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## Research article

# New error bounds for the tensor complementarity problem 

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#### Abstract

This paper discusses new error bounds for the tensor complementarity problem using a $P$-tensor. A new lower error bound and a global error bound are presented for such a problem. It is proved that the norm of the exact solution of the tensor complementarity problem with a $P$-tensor has a lower bound and an upper bound. When the order of a tensor is 2 , all the results for the tensor complementarity problem obtained reduce to those for the linear complementarity problem.


Keywords: tensor complementarity problem; $P$-tensor; error bound; linear complementarity problem; $P$-matrix

## 1. Introduction

The set of all real $r$ th-order $n$-dimensional tensors is denoted by $\mathbb{T}_{r, n}$, where $r \geq 3$ and $n \geq 2$ are positive integers. A tensor $\mathscr{A} \in \mathbb{T}_{r, n}$ is called a $P$-tensor [1], if for each vector $y \in \mathbb{R}^{n} \backslash\{0\}$, there exists an index $j \in J_{n}$ such that

$$
y_{j}\left(\mathscr{A} y^{r-1}\right)_{j} \geq 0,
$$

where $J_{n}$ defines the index set $\{1,2, \ldots, n\}$. For a given vector $q \in \mathbb{R}^{n}$ and a tensor $\mathscr{A}=\left(a_{j_{1} \ldots j_{r}}\right) \in \mathbb{T}_{r, n}$ with a multi-array of real entries $a_{j_{1} \ldots j_{r}}$, where $j_{i} \in J_{n}$ for $i \in\{1, \ldots, r\}$, the tensor complementarity problem denoted by the $\operatorname{TCP}(\mathscr{A}, q)$, is to find a real vector $y \in \mathbb{R}^{n}$ such that

$$
\begin{equation*}
y \geq 0, \quad q+\mathscr{A} y^{r-1} \geq 0, \quad \text { and } \quad y^{T}\left(q+\mathscr{A} y^{r-1}\right)=0, \tag{1.1}
\end{equation*}
$$

where $\mathscr{A} y^{r-1} \in \mathbb{R}^{n}$ and the $j$ th element of $\mathscr{A} y^{r-1}$ is determined by

$$
\left(\mathscr{A} y^{r-1}\right)_{j}:=\sum_{j_{2}, \ldots, j_{r}=1}^{n} a_{j j_{2} \ldots j_{r}} y_{j_{2}} \cdots y_{j_{r}}
$$

for $j \in J_{n}$. When the tensor $\mathscr{A}$ is a matrix, the $\operatorname{TCP}(\mathscr{A}, q)$ reduces to the linear complementarity problem [2], denoted by the $\operatorname{LCP}(M, q)$, which is to find a real vector $y \in \mathbb{R}^{n}$ such that

$$
y \geq 0, \quad q+M y \geq 0, \quad \text { and } \quad y^{T}(q+M y)=0
$$

where $M \in \mathbb{R}^{n \times n}$ and $q \in \mathbb{R}^{n}$. Error bounds of the $\operatorname{LCP}(M, q)$ have been extensively studied in recent years. For example, Mathias and Pang in [3] introduced fundamental quantities associated with an arbitrary $P$-matrix and derived global upper and lower error bounds for the approximate solution of the $\operatorname{LCP}(M, q)$ with a $P$-matrix. Global upper and lower error bounds to the $\operatorname{LCP}(M, q)$ with a $P$ matrix were given in [2] by Cottle et al. We refer to [4-7] for more new results on the estimation of error bounds to the $\operatorname{LCP}(M, q)$ with a $P$-matrix. We denote the $\operatorname{LCP}(M, q)$ with a $P$-matrix by the $\operatorname{LCP}(M, q ; p)$ and the $\operatorname{TCP}(\mathscr{A}, q)$ with a $P$-tensor by the $\operatorname{TCP}(\mathscr{A}, q ; p)$.

In recent years, the properties of several types of structured tensors in [8,9] were used to investigate some properties about the $\operatorname{TCP}(\mathscr{A}, q)$ solution set. The nonempty of the solution set of the $\operatorname{TCP}(\mathscr{A}, q)$ and the compactness of the solution set of the $\operatorname{TCP}(\mathscr{A}, q)$ were explored in $[10,11]$ by Che et al. Huang et al. [12,13] proved the existence of the solution of the $\operatorname{TCP}(\mathscr{A}, q)$. Yu et al. [14] evaluated the stability features of the $\operatorname{TCP}(\mathscr{A}, q)$ solution set. Zheng et al. [15] extended the results in [3] to the tensors and presented two $\operatorname{TCP}(\mathscr{A}, q ; p)$ global error bounds. In addition, some applications of the $\operatorname{TCP}(\mathscr{A}, q)$ were given in [16]. In this paper, we mainly expand the error bounds of the approximate solution of the $\operatorname{LCP}(M, q ; p)$ in $[2,7]$ to the cases of the $\operatorname{TCP}(\mathscr{A}, q ; p)$. We also extend the bound of the norm of the exact solution of the $\operatorname{LCP}(M, q ; p)$ in [7] to the case of the $\operatorname{TCP}(\mathscr{A}, q ; p)$.

The rest of this paper is arranged as follows. Section 2 presents some fundamental concepts and summarizes some related results that will be used later. Some new error bounds of the $\operatorname{TCP}(\mathscr{A}, q ; p)$ are given in Section 3. Section 4 drawn some conclusions.

## 2. Preliminaries

In this section, we summarize some results and introduce some denotations that will be used later. The following results are true for a $P$-tensor.

Lemma 2.1. ( [17]) For any P-tensor $\mathscr{A} \in \mathbb{T}_{r, n}$ and any $q \in \mathbb{R}^{n}$, the solution set of the $\operatorname{TCP}(\mathscr{A}, q)$ is nonempty and compact.
Lemma 2.2. ( $[15,18]$ ) There does not exist an odd order P-tensor.
For any tensor $\mathscr{A} \in \mathbb{T}_{r, n}$, the infinite norm of $\mathscr{A}$ is defined as follows:

$$
\|\mathscr{A}\|_{\infty}:=\max _{j \in J_{n}} \sum_{j_{2}, \ldots, j_{r}=1}^{n}\left|a_{j j_{2} \ldots j_{r}}\right|
$$

Let $T: \mathbb{R}^{n} \rightarrow \mathbb{R}^{n}$ be an operator, $T$ is said to be positively homogeneous iff $T(t y)=t T(y)$ holds, for any positive $t, y \in \mathbb{R}^{n}$. Song and Qi in [1] introduced two quantities of the form

$$
\begin{equation*}
\alpha\left(T_{\mathscr{A}}\right):=\min _{\|y\|_{\infty}=1} \max _{j \in J_{n}} y_{j}\left(T_{\mathscr{A}} y\right)_{j} \tag{2.1}
\end{equation*}
$$

for an arbitrary positive even integer $r$, and

$$
\begin{equation*}
\alpha\left(F_{\mathscr{A}}\right):=\min _{\|y\|_{\infty}=1} \max _{j \in J_{n}} y_{j}\left(F_{\mathscr{A}} y\right)_{j} . \tag{2.2}
\end{equation*}
$$

Here $T_{\mathscr{A}}: \mathbb{R}^{n} \rightarrow \mathbb{R}^{n}$ and $F_{\mathscr{A}}: \mathbb{R}^{n} \rightarrow \mathbb{R}^{n}$ are two operators that are positively homogenous and defined by

$$
T_{\mathscr{A}} y:= \begin{cases}\|y\|_{2}^{2-r} \mathscr{A} y^{r-1}, & y \neq 0  \tag{2.3}\\ 0, & y=0\end{cases}
$$

and

$$
\begin{equation*}
F_{\mathscr{A}} y:=\left(\mathscr{A} y^{r-1}\right)^{\left[\frac{1}{r-1}\right]} \tag{2.4}
\end{equation*}
$$

respectively. Here $y^{\left[\frac{1}{r-1}\right]}=\left(y_{1}^{\frac{1}{r-1}}, y_{2}^{\frac{1}{r-1}}, \ldots, y^{\frac{1}{r-1}}\right)^{T}$ for $y=\left(y_{1}, y_{2}, \ldots, y_{n}\right)^{T}$. It is true that

$$
\begin{equation*}
\alpha\left(F_{\mathscr{A}}\right)\|y\|_{\infty}^{2} \leq \max _{j \in J_{n}} y_{j}\left(F_{\mathscr{A}} y\right)_{j}=\max _{j \in J_{n}} y_{j}\left(\mathscr{A} y^{r-1}\right)_{j}^{\frac{1}{r-1}} . \tag{2.5}
\end{equation*}
$$

The following result in [1] gives two criterions of a $P$-tensor based on $\alpha\left(F_{\mathscr{A}}\right)$ and $\alpha\left(T_{\mathscr{A}}\right)$.
Lemma 2.3. ( [1]) Let $\mathscr{A} \in \mathbb{T}_{r, n}$, $\mathscr{A}$ is a P-tensor iff $\alpha\left(T_{\mathscr{A}}\right)>0$. When $r$ is even, it is especially true that $\mathscr{A}$ is a $P$-tensor iff $\alpha\left(F_{\mathscr{A}}\right)>0$.

## 3. New error bounds to the $\operatorname{TCP}(\mathscr{A}, q)$

In this section, new error bounds of the approximate solution of (1.1) are proposed. Denote the solution set of (1.1) by the set of the form

$$
\begin{equation*}
S:=\left\{y \in \mathbb{R}^{n} \mid y \geq 0, q+\mathscr{A} y^{r-1} \geq 0, y^{T}\left(q+\mathscr{A} y^{r-1}\right)=0\right\} \tag{3.1}
\end{equation*}
$$

then according to Lemma $2.1, S$ is nonempty and compact when $\mathscr{A} \in \mathbb{T}_{r, n}$ is a $P$-tensor. Thus for any $v \in \mathbb{R}^{n}$, there is a vector $\tilde{y} \in S$ such that

$$
\begin{equation*}
\|v-\tilde{y}\|_{\infty}=\min _{y \in S}\|v-y\|_{\infty} . \tag{3.2}
\end{equation*}
$$

We also need the results as follows.
Lemma 3.1. For an arbitrary positive integer $r$, it is true that

$$
\begin{equation*}
\left\|\mathscr{A} y^{r-1}\right\|_{\infty} \leq\|y\|_{\infty}^{r-1}\|\mathscr{A}\|_{\infty} . \tag{3.3}
\end{equation*}
$$

Proof. In fact

$$
\begin{aligned}
\left\|\mathscr{A} y^{r-1}\right\|_{\infty} & =\max _{j \in J_{n}}\left|\left(\mathscr{A} y^{r-1}\right)_{j}\right| \\
& =\max _{j \in J_{n}}\left|\sum_{j_{2}, \ldots, j_{r}=1}^{n} a_{j_{2} \ldots . . r_{r}} y_{j_{2}} \ldots y_{j_{r}}\right| \\
& \leq \max _{j \in J_{n}} \sum_{j_{2}, \ldots, j_{r}=1}^{n} \mid a_{j_{2} \ldots . . j_{r}}\| \| y \|_{\infty}^{r-1} \\
& =\|y\|_{\infty}^{r-1}\|\mathscr{A}\|_{\infty} .
\end{aligned}
$$

This completes the proof.
Theorem 3.1. Suppose $q \in \mathbb{R}^{n}, \mathscr{A} \in \mathbb{T}_{r, n}$ is a P-tensor. Let $\tilde{y}$ be the unique solution of the $\operatorname{TCP}(\mathscr{A}, q)$. We have

$$
\begin{equation*}
\frac{\left\|\tilde{v}_{\tilde{y}}\right\|_{\infty}}{\max \left\{1,\|\mathscr{A}\|_{\infty}^{\frac{1}{r-1}}\right\}} \leq\|v-\tilde{y}\|_{\infty}, \forall v \in \mathbb{R}^{n}, \tag{3.4}
\end{equation*}
$$

where $\tilde{v}_{\tilde{y}}$ is defined by

$$
\begin{equation*}
\tilde{v}_{\tilde{y}}:=\min \left\{v,\left(\mathscr{A}(v-\tilde{y})^{r-1}\right)^{\left[\frac{1}{r-1}\right]}+\left(q+\mathscr{A} \tilde{y}^{r-1}\right)^{\left[\frac{1}{r-1}\right]}\right\} . \tag{3.5}
\end{equation*}
$$

Proof. First show that for any $v, w \in \mathbb{R}^{n}$, the following inequality holds,

$$
\begin{equation*}
\left\|\tilde{v}_{\tilde{y}}-\tilde{w}_{\tilde{y}}\right\|_{\infty} \leq \max \left\{1,\|\mathscr{A}\|_{\infty}^{\frac{1}{r-1}}\right\}\left(\|v-\tilde{y}\|_{\infty}+\|w-\tilde{y}\|_{\infty}\right), \tag{3.6}
\end{equation*}
$$

where $\tilde{v}_{\tilde{y}}$ is defined in (3.5) and $\tilde{w}_{\tilde{y}}$ is determined by (3.5) with $v$ being replaced by $w$. Denote $y=\tilde{v}_{\tilde{y}}$ and $x=\tilde{w}_{\tilde{y}}$, suppose that $\left|y_{j}-x_{j}\right|=y_{j}-x_{j}, \forall j \in J_{n}$, then we have

$$
\begin{aligned}
& y=\tilde{v}_{\tilde{y}}=\min \left\{v,\left(\mathscr{A}(v-\tilde{y})^{r-1}\right)^{\left[\frac{1}{r-1}\right]}+\left(q+\mathscr{A} \tilde{y}^{r-1}\right)^{\left[\frac{1}{r-1}\right]}\right\}, \\
& x=\tilde{w}_{\tilde{y}}=\min \left\{w,\left(\mathscr{A}(w-\tilde{y})^{r-1}\right)^{\left[\frac{1}{r-1}\right]}+\left(q+\mathscr{A} \tilde{y}^{r-1}\right)^{\left[\frac{1}{r-1}\right]}\right\} .
\end{aligned}
$$

Thus,

$$
\begin{aligned}
& y_{j} \leq v_{j} \quad \text { and } \quad y_{j} \leq\left(\mathscr{A}(v-\tilde{y})^{r-1}\right)_{j}^{\frac{1}{r-1}}+\left(q+\mathscr{A} \tilde{y}^{r-1}\right)_{j}^{\frac{1}{r-1}}, \\
& x_{j}=w_{j} \quad \text { or } \quad x_{j}=\left(\mathscr{A}(w-\tilde{y})^{r-1}\right)_{j}^{\frac{1}{r-1}}+\left(q+\mathscr{A} \tilde{y}^{r-1}\right)_{j}^{\frac{1}{r-1}} .
\end{aligned}
$$

In the following, we prove this result in two cases. If $x_{j}=w_{j}$, then

$$
\begin{aligned}
\left|y_{j}-x_{j}\right|=y_{j}-x_{j} & \leq v_{j}-w_{j} \\
& \leq\|v-w\|_{\infty} \\
& =\|(v-\tilde{y})-(w-\tilde{y})\|_{\infty} \\
& \leq\|v-\tilde{y}\|_{\infty}+\|w-\tilde{y}\|_{\infty} .
\end{aligned}
$$

Therefore

$$
\begin{equation*}
\|y-x\|_{\infty} \leq\|v-\tilde{y}\|_{\infty}+\|w-\tilde{y}\|_{\infty} . \tag{3.7}
\end{equation*}
$$

If $x_{j}=\left(\mathscr{A}(w-\tilde{y})^{r-1}\right)_{j}^{\frac{1}{r-1}}+\left(q+\mathscr{A} \tilde{y}^{r-1}\right)_{j}^{\frac{1}{r-1}}$, then

$$
\begin{aligned}
\left|y_{j}-x_{j}\right|=y_{j}-x_{j} & \leq\left(\mathscr{A}(v-\tilde{y})^{r-1}\right)_{j}^{\frac{1}{r-1}}-\left(\mathscr{A}(w-\tilde{y})^{r-1}\right)_{j}^{\frac{1}{r-1}} \\
& \leq\left\|\mathscr{A}(v-\tilde{y})^{r-1}\right\|_{\infty}^{\frac{1}{r-1}}+\left\|\mathscr{A}(w-\tilde{y})^{r-1}\right\|_{\infty}^{\frac{1}{r-1}} .
\end{aligned}
$$

It follows from Lemma 3.1, that

$$
\begin{gathered}
\left\|\mathscr{A}(v-\tilde{y})^{r-1}\right\|_{\infty} \leq\|v-\tilde{y}\|_{\infty}^{r-1}\|\mathscr{A}\|_{\infty}, \\
\left\|\mathscr{A}(w-\tilde{y})^{r-1}\right\|_{\infty} \leq\|w-\tilde{y}\|_{\infty}^{r-1}\|\mathscr{A}\|_{\infty} .
\end{gathered}
$$

Thus it holds that

$$
\begin{equation*}
\|y-x\|_{\infty} \leq\|\mathscr{A}\|_{\infty}^{\frac{1}{r-1}}\left(\|v-\tilde{y}\|_{\infty}+\|w-\tilde{y}\|_{\infty}\right) . \tag{3.8}
\end{equation*}
$$

Combining (3.7) and (3.8) results in (3.6). Let $w=\tilde{y}$ in (3.6), then

$$
\begin{equation*}
\left\|\tilde{v}_{\tilde{y}}-\min \left\{\tilde{y},\left(q+\mathscr{A} \tilde{y}^{r-1}\right)^{\left[\frac{1}{r-1}\right]}\right\}\right\|_{\infty} \leq \max \left\{1,\|\mathscr{A}\|_{\infty}^{\frac{1}{r-1}}\right\}\|v-\tilde{y}\|_{\infty} . \tag{3.9}
\end{equation*}
$$

Given that $\tilde{y}$ solves the $\operatorname{TCP}(\mathscr{A}, q)$, then we have

$$
\min \left\{\tilde{y},\left(q+\mathscr{A} \tilde{y}^{r-1}\right)^{\left[\frac{1}{r-1}\right]}\right\}=0
$$

It follows from (3.9) that

$$
\left\|\min \left\{v,\left(\mathscr{A}(v-\tilde{y})^{r-1}\right)^{\left[\frac{1}{r-1}\right]}+\left(q+\mathscr{A} \tilde{y}^{r-1}\right)^{\left[\frac{1}{r-1}\right]}\right\}\right\|_{\infty} \leq \max \left\{1,\|\mathscr{A}\|_{\infty}^{\frac{1}{r-1}}\right\}\|v-\tilde{y}\|_{\infty},
$$

which implies (3.4). This completes the proof.
We remark that a lower error bound (Theorem 3.1) for the $\operatorname{TCP}(\mathscr{A}, q)$ with a $P$-tensor in this paper is sharper than the result (Theorem 3.2) in [15]. Because

$$
\frac{\left\|\tilde{v}_{\tilde{y}}\right\|_{\infty}}{1+\|\mathscr{A}\|_{\infty}^{\frac{1}{r-1}}} \leq \frac{\left\|\tilde{v}_{\tilde{y}}\right\|_{\infty}}{\max \left\{1,\|\mathscr{A}\|_{\infty}^{\frac{1}{r-1}}\right\}}, \tilde{v}_{\tilde{y}}:=\min \left\{v,\left(\mathscr{A}(v-\tilde{y})^{r-1}\right)^{\left[\frac{1}{r-1}\right]}+\left(q+\mathscr{A} \tilde{y}^{r-1}\right)^{\left[\frac{1}{r-1}\right]}\right\}
$$

The following result gives a global error bound on the approximate solution of (1.1).
Theorem 3.2. Suppose $\mathscr{A} \in \mathbb{T}_{r, n}$ is a P-tensor. Let $\tilde{y}$ be the unique solution of the $\operatorname{TCP}(\mathscr{A}, q)$. We have

$$
\begin{equation*}
\frac{\left(1+\|\mathscr{A}\|_{\infty}^{\frac{1}{r-1}}\right)\left\|\tilde{v}_{\tilde{y}}\right\|_{\infty}-\sqrt{\Delta_{1}}}{2 \alpha\left(F_{\mathscr{A}}\right)} \leq\|v-\tilde{y}\|_{\infty} \leq \frac{\left(1+\|\mathscr{A}\|_{\infty}^{\frac{1}{r-1}}\right)\left\|\tilde{v}_{\tilde{y}}\right\|_{\infty}+\sqrt{\Delta_{1}}}{2 \alpha\left(F_{\mathscr{A}}\right)}, \forall v \in \mathbb{R}^{n}, \tag{3.10}
\end{equation*}
$$

where

$$
\Delta_{1}=\left(1+\|\mathscr{A}\|_{\infty}^{\frac{1}{l-1}}\right)^{2}\left\|\tilde{v}_{\tilde{y}}\right\|_{\infty}^{2}-4 \alpha\left(F_{\mathscr{A}}\right)\left(\tilde{v}_{\tilde{y}}\right)_{k_{1}}^{2} \geq 0
$$

with $k_{1}$ satisfying $\left(\tilde{v}_{\tilde{y}}\right)_{k_{1}} \neq 0$,

$$
\left(\mathscr{A}(v-\tilde{y})^{r-1}\right)_{k_{1}}^{\frac{1}{r-1}}(v-\tilde{y})_{k_{1}}=\max _{j \in J_{n}}\left\{\left(\mathscr{A}(v-\tilde{y})^{r-1}\right)_{j}^{\frac{1}{r-1}}(v-\tilde{y})_{j}\right\}
$$

and $\alpha\left(F_{\mathscr{A}}\right)$ is defined in (2.2).
Proof. We first show that the following inequality holds

$$
\begin{equation*}
\alpha\left(F_{\mathscr{A}}\right)\|v-\tilde{y}\|_{\infty}^{2}-\left(1+\|\mathscr{A}\|_{\infty}^{\frac{1}{-1}}\right)\left\|\tilde{v}_{\tilde{y}}\right\|_{\infty}\|v-\tilde{y}\|_{\infty}+\left(\tilde{v}_{\tilde{y}}\right)_{k_{1}}^{2} \leq 0 . \tag{3.11}
\end{equation*}
$$

Suppose $w=\left(q+\mathscr{A} \tilde{y}^{r-1}\right)^{\left[\frac{1}{r-1}\right]}$. Since $\tilde{y}$ solves (1.1), we can prove that

$$
\tilde{y} \geq 0, w \geq 0, \tilde{y}^{T} w=0 .
$$

Let $x=v-\tilde{v}_{\tilde{y}}$ and $z=\left(\mathscr{A}(v-\tilde{y})^{r-1}\right)^{\left[\frac{1}{r-1}\right]}+\left(q+\mathscr{A} \tilde{y}^{r-1}\right)^{\left[\frac{1}{r-1}\right]}-\tilde{v}_{\tilde{y}}$, where $\tilde{v}_{\tilde{y}}$ is defined as that in (3.5), then we have that

$$
x \geq 0, z \geq 0, x^{T} z=0
$$

Therefore, for any $j \in J_{n}$,

$$
\begin{aligned}
0 \geq x_{j} z_{j}-x_{j} w_{j}-\tilde{y}_{j} z_{j}+\tilde{y}_{j} w_{j} & =(z-w)_{j}(x-\tilde{y})_{j} \\
& =\left[\left(\mathscr{A}(v-\tilde{y})^{r-1}\right)^{\left[\frac{1}{r-1}\right]}-\tilde{v}_{\tilde{y}}\right]_{j}\left(v-\tilde{v}_{\tilde{y}}-\tilde{y}\right)_{j} \\
& =\left(\mathscr{A}(v-\tilde{y})^{r-1}\right)_{j}^{\frac{1}{r-1}}(v-\tilde{y})_{j}-\left(\tilde{v}_{\tilde{y}}\right)_{j}(v-\tilde{y})_{j} \\
& -\left(\mathscr{A}(v-\tilde{y})^{r-1}\right)_{j}^{\frac{1}{r-1}}\left(\tilde{v}_{\tilde{y}}\right)_{j}+\left(\tilde{v}_{\tilde{y}}\right)_{j}^{2} .
\end{aligned}
$$

Thus

$$
\left(\tilde{v}_{\tilde{y}}\right)_{j}(v-\tilde{y})_{j}+\left(\mathscr{A}(v-\tilde{y})^{r-1}\right)_{j}^{\frac{1}{r-1}}\left(\tilde{v}_{\tilde{y}}\right)_{j}-\left(\tilde{v}_{\tilde{y}}\right)_{j}^{2} \geq\left(\mathscr{A}(v-\tilde{y})^{r-1}\right)_{j}^{\frac{1}{r-1}}(v-\tilde{y})_{j} .
$$

Let

$$
\left(\mathscr{A}(v-\tilde{y})^{r-1}\right)_{k_{1}}^{\frac{1}{r-1}}(v-\tilde{y})_{k_{1}}=\max _{j \in J_{n}}\left\{\left(\mathscr{A}(v-\tilde{y})^{r-1}\right)_{j}^{\frac{1}{r-1}}(v-\tilde{y})_{j}\right\}
$$

then

$$
\begin{align*}
& \max _{j \in J_{n}}\left\{\left(\mathscr{A}(v-\tilde{y})^{r-1}\right)_{j}^{\frac{1}{r-1}}(v-\tilde{y})_{j}\right\} \\
\leq & \left(\tilde{v}_{\tilde{y}}\right)_{k_{1}}(v-\tilde{y})_{k_{1}}+\left(\mathscr{A}(v-\tilde{y})^{r-1}\right)_{k_{1}}^{\frac{1}{r-1}}\left(\tilde{v}_{\tilde{y}}\right)_{k_{1}}-\left(\tilde{v}_{\tilde{y}}\right)_{k_{1}}^{2}  \tag{3.12}\\
\leq & \left\|\tilde{v}_{\tilde{y}}\right\|_{\infty}\|v-\tilde{y}\|_{\infty}+\left\|\left(\mathscr{A}(v-\tilde{y})^{r-1}\right)^{\frac{1}{r-1}}\right\|_{\infty}\left\|\tilde{v}_{\tilde{y}}\right\|_{\infty}-\left(\tilde{y}_{\tilde{y}}\right)_{k_{1}}^{2} .
\end{align*}
$$

From Lemma 3.1, we have that

$$
\begin{equation*}
\left\|\left(\mathscr{A}(v-\tilde{y})^{r-1}\right)^{\frac{1}{r-1}}\right\|_{\infty} \leq\|v-\tilde{y}\|_{\infty}\|\mathscr{A}\|_{\infty}^{\frac{1}{r-1}} . \tag{3.13}
\end{equation*}
$$

Furthermore, we can deduce from (2.5) that

$$
\begin{equation*}
\alpha\left(F_{\mathscr{A}}\right)\|v-\tilde{y}\|_{\infty}^{2} \leq \max _{j \in J_{n}}\left\{\left(\mathscr{A}(v-\tilde{y})^{r-1}\right)_{j}^{\frac{1}{r-1}}(v-\tilde{y})_{j}\right\} . \tag{3.14}
\end{equation*}
$$

Therefore, combining (3.12)-(3.14) results in

$$
\begin{aligned}
\alpha\left(F_{\mathscr{A}}\right)\|v-\tilde{y}\|_{\infty}^{2} & \leq(v-\tilde{y})_{k_{1}}\left(\tilde{v}_{\tilde{y}}\right)_{k_{1}}+\left(\mathscr{A}(v-\tilde{y})^{r-1}\right)_{k_{1}}^{\frac{1}{r-1}}\left(\tilde{v}_{\tilde{y}}\right)_{k_{1}}-\left(\tilde{v}_{\tilde{y}}\right)_{k_{1}}^{2} \\
& \leq\|v-\tilde{y}\|_{\infty}\left\|\tilde{v}_{\tilde{y}}\right\|_{\infty}+\left\|\left(\mathscr{A}(v-\tilde{y})^{r-1}\right)^{\frac{1}{r-1}}\right\|_{\infty}\left\|\tilde{v}_{\tilde{y}}\right\|_{\infty}-\left(\tilde{v}_{\tilde{y}}\right)_{k_{1}}^{2} \\
& =\|v-\tilde{y}\|_{\infty}\left(1+\|\mathscr{A}\|_{\infty}^{\frac{1}{r-1}}\right)\left\|\tilde{v}_{\tilde{y}}\right\|_{\infty}-\left(\tilde{v}_{\tilde{y}}\right)_{k_{1}}^{2} .
\end{aligned}
$$

If $\left(\tilde{v}_{\tilde{y}}\right)_{k_{1}}=0$, then $v=\tilde{y}$; otherwise, (3.11) holds. According to Lemma 2.3, we have $\alpha\left(F_{\mathscr{A}}\right)>0$, here $\mathscr{A}$ is a $P$-tensor. We can derive (3.10) by solving (3.11). The proof is completed.

If we set $v=0$ in Theorem 3.2, we obtain a new bound for the norm of the exact solution of (1.1).

Corollary 1. Let $v=0$, then under the conditions of Theorem 3.2, we have that

$$
\begin{equation*}
\frac{\left|\left((-q)_{+}\right)_{k_{2}}\right|\left(1+\|\mathscr{A}\|_{\infty}^{\frac{1}{r-1}}\right)-\sqrt{\Delta_{2}}}{2 \alpha\left(F_{\mathscr{A}}\right)} \leq\|\tilde{y}\|_{\infty} \leq \frac{\left|\left((-q)_{+}\right)_{k_{2}}\right|\left(1+\|\mathscr{A}\|_{\infty}^{\frac{1}{r_{0}-1}}\right)+\sqrt{\Delta_{2}}}{2 \alpha\left(F_{\mathscr{A}}\right)}, \tag{3.15}
\end{equation*}
$$

where

$$
\begin{gathered}
(-q)_{+}=\min \{-q, 0\}, \\
\Delta_{2}=\left((-q)_{+}\right)_{k_{2}}^{2}\left(1+\|\mathscr{A}\|_{\infty}^{\frac{1}{r-1}}\right)^{2}-4 \alpha\left(F_{\mathscr{A}}\right)\left((-q)_{+}\right)_{k_{2}}^{2} \geq 0
\end{gathered}
$$

with $k_{2}$ satisfying

$$
\tilde{y}_{k_{2}}\left(\mathscr{A} \tilde{y}^{r-1}\right)_{k_{2}}^{\frac{1}{r-1}}=\max _{j \in J_{n}}\left\{\tilde{y}_{j}\left(\mathscr{A} \tilde{y}^{r-1}\right)_{j}^{\frac{1}{r-1}}\right\}, \text { and } \quad\left((-q)_{+}\right)_{k_{2}} \neq 0 \text {, }
$$

and $\alpha\left(F_{\mathscr{A}}\right)$ is defined in (2.2).
Proof. The proof is similar to that of Theorem 3.2 and is omitted.
We have obtained a new lower error bound in Theorem 3.1 and a global error bound in Theorem 3.2 to the $\operatorname{TCP}(\mathscr{A}, q ; p)$.

We remark that when $r=2$, Theorem 3.2 and Corollary 1 reduce to Theorem 3.1 in [7] and Corollary 3.1 in [7], respectively.

When $r=2$, the tensor $\mathscr{A} \in \mathbb{T}_{r, n}$ reduces to a matrix $M$. Thus, $F_{\mathscr{A}} y:=\left(\mathscr{A} y^{r-1}\right)^{\left[\frac{1}{r-1}\right]}=M y$, we have

$$
\alpha\left(F_{\mathscr{A}}\right):=\min _{\|y\|_{\infty}=1} \max _{j \in J_{n}} y_{j}\left(F_{\mathscr{A}} y\right)_{j}=\min _{\|y\|_{\infty}=1} \max _{j \in J_{n}} y_{j}(M y)_{j}=\alpha(M) .
$$

Furthermore, we can deduce from (3.5) that

$$
\begin{aligned}
& \tilde{v}_{\tilde{y}}: \\
&=\min \left\{v,\left(\mathscr{A}(v-\tilde{y})^{r-1}\right)^{\left[\frac{1}{r-1}\right]}+\left(q+\mathscr{A} \tilde{y}^{r-1}\right)^{\left[\frac{1}{r-1}\right]}\right\} \\
&=\min \{v, M(v-\tilde{y})+q+M \tilde{y}\} \\
&=\min \{v, q+M v\}=u,
\end{aligned}
$$

which implies that

$$
\begin{aligned}
\Delta_{1} & =\left(1+\|\mathscr{A}\|_{\infty}^{\frac{1}{-1}-1}\right)^{2}\left\|\tilde{v}_{\tilde{y}}\right\|_{\infty}^{2}-4 \alpha\left(F_{\mathscr{A}}\right)\left(\tilde{v}_{\tilde{y}}\right)_{k_{1}}^{2} \\
& =\left(1+\|M\|_{\infty}\right)^{2}\|\min \{v, q+M v\}\|_{\infty}^{2}-4 \alpha(M)(\min \{v, q+M v\})_{k_{1}}^{2} \\
& =\left(1+\|M\|_{\infty}\right)^{2}\|u\|_{\infty}^{2}-4 \alpha(M) u_{k_{1}}^{2}=\Delta
\end{aligned}
$$

with $k_{1}$ satisfying $u_{k_{1}} \neq 0$ and

$$
(v-\tilde{y})_{k_{1}}(M(v-\tilde{y}))_{k_{1}}=\max _{j \in J_{n}}\left\{(v-\tilde{y})_{j}(M(v-\tilde{y}))_{j}\right\},
$$

and that

$$
\begin{aligned}
\Delta_{2} & =\left((-q)_{+}\right)_{k_{2}}^{2}\left(1+\|\mathscr{A}\|_{\infty}^{\frac{1}{1-1}}\right)^{2}-4 \alpha\left(F_{\mathscr{A}}\right)\left((-q)_{+}\right)_{k_{2}}^{2} \\
& =\left((-q)_{+}\right)_{k_{2}}^{2}\left(1+\|M\|_{\infty}\right)^{2}-4 \alpha(M)\left((-q)_{+}\right)_{k_{2}}^{2} \\
& =\Delta^{\prime}
\end{aligned}
$$

with $k_{2}$ satisfying $\left((-q)_{+}\right)_{k_{2}} \neq 0$ and

$$
\tilde{y}_{k_{2}}(M \tilde{y})_{k_{2}}=\max _{j \in J_{n}}\left\{\tilde{y}_{j}(M \tilde{y})_{j}\right\} .
$$

Therefore, Theorem 3.1 reduces to Theorem 5.10.6 in [2].
Similarly, when $r=2$, Theorem 3.2 is an extension of Theorem 3.1 in [7], and Corollary 1 is an extension of Corollary 3.1 in [7].

## 4. Conclusions

In this paper, we present a new lower error bound and a result of the global error bound on the approximate solution to the $\operatorname{TCP}(\mathscr{A}, q)$ with a $P$-tensor. The new bound on the norm of the exact solution to the $\operatorname{TCP}(\mathscr{A}, q)$ with a $P$-tensor is derived.

As we all know, error bounds have important applications in iterative methods for solving related optimization problems. For example, we use the obtained error bounds to analyze the convergence of the iterative method for solving the $\operatorname{TCP}(\mathscr{A}, q)$. We can futher study the numerical algorithm to compute the error bounds of the $\operatorname{TCP}(\mathscr{A}, q)$ with a $P$-tensor (see [19]).

## Acknowledgments

Research by G.X. Huang was supported in part by Key Laboratory of bridge nondestructive testing and engineering calculation Open fund projects (grant 2020QZJ03).

## Conflict of interest

The authors declare there is no conflicts of interest.

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