

ERA, 30(5): 1691–1707. DOI: 10.3934/era.2022085 Received: 13 August 2021 Revised: 15 January 2022 Accepted: 15 January 2022 Published: 25 March 2022

http://www.aimspress.com/journal/era

Research article

Periodic solutions to symmetric Newtonian systems in neighborhoods of orbits of equilibria

Anna Gołębiewska, Marta Kowalczyk, Sławomir Rybicki*and Piotr Stefaniak

Faculty of Mathematics and Computer Science, Nicolaus Copernicus University in Toruń, PL-87-100 Toruń, ul. Chopina 12/18, Poland

* Correspondence: Email: rybicki@mat.umk.pl; Tel: +48566112924; Fax: +48566228979.

Abstract: The aim of this paper is to prove the existence of periodic solutions to symmetric Newtonian systems in any neighborhood of an isolated orbit of equilibria. Applying equivariant bifurcation techniques we obtain a generalization of the classical Lyapunov center theorem to the case of symmetric potentials with orbits of non-isolated critical points. Our tool is an equivariant version of the Conley index. To compare the indices we compute cohomological dimensions of some orbit spaces.

Keywords: Lyapunov center theorem; symmetric Newtonian systems; equivariant Conley index; periodic solutions; symmetric bifurcations

On the occasion of the 75th birthday of Professor E. N. Dancer

1. Introduction

Studying non-stationary periodic solutions to Hamiltonian and Newtonian systems in a neighborhood of an isolated equilibrium is one of the most important classical problems of differential equations. This problem has a long history and has been studied by many mathematicians for centuries, see the following classical articles due to Lyapunov [1], Weinstein [2], Moser [3], Fadell and Rabinowitz [4], Montaldi, Roberts and Stewart [5], Bartsch [6] and references therein. We are aware that this list is far from being complete. Note that the stationary solutions considered in these papers have been assumed to be non-degenerate. It is worth to point out that non-degenerate as well as isolated degenerate stationary solutions have been considered by Dancer and the third author in [7] and Szulkin in [8].

In this article we focus our attention on symmetric Newtonian systems. More precisely, we consider \mathbb{R}^N as an orthogonal representation of a compact Lie group Γ and a Γ -invariant potential $U: \mathbb{R}^N \to \mathbb{R}$ of class C^2 , i.e., the potential U satisfying $U(\gamma u) = U(u)$ for all $\gamma \in \Gamma$ and $u \in \mathbb{R}^N$. If u_0 is a critical

point of *U*, i.e., $\nabla U(u_0) = 0$, then the orbit $\Gamma(u_0) = \{\gamma u_0 : \gamma \in \Gamma\}$ consists of critical points of *U*, i.e., $\Gamma(u_0) \subset (\nabla U)^{-1}(0)$. It is known that the orbit $\Gamma(u_0)$ is Γ -homeomorphic to Γ/Γ_{u_0} , where $\Gamma_{u_0} = \{\gamma \in \Gamma: \gamma u_0 = u_0\}$ is the stabilizer of u_0 . Hence if dim $\Gamma \ge 1$, then it can happen that dim $\Gamma(u_0) \ge 1$, i.e., the critical point u_0 is not isolated in $(\nabla U)^{-1}(0)$.

We study the existence of non-stationary periodic solutions of the following Γ -symmetric system

$$\ddot{u}(t) = -\nabla U(u(t)) \tag{1.1}$$

in any neighborhood of the isolated orbit $\Gamma(u_0) \subset (\nabla U)^{-1}(0)$. In other words, we are going to prove a symmetric version of the classical Lyapunov center theorem, where, due to additional Γ -symmetries, an isolated stationary solution is replaced by an isolated orbit of stationary solutions. The theorems, which are the main results of our paper, are formulated below.

Define $\sigma^+(\nabla^2 U(u_0)) = \sigma(\nabla^2 U(u_0)) \cap (0, +\infty)$ and put $\mathcal{B} = \{\beta_1, \beta_2, \dots, \beta_q\}$, where $\beta_1 > \beta_2 > \dots > \beta_q > 0$ are such that $\sigma^+(\nabla^2 U(u_0)) = \{\beta_1^2, \dots, \beta_q^2\}$.

Theorem 1.1. [Symmetric Lyapunov center theorem for a non-degenerate orbit] Let $\Omega \subset \mathbb{R}^N$ be an open and Γ -invariant subset of an orthogonal representation \mathbb{R}^N of a compact Lie group Γ . Assume that $U: \Omega \to \mathbb{R}$ is a Γ -invariant potential of class C^2 , $u_0 \in \Omega \cap (\nabla U)^{-1}(0)$ and

- *1*. $\Gamma_{u_0} = S^1$ or $\Gamma_{u_0} = \mathbb{Z}_m$ for some $m \in \mathbb{N}$,
- 2. dim ker $\nabla^2 U(u_0) = \dim \Gamma(u_0)$,
- 3. $\sigma^+(\nabla^2 U(u_0)) \neq \emptyset$.

If there exists $\beta_{i_0} \in \mathcal{B}$ satisfying the conditions:

(A1) $\beta_j/\beta_{j_0} \notin \mathbb{N}$ for $\beta_j \in \mathcal{B} \setminus \{\beta_{j_0}\}$, (A2) if $\Gamma_{u_0} = S^1$, then the associated eigenspace $V_{\nabla^2 U(u_0)}(\beta_{j_0}^2)$ is a nontrivial S^1 -representation,

then there exists a sequence (u_k) of periodic solutions of the system (1.1) with a sequence (T_k) of minimal periods such that $T_k \to 2\pi/\beta_{j_0}$ and for any $\varepsilon > 0$ there exists $k_0 \in \mathbb{N}$ such that $u_k([0, T_k]) \subset \Gamma(u_0)_{\varepsilon} = \bigcup_{u \in \Gamma(u_0)} B_{\varepsilon}(\mathbb{R}^N, u)$ for all $k \ge k_0$.

Theorem 1.2. [Symmetric Lyapunov center theorem for a minimal orbit] Let $\Omega \subset \mathbb{R}^N$ be an open and Γ -invariant subset of an orthogonal representation \mathbb{R}^N of a compact Lie group Γ . Assume that $U: \Omega \to \mathbb{R}$ is a Γ -invariant potential of class C^2 , $u_0 \in \Omega \cap (\nabla U)^{-1}(0)$ and

- 1. $\Gamma_{u_0} = S^1 \text{ or } \Gamma_{u_0} = \mathbb{Z}_m \text{ for some } m \in \mathbb{N},$
- 2. $\Gamma(u_0)$ consists of minima of the potential U,
- 3. $\Gamma(u_0)$ is isolated in $(\nabla U)^{-1}(0)$,
- 4. $\sigma^+(\nabla^2 U(u_0)) \neq \emptyset$.

If there exists $\beta_{j_0} \in \mathcal{B}$ satisfying the conditions:

(A1) $\beta_j / \beta_{j_0} \notin \mathbb{N}$ for $\beta_j \in \mathcal{B} \setminus \{\beta_{j_0}\}$, (A2) if $\Gamma_{u_0} = S^1$, then the associated eigenspace $V_{\nabla^2 U(u_0)}(\beta_{j_0}^2)$ is a nontrivial S^1 -representation,

then there exists a sequence (u_k) of periodic solutions of the system (1.1) with a sequence (T_k) of minimal periods such that $T_k \to 2\pi/\beta_{j_0}$ and for any $\varepsilon > 0$ there exists $k_0 \in \mathbb{N}$ such that $u_k([0, T_k]) \subset \Gamma(u_0)_{\varepsilon}$ for all $k \ge k_0$.

Electronic Research Archive

Note that the condition (A2) can be replaced by a different one. We discuss it in more details in Remark 3.7.

Note that if $\sigma^+(\nabla^2 U(u_0)) \neq \emptyset$, then obviously β_1 satisfies the assumption (A1). If additionally β_1 satisfies the assumption (A2) and the remaining assumptions of the theorems are fullfilled, then there exists at least one sequence (u_k) of periodic solutions of the system (1.1) with a sequence (T_k) of minimal periods converging to $2\pi/\beta_1$. Moreover, selecting various β_{j_0} satisfying all the assumptions we obtain different sequences of periodic solutions which can be distinguished by their minimal periods.

We emphasize that in Theorem 1.1 we consider a non-degenerate orbit $\Gamma(u_0)$, i.e., an orbit satisfying the condition dim ker $\nabla^2 U(u_0) = \dim \Gamma(u_0)$, whereas in Theorem 1.2 we allow the orbit $\Gamma(u_0)$ to be degenerate, i.e., such that dim ker $\nabla^2 U(u_0) > \dim \Gamma(u_0)$.

Results of this type have been proved in [9, 10] for symmetric Newtonian systems and in [11] for symmetric Hamiltonian systems under the assumption that the stabilizer Γ_{u_0} is trivial, i.e., the orbit $\Gamma(u_0)$ is Γ -homeomorphic to the group Γ . On the other hand, in [12] we have considered symmetric Newtonian systems under the assumption that the stabilizer Γ_{u_0} is isomorphic to a finite-dimensional torus $T \subset \Gamma$, i.e., the orbit $\Gamma(u_0)$ is Γ -homeomorphic to Γ/T .

In our paper we consider orbits $\Gamma(u_0)$ such that the stabilizer Γ_{u_0} equals S^1 or \mathbb{Z}_m , i.e., the orbit $\Gamma(u_0)$ is Γ -homeomorphic to Γ/S^1 or Γ/\mathbb{Z}_m . It is worth pointing out that the case $\Gamma_{u_0} = \mathbb{Z}_m$ has not been considered in our previous articles.

In [9–12] the solutions of the system (1.1) have been considered as orbits of critical points of a family of $(\Gamma \times S^1)$ -invariant functionals defined on an appropriately chosen Hilbert space, which is an orthogonal representation of the group $\Gamma \times S^1$. To prove the main results of these articles we have applied the techniques of equivariant bifurcation theory. As a topological tool we have used the infinite-dimensional generalization of the $(\Gamma \times S^1)$ -equivariant Conley index defined by Izydorek, see [13]. To show the existence of non-stationary periodic solutions of the system (1.1) in an arbitrary neighborhood of the orbit $\Gamma(u_0)$ we have proved the change of this index. To distinguish between two Conley indices we have used the equivariant Euler characteristic, which is an element of the Euler ring $U(\Gamma \times S^1)$, see [14]. These calculations were rather tedious and complicated.

In this paper we apply a different approach. Namely, we consider orbit spaces of the equivariant Conley indices, which are the homotopy types of the weighted projective spaces or the lens complexes. Since the cohomology groups of the weighted projective spaces and the lens complexes are known, see [15], we compute the cohomological dimensions of these spaces. This technique of distinguishing between equivariant Conley indices seems to be much simpler.

To be more precise, instead of making calculations in the Euler ring $U(\Gamma \times S^1)$ we employ the concept of a quotient space and use the notion of the cohomological dimension to prove a change of the equivariant Conley index.

The topological results described above are given in Section 2, whereas Section 3 contains the proofs of Theorems 1.1 and 1.2. Additionally, in the appendix we recall some relevant material needed in the previous sections.

2. Preliminary results

In this section we study the Γ -homotopy equivalence of some finite pointed Γ -CW-complexes (see [14] for the definition), where Γ is a compact Lie group. In particular, we are interested in com-

plexes being of the form of smash products over some groups $H \in \text{sub}(\Gamma)$, where $\text{sub}(\Gamma)$ denotes the set of closed subgroups of Γ . Below we recall the definition of such a space, see [14] for details.

Fix $H \in \operatorname{sub}(\Gamma)$ and let \mathbb{X} be a pointed H-space with a base point *. Denote by Γ^+ the group Γ with a disjoint Γ -fixed base point added. Recall that the smash product of Γ^+ and \mathbb{X} is $\Gamma^+ \wedge \mathbb{X} = \Gamma^+ \times \mathbb{X}/\Gamma^+ \vee \mathbb{X} = \Gamma \times \mathbb{X}/\Gamma \times \{*\}$. The group H acts on the pointed space $\Gamma^+ \wedge \mathbb{X}$ by $(h, [\gamma, x]) \mapsto [\gamma h^{-1}, hx]$. We denote the orbit space of this action by $\Gamma^+ \wedge_H \mathbb{X}$ and call it the smash over H. The formula $(\gamma', [\gamma, x]) \mapsto [\gamma' \gamma, x]$ induces a Γ -action so that $\Gamma^+ \wedge_H \mathbb{X}$ becomes a pointed Γ -space.

Remark 2.1. If X is a finite pointed H-CW-complex, then $\Gamma^+ \wedge_H X$ is a Γ -CW complex, see [9], and the orbit space X/H is a finite pointed CW-complex, see [14].

For brevity we will write $\mathbb{X} \approx_H \mathbb{Y}$ if *H*-CW-complexes \mathbb{X} , \mathbb{Y} are *H*-homotopically equivalent. In the non-equivariant case, $\mathcal{X} \approx \mathcal{Y}$ denotes homotopical equivalence of CW-complexes \mathcal{X} , \mathcal{Y} .

Lemma 2.2. Let \mathbb{X} , \mathbb{Y} be finite pointed *H*-*CW*-complexes. If $\Gamma^+ \wedge_H \mathbb{X} \approx_{\Gamma} \Gamma^+ \wedge_H \mathbb{Y}$, then $\mathbb{X}/H \approx \mathbb{Y}/H$.

Proof. Consider the orbit spaces $(\Gamma^+ \wedge_H \mathbb{X})/\Gamma$, $(\Gamma^+ \wedge_H \mathbb{Y})/\Gamma$ and note that from the assumption and the formula (1.12) of [14, Chapter 1] we get

$$(\Gamma^+ \wedge_H \mathbb{X})/\Gamma \approx (\Gamma^+ \wedge_H \mathbb{Y})/\Gamma.$$
(2.1)

For an *H*-space \mathbb{W} denote by $\Gamma \times_H \mathbb{W}$ the twisted product over *H*. The inclusion $\mathbb{W} \to \Gamma \times_H \mathbb{W}$ induces a homeomorphism of \mathbb{W}/H and $(\Gamma \times_H \mathbb{W})/\Gamma$, see for instance [14]. Moreover, if \mathbb{W} is a pointed *H*-space, $\Gamma^+ \wedge_H \mathbb{W} = (\Gamma \times_H \mathbb{W})/(\Gamma \times_H \{*\})$. Therefore,

$$(\Gamma^+ \wedge_H \mathbb{X})/\Gamma \approx \mathbb{X}/H$$
 and $(\Gamma^+ \wedge_H \mathbb{Y})/\Gamma \approx \mathbb{Y}/H.$ (2.2)

Combining (2.1) and (2.2) we obtain the assertion.

From this lemma it follows that in some cases we can reduce comparing the Γ -equivariant homotopy types of Γ -CW-complexes of the form $\Gamma^+ \wedge_H \mathbb{X}$ to comparing the homotopy types of CW-complexes of the form \mathbb{X}/H .

To consider the homotopy equivalence of CW-complexes we will use the notion of the cohomological dimension of a CW-complex. For a CW-complex \mathcal{Z} denote by $\widetilde{H}^k(\mathcal{Z};\mathbb{Z})$ the *k*-th reduced cohomology group of \mathcal{Z} . If there exists a number $k \ge 0$ such that $\widetilde{H}^k(\mathcal{Z};\mathbb{Z}) \ne 0$, then we define the cohomological dimension of a CW-complex \mathcal{Z} by

$$C\mathcal{D}(\mathcal{Z}) := \max\{k \in \mathbb{N} \cup \{0\} \colon H^k(\mathcal{Z}; \mathbb{Z}) \neq 0\}.$$

Obviously, if Z_1, Z_2 are homotopically equivalent CW-complexes, then $C\mathcal{D}(Z_1) = C\mathcal{D}(Z_2)$.

Lemma 2.3. Let Z_1, Z_2 be finite CW-complexes such that $CD(Z_1)$ and $CD(Z_2)$ are well-defined. Then we have $CD(Z_1 \land Z_2) = CD(Z_1) + CD(Z_2)$.

Proof. Since Z_1, Z_2 are finite CW-complexes, the groups $\widetilde{H}^{q_1}(Z_1; \mathbb{Z}), \widetilde{H}^{q_1}(Z_2; \mathbb{Z})$ are finitely generated free groups for every $q_1, q_2 \in \mathbb{N} \cup \{0\}$. Therefore, by the Künneth formula, see [16], we obtain the reduced cross product isomorphism

$$\times: \widetilde{H}^{q_1}(\mathcal{Z}_1;\mathbb{Z}) \otimes \widetilde{H}^{q_2}(\mathcal{Z}_2;\mathbb{Z}) \to \widetilde{H}^{q_1+q_2}(\mathcal{Z}_1 \wedge \mathcal{Z}_2;\mathbb{Z}).$$

Electronic Research Archive

Volume 30, Issue 5, 1691–1707.

That is why the reduced cross product

$$\times: \widetilde{H}^{\mathcal{CD}(\mathcal{Z}_1)}(\mathcal{Z}_1;\mathbb{Z}) \otimes \widetilde{H}^{\mathcal{CD}(\mathcal{Z}_2)}(\mathcal{Z}_2;\mathbb{Z}) \to \widetilde{H}^{\mathcal{CD}(\mathcal{Z}_1) + \mathcal{CD}(\mathcal{Z}_2)}(\mathcal{Z}_1 \wedge \mathcal{Z}_2;\mathbb{Z})$$

is an isomorphism of non-trivial groups.

What is left is to show that $\widetilde{H}^q(\mathbb{Z}_1 \wedge \mathbb{Z}_2; \mathbb{Z}) = 0$ for any $q > C\mathcal{D}(\mathbb{Z}_1) + C\mathcal{D}(\mathbb{Z}_2)$. Note that if $q > C\mathcal{D}(\mathbb{Z}_1) + C\mathcal{D}(\mathbb{Z}_2)$ and $q = q_1 + q_2$ then $q_1 > C\mathcal{D}(\mathbb{Z}_1)$ or $q_2 > C\mathcal{D}(\mathbb{Z}_2)$. Therefore the reduced cross product

$$\times \colon \widetilde{H}^{q_1}(\mathcal{Z}_1;\mathbb{Z}) \otimes \widetilde{H}^{q_2}(\mathcal{Z}_2;\mathbb{Z}) \to \widetilde{H}^{q_1+q_2}(\mathcal{Z}_1 \wedge \mathcal{Z}_2;\mathbb{Z})$$

is an isomorphism of trivial groups, which completes the proof.

From now on, we assume that *H* is a closed subgroup of S^1 , i.e., $H \in \overline{sub}(S^1) = \{S^1, \mathbb{Z}_1, \mathbb{Z}_2, \ldots\}$. Let \mathbb{V} be an orthogonal representation of the group *H* with the isotypical decomposition

$$\mathbb{V} = \mathbb{R}[k_0, 0] \oplus \mathbb{R}[k_1, m_1] \oplus \ldots \oplus \mathbb{R}[k_p, m_p],$$

where $k_0 \in \mathbb{N} \cup \{0\}, k_1, \ldots, k_p \in \mathbb{N}$ and $m_1, \ldots, m_p \in \mathbb{N}$ (in the case $H = \mathbb{Z}_m$ we assume that $m_1, \ldots, m_p \in \{1, \ldots, m-1\}$), see Appendix for more details. If \mathbb{V} is a non-trivial *H*-representation, we denote $\widehat{\mathbb{V}} = \mathbb{R}[k_1, m_1] \oplus \ldots \oplus \mathbb{R}[k_p, m_p]$, otherwise we put $\widehat{\mathbb{V}} = \{0\}$. Note that $\mathbb{V} = \mathbb{R}[k_0, 0] \oplus \widehat{\mathbb{V}}$ and $\widehat{\mathbb{V}}$ is even-dimensional.

Denote by S^{\vee} the one-point compactification of \mathbb{V} . The space S^{\vee} has the *H*-homotopy type of a finite pointed *H*-CW-complex, see for instance [17].

Lemma 2.4. Let \mathbb{V} be an orthogonal H-representation. Then

- (1) if \mathbb{V} is a trivial *H*-representation, then $C\mathcal{D}(S^{\mathbb{V}}/H) = \dim \mathbb{V}$,
- (2) if \mathbb{V} is a non-trivial S^1 -representation such that dim $\mathbb{V} > 2$ or \mathbb{V} is an arbitrary non-trivial \mathbb{Z}_m representation, then

$$C\mathcal{D}(S^{\mathbb{V}}/H) = \begin{cases} \dim \mathbb{V} & \text{if } H = \mathbb{Z}_m, \\ \dim \mathbb{V} - 1 & \text{if } H = S^1, \end{cases}$$

(3) if \mathbb{V} is a non-trivial S^1 -representation such that dim $\widehat{\mathbb{V}} = 2$, then all the reduced cohomology groups $\widetilde{H}^k(S^{\mathbb{V}}/S^1)$ are trivial.

Proof. Let $H \in \overline{\text{sub}}(S^1)$. If \mathbb{V} is a trivial representation of H, i.e., $\mathbb{V} = \mathbb{R}[k_0, 0]$, then $S^{\mathbb{V}}/H \approx S^{k_0}$ and therefore $C\mathcal{D}(S^{\mathbb{V}}/H) = k_0$, which proves (1).

To prove (2) assume that \mathbb{V} is a non-trivial *H*-representation. Consider the unit sphere in $\widehat{\mathbb{V}}$, denoted by $S(\widehat{\mathbb{V}})$, and its unreduced suspension $\Sigma S(\widehat{\mathbb{V}})$. Note that $S^{\widehat{\mathbb{V}}} \approx \Sigma S(\widehat{\mathbb{V}})$ and $\Sigma(S(\widehat{\mathbb{V}}))/H = \Sigma(S(\widehat{\mathbb{V}})/H)$. By the suspension isomorphism of cohomology theory we obtain

$$\widetilde{H}^{k+1}(S^{\widehat{\mathbb{V}}}/H;\mathbb{Z}) = \widetilde{H}^{k+1}(\Sigma(S(\widehat{\mathbb{V}}))/H;\mathbb{Z}) = \widetilde{H}^{k+1}(\Sigma(S(\widehat{\mathbb{V}})/H);\mathbb{Z}) = \widetilde{H}^{k}(S(\widehat{\mathbb{V}})/H;\mathbb{Z})$$
(2.3)

for $k \ge 0$.

From Theorems 1 and 2 of [15] it follows that if \mathbb{V} is any non-trivial \mathbb{Z}_m -representation or an S^1 -representation such that dim $\widehat{\mathbb{V}} > 2$, then at least one of the cohomology groups $H^k(S(\widehat{\mathbb{V}})/H;\mathbb{Z})$ is non-trivial and therefore $C\mathcal{D}(S(\widehat{\mathbb{V}})/H)$ is well-defined. Moreover,

$$C\mathcal{D}(S(\widehat{\mathbb{V}})/H) = \begin{cases} \dim \widehat{\mathbb{V}} - 1 & \text{if } H = \mathbb{Z}_m, \\ \dim \widehat{\mathbb{V}} - 2 & \text{if } H = S^1. \end{cases}$$
(2.4)

Electronic Research Archive

Volume 30, Issue 5, 1691–1707.

By (2.3), $C\mathcal{D}(S^{\widehat{\mathbb{V}}}/H)$ is also well-defined and

$$C\mathcal{D}(S^{\mathbb{V}}/H) = C\mathcal{D}(S(\widehat{\mathbb{V}})/H) + 1.$$
(2.5)

Moreover,

$$S^{\mathbb{V}}/H = (S^{\widehat{\mathbb{V}} \oplus \mathbb{R}[k_0,0]})/H = (S^{\widehat{\mathbb{V}}} \wedge S^{k_0})/H = (S^{\widehat{\mathbb{V}}}/H) \wedge S^{k_0}$$

and $C\mathcal{D}(S^{k_0})$ is well-defined. Therefore the assumptions of Lemma 2.3 for $\mathcal{Z}_1 = S^{\widehat{\mathbb{V}}}/H$, $\mathcal{Z}_2 = S^{k_0}$ are satisfied. Hence

$$C\mathcal{D}(S^{\mathbb{V}}/H) = C\mathcal{D}((S^{\mathbb{V}}/H) \wedge S^{k_0}) = C\mathcal{D}(S^{\mathbb{V}}/H) + C\mathcal{D}(S^{k_0}) = C\mathcal{D}(S^{\mathbb{V}}/H) + k_0$$

This, combined with (2.4)-(2.5), completes the proof of (2).

Finally, to prove (3) notice that if \mathbb{V} is an S^1 -representation such that dim $\widehat{\mathbb{V}} = 2$, i.e., $\mathbb{V} = \mathbb{R}[k_0, 0] \oplus \mathbb{R}[1, m_1]$ for $k_0 \ge 0$, $m_1 \ge 1$, then $S^{\widehat{\mathbb{V}}}/S^1$ is contractible and therefore so is $S^{\mathbb{V}}/S^1 = (S^{\widehat{\mathbb{V}}}/S^1) \wedge S^{k_0}$ for $k_0 \ge 0$. Consequently all the reduced cohomology groups $\widetilde{H}^k(S^{\mathbb{V}}/S^1)$ are trivial.

We are now in a position to prove the main theorem of this section.

Theorem 2.5. Suppose that $H \in sub(S^1)$ and \mathbb{V}_1 , \mathbb{V}_2 are orthogonal H-representations. If one of the following conditions is satisfied:

(1) $H = \mathbb{Z}_m$ and $\dim \mathbb{V}_1 \neq \dim \mathbb{V}_2$, (2) $H = S^1$, $\dim \mathbb{V}_1 \neq \dim \mathbb{V}_2$ and additionally: (2.1) either $\dim \widehat{\mathbb{V}}_1$, $\dim \widehat{\mathbb{V}}_2 > 2$ (2.2) or $\dim \widehat{\mathbb{V}}_1 = \dim \widehat{\mathbb{V}}_2 = 0$,

(3) $H = S^1$, dim $\widehat{\mathbb{V}}_1 > 2$, dim $\widehat{\mathbb{V}}_2 = 0$ and dim $\mathbb{V}_1 - \dim \mathbb{V}_2 \neq 1$,

- (4) $H = S^1$, dim $\widehat{\mathbb{V}}_1 = 0$, dim $\widehat{\mathbb{V}}_2 > 2$ and dim $\mathbb{V}_2 \dim \mathbb{V}_1 \neq 1$,
- (5) $H = S^1$ and exactly one of the numbers dim $\widehat{\mathbb{V}}_1$, dim $\widehat{\mathbb{V}}_2$ is equal to 2,

then $\Gamma^+ \wedge_H S^{\mathbb{V}_1} \not\approx_{\Gamma} \Gamma^+ \wedge_H S^{\mathbb{V}_2}$, i.e., $\Gamma^+ \wedge_H S^{\mathbb{V}_1}$ and $\Gamma^+ \wedge_H S^{\mathbb{V}_2}$ are not Γ -homotopically equivalent.

Proof. Suppose that (1) is satisfied. From Lemma 2.4 it follows that $C\mathcal{D}(S^{\mathbb{V}_1}/\mathbb{Z}_m) \neq C\mathcal{D}(S^{\mathbb{V}_2}/\mathbb{Z}_m)$ and hence $S^{\mathbb{V}_1}/\mathbb{Z}_m \not\approx S^{\mathbb{V}_2}/\mathbb{Z}_m$. Therefore, by Lemma 2.2, $\Gamma^+ \wedge_{\mathbb{Z}_m} S^{\mathbb{V}_1} \not\approx_{\Gamma} \Gamma^+ \wedge_{\mathbb{Z}_m} S^{\mathbb{V}_2}$. The proof for (2) is analogous.

If (3) is fullfiled, then, by Lemma 2.4, $C\mathcal{D}(S^{\mathbb{V}_1}/S^1) = \dim \mathbb{V}_1 - 1$ and $C\mathcal{D}(S^{\mathbb{V}_2}/S^1) = \dim \mathbb{V}_2$. Hence, by the assumption, $C\mathcal{D}(S^{\mathbb{V}_1}/S^1) \neq C\mathcal{D}(S^{\mathbb{V}_2}/S^1)$. Reasoning similarly as in the previous case we prove the assertion. The proof in the case (4) is the same.

If (5) is satisfied, we can assume without loss of generality that dim $\widehat{\mathbb{V}}_1 = 2$ and dim $\widehat{\mathbb{V}}_2 \neq 2$. By Lemma 2.4, all the reduced cohomology groups $\widetilde{H}^k(S^{\mathbb{V}_1}/S^1;\mathbb{Z})$ are trivial and at least one of the groups $\widetilde{H}^k(S^{\mathbb{V}_2}/S^1;\mathbb{Z})$ is non-trivial. Hence $S^{\mathbb{V}_1}/S^1 \not\approx S^{\mathbb{V}_2}/S^1$ and, by Lemma 2.2, $\Gamma^+ \wedge_{S^1} S^{\mathbb{V}_1} \not\approx_{\Gamma} \Gamma^+ \wedge_{S^1} S^{\mathbb{V}_2}$. This completes the proof.

Remark 2.6. From the proof of Lemma 2.4 it follows that if \mathbb{V}_1 and \mathbb{V}_2 are orthogonal S^1 -representations such that $\dim \widehat{\mathbb{V}}_1 = \dim \widehat{\mathbb{V}}_2 = 2$, then $S^{\mathbb{V}_1}/S^1$ and $S^{\mathbb{V}_2}/S^1$ are contractible and consequently they are homotopically equivalent. Therefore in the case of such representations our method does not allow us to distinguish between the Γ -homotopy types of $\Gamma^+ \wedge_{S^1} S^{\mathbb{V}_1}$ and $\Gamma^+ \wedge_{S^1} S^{\mathbb{V}_2}$.

Electronic Research Archive

3. Proofs of Theorems 1.1 and 1.2

In this section we prove the symmetric Lyapunov center theorems formulated in Introduction, namely Theorems 1.1 and 1.2. We start with reviewing some classical facts on the variational setting for our problem. The material is standard and well known.

Assume that $\Omega \subset \mathbb{R}^N$ is an open and Γ -invariant subset of an orthogonal representation \mathbb{R}^N of a compact Lie group Γ and $U: \Omega \to \mathbb{R}$ is a Γ -invariant potential of class C^2 . Using the techniques of equivariant bifurcation theory we will study periodic solutions of the system (1.1).

It is well-known that instead of studying solutions of an arbitrary period, one can consider only 2π -periodic solutions of the parameterized system

$$\ddot{u}(t) = -\lambda^2 \nabla U(u(t)). \tag{3.1}$$

More precisely, by a standard change of variables, it can be shown that $2\pi\lambda$ -periodic solutions of (1.1) correspond to 2π -periodic solutions of (3.1). Moreover, in this case it is obvious that we can restrict the consideration of (3.1) to $\lambda \in (0, +\infty)$.

To reformulate the problem we consider a separable Hilbert space $(\mathbb{H}^1_{2\pi}, \langle \cdot, \cdot \rangle_{\mathbb{H}^1_{2\pi}})$, where

$$\mathbb{H}_{2\pi}^{1} = \{ u \colon [0, 2\pi] \to \mathbb{R}^{N} \colon u \text{ is abs. continuous, } u(0) = u(2\pi), \dot{u} \in L^{2}([0, 2\pi], \mathbb{R}^{N}) \}$$

and

$$\langle u, v \rangle_{\mathbb{H}^1_{2\pi}} = \int_0^{2\pi} (\dot{u}(t), \dot{v}(t)) + (u(t), v(t)) dt$$

With our assumptions, this space is an orthogonal representation of Γ , where the action is given by

$$\Gamma \times \mathbb{H}^1_{2\pi} \ni (\gamma, u) \mapsto \gamma u. \tag{3.2}$$

Additionally,

$$\mathbb{H}^1_{2\pi} = \mathbb{H}_0 \oplus \bigoplus_{k=1}^{\infty} \mathbb{H}_k,$$

where $\mathbb{H}_0 = \mathbb{R}^N$ and $\mathbb{H}_k = \{a \cos kt + b \sin kt : a, b \in \mathbb{R}^N\}$, for k > 0, are orthogonal representations of Γ .

For simplicity of notation from now on A stands for $\nabla^2 U(u_0)$. Denote by $\alpha_1, \ldots, \alpha_q$ the distinct eigenvalues of A and by $V_A(\alpha_1), \ldots, V_A(\alpha_q)$ the corresponding eigenspaces. Using the decomposition

$$\mathbb{R}^N = V_A(\alpha_1) \oplus \ldots \oplus V_A(\alpha_q)$$

we identify \mathbb{H}_k with

$$(V_A(\alpha_1) \oplus V_A(\alpha_1)) \oplus \ldots \oplus (V_A(\alpha_a) \oplus V_A(\alpha_a)).$$
(3.3)

Set $H = \Gamma_{u_0}$ and remind that $H \in \overline{\text{sub}}(S^1)$. It is known that since U is Γ -invariant, A is H-equivariant and therefore all the eigenspaces in (3.3) are H-representations. Taking into consideration (3.2) and formulas (4.1), (4.2), we conclude that there exist $p \ge 0$ and $k_0, \ldots, k_p \in \mathbb{N} \cup \{0\}, m_1, \ldots, m_p \in \mathbb{N}$ such that \mathbb{H}_k is H-equivalent to

$$\mathbb{R}[2k_0, 0] \oplus \mathbb{R}[2k_1, m_1] \oplus \mathbb{R}[2k_p, m_p]. \tag{3.4}$$

Electronic Research Archive

Now define a Γ -invariant functional $\Phi \colon \mathbb{H}^1_{2\pi} \times (0, +\infty) \to \mathbb{R}$ of class C^2 by the formula

$$\Phi(u,\lambda) = \int_0^{2\pi} \left(\frac{1}{2} ||\dot{u}(t)||^2 - \lambda^2 U(u(t))\right) \, dt.$$

Notice that 2π -periodic solutions of the system (3.1) can be considered as critical points of Φ and so we will study solutions of the following equation:

$$\nabla_u \Phi(u, \lambda) = 0. \tag{3.5}$$

Fix $u_0 \in (\nabla U)^{-1}(0)$ and define the constant function $\tilde{u}_0 \equiv u_0$. Then \tilde{u}_0 is a stationary solution of the system (3.1) for every $\lambda > 0$. Since $\Gamma(u_0) \subset (\nabla U)^{-1}(0)$, $\Gamma(\tilde{u}_0)$ consists of solutions of (3.1) for all $\lambda > 0$. In the rest of this section we use this notation, considering $\Gamma(u_0)$ as a set in \mathbb{R}^N and $\Gamma(\tilde{u}_0)$ in $\mathbb{H}^1_{2\pi}$. Consequently, we define the neighborhoods of these orbits in appropriate spaces, i.e., $\Gamma(u_0)_{\epsilon} = \bigcup_{u \in \Gamma(u_0)} B_{\epsilon}(\mathbb{R}^N, u) \subset \mathbb{R}^N$ and $\Gamma(\tilde{u}_0)_{\epsilon} = \bigcup_{u \in \Gamma(\tilde{u}_0)} B_{\epsilon}(\mathbb{H}^1_{2\pi}, u) \subset \mathbb{H}^1_{2\pi}$, where $B_{\epsilon}(\mathbb{V}, u)$ denotes the open ball in the space \mathbb{V} , of radius ϵ , centered at u.

Now define $\mathcal{T} = \Gamma(\tilde{u}_0) \times (0, +\infty) \subset \mathbb{H}^1_{2\pi} \times (0, +\infty)$. The elements of this family are called the trivial solutions of (3.5), whereas the elements of the set

$$\mathcal{N} = \{(u, \lambda) \in \mathbb{H}^1_{2\pi} \times (0, +\infty) \setminus \mathcal{T} : \nabla_u \Phi(u, \lambda) = 0\}$$

are called the non-trivial solutions. We will study the existence of local bifurcations of non-trivial solutions of Eq (3.5) from \mathcal{T} , and so let us first introduce the notion of a local bifurcation.

Definition 3.1. Fix $\lambda_0 > 0$. The orbit $\Gamma(\tilde{u}_0) \times \{\lambda_0\} \subset \mathcal{T}$ is called an orbit of local bifurcation of solutions of (3.5) if $\Gamma(\tilde{u}_0) \times \{\lambda_0\} \subset cl(\mathcal{N})$.

Remark 3.2. From the above definition it follows that if the orbit $\Gamma(\tilde{u}_0) \times \{\lambda_0\}$ is an orbit of local bifurcation, then there exists a sequence (u_k, λ_k) in \mathcal{N} such that $\lambda_k \to \lambda_0$ and u_k is a 2π -periodic solution of (3.1), corresponding to $\lambda = \lambda_k$, where for all $\epsilon > 0$ there is $k_0 \in \mathbb{N}$ such that $u_k \in \Gamma(\tilde{u}_0)_{\epsilon}$ for $k \ge k_0$. Moreover, since the orbit $\Gamma(u_0)$ is isolated in the set of critical points of the potential U, for ϵ sufficiently small the obtained subsequence consists of non-stationary 2π -periodic solutions.

Remark 3.3. To prove Theorems 1.1 and 1.2 we use the fact (see Lemma 3.1 of [12]) that the existence of a local bifurcation in the function space implies the existence of a local bifurcation in the phase space. More precisely, the existence of a local bifurcation of solutions of (3.5) from the Γ -orbit $\Gamma(\tilde{u}_0) \times$ $\{\lambda_0\} \subset \mathcal{T}$ implies the existence of a sequence (u_k) of periodic solutions of the system (1.1) with a sequence (T_k) of (not necessarily minimal) periods such that $T_k \to 2\pi\lambda_0$ and for any $\epsilon > 0$ there exists $k_0 \in \mathbb{N}$ such that $u_k([0, T_k]) \subset \Gamma(u_0)_{\epsilon}$ for all $k \ge k_0$.

To formulate the necessary condition of a local bifurcation we use the following result given in [10]: the orbit $\Gamma(\tilde{u}_0) \times \{\lambda_0\}$ can be an orbit of local bifurcation only if

$$\ker \nabla_u^2 \Phi(\tilde{u}_0, \lambda_0) \cap \bigoplus_{k=1}^{\infty} \mathbb{H}_k \neq \emptyset,$$

Electronic Research Archive

i.e., if the kernel is not fully contained in \mathbb{H}_0 . The description of ker $\nabla_u^2 \Phi(\tilde{u}_0, \lambda_0)$ can be obtained with the use of the formulas characterizing the action of such an operator on subrepresentations \mathbb{H}_k given in Lemma 5.1.1 of [18]. From this lemma it follows that

$$\sigma(\nabla_u^2 \Phi(\tilde{u}_0, \lambda)) = \left\{ \frac{k^2 - \lambda^2 \alpha}{k^2 + 1} \colon \alpha \in \sigma(\nabla^2 U(u_0)), k = 0, 1, 2, \ldots \right\}.$$
(3.6)

Recall that $\mathcal{B} = \{\beta_1, \beta_2, \dots, \beta_q\}$, where $\beta_1 > \beta_2 > \dots > \beta_q > 0$ are such that $\sigma^+(\nabla^2 U(u_0)) = \{\beta_1^2, \dots, \beta_q^2\}$. Put $\Lambda = \{\frac{k}{\beta} : k \in \mathbb{N}, \beta \in \mathcal{B}\}$. Then we have:

Fact 3.4. If $\Gamma(\tilde{u}_0) \times \{\lambda_0\}$ is an orbit of local bifurcation of solutions of (3.5) then $\lambda_0 \in \Lambda$.

To obtain the sufficient condition we use Izydorek's version of the Conley index, see Appendix for the definition. For $\lambda \notin \Lambda$ from Fact 3.4 it follows that the orbit $\Gamma(\tilde{u}_0)$ is isolated in $(\nabla \Phi(\cdot, \lambda))^{-1}(0)$. Since the operator is a gradient one, this orbit is an isolated invariant set of the flow generated by $-\nabla_u \Phi(\cdot, \lambda)$, i.e., it is an isolated invariant set in the sense of the Conley index theory. Hence the Conley index $CI_{\Gamma}(\Gamma(\tilde{u}_0), -\nabla_u \Phi(\cdot, \lambda))$ is well-defined for $\lambda \notin \Lambda$. From the continuation property it follows that if there is a change of this index then there occurs a local bifurcation, see [13]. More precisely, there holds the following theorem.

Theorem 3.5. Let $\lambda_0 \in \Lambda$. If λ_- , λ_+ are such that $[\lambda_-, \lambda_+] \cap \Lambda = \{\lambda_0\}$ and

$$CI_{\Gamma}(\Gamma(\tilde{u}_0), -\nabla_u \Phi(\cdot, \lambda_-)) \neq CI_{\Gamma}(\Gamma(\tilde{u}_0), -\nabla_u \Phi(\cdot, \lambda_+)),$$
(3.7)

then $\Gamma(\tilde{u}_0) \times \{\lambda_0\}$ is an orbit of local bifurcation of solutions of (3.5).

Remark 3.6. Note that from Remark 3.3 and Fact 3.4 it follows that the periods of solutions of (1.1) in the bifurcating sequences have to converge to $2\pi_{\beta}^{k}$, where $\frac{k}{\beta} \in \Lambda$. However, these periods do not have to be minimal. On the other hand, if we consider bifurcations from the orbits of the form $\Gamma(\tilde{u}_{0}) \times \{\frac{1}{\beta_{j_{0}}}\}$, where $\beta_{j_{0}} \in \mathcal{B}$ satisfies the nonresonance condition $\beta_{j}/\beta_{j_{0}} \notin \mathbb{N}$ for $\beta_{j} \in \mathcal{B} \setminus \{\beta_{j_{0}}\}$, then the obtained periods are minimal. Therefore to prove the assertions of Theorems 1.1 and 1.2 we restrict our attention to such orbits.

Now we are in a position to prove the main results of our article, namely Theorems 1.1 and 1.2.

3.1. Proof of Theorem 1.1

To prove the assertion we study local bifurcations from the levels satisfying the necessary condition given in Fact 3.4. From Remark 3.6 it follows that we can restrict our attention to the set $\Lambda_0 \subset \Lambda$, where

$$\Lambda_0 = \left\{ \frac{1}{\beta_{j_0}} : \beta_{j_0} \in \mathcal{B} \text{ and } \beta_{j_0} \text{ satisfies } (A1) \text{ and } (A2) \right\}.$$
(3.8)

Obviously, if the assumptions of Theorem 1.1 are satisfied, this set is nonempty.

Fix $\lambda_0 = \frac{1}{\beta_{j_0}} \in \Lambda_0$. By the definition of Λ , there exists $\varepsilon > 0$ such that $[\lambda_0 - \varepsilon, \lambda_0 + \varepsilon] \cap \Lambda = {\lambda_0}$. Put $\lambda_{\pm} = \lambda_0 \pm \varepsilon$. Then, since $\lambda_{\pm} \notin \Lambda$, the Conley indices $CI_{\Gamma}(\Gamma(\tilde{u}_0), -\nabla_u \Phi(\cdot, \lambda_{\pm}))$ are well-defined.

By Theorem 3.5, to prove our assertion it is enough to show that the inequality (3.7) holds. Note that $\nabla \Phi(\cdot, \lambda_{\pm})$ are of the form of completely continuous perturbations of the identity and therefore

completely continuous perturbations of linear, bounded, Fredholm, self adjoint operators $\nabla_u^2 \Phi(\tilde{u}_0, \lambda_{\pm})$. From the definition of the equivariant Conley index (see [13] or Subsection 4.2 of Appendix), $CI_{\Gamma}(\Gamma(\tilde{u}_0), -\nabla_u \Phi(\cdot, \lambda_{\pm}))$ are the Γ -homotopy types of Γ -spectra of the types $(\mathbb{H}_{n+1,\pm}^+)_{n=0}^{\infty}$, where $\mathbb{H}_{n+1,\pm}^+$ are the direct sums of eigenspaces of $-\nabla_u^2 \Phi(\tilde{u}_0, \lambda_{\pm})_{|\mathbb{H}_{n+1}}$ corresponding to the positive eigenvalues. Since $\nabla_u^2 \Phi(\tilde{u}_0, \lambda_{\pm}) = Id - \mathcal{L}_{\pm}$ with \mathcal{L}_{\pm} being linear, compact and self adjoint operators, by the spectral theorem for compact operators it follows that the eigenvalues of $-\nabla_u^2 \Phi(\tilde{u}_0, \lambda_{\pm})$ converge to -1. Consequently, for *n* sufficiently large, $\mathbb{H}_{n+1,\pm}^+ = \emptyset$ and the sequences of Γ -CW-complexes $CI_{\Gamma}(\Gamma(\tilde{u}_0), -\nabla_u \Phi^n(\cdot, \lambda_{\pm}))$ stabilize, where $\Phi^n = \Phi_{|\mathbb{H}^n \times \mathbb{R}}$. Therefore, the condition (3.7) is equivalent to

$$CI_{\Gamma}(\Gamma(\tilde{u}_0), -\nabla_u \Phi^n(\cdot, \lambda_-)) \neq CI_{\Gamma}(\Gamma(\tilde{u}_0), -\nabla_u \Phi^n(\cdot, \lambda_+))$$
(3.9)

for *n* sufficiently large. In the following we assume that such *n* is fixed.

Consider $T_{u_0}^{\perp}\Gamma(u_0)$ - the space normal to the orbit $\Gamma(u_0)$ at u_0 in \mathbb{R}^N . Identifying \mathbb{H}_0 with \mathbb{R}^N , we write $\mathbb{W}^n = T_{u_0}^{\perp}\Gamma(u_0) \oplus \bigoplus_{k=1}^n \mathbb{H}_k$ for the normal space to $\Gamma(\tilde{u}_0)$ in $\bigoplus_{k=0}^n \mathbb{H}_k$. Put $\Psi_{\pm}^n = \Phi^n(\cdot, \lambda_{\pm})_{|\mathbb{W}^n} \colon \mathbb{W}^n \to \mathbb{R}$. It is known that the space \mathbb{W}^n and the functionals Ψ_{\pm}^n are *H*-invariant. Moreover, the set $\{\tilde{u}_0\}$ is isolated in $(\nabla \Psi_{\pm}^n)^{-1}(0)$, and so $\{\tilde{u}_0\}$ is an isolated invariant set in the sense of the Conley index. Therefore, the Conley indices $CI_H(\{\tilde{u}_0\}, -\nabla \Psi_{\pm}^n)$ are well-defined. Furthermore, by Theorem 4.3 we have

$$CI_{\Gamma}(\Gamma(\tilde{u}_0), -\nabla_u \Phi^n(\cdot, \lambda_{\pm})) = \Gamma^+ \wedge_H CI_H(\{\tilde{u}_0\}, -\nabla \Psi^n_{\pm}).$$
(3.10)

Therefore to study inequality (3.9) we will first investigate the indices $CI_H(\{\tilde{u}_0\}, -\nabla \Psi_{\pm}^n)$ and then apply the abstract results from the previous section.

Since \tilde{u}_0 is a non-degenerate critical point of Ψ^n_{\pm} , we can apply Remark 4.2 to conclude that these indices are the homotopy types of $S^{(\mathbb{W}^n_{\pm})^+}$, where $(\mathbb{W}^n_{\pm})^+$ is the direct sum of eigenspaces of $-\nabla^2 \Psi^n_{\pm}(\tilde{u}_0)$ corresponding to the positive eigenvalues. Therefore we study the spectral decompositions of \mathbb{W}^n given by the isomorphisms $-\nabla^2 \Psi^n_{\pm}(\tilde{u}_0)$.

Note that for both operators, \mathbb{W}^n can be decomposed as

$$\mathbb{W}^n = \mathbb{H}_1 \oplus \Big(T_{u_0}^{\perp} \Gamma(u_0) \oplus \bigoplus_{k=2}^n \mathbb{H}_k \Big).$$

Observe that the direct sum of the eigenspaces corresponding to the positive eigenvalues of $-\nabla^2 \Psi^n_{\pm}(\tilde{u}_0)_{|\mathbb{H}_k}$ is $\mathbb{H}^+_{k,\pm}$. Analogously, as an appropriate direct sum of the eigenspaces, we can define $(T^{\perp}_{u_0}\Gamma(u_0))^+_{\pm}$. Moreover the description of these spaces can be obtained in the same way as formula (3.6). More precisely, from Lemma 5.1.1 of [18] we obtain that the action of $-\nabla^2 \Psi^n_{\pm}(\tilde{u}_0)$ on $u(t) = a_k \cos kt + b_k \sin kt \in \mathbb{H}_k$ is given by

$$-\nabla^2 \Psi^n_{\pm}(\tilde{u}_0)(u(t)) = -\left(\frac{k^2}{k^2+1}Id - \frac{1}{k^2+1}\lambda^2_{\pm}A\right)a_k\cos kt - \left(\frac{k^2}{k^2+1}Id - \frac{1}{k^2+1}\lambda^2_{\pm}A\right)b_k\sin kt.$$

Therefore, using (3.3) we obtain that for $k \ge 0$

$$\mathbb{H}^+_{k,\pm} = \bigoplus_{\beta_j^2 > \frac{k^2}{\lambda_{\pm}^2}} \left(V_A(\beta_j^2) \oplus V_A(\beta_j^2) \right).$$

Electronic Research Archive

In particular, from the definition of λ_{\pm} it follows that

$$\begin{split} \mathbb{H}_{1,-}^{+} &= \bigoplus_{\beta_{j}^{2} > \beta_{j_{0}}^{2}} \left(V_{A}(\beta_{j}^{2}) \oplus V_{A}(\beta_{j}^{2}) \right), \\ \mathbb{H}_{1,+}^{+} &= \bigoplus_{\beta_{j}^{2} \ge \beta_{j_{0}}^{2}} \left(V_{A}(\beta_{j}^{2}) \oplus V_{A}(\beta_{j}^{2}) \right) = \mathbb{H}_{1,-}^{+} \oplus \left(V_{A}(\beta_{j_{0}}^{2}) \oplus V_{A}(\beta_{j_{0}}^{2}) \right) \end{split}$$

Moreover $(T_{u_0}^{\perp}\Gamma(u_0))_{-}^{+} = (T_{u_0}^{\perp}\Gamma(u_0))_{+}^{+}$ and $\mathbb{H}_{k,-}^{+} = \mathbb{H}_{k,+}^{+}$ for $k \ge 2$.

Put $\mathcal{V} = V_A(\beta_{j_0}^2) \oplus V_A(\beta_{j_0}^2)$. If $H = S^1$, then by $\widehat{\mathcal{V}}$ we denote the orthogonal complement of \mathcal{V}^{S^1} in \mathcal{V} , where \mathcal{V}^{S^1} is the set of fixed points of the S^1 -action on \mathcal{V} . By the assumption (A2) of our theorem we have dim $\widehat{\mathcal{V}} \ge 4$.

Therefore we obtain

Put `

$$(\mathbb{W}_{-}^{n})^{+} = (T_{u_{0}}^{\perp}\Gamma(u_{0}))_{-}^{+} \oplus \left(\bigoplus_{k=2}^{n} \mathbb{H}_{k,-}^{+}\right) \oplus \mathbb{H}_{1,-}^{+},$$

$$(\mathbb{W}_{+}^{n})^{+} = (T_{u_{0}}^{\perp}\Gamma(u_{0}))_{+}^{+} \oplus \left(\bigoplus_{k=2}^{n} \mathbb{H}_{k,+}^{+}\right) \oplus \mathbb{H}_{1,+}^{+} = (T_{u_{0}}^{\perp}\Gamma(u_{0}))_{-}^{+} \oplus \left(\bigoplus_{k=2}^{n} \mathbb{H}_{k,-}^{+}\right) \oplus \mathbb{H}_{1,-}^{+} \oplus \mathcal{V}.$$

$$\mathbb{V}_{1} = (T_{u_{0}}^{\perp}\Gamma(u_{0}))_{-}^{+} \oplus \left(\bigoplus_{k=2}^{n} \mathbb{H}_{k,-}^{+}\right) \oplus \mathbb{H}_{1,-}^{+}. \text{ Summing up,}$$

$$CI_{H}(\{\tilde{u}_{0}\}, -\nabla \Psi_{-}^{n}) = S^{\mathbb{V}_{1}}, \quad CI_{H}(\{\tilde{u}_{0}\}, -\nabla \Psi_{+}^{n}) = S^{\mathbb{V}_{1} \oplus \mathcal{V}}$$

and the representations \mathbb{V}_1 and $\mathbb{V}_2 = \mathbb{V}_1 \oplus \mathcal{V}$ satisfy the assumptions of Theorem 2.5 (in the case $H = S^1$ we take into consideration that dim $\widehat{\mathcal{V}} \ge 4$). Hence

$$\Gamma^+ \wedge_H S^{\mathbb{V}_1} \not\approx_{\Gamma} \Gamma^+ \wedge_H S^{\mathbb{V}_1 \oplus \mathcal{V}}.$$

Applying formula (3.10) we obtain that inequality (3.9) holds, which completes the proof.

3.2. Proof of Theorem 1.2

Throughout this proof we use the notation of the one of Theorem 1.1. As in that proof, to show the assertion we will study local bifurcations from the orbit $\Gamma(\tilde{u}_0) \times \{\lambda_0\}$ for a fixed $\lambda_0 \in \Lambda_0$, where Λ_0 is defined by (3.8). To this end we will apply an equivariant version of the so called splitting lemma, see for instance Lemma 3.2 of [18].

As in the previous proof, our aim is to study inequality (3.9), so we again investigate the indices $CI_H(\{\tilde{u}_0\}, -\nabla \Psi^n_{\pm})$. We first shift the critical point \tilde{u}_0 to the origin, i.e., we consider *H*-invariant maps $\Pi^n_{\pm} : \mathbb{W}^n \to \mathbb{R}$ given by $\Pi^n_{\pm}(u) = \Psi^n_{\pm}(u + \tilde{u}_0)$. Then

$$CI_{H}(\{\tilde{u}_{0}\}, -\nabla \Psi_{+}^{n}) = CI_{H}(\{0\}, -\nabla \Pi_{+}^{n}).$$

It is easy to observe that ker $\nabla^2 \Pi_{-}^n(0) = \ker \nabla^2 \Pi_{+}^n(0)$ and im $\nabla^2 \Pi_{-}^n(0) = \operatorname{im} \nabla^2 \Pi_{+}^n(0)$, for simplicity we denote these spaces respectively by \mathcal{N} and \mathcal{R} . Note that from the definition of λ_{\pm} we obtain $\mathcal{N} \subset \mathbb{H}_0$.

Electronic Research Archive

Put $\mathcal{A}_{\pm} = (\nabla^2 \Pi^n_{\pm}(0))_{|\mathcal{R}}$ and note that \mathcal{A}_{\pm} are isomorphisms. Applying the splitting lemma we get *H*invariant maps $\varphi_{\pm} \colon \mathcal{N} \to \mathbb{R}$ and *H*-invariant homotopies between $\nabla \Pi_{\pm}^{n}$ and $(\nabla \varphi_{\pm}, \mathcal{A}_{\pm})$, with {0} being an isolated invariant set at all levels of these homotopies. Applying the continuation property of the Conley index we obtain

$$CI_H(\{0\}, -\nabla \Pi^n_{\pm}) = CI_H(\{0\}, (-\nabla \varphi_{\pm}, -\mathcal{A}_{\pm})).$$

Reasoning as in the proof of Lemma 3.3.1 of [10] one can prove that $0 \in \mathcal{N}$ is an isolated critical point (more precisely: an isolated local maximum) of φ_{\pm} . Therefore {0} is an isolated invariant set for the flows generated by $-\nabla \varphi_{\pm}$. Moreover, since $-\mathcal{A}_{\pm}$ are isomorphisms, {0} is also an isolated invariant set for the flows generated by these operators. Hence we can apply the product formula (see Theorem 4.1) and obtain

$$CI_H(\{0\}, (-\nabla\varphi_{\pm}, -\mathcal{A}_{\pm})) = CI_H(\{0\}, -\nabla\varphi_{\pm}) \wedge CI_H(\{0\}, -\mathcal{A}_{\pm}).$$

$$(3.11)$$

Moreover, reasoning as in the proof of Lemma 2.2 of [12], we get

$$CI_H(\{0\}, -\nabla \varphi_{\pm}) = S^N$$

To find the latter factor in (3.11) consider $\mathbb{V} = ((T_{u_0}^{\perp}\Gamma(u_0) \ominus \mathcal{N}) \oplus \bigoplus_{k=2}^n \mathbb{H}_k$ and the subspace \mathbb{V}_{\pm}^+ being the direct sum of the eigenspaces of $-(\mathcal{A}_{\pm})_{\mathbb{V}}$ corresponding to the positive eigenvalues. Then, as in the proof of Theorem 1.1,

$$CI_H(\{0\}, -\mathcal{A}_{\pm}) = S^{\mathbb{V}_{\pm}^+ \oplus \mathbb{H}_{1,\pm}^+}$$

and $\mathbb{H}_{1,+}^+ = \mathbb{H}_{1,-}^+ \oplus \left(V_A(\beta_{i_0}^2) \oplus V_A(\beta_{i_0}^2) \right)$ and $\mathbb{V}_+^+ = \mathbb{V}_-^+$. Hence

$$CI_{H}(\{0\}, -\nabla\Pi_{\pm}^{n}) = S^{\mathcal{N}} \wedge S^{\mathbb{V}_{\pm}^{+} \oplus \mathbb{H}_{1,\pm}^{+}} = S^{\mathcal{N} \oplus \mathbb{V}_{\pm}^{+} \oplus \mathbb{H}_{1,\pm}^{+}}$$

As in the proof of Theorem 1.1, by Theorem 2.5 we obtain

$$\Gamma^+ \wedge_H (S^{\mathcal{N} \oplus \mathbb{V}^+_{\pm} \oplus \mathbb{H}^+_{1,-}}) \not\approx_{\Gamma} \Gamma^+ \wedge_H (S^{\mathcal{N} \oplus \mathbb{V}^+_{\pm} \oplus \mathbb{H}^+_{1,+}}).$$

Applying the equality (3.10) and Theorem 3.5 we finish the proof.

3.3. Final remarks and open questions

We finish this paper with some remarks.

Remark 3.7. One can prove Theorems 1.1 and 1.2 (the proof is litterally the same), if $\Gamma_{u_0} = S^1$ and the assumption (A2) is replaced by one of the following conditions:

- 1. $(\mathbb{R}^N)^{S^1} = \{0\},\$
- 2. $V_A(\beta_j^2)$ are trivial S¹-representations for every $\beta_j \in \mathcal{B}$,
- 3. $V_A(\beta_{j_0}^2)$ is a trivial S¹-representation and one of the following assumptions is fullfilled:
 - (a) there exists $\beta_j \in \mathcal{B}$ such that $\beta_j^2 > \beta_{j_0}^2$ and $V_A(\beta_j^2)$ is a non-trivial S¹-representation,
 - (b) there exists $\beta_j \in \mathcal{B}$ such that $V_A(\beta_i^2)$ is a non-trivial S¹-representation and dim $\widehat{V_A(\beta_i^2)} > 2$, where $\widehat{V_A(\beta_j^2)}$ is the orthogonal complement of $(V_A(\beta_j^2))^{S^1}$ in $V_A(\beta_j^2)$, (c) there exist $\beta_{j_1}, \beta_{j_2} \in \mathcal{B}, \ \beta_{j_1}^2 \neq \beta_{j_2}^2$, such that $V_A(\beta_{j_1}^2), \ V_A(\beta_{j_2}^2)$ are non-trivial S^1 -
 - representations.

Electronic Research Archive

Remark 3.8. Taking into consideration the assumption (1) of Theorems 1.1 and 1.2 the following question seems to be interesting: are the counterparts of these theorems true for Γ_{u_0} being any closed subgroup of the Lie group Γ ? As far as we know, this question is at present far from being solved.

Remark 3.9. In the assertions of our theorems we obtain the existence of sequences of non-stationary periodic solutions of system (1.1) emanating from the orbit. An interesting question is as follows: under the assumptions of these theorems, does it emanate a connected set of such solutions? It is known, that the branching of connected sets can be obtained via a suitable degree theory. Therefore a natural approach to answer this question is to use the relationship between the equivariant Conley index and the degree for equivariant gradient maps, see [19]. However, this problem is a little bit delicate, since in general a change of the equivariant Conley index does not imply a change of the degree for equivariant gradient maps. That is why the further study of the obtained degree is needed. Another approach is to apply the theory of the index of an orbit defined via the degree, see [20], [21].

Remark 3.10. It is well-known that $\mathbb{H}^1_{2\pi}$ is an orthogonal representation of the group S^1 with the action given by shift in time. Therefore, with the action of Γ described above, it can also be considered as a $(\Gamma \times S^1)$ -representation. However, in our paper we study bifurcations from orbits of constant solutions. In such a case the $(\Gamma \times S^1)$ -orbit is the same as the Γ -orbit, i.e., $(\Gamma \times S^1)(\tilde{u}_0) \approx \Gamma(\tilde{u}_0)$. Using our method and considering additionally the S^1 -action one cannot obtain any additional information. Hence, for simplicity of computation, we restrict our attention to the action of the group Γ .

4. Appendix

4.1. Representations of S^1 and \mathbb{Z}_m .

In this subsection we give a description of finite-dimensional orthogonal real representations of S^1 and \mathbb{Z}_m and recall the definitions of the two topological objects which we use to prove our abstract results.

Let $l \in \mathbb{N}$ and consider a two-dimensional S^1 -representation (denoted by $\mathbb{R}[1, l]$) with the action of the group S^1 given by $(e^{i\phi}, (x, y)) \mapsto \Phi(\phi)^l(x, y)^T = \Phi(l \cdot \phi)(x, y)^T$, where

$$\Phi(\phi) = \begin{bmatrix} \cos \phi & -\sin \phi \\ \sin \phi & \cos \phi \end{bmatrix}$$

For $k, l \in \mathbb{N}$ we will denote by $\mathbb{R}[k, l]$ the direct sum of k copies of $\mathbb{R}[1, l]$ and additionally by $\mathbb{R}[k, 0]$ the trivial k-dimensional S^1 -representation. It is known that if \mathbb{V} is a finite-dimensional orthogonal S^1 -representation, then there exist finite sequences $(k_i), (m_i)$ such that $k_0 \in \mathbb{N} \cup \{0\}, k_i, m_i \in \mathbb{N}$ and \mathbb{V} is equivalent to

$$\mathbb{R}[k_0, 0] \oplus \mathbb{R}[k_1, m_1] \oplus \ldots \oplus \mathbb{R}[k_p, m_p], \tag{4.1}$$

see [22].

Analogously, when no confusion can arise, for $l \in \{1, ..., m-1\}$ we denote by $\mathbb{R}[1, l]$ the twodimensional irreducible representation of the finite cyclic group \mathbb{Z}_m with the action $(e^{i\frac{2\pi k}{m}}, (x, y)) \mapsto \Phi(\frac{2\pi k}{m})^l(x, y)^T$ and by $\mathbb{R}[k, 0]$ the trivial k-dimensional \mathbb{Z}_m -representation. As before, $\mathbb{R}[k, l]$ is the direct sum of k copies of $\mathbb{R}[1, l]$. It is known that if \mathbb{V} is a finite-dimensional orthogonal \mathbb{Z}_m -representation, then \mathbb{V} is equivalent to

$$\mathbb{R}[k_0, 0] \oplus \mathbb{R}[k_1, m_1] \oplus \ldots \oplus \mathbb{R}[k_p, m_p], \tag{4.2}$$

Electronic Research Archive

where $k_0 \in \mathbb{N} \cup \{0\}, k_1, \dots, k_p \in \mathbb{N}, m_1, \dots, m_p \in \{1, \dots, m-1\}$, see [22].

If now \mathbb{V} is an S^1 -representation without non-trivial fixed points, i.e., such that $k_0 = 0$ in (4.1), then the orbit space $S(\mathbb{V})/S^1$ of the action of S^1 on the sphere $S(\mathbb{V})$ is called the twisted projective space. Similarly if \mathbb{V} is a \mathbb{Z}_m -representation such that $k_0 = 0$ in (4.2), then the orbit space $S(\mathbb{V})/\mathbb{Z}_m$ is called the lens complex.

Note that we use in this article results of Kawasaki from [15] and therefore the above terminology is taken from this paper. However, these topological spaces are also known by different names - the twisted projective space is called the weighted projective space and the lens complex is known as the weighted lens space.

4.2. Equivariant Conley index

In this subsection we introduce the basic notion of the equivariant Conley index. We start with the finite-dimensional case, for a more complete exposition we refer to [23, 24].

As before, we denote by Γ a compact Lie group. Let \mathbb{V} be a real finite-dimensional orthogonal Γ -representation and $\varphi \colon \mathbb{V} \to \mathbb{R}$ a Γ -invariant map of class C^2 . Suppose that *S* is an isolated invariant set of the flow generated by $-\nabla \varphi$. In such a situation the Conley index of *S* is defined (see [23,24]) as the Γ -homotopy type of a pointed Γ -CW-complex. We denote it by $CI_{\Gamma}(S, -\nabla \varphi)$.

The equivariant Conley index has all the properties of the classical (non-equivariant) index given in [25]. For the convenience of the reader we recall some of them, particularly important in the proofs of our results. We start with the product formula.

Theorem 4.1. Let S_i , for i = 1, 2, be isolated Γ -invariant sets for the Γ -flows generated by $-\nabla \varphi_i \colon \mathbb{V}_i \to \mathbb{V}_i$ which are Γ -equivariant maps of class C^1 and \mathbb{V}_i are real finite-dimensional orthogonal Γ -representations. Then

$$CI_{\Gamma}(S_1 \times S_2, (-\nabla \varphi_1, -\nabla \varphi_2)) = CI_{\Gamma}(S_1, -\nabla \varphi_1) \wedge CI_{\Gamma}(S_2, -\nabla \varphi_2).$$

In the case of an isolated invariant set containing only a non-degenerate critical point the Conley index has a relatively simple structure. Namely, analogously as in the non-equivariant case (see [26]), we have the following:

Remark 4.2. Suppose that $\varphi \colon \mathbb{V} \to \mathbb{R}$ is a Γ -invariant map of class C^2 and suppose that $x_0 \in \mathbb{V}$ is an isolated non-degenerate critical point of φ . Then $CI_{\Gamma}(\{x_0\}, -\nabla\varphi)$ is the Γ -homotopy type of $S^{\mathbb{V}^+}$, where \mathbb{V}^+ is the direct sum of eigenspaces of $-\nabla^2 \varphi(x_0)$ corresponding to the positive eigenvalues.

In a more general case of the isolated invariant set containing an isolated critical orbit, there is a relation between the Γ -indices of this orbit and a critical point of the restriction, see Theorem 2.4.2 of [10]. The relation is given in terms of the smash product over the stabilizer of this critical point. For the convenience of the reader we recall it in the next theorem.

Theorem 4.3. Suppose that $\varphi \colon \mathbb{V} \to \mathbb{R}$ is a Γ -invariant map of class C^2 and the orbit $\Gamma(x_0) \subset (\nabla \varphi)^{-1}(0)$ is isolated. Define $\psi = \varphi_{|T_{10}^{\perp}\Gamma(x_0)}$. Then

$$CI_{\Gamma}(\Gamma(x_0), -\nabla \varphi) = \Gamma^+ \wedge_{\Gamma_{x_0}} CI_{\Gamma_{x_0}}(\{x_0\}, -\nabla \psi).$$

Let us now consider the infinite-dimensional case. First we recall the notion of a Γ -spectrum. Let $\xi = (\mathbb{V}_n)_{n=0}^{\infty}$ be a sequence of finite-dimensional orthogonal representations of the group Γ . The pair

 $\mathcal{E} = ((\mathcal{E}_n)_{n=n(\mathcal{E})}^{\infty}, (\epsilon_n)_{n=n(\mathcal{E})}^{\infty})$ is called a Γ -spectrum of the type ξ if, for every $n \ge n(\mathcal{E})$, \mathcal{E}_n is a finite pointed Γ -CW-complex, $\epsilon_n : S^{\mathbb{V}_n} \wedge \mathcal{E}_n \to \mathcal{E}_{n+1}$ is a morphism and there exists $n_0 > n(\mathcal{E})$ such that ϵ_n is a Γ -homotopy equivalence for $n \ge n_0$.

The equivariant Conley index in the infinite-dimensional situation has been defined by Izydorek, see [13], as the Γ -homotopy type of a Γ -spectrum. Izydorek's definition is given for a general \mathcal{LS} -flow. Since in our paper we do not need the equivariant Conley index in the general case, we will briefly sketch the definition in the simplified situation, appropriate in our applications.

Consider an infinite-dimensional separable Hilbert space \mathbb{H} which is an orthogonal representation of Γ . Let $\Phi : \mathbb{H} \to \mathbb{R}$ be a functional of the form $\Phi(u) = \frac{1}{2} \langle Lu, u \rangle - K(u)$ such that *L* is a linear, bounded, self adjoint, Fredholm and Γ -equivariant operator and ∇K is a Γ -equivariant completely continuous operator of class C^1 .

Suppose that $\mathbb{H} = \overline{\bigoplus_{k=0}^{\infty} \mathbb{H}_k}$, where \mathbb{H}_k are disjoint orthogonal finite-dimensional representations of Γ such that $\mathbb{H}_0 = \ker L$ and $L(\mathbb{H}_k) = \mathbb{H}_k$ for every k. Suppose that S is an isolated invariant set of the flow generated by $-\nabla\Phi$ and put $\mathbb{H}^n = \bigoplus_{k=0}^n \mathbb{H}_k$. If O is an isolating Γ -neighborhood of S, then $O \cap \mathbb{H}^n$ is an isolating Γ -neighborhood for the flow generated by $-\nabla\Phi_{\mathbb{H}^n}$ for n sufficiently large. Denote by S_n the maximal invariant subset in $O \cap \mathbb{H}^n$ and consider $\mathcal{E}_n = CI_{\Gamma}(S_n, -\nabla\Phi_{\mathbb{H}^n})$. Then the Conley index of S, denoted as in the finite-dimensional case by $CI_{\Gamma}(S, -\nabla\Phi)$, is defined as the Γ -homotopy type of a Γ -spectrum ($\mathcal{E}_n, \epsilon_n$) of the type (\mathbb{H}_{n+1}^+) $_{n=0}^{\infty}$, where \mathbb{H}_{n+1}^+ is the direct sum of eigenspaces of $-L_{\mathbb{H}_{n+1}}$ corresponding to the positive eigenvalues and $\epsilon_n \colon S^{\mathbb{H}_{n+1}^+} \wedge \mathcal{E}_n \to \mathcal{E}_{n+1}$ are some morphisms obtained via the product formula given in Theorem 4.1.

Acknowledgments

The authors would like to express their gratitude to Professor Kazimierz Gęba for many helpful and valuable discussions.

Conflict of interest

The authors declare there is no conflicts of interest.

References

- 1. A. M. Lyapunov, Problème général de la stabilité du mouvement, *Ann. Fac. Sci. Univ. Toulouse*, **9** (1907), 203–474.
- A. Weinstein, Normal modes for nonlinear Hamiltonian systems, *Invent. Math.*, 20 (1973), 47–57. https://doi.org/10.1007/BF01405263
- 3. J. Moser, Periodic orbits near an equilibrium and a theorem by Alan Weinstein, *Comm. Pure Appl. Math.*, **29** (1976), 724–747. https://doi.org/10.1002/cpa.3160290613
- E. Fadell, P. H. Rabinowitz, Generalized cohomological index theories for Lie group actions with an application to bifurcation questions for Hamiltonian systems, *Invent. Math.*, 45 (1978), 139– 174. https://doi.org/10.1007/BF01390270

- 5. J. A. Montaldi, R. M. Roberts, I. N. Stewart, Periodic solutions near equilibria of symmetric Hamiltonian systems, *Phil. Trans. R. Soc. Lond. A*, **325** (1988), 237–293. https://doi.org/10.1098/rsta.1988.0053
- T. Bartsch, A generalization of the Weinstein-Moser theorems on periodic orbits of a Hamiltonian system near an equilibrium, *Ann. Inst. H. Poincaré Anal. Non Linéaire*, 14 (1997), 691–718. https://doi.org/10.1016/S0294-1449(97)80130-8
- 7. E. N. Dancer, S. Rybicki, A note on periodic solutions of autonomous Hamiltonian systems emanating from degenerate stationary solutions, *Differ. Integral Equ.*, **12** (1999), 147–160.
- 8. A. Szulkin, Bifurcation for strongly indefinite functionals and a Liapunov type theorem for Hamiltonian systems, *Differ. Integral Equ.*, **7** (1994), 217–234.
- 9. E. Pérez-Chavela, S. Rybicki, D. Strzelecki, Symmetric Liapunov center theorem, *Calc. Var. Partial Differ. Equ.*, **56** (2017), 1–23. https://doi.org/10.1007/s00526-017-1120-1
- E. Pérez-Chavela, S. Rybicki, D. Strzelecki, Symmetric Liapunov center theorem for minimal orbit, J. Differ. Equ., 265 (2018), 752–778. https://doi.org/10.1016/j.jde.2018.03.009
- D. Strzelecki, Periodic solutions of symmetric Hamiltonian systems, Arch. Ration. Mech. Anal., 237 (2020), 921–950. https://doi.org/10.1007/s00205-020-01522-6
- 12. M. Kowalczyk, E. Pérez-Chavela, S. Rybicki, Symmetric Lyapunov center theorem for orbit with nontrivial isotropy group, *Adv. Differ. Equ.*, **25** (2020), 1–30.
- 13. M. Izydorek, Equivariant Conley index in Hilbert spaces and applications to strongly indefinite problems, *Nonlinear Anal.*, **51** (2002), 33–66. https://doi.org/10.1016/S0362-546X(01)00811-2
- 14. T. tom Dieck, *Transformation groups*, Walter de Gruyter & Co., Berlin, 1987. https://doi.org/10.1515/9783110858372
- 15. T. Kawasaki, Cohomology of twisted projective spaces and lens complexes, *Math. Ann.*, **206** (1973), 243–248. https://doi.org/10.1007/BF01429212
- 16. A. Hatcher, *Algebraic topology*, Cambridge University Press, Cambridge, 2002. https://doi.org/10.1017/S0013091503214620
- 17. K. H. Mayer, G-invariante Morse-funktionen, *Manuscripta Math.*, **63** (1989), 99–114. http://dx.doi.org/10.1007/bf01173705
- J. Fura, A. Ratajczak, S. Rybicki, Existence and continuation of periodic solutions of autonomous Newtonian systems, *J. Differ. Equ.*, 218 (2005), 216–252. https://doi.org/10.1016/j.jde.2005.04.004
- 19. A. Gołębiewska, S. Rybicki, Equivariant Conley index versus degree for equivariant gradient maps, *Discrete Contin. Dyn. Syst. Ser. S*, **6** (2013), 985–997. http://dx.doi.org/10.3934/dcdss.2013.6.985
- 20. Z. Balanov, W. Krawcewicz, H. Steinlein, Applied Equivariant Degree, AIMS Series on Differential Equations & Dynamical Systems, 1, Springfield, 2006.
- A. Gołębiewska, P. Stefaniak, Global bifurcation from an orbit of solutions to noncooperative semi-linear Neumann problem, *J. Differ. Equ.*, 268 (2020), 6702–6728. https://doi.org/10.1016/j.jde.2019.11.053

- 22. J. P. Serre, Linear representations of finite groups, *Graduate Texts in Mathematics*, **42** (1977), Springer-Verlag, New York-Heidelberg. https://doi.org/10.1007/978-1-4684-9458-7
- 23. T. Bartsch, Topological methods for variational problems with symmetries, *Lect. Notes Math.*, **1560**, Springer-Verlag, Berlin, 1993. https://doi.org/10.1007/BFb0073859
- 24. K. Gęba, Degree for gradient equivariant maps and equivariant Conley index, *Topological nonlinear analysis II*, Birkhäuser, (1997), 247–272. https://doi.org/10.1007/978-1-4612-4126-3_5
- 25. C. Conley, Isolated invariants sets and the Morse index, *CBMS Regional Conference Series in Mathematics*, **38**, American Mathematical Society, Providence, R. I., 1978. https://doi.org/10.1090/cbms/038
- 26. J. Smoller, A. Wasserman, Bifurcation and symmetry-breaking, *Invent. Math.*, **100** (1990), 63–95. https://doi.org/10.1007/BF01231181



 \bigcirc 2022 the Author(s), licensee AIMS Press. This is an open access article distributed under the terms of the Creative Commons Attribution License (http://creativecommons.org/licenses/by/4.0)