



Research article

Dynamics of a three-molecule autocatalytic Schnakenberg model with cross-diffusion: Turing patterns of spatially homogeneous Hopf bifurcating periodic solutions

Weiyu Li and Hongyan Wang*

College of Science, Heilongjiang Bayi Agricultural University, Daqing 163319, China

* **Correspondence:** Email: math2023@byau.edu.cn, 21009187@qq.com.

Abstract: In this paper, a three-molecule autocatalytic Schnakenberg model with cross-diffusion is established, the instability of bifurcating periodic solutions caused by diffusion is studied, that is, diffusion can destabilize the stable periodic solutions of the ordinary differential equation (ODE) system. First, utilizing the local Hopf bifurcation theory, the central manifold theory, the normal form method and the regular perturbation theory of the infinite dimensional dynamical system, the stability of periodic solutions for the ODE system is discussed. Second, for this model, according to the implicit function existence theorem and Floquet theory, the Turing instability of spatially homogeneous Hopf bifurcating periodic solutions is studied. It is proved that the otherwise stable Hopf bifurcating periodic solutions in the ODE system produces Turing instability in the Schnakenberg model with cross-diffusion. Finally, through numerical simulations, it is verified that Turing instability of periodic solutions is determined by cross-diffusion rates.

Keywords: schnakenberg model; cross-diffusion; spatially homogeneous periodic solutions; Turing instability

1. Introduction

In nonlinear chemical reaction systems, the three-molecule autocatalytic model shows abundant dynamical behaviors, many abundant research results have been obtained [1–7]. In 1979, Schnakenberg proposed a typical three-molecule autocatalytic reaction-diffusion model [8]. In [9], the authors studied the one-dimensional static Turing bifurcation of Schnakenberg model. In [10–12], the authors introduced the relevant research background of reaction-diffusion Schnakenberg system. However, most references [13–16] focus on whether the constant equilibrium solution has Turing instability, but pay little attention to whether the periodic solutions of system may also suffer from Turing instability. Therefore, by applying the theoretical methods in [17, 18], we study the Turing instability of Hopf

bifurcating periodic solutions for the Schnakenberg model.

On the basis of the Schnakenberg model [8], We introduce self-diffusion and cross-diffusion coefficients, and establish reaction-diffusion Schnakenberg model with cross-diffusion and self-diffusion:

$$\begin{cases} u_t - d_{11}\Delta u - d_{12}\Delta v = a - u + u^2v, & x \in \Omega, t > 0, \\ v_t - d_{21}\Delta v - d_{22}\Delta u = b - u^2v, & x \in \Omega, t > 0, \\ u(x, 0) = u_*(x), v(x, 0) = v_*(x), & x \in \Omega, \\ \frac{\partial u}{\partial \nu} = \frac{\partial v}{\partial \nu} = 0, & x \in \partial\Omega, t > 0, \end{cases} \quad (1.1)$$

where Ω is a open bounded domain in n -dimensional Euclidean space, and its boundary $\partial\Omega$ is smooth. Δ is Laplace operator. The parameters $a, b, d_{11}, d_{12}, d_{21}, d_{22}$ are all positive constants. $u = u(x, t)$ and $v = v(x, t)$ indicate the concentrations of chemicals at position $x \in \Omega$ and time $t > 0$, respectively, and the initial concentrations $u_*(x), v_*(x)$ are nonnegative functions. d_{11}, d_{22} denote self-diffusion coefficients of u and v , respectively. d_{12}, d_{21} represent cross-diffusion coefficients of u and v , respectively. Simultaneously, we suppose that $d_{11}d_{22} - d_{12}d_{21} > 0$ holds.

2. Hopf bifurcation and stability of periodic solutions for the ODE system and perturbed system

2.1. Stability of periodic solutions for the ODE system

We consider the corresponding zero-dimensional dynamic system of system (1.1)

$$\begin{cases} \frac{du}{dt} = a - u + u^2v, & t > 0, \\ \frac{dv}{dt} = b - u^2v, & t > 0, \\ u(0) = u_* > 0, v(0) = v_* > 0. \end{cases} \quad (2.1)$$

The equilibrium (u_0, v_0) of system (2.1) satisfies

$$\begin{cases} a - u + u^2v = 0, \\ b - u^2v = 0. \end{cases}$$

with $u_0 = a + b, v_0 = \frac{b}{(a+b)^2}$. By straightforward computation, we know (u_0, v_0) is the only equilibrium of system (2.1). For convenience, setting $\mu := a + b$, then $(u_0, v_0) = \left(\mu, \frac{b}{\mu^2}\right)$. In the following, for the three-molecule autocatalytic Schnakenberg model, we discuss the stability of its Hopf bifurcating periodic solutions by taking μ as parameter.

Theorem 2.1. Let $\mu_0^H = \sqrt[3]{b + \sqrt{b^2 + \frac{1}{27}}} + \sqrt[3]{b - \sqrt{b^2 + \frac{1}{27}}}$, for the ODEs (2.1), the following statements are true:

- (1) At $\left(\mu, \frac{b}{\mu^2}\right)^T$, system (2.1) is unstable for $\mu \in \left(0, \mu_0^H\right)$, while locally asymptotically stable for $\mu \in \left(\mu_0^H, +\infty\right)$.

(2) At $\lambda = \mu_0^H$, system has a family of periodic solutions $(u_T(t), v_T(t))^T$ bifurcating from $(\mu, \frac{b}{\mu^2})^T$. Supercritical Hopf bifurcation of system (2.1) occurs at $(\mu, \frac{b}{\mu^2})^T$, and the bifurcating periodic solutions are stable.

Proof. The Jacobian matrix of system (2.1) at $(\mu, v_\mu)^T$ is $J(\mu) = \begin{pmatrix} -1 + \frac{2b}{\mu} & \mu^2 \\ -\frac{2b}{\mu} & -\mu^2 \end{pmatrix}$. The characteristic equation of $J(\mu)$ is

$$\lambda^2 - T(\mu)\lambda + D(\mu) = 0, \quad (2.2)$$

with

$$T(\mu) = -\mu^2 - 1 + \frac{2b}{\mu}, \quad D(\mu) = \mu^2.$$

The eigenvalue $\lambda(\mu)$ of $J(\mu)$ is given by

$$\lambda(\mu) = \frac{T(\mu) \pm \sqrt{T^2(\mu) - 4D(\mu)}}{2}.$$

When $\mu \geq 2b$, all the eigenvalues of $J(\mu)$ have strict negative real parts, according to the stability theory, the equilibrium $(\mu, \frac{b}{\mu^2})^T$ is locally asymptotically stable. When $0 < \mu < 2b$, $T'(\mu) = -2\mu - \frac{2b}{\mu^2} < 0$, then $T(\mu)$ is monotonically decreasing for $0 < \mu < 2b$. Since $\lim_{\mu \rightarrow 0} T(\mu) = +\infty$, $T(2b) = -4b - \frac{1}{2b} < 0$, then $T(\mu)$ has only zero point $\mu_0^H \in (0, 2b)$, namely, $T(\mu_0^H) = 0$. For any $\mu \in (\mu_0^H, 2b)$, we have $T(\mu) < 0$, then system (2.1) is locally asymptotically stable at $(\mu, \frac{b}{\mu^2})^T$, while for any $\mu \in (0, \mu_0^H)$, system (2.1) is unstable at $(\mu, \frac{b}{\mu^2})^T$. When $\mu = \mu_0^H$, $J(\mu)$ has a pair of pure imaginary roots $\lambda = \pm i\omega_0$ with $\omega_0 = \mu$. Let $\lambda(\mu) = \alpha(\mu) \pm i\omega(\mu)$ be the roots of Eq (2.2) near $\mu = \mu_0^H$, then we have

$$\alpha(\mu) = -\frac{\mu^2}{2} - \frac{1}{2} + \frac{b}{\mu}, \quad \left. \frac{d\alpha(\mu)}{d\mu} \right|_{\mu=\mu_0^H} < 0.$$

According to Poincaré-Andronov-Hopf bifurcation theorem, system (2.1) experiences a Hopf bifurcation at $\mu = \mu_0^H$.

Next, we study the properties of Hopf bifurcating periodic solutions of system (2.1). Here, we still use the notations and computation in [20] to deduce the expression of cubic term coefficient $c_1(\mu_0^H)$ in the norm form. By [21], we can rewrite the Poincaré normal form of the abstract form of system (2.1) in the small neighborhood of p_0 as follows:

$$\frac{dU}{dt} = J(\mu_0^H)U + F(\mu, U) \Big|_{\mu=\mu_0^H}. \quad (2.3)$$

Let the eigenvector of $J(\mu_0^H)$ corresponding to the eigenvalue $i\omega_0$ be $q = (a_0, b_0)^T$ satisfying

$$J(\mu_0^H)q = i\omega_0 q, \quad q = (a_0, b_0)^T = (-\mu_0^H, \mu_0^H - i)^T.$$

Define inner product in $X_{\mathbb{C}}$:

$$\langle U_1, U_2 \rangle = \int_0^{l\pi} (\bar{u}_1 u_2 + \bar{v}_1 v_2) dx,$$

where $U_i = (u_i, v_i)^T \in X_{\mathbb{C}}, i = 1, 2$. Note that $\langle \lambda U_1, U_2 \rangle = \bar{\lambda} \langle U_1, U_2 \rangle$, denote the adjoint operator of $J(\mu_0^H)$ by $J^*(\mu_0^H)$, then the eigenvector of $J^*(\mu_0^H)$ corresponding to the eigenvalue $-i\omega_0$ be $q^* = (a_0^*, b_0^*)^T \in X^{\mathbb{C}}$ satisfying

$$J^*(\mu_0^H) q^* = -i\omega_0 q^*, \quad \langle q^*, q \rangle = 1, \quad \langle q^*, \bar{q} \rangle = 0.$$

Therefore, $q^* = (a_0^*, b_0^*)^T = \left(\frac{-1-i\mu_0^H}{2\mu_0^H i\pi}, \frac{-i}{2i\pi} \right)^T$. Performing the spatial decomposition $X = X^c \oplus X^s$, where $X^c = \{zq + \bar{z}\bar{q} | z \in \mathbb{C}\}$, $X^s = \{u \in X | \langle q^*, u \rangle = 0\}$, then for any $U = (u, v)^T \in X$, there exist $z \in \mathbb{C}$ and $\omega = (\omega_1, \omega_2) \in X^s$ such that $(u, v)^T = zq + \bar{z}\bar{q} + (\omega_1, \omega_2)^T$. Thus, system (2.3) can be transformed into the following system with (z, ω) as the coordinate:

$$\begin{cases} \frac{dz}{dt} = i\omega z + \langle q^*, F(p, U) |_{p=p_0} \rangle, \\ \frac{d\omega}{dt} = L(p_0)\omega + H(z, \bar{z}, \omega), \end{cases} \quad (2.4)$$

with

$$\begin{cases} H(z, \bar{z}, \omega) = F(p, U) |_{p=p_0} - \langle q^*, F(p, U) |_{p=p_0} \rangle q - \langle \bar{q}^*, F(p, U) |_{p=p_0} \rangle \bar{q}, \\ F(p, U) |_{p=p_0} = F_0(zq + \bar{z}\bar{q} + \omega). \end{cases} \quad (2.5)$$

Writing F_0 as

$$F_0(U) = \frac{1}{2}Q(U, U) + \frac{1}{6}C(U, U, U) + O(|U|^4), \quad (2.6)$$

here, Q, C is a symmetric multilinear form. For convenience, denoting $Q_{XY} = Q(X, Y), C_{XYZ} = C(X, Y, Z)$, we calculate $Q_{qq}, Q_{q\bar{q}}$ and $C_{qq\bar{q}}$, where

$$Q_{qq} = \begin{pmatrix} c_0 \\ d_0 \end{pmatrix}, \quad Q_{q\bar{q}} = \begin{pmatrix} e_0 \\ f_0 \end{pmatrix}, \quad C_{qq\bar{q}} = \begin{pmatrix} g_0 \\ h_0 \end{pmatrix},$$

here, denoting $f(u, v) = a - u + u^2v$, $g(u, v) = b - u^2v$, with

$$\begin{aligned} c_0 &= f_{uu}a_0^2 + 2f_{uv}a_0b_0 + f_{vv}b_0^2 = \mu_0^H - 3\mu_0^{H^3} + 4\mu_0^{H^2}i, \\ d_0 &= g_{uu}a_0^2 + 2g_{uv}a_0b_0 + g_{vv}b_0^2 = -c_0 = -\mu_0^H + 3\mu_0^{H^3} - 4\mu_0^{H^2}i, \\ e_0 &= f_{uu}|a_0|^2 + f_{uv}(a_0\bar{b}_0 + \bar{a}_0b_0) + f_{vv}|b_0|^2 = \mu_0^H - 3\mu_0^{H^3}, \\ f_0 &= g_{uu}|a_0|^2 + g_{uv}(a_0\bar{b}_0 + \bar{a}_0b_0) + g_{vv}|b_0|^2 = -e_0 = 3\mu_0^{H^3} - \mu_0^H, \\ g_0 &= f_{uuu}|a_0|^2a_0 + f_{uuv}(2|a_0|^2b_0 + a_0^2\bar{b}_0) + f_{uvv}(2|b_0|^2a_0 + b_0^2\bar{a}_0) = 6\mu_0^{H^3} - 2\mu_0^{H^2}i, \\ h_0 &= g_{uuu}|a_0|^2a_0 + g_{uuv}(2|a_0|^2b_0 + a_0^2\bar{b}_0) + g_{uvv}(2|b_0|^2a_0 + b_0^2\bar{a}_0) = -g_0 = -6\mu_0^{H^3} + 2\mu_0^{H^2}i, \end{aligned}$$

here, all the partial derivatives of $f(u, v)$ and $g(u, v)$ are evaluated at the bifurcation point $\left(\mu_0^H, \frac{b}{\mu_0^{H^2}} \right)^T$,

Let

$$H(z, \bar{z}, \omega) = \frac{H_{20}}{2}z^2 + H_{11}z\bar{z} + \frac{H_{02}}{2}\bar{z}^2 + o(|z|^3) + o(|z||\omega|), \quad (2.7)$$

from (2.5) and (2.6), we can obtain

$$\begin{cases} H_{20} = Q_{qq} - \langle q^*, Q_{qq} \rangle q - \langle \bar{q}^*, Q_{qq} \rangle \bar{q} \\ H_{11} = Q_{q\bar{q}} - \langle q^*, Q_{q\bar{q}} \rangle q - \langle \bar{q}^*, Q_{q\bar{q}} \rangle \bar{q} \end{cases}$$

Because system (2.4) has normal manifold, which can be written as follows

$$\omega = \frac{\omega_{20}}{2} z^2 + \omega_{11} z \bar{z} + \frac{\omega_{02}}{2} \bar{z}^2 + o(|z|^3). \quad (2.8)$$

By (2.7), (2.8) and $J(\mu_0^H)\omega + H(z, \bar{z}, \omega) = \frac{d\omega}{dt} = \frac{\partial\omega}{\partial z} \frac{dz}{dt} + \frac{\partial\omega}{\partial \bar{z}} \frac{d\bar{z}}{dt}$, we have

$$\omega_{20} = (2i\omega_0 I - J(\mu_0^H))^{-1} H_{20}, \quad \omega_{11} = -J^{-1}(\mu_0^H) H_{11}.$$

By calculation, we have

$$\begin{aligned} \langle q^*, Q_{qq} \rangle &= -\frac{c_0}{2\mu_0^H} = \frac{-\mu_0^H + 3\mu_0^{H^3} - 4\mu_0^{H^2}i}{2\mu_0^H}, & \langle q^*, Q_{q\bar{q}} \rangle &= -\frac{e_0}{2\mu_0^H} = \frac{-\mu_0^H + 3\mu_0^{H^3}}{2\mu_0^H}, \\ \langle \bar{q}^*, C_{qq\bar{q}} \rangle &= -\frac{g_0}{2\mu_0^H} = \frac{-6\mu_0^{H^3} + 2\mu_0^{H^2}i}{2\mu_0^H}, & \langle \bar{q}^*, Q_{qq} \rangle &= -\frac{c_0}{2\mu_0^H} = \frac{-\mu_0^H + 3\mu_0^{H^3} - 4\mu_0^{H^2}i}{2\mu_0^H}, \\ \langle \bar{q}^*, Q_{q\bar{q}} \rangle &= -\frac{e_0}{2\mu_0^H} = \frac{-\mu_0^H + 3\mu_0^{H^3}}{2\mu_0^H}, \end{aligned}$$

we can also get $H_{20} = 0, H_{11} = 0$, this implies $\omega_{20} = \omega_{11} = 0$, then

$$\langle q^*, Q_{\omega_{11}q} \rangle = \langle q^*, Q_{\omega_{20}\bar{q}} \rangle = 0.$$

Thus, we have

$$c_1(\mu) = \frac{i}{2\omega_0} \langle q^*, Q_{qq} \rangle \cdot \langle q^*, Q_{q\bar{q}} \rangle + \frac{1}{2} \langle \bar{q}^*, C_{qq\bar{q}} \rangle.$$

The real part and imaginary part of $c_1(\mu_0^H)$ are as follows

$$\begin{aligned} \operatorname{Re} c_1(\mu_0^H) &= \operatorname{Re} \left\{ \frac{i}{2\omega_0} \langle q^*, Q_{qq} \rangle \cdot \langle q^*, Q_{q\bar{q}} \rangle + \frac{1}{2} \langle \bar{q}^*, C_{qq\bar{q}} \rangle \right\} = -\frac{1}{2}, \\ \operatorname{Im} c_1(\mu_0^H) &= \operatorname{Im} \left\{ \frac{i}{2\omega_0} \langle q^*, Q_{qq} \rangle \cdot \langle q^*, Q_{q\bar{q}} \rangle + \frac{1}{2} \langle \bar{q}^*, C_{qq\bar{q}} \rangle \right\} = \frac{1}{8\mu_0^H} - \frac{\mu_0^H}{4} + \frac{9\mu_0^{H^3}}{8}. \end{aligned} \quad (2.9)$$

By $\operatorname{Re} c_1(\mu_0^H) < 0$, we know that the Hopf bifurcating periodic solutions of system (2.1) are stable at $\mu = \mu_0^H$. Additionally, because transversality condition $\left. \frac{d\alpha(\mu)}{d\mu} \right|_{\mu=\mu_0^H} < 0$, so the direction of Hopf bifurcation is subcritical. \square

2.2. Hopf bifurcation and stability of periodic solutions for the perturbed system

We introduce the following perturbed system model on the basis of ODEs (2.1)

$$\begin{pmatrix} 1 + \varepsilon d_{11} & \varepsilon d_{12} \\ \varepsilon d_{21} & 1 + \varepsilon d_{22} \end{pmatrix} \begin{pmatrix} \frac{du}{dt} \\ \frac{dv}{dt} \end{pmatrix}^T = \begin{pmatrix} a - u + u^2 v \\ b - u^2 v \end{pmatrix}, \quad (2.10)$$

here, ε is sufficiently small such that $\begin{pmatrix} 1 + \varepsilon d_{11} & \varepsilon d_{12} \\ \varepsilon d_{21} & 1 + \varepsilon d_{22} \end{pmatrix}$ is reversible. System (2.10) is equivalent to the following system

$$\begin{pmatrix} \frac{du}{dt} \\ \frac{dv}{dt} \end{pmatrix}^T = \frac{1}{N(\varepsilon)} \begin{pmatrix} 1 + d_{22}\varepsilon & -d_{12}\varepsilon \\ -d_{21}\varepsilon & 1 + d_{11}\varepsilon \end{pmatrix} \begin{pmatrix} a - u + u^2 v \\ b - u^2 v \end{pmatrix}, \quad (2.11)$$

where

$$N(\varepsilon) := \left| \begin{pmatrix} 1 + d_{22}\varepsilon & -d_{12}\varepsilon \\ -d_{21}\varepsilon & 1 + d_{11}\varepsilon \end{pmatrix} \right| = (d_{11}d_{22} - d_{12}d_{21})\varepsilon^2 + (d_{11} + d_{22})\varepsilon + 1 > 0.$$

Then at (μ, v_μ) , the Jacobian matrix of system (2.11) is

$$J(\mu, \varepsilon) := \frac{1}{N(\varepsilon)} \begin{pmatrix} a_{11}(\mu, \varepsilon) & a_{12}(\mu, \varepsilon) \\ a_{21}(\mu, \varepsilon) & a_{22}(\mu, \varepsilon) \end{pmatrix}, \quad (2.12)$$

with

$$\begin{aligned} a_{11}(\mu, \varepsilon) &:= (1 + d_{22}\varepsilon) \left(-1 + \frac{2b}{\mu} \right) + d_{12}\varepsilon \frac{2b}{\mu}, & a_{12}(\mu, \varepsilon) &:= (1 + d_{22}\varepsilon)\mu^2 + d_{12}\varepsilon\mu^2, \\ a_{21}(\mu, \varepsilon) &:= -(1 + d_{11}\varepsilon) \frac{2b}{\mu} - d_{21}\varepsilon \left(-1 + \frac{2b}{\mu} \right), & a_{22}(\mu, \varepsilon) &:= -\mu^2(1 + d_{11}\varepsilon) - d_{21}\varepsilon\mu^2. \end{aligned} \quad (2.13)$$

The characteristic equation corresponding to the jacobian matrix $J(\mu, \varepsilon)$ is

$$\lambda^2 - H(\mu, \varepsilon)\lambda + D(\mu, \varepsilon) = 0, \quad (2.14)$$

where

$$\begin{aligned} H(\mu, \varepsilon) &= \frac{1}{N(\varepsilon)} \left[\left(\frac{2b}{\mu} - 1 - \mu^2 \right) + \varepsilon \left(d_{22} \left(\frac{2b}{\mu} - 1 \right) - \mu^2 d_{11} + d_{12} \cdot \frac{2b}{\mu} - d_{21} \cdot \mu^2 \right) \right], \\ D(\mu, \varepsilon) &= \frac{\mu^2}{N(\varepsilon)}. \end{aligned} \quad (2.15)$$

Notice that $H(\mu_0^H, 0) = T(\mu_0^H) = 0$ and $\partial_\mu H(\mu, \varepsilon) = T'(\mu_0^H) \neq 0$. According to the implicit function existence theorem, there exist a sufficiently small $\varepsilon_0 > 0$ and a continuously differentiable function $\mu_\varepsilon^H = \mu^H(\varepsilon)$ such that when $\varepsilon \in (-\varepsilon_0, \varepsilon_0)$, $H(\mu_\varepsilon^H, \varepsilon) = 0$ and $\mu^H(0) = \mu_0^H$ hold. Let $\lambda(\mu_\varepsilon) = \beta(\mu_\varepsilon) \pm i\omega(\mu_\varepsilon)$ be the characteristic root of Eq 2.14, then when $\mu \rightarrow \mu_\varepsilon$, we have

$$\beta(\mu_\varepsilon) = \frac{1}{2}H(\mu, \varepsilon), \quad \omega(\mu_\varepsilon) = \frac{1}{2}\sqrt{4D(\mu, \varepsilon) - H^2(\mu, \varepsilon)}. \quad (2.16)$$

By [18], we have the following lemma.

Lemma 2.1. Assume μ is sufficiently close to μ_ε^H , T is the minimum positive period of the stable periodic solution $(u_T(t), v_T(t))$ of system (2.1) bifurcating from (μ, v_μ) , then there exists $\varepsilon_1 > 0$ such that for any $\varepsilon \in (-\varepsilon_1, \varepsilon_1)$, system (2.10) has a periodic solution $(u_T(t, \varepsilon), v_T(t, \varepsilon))$ depending on ε . Its minimum positive period is $T(\varepsilon)$, simultaneously, it satisfies

1) When $\varepsilon \rightarrow 0$, $(u_T(t, \varepsilon), v_T(t, \varepsilon)) \rightarrow (u_T(t), v_T(t))$ and $T(\varepsilon) \rightarrow T$.

2) $T(\varepsilon) = \frac{2\pi}{\omega(\mu_\varepsilon^H)} \left(1 + \left(\frac{\beta'(\mu_\varepsilon^H) \operatorname{Im}(c_1(\mu_\varepsilon^H))}{\omega(\mu_\varepsilon^H) \operatorname{Re}(c_1(\mu_\varepsilon^H))} - \frac{\omega'(\mu_\varepsilon^H)}{\omega(\mu_\varepsilon^H)} \right) (\mu - \mu_\varepsilon^H) + O\left((\mu - \mu_\varepsilon^H)^2\right) \right)$ with

$$c_1(\mu_\varepsilon^H) = \frac{i}{2\omega(\mu_\varepsilon^H)} \left(g_{20}(\varepsilon)g_{11}(\varepsilon) - 2|g_{11}(\varepsilon)|^2 - \frac{1}{3}|g_{02}(\varepsilon)|^2 \right) + \frac{g_{21}(\varepsilon)}{2}.$$

Theorem 2.2. Suppose that μ is sufficiently close to μ_ε^H , $(u_T(t), v_T(t))$ is the stable periodic solution of system (2.1), then when $\varepsilon \rightarrow 0$, we have

$$T'(0) = \frac{\pi}{\mu_0^H} \left(L_1(\mu_0^H)d_{11} - L_2(\mu_0^H)d_{22} - L_3(\mu_0^H)d_{12} - L_4(\mu_0^H)d_{21} \right),$$

with

$$\begin{aligned} L_1(\mu_0^H) &= \frac{5}{4} - \frac{\mu_0^{H2}}{2} + \frac{9\mu_0^{H4}}{4}, & L_2(\mu_0^H) &= \left(\frac{1}{4\mu_0^{H2}} + \frac{9\mu_0^{H2}}{4} - 1 \right) \left(\frac{2b}{\mu_0^H} - 1 \right) - 1, \\ L_3(\mu_0^H) &= \left(\frac{1}{4\mu_0^H} + \frac{9\mu_0^{H3}}{4} - \mu_0^H \right) \frac{2b}{\mu_0^{H2}}, & L_4(\mu_0^H) &= \left(\mu_0^H - \frac{1}{4\mu_0^H} - \frac{9\mu_0^{H3}}{4} \right) \mu_0^H. \end{aligned}$$

Proof. According to Lemma 2.1, we have

$$T'(\varepsilon) = -\frac{2\pi}{\omega^2(\mu_\varepsilon^H)} \frac{d\omega(\mu_\varepsilon^H)}{d\varepsilon} - \frac{2\pi}{\omega(\mu_\varepsilon^H)} \left(\frac{\beta'(\mu_\varepsilon^H) \operatorname{Im}(c_1(\mu_\varepsilon^H))}{\omega(\mu_\varepsilon^H) \operatorname{Re}(c_1(\mu_\varepsilon^H))} - \frac{\omega'(\mu_\varepsilon^H)}{\omega(\mu_\varepsilon^H)} \right) \frac{d\mu_\varepsilon^H}{d\varepsilon} + O(\mu - \mu_\varepsilon^H).$$

If $\mu \rightarrow \mu_\varepsilon^H$, then $O(\mu - \mu_\varepsilon^H) \rightarrow 0$, so the sign of $T'(\varepsilon)$ is mainly determined by the sign of the first two at $\varepsilon = 0$. Next, we calculate the expressions of $\left. \frac{d\mu_\varepsilon^H}{d\varepsilon} \right|_{\varepsilon=0}$ and $\left. \frac{d\omega(\mu_\varepsilon^H)}{d\varepsilon} \right|_{\varepsilon=0}$.

At $\mu = \mu_\varepsilon^H$, by (2.15), we can derive

$$\left(\frac{2b}{\mu_\varepsilon^H} - 1 - \mu_\varepsilon^{H2} \right) + \varepsilon \left(d_{22} \left(-1 + \frac{2b}{\mu_\varepsilon^H} \right) - \mu_\varepsilon^{H2} d_{11} + d_{12} \frac{2b}{\mu_\varepsilon^H} - d_{21} \mu_\varepsilon^{H2} \right) = 0. \quad (2.17)$$

Differentiating (2.17) with ε , we have

$$\left. \frac{d\mu_\varepsilon^H}{d\varepsilon} \right|_{\varepsilon=0} = \frac{b(\mu_0^H)}{\frac{2b}{\mu_0^{H2}} + 2\mu_0^H}, \quad (2.18)$$

with

$$b(\mu_0^H) = d_{22} \left(-1 + \frac{2b}{\mu_0^H} \right) - \mu_0^{H2} d_{11} + d_{12} \frac{2b}{\mu_0^H} - d_{21} \mu_0^{H2}. \quad (2.19)$$

According to (2.16),

$$\omega(\mu) = \frac{1}{2} \sqrt{4D(\mu, \varepsilon) - H^2(\mu, \varepsilon)}.$$

Differentiating it with μ , we know

$$\omega'(\mu) = \frac{\partial_{\mu} D(\mu, \varepsilon) - \frac{1}{2} H(\mu, \varepsilon) \partial_{\mu} H(\mu, \varepsilon)}{\sqrt{4D(\mu, \varepsilon) - H^2(\mu, \varepsilon)}}.$$

When $\mu \rightarrow \mu_{\varepsilon}^H$, $H(\mu_{\varepsilon}^H, \varepsilon) = 0$ and $\partial_{\lambda} D(\mu_{\varepsilon}^H, \varepsilon) = \frac{1}{N(\varepsilon)} D'(\mu_{\varepsilon}^H)$. Hence,

$$\omega'(\mu_0^H) = \frac{\partial_{\lambda} D(\mu_{\varepsilon}^H, \varepsilon)}{2\sqrt{D(\mu_{\varepsilon}^H, \varepsilon)}} \Big|_{\varepsilon=0} = \frac{D'(\mu_{\varepsilon}^H)}{2\sqrt{N(\varepsilon)D(\mu_{\varepsilon}^H)}} \Big|_{\varepsilon=0} = \frac{D'(\mu)}{2\sqrt{D(\mu)}}. \quad (2.20)$$

From $\omega(\mu_{\varepsilon}^H) = \sqrt{D(\mu_{\varepsilon}^H, \varepsilon)}$ and $D(\mu_{\varepsilon}^H, \varepsilon) = \frac{D(\mu_{\varepsilon}^H)}{N(\varepsilon)}$, differentiating them with ε , we can obtain

$$\frac{d\omega(\mu_{\varepsilon}^H)}{d\varepsilon} = \frac{1}{2\sqrt{D(\mu_{\varepsilon}^H, \varepsilon)}} \frac{d}{d\varepsilon} (D(\mu_{\varepsilon}^H, \varepsilon)). \quad (2.21)$$

$$\frac{d}{d\varepsilon} (D(\mu_{\varepsilon}^H, \varepsilon)) = -\frac{N'(\varepsilon)}{N^2(\varepsilon)} D(\mu_{\varepsilon}^H) + \frac{d}{d\varepsilon} (D(\mu_{\varepsilon}^H)) \frac{1}{N(\varepsilon)}. \quad (2.22)$$

When $\varepsilon = 0$, we get

$$\begin{aligned} -\frac{N'(0)}{N^2(0)} D(\mu_0^H) &= -(d_{11} + d_{22}) D(\mu_0^H), \\ \frac{d}{d\varepsilon} (D(\mu_{\varepsilon}^H)) \frac{1}{N(\varepsilon)} \Big|_{\varepsilon=0} &= D'(\mu_0) \frac{d\mu_{\varepsilon}^H}{d\varepsilon} (0). \end{aligned} \quad (2.23)$$

Thus, according to (2.22) and (2.23), we have

$$\frac{d}{d\varepsilon} (D(\mu_{\varepsilon}^H, \varepsilon)) \Big|_{\varepsilon=0} = -(d_{11} + d_{22}) D(\mu_0^H) + \frac{b(\mu_0^H)}{\frac{2b}{\mu_0^{H^2}} + 2\mu_0^H} D'(\mu_0^H), \quad (2.24)$$

where $b(\mu_0^H)$ is defined in (2.19). From (2.21) and (2.24), we can obtain

$$\frac{d}{d\varepsilon} (\omega(\mu_{\varepsilon}^H)) \Big|_{\varepsilon=0} = -\frac{1}{2} \sqrt{D(\mu_0^H)} \left(d_{11} + d_{22} - \frac{b(\mu_0^H)}{\mu_0^{H^2} + 2\mu_0^H} \frac{D'(\mu_0^H)}{D(\mu_0^H)} \right). \quad (2.25)$$

By (2.18), (2.20) and (2.25), we can deduce

$$T'(0) = \frac{\pi}{D(\mu_0^H)} \left(\sqrt{D(\mu_0^H)} d_{11} + \sqrt{D(\mu_0^H)} d_{22} + \frac{b(\mu_0^H) \operatorname{Im}(c_1(\mu_0^H))}{\operatorname{Re}(c_1(\mu_0^H))} \right). \quad (2.26)$$

At last, substituting (2.19) into (2.26), we can obtain

$$T'(0) = \frac{\pi}{\mu_0^H} (L_1(\mu_0^H) d_{11} - L_2(\mu_0^H) d_{22} - L_3(\mu_0^H) d_{12} - L_4(\mu_0^H) d_{21}),$$

with

$$\begin{aligned} L_1(\mu_0^H) &= \frac{5}{4} - \frac{\mu_0^{H2}}{2} + \frac{9\mu_0^{H4}}{4}, & L_2(\mu_0^H) &= \left(\frac{1}{4\mu_0^{H2}} + \frac{9\mu_0^{H2}}{4} - 1 \right) \left(\frac{2b}{\mu_0^H} - 1 \right) - 1, \\ L_3(\mu_0^H) &= \left(\frac{1}{4\mu_0^H} + \frac{9\mu_0^{H3}}{4} - \mu_0^H \right) \frac{2b}{\mu_0^{H2}}, & L_4(\mu_0^H) &= \left(\mu_0^H - \frac{1}{4\mu_0^H} - \frac{9\mu_0^{H3}}{4} \right) \mu_0^H. \end{aligned}$$

□

3. Turing instability of spatially homogeneous Hopf bifurcating periodic solutions

In this section, applying the theory elaborated in [17], we study stable spatially homogeneous Hopf bifurcating periodic solutions of system (2.1) will become Turing unstable in reaction-diffusion system (1.1) with cross-diffusion. According to the previous discussion, we give the following theorem.

Theorem 3.1. *Suppose that μ is sufficiently close to μ_0 , $(u_T(t), v_T(t))$ is stable spatially homogeneous Hopf bifurcating periodic solution of system (2.1) bifurcating from (μ, v_μ) . If $T'(0) < 0$ and Ω is large enough, then $(u_T(t), v_T(t))$ will become Turing unstable in system (1.1) with cross-diffusion.*

Proof. Assume that the stable periodic solution of system (2.1) is $(u_T(t), v_T(t))$ with minimum positive period T , then the linearized system of (1.1) evaluated at $(u_T(t), v_T(t))$ is

$$\left(\frac{\partial \phi}{\partial t}, \frac{\partial \varphi}{\partial t}\right)^T = \text{diag}(D\Delta\phi, D\Delta\varphi) + J_T(t)(\phi, \varphi)^T, \quad (3.1)$$

where $D := \begin{pmatrix} d_{11} & d_{12} \\ d_{21} & d_{22} \end{pmatrix}$, Δ is Laplace operator, the Jacobian matrix of system (2.1) at $(u_T(t), v_T(t))$ is

$J_T(t) := \begin{pmatrix} -1 + 2u_T(t)v_T(t) & u_T^2(t) \\ -2u_T(t)v_T(t) & -u_T^2(t) \end{pmatrix}$. Setting β_n and $\eta_n(x)$ be the eigenvalue and eigenfunction of $-\Delta$

in Ω with Neumann boundary condition. Let $(\phi, \varphi)^T = (h(t), g(t))^T \sum_{n=0}^{\infty} k_n \eta_n(x)$, then

$$\left(\frac{dh}{dt}, \frac{dg}{dt}\right)^T = -\tau D \begin{pmatrix} h(t) \\ g(t) \end{pmatrix} + J_T(t) \begin{pmatrix} h(t) \\ g(t) \end{pmatrix}, \quad (3.2)$$

in which, $\tau := \beta_n \geq 0, n \in \mathbb{N}_0 := \{0, 1, 2, \dots\}$. Assume $d_{11} = d_{12} = d_{21} = d_{22} = 0$, then system (3.2) can be rewritten as

$$\left(\frac{dh}{dt}, \frac{dg}{dt}\right)^T = J_T(t)(h(t), g(t))^T. \quad (3.3)$$

Let $\Phi(t)$ be the fundamental solution matrix of system (3.3) satisfying $\Phi(0) = I_2$. Denote $\lambda_i, i = 1, 2$ as the eigenvalue of $\Phi(T)$, the corresponding characteristic function is $(N_i, M_i)^T$, i.e.,

$$\Phi(T)(N_i, M_i)^T = \lambda_i(N_i, M_i)^T,$$

then λ_i is the Floquet multiplier corresponding to the periodic solution $(u_T(t), v_T(t))$ of system (3.2). Define

$$(\phi_i(t), \psi_i(t))^T := \Phi(t)(N_i, M_i)^T,$$

apparently,

$$(\phi_i(0), \psi_i(0))^T = (N_i, M_i)^T, \Phi(T)(\phi_i(0), \psi_i(0))^T = \lambda_i(\phi_i(0), \psi_i(0))^T.$$

In system (2.1), differentiating with t , we have

$$\left(\frac{du'}{dt}, \frac{dv'}{dt}\right)^T = \begin{pmatrix} -1 + 2uv & u^2 \\ -2uv & -u^2 \end{pmatrix} \begin{pmatrix} u' \\ v' \end{pmatrix}.$$

Then 1 is the eigenvalue of $\Phi(T)$, the corresponding eigenvector is $(u'_T(0), v'_T(0))^T$. We might as well assume $\lambda_1 = 1$, $(\phi_1(t), \psi_1(t))^T = (u'_T(t), v'_T(t))^T$. Since $(u_T(t), v_T(t))$ is stable, then $|\lambda_2| < 1$. Let $\Phi(t, \tau)$ be the fundamental solution matrix of system (3.2), and $\Phi(0, \tau) = I$, namely,

$$\frac{\partial \Phi(t, \tau)}{\partial t} = -\tau D\Phi(t, \tau) + J_T(t)\Phi(t, \tau).$$

For sufficiently small τ , $\Phi(t, \tau)$ is continuously differentiable with respect to t and τ , and $\Phi(t, 0) = \Phi(t)$. Define mapping $\mathcal{L} : [0, +\infty) \times C \times C^2 \rightarrow C^2$, where $C := \mathbb{R} \oplus i\mathbb{R}$, we have

$$\mathcal{L}\left(\tau, \delta_i, \begin{pmatrix} n_i \\ m_i \end{pmatrix}\right) := \Phi(T, \tau) \begin{pmatrix} n_i \\ m_i \end{pmatrix} - \delta_i \begin{pmatrix} n_i \\ m_i \end{pmatrix},$$

clearly, $\mathcal{L}(0, \lambda_i, (N_i, M_i)^T) = (0, 0)^T$ and

$$\mathcal{L}_{\delta_i}(0, \lambda_i, (N_i, M_i)^T) = -(N_i, M_i)^T, \quad \mathcal{L}_{(n_i, m_i)^T}(0, \lambda_i, (N_i, M_i)^T) = \Phi(T) - \lambda_i I,$$

here, \mathcal{L}_{δ_i} is the Fréchet derivative of \mathcal{L} with respect to δ_i , and $\mathcal{L}_{(n_i, m_i)^T}$ is the Fréchet derivative of \mathcal{L} with respect to $(n_i, m_i)^T$. Setting λ_i is the single eigenvalue of $\Phi(T)$, then we have

$$\begin{aligned} \text{Ker}(\lambda_i I - \Phi(T)) &= \text{span}\{(N_i, M_i)^T\}, \\ (N_i, M_i)^T &\notin \text{Rank}(\lambda_i I - \Phi(T)). \end{aligned}$$

where Ker represents the kernel of $\lambda_i I - \Phi(T)$, and Rank represents the range of $\lambda_i I - \Phi(T)$, then $\mathcal{L}_{(\delta_i, (n_i, m_i)^T)}(0, \lambda_i, (N_i, M_i)^T)$, $i = 1, 2$ is an isomorphic mapping. By the implicit function theorem, there exist $\tau_1 > 0$, $\tau \in (-\tau_1, \tau_1)$ and continuously differentiable functions $\delta_i(\tau)$, $n_i(\tau)$, $m_i(\tau)$ such that

$$\Phi(T, \tau)(n_i(\tau), m_i(\tau))^T = \delta_i(\tau)(n_i(\tau), m_i(\tau))^T, \quad (3.4)$$

where $\delta_i(\tau)$, $i = 1, 2$ are the Floquet multipliers corresponding to $(u_T(t), v_T(t))$. Define

$$(\phi_i(t, \tau), \psi_i(t, \tau))^T := \Phi(t, \tau)(n_i(\tau), m_i(\tau))^T, \quad (3.5)$$

by $\Phi(0, \tau) = I$ and (3.5), we can obtain

$$(\phi_i(0, \tau), \psi_i(0, \tau))^T = (n_i(\tau), m_i(\tau))^T. \quad (3.6)$$

From (3.4) and (3.6), we have

$$\Phi(T, \tau)(\phi_i(0, \tau), \psi_i(0, \tau))^T = \delta_i(\tau)(\phi_i(0, \tau), \psi_i(0, \tau))^T.$$

Specifically, by (3.5), we have

$$\begin{aligned} (\phi_i(t, 0), \psi_i(t, 0))^T &= \Phi(t, 0)(n_i(0), m_i(0))^T = \Phi(t)(N_i, M_i)^T, \\ &= \Phi(t)(\phi_i(0), \psi_i(0))^T = (\phi_i(t), \psi_i(t))^T. \end{aligned} \quad (3.7)$$

By the definition of $(\phi_1(t, \tau), \psi_1(t, \tau))^T$ in (3.5), we can obtain

$$\left(\frac{\partial \phi_1(t, \tau)}{\partial t}, \frac{\partial \psi_1(t, \tau)}{\partial t}\right)^T = -\tau D(\phi_1(t, \tau), \psi_1(t, \tau))^T + J_T(t)(\phi_1(t, \tau), \psi_1(t, \tau))^T. \quad (3.8)$$

Differentiating (3.8) with respect to τ and setting $\tau = 0$, we have

$$\left(\frac{\partial \phi_{1\tau}(t, 0)}{\partial t}, \frac{\partial \psi_{1\tau}(t, 0)}{\partial t} \right)^T = -D(\phi_1(t), \psi_1(t))^T + J_T(t)(\phi_{1\tau}(t, 0), \psi_{1\tau}(t, 0))^T, \quad (3.9)$$

here, $\phi_{1\tau} := \partial_\tau \phi_1, \psi_{1\tau} := \partial_\tau \psi_1$. On the other hand, from (3.4) and (3.5), we can derive

$$(\phi_1(T, \tau), \psi_1(T, \tau))^T = \delta_1(\tau)(\phi_1(0, \tau), \psi_1(0, \tau))^T. \quad (3.10)$$

Differentiating (3.10) with τ , we get

$$(\phi_{1\tau}(T, \tau), \psi_{1\tau}(T, \tau))^T = \delta'_1(\tau)(\phi_1(0, \tau), \psi_1(0, \tau))^T + \delta_1(\tau)(\phi_{1\tau}(0, \tau), \psi_{1\tau}(0, \tau))^T. \quad (3.11)$$

In (3.11), setting $\tau = 0$, from (3.6) and $\delta_1(0) = \lambda_1 = 1$, we have

$$(\phi_{1\tau}(T, 0), \psi_{1\tau}(T, 0))^T = \delta'_1(0)(\phi_1(0), \psi_1(0))^T + (\phi_{1\tau}(0, 0), \psi_{1\tau}(0, 0))^T. \quad (3.12)$$

According to Lemma 2.1, $(u_T(t, \varepsilon), v_T(t, \varepsilon))$ is the periodic solution of system (2.10), that is,

$$(I + \varepsilon D) \left(\frac{\partial u_T(t, \varepsilon)}{\partial t}, \frac{\partial v_T(t, \varepsilon)}{\partial t} \right)^T = \begin{pmatrix} a - u_T(t, \varepsilon) + u_T^2(t, \varepsilon)v_T(t, \varepsilon) \\ b - u_T^2(t, \varepsilon)v_T(t, \varepsilon) \end{pmatrix}. \quad (3.13)$$

Differentiating (3.13) with respect to ε and setting $\varepsilon = 0$, we have

$$\left(\frac{d(\partial_t u_T(t, 0))}{d\varepsilon}, \frac{d(\partial_t v_T(t, 0))}{d\varepsilon} \right)^T = -D(\phi_1(t), \psi_1(t))^T + J_T(t) \left(\frac{du_T(t, 0)}{d\varepsilon}, \frac{dv_T(t, 0)}{d\varepsilon} \right)^T, \quad (3.14)$$

where $\partial_t u_T(t, 0) = \phi_1(t), \partial_t v_T(t, 0) = \psi_1(t)$. Since $(u_T(t, \varepsilon), v_T(t, \varepsilon))$ is the periodic solution with period $T(\varepsilon)$, thus,

$$(u_T(t, \varepsilon), v_T(t, \varepsilon))^T = (u_T(t + T(\varepsilon), \varepsilon), v_T(t + T(\varepsilon), \varepsilon))^T. \quad (3.15)$$

In (3.15), differentiating with respect to ε and setting $\varepsilon = 0, t = 0$, then

$$\left(\frac{du_T(T, 0)}{d\varepsilon}, \frac{dv_T(T, 0)}{d\varepsilon} \right)^T = -T'(0)(\phi_1(0), \psi_1(0))^T + \left(\frac{du_T(0, 0)}{d\varepsilon}, \frac{dv_T(0, 0)}{d\varepsilon} \right)^T, \quad (3.16)$$

here, $u_T(t, 0) = u_T(t), v_T(t, 0) = v_T(t), T(0) = T$. Define

$$\Gamma(t) := (\phi_{1\tau}(t, 0), \psi_{1\tau}(t, 0))^T - \left(\frac{du_T(t, 0)}{d\varepsilon}, \frac{dv_T(t, 0)}{d\varepsilon} \right)^T.$$

From (3.9), (3.12), (3.14) and (3.16), we have

$$\frac{d}{dt} \Gamma(t) = J_T(t) \Gamma(t), \quad (3.17)$$

$$\Gamma(T) - \Gamma(0) = (\delta'_1(0) + T'(0))(\phi_1(0), \psi_1(0))^T. \quad (3.18)$$

Let $\Gamma(t) = \Phi(t)(Y_1, Y_2)^T$ be the general solution of (3.17), where any vector $(Y_1, Y_2)^T \in \mathbb{R}^2$. Since $(\phi_1(0), \psi_1(0))^T$ and $(\phi_2(0), \psi_2(0))^T$ are linearly independent, then there exist constants γ_1 and γ_2 so that

$$(Y_1, Y_2)^T = \gamma_1(\phi_1(0), \psi_1(0))^T + \gamma_2(\phi_2(0), \psi_2(0))^T. \quad (3.19)$$

Substituting (3.19) into (3.18), we can obtain $\delta'_1(0) + T'(0) = 0$. Assume that $T'(0) < 0$, which is equivalent to $\delta'_1(0) > 0$, if Ω is large enough so that the minimum positive eigenvalue of $-\Delta$ is small enough, then there exists at least one eigenvalue β_n of $-\Delta$ such that $\delta_1(\tau) = \delta_1(\beta_n) > 1$. Thus, $(u_T(t), v_T(t))$ becomes Turing unstable in reaction-diffusion system (1.1) with cross-diffusion. \square

4. Numerical simulations

In this section, we shall select several groups of data for numerical simulations to support theoretical analysis. In system (1.1), Fix parameters $a = 0.1823$, $b = 0.5$, initial values $u_0 = 0.6 + 0.01 \cos x$, $v_0 = 1 + 0.01 \sin x$, then the equilibrium is $(0.6823, 1.074)$, $\mu_0^H = 0.6823278$, $\operatorname{Re} c_1(\mu_0^H) = -0.5 < 0$, $\operatorname{Im} c_1(\mu_0^H) = -0.0270945 < 0$. According to Theorem 2.1, system (2.1) produces a spatially homogeneous Hopf bifurcating periodic solution $(u_T(t), v_T(t))^T$ at the equilibrium, which is stable and subcritical. By calculation, we can obtain

$$L_1(\mu_0^H) = 1.50492, \quad L_2(\mu_0^H) = -0.72787, \quad L_3(\mu_0^H) = 0.85664, \quad L_4(\mu_0^H) = -0.27213.$$

For different diffusion coefficients, Turing instability of system (1.1) at the periodic solution $(u_T(t), v_T(t))^T$ is different. Hence, we give diffusion coefficients in four cases and carry out corresponding numerical simulations.

(1) If we select $d_{11} = 1$, $d_{22} = 1$, $d_{12} = d_{21} = 0$, at this moment, Turing instability of $(u_T(t), v_T(t))^T$ does not exist in system (1.1) (Figure 1). That is, the same diffusion rates will not cause Turing instability of periodic solution ([19]).

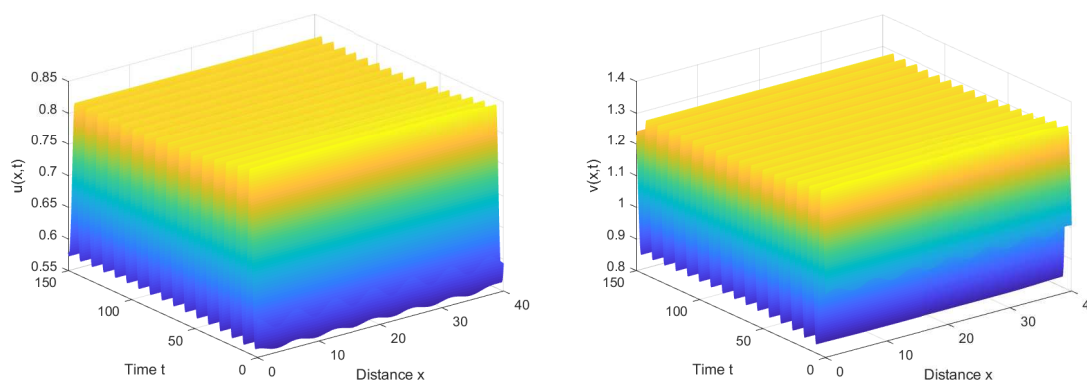


Figure 1. Turing instability of periodic solution fails.

(2) If we select $d_{11} = 0.05$, $d_{22} = 2$, $d_{12} = d_{21} = 0$, then

$$L_1(\mu_0^H)d_{11} + L_2(\mu_0^H)d_{22} - L_3(\mu_0^H)d_{12} - L_4(\mu_0^H)d_{21} < 0.$$

According to Theorem 3.1, system (1.1) is Turing unstable at periodic solution $(u_T(t), v_T(t))^T$. Through simulation simulation, it can be observed that the stable periodic solution produces Turing bifurcation (Figure 2), which is consistent with the theoretical analysis.

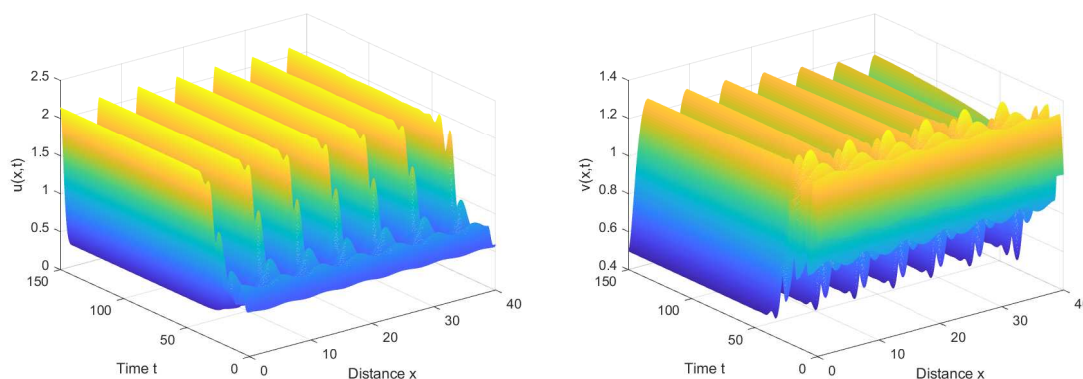


Figure 2. self-diffusion induces Turing instability of periodic solution.

(3) If we choose $d_{11} = d_{22} = 1, d_{21} = 0.2, d_{12} = 1.05$, from Theorem 3.1, we have

$$L_1(\mu_0^H)d_{11} + L_2(\mu_0^H)d_{22} - L_3(\mu_0^H)d_{12} - L_4(\mu_0^H)d_{21} < 0,$$

then system (1.1) is Turing unstable at periodic solution $(u_T(t), v_T(t))^T$. Through simulation simulation, it can be verified that the stable periodic solution generates Turing bifurcation (Figure 3). Therefore, cross-diffusion causes the stable periodic solution of system (1.1) to become Turing unstable. self-diffusion induces Turing instability of periodic solution.

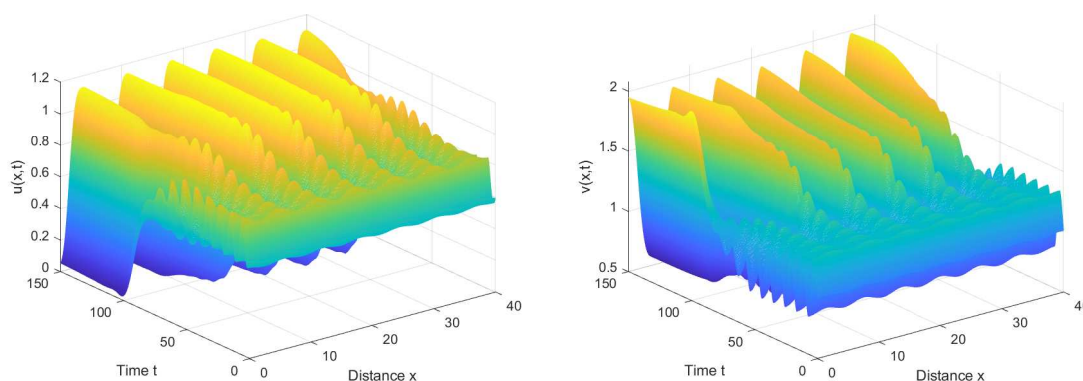


Figure 3. Cross-diffusion causes Turing instability of periodic solution.

(4) If we choose $d_{11} = 0.5, d_{12} = 1.5, d_{21} = 0.6, d_{22} = 4$, then

$$L_1(\mu_0^H)d_{11} + L_2(\mu_0^H)d_{22} - L_3(\mu_0^H)d_{12} - L_4(\mu_0^H)d_{21} < 0.$$

By Theorem 3.1, we can derive that diffusion causes the stable periodic solution of system (1.1) to become Turing unstable (Figure 4). This conforms to the theoretical analysis.

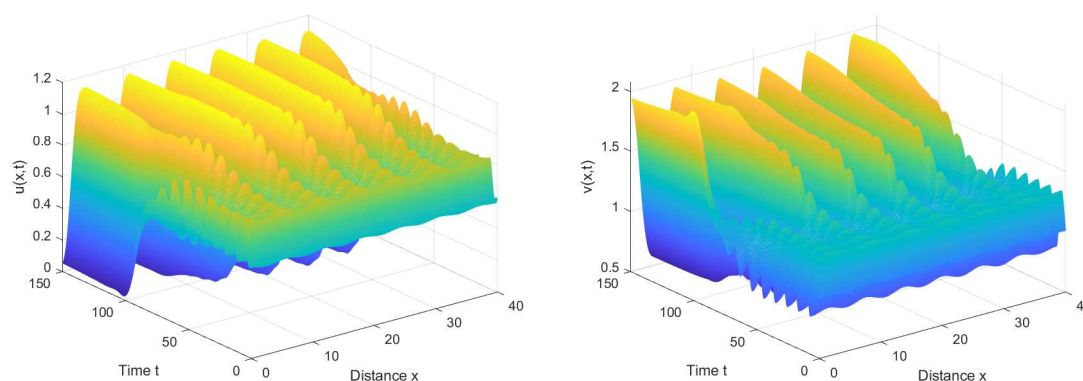


Figure 4. self-diffusion and cross-diffusion) induce Turing instability of periodic solution.

5. Conclusions

In this paper, a three-molecule autocatalytic Schnakenberg model with cross-diffusion is considered. From both theoretical and numerical perspectives, we investigated how cross-diffusion causes the Turing instability of spatially homogeneous Hopf bifurcating periodic solutions.

The theoretical results indicate that in the Schnakenberg model, when the parameters satisfy certain conditions and Ω is sufficiently large, once the instability of periodic solutions induced by diffusion occurs, new and rich spatiotemporal patterns may emerge. For the reaction-diffusion Schnakenberg model, we can derive the precise conditions of diffusion rates, under which the periodic solutions may experience the instability caused by diffusion.

By numerical simulations, the Turing instability of periodic solution $(u_T(t), v_T(t))^T$ can be observed. Figure 1 shows that without cross-diffusion coefficients, the identical self-diffusion coefficients will not cause the stable periodic solution to produce Turing bifurcation. Figures 2 and 4 illustrate that with appropriate diffusion coefficients, the stable periodic solution of system (1.1) generates Turing instability. Figure 3 indicates that if we select appropriate cross-diffusion coefficients, even for the models with identical self-diffusion rates, cross-diffusion can also cause stable periodic solution to produce Turing bifurcation. Thus, the Turing instability of stable periodic solution $(u_T(t), v_T(t))^T$ is actually induced by cross-diffusion.

Conflict of interest

The authors declare there is no conflicts of interest.

References

1. A. D. Anna, P. G. Lignola, S. K. Scott, The application of singularity theory to isothermal autocatalytic open systems, *Proc. R. Soc. A: Math.*, **403** (1986), 341–363. <https://doi.org/10.1098/rspa.1986.0015>
2. J. M. Mahaffy, Cellular control models with linked positive and negative feedback and delays. I. the models, *J. Theor. Biol.*, **106** (1984), 89–102. [https://doi.org/10.1016/0022-5193\(84\)90011-0](https://doi.org/10.1016/0022-5193(84)90011-0)

3. B. Peng, S. K. Scott, K. Showalter, Period doubling and chaos in a three-variable autocatalator, *J. Phys. Chem.*, **94** (1990), 5243–5246. <https://doi.org/10.1021/j100376a014>
4. D. T. Lynch, Chaotic behavior of reaction systems: Mixed cubic and quadratic autocatalysis, *Chem. Eng. Sci.*, **47** (1992), 4435–4444. [https://doi.org/10.1016/0009-2509\(92\)85121-Q](https://doi.org/10.1016/0009-2509(92)85121-Q)
5. K. Alhumaizi, R. Aris, Chaos in a simple two-phase reactor, *Chaos Solitons Fractals*, **4** (1994), 1985–2014. [https://doi.org/10.1016/0960-0779\(94\)90117-1](https://doi.org/10.1016/0960-0779(94)90117-1)
6. H. Liu, B. Ge, Turing instability of periodic solutions for the Gierer-Meinhardt model with cross-diffusion, *Chaos Solitons Fractals*, **155** (2022), 111752. <https://doi.org/10.1016/j.chaos.2021.111752>
7. H. Liu, B. Ge, J. Shen, Dynamics of periodic solutions in the reaction-diffusion glycolysis model: Mathematical mechanisms of Turing pattern formation, *Appl. Math. Comput.*, **431** (2022), 127324. <https://doi.org/10.1016/j.amc.2022.127324>
8. J. Schnakenberg, Simple chemical reaction systems with limit cycle behaviour, *J. Theor. Biol.*, **81** (1979), 389–400. [https://doi.org/10.1016/0022-5193\(79\)90042-0](https://doi.org/10.1016/0022-5193(79)90042-0)
9. D. Iron, J. Wei, M. Winter, Stability analysis of Turing patterns generated by the Schnakenberg model, *J. Math. Biol.*, **49** (2004), 359–390. [10.1007/s00285-003-0258-y](https://doi.org/10.1007/s00285-003-0258-y)
10. A. May, P. A. Firby, A. P. Bassom, Diffusion driven instability in an inhomogeneous circular domain, *Mathematical and Computer Modelling*, **29** (1999), 53–66. [https://doi.org/10.1016/S0895-7177\(99\)00039-4](https://doi.org/10.1016/S0895-7177(99)00039-4)
11. A. Madzvamuse, Time-stepping schemes for moving grid finite elements applied to reaction-diffusion systems on fixed and growing domains, *J. Comput. Phys.*, **214** (2006), 239–263. <https://doi.org/10.1016/j.jcp.2005.09.012>
12. M. J. Ward, J. Wei, The existence and stability of asymmetric spike patterns for the Schnakenberg Model, *Stud. Appl. Math.*, **109** (2002), 229–264. <https://doi.org/10.1111/1467-9590.00223>
13. P. Liu, J. Shi, Y. Wang, X. Feng, Bifurcation analysis of reaction-diffusion Schnakenberg model, *J. Math. Chem.*, **51** (2013), 2001–2019. <https://doi.org/10.1007/s10910-013-0196-x>
14. C. Xu, J. Wei, Hopf bifurcation analysis in a one-dimensional Schnakenberg reaction-diffusion model, *Nonlinear Anal. Real World Appl.*, **13** (2012), 1961–1977. <https://doi.org/10.1016/j.nonrwa.2012.01.001>
15. F. Yi, E. A. Gaffney, S. Seirin-Lee, The bifurcation analysis of turing pattern formation induced by delay and diffusion in the Schnakenberg system, *Discrete Contin. Dyn. Syst.*, **22** (2017), 647–668. <https://doi.org/10.3934/dcdsb.2017031>
16. H. Wei, Z. Bao, Hopf bifurcation analysis of a reaction-diffusion Sel'kov system, *J. Math. Anal. Appl.*, **356** (2009), 633–641. <https://doi.org/10.1016/j.jmaa.2009.03.058>
17. K. Maginu, Stability of spatially homogeneous periodic solutions of reaction-diffusion equations, *J. Differ. Equations*, **31** (1979), 130–138. [https://doi.org/10.1016/0022-0396\(79\)90156-6](https://doi.org/10.1016/0022-0396(79)90156-6)
18. F. Yi, Turing instability of the periodic solutions for reaction-diffusion systems with cross-diffusion and the patch model with cross-diffusion-like coupling, *J. Differ. Equations*, **281** (2021), 379–410. <https://doi.org/10.1016/j.jde.2021.02.006>

19. D. B. Henry, *Geometric Theory of Semilinear Parabolic Equations*, Springer-Verlag, Berlin, 1981.
20. F. Yi, J. Wei, J. Shi, Bifurcation and spatiotemporal patterns in a homogeneous diffusive predator-prey system, *J. Differ. Equations*, **246** (2009), 1944–1977. <https://doi.org/10.1016/j.jde.2008.10.024>
21. B. D. Hassard, N. D. Kazarinoff, Y. H. Wan, *Theory and applications of Hopf bifurcation*, Cambridge University Press, 1981.



AIMS Press

© 2023 the Author(s), licensee AIMS Press. This is an open access article distributed under the terms of the Creative Commons Attribution License (<http://creativecommons.org/licenses/by/4.0>)