theta_1 \leq \theta_2 \leq \theta_3 \leq \theta_4 \leq \theta_5 \leq \theta_6$  and  $\theta'_1 \leq \theta'_2 \leq \theta_3 \leq \theta_4 \leq \theta'_5 \leq \theta'_6$ . It is indicated by  $\mathfrak{L}_{\mathfrak{R}TriLDFN} = \left\{ (\theta_1, \theta_2, \theta_3, \theta_5, \theta_6), (\theta'_1, \theta'_2, \theta_3, \theta'_5, \theta'_6) \right\}$ . The circumcenters of the centroids for the triangular LDFN's membership function and nonmembership function are defined as follows.

$$\hat{S}_{A_{(\zeta_{\mathfrak{R}}^x(x))}}(\bar{x}_0, \bar{y}_0) = \left( \frac{\theta_1 + 4\theta_3 + \theta_6}{6}, \frac{4(\theta_1 - \theta_3)(\theta_6 - \theta_3) + 5}{12} \right), \quad (4.12)$$

$$\hat{S}_{A_{(\alpha(x))}}(\bar{x}'_0, \bar{y}'_0) = \left( \frac{\theta'_2 + 4\theta_3 + \theta'_5}{6}, \frac{4(\theta'_2 - \theta_3)(\theta'_5 - \theta_3) + 5}{12} \right), \quad (4.13)$$

and

$$\hat{S}_{A_{(t_{\mathfrak{R}}^y(x))}}(\bar{x}_1, \bar{y}_1) = \left( \frac{\theta_2 + 4\theta_3 + \theta_5}{6}, \frac{4(\theta_2 - \theta_3)(-\theta_5 + \theta_3) + 7}{12} \right), \quad (4.14)$$

$$\hat{S}_{A_{(\beta(x))}}(\bar{x}'_1, \bar{y}'_1) = \left( \frac{\theta'_1 + 4\theta_3 + \theta'_6}{6}, \frac{4(\theta'_1 - \theta_3)(-\theta'_6 + \theta_3) + 7}{12} \right). \quad (4.15)$$

**Example 4.2.** Consider two TriLDFN  $A = \left\{ \begin{array}{l} (2, 4, 5, 7, 9) \\ (1, 3, 5, 8, 10) \end{array} \right\}$  and  $B = \left\{ \begin{array}{l} (3, 5, 7, 8, 9) \\ (2, 4, 7, 9, 9) \end{array} \right\}$ . Then using the proposed method we find  $\mathfrak{R}(A)$ ,

$$\hat{S}_{A_{(\zeta_{\mathfrak{R}}^x(x))}}(\bar{x}_0, \bar{y}_0) = \left( \frac{\theta_1 + 4\theta_3 + \theta_6}{6}, \frac{4(\theta_1 - \theta_3)(\theta_6 - \theta_3) + 5}{12} \right) = (5.16, -3.58), \quad (4.16)$$

$$\hat{S}_{A_{(\alpha(x))}}(\bar{x}'_0, \bar{y}'_0) = \left( \frac{\theta'_2 + 4\theta_3 + \theta'_5}{6}, \frac{4(\theta'_2 - \theta_3)(\theta'_5 - \theta_3) + 5}{12} \right) = (5.16, -1.58), \quad (4.17)$$

$$\hat{S}_{A_{(t_{\mathfrak{R}}^y(x))}}(\bar{x}_1, \bar{y}_1) = \left( \frac{\theta_2 + 4\theta_3 + \theta_5}{6}, \frac{4(\theta_2 - \theta_3)(-\theta_5 + \theta_3) + 7}{12} \right) = (5.33, 1.25), \quad (4.18)$$

$$\hat{S}_{A_{(\beta(x))}}(\bar{x}'_1, \bar{y}'_1) = \left( \frac{\theta'_1 + 4\theta_3 + \theta'_6}{6}, \frac{4(\theta'_1 - \theta_3)(-\theta'_6 + \theta_3) + 7}{12} \right) = (5.16, 7.25). \quad (4.19)$$

Also,

$$\begin{aligned} \mathfrak{R}_{A_{(\zeta_{\mathfrak{R}}^x(x))}} &= \sqrt{x_0^2 + y_0^2} = 6.28, & \mathfrak{R}_{A_{(\alpha(x))}} &= \sqrt{x_0'^2 + y_0'^2} = 5.39, \\ \mathfrak{R}_{A_{(t_{\mathfrak{R}}^y(x))}} &= \sqrt{x_1^2 + y_1^2} = 5.47, & \mathfrak{R}_{A_{(\beta(x))}} &= \sqrt{x_1'^2 + y_1'^2} = 8.89. \end{aligned} \quad (4.20)$$

Now,

$$\mathfrak{R}_A = \frac{1}{4} \left( R_{A_{(\zeta_{\mathfrak{R}}^x(x))}} + R_{A_{(\alpha(x))}} + R_{A_{(t_{\mathfrak{R}}^y(x))}} + R_{A_{(\beta(x))}} \right) = 6.50. \quad (4.21)$$

Now, using the proposed method we find  $\mathfrak{R}(B)$ ,

$$\hat{S}_{B_{(\zeta_R^{\alpha(x)})}}(\bar{x}_0, \bar{y}_0) = \left( \frac{\theta_1 + 4\theta_3 + \theta_6}{6}, \frac{4(\theta_1 - \theta_3)(\theta_6 - \theta_3) + 5}{12} \right) = (6.66, -2.25), \quad (4.22)$$

$$\hat{S}_{B_{(\alpha(x))}}(\bar{x}'_0, \bar{y}'_0) = \left( \frac{\theta'_2 + 4\theta_3 + \theta'_5}{6}, \frac{4(\theta'_2 - \theta_3)(\theta'_5 - \theta_3) + 5}{12} \right) = (6.83, -1.58), \quad (4.23)$$

$$\hat{S}_{B_{(\eta_{\mathfrak{R}}^{\alpha(x)})}}(\bar{x}_1, \bar{y}_1) = \left( \frac{\theta_2 + 4\theta_3 + \theta_5}{6}, \frac{4(\theta_2 - \theta_3)(-\theta_5 + \theta_3) + 7}{12} \right) = (6.83, 1.25), \quad (4.24)$$

$$\hat{S}_{B_{(\beta(x))}}(\bar{x}'_1, \bar{y}'_1) = \left( \frac{\theta'_1 + 4\theta_3 + \theta'_6}{6}, \frac{4(\theta'_1 - \theta_3)(-\theta'_6 + \theta_3) + 7}{12} \right) = (6.5, 3.91). \quad (4.25)$$

Also,

$$\begin{aligned} \mathfrak{R}_{B_{(\zeta_R^{\alpha(x)})}} &= \sqrt{x_0^2 + y_0^2} = 6.97, & \mathfrak{R}_{B_{(\alpha(x))}} &= \sqrt{x_0'^2 + y_0'^2} = 7.01, \\ \mathfrak{R}_{B_{(\eta_{\mathfrak{R}}^{\alpha(x)})}} &= \sqrt{x_1^2 + y_1^2} = 6.94, & \mathfrak{R}_{B_{(\beta(x))}} &= \sqrt{x_1'^2 + y_1'^2} = 7.58. \end{aligned} \quad (4.26)$$

Now,

$$\mathfrak{R}_B = \frac{1}{4} \left( R_{B_{(\zeta_R^{\alpha(x)})}} + R_{B_{(\alpha(x))}} + R_{B_{(\eta_{\mathfrak{R}}^{\alpha(x)})}} + R_{B_{(\beta(x))}} \right) = 7.12. \quad (4.27)$$

As  $\mathfrak{R}(A) < \mathfrak{R}(B) \implies A < B$ .

## 5. Conclusions

The linear Diophantine fuzzy numbers have been identified in this research. In this study, we discovered the circumcenter of centroids of the membership function and non-membership function of a linear Diophantine fuzzy number. We also suggested a distance approach for ranking the linear Diophantine fuzzy number depending on the circumcenter of centroids. The suggested method gives the precise organization of linear Diophantine fuzzy numbers. It may be used to rank the linear Diophantine fuzzy numbers in order to deal with various fuzzy optimization issues. This method can be implemented to rank trapezoidal in addition to triangular fuzzy numbers and their counterparts. The following areas may be covered by our future projects:

- (i) Linear programming problems;
- (ii) Differential equations;
- (iii) Game theory;
- (iv) Transportation problems;
- (v) Differential games.

## Acknowledgements

The authors would like to express their sincere thanks to the anonymous reviewers for their careful reading and constructive comments.

## Conflict of interest

The authors of this paper declare that they have no conflict of interest.

## References

1. S. Abbasbandy, T. Hajjari, A new approach for ranking of trapezoidal fuzzy numbers, *Comput. Math. Appl.*, **57** (2009), 413–419. <https://doi.org/10.1016/j.camwa.2008.10.090>
2. M. Akram, *m-Polar fuzzy graphs: Theory, methods and applications*, Fuzziness and Soft Computing, Springer, **371** (2019), 1–296. <https://doi.org/10.1007/978-3-030-03751-2>
3. J. Ali, H. Garg, On spherical fuzzy distance measure and TAOV method for decision-making problems with incomplete weight information, *Eng. Appl. Artif. Intell.*, **119** (2023), 105726. <https://doi.org/10.1016/j.engappai.2022.105726>
4. J. Ali, M. Naeem, Multi-criteria decision-making method based on complex t-spherical fuzzy Aczel-Alsina aggregation operators and their application, *Symmetry*, **15** (2022), 85. <https://doi.org/10.3390/sym15010085>
5. J. Ali, A q-rung orthopair fuzzy MARCOS method using novel score function and its application to solid waste management, *Appl. Intell.*, **52** (2022), 8770–8792. <https://doi.org/10.1007/s10489-021-02921-2>
6. J. Ali, M. Naeem, Cosine similarity measures between q-rung orthopair linguistic sets and their application to group decision making problems, *Sci. Rep.*, **12** (2022), 14456. <https://doi.org/10.1038/s41598-022-18694-8>
7. A. O. Almagrabi, S. Abdullah, M. Shams, Y. D. Al-Otaibi, S. Ashraf, A new approach to q-linear Diophantine fuzzy emergency decision support system for COVID19, *J. Amb. Intell. Hum. Comp.*, **13** (2022), 1687–1713. <https://doi.org/10.1007/s12652-021-03130-y>
8. P. P. Angelov, Optimization in an intuitionistic fuzzy environment, *Fuzzy Set. Syst.*, **86** (1997), 299–306. [https://doi.org/10.1016/S0165-0114\(96\)00009-7](https://doi.org/10.1016/S0165-0114(96)00009-7)
9. A. Ashraf, K. Ullah, A. Hussain, M. Bari, Interval-valued picture fuzzy maclaurin symmetric mean operator with application in multiple attribute decision-making, *Rep. Mech. Eng.*, **3** (2022), 210–226. <https://doi.org/10.31181/rme20020042022a>
10. K. T. Atanasov, Intuitionistic fuzzy sets, *Fuzzy Set. Syst.*, **20** (1986), 87–96. [https://doi.org/10.1016/S0165-0114\(86\)80034-3](https://doi.org/10.1016/S0165-0114(86)80034-3)
11. S. Ayub, M. Shabir, M. Riaz, M. Aslam, R. Chinram, Linear Diophantine fuzzy relations and their algebraic properties with decision making, *Symmetry*, **13** (2021), 945. <https://doi.org/10.3390/sym13060945>
12. R. E. Bellman, L. A. Zadeh, Decision-making in a fuzzy environment, *Manag. Sci.*, **17** (1970), B-141. <https://doi.org/10.1287/mnsc.17.4.B141>
13. S. K. Bharati, S. R. Singh, Solving multi objective linear programming problems using intuitionistic fuzzy optimization method: A comparative study, *Int. J. Model. Optim.*, **4** (2014), 1–7. <https://doi.org/10.7763/IJMO.2014.V4.339>

14. S. K. Bharati, S. R. Singh, A note on solving a fully intuitionistic fuzzy linear programming problem based on sign distance, *Int. J. Comput. Appl.*, **119** (2015), 30–35. <https://doi.org/10.5120/21379-4347>
15. S. K. Bharati, R. Malhotra, Two stage intuitionistic fuzzy time minimizing transportation problem based on generalized Zadeh's extension principle, *Int. J. Syst. Assur. Eng.*, **8** (2017), 1442–1449. <https://doi.org/10.1007/s13198-017-0613-9>
16. J. Chen, S. Li, S. Ma, X. Wang, m-Polar fuzzy sets: An extension of bipolar fuzzy sets, *Sci. World J.*, **2014** (2014), 1–8. <https://doi.org/10.1155/2014/416530>
17. K. P. Chiao, Characteristic value of fuzzy number defined with parameter integral form, *Proc. Ninth Nat. Conf. Fuzzy Theo. Appl.*, 2000.
18. A. K. Das, C. Granados, FP-Intuitionistic multi-fuzzy N-soft set and its induced FP-Hesitant N soft set in decision-making, *Decis. Mak. Appl. Manag. Eng.*, **5** (2022), 67–89. <https://doi.org/10.31181/dmame181221045d>
19. P. K. De, D. Das, A study on ranking of trapezoidal intuitionistic fuzzy numbers, *Int. J. Comput. Inf. Sys. Indust. Manag. Appl.*, **6** (2014), 437–444.
20. D. Dubey, S. Chandra, A. Mehra, Fuzzy linear programming under interval uncertainty based on IFS representation, *Fuzzy Set. Syst.*, **188** (2012), 68–87. <https://doi.org/10.1016/j.fss.2011.09.008>
21. A. Ebrahimnejad, J. L. Verdegay, *Fuzzy sets-based methods and techniques for modern analytics*, Springer, Switzerland, **364** (2018). <https://doi.org/10.1007/978-3-319-73903-8>
22. M. Esmailzadeh, M. Esmailzadeh, New distance between triangular intuitionistic fuzzy numbers, *Adv. Comput. Math. Appl.*, **2** (2013), 310–314
23. H. M. A. Farid, R. Kausar, M. Riaz, D. Marinkovic, M. Stankovic, Linear Diophantine fuzzy fairly averaging operator for suitable biomedical material selection, *Axioms*, **11** (2022), 735. <https://doi.org/10.3390/axioms11120735>
24. A. H. Ganesh, M. Suresh, Ordering of generalised trapezoidal fuzzy numbers based on area method using euler line of centroids, *Adv. Fuzzy Math.*, **12** (2017), 783–791.
25. H. Garg, A novel correlation coefficients between Pythagorean fuzzy sets and its applications to decision-making processes, *Int. J. Intel. Syst.*, **31** (2016), 1234–1252. <https://doi.org/10.1002/int.21827>
26. P. Grzegorzewski, Distances and orderings in a family of intuitionistic fuzzy numbers, *EUSFLAT Conf.*, 2003, 223–227.
27. P. Gupta, M. K. Mehrlawat, F. Ahemad, An MAGDM approach with q-rung orthopair trapezoidal fuzzy information for waste disposal site selection problem, *Int. J. Intel. Syst.*, **36** (2021), 4524–4559. <https://doi.org/10.1002/int.22468>
28. M. R. Hashmi, S. T. Tehrim, M. Riaz, D. Pamucar, G. Cirovic, Spherical linear diophantine fuzzy soft rough sets with multi-criteria decision making, *Axioms*, **10** (2021), 185. <https://doi.org/10.3390/axioms10030185>
29. A. Iampan, G. S. García, M. Riaz, H. M. A. Farid, R. Chinram, Linear Diophantine fuzzy Einstein aggregation operators for multi-criteria decision-making problems, *J. Math.*, **2021** (2021), 1–31. <https://doi.org/10.1155/2021/5548033>

30. B. Jana, T. K. Roy, Multi-objective intuitionistic fuzzy linear programming and its application in transportation model, *Notes Intuition. Fuzzy Set.*, **13** (2007), 34–51.
31. H. Kamac, Linear Diophantine fuzzy algebraic structures, *J. Amb. Intell. Hum. Comp.*, **12** (2021), 10353–10373. <https://doi.org/10.1007/s12652-020-02826-x>
32. N. Khan, N. Yaqoob, M. Shams, Y. U. Gaba, M. Riaz, Solution of linear and quadratic equations based on triangular linear diophantine fuzzy numbers, *J. Funct. Space.*, **2021** (2021), 1–14. <https://doi.org/10.1155/2021/8475863>
33. A. Kumar, M. Kaur, A ranking approach for intuitionistic fuzzy numbers and its application, *J. Appl. Res. Technol.*, **11** (2013), 381–396. [https://doi.org/10.1016/S1665-6423\(13\)71548-7](https://doi.org/10.1016/S1665-6423(13)71548-7)
34. D. F. Li, A ratio ranking method of triangular intuitionistic fuzzy numbers and its application to MADM problems, *Comput. Math. Appl.*, **60** (2010), 1557–1570. <https://doi.org/10.1016/j.camwa.2010.06.039>
35. G. S. Mahapatra, M. Mitra, T. K. Roy, Intuitionistic fuzzy multi-objective mathematical programming on reliability optimization model, *Int. J. Fuzzy Syst.*, **12** (2010), 259–266. <https://doi.org/10.30000/IJFS.201009.0010>
36. T. Mahmood, I. Haleemzai, Z. Ali, D. Pamucar, D. Marinkovic, Power Muirhead mean operators for interval-valued linear Diophantine fuzzy sets and their application in decision-making strategies, *Mathematics*, **10** (2021), 70. <https://doi.org/10.3390/math10010070>
37. H. B. Mitchell, Ranking-intuitionistic fuzzy numbers, *Int. J. Uncertain. Fuzz.*, **12** (2004), 377–386. <https://doi.org/10.1142/S0218488504002886>
38. M. M. S. Mohammad, S. Abdullah, M. M. Al-Shomrani, Some linear Diophantine fuzzy similarity measures and their application in decision making problem, *IEEE Access*, **10** (2022), 29859–29877. <https://doi.org/10.1109/ACCESS.2022.3151684>
39. S. Mukherjee, K. Basu, Solution of a class of intuitionistic fuzzy assignment problem by using similarity measures, *Knowl.-Based Syst.*, **27** (2012), 170–179. <https://doi.org/10.1016/j.knosys.2011.09.007>
40. S. H. Nasser, N. Taghi-Nezhad, A. Ebrahimnejad, A note on ranking fuzzy numbers with an area method using circumcenter of centroids, *Fuzzy Inform. Eng.*, **9** (2017), 259–268. <https://doi.org/10.1016/j.fiae.2017.06.009>
41. V. L. G. Nayagam, S. Jeevaraj, G. Sivaraman, Complete ranking of intuitionistic fuzzy numbers, *Fuzzy Inform. Eng.*, **8** (2016), 237–254. <https://doi.org/10.1016/j.fiae.2016.06.007>
42. H. M. Nehi, A new ranking method for intuitionistic fuzzy numbers, *Int. J. Fuzzy Syst.*, **12** (2010), 80–86.
43. A. K. Nishad, S. K. Bharati, S. R. Singh, *A new centroid method of ranking for intuitionistic fuzzy numbers*, Proceedings of the Second International Conference on Soft Computing for Problem Solving (SocProS 2012), Springer, New Delhi, **236** (2014), 151–159.
44. G. A. Papakostas, A. G. Hatzimichailidis, V. G. Kaburlasos, Distance and similarity measures between intuitionistic fuzzy sets: A comparative analysis from a pattern recognition point of view, *Pattern Recogn. Lett.*, **34** (2013), 1609–1622. <https://doi.org/10.1016/j.patrec.2013.05.015>

45. K. A. Prakash, M. Suresh, S.Vengataasalam, A new approach for ranking of intuitionistic fuzzy numbers using a centroid concept, *Math. Sci.*, **10** (2016), 177–184. <https://doi.org/10.1007/s40096-016-0192-y>
46. P. Rao, N. R. Shankar, Ranking fuzzy numbers with a distance method using circumcenter of centroids and an index of modality, *Adv. Fuzzy Syst.*, **2011** (2011), 1–7. <https://doi.org/10.1155/2011/178308>
47. M. Riaz, M. R. Hashmi, Linear Diophantine fuzzy set and its applications towards multi-attribute decision-making problems, *J. Intel. Fuzzy Syst.*, **37** (2019), 5417–5439. <https://doi.org/10.3233/JIFS-190550>
48. M. Riaz, H. M. A. Farid, Picture fuzzy aggregation approach with application to third-party logistic provider selection process, *Rep. Mech. Eng.*, **3** (2022), 227–236. <http://dx.doi.org/10.31181/rme20023062022r>
49. J. Ramesh, Decision making in the presence of fuzzy variables, *IEEE Trans. Syst. Man Cybern. Syst.*, **6** (1976), 698–703. <https://doi.org/10.1109/TSMC.1976.4309421>
50. S. S. Roseline, E. C. H. Amirtharaj, A new ranking of intuitionistic fuzzy numbers with distance method based on the circumcenter of centroids, *Int. J. Appl. Math.*, **2** (2013), 37–44.
51. E. Szmidt, J. Kacprzyk, Distances between intuitionistic fuzzy sets, *Fuzzy Set. Syst.*, **114** (2000), 505–518. [https://doi.org/10.1016/S0165-0114\(98\)00244-9](https://doi.org/10.1016/S0165-0114(98)00244-9)
52. X. Wang, E. E. Kerre, Reasonable properties for the ordering of fuzzy quantities (I), *Fuzzy Set. Syst.*, **118** (2001), 375–385. [https://doi.org/10.1016/S0165-0114\(99\)00062-7](https://doi.org/10.1016/S0165-0114(99)00062-7)
53. W. Wang, X. Xin, Distance measure between intuitionistic fuzzy sets, *Pattern Recogn. Lett.*, **26** (2005), 2063–2069. <https://doi.org/10.1016/j.patrec.2005.03.018>
54. R. R. Yager, *Pythagorean fuzzy subsets*, In 2013 Joint IFSA World Congress and NAFIPS Annual Meeting (IFSA/NAFIPS), IEEE, Canada, 2013, 57–61. <https://doi.org/10.1109/IFSA-NAFIPS.2013.6608375>
55. R. R. Yager, Pythagorean membership grades in multicriteria decision making, *IEEE Trans. Fuzzy Syst.*, **22** (2013), 958–965. <https://doi.org/10.1109/TFUZZ.2013.2278989>
56. L. A. Zadeh, Fuzzy sets, *Inform. Control*, **8** (1965), 338–353. [https://doi.org/10.1016/S0019-9958\(65\)90241-X](https://doi.org/10.1016/S0019-9958(65)90241-X)
57. W. R. Zhang, *Bipolar fuzzy sets and relations: A computational framework for cognitive modeling and multiagent decision analysis*, Proceedings of the First International Joint Conference of The North American Fuzzy Information Processing Society Biannual Conference, The Industrial Fuzzy Control and Intellige, 1994, 305–309. <https://doi.org/10.1109/IJCF.1994.375115>



AIMS Press

©2023 the Author(s), licensee AIMS Press. This is an open access article distributed under the terms of the Creative Commons Attribution License (<http://creativecommons.org/licenses/by/4.0>)