



Research article

Exploratory mean-variance portfolio selection with constant elasticity of variance models in regime-switching markets

Xiaoyu Xing*, **Xingtian Zhang** and **Jiarou Luo**

School of Sciences, Hebei University of Technology, Beichen District, Tianjin 300401, China

* **Correspondence:** Email: xingxiaoyutj@163.com.

Appendix

A. Proof of Equation (2.9)

According to Guo et al. [27], we derive the exploratory wealth process under stochastic policy Π . Assume the investor selects portfolios according to strategy Π , which is independent of the driving Brownian motion. By the Central Limit Theorem, the limiting distribution depends only on the first and second moments. Consider N independent Brownian sample paths $\{W_t^n, n = 1, 2, \dots, N\}$. For a uniform partition of $[0, T]$ with mesh size Δt , the corresponding wealth increment on $[t, t + \Delta t]$ takes the form

$$\Delta X^n(t) \approx (\mu(t, \alpha_t) - r)u(t)\Delta t + \sigma(t, \alpha_t)(S^n(t))^{\beta(t, \alpha_t)}u(t)\Delta W_t^n, \quad (\text{A.1})$$

and the corresponding risky asset is

$$\Delta S^n(t) \approx \mu(t, \alpha_t)S^n(t)\Delta t + \sigma(t, \alpha_t)(S^n(t))^{\beta(t, \alpha_t)+1}\Delta W_t^n. \quad (\text{A.2})$$

The law of large numbers yields

$$\begin{aligned}
\frac{1}{N} \sum_{n=1}^N \Delta X^n(t) &\approx \frac{1}{N} \sum_{n=1}^N \left[(\mu(t, \alpha_t) - r) u(t, \alpha_t) \Delta t + \sigma(t, \alpha_t) (S^n(t))^{\beta(t, \alpha_t)} u(t, \alpha_t) \Delta W_t^n \right] \\
&\xrightarrow{\text{a.s.}} \left((\mu(t, \alpha_t) - r) \int_R u(t, \alpha_t) d\Pi_t(u) \right) \Delta t, \\
\frac{1}{N} \sum_{n=1}^N (\Delta X^n(t))^2 &\approx \frac{1}{N} \sum_{n=1}^N \sigma^2(t, \alpha_t) (S^n(t))^{2\beta(t, \alpha_t)} u^2(t, \alpha_t) \Delta t \xrightarrow{\text{a.s.}} \left(\sigma^2(t, \alpha_t) S(t)^{2\beta(t, \alpha_t)} \int_R u^2(t, \alpha_t) d\Pi_t(u) \right) \Delta t, \\
\frac{1}{N} \sum_{n=1}^N \Delta X^n(t) \Delta S^n(t) &\approx \frac{1}{N} \sum_{n=1}^N \sigma^2(t, \alpha_t) (S^n(t))^{2\beta(t, \alpha_t)+1} u(t, \alpha_t) \Delta t \xrightarrow{\text{a.s.}} \left(\sigma^2(t, \alpha_t) S(t)^{2\beta(t, \alpha_t)+1} \int_R u(t, \alpha_t) d\Pi_t(u) \right) \Delta t,
\end{aligned} \tag{A.3}$$

on the other hand

$$\frac{1}{N} \sum_{n=1}^N \Delta X^n(t) \xrightarrow{\text{a.s.}} E[\Delta X_t], \quad \frac{1}{N} \sum_{n=1}^N (\Delta X^n(t))^2 \xrightarrow{\text{a.s.}} E[(\Delta X_t)^2], \quad \frac{1}{N} \sum_{n=1}^N \Delta X^n(t) \Delta S^n(t) \xrightarrow{\text{a.s.}} E[\Delta X(t) \Delta S(t)].$$

We replace (2.4) with the following process linked to the randomized strategy, which serves as the basis for the EMV formulation

$$dX^{\Pi}(t) = (\mu(t, \alpha_t) - r) M(t, \alpha_t) dt + \sigma(t, \alpha_t) S_t^{\beta(t, \alpha_t)} (M(t, \alpha_t) dW_t + N(t, \alpha_t) d\tilde{W}_t). \tag{A.4}$$

\tilde{W}_t is the Brownian motion independent of W_t and

$$M(t, \alpha_t) := \int_{\mathbb{R}} u(t, \alpha_t) d\Pi_t(u), \quad N^2(t, \alpha_t) := \int_{\mathbb{R}} u^2(t, \alpha_t) d\Pi_t(u) - M^2(t, \alpha_t).$$

B. Proof of Theorem 3.2

Recall the classical MV problem with regime switching (2.8). By applying the dynamic programming principle, we derive the HJB equation

$$\begin{aligned}
\min_u \left\{ & (\mu_i - r) u(t, e_i) V_x(t, s, x, e_i) + \frac{1}{2} \sigma_i^2 s^{2\beta_i} u^2(t, e_i) V_{xx}(t, s, x, e_i) + \sigma_i^2 s^{2\beta_i+1} u(t, e_i) V_{sx}(t, s, x, e_i) \right. \\
& \left. + \sum_{j=1}^n q_{ij} V(t, x, s, e_j) \right\} + V_t(t, s, x, e_i) + \mu_i s V_s(t, s, x, e_i) + \frac{1}{2} \sigma_i^2 s^{2\beta_i+2} V_{ss}(t, s, x, e_i) = 0.
\end{aligned} \tag{B.1}$$

The optimal solution $u^*(t, s, x, e_i)$ of the HJB equation is given by

$$u^*(t, s, x, e_i) = -\frac{(\mu_i - r) V_x(t, s, x, e_i) + \sigma_i^2 s^{2\beta_i+1} V_{sx}(t, s, x, e_i)}{\sigma_i^2 s^{2\beta_i} V_{xx}(t, s, x, e_i)}. \tag{B.2}$$

Assuming the value function is

$$V(t, s, x, e_i) = a(t, s, e_i)(x - w)^2 - (w - z)^2 + b(t, s, e_i). \tag{B.3}$$

Substituting the optimal strategy $u^*(t, s, x, e_i)$ and $V(t, s, x, e_i)$ into the HJB equation yields

$$\begin{aligned}
& a_t(t, s, e_i)(x-w)^2 + (\mu_i - r) \left(-\frac{(\mu_i - r)2a(t, s, e_i) + \sigma_i^2 s^{2\beta_i+1} \cdot 2a_s(t, s, e_i)}{\sigma_i^2 \cdot s^{2\beta_i} \cdot 2a} \right) 2a(t, s, e_i)(x-w)^2 \\
& + b_t(t, s, e_i) + \frac{1}{2} \sigma_i^2 s^{2\beta_i} \left[\left(\frac{(\mu_i - r)2a(t, s, e_i)(x-w) + \sigma_i^2 s^{2\beta_i+1} 2a_s(t, s, e_i)(x-w)}{\sigma_i^2 s^{2\beta_i} 2a(t, s, e_i)} \right)^2 \right] 2a(t, s, e_i) \\
& + \frac{1}{2} \sigma_i^2 s^{2\beta_i+2} [a_{ss}(t, s, e_i)(x-w)^2 + b_{ss}(t, s, e_i)] + \sum_{j=1}^n q_{ij} (a(t, s, e_j)(x-w)^2 + b(t, s, e_j)) \\
& + \sigma_i^2 s^{2\beta_i+1} \left(-\frac{(\mu_i - r)2a(t, s, e_i) + 2\sigma_i^2 s^{2\beta_i+1} a_s(t, s, e_i)}{2\sigma_i^2 s^{2\beta_i} a} \right) (2a_s(t, s, e_i)(x-w)^2) \\
& + \mu_i s (a_s(t, s, e_i)(x-w)^2 + b_s(t, s, e_i)) = 0.
\end{aligned} \tag{B.4}$$

Setting the coefficient of $(x-w)^2$ to zero, we obtain

$$\begin{aligned}
& a_t(t, s, e_i) - \left(\frac{(\mu_i - r)^2}{\sigma_i^2 s^{2\beta_i}} \right) a(t, s, e_i) + (-2(\mu_i - r) + \mu_i) s a_s(t, s, e_i) - \sigma_i^2 s^{2\beta_i+2} \frac{a_s^2(t, s, e_i)}{a(t, s, e_i)} \\
& + \frac{1}{2} \sigma_i^2 s^{2\beta_i+2} a_{ss}(t, s, e_i) + \sum_{j=1}^n q_{ij} a(t, s, e_j) = 0.
\end{aligned} \tag{B.5}$$

Setting the constant term to zero, the differential equation becomes

$$b_t(t, s, e_i) + \mu_i s b_s(t, s, e_i) + \frac{1}{2} \sigma_i^2 s^{2\beta_i+2} b_{ss}(t, s, e_i) + \sum_{j=1}^n q_{ij} (b(t, s, e_j)) = 0. \tag{B.6}$$

The solution to differential equation (B.5) can be obtained using the same method as for Equation (3.7), Equation (B.6) has a particular solution of $b(t, s, e_i) = 0$. We finally obtain the value of $\mathbf{a}(t, s)$ as

$$\mathbf{a}(t, s) = \mathbf{H}(t) \exp(\mathbf{K}(t) \mathbf{Y}), \tag{B.7}$$

where $h_i(t)$ and $k_i(t)$ satisfy the equations (3.16) and (3.17).

C. Proof of Theorem 4.1

Fix $(t, x, s, e_i) \in [0, T] \times \mathbb{R} \times \mathbb{R} \times \mathcal{N}$. Suppose the policy $\Pi = \{\Pi_v, v \in [t, T]\}$ is admissible, and let $\{X_s^\Pi, s \in [t, T]\}$ denote the corresponding wealth process. $\tilde{\Pi}$ is obtained from (4.1). Applying Itô's

lemma, we obtain

$$\begin{aligned}
V^\Pi(h, X_h^{\tilde{\Pi}}, S_h, e_i) &= V^\Pi(t, x, s, e_i) + \int_t^h V_t^\Pi(v, X_v^{\tilde{\Pi}}, S_v, \alpha_v) dv + \int_t^h V_x^\Pi(v, X_v^{\tilde{\Pi}}, S_v, \alpha_v) dX_v^{\tilde{\Pi}} \\
&\quad + \int_t^h V_s^\Pi(v, X_v^{\tilde{\Pi}}, S_v, \alpha_v) dS_v + \frac{1}{2} \int_t^h V_{xx}^\Pi(v, X_v^{\tilde{\Pi}}, S_v, \alpha_v) d\langle X^{\tilde{\Pi}}, X^{\tilde{\Pi}} \rangle_v \\
&\quad + \frac{1}{2} \int_t^h V_{ss}^\Pi(v, X_v^{\tilde{\Pi}}, S_v, \alpha_v) d\langle S, S \rangle_v + \int_t^h V_{sx}^\Pi(v, X_v^{\tilde{\Pi}}, S_v, \alpha_v) d\langle X^{\tilde{\Pi}}, S \rangle_v \\
&\quad + \int_t^h \sum_{j=1}^n q_{\alpha_v j} V(v, X_v^{\tilde{\Pi}}, S_v, e_j) dv \\
&= V^\Pi(t, x, s, e_i) + \int_t^h (\sigma_i S_v^{\beta_i} M_i^{\tilde{\Pi}} V_x^\Pi(v, X_v^{\tilde{\Pi}}, S_v, \alpha_v) + \sigma_i S_v^{\beta_i+1} V_s^\Pi(v, X_v^{\tilde{\Pi}}, S_v, \alpha_v)) dW_v \\
&\quad + \int_t^h \sigma_i S_v^{\beta_i} N_i^{\tilde{\Pi}} V_x^\Pi(v, X_v^{\tilde{\Pi}}, S_v, \alpha_v) d\tilde{W}_v \\
&\quad + \int_t^h \left(V_t^\Pi(v, X_v^{\tilde{\Pi}}, S_v, e_i) + (\mu_i - r) M_i^{\tilde{\Pi}} V_x^\Pi(v, X_v^{\tilde{\Pi}}, S_v, \alpha_v) + \mu_i S_v V_s^\Pi(v, X_v^{\tilde{\Pi}}, S_v, \alpha_v) \right. \\
&\quad \left. + \frac{1}{2} \sigma_i^2 S_v^{2\beta_i} [(M_i^{\tilde{\Pi}})^2 + (N_i^{\tilde{\Pi}})^2] V_{xx}^\Pi(v, X_v^{\tilde{\Pi}}, S_v, \alpha_v) + \frac{1}{2} \sigma_i^2 S_v^{2\beta_i+2} V_{ss}^\Pi(v, X_v^{\tilde{\Pi}}, S_v, \alpha_v) \right. \\
&\quad \left. + \sigma_i^2 S_v^{2\beta_i+1} M_i^{\tilde{\Pi}} V_{sx}^\Pi(v, X_v^{\tilde{\Pi}}, S_v, \alpha_v) + \sum_{j=1}^n q_{\alpha_v j} V(v, X_v^{\tilde{\Pi}}, S_v, e_j) \right) dv. \tag{C.1}
\end{aligned}$$

Define the stopping time as

$$\tau_n := \inf \left\{ h \geq t : \int_t^h \sigma_i^2 S_v^{2\beta_i+2} (V_s^\Pi(v, X_v^{\tilde{\Pi}}, S_v, \alpha_v))^2 + \sigma_i^2 S_v^{2\beta_i} ((N_i^{\tilde{\Pi}})^2 + (M_i^{\tilde{\Pi}})^2) (V_x^\Pi(v, X_v^{\tilde{\Pi}}, S_v, \alpha_v))^2 dv \geq n \right\},$$

where $n \geq 1$, we obtain the following results

$$\begin{aligned}
V^\Pi(t, x, s, e_i) &= E \left[V^\Pi(h \wedge \tau_n, X_{h \wedge \tau_n}^{\tilde{\Pi}}, S_{h \wedge \tau_n}, \alpha_{h \wedge \tau_n}) \right. \\
&\quad - \int_t^{h \wedge \tau_n} \left(V_t^\Pi(v, X_v^{\tilde{\Pi}}, S_v, \alpha_v) + (\mu_i - r) M_i^{\tilde{\Pi}} V_x^\Pi(v, X_v^{\tilde{\Pi}}, S_v, \alpha_v) \right. \\
&\quad \left. + \mu_i S_v V_s^\Pi(v, X_v^{\tilde{\Pi}}, S_v, \alpha_v) + \frac{1}{2} \sigma_i^2 S_v^{2\beta_i} [(M_i^{\tilde{\Pi}})^2 + (N_i^{\tilde{\Pi}})^2] V_{xx}^\Pi(v, X_v^{\tilde{\Pi}}, S_v, \alpha_v) \right. \\
&\quad \left. + \frac{1}{2} \sigma_i^2 S_v^{2\beta_i+2} V_{ss}^\Pi(v, X_v^{\tilde{\Pi}}, S_v, \alpha_v) + \sigma_i^2 S_v^{2\beta_i+1} M_i^{\tilde{\Pi}} V_{sx}^\Pi(v, X_v^{\tilde{\Pi}}, S_v, \alpha_v) \right. \\
&\quad \left. + \sum_{j=1}^n q_{\alpha_v j} V(v, X_v^{\tilde{\Pi}}, S_v, e_j) \right) dv \right]. \tag{C.2}
\end{aligned}$$

Under standard verification arguments and assuming V^Π is sufficiently smooth, we have

$$\begin{aligned} & V_t^\Pi(t, x, s, e_i) + (\mu_i - r) M_i^\Pi V_x^\Pi(t, x, s, e_i) + \frac{1}{2} \sigma_i^2 s^{2\beta_i} ((M_i^\Pi)^2 + (N_i^\Pi)^2) V_{xx}^\Pi(t, x, s, e_i) + \mu_i s V_s^\Pi(t, x, s, e_i) \\ & + \frac{1}{2} \sigma_i^2 s^{2\beta_i+2} V_{ss}^\Pi(t, x, s, e_i) + \sigma_i^2 s^{2\beta_i+1} M_i^\Pi V_{sx}^\Pi(t, x, s, e_i) - \lambda(t) \Phi(\Pi) + \sum_{j=i}^n q_{ij} V(t, x, s, e_j) = 0, \end{aligned} \quad (\text{C.3})$$

for any $(t, x, s, e_i) \in [0, T] \times \mathbb{R} \times \mathbb{R} \times \mathcal{N}$, we have

$$\begin{aligned} & V_t^\Pi(t, x, s, e_i) + \min_{\Pi'} \left((\mu_i - r) M_i^{\Pi'} V_x^{\Pi'}(t, x, s, e_i) + \frac{1}{2} \sigma_i^2 s^{2\beta_i} ((M_i^{\Pi'})^2 + (N_i^{\Pi'})^2) V_{xx}^{\Pi'}(t, x, s, e_i) + \mu_i s V_s^{\Pi'}(t, x, s, e_i) \right. \\ & \left. + \frac{1}{2} \sigma_i^2 s^{2\beta_i+2} V_{ss}^{\Pi'}(t, x, s, e_i) + \sigma_i^2 s^{2\beta_i+1} M_i^{\Pi'} V_{sx}^{\Pi'}(t, x, s, e_i) - \lambda(t) \Phi(\Pi') + \sum_{j=1}^n q_{ij} V(t, x, s, e_j) \right) \leq 0. \end{aligned} \quad (\text{C.4})$$

The infimum in the Hamiltonian operator of the HJB equation $\tilde{\Pi}$ is explicitly attained by the feedback strategy derived from the regularizer's optimality condition in (C.4). Specifically

$$V^\Pi(t, x, s, e_i) \geq E \left[V^\Pi(h \wedge \tau_n, X_{h \wedge \tau_n}^{\tilde{\Pi}}, S_{h \wedge \tau_n}^{\tilde{\Pi}}, \alpha_{h \wedge \tau_n}) - \int_t^{h \wedge \tau_n} \lambda(v) \Phi(\tilde{\Pi}_v) dv \mid X_t^{\tilde{\Pi}} = x \right]. \quad (\text{C.5})$$

For any fixed $(t, x, s, e_i) \in [0, T] \times \mathbb{R} \times \mathbb{R} \times \mathcal{N}$, let $h = T$. Given the terminal condition $V^\Pi(T, x, s, e_i) = V^{\tilde{\Pi}}(T, x, s, e_i) = (x - w)^2 - (w - z)^2$ and the admissibility of $\tilde{\Pi}$, we apply the Dominated Convergence Theorem as $n \rightarrow \infty$ to obtain

$$V^\Pi(t, x, s, e_i) \geq E \left[V^{\tilde{\Pi}}(T, X_T^{\tilde{\Pi}}, S_T^{\tilde{\Pi}}, \alpha_T) - \int_t^T \lambda(v) \Phi(\tilde{\Pi}_v) dv \mid X_t^{\tilde{\Pi}} = x \right] = V^{\tilde{\Pi}}(t, x, s, e_i). \quad (\text{C.6})$$



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