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Research article

# Multiple solutions for quasi-linear elliptic equations with Berestycki-Lions type nonlinearity 

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Abstract: We studied the modified nonlinear Schrödinger equation

$$
\begin{equation*}
-\Delta u-\frac{1}{2} \Delta\left(u^{2}\right) u=g(u)+h(x), \quad u \in H^{1}\left(\mathbb{R}^{N}\right), \tag{0.1}
\end{equation*}
$$

where $N \geq 3, g \in C(\mathbb{R}, \mathbb{R})$ is a nonlinear function of Berestycki-Lions type, and $h \not \equiv 0$ is a nonnegative function. When $\|h\|_{L^{2}\left(\mathbb{R}^{N}\right)}$ is suitably small, we proved that (0.1) possesses at least two positive solutions by variational approach, one of which is a ground state while the other is of mountain pass type.

Keywords: nonhomogeneous quasi-linear elliptic equation; ground state solution; mountain pass type solution; variational methods
Mathematics Subject Classification: 35J20, 35J62

## 1. Introduction

The nonlinear scalar field equation

$$
\begin{equation*}
-\Delta u=g(u) \quad \text { in } \mathbb{R}^{N} \tag{1.1}
\end{equation*}
$$

has been widely studied by many authors. In the celebrated papers [1,2], H. Berestycki and P.-L. Lions proved that (1.1) has a positive ground state solution, which is radially symmetric and decreasing with respect to $r=|x|$, and also has infinitely many (possibly sign-changing) solutions when $N \geq 3$ and $g$ satisfies the almost optimal assumptions:
$\left(g_{1}\right) g \in C(\mathbb{R}, \mathbb{R})$ and $g$ is odd;
$\left(g_{2}\right)-\infty<\liminf _{t \rightarrow 0^{+}} g(t) / t \leq \lim \sup _{t \rightarrow 0^{+}} g(t) / t=-\kappa<0$;
$\left(g_{3}\right)-\infty \leq \lim \sup _{t \rightarrow+\infty} g(t) / t^{2^{*}-1} \leq 0$, where $2^{*}=2 N /(N-2)$;
$\left(g_{4}\right)$ there is a constant $\zeta>0$ such that $G(\zeta):=\int_{0}^{\zeta} g(t) d t>0$.
The above classical result has already been generalized in many directions. See, e.g., [3,4] for nonradial solutions of (1.1), [5-8] for nonautonomous semi-linear problems, [9-11] for quasi-linear problems, and $[12,13]$ for nonlocal problems. In particular, the nonhomogeneous semi-linear elliptic equation

$$
\begin{equation*}
-\Delta u=g(u)+h(x) \quad \text { in } \mathbb{R}^{N}, \tag{1.2}
\end{equation*}
$$

which can be seen as a perturbation of (1.1), was investigated in [6]. Using Ekeland's variational principle and the mountain pass theorem, the authors proved that (1.2) has at least two nontrivial solutions when $\|h\|_{L^{2}\left(\mathbb{R}^{N}\right)}$ is suitably small. We also refer to $[14,15]$ for related results.

Motivated by $[1,2,6,9]$, we study the modified nonlinear Schrödinger equation

$$
\begin{equation*}
-\Delta u-\frac{1}{2} \Delta\left(u^{2}\right) u=g(u)+h(x), \quad u \in H^{1}\left(\mathbb{R}^{N}\right), \tag{1.3}
\end{equation*}
$$

where, again, $N \geq 3, g$ is a nonlinear function of Berestycki-Lions type, and $h \not \equiv 0$ is a nonnegative function. It is well known that (1.3) models the time evolution of the condensate wave function in super-fluid film. It also appears in the theory of Heisenberg ferromagnet and magnons, in dissipative quantum mechanics, and in condensed matter theory. See [16-18] for details on the background of (1.3). To state our main result, we make the following assumptions on $g$ and $h$ :
$\left(g_{1}^{\prime}\right) g \in C(\mathbb{R}, \mathbb{R})$;
$\left(g_{3}^{\prime}\right) \lim _{t \rightarrow+\infty} g(t) / t^{2 \cdot 2^{*}-1}=0 ;$
(h) $h \in C^{1}\left(\mathbb{R}^{N}, \mathbb{R}\right) \cap L^{2}\left(\mathbb{R}^{N}\right), h(x)=h(|x|) \supsetneqq 0$, and $\nabla h(x) \cdot x \in L^{2 N /(N+2)}\left(\mathbb{R}^{N}\right)$.

Theorem 1.1. Assume $\left(g_{1}^{\prime}\right),\left(g_{2}\right),\left(g_{3}^{\prime}\right)$, and $\left(g_{4}\right)$ hold, then there exists a constant $\delta>0$ such that, for any function $h$ satisfying ( $h$ ) and $\|h\|_{L^{2}\left(\mathbb{R}^{N}\right)}<\delta$, (1.3) has at least two positive solutions, one of which is a ground state while the other is of mountain pass type.
Remark 1.2. The positive number $\delta$ in Theorem 1.1 will be given explicitly in the proof of Lemma 3.1. As mentioned in [19], the critical exponent for (1.3) is not $2^{*}$ but $2 \cdot 2^{*}$. This is why we assume different growth condition $\left(g_{3}^{\prime}\right)$ instead of $\left(g_{3}\right)$ in Theorem 1.1.

Remark 1.3. In the proof of Theorem 1.1, we borrow some ideas from [6]. However, due to the appearance of $\Delta\left(u^{2}\right) u$ and growth condition on $g$, there is no approximate function space in which the energy functional of (1.3) is both well defined and satisfies the compactness condition. To overcome this difficulty, we will make a change of variables to transform (1.3) into a new semi-linear problem, then we adopt similar ideas as in [6] to verify the geometrical structure and compactness property of the reduced functional. Nevertheless, the analysis is more delicate because the reduced functional involves the transform function.

## 2. Variational Framework

Since positive solutions are of particular interest in this paper, we always assume with no restriction that $g(t)=-\kappa t$ for $t \leq 0$ in the following arguments, where $\kappa>0$ is given in $\left(g_{2}\right)$. In form, (1.3) is the Euler equation of the energy functional

$$
\mathcal{E}(u)=\frac{1}{2} \int_{\mathbb{R}^{N}}\left(1+u^{2}\right)|\nabla u|^{2} d x-\int_{\mathbb{R}^{N}} G(u) d x-\int_{\mathbb{R}^{N}} h(x) u d x,
$$

where $G(u)=\int_{0}^{u} g(t) d t$. However, standard variational methods cannot be applied directly because one lacks an appropriate working space in which $\mathcal{E}$ is both well-defined and enjoys compactness properties. In order to surmount this obstacle, we shall adopt a change of unknown to transform (1.3) into a semilinear problem. Let $u=f(v)$ be the inverse function of

$$
v=\int_{0}^{u} \sqrt{1+t^{2}} d t=\frac{1}{2} u \sqrt{1+u^{2}}+\frac{1}{2} \ln \left(u+\sqrt{1+u^{2}}\right) .
$$

We recall some basic properties of $f$ in the next lemma (see $[20,21]$ ).
Lemma 2.1. $f$ is odd and has the following properties:

$$
f^{\prime}(0)=\lim _{t \rightarrow 0} f(t) / t=1, \quad \lim _{t \rightarrow+\infty} f(t) / \sqrt{t}=\sqrt{2},
$$

and

$$
0<f^{\prime}(t) \leq 1, \quad|f(t)| \leq \min \{|t|, \quad \sqrt{2|t|}\}, \quad \frac{1}{2} f^{2}(t) \leq f(t) f^{\prime}(t) t \leq f^{2}(t), \text { for } t \in \mathbb{R}
$$

Setting $u=f(v)$, we change the functional $\mathcal{E}$ into

$$
J(v):=\mathcal{E}(f(v))=\frac{1}{2} \int_{\mathbb{R}^{N}}|\nabla v|^{2} d x-\int_{\mathbb{R}^{N}} G(f(v)) d x-\int_{\mathbb{R}^{N}} h(x) f(v) d x .
$$

By Lemma 2.1, one sees that $J$ is well-defined in the Sobolev space $H_{r}^{1}\left(\mathbb{R}^{N}\right)$ and is of class $C^{1}$. Moreover, if $v \in H_{r}^{1}\left(\mathbb{R}^{N}\right)$ is a critical point of $J$, then $u=f(v)$ is a positive solution of (1.3). Indeed, since $J^{\prime}(v)=0$, we have

$$
\begin{aligned}
0 & =\int_{\mathbb{R}^{N}}\left|\nabla v^{-}\right|^{2} d x-\int_{\mathbb{R}^{N}} g(f(v)) f^{\prime}(v) v^{-} d x-\int_{\mathbb{R}^{N}} h(x) f^{\prime}(v) v^{-} d x \\
& =\int_{\mathbb{R}^{N}}\left|\nabla v^{-}\right|^{2} d x+\kappa \int_{\mathbb{R}^{N}} f\left(v^{-}\right) f^{\prime}\left(v^{-}\right) v^{-} d x-\int_{\mathbb{R}^{N}} h(x) f^{\prime}(v) v^{-} d x,
\end{aligned}
$$

where $v^{-}=\min \{v, 0\}$. By Lemma 2.1 again and $(h)$,

$$
\int_{\mathbb{R}^{N}}\left|\nabla v^{-}\right|^{2} d x=\int_{\mathbb{R}^{N}} f^{2}\left(v^{-}\right) d x=0
$$

Using Lemma 2.1 once more and the Sobolev inequality, we obtain

$$
\begin{aligned}
\int_{\mathbb{R}^{N}}\left(v^{-}\right)^{2} d x & \leq C_{1} \int_{\Omega_{1}} f^{2}\left(v^{-}\right) d x+\int_{\Omega_{2}}\left|v^{-}\right|^{*} d x \\
& \leq C_{1} \int_{\mathbb{R}^{N}} f^{2}\left(v^{-}\right) d x+C_{2}\left(\int_{\mathbb{R}^{N}}\left|\nabla v^{-}\right|^{2} d x\right)^{\frac{N}{N-2}},
\end{aligned}
$$

where $\Omega_{1}=\left\{x| | v^{-}(x) \mid \leq 1\right\}$ and $\Omega_{2}=\left\{x| | v^{-}(x) \mid>1\right\}$, then $v^{-}=0$, so $v \geq 0$ in $\mathbb{R}^{N}$. By $\left(g_{1}^{\prime}\right),\left(g_{2}\right)$, and $\left(g_{3}^{\prime}\right)$, there exists a constant $K>0$ such that $\left|g(f(t)) f^{\prime}(t)\right| \leq K\left(|t|+|t|^{*-1}\right)$ for $t \in \mathbb{R}$. Since $J^{\prime}(v)=0$, one has

$$
-\Delta v+K\left(1+v^{2^{*}-2}\right) v=g(f(v)) f^{\prime}(v)+K\left(v+v^{2^{*}-1}\right)+h(x) f^{\prime}(v) \geq 0 \quad \text { in } \mathbb{R}^{N} .
$$

By the elliptic regularity theory, [1, Radial Lemma A.II], and the strong maximum principle, we can prove that $v$ is positive in $\mathbb{R}^{N}$. Now, a standard argument shows that $u=f(v)$ is a positive solution of (1.3). Therefore, to prove Theorem 1.1, it suffices to find two critical points of $J$ in $H_{r}^{1}\left(\mathbb{R}^{N}\right)$. We shall fulfill this task by using Ekeland's variational principle and the mountain pass theorem.

Lemma 2.2. ( [22, Theorem 1.1]) Assume that $(X, d)$ is a complete metric space and that $I: X \rightarrow$ $\mathbb{R} \cup\{+\infty\}$ is lower semicontinuous, bounded from below, and not identical to $+\infty$. Let $\epsilon>0$ be arbitrary given. If $u \in X$ satisfies $I(u) \leq \inf _{X} I+\epsilon$, then there exists $v \in X$ such that

$$
I(v) \leq I(u), d(u, v) \leq 1, \quad I(w)>I(v)-\epsilon d(v, w) \text { for any } w \in X \backslash\{v\} .
$$

The next lemma is an expression of the mountain pass theorem without the Palais-Smale condition, which is essentially due to A. Ambrosetti and P. Rabinowitz (see [23, Theorem 2.1]).

Lemma 2.3. Let $X$ be a Banach space and $I \in C^{1}(X, \mathbb{R})$. Assume $I(0)=0$ and

- there exist $\rho>0$ and $\alpha>0$ such that $I(u) \geq \alpha$ if $\|u\|=\rho$,
- there exists a function $\omega \in X$ such that $\|\omega\|>\rho$ and $I(\omega) \leq 0$.

Let $\Gamma=\{\gamma \in C([0,1], X) \mid \gamma(0)=0, \gamma(1)=\omega\}$ and set

$$
c=\inf _{\gamma \in \Gamma} \max _{t \in[0,1]} I(\gamma(t)) \geq \alpha,
$$

then there exists $\left\{u_{n}\right\} \subset X$ satisfying $I\left(u_{n}\right) \rightarrow c$ and $I^{\prime}\left(u_{n}\right) \rightarrow 0$ in $X^{*}$ as $n \rightarrow \infty$.

## 3. Proof of Theorem 1.1

By $\left(g_{1}^{\prime}\right),\left(g_{2}\right),\left(g_{3}^{\prime}\right)$, and Lemma 2.1, there exist $a, b>0$ such that

$$
\begin{equation*}
G(f(t)) \leq-a t^{2}+b|t|^{2^{*}}, \quad \text { for } t \in \mathbb{R} \tag{3.1}
\end{equation*}
$$

and for any $\epsilon>0$, there is $C_{\epsilon}>0$ such that

$$
\begin{equation*}
|G(f(t))| \leq C_{\epsilon} t^{2}+\epsilon|t|^{2^{*}}, \text { for } t \in \mathbb{R} . \tag{3.2}
\end{equation*}
$$

We will work in $H_{r}^{1}\left(\mathbb{R}^{N}\right)$, a subspace of $H^{1}\left(\mathbb{R}^{N}\right)$ consisting of radially symmetric functions. Denote $B_{\rho}=\left\{v \in H_{r}^{1}\left(\mathbb{R}^{N}\right) \mid\|v\| \leq \rho\right\}$ and $\partial B_{\rho}=\left\{v \in H_{r}^{1}\left(\mathbb{R}^{N}\right) \mid\|v\|=\rho\right\}$. We first study the geometrical structure of $J$ in the next lemmas.

Lemma 3.1. There exist $\delta>0, \rho>0$, and $\alpha>0$ such that if $\|h\|_{L^{2}\left(\mathbb{R}^{N}\right)}<\delta$, then $\inf _{\partial B_{\rho}} J \geq \alpha$.
Proof. It follows from (3.1), the Hölder inequality, and Lemma 2.1 that

$$
\begin{aligned}
J(v) & \geq C_{1}\|v\|^{2}-b \int_{\mathbb{R}^{N}}|v|^{2^{*}} d x-\|h\|_{L^{2}\left(\mathbb{R}^{N}\right)}\|v\|_{L^{2}\left(\mathbb{R}^{N}\right)} \\
& \geq C_{1}\|v\|^{2}-C_{2}\|v\|^{2^{*}}-\|h\|_{L^{2}\left(\mathbb{R}^{N}\right)}\|v\| \\
& =\|v\|\left(C_{1}\|v\|-C_{2}\|v\|^{2^{*}-1}-\|h\|_{L^{2}\left(\mathbb{R}^{N}\right)}\right),
\end{aligned}
$$

where $C_{j}>0$ for $j=1,2$. We choose

$$
\delta=2\left(\frac{N-2}{C_{2}}\right)^{\frac{N-2}{4}}\left(\frac{C_{1}}{N+2}\right)^{\frac{N+2}{4}}>0, \quad \rho=\left(\frac{C_{1}(N-2)}{C_{2}(N+2)}\right)^{\frac{N-2}{4}}>0, \quad \alpha=\delta \rho>0,
$$

then $\inf _{\partial B_{\rho}} J \geq \rho\left(2 \delta-\|h\|_{L^{2}\left(\mathbb{R}^{N}\right)}\right) \geq \alpha$, provided that $\|h\|_{L^{2}\left(\mathbb{R}^{N}\right)}<\delta$. The proof is finished.

Lemma 3.2. Set

$$
m_{0}:=\inf _{B_{\rho}} J,
$$

where $\rho>0$ is as in Lemma 3.1. We have $m_{0} \in(-\infty, 0)$.
Proof. It is clear that $m_{0}>-\infty$. Since $h \supsetneqq 0$ in $\mathbb{R}^{N}$, one can find a function $\varphi \in H_{r}^{1}\left(\mathbb{R}^{N}\right)$ such that

$$
0 \leq \varphi \leq 1 \quad \text { and } \quad \int_{\mathbb{R}^{N}} h(x) \varphi d x>0 .
$$

By (3.2) and Lemma 2.1, there exists $C>0$ such that

$$
\begin{aligned}
\limsup _{t \rightarrow 0^{+}} \frac{J(t \varphi)}{t} & =\limsup _{t \rightarrow 0^{+}}\left(\frac{t}{2} \int_{\mathbb{R}^{N}}|\nabla \varphi|^{2} d x-\frac{1}{t} \int_{\mathbb{R}^{N}} G(f(t \varphi)) d x-\frac{1}{t} \int_{\mathbb{R}^{N}} h(x) f(t \varphi) d x\right) \\
& \leq \limsup _{t \rightarrow 0^{+}}\left(C_{\epsilon} t \int_{\mathbb{R}^{N}} \varphi^{2} d x+\epsilon t^{2^{*}-1} \int_{\mathbb{R}^{N}}|\varphi|^{2^{*}} d x-C \int_{\mathbb{R}^{N}} h(x) \varphi d x\right) \\
& =-C \int_{\mathbb{R}^{N}} h(x) \varphi d x<0 .
\end{aligned}
$$

Let $t>0$ be sufficiently small such that $\|t \varphi\|<\rho$ and $J(t \varphi)<0$, then we have $m_{0}<0$ as desired.
Lemma 3.3. There exists $\omega \in H_{r}^{1}\left(\mathbb{R}^{N}\right) \backslash B_{\rho}$ such that $J(\omega)<0$, where $\rho>0$ is as in Lemma 3.1.
Proof. Let $\tau>0$ be such that $f(\tau)=\zeta$, where $\zeta>0$ is given in ( $g_{4}$ ). We define, as in [1],

$$
\omega_{R}(x)= \begin{cases}\tau, & \text { if }|x|<R, \\ \tau(R+1-|x|), & \text { if } R \leq|x| \leq R+1, \\ 0, & \text { if }|x|>R+1,\end{cases}
$$

where $R>1$ will be determined later, then $\omega_{R} \in H_{r}^{1}\left(\mathbb{R}^{N}\right)$ and a simple calculation shows that

$$
\begin{equation*}
\int_{\mathbb{R}^{N}}\left|\nabla \omega_{R}\right|^{2} d x \leq C_{1} R^{N-1} \quad \text { and } \quad \int_{\mathbb{R}^{N}} G\left(f\left(\omega_{R}\right)\right) d x \geq C_{2} R^{N}-C_{3} R^{N-1} \tag{3.3}
\end{equation*}
$$

where $C_{1}, C_{2}, C_{3}>0$ are independent of $R$. Set $\omega_{R, t}=\omega_{R}(\cdot / t)$ for $t>0$. By (h) and (3.3), one has

$$
J\left(\omega_{R, t}\right) \leq C_{1} R^{N-1} t^{N-2}-\left(C_{2} R^{N}-C_{3} R^{N-1}\right) t^{N} .
$$

Choosing $R>1$ and $t>0$ sufficiently large, we have $\left\|\omega_{R, t}\right\|>\rho$ and $J\left(\omega_{R, t}\right)<0$.
Next, we investigate the compactness property of the functional $J$.
Lemma 3.4. Any bounded Palais-Smale sequence of $J$ in $H_{r}^{1}\left(\mathbb{R}^{N}\right)$ has a convergent subsequence.
Proof. Let $\left\{v_{n}\right\} \subset H_{r}^{1}\left(\mathbb{R}^{N}\right)$ be a sequence satisfying $\left\|v_{n}\right\| \leq C, J\left(v_{n}\right) \leq C$ and $J^{\prime}\left(v_{n}\right) \rightarrow 0$ in $\left(H_{r}^{1}\left(\mathbb{R}^{N}\right)\right)^{*}$ as $n \rightarrow \infty$. We assume by extracting a subsequence that $v_{n} \rightharpoonup v$ weakly in $H_{r}^{1}\left(\mathbb{R}^{N}\right), v_{n} \rightarrow v$ strongly in $L^{p}\left(\mathbb{R}^{N}\right)$ for $2<p<2^{*}$, and $v_{n} \rightarrow v$ a.e. in $\mathbb{R}^{N}$, then $f^{\prime}\left(v_{n}\right)\left(v_{n}-v\right) \rightharpoonup 0$ weakly in $L^{2}\left(\mathbb{R}^{N}\right)$ and, henceforth, by $(h)$ and Lemma 2.1,

$$
\begin{equation*}
\int_{\mathbb{R}^{N}} h(x)\left(f^{\prime}\left(v_{n}\right)-f^{\prime}(v)\right)\left(v_{n}-v\right) d x=o_{n}(1), \text { as } n \rightarrow \infty \tag{3.4}
\end{equation*}
$$

Here and after, $o_{n}(1)$ stands for a generic infinitesimal as $n \rightarrow \infty$. Using (3.4) leads to

$$
\begin{aligned}
o_{n}(1) & =\left\langle J^{\prime}\left(v_{n}\right)-J^{\prime}(v), v_{n}-v\right\rangle \\
& =\int_{\mathbb{R}^{N}}\left|\nabla\left(v_{n}-v\right)\right|^{2} d x-\int_{\mathbb{R}^{N}}\left(g\left(f\left(v_{n}\right)\right) f^{\prime}\left(v_{n}\right)-g(f(v)) f^{\prime}(v)\right)\left(v_{n}-v\right) d x+o_{n}(1) \\
& \geq \min \{1, \kappa\}\left\|v_{n}-v\right\|^{2}-\int_{\mathbb{R}^{N}}\left(g\left(f\left(v_{n}\right)\right) f^{\prime}\left(v_{n}\right)+\kappa v_{n}-g(f(v)) f^{\prime}(v)-\kappa v\right)\left(v_{n}-v\right) d x+o_{n}(1) .
\end{aligned}
$$

To conclude our proof, it suffices to show that

$$
\begin{equation*}
\int_{\mathbb{R}^{N}}\left(g\left(f\left(v_{n}\right)\right) f^{\prime}\left(v_{n}\right)+\kappa v_{n}-g(f(v)) f^{\prime}(v)-\kappa v\right)\left(v_{n}-v\right) d x \leq o_{n}(1), \text { as } n \rightarrow \infty . \tag{3.5}
\end{equation*}
$$

Let us define

$$
g_{1}(t)= \begin{cases}\left(g(f(t)) f^{\prime}(t)+\kappa t\right)^{+}, & \text {if } t \geq 0 \\ \left(g(f(t)) f^{\prime}(t)+\kappa t\right)^{-}, & \text {if } t \leq 0\end{cases}
$$

and $g_{2}(t)=g(f(t)) f^{\prime}(t)+\kappa t-g_{1}(t)$ for $t \in \mathbb{R}$, then

$$
\begin{equation*}
\lim _{t \rightarrow 0} \frac{g_{1}(t)}{t}=\lim _{t \rightarrow \infty} \frac{g_{1}(t)}{|t|^{*}-1}=0 \tag{3.6}
\end{equation*}
$$

and

$$
\begin{equation*}
g_{2}(t) t \leq 0, \quad\left|g_{2}(t)\right| \leq C\left(|t|+|t|^{2^{*}-1}\right), \quad \text { for } t \in \mathbb{R} \tag{3.7}
\end{equation*}
$$

By (3.6), for any $\epsilon>0$ and $p \in\left(2,2^{*}\right)$, there is a constant $C_{\epsilon, p}>0$ such that

$$
\left|g_{1}(t)\right| \leq \epsilon\left(|t|+|t|^{2^{*}-1}\right)+C_{\epsilon, p}|t|^{p-1}, \text { for } t \in \mathbb{R}
$$

which, combined with $v_{n} \rightarrow v$ strongly in $L^{p}\left(\mathbb{R}^{N}\right)$, implies that

$$
\begin{equation*}
\int_{\mathbb{R}^{N}}\left(g_{1}\left(v_{n}\right)-g_{1}(v)\right)\left(v_{n}-v\right) d x=o_{n}(1), \text { as } n \rightarrow \infty . \tag{3.8}
\end{equation*}
$$

Since $v_{n} \rightharpoonup v$ weakly in $H_{r}^{1}\left(\mathbb{R}^{N}\right)$, one has

$$
\begin{equation*}
\int_{\mathbb{R}^{N}} g_{2}(v)\left(v_{n}-v\right) d x=o_{n}(1), \text { as } n \rightarrow \infty . \tag{3.9}
\end{equation*}
$$

Clearly, (3.7) and Fatou's lemma imply that

$$
\begin{equation*}
\limsup _{n \rightarrow \infty} \int_{\mathbb{R}^{N}} g_{2}\left(v_{n}\right) v_{n} d x \leq \int_{\mathbb{R}^{N}} g_{2}(v) v d x . \tag{3.10}
\end{equation*}
$$

By (3.7) and the dominated convergence theorem, it is easy to verify that

$$
\begin{equation*}
\int_{\mathbb{R}^{v}} g_{2}\left(v_{n}\right) v d x=\int_{\mathbb{R}^{N}} g_{2}(v) v d x+o_{n}(1), \text { as } n \rightarrow \infty \tag{3.11}
\end{equation*}
$$

Combining (3.9)-(3.11), we have

$$
\begin{equation*}
\int_{\mathbb{R}^{N}}\left(g_{2}\left(v_{n}\right)-g_{2}(v)\right)\left(v_{n}-v\right) d x \leq o_{n}(1), \text { as } n \rightarrow \infty, \tag{3.12}
\end{equation*}
$$

then (3.5) is a direct consequence of (3.8) and (3.12). The proof is complete.

Lemma 3.5. If $v \in H_{r}^{1}\left(\mathbb{R}^{N}\right)$ is a critical point of $J$, then $P(v)=0$, where

$$
P(v)=\frac{N-2}{2} \int_{\mathbb{R}^{N}}|\nabla v|^{2} d x-N \int_{\mathbb{R}^{N}}(G(f(v))+h(x) f(v)) d x-\int_{\mathbb{R}^{N}}(\nabla h(x) \cdot x) f(v) d x .
$$

Proof. Since the argument is standard, we omit the details.
Lemma 3.6. If $v \in H_{r}^{1}\left(\mathbb{R}^{N}\right)$ is a critical point of $J$, then

$$
J(v) \geq-\frac{1}{4 N S}\|\nabla h(x) \cdot x\|_{L^{2 N /(N+2)}\left(\mathbb{R}^{N}\right)}^{2},
$$

where $S>0$ is the best constant of the Sobolev embedding $D^{1,2}\left(\mathbb{R}^{N}\right) \hookrightarrow L^{2^{*}}\left(\mathbb{R}^{N}\right)$.
Proof. Let $v \in H_{r}^{1}\left(\mathbb{R}^{N}\right)$ be a critical point of $J$, then $P(v)=0$ by Lemma 3.5, and

$$
J(v)=J(v)-\frac{1}{N} P(v)=\frac{1}{N} \int_{\mathbb{R}^{N}}|\nabla v|^{2} d x+\frac{1}{N} \int_{\mathbb{R}^{N}}(\nabla h(x) \cdot x) f(v) d x .
$$

By the Hölder inequality and Lemma 2.1, one has

$$
\begin{aligned}
J(v) & \geq \frac{1}{N} \int_{\mathbb{R}^{N}}|\nabla v|^{2} d x-\frac{1}{N}\|\nabla h(x) \cdot x\|_{L^{2 N(N+2)}\left(\mathbb{R}^{N}\right)}\|v\|_{L^{2^{*}}\left(\mathbb{R}^{N}\right)} \\
& \geq \frac{1}{N} \int_{\mathbb{R}^{N}}|\nabla v|^{2} d x-\frac{1}{N S^{1 / 2}}\|\nabla h(x) \cdot x\|_{L^{2 N(N+2)}\left(\mathbb{R}^{N}\right)}\left(\int_{\mathbb{R}^{N}}|\nabla v|^{2} d x\right)^{\frac{1}{2}} \\
& \geq-\frac{1}{4 N S}\|\nabla h(x) \cdot x\|_{L^{2 N /(N+2)}\left(\mathbb{R}^{N}\right)}^{2} .
\end{aligned}
$$

The proof is complete.
Proof of Theorem 1.1. Let $\delta>0$ be as in Lemma 3.1 and assume that $h$ satisfies $(h)$ and $\|h\|_{L^{2}\left(\mathbb{R}^{N}\right)}<\delta$. We first establish the existence of a positive ground state solution. In view of Lemmas 2.2 and 3.2, there exists a sequence $\left\{v_{n}\right\} \subset B_{\rho}$ such that $m_{0} \leq J\left(v_{n}\right) \leq m_{0}+\frac{1}{n}$ and

$$
\begin{equation*}
J(w) \geq J\left(v_{n}\right)-\frac{1}{n}\left\|w-v_{n}\right\|, \text { for any } w \in B_{\rho} . \tag{3.13}
\end{equation*}
$$

By Lemmas 3.1 and 3.2, we may assume with no loss of generality that $\left\|v_{n}\right\|<\rho$ for all $n \in \mathbb{N}$. For any $\varphi \in H_{r}^{1}\left(\mathbb{R}^{N}\right)$ with $\|\varphi\|=1$ and any small positive $t$, we see from (3.13) that $\frac{J\left(v_{n}+t \varphi\right)-J\left(v_{n}\right)}{t} \geq-\frac{1}{n}$. Letting $t \rightarrow 0$, we have $\left\langle J^{\prime}\left(v_{n}\right), \varphi\right\rangle \geq-\frac{1}{n}$. Replacing $\varphi$ by $-\varphi$, we also have $\left\langle J^{\prime}\left(v_{n}\right), \varphi\right\rangle \leq \frac{1}{n}$ and, henceforth, $J^{\prime}\left(v_{n}\right) \rightarrow 0$ in $\left(H_{r}^{1}\left(\mathbb{R}^{N}\right)\right)^{*}$ as $n \rightarrow \infty$. Therefore, $\left\{v_{n}\right\}$ is a bounded Palais-Smale sequence of $J$ in $H_{r}^{1}\left(\mathbb{R}^{N}\right)$ at the level $m_{0}$. It follows from Lemma 3.4 that there exists $v \in B_{\rho}$ such that $v_{n} \rightarrow v$ strongly in $H_{r}^{1}\left(\mathbb{R}^{N}\right)$ up to a subsequence, so $v$ is a nontrivial critical point of $J$.

The above argument shows that $\mathcal{K}=\left\{v \in H_{r}^{1}\left(\mathbb{R}^{N}\right) \mid J^{\prime}(v)=0\right\} \neq \emptyset$. Now, we define

$$
c_{0}:=\inf _{v \in \mathcal{K}} J(v) .
$$

Thus, $c_{0} \in(-\infty, 0)$ by Lemmas 3.2 and 3.6. Let $\left\{\hat{v}_{n}\right\} \subset \mathcal{K}$ be a minimizing sequence for $c_{0}$, then

$$
\begin{equation*}
c_{0}+o_{n}(1)=J\left(\hat{v}_{n}\right)-\frac{1}{N} P\left(\hat{v}_{n}\right)=\frac{1}{N} \int_{\mathbb{R}^{N}}\left|\nabla \hat{v}_{n}\right|^{2} d x+\frac{1}{N} \int_{\mathbb{R}^{N}}(\nabla h(x) \cdot x) f\left(\hat{v}_{n}\right) d x . \tag{3.14}
\end{equation*}
$$

Using the Hölder inequality and (h), one has

$$
\begin{align*}
c_{0}+o_{n}(1) & \geq \frac{1}{N} \int_{\mathbb{R}^{N}}\left|\nabla \hat{v}_{n}\right|^{2} d x-\frac{1}{N}\|\nabla h(x) \cdot x\|_{L^{2 N /(N+2)}\left(\mathbb{R}^{N}\right)}\left\|\hat{v}_{n}\right\|_{L^{2^{*}}\left(\mathbb{R}^{N}\right)} \\
& \geq \frac{1}{N} \int_{\mathbb{R}^{N}}\left|\nabla \hat{v}_{n}\right|^{2} d x-\frac{1}{N S^{1 / 2}}\|\nabla h(x) \cdot x\|_{L^{2 N /(N+2)}\left(\mathbb{R}^{N}\right)}\left(\int_{\mathbb{R}^{N}}\left|\nabla \hat{v}_{n}\right|^{2} d x\right)^{\frac{1}{2}} \tag{3.15}
\end{align*}
$$

This implies $\left\{\left\|\nabla \hat{v}_{n}\right\|_{L^{2}\left(\mathbb{R}^{N}\right)}\right\}$ is bounded. In view of (3.1), we have

$$
\begin{align*}
\frac{1}{2} \int_{\mathbb{R}^{N}}\left|\nabla \hat{v}_{n}\right|^{2} d x+a \int_{\mathbb{R}^{N}} \hat{v}_{n}^{2} d x & \leq J\left(\hat{v}_{n}\right)+b \int_{\mathbb{R}^{N}}\left|\hat{v}_{n}\right|^{2^{*}} d x+\|h\|_{L^{2}\left(\mathbb{R}^{N}\right)} \mid \hat{v}_{n} \|_{L^{2}\left(\mathbb{R}^{N}\right)} \\
& \leq c_{0}+o_{n}(1)+C\left(\int_{\mathbb{R}^{N}}\left|\nabla \hat{v}_{n}\right|^{2} d x\right)^{\frac{N}{N-2}}+\|h\|_{L^{2}\left(\mathbb{R}^{N}\right)}\left\|\hat{v}_{n}\right\|_{L^{2}\left(\mathbb{R}^{N}\right)} \tag{3.16}
\end{align*}
$$

then $\left\{\hat{v}_{n}\right\}$ is bounded in $H_{r}^{1}\left(\mathbb{R}^{N}\right)$. Using Lemma 3.4 again, we see that there exists $\hat{v} \in H_{r}^{1}\left(\mathbb{R}^{N}\right)$ such that $\hat{v}_{n} \rightarrow \hat{v}$ strongly in $H_{r}^{1}\left(\mathbb{R}^{N}\right)$ up to a subsequence, so $\hat{v}$ is a nontrivial critical point of $J$. The arguments in Section 2 indicate that $\hat{u}=f(\hat{v})$ is a positive solution of (1.3) and $\mathcal{E}(\hat{u})=J(\hat{v})=c_{0}<0$.

Next, we prove the existence of a mountain pass type solution. By Lemmas 3.1 and 3.3,

$$
J(0)=0, \quad \omega \in H_{r}^{1}\left(\mathbb{R}^{N}\right) \backslash B_{\rho}, \quad \inf _{\partial B_{\rho}} J \geq \alpha>0>J(\omega) .
$$

Let $\Gamma=\left\{\gamma \in C\left([0,1], H_{r}^{1}\left(\mathbb{R}^{N}\right)\right) \mid \gamma(0)=0, \gamma(1)=\omega\right\}$ and define the minimax value

$$
\begin{equation*}
c_{1}:=\inf _{\gamma \in \Gamma} \max _{t \in[0,1]} J(\gamma(t)) \geq \alpha>0 . \tag{3.17}
\end{equation*}
$$

By Lemma 2.3, there exists a Palais-Smale sequence of $J$ at the level $c_{1}$. However, it seems impossible to verify the boundedness of such a Palais-Smale sequence. To overcome this difficulty, we shall adopt an idea originated in [24]. Define a map $\Phi: \mathbb{R} \times H_{r}^{1}\left(\mathbb{R}^{N}\right) \rightarrow H_{r}^{1}\left(\mathbb{R}^{N}\right)$ by $\Phi(\theta, v)(x)=v\left(e^{-\theta} x\right)$. We introduce an auxiliary functional $J \circ \Phi: \mathbb{R} \times H_{r}^{1}\left(\mathbb{R}^{N}\right) \rightarrow \mathbb{R}$ given by

$$
(J \circ \Phi)(\theta, v)=\frac{e^{(N-2) \theta}}{2} \int_{\mathbb{R}^{N}}|\nabla v|^{2} d x-e^{N \theta} \int_{\mathbb{R}^{N}} G(f(v)) d x-e^{N \theta} \int_{\mathbb{R}^{N}} h\left(e^{\theta} x\right) f(v) d x
$$

Clearly, $J \circ \Phi \in C^{1}\left(\mathbb{R} \times H_{r}^{1}\left(\mathbb{R}^{N}\right), \mathbb{R}\right)$ and $(J \circ \Phi)(0, v)=J(v)$ for $v \in H_{r}^{1}\left(\mathbb{R}^{N}\right)$. It is easy to verify that

$$
c_{1}=\inf _{\tilde{\gamma} \in \tilde{\Gamma}} \max _{t \in[0,1]}(J \circ \Phi)(\tilde{\gamma}(t)),
$$

where $\tilde{\Gamma}=\left\{\tilde{\gamma} \in C\left([0,1], \mathbb{R} \times H_{r}^{1}\left(\mathbb{R}^{N}\right)\right) \mid \tilde{\gamma}(0)=(0,0), \tilde{\gamma}(1)=(0, \omega)\right\}$. By (3.17), for each $n \in \mathbb{N}$, there is $\gamma_{n} \in \Gamma$ such that $\max _{t \in[0,1]} J\left(\gamma_{n}(t)\right)<c_{1}+\frac{1}{n}$. Setting $\tilde{\gamma}_{n}=\left(0, \gamma_{n}\right)$, we have $\tilde{\gamma}_{n} \in \tilde{\Gamma}$ and $\max _{t \in[0,1]}(J \circ \Phi)\left(\tilde{\gamma}_{n}(t)\right)=\max _{t \in[0,1]} J\left(\gamma_{n}(t)\right)<c_{1}+\frac{1}{n}$. Using similar arguments as in [25, Lemma 4.3] or by [26, Theorem 2.8], there exists a sequence $\left\{\left(\theta_{n}, v_{n}\right)\right\} \subset \mathbb{R} \times H_{r}^{1}\left(\mathbb{R}^{N}\right)$ such that

$$
(J \circ \Phi)\left(\theta_{n}, v_{n}\right) \rightarrow c_{1}, \quad \operatorname{dist}\left(\left(\theta_{n}, v_{n}\right), \tilde{\gamma}_{n}[0,1]\right) \rightarrow 0, \quad(J \circ \Phi)^{\prime}\left(\theta_{n}, v_{n}\right) \rightarrow 0 \text { in }\left(\mathbb{R} \times H_{r}^{1}\left(\mathbb{R}^{N}\right)\right)^{*}
$$

as $n \rightarrow \infty$, then it must be $\theta_{n} \rightarrow 0$ as $n \rightarrow \infty$. Setting $\tilde{v}_{n}=\Phi\left(\theta_{n}, v_{n}\right)$, we see that

$$
J\left(\tilde{v}_{n}\right)=(J \circ \Phi)\left(\theta_{n}, v_{n}\right) \rightarrow c_{1}, \quad P\left(\tilde{v}_{n}\right)=\left\langle(J \circ \Phi)^{\prime}\left(\theta_{n}, v_{n}\right),(1,0)\right\rangle \rightarrow 0, \quad \text { as } n \rightarrow \infty
$$

and

$$
\left\langle J^{\prime}\left(\tilde{v}_{n}\right), \varphi\right\rangle=\left\langle(J \circ \Phi)^{\prime}\left(\theta_{n}, v_{n}\right),\left(0, \Phi\left(-\theta_{n}, \varphi\right)\right)\right\rangle, \text { for any } \varphi \in H_{r}^{1}\left(\mathbb{R}^{N}\right),
$$

then, since $\theta_{n} \rightarrow 0$, we have $J^{\prime}\left(\tilde{v}_{n}\right) \rightarrow 0$ in $\left(H_{r}^{1}\left(\mathbb{R}^{N}\right)\right)^{*}$. Similar arguments as in (3.14)-(3.16) indicate that $\left\{\tilde{v}_{n}\right\} \subset H_{r}^{1}\left(\mathbb{R}^{N}\right)$ is a bounded Palais-Smale sequence of $J$ at the level $c_{1}$. Using Lemma 3.4 once more, for some $\tilde{v} \in H_{r}^{1}\left(\mathbb{R}^{N}\right)$, we have $\tilde{v}_{n} \rightarrow \tilde{v}$ strongly in $H_{r}^{1}\left(\mathbb{R}^{N}\right)$ up to a subsequence, so $\tilde{v}$ is a nontrivial critical point of $J$. The arguments in Section 2 ensure that $\tilde{u}=f(\tilde{v})$ is a positive solution of (1.3) and $\mathcal{E}(\tilde{u})=J(\tilde{v})=c_{1}>0$. The proof is finished.

## Use of AI tools declaration

The authors declare they have not used Artificial Intelligence (AI) tools in the creation of this article.

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## Conflict of interest

The authors declare there is no conflict of interest.

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