



MEAN-FIELD LIMIT OF COLLECTIVE DYNAMICS WITH TIME-VARYING WEIGHTS

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ABSTRACT. In this paper, we derive the mean-field limit of a collective dynamics model with time-varying weights, for weight dynamics that preserve the total mass of the system as well as indistinguishability of the agents. The limit equation is a transport equation with source, where the (non-local) transport term corresponds to the position dynamics, and the (non-local) source term comes from the weight redistribution among the agents. We show existence and uniqueness of the solution for both microscopic and macroscopic models and introduce a new empirical measure taking into account the weights. We obtain the convergence of the microscopic model to the macroscopic one by showing continuity of the macroscopic solution with respect to the initial data, in the Wasserstein and Bounded Lipschitz topologies.

1. Introduction. A wide range of mathematical models fall into the category of *interacting particle systems*. Whether they describe the trajectories of colliding particles [7], the behavior of animal groups [1, 6, 13, 22], the cooperation of robots [4] or the evolution of opinions [9, 12, 15], their common objective is to model the dynamics of a group of particles in interaction. Some of the most widely used models include the Hegselmann-Krause model for opinion dynamics [15], the Vicsek model for fish behavior [22] and the Cucker-Smale model for bird flocks [6]. Two main points of view can be adopted in the modeling process. The Lagrangian (or microscopic) approach deals with individual particles and models the trajectory of each one separately, via a system of coupled Ordinary Differential Equations (ODE). This approach's major limitation is that the dimension of the resulting system is proportional to the number of particles, which can quickly become unmanageable. To combat this effect, one can instead adopt the Eulerian (or macroscopic) approach, and track the concentration of particles at each point of the state space. The resulting equation is a Partial Differential Equation (PDE) giving the evolution of the density of particles over the state space, and whose dimension is independent of the number of particles.

The question of how microscopic properties of particles give rise to macroscopic properties of the system is fundamental in physics. A way to connect the microscopic and the macroscopic points of view is through the *mean-field limit*. First

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introduced in the context of gas dynamics, the mean-field limit, applied to systems of weakly interacting particles with a large radius of interaction, derives the macroscopic equation as the limit of the microscopic one when the number of particles tends to infinity [3, 10]. The term *mean-field* refers to the fact that the effects of all particles located at the same position are averaged, instead of considering the individual force exerted by each particle. The mean-field limits of the Hegselmann-Krause, Vicsek and Cucker-Smale models were derived in [5, 8, 10, 14]. More specifically, the mean-field limit of a general system of interacting particles described by

$$\dot{x}_i(t) = \frac{1}{N} \sum_{j=1}^N \phi(x_j(t) - x_i(t)) \quad (1)$$

is given by the non-local transport equation in the space of probability measures

$$\begin{aligned} \partial_t \mu_t(x) + \nabla \cdot (V[\mu_t](x) \mu_t(x)) &= 0, \\ V[\mu_t](x) &= \int_{\mathbb{R}^d} \phi(y - x) d\mu_t(y), \end{aligned} \quad (2)$$

where $\mu_t(x)$ represents the density of particles at position x and time t , and where the velocity $V[\mu_t]$ is given by convolution with the density of particles. The proof of the mean-field limit lies on the key observation that the *empirical measure* $\mu_t^N = \frac{1}{N} \sum_{i=1}^N \delta_{x_i(t)}$, defined from the positions of the N particles satisfying the microscopic system (1), is actually a solution to the macroscopic equation (2). Notice that the passage from the microscopic system to its macroscopic formulation via the empirical measure entails an irreversible information loss. Indeed, the empirical measure keeps track only of the number (or proportion) of particles at each point of space, and loses the information of the indices, that is the “identity” of the particles. This observation illustrates a necessary condition for the mean-field limit to hold: the *indistinguishability* of particles. Informally, two particles x_i, x_j are said to be indistinguishable if they can be exchanged without modifying the dynamics of the other particles. System (1) satisfies trivially this condition, since the interaction function ϕ depends only on the positions of the particles and not on their indices.

In [16, 17], we introduced an augmented model for opinion dynamics with time-varying influence. In this model, each particle, or agent, is represented both by its opinion x_i and its weight of influence m_i . The weights are assumed to evolve in time via their own dynamics, and model a modulating social hierarchy within the group, where the most influential agents (the ones with the largest weights) have a stronger impact on the dynamics of the group. The microscopic system is written as follows:

$$\begin{cases} \dot{x}_i(t) = \frac{1}{M} \sum_{j=1}^N m_j(t) \phi(x_j(t) - x_i(t)), \\ \dot{m}_i(t) = \psi_i((x_j(t))_{j \in \{1, \dots, N\}}, (m_j(t))_{j \in \{1, \dots, N\}}), \end{cases} \quad (3)$$

where the functions ψ_i give the weights’ dynamics and M represents the sum of all initial weights.

As for the classical dynamics (1), we aim to address the natural question of the large population limit. To take into account the weights of the particles, we can

define a modified empirical measure by $\mu_t^N = \frac{1}{M} \sum_{i=1}^N m_i(t) \delta_{x_i(t)}$, so that $\mu_t^N(x)$ represents the *weighted proportion* of the population with opinion x at time t . In this new context, informally, indistinguishability is satisfied if agents (x_i, m_i) and (x_j, m_j) can be exchanged or grouped without modifying the overall dynamics. However, this condition may or may not be satisfied, depending on the weight dynamics ψ_i in the general system (3). In [2], we derived the graph limit of system (3) for a general class of models in which indistinguishability is not necessarily satisfied. Here, on the other hand, in order to derive the mean-field limit of system (3), we will focus on a subclass of mass dynamics that does preserve indistinguishability of the particles, given by:

$$\psi_i(x, m) := m_i \frac{1}{M^q} \sum_{j_1=1}^N \cdots \sum_{j_q=1}^N m_{j_1} \cdots m_{j_q} S(x_i, x_{j_1}, \dots, x_{j_q}). \quad (4)$$

Given symmetry assumptions on S , this specific choice of weight dynamics ensures that the weights remain positive, and also preserves the total weight of the system (as will be proven in Proposition 1). From a modeling point of view, since the weights represent the agents' influence on the group, it is natural to restrict them to positive values. The total weight conservation implies that no weight is created within the system, and that the only weight variations are due to redistribution. One can easily prove that if $(x_i, m_i)_{i \in \{1, \dots, N\}}$ satisfy the microscopic system (3)-(4), the modified empirical measure μ_t^N satisfies the following transport equation with source

$$\partial_t \mu_t(x) + \nabla \cdot (V[\mu_t](x) \mu_t(x)) = h[\mu_t](x), \quad (5)$$

in which the left-hand part of the equation, representing non-local transport, is identical to the limit PDE (2) for the system without time-varying weights. The non-local source term of the right-hand side corresponds to the weight dynamics and is given by convolution with μ_t :

$$h[\mu_t](x) = \left(\int_{(\mathbb{R}^d)^q} S(x, y_1, \dots, y_q) d\mu_t(y_1) \cdots d\mu_t(y_q) \right) \mu_t(x).$$

Since we impose no restriction on the sign of S , this source term $h[\mu_t]$ belongs to the set of signed Radon measures, even if (as we will show), μ_t remains a probability measure at all time.

In [21], well-posedness of (5) was proven for a globally bounded source term satisfying a global Lipschitz condition with respect to the density μ_t . However, the possibly high-order non-linearity of our source term $h[\mu_t]$ prevents us from applying these results in our setting.

Thus, the aim of this paper is to give a meaning to the transport equation with source (5), to prove existence and uniqueness of its solution, and to show that it is the mean-field limit of the microscopic system (3)-(4). Denoting by $\mathcal{P}_c(\mathbb{R}^d)$ the set of probability measures of \mathbb{R}^d with compact support, our central results can be stated in the form of two main theorems:

Theorem 1.1. *For all $T > 0$ and $\mu_0 \in \mathcal{P}_c(\mathbb{R}^d)$, there exists a unique weak solution $\mu_t \in C([0, T], \mathcal{P}_c(\mathbb{R}^d))$ to equation (5) satisfying $\mu_{t=0} = \mu_0$.*

Theorem 1.2. *For each $N \in \mathbb{N}$, let $(x_i^N, m_i^N)_{i \in \{1, \dots, N\}}$ be the solutions to (3)-(4) on $[0, T]$, and let $\mu_t^N := \frac{1}{M} \sum_{i=1}^N m_i^N(t) \delta_{x_i^N(t)}$ be the corresponding empirical*

measures. If there exists $\mu_0 \in \mathcal{P}_c(\mathbb{R}^d)$ such that $\lim_{N \rightarrow \infty} \mathcal{D}(\mu_0^N, \mu_0) = 0$, then for all $t \in [0, T]$,

$$\lim_{N \rightarrow \infty} \mathcal{D}(\mu_t^N, \mu_t) = 0,$$

where $\mu_t \in \mathcal{P}_c(\mathbb{R}^d)$ is the solution to the transport equation with source (5).

The convergence holds in the Bounded Lipschitz and in the Wasserstein topologies, where \mathcal{D} represents either the Bounded Lipschitz distance, or any of the p -Wasserstein distances ($p \in \mathbb{N}^*$). In particular, we show that the solution stays a probability measure at all time, a consequence of the total mass conservation at the microscopic level.

We begin by presenting the microscopic model, and by showing that under key assumptions on the mass dynamics, it preserves not only indistinguishability of the agents, but also positivity of the weights as well as the total weight of the system. We then recall the definition and relationship between the Wasserstein, Generalized Wasserstein and Bounded Lipschitz distances. The third section is dedicated to the proof of existence and uniqueness of the solution to the macroscopic equation, by means of an operator-splitting numerical scheme. We show continuity with respect to the initial data in the Bounded Lipschitz and Wasserstein topologies. This allows us to conclude with the key convergence result, in Section 4. Lastly, we illustrate our results with numerical simulations comparing the solutions to the microscopic and the macroscopic models, for a specific choice of weight dynamics.

2. Microscopic model. In [16], a general model was introduced for opinion dynamics with time-varying influence. Given a set of N agents with positions and weights respectively given by $(x_i)_{i \in \{1, \dots, N\}}$ and $(m_i)_{i \in \{1, \dots, N\}}$, an agent j influences another agent i 's position (or opinion) depending on the distance separating i and j , as well as on the weight (or “influence”) of j . In parallel, the evolution of each agent's weight m_j depends on all the agents' positions and weights. In this general setting, the system can be written as:

$$\begin{cases} \dot{x}_i(t) = \frac{1}{M} \sum_{j=1}^N m_j(t) \phi(x_j(t) - x_i(t)), \\ \dot{m}_i(t) = \psi_i((x_j(t))_{j \in \{1, \dots, N\}}, (m_j(t))_{j \in \{1, \dots, N\}}), \end{cases} \quad i \in \{1, \dots, N\}, \quad (6)$$

where $M = \sum_{i=1}^N m_i^0$ represents the initial total mass of the system, $\phi \in C(\mathbb{R}^{dN}; \mathbb{R}^{dN})$ denotes the interaction function and $\psi_i \in C(\mathbb{R}^{dN} \times \mathbb{R}^N; \mathbb{R})$ dictates the weights' evolution. Well-posedness of this general system was proven in [2], for suitable weight dynamics ψ_i .

In this paper, we aim to study the mean-field limit of system (6) for a more specific choice of weight dynamics that will ensure the following properties:

- positivity of the weights: $m_i \geq 0$ for all $i \in \{1, \dots, N\}$;
- conservation of the total mass: $\sum_{i=1}^N m_i \equiv M$;
- indistinguishability of the agents.

These key properties will be used extensively to prove well-posedness of the system and convergence to the mean-field limit. We now introduce the model that will be our focus for the rest of the paper. Let $(x_i^0)_{i \in \{1, \dots, N\}} \in \mathbb{R}^{dN}$ and $(m_i^0)_{i \in \{1, \dots, N\}} \in (\mathbb{R}^+)^N$. We study the evolution of the N positions and weights according to the following dynamics:

$$\begin{cases} \dot{x}_i(t) = \frac{1}{M} \sum_{j=1}^N m_j(t) \phi(x_j(t) - x_i(t)), \\ x_i(0) = x_i^0, \\ \dot{m}_i(t) = m_i(t) \frac{1}{M^q} \sum_{j_1=1}^N \cdots \sum_{j_q=1}^N m_{j_1}(t) \cdots m_{j_q}(t) S(x_i(t), x_{j_1}(t), \dots, x_{j_q}(t)), \\ m_i(0) = m_i^0 \end{cases} \quad (7)$$

where $q \in \mathbb{N}$, and ϕ and S satisfy the following hypotheses:

Hypothesis 1. $\phi \in \text{Lip}(\mathbb{R}^d; \mathbb{R}^d)$ with $\|\phi\|_{\text{Lip}} := L_\phi$.

Hypothesis 2. $S \in C((\mathbb{R}^d)^{q+1}; \mathbb{R})$ is globally bounded and Lipschitz. More specifically, there exist \bar{S} , $L_S > 0$ such that

$$\forall y \in (\mathbb{R}^d)^{q+1}, \quad |S(y)| \leq \bar{S}. \quad (8)$$

and

$$\forall y \in (\mathbb{R}^d)^{q+1}, \forall z \in (\mathbb{R}^d)^{q+1}, |S(y_0, \dots, y_q) - S(z_0, \dots, z_q)| \leq L_S \sum_{i=0}^q |y_i - z_i|. \quad (9)$$

Furthermore, we require that S satisfy the following skew-symmetry property: there exists $(i, j) \in \{0, \dots, q\}^2$ such that for all $y \in (\mathbb{R}^d)^{q+1}$,

$$S(y_0, \dots, y_i, \dots, y_j, \dots, y_q) = -S(y_0, \dots, y_j, \dots, y_i, \dots, y_q). \quad (10)$$

Remark 1. The most common models encountered in the literature use an interaction function ϕ of one of the following forms:

- $\phi(x) := a(|x|)x$ for some $a : \mathbb{R}^+ \rightarrow \mathbb{R}$
- $\phi(x) := \nabla W(x)$ is the gradient of some interaction potential $W : \mathbb{R}^d \rightarrow \mathbb{R}$.

Remark 2. The global boundedness of S (8) is assumed to simplify the presentation, but all our results also hold without this assumption. Indeed, the continuity of S is enough to infer the existence of a global bound S_R as long as all x_i are contained in the ball $B(0, R)$, or, in the macroscopic setting, as long as $\text{supp}(\mu) \subset B(0, R)$.

In (7), the q nested sums allow for a great variety of models, for instance involving averages of various quantities. In practice, most models of interest will correspond to $q \in \{1, 2, 3\}$ (see [2] (Section 5.2), [16] (Section 2.1), [17] (Section 5.1), and Section 6).

The skew-symmetric property of S is essential in order to prevent blow-up of the individual weights. Indeed, as we show in the following proposition, it allows us to prove that the total mass is conserved and that each of the weights stays positive. Thus, despite the non-linearity of the weight dynamics, the weights remain bounded at all time, and in particular there can be no finite-time blow-up, which will ensure the existence of the solution.

Proposition 1. *Let $(x, m) \in C([0, T]; (\mathbb{R}^d)^N \times \mathbb{R}^N)$ be a solution to (7). Then it holds:*

- (i) *For all $t \in [0, T]$, $\sum_{i=1}^N m_i(t) = M$.*
- (ii) *If for all $i \in \{1, \dots, N\}$, $m_i^0 > 0$, then for all $t \in [0, T]$, for all $i \in \{1, \dots, N\}$, $m_i(t) > 0$.*
- (iii) *If for all $i \in \{1, \dots, N\}$, $m_i^0 > 0$, then for all $t \in [0, T]$, for all $i \in \{1, \dots, N\}$, $m_i(t) \leq m_i^0 e^{S t}$.*

Proof. (i) Without loss of generality, we suppose that for all $y \in (\mathbb{R}^d)^{q+1}$,

$$S(y_0, y_1, \dots, y_q) = -S(y_1, y_0, \dots, y_q).$$

Then it holds

$$\begin{aligned} \frac{d}{dt} \sum_{i=1}^N m_i &= \frac{1}{M^q} \sum_{j_2=1}^N \cdots \sum_{j_q=1}^N \left[\sum_{j_0 < j_1} m_{j_0} \cdots m_{j_q} S(x_{j_0}, \dots, x_{j_q}) \right. \\ &\quad \left. + \sum_{j_0 > j_1} m_{j_0} \cdots m_{j_q} S(x_{j_0}, \dots, x_{j_q}) \right] \\ &= \frac{1}{M^q} \sum_{j_2=1}^N \cdots \sum_{j_q=1}^N \left[\sum_{j_0 < j_1} m_{j_0} \cdots m_{j_q} S(x_{j_0}, x_{j_1}, \dots, x_{j_q}) \right. \\ &\quad \left. + \sum_{j_1 > j_0} m_{j_0} \cdots m_{j_q} S(x_{j_1}, x_{j_0}, \dots, x_{j_q}) \right] = 0. \end{aligned}$$

(ii) Let us now suppose that $m_i^0 > 0$ for all $i \in \{1, \dots, N\}$. Let $t^* := \inf\{t \geq 0 \mid \exists i \in \{1, \dots, N\}, m_i(t) = 0\}$. Assume that $t^* < \infty$. Then for all $i \in \{1, \dots, N\}$, for all $t < t^*$,

$$\begin{aligned} \dot{m}_i &= m_i \frac{1}{M^q} \sum_{j_1=1}^N \cdots \sum_{j_q=1}^N m_{j_1} \cdots m_{j_q} S(x_i, x_{j_1}, \dots, x_{j_q}) \\ &\geq -m_i \frac{1}{M^q} \sum_{j_1=1}^N \cdots \sum_{j_q=1}^N m_{j_1} \cdots m_{j_q} \bar{S} = -\bar{S} m_i, \end{aligned}$$

where the last equality comes from the first part of the proposition. From Gronwall's Lemma, for all $t < t^*$, it holds

$$m_i(t) \geq m_i^0 e^{-\bar{S}t} \geq m_i^0 e^{-\bar{S}t^*} > 0.$$

Since m_i is continuous, this contradicts the fact that there exists $i \in \{1, \dots, N\}$ such that $m_i(t^*) = 0$. Hence for all $t \geq 0$, $m_i(t) > 0$.

(iii) Lastly, the third point is a consequence of Gronwall's Lemma. \square

Well-posedness of the system (7) is a consequence of the boundedness of the total mass. We have the following result.

Proposition 2. *For all $T > 0$, there exists a unique solution to (7) defined on the interval $[0, T]$.*

Proof. The proof, modeled after the proofs for the well-posedness of the Graph Limit model in [2], is provided in the Appendix. \square

We draw attention to the fact that System (7) also preserves indistinguishability of the agents. This property, introduced in [17] and [2], is necessary for the definition of empirical measure to make sense in this new setting.

Indeed, the empirical measure, defined by $\mu_t^N = \frac{1}{M} \sum_{i=1}^N m_i^N(t) \delta_{x_i^N(t)}$ is invariant by relabeling of the indices or by grouping of the agents. Hence for the macroscopic model to reflect the dynamics of the microscopic one, the microscopic dynamics must be the same for relabeled or grouped initial data. This leads us to the following *indistinguishability* condition:

Definition 2.1. We say that system (6) satisfies *indistinguishability* if for all $J \subseteq \{1, \dots, N\}$, for all $(x^0, m^0) \in \mathbb{R}^{dN} \times \mathbb{R}^N$ and $(y^0, p^0) \in \mathbb{R}^{dN} \times \mathbb{R}^N$ satisfying

$$\begin{cases} x_i^0 = y_i^0 = x_j^0 = y_j^0 & \text{for all } (i, j) \in J^2 \\ x_i^0 = y_i^0 & \text{for all } i \in \{1, \dots, N\} \\ m_i^0 = p_i^0 & \text{for all } i \in J^c \\ \sum_{i \in J} m_i^0 = \sum_{i \in J} p_i^0, \end{cases}$$

the solutions $t \mapsto (x(t), m(t))$ and $t \mapsto (y(t), p(t))$ to system (6) with respective initial conditions (x^0, m^0) and (y^0, p^0) satisfy for all $t \geq 0$,

$$\begin{cases} x_i(t) = y_i(t) = x_j(t) = y_j(t) & \text{for all } (i, j) \in J^2 \\ x_i(t) = y_i(t) & \text{for all } i \in \{1, \dots, N\} \\ m_i(t) = p_i(t) & \text{for all } i \in J^c \\ \sum_{i \in J} m_i(t) = \sum_{i \in J} p_i(t). \end{cases}$$

Whereas the general system (6) does not necessarily satisfy this property, one easily proves that system (7) does satisfy indistinguishability (see [2] for the detailed proof).

3. Notations and distances. Let $\mathcal{P}(\mathbb{R}^d)$ denote the set of probability measures of \mathbb{R}^d , $\mathcal{P}_c(\mathbb{R}^d)$ the set of probability measures with compact support, $\mathcal{M}(\mathbb{R}^d)$ the set of (positive) Borel measures with finite mass, and $\mathcal{M}^s(\mathbb{R}^d)$ the set of signed Radon measures. Let $\mathcal{B}(\mathbb{R}^d)$ denote the family of Borel subsets of \mathbb{R}^d .

From here onward, $C(E)$ (respectively $C(E; F)$) will denote the set of continuous functions of E (resp. from E to F), $C^{\text{Lip}}(E)$ (respectively $C^{\text{Lip}}(E; F)$) the set of Lipschitz functions, and C_c (respectively $C_c(E; F)$) the set of functions with compact support. The Lipschitz norm of a function $f \in C^{\text{Lip}}(E; F)$ is defined by

$$\|f\|_{\text{Lip}} := \sup_{x, y \in E, x \neq y} \frac{d_F(f(x) - f(y))}{d_E(x - y)}.$$

For all $\mu \in \mathcal{M}(\mathbb{R}^d)$, we will denote by $|\mu| := \mu(\mathbb{R}^d)$ the total mass of μ .

For all $\mu \in \mathcal{M}^s(\mathbb{R}^d)$, let μ_+ and μ_- respectively denote the upper and lower variations of μ , defined by $\mu_+(E) := \sup_{A \subseteq E} \mu(A)$ and $\mu_-(E) := -\inf_{A \subseteq E} \mu(A)$ for all $E \in \mathcal{B}(\mathbb{R}^d)$, so that $\mu = \mu_+ - \mu_-$. We will denote by $|\mu|$ the total variation of μ defined by $|\mu| := \mu_+(\mathbb{R}^d) + \mu_-(\mathbb{R}^d)$.

3.1. Generalized Wasserstein and bounded Lipschitz distances. We begin by giving a brief reminder on the various distances that will be used throughout this paper. The natural distance to study the transport of the measure μ_t by the non-local vector field $V[\mu_t]$ is the p -Wasserstein distance W_p , defined for probability measures with bounded p -moment $\mathcal{P}_p(\mathbb{R}^d)$ (see [23]):

$$W_p(\mu, \nu) := \left(\inf_{\pi \in \Pi(\mu, \nu)} \int_{\mathbb{R}^d \times \mathbb{R}^d} |x - y|^p d\pi(x, y) \right)^{1/p},$$

for all $\mu, \nu \in \mathcal{P}_p(\mathbb{R}^d)$, where Π is the set of transference plans with marginals μ and ν , defined by

$$\Pi(\mu, \nu) = \{\pi \in \mathcal{P}(\mathbb{R}^d \times \mathbb{R}^d); \forall A, B \in \mathcal{B}(\mathbb{R}^d), \pi(A \times \mathbb{R}^d) = \mu(A), \pi(\mathbb{R}^d \times B) = \nu(B)\}.$$

In the particular case $p = 1$, there is an equivalent definition of W_1 by the Kantorovich-Rubinstein duality :

$$W_1(\mu, \nu) = \sup \left\{ \int_{\mathbb{R}^d} f(x) d(\mu(x) - \nu(x)); \quad f \in C_c^{0,\text{Lip}}(\mathbb{R}^d), \|f\|_{\text{Lip}} \leq 1 \right\}$$

for all $\mu, \nu \in \mathcal{P}_1(\mathbb{R}^d)$. The Wasserstein distance was extended in [18, 19] to the set of positive Radon measures with possibly different masses. For $a, b > 0$, the generalized Wasserstein distance $W_p^{a,b}$ is defined by:

$$W_p^{a,b}(\mu, \nu) = \left(\inf_{\tilde{\mu}, \tilde{\nu} \in \mathcal{M}_p(\mathbb{R}^d), |\tilde{\mu}| = |\tilde{\nu}|} a^p (|\mu - \tilde{\mu}| + |\nu - \tilde{\nu}|)^p + b^p \tilde{W}_p^p(\tilde{\mu}, \tilde{\nu}) \right)^{1/p}$$

for all $\mu, \nu \in \mathcal{M}_p(\mathbb{R}^d)$, where $\mathcal{M}_p(\mathbb{R}^d)$ denotes the set of positive Radon measures with bounded p -moment, and $\tilde{W}_p(\tilde{\mu}, \tilde{\nu})$ is defined for all positive measures $\tilde{\mu}, \tilde{\nu}$ with the same mass, by $\tilde{W}_p(\tilde{\mu}, \tilde{\nu}) = 0$ if $|\tilde{\mu}| = |\tilde{\nu}| = 0$ and $\tilde{W}_p(\tilde{\mu}, \tilde{\nu}) = |\tilde{\mu}|^{1/p} W_p(\frac{\tilde{\mu}}{|\tilde{\mu}|}, \frac{\tilde{\nu}}{|\tilde{\nu}|})$ if $|\tilde{\mu}| = |\tilde{\nu}| > 0$.

Remark 3. Observe that the classical and the generalized Wasserstein distances do not generally coincide on the set of probability measures. Indeed, the Wasserstein distance between μ and ν represents the cost of transporting μ to ν , and is inextricably linked to the distance between their supports. The generalized Wasserstein distance, on the other hand, allows one to choose between *transporting* μ to ν (with a cost proportional to b) and *creating or removing mass* from μ or ν (with a cost proportional to a). Taking for instance $\mu = \delta_{x_1}$ and $\nu = \delta_{x_2}$, the Wasserstein distance $W_p(\delta_{x_1}, \delta_{x_2}) = d(x_1, x_2)$ increases linearly with the distance between the centers of mass of μ and ν . However, one can easily see that

$$\begin{aligned} W_1^{1,1}(\delta_{x_1}, \delta_{x_2}) &= \inf_{0 \leq \varepsilon \leq 1} (|\delta_{x_1} - \varepsilon \delta_{x_1}| + |\delta_{x_2} - \varepsilon \delta_{x_2}| + \varepsilon W_p(\delta_{x_1}, \delta_{x_2})) \\ &= \inf_{0 \leq \varepsilon \leq 1} (2(1 - \varepsilon) + \varepsilon d(x_1, x_2)) \end{aligned}$$

from which it holds: $W_1^{1,1}(\delta_{x_1}, \delta_{x_2}) = \min(d(x_1, x_2), 2)$.

More generally, if $\mu, \nu \in \mathcal{P}_p(\mathbb{R}^d)$, taking $\tilde{\mu} = \mu$ and $\tilde{\nu} = \nu$ in the definition of $W_p^{a,b}$ yields $W_p^{a,b}(\mu, \nu) \leq b W_p(\mu, \nu)$. On the other hand, taking $\tilde{\mu} = \tilde{\nu} = 0$ yields $W_p^{a,b}(\mu, \nu) \leq a(|\mu| + |\nu|)$. In particular, for $a = b = 1$, the generalized Wasserstein distance $W_1^{1,1}$ also satisfies a duality property and coincides with the *Bounded Lipschitz Distance* $\rho(\mu, \nu)$ (see [11]): for all $\mu, \nu \in \mathcal{M}(\mathbb{R}^d)$, $W_1^{1,1}(\mu, \nu) = \rho(\mu, \nu)$, where

$$\rho(\mu, \nu) := \sup \left\{ \int_{\mathbb{R}^d} f(x) d(\mu(x) - \nu(x)); \quad f \in C_c^{0,\text{Lip}}(\mathbb{R}^d), \|f\|_{\text{Lip}} \leq 1, \|f\|_{L^\infty} \leq 1 \right\}.$$

In turn, this Generalized Wasserstein distance was extended in [21] to the space $\mathcal{M}_1^s(\mathbb{R}^d)$ of signed measures with finite mass and bounded first moment as follows:

$$\forall \mu, \nu \in \mathcal{M}_1^s(\mathbb{R}^d), \quad \mathbb{W}_1^{a,b}(\mu, \nu) = W_1^{a,b}(\mu_+ + \nu_-, \mu_- + \nu_+)$$

where μ_+, μ_-, ν_+ and ν_- are any measures in $\mathcal{M}(\mathbb{R}^d)$ such that $\mu = \mu_+ - \mu_-$ and $\nu = \nu_+ - \nu_-$. We draw attention to the fact that for positive measures, the two generalized Wasserstein distances coincide:

$$\forall \mu, \nu \in \mathcal{M}_1(\mathbb{R}^d), \quad \mathbb{W}_1^{a,b}(\mu, \nu) = W_1^{a,b}(\mu, \nu).$$

Again, for $a = b = 1$, the duality formula holds and the Generalized Wasserstein distance $\mathbb{W}_1^{1,1}$ is equal to the Bounded Lipschitz distance ρ :

$$\forall \mu, \nu \in \mathcal{M}_1^s(\mathbb{R}^d), \quad \mathbb{W}_1^{1,1}(\mu, \nu) = \rho(\mu, \nu).$$

From here onward, we will denote by $\rho(\mu, \nu)$ the Bounded Lipschitz distance, equal to the generalized Wasserstein distances $\mathbb{W}_1^{1,1}$ on $\mathcal{M}(\mathbb{R}^d)$ and $\mathbb{W}_1^{1,1}$ on $\mathcal{M}^s(\mathbb{R}^d)$. The properties of the Generalized Wasserstein distance mentioned above give us the following estimate, that will prove useful later on:

$$\rho(\mu, \nu) \leq |\mu| + |\nu|. \quad (11)$$

We recall other properties of the Generalized Wasserstein distance proven in [21] (Lemma 18 and Lemma 33). Although they hold for any $\mathbb{W}_1^{a,b}$, we write them here in the particular case $\mathbb{W}_1^{1,1} = \rho$:

Proposition 3. *Let $\mu_1, \mu_2, \nu_1, \nu_2$ in $\mathcal{M}^s(\mathbb{R}^d)$ with finite mass on \mathbb{R}^d . It holds:*

- $\rho(\mu_1 + \nu_1, \mu_2 + \nu_2) = \rho(\mu_1, \mu_2)$
- $\rho(\mu_1 + \nu_1, \mu_2 + \nu_2) \leq \rho(\mu_1, \mu_2) + \rho(\nu_1, \nu_2)$

The following proposition, proven in [21], holds for any $\mathbb{W}_1^{a,b}$. Again, for simplicity, we state it for the particular case of the distance ρ . Note that to simplify notations and to differentiate from function norms, all vector norms for elements of \mathbb{R}^d , $d \geq 1$, will be written $|\cdot|$. The difference with the mass or total variation of a measure will be clear from context.

Proposition 4. *Let $v_1, v_2 \in C([0, T] \times \mathbb{R}^d)$ be two vector fields, both satisfying for all $t \in [0, T]$ and $x, y \in \mathbb{R}^d$ the properties $|v_i(t, x) - v_i(t, y)| \leq L|x - y|$ and $|v_i(t, x)| \leq M$, where $i \in \{1, 2\}$. Let $\mu, \nu \in \mathcal{M}^s(\mathbb{R}^d)$. Let $\Phi_t^{v_i}$ denote the flow of v_i , that is the unique solution to*

$$\frac{d}{dt} \Phi_t^{v_i}(x) = v_i(t, \Phi_t^{v_i}(x)); \quad \Phi_0^{v_i}(x) = x.$$

Then

- $\rho(\Phi_t^{v_1} \# \mu, \Phi_t^{v_1} \# \nu) \leq e^{Lt} \rho(\mu, \nu)$
- $\rho(\mu, \Phi_t^{v_1} \# \mu) \leq tM|\mu|$
- $\rho(\Phi_t^{v_1} \# \mu, \Phi_t^{v_2} \# \mu) \leq |\mu| \frac{e^{Lt} - 1}{L} \|v_1 - v_2\|_{L^\infty(0, T; \mathcal{C}^0)}$
- $\rho(\Phi_t^{v_1} \# \mu, \Phi_t^{v_2} \# \nu) \leq e^{Lt} \rho(\mu, \nu) + \min\{|\mu|, |\nu|\} \frac{e^{Lt} - 1}{L} \|v_1 - v_2\|_{L^\infty(0, T; \mathcal{C}^0)}.$

The notation $\#$ used above denotes the push-forward, defined as follows: for $\mu \in \mathcal{M}^s(\mathbb{R}^d)$ and $\phi : \mathbb{R}^d \rightarrow \mathbb{R}^d$ a Borel map, the push-forward $\phi \# \mu$ is the measure on \mathbb{R}^d defined by $\phi \# \mu(E) := \mu(\phi^{-1}(E))$, for any Borel set $E \subset \mathbb{R}^d$.

We end this section with a result of completeness that will prove central in the subsequent sections. As remarked in [21], $(\mathcal{M}^s(\mathbb{R}^d), \mathbb{W}_p^{a,b})$ is not a Banach space. However, $(\mathcal{M}(\mathbb{R}^d), W_p^{a,b})$ is (as shown in [19]), and we can also show the following:

Proposition 5. *$\mathcal{P}(\mathbb{R}^d)$ is complete with respect to the Generalized Wasserstein distance $W_p^{a,b}$.*

Proof. Let $\{\mu_n\} \subset \mathcal{P}(\mathbb{R}^d)$ be a Cauchy sequence with respect to $W_p^{a,b}$. It was proven in the proof of Proposition 4 in [19] that $\{\mu_n\}$ is tight. From Prokhorov's theorem, there exists $\mu^* \in \mathcal{P}(\mathbb{R}^d)$ and a subsequence $\{\mu_{n_k}\}$ of $\{\mu_n\}$ such that $\mu_{n_k} \rightharpoonup_{k \rightarrow \infty} \mu^*$. From Theorem 3 of [19], this implies that $W_p^{a,b}(\mu_{n_k}, \mu^*) \rightarrow 0$. From the Cauchy property of $\{\mu_n\}$ and the triangular inequality, this in turn implies that $W_p^{a,b}(\mu_n, \mu^*) \rightarrow 0$. \square

In particular, note that $\mathcal{P}(\mathbb{R}^d)$ is also complete with respect to the Bounded Lipschitz distance ρ .

3.2. Comparison between the distances. From the definition of the Bounded-Lipschitz distance as a particular case of the Generalized Wasserstein distance $\mathbb{W}_1^{1,1}$ (for $a = b = 1$), we have the following property:

$$\forall \mu, \nu \in \mathcal{P}(\mathbb{R}^d), \quad \rho(\mu, \nu) \leq W_1(\mu, \nu). \quad (12)$$

As pointed out in Remark 3, the converse is not true in general. However, we can show that for measures with bounded support, one can indeed control the 1-Wasserstein distance with the Bounded Lipschitz one.

Proposition 6. *Let $R > 0$. For all $\mu, \nu \in \mathcal{P}_c(\mathbb{R}^d)$, if $\text{supp}(\mu) \cup \text{supp}(\nu) \subset B(0, R)$, it holds*

$$\rho(\mu, \nu) \leq W_1(\mu, \nu) \leq C_R \rho(\mu, \nu)$$

where $C_R = \max(1, R)$.

Proof. Let $\mu, \nu \in \mathcal{P}_c(\mathbb{R}^d)$, such that $\text{supp}(\mu) \cup \text{supp}(\nu) \subset B(0, R)$.

Let $A := \{\int_{\mathbb{R}^d} f d(\mu - \nu); f \in C_c^{0,\text{Lip}}(\mathbb{R}^d), \|f\|_{\text{Lip}} \leq 1, \|f\|_{L^\infty} \leq 1\}$ and $B := \{\int_{\mathbb{R}^d} f d(\mu - \nu); f \in C_c^{0,\text{Lip}}(\mathbb{R}^d), \|f\|_{\text{Lip}} \leq 1\}$. Then $\rho(\mu, \nu) = \sup_{a \in A} a$ and $W_1(\mu, \nu) = \sup_{b \in B} b$. It is clear that $A \subset B$, which proves the first inequality.

Let $\tilde{B} = \{\int_{\mathbb{R}^d} f d(\mu - \nu); f \in C_c^{0,\text{Lip}}(\mathbb{R}^d), \|f\|_{\text{Lip}} \leq 1, f(0) = 0\}$. Clearly, $\tilde{B} \subset B$. Let us show that $B \subset \tilde{B}$. Let $b \in B$. There exists $f_b \in C_c^{0,\text{Lip}}(\mathbb{R}^d)$ such that $\|f_b\|_{\text{Lip}} \leq 1$ and $b = \int_{\mathbb{R}^d} f_b d(\mu - \nu)$. Let us define $\tilde{f}_b \in C(\mathbb{R}^d)$ such that for all $x \in B(0, R)$, $\tilde{f}_b(x) = f_b(x) - f_b(0)$. It holds $\|\tilde{f}_b\|_{\text{Lip}(B(0, R))} \leq 1$. We prolong \tilde{f}_b outside of $B(0, R)$ in such a way that $\tilde{f}_b \in C_c^{0,\text{Lip}}(\mathbb{R}^d)$ $\arg \max(\tilde{f}_b) \in B(0, R)$ and $\|\tilde{f}_b\|_{\text{Lip}(\mathbb{R}^d)} \leq 1$. Then since the supports of μ and ν are contained in $B(0, R)$,

$$\int_{\mathbb{R}^d} \tilde{f}_b d(\mu - \nu) = \int_{B(0, R)} \tilde{f}_b d(\mu - \nu) = \int_{B(0, R)} f_b d(\mu - \nu) - f_b(0) \int_{B(0, R)} d(\mu - \nu) = b$$

where the last equality is deduced from $\mu(B(0, R)) = \nu(B(0, R)) = 1$. Thus $b \in \tilde{B}$, so $B = \tilde{B}$.

Let us now show that there exists $a \in A$ such that $b \leq \max(1, R)a$. If $\|\tilde{f}_b\|_{L^\infty(\mathbb{R}^d)} \leq 1$, then $b \in A$. If $\|\tilde{f}_b\|_{L^\infty(\mathbb{R}^d)} > 1$, let $f_a := \tilde{f}_b / \|\tilde{f}_b\|_{L^\infty(\mathbb{R}^d)}$. It holds $\|f_a\|_{L^\infty(\mathbb{R}^d)} \leq 1$ and $\|f_a\|_{\text{Lip}} \leq 1$. Thus $a := \int_{\mathbb{R}^d} f_a d(\mu - \nu) \in A$ and it holds

$$b = \|\tilde{f}_b\|_{L^\infty(\mathbb{R}^d)} \int_{\mathbb{R}^d} \tilde{f}_b / \|\tilde{f}_b\|_{L^\infty(\mathbb{R}^d)} d(\mu - \nu) \leq \|\tilde{f}_b\|_{L^\infty(\mathbb{R}^d)} a.$$

Since $\tilde{f}_b(0) = 0$ and $\|\tilde{f}_b\|_{\text{Lip}} \leq 1$, it holds $\|\tilde{f}_b\|_{L^\infty(B(0, R))} \leq R$, hence $\|\tilde{f}_b\|_{L^\infty(\mathbb{R}^d)} \leq R$. Then, for all $b \in B$, there exists $a \in A$ such that $b \leq \max(1, R)a$, which implies that $\sup_{b \in B} b \leq \max(1, R) \sup_{a \in A} a$. \square

It is a well-known property of the Wasserstein distances that for all $m \leq p$, for all $\mu, \nu \in \mathcal{P}_p(\mathbb{R}^d)$,

$$W_m(\mu, \nu) \leq W_p(\mu, \nu). \quad (13)$$

The proof of this result is a simple application of the Jensen inequality [23].

The converse is false in general. However, once again, we can prove more for measures with compact support in the case $m = 1$.

Proposition 7. *Let $R > 0$ and $p \in \mathbb{N}^*$. For all $\mu, \nu \in \mathcal{P}_c(\mathbb{R}^d)$, if $\text{supp}(\mu) \cup \text{supp}(\nu) \subset B(0, R)$,*

$$W_p(\mu, \nu) \leq (2R)^{\frac{p-1}{p}} W_1(\mu, \nu)^{\frac{1}{p}}.$$

Proof. Let $\pi \in \Pi(\mu, \nu)$ be a transference plan with marginals μ and ν . Since the supports of μ and ν are contained in $B(0, R)$, the support of π is contained in $B(0, R) \times B(0, R)$. We can then write:

$$\begin{aligned} \int_{\mathbb{R}^d \times \mathbb{R}^d} d(x, y)^p d\pi(x, y) &= \int_{B(0, R)^2} d(x, y)^p d\pi(x, y) \\ &\leq (2R)^{p-1} \int_{B(0, R)^2} d(x, y) d\pi(x, y) \end{aligned}$$

from which we deduce the claimed property. \square

4. Macroscopic model. In this section, we give a meaning to the non-linear and non-local transport equation with source:

$$\partial_t \mu_t(x) + \nabla \cdot (V[\mu_t](x) \mu_t(x)) = h[\mu_t](x), \quad \mu_{t=0} = \mu_0, \quad (14)$$

where the non-local vector field V and source term h are defined as follows:

- Let $\phi \in \text{Lip}(\mathbb{R}^d; \mathbb{R}^d)$ satisfy Hyp. 1. We define $V \in C^{0, \text{Lip}}(\mathcal{M}(\mathbb{R}^d); C^{0, \text{Lip}}(\mathbb{R}^d))$ by:

$$\forall \mu \in \mathcal{M}(\mathbb{R}^d), \quad \forall x \in \mathbb{R}^d, \quad V[\mu](x) := \int_{\mathbb{R}^d} \phi(x - y) d\mu(y). \quad (15)$$

- Let $S \in C^0((\mathbb{R}^d)^{q+1}; \mathbb{R})$ satisfy Hyp. 2. We define $h \in C^{0, \text{Lip}}(\mathcal{M}(\mathbb{R}^d); \mathcal{M}^s(\mathbb{R}^d))$ by: $\forall \mu \in \mathcal{M}(\mathbb{R}^d), \forall x \in \mathbb{R}^d$,

$$h[\mu](x) := \left(\int_{(\mathbb{R}^d)^q} S(x, y_1, \dots, y_q) d\mu(y_1) \cdots d\mu(y_q) \right) \mu(x). \quad (16)$$

The solution to (14) will be understood in the following weak sense:

Definition 4.1. A measure-valued weak solution to (14) is a measure-valued map $\mu \in C^0([0, T], \mathcal{M}^s(\mathbb{R}^d))$ satisfying $\mu_{t=0} = \mu_0$ and for all $f \in C_c^\infty(\mathbb{R}^d)$,

$$\frac{d}{dt} \int_{\mathbb{R}^d} f(x) d\mu_t(x) = \int_{\mathbb{R}^d} V[\mu_t] \cdot \nabla f(x) d\mu_t(x) + \int_{\mathbb{R}^d} f(x) dh[\mu_t](x). \quad (17)$$

Remark 4. This model is a modified version of the one proposed in [20]. The form of the source term (16) is slightly more general than the one of [20] (where h was defined as $h[\mu](x) = (S_1 + S_2 \star \mu) \mu$). However we also introduce a more restrictive condition (10) that will force the source term to be a signed measure with zero total mass.

The first aim of this paper will be to prove Theorem 1.1, stated again for convenience:

Theorem 1. *For all $T > 0$ and $\mu_0 \in \mathcal{P}_c(\mathbb{R}^d)$, there exists a unique weak solution $\mu_t \in C([0, T], \mathcal{P}_c(\mathbb{R}^d))$ to equation (14) satisfying $\mu_{t=0} = \mu_0$.*

Notice that we are almost in the frameworks of [18] and [21]. In [18], existence and uniqueness was proven for a transport equation with source of the form (14), for measures in $\mathcal{M}(\mathbb{R}^d)$ and with source term $h \in C^{0, \text{Lip}}(\mathcal{M}(\mathbb{R}^d), \mathcal{M}(\mathbb{R}^d))$. Since in our case, $h[\mu]$ is a signed measure, we cannot apply directly the theory of [18]. In [21],

existence and uniqueness was proven for a transport equation with source of the form (14), for measures in $\mathcal{M}^s(\mathbb{R}^d)$ and with source term $h \in C^{0,\text{Lip}}(\mathcal{M}^s(\mathbb{R}^d), \mathcal{M}^s(\mathbb{R}^d))$. However, as we will see in Section 4.1, the source term h in (16) does not satisfy some of the assumptions of [21], namely a global Lipschitz property and a global bound on the mass of $h[\mu]$.

4.1. Properties of the model. We now prove that the vector field $V[\mu]$ satisfies Lipschitz and boundedness properties, provided that $|\mu|$ is bounded.

First, notice that the continuity of ϕ implies that for all $R > 0$ and $x \in \mathbb{R}^d$ such that $|x| \leq 2R$, there exists $\phi_R > 0$ such that $|\phi(x)| \leq \phi_R$. More specifically, since ϕ is Lipschitz, $\phi_R = \phi_0 + 2L_\phi R$, with $\phi_0 := \phi(0)$.

Proposition 8. *The vector field V defined by (15) satisfies the following:*

- For all $\mu \in \mathcal{M}^s(\mathbb{R}^d)$ such that $\text{supp}(\mu) \subset B(0, R)$, for all $x \in B(0, R)$, $|V[\mu](x)| \leq \phi_R |\mu|$.
- For all $(x, z) \in \mathbb{R}^{2d}$, for all $\mu \in \mathcal{M}^s(\mathbb{R}^d)$, $|V[\mu](x) - V[\mu](z)| \leq L_\phi |\mu| |x - z|$.
- For all $\mu, \nu \in \mathcal{M}^s(\mathbb{R}^d)$ such that $\text{supp}(\mu) \cup \text{supp}(\nu) \subset B(0, R)$, $\|V[\mu] - V[\nu]\|_{L^\infty(B(0, R))} \leq (L_\phi + \phi_R) \rho(\mu, \nu)$.

Proof. The first and second properties are immediate from the definition of V . Lastly, for all $\mu, \nu \in \mathcal{M}^s(\mathbb{R}^d)$ such that $\text{supp}(\mu) \cup \text{supp}(\nu) \subset B(0, R)$ for all $x \in B(0, R)$,

$$\begin{aligned} |V[\mu](x) - V[\nu](x)| &= \int_{B(0, R)} \phi(y - x) d(\mu(y) - \nu(y)) \\ &\leq (L_\phi + \phi_R) \sup_{f \in C_c^{0,\text{Lip}}, \|f\|_{\text{Lip}} \leq 1, \|f\|_\infty \leq 1} \int_{\mathbb{R}^d} f(y) d(\mu(y) - \nu(y)) \\ &\leq (L_\phi + \phi_R) \rho(\mu, \nu), \end{aligned}$$

where we used the fact that for all $x \in B(0, R)$, the function $y \mapsto (L_\phi + \phi_R)^{-1} \phi(y - x)$ has both Lipschitz and L^∞ norms bounded by 1, and the definition of ρ . \square

Proposition 9. *The source term h defined by (16) satisfies the following:*

- (i) $\forall \mu \in \mathcal{M}^s(\mathbb{R}^d)$, $h[\mu](\mathbb{R}^d) = 0$
- (ii) $\forall \mu \in \mathcal{M}^s(\mathbb{R}^d)$, $\text{supp}(h[\mu]) = \text{supp}(\mu)$
- (iii) For all $Q \geq 0$, there exists L_h such that for all $\mu, \nu \in \mathcal{M}^s(\mathbb{R}^d)$ with compact support and with bounded total variation $|\mu| \leq Q$ and $|\nu| \leq Q$, $\rho(h[\mu], h[\nu]) \leq L_h \rho(\mu, \nu)$.
- (iv) $\forall \mu \in \mathcal{M}(\mathbb{R}^d)$, $|h[\mu]| \leq \bar{S} |\mu|^{q+1}$.
- (v) $\forall \mu \in \mathcal{M}(\mathbb{R}^d)$, $\forall E \subset \mathbb{R}^d$, $h[E] \geq -\bar{S} |\mu| \mu(E)$.

Proof. For conciseness, we denote $y = (y_1, \dots, y_q)$, $d\mu = d\mu(x)$ and $d\mu_i = d\mu(y_i)$.

(i) Let $\mu \in \mathcal{M}^s(\mathbb{R}^d)$. From the definition of h , we compute:

$$\begin{aligned} h[\mu](\mathbb{R}^d) &= \int_{(\mathbb{R}^d)^{q+1}} S(y_0, \dots, y_q) d\mu_0 \cdots d\mu_q \\ &= \frac{1}{2} \int_{(\mathbb{R}^d)^{q+1}} S(y_0, \dots, y_q) d\mu_0 \cdots d\mu_q \\ &\quad + \frac{1}{2} \int_{(\mathbb{R}^d)^{q+1}} S(y_0, \dots, y_j, \dots, y_i, \dots, y_q) d\mu_0 \cdots d\mu_q \end{aligned}$$

where we used the change of variables $y_i \leftrightarrow y_j$ to obtain the second term. Then, using the skew-symmetric property (10), we obtain $h[\mu](\mathbb{R}^d) = 0$.

(ii) The second property is immediate from the definition of $h[\mu]$.

(iii) For the third point, let $\mu, \nu \in \mathcal{M}^s(\mathbb{R}^d)$ with compact support, and satisfying $|\mu| \leq Q$ and $|\nu| \leq Q$. For all $f \in \mathcal{C}_c^{0,\text{Lip}}$ such that $\|f\|_\infty \leq 1$ and $\|f\|_{\text{Lip}} \leq 1$,

$$\begin{aligned}
 & \int_{\mathbb{R}^d} f(x) d(h[\mu] - h[\nu]) \\
 &= \int_{\mathbb{R}^d} f(x) \int_{\mathbb{R}^{qd}} S(x, y) d\mu_1 \cdots d\mu_q d\mu - \int_{\mathbb{R}^d} f(x) \int_{\mathbb{R}^{qd}} S(x, y) d\nu_1 \cdots d\nu_q d\nu \\
 &= \int_{\mathbb{R}^d} f(x) \int_{\mathbb{R}^{qd}} S(x, y) d\mu_1 \cdots d\mu_q d(\mu - \nu) \\
 &\quad + \sum_{i=1}^q \int_{\mathbb{R}^d} f(x) \int_{\mathbb{R}^{qd}} S(x, y) d\mu_1 \cdots d\mu_i d\nu_{i+1} \cdots d\nu_q d\nu \\
 &\quad - \sum_{i=1}^q \int_{\mathbb{R}^d} f(x) \int_{\mathbb{R}^{qd}} S(x, y) d\mu_1 \cdots d\mu_{i-1} d\nu_i \cdots d\nu_q d\nu \\
 &= \int_{\mathbb{R}^{(q+1)d}} f(x) S(x, y) d\mu_1 \cdots d\mu_q d(\mu - \nu) \\
 &\quad + \sum_{i=1}^q \int_{\mathbb{R}^{(q+1)d}} f(x) S(x, y) d\mu_1 \cdots d(\mu_i - \nu_i) d\nu_{i+1} \cdots d\nu_q d\nu.
 \end{aligned}$$

We begin by studying the first term $A(f) := \int_{\mathbb{R}^d} f(x) \psi(x) d(\mu(x) - \nu(x))$, where ψ is defined by $\psi : x \mapsto \int_{\mathbb{R}^{qd}} S(x, y) d\mu_1 \cdots d\mu_q$. Notice that

$$|\psi(x)| = \left| \int_{\mathbb{R}^{qd}} S(x, y) d\mu_1 \cdots d\mu_q \right| \leq \bar{S} |\mu|^q \leq \bar{S} Q^q.$$

Furthermore, for all $(x, z) \in \mathbb{R}^{2d}$,

$$|\psi(x) - \psi(z)| = \left| \int_{\mathbb{R}^{qd}} (S(x, y) - S(z, y)) d\mu_1 \cdots d\mu_q \right| \leq L_S |\mu|^q |x - z|,$$

where we used the Lipschitz property (9) of S . Thus, for all $x \in \mathbb{R}^d$, $|f(x)\psi(x)| \leq \bar{S} Q^q$. Furthermore, for all $(x, z) \in \mathbb{R}^{2d}$,

$$|f(x)\psi(x) - f(z)\psi(z)| = |f(x)(\psi(x) - \psi(z)) + (f(x) - f(z))\psi(z)| \leq (L_S + \bar{S}) Q^q |x - z|.$$

This implies that the function $g : x \mapsto \frac{1}{Q^q(\bar{S} + L_S)} f(x)\psi(x)$ satisfies $g \in \mathcal{C}_c^{0,\text{Lip}}$, $\|g\|_\infty \leq 1$ and $\|g\|_{\text{Lip}} \leq 1$. Then, using the definition of ρ , we deduce that

$$A(f) = Q^q (L_S + \bar{S}) \int_{\mathbb{R}^d} g(x) d(\mu(x) - \nu(x)) \leq Q^q (L_S + \bar{S}) \rho(\mu, \nu).$$

Now, let

$$\zeta_i : y_i \mapsto \int_{\mathbb{R}^{qd}} f(x) S(x, y_1 \cdots, y_q) d\mu(y_1) \cdots d\mu(y_{i-1}) d\nu(y_{i+1}) \cdots d\nu(y_q) d\nu(x)$$

and $B_i(f) := \int_{\mathbb{R}^d} \zeta_i(y_i) d(\mu(y_i) - d\nu(y_i))$.

For all $y_i \in \mathbb{R}^d$, $|\zeta_i(y_i)| \leq \|f\|_{L^\infty} \|S\|_{L^\infty} |\mu|^{i-1} |\nu|^{q-i+1} \leq \bar{S} Q^q$. Moreover, for all $(y_i, z_i) \in \mathbb{R}^{2d}$,

$$\begin{aligned} & |\zeta_i(y_i) - \zeta_i(z_i)| \\ &= \left| \int_{\mathbb{R}^{qd}} f(x) (S(x, y) - S(x, y_1, \dots, z_i, \dots, y_q)) d\mu_1 \cdots d\mu_{i-1} d\nu_{i+1} \cdots d\nu_q d\nu \right| \\ &\leq \|f\|_{L^\infty} L_S |y_i - z_i| |\mu|^{i-1} |\nu|^{q-i+1} \leq L_S Q^q |y_i - z_i|. \end{aligned}$$

Hence, the function $g_i : y_i \mapsto \frac{1}{Q^q(L_S + \bar{S})} \zeta_i(y_i)$ satisfies $g_i \in \mathcal{C}^{0, \text{Lip}}$, $\|g_i\|_\infty \leq 1$ and $\|g_i\|_{\text{Lip}} \leq 1$, so

$$\begin{aligned} B_i(f) &\leq Q^q(L_S + \bar{S}) \sup_{f \in \mathcal{C}_c^{0, \text{Lip}}, \|f\|_\infty \leq 1, \|f\|_{\text{Lip}} \leq 1} \int_{\mathbb{R}^d} f(x) d(\mu(x) - \nu(x)) \\ &\leq Q^q(L_S + \bar{S}) \rho(\mu, \nu). \end{aligned}$$

We conclude that for all $f \in \mathcal{C}_c^{0, \text{Lip}}$ such that $\|f\|_\infty \leq 1$ and $\|f\|_{\text{Lip}} \leq 1$,

$$\int_{\mathbb{R}^d} f(x) d(h[\mu](x) - h[\nu](x)) = A(f) + \sum_{i=1}^q B_i(f) \leq (q+1) Q^q(L_S + \bar{S}) \rho(\mu, \nu).$$

(iv) Let $\mu \in \mathcal{M}^s(\mathbb{R}^d)$. From the definition of h , it follows immediately that $|h[\mu]| \leq \bar{S} |\mu|^{q+1}$.

(v) Lastly, for all $\mu \in \mathcal{M}(\mathbb{R}^d)$ and $E \subset \mathbb{R}^d$,

$$h[\mu](E) = \int_E \int_{\mathbb{R}^{dq}} S(x, y) d\mu_1 \cdots d\mu_q d\mu \geq -\bar{S} |\mu|^q \mu(E).$$

□

4.2. Numerical scheme. In [21], existence of the solution to (14) was proven by showing that it is the limit of a numerical scheme discretizing time. It would seem natural to apply directly the results of [21] on well-posedness of the equation in $\mathcal{M}^s(\mathbb{R}^d)$. However, the conditions on the source function h required in [21], namely

$$\|h[\mu] - h[\nu]\| \leq L_h \|\mu - \nu\|, \quad |h[\mu]| \leq P \quad \text{and} \quad \text{supp}(h[\mu]) \subset B_0(R) \quad (18)$$

uniformly for all $\mu, \nu \in \mathcal{M}^s(\mathbb{R}^d)$ are not satisfied in our setting (since L_h and P depend on $|\mu|$, $|\nu|$, as seen in Proposition 9). Instead, we notice that they do hold uniformly for $\mu, \nu \in \mathcal{P}_c(\mathbb{R}^d)$. Hence if the numerical scheme designed in [21] preserved mass and positivity, one could hope to adapt the proof by restricting it to probability measures. However, we can show that the scheme of [21] preserves neither positivity, nor total variation.

For this reason, in order to prove existence of the solution to (14), we design a new operator-splitting numerical scheme that conserves mass and positivity (hence total variation). The inequalities (18) will then hold for all solutions of the scheme, which will allow us to prove that it converges (with a technique very close to the techniques of [18, 21]) in the space $C([0, T], \mathcal{P}(\mathbb{R}^d))$ (Section 4.2). It will only remain to prove that the limit of the scheme $\bar{\mu}$ is indeed a solution to (14), and that this solution is unique (Section 4.3).

NUMERICAL SCHEME \mathbb{S} .

Let $T > 0$, $k \in \mathbb{N}$, and let $\Delta t = \frac{T}{2^k}$. Set $\mu_0^k := \mu_0$. For all $n \in \mathbb{N}$,

- $\forall t \in (n\Delta t, (n + \frac{1}{2})\Delta t]$, let $\tau = t - n\Delta t$ and $\mu_t^k := \mu_{n\Delta t}^k + 2\tau h[\mu_{n\Delta t}^k]$.
- $\forall t \in ((n + \frac{1}{2})\Delta t, (n + 1)\Delta t]$, let $\tau' = t - (n + \frac{1}{2})\Delta t$ and $\mu_t^k := \Phi_{2\tau'}^{V[\mu_{n\Delta t}^k]} \# \mu_{(n+\frac{1}{2})\Delta t}^k$.

Remark that the factor 2 in both steps of the numerical scheme is used in order to obtain the usual operator-splitting decomposition: $\mu_{(n+\frac{1}{2})\Delta t}^k = \mu_{n\Delta t}^k + \Delta t h[\mu_{n\Delta t}^k]$ and $\mu_{(n+1)\Delta t}^k = \Phi_{\Delta t}^{V[\mu_{n\Delta t}^k]} \# \mu_{(n+\frac{1}{2})\Delta t}^k$.

As stated above, we begin by proving a key property of the scheme \mathbb{S} : it preserves mass and positivity.

Proposition 10. *If $\mu_0 \in \mathcal{P}(\mathbb{R}^d)$, then for all $k \geq \log_2(\bar{S}T)$, for all $t \in [0, T]$, $\mu_t^k \in \mathcal{P}(\mathbb{R}^d)$.*

Proof. Let $\mu_0 \in \mathcal{P}(\mathbb{R}^d)$. We first show that $\mu_t^k(\mathbb{R}^d) = 1$ for all $k \in \mathbb{N}$ and $t \in [0, T]$. Suppose that for some $n \in \mathbb{N}$, $\mu_{n\Delta t}^k(\mathbb{R}^d) = 1$.

- For all $t \in (n\Delta t, (n + \frac{1}{2})\Delta t]$, from Prop. 9,

$$\mu_t^k(\mathbb{R}^d) = \mu_{n\Delta t}^k(\mathbb{R}^d) + 2(t - n\Delta t)h[\mu_{n\Delta t}^k](\mathbb{R}^d) = 1.$$

- For all $t \in ((n + \frac{1}{2})\Delta t, (n + 1)\Delta t]$,

$$\mu_t^k(\mathbb{R}^d) = \mu_{(n+\frac{1}{2})\Delta t}^k(\Phi_{-2(t-(n+\frac{1}{2})\Delta t)}^{V[\mu_{n\Delta t}^k]}(\mathbb{R}^d)) = \mu_{(n+\frac{1}{2})\Delta t}^k(\mathbb{R}^d) = 1.$$

This proves that $\mu_t^k(\mathbb{R}^d) = 1$ for all $t \in [0, T]$ by induction on n . We now show that $\mu_t^k \in \mathcal{M}(\mathbb{R}^d)$ for all $k \in \mathbb{N}$ and $t \in [0, T]$. Suppose that for some $n \in \mathbb{N}$, for all $E \subset \mathbb{R}^d$, $\mu_{n\Delta t}^k(E) \geq 0$.

- For all $t \in (n\Delta t, (n + \frac{1}{2})\Delta t]$, for all $E \subset \mathbb{R}^d$, since $k \geq \log_2(\bar{S}T)$,

$$\mu_t^k(E) \geq \mu_{n\Delta t}^k(E) - \Delta t \bar{S} \mu_{n\Delta t}^k(\mathbb{R}^d)^k \mu_{n\Delta t}^k(E) \geq (1 - 2^{-k}T\bar{S})\mu_{n\Delta t}^k(E) \geq 0,$$

where we used point (v) of Prop. 9.

- For all $t \in ((n + \frac{1}{2})\Delta t, (n + 1)\Delta t]$, for all $E \subset \mathbb{R}^d$,

$$\mu_t^k(E) = \mu_{(n+\frac{1}{2})\Delta t}^k(\Phi_{-2(t-(n+\frac{1}{2})\Delta t)}^{V[\mu_{n\Delta t}^k]}(E)) \geq 0$$

by definition of the push-forward.

The result is proven by induction on n . \square

We also prove another key property of the scheme: it preserves compactness of the support.

Proposition 11. *Let $\mu_0 \in \mathcal{P}_c(\mathbb{R}^d)$ and $R > 0$ such that $\text{supp}(\mu_0) \subset B(0, R)$. Then there exists R_T independent of k such that for all $t \in [0, T]$, for all $k \in \mathbb{N}$, $\text{supp}(\mu_t^k) \subset B(0, R_T)$.*

Proof. Let $k \in \mathbb{N}$ and suppose that for some $n \in \mathbb{N}$, $\text{supp}(\mu_{n\Delta t}^k) \subset B(0, R_{n,k})$. For all $t \in (n\Delta t, (n + \frac{1}{2})\Delta t]$, $\text{supp}(\mu_t^k) = \text{supp}(\mu_{n\Delta t}^k) \cup \text{supp}(h[\mu_{n\Delta t}^k]) = \text{supp}(\mu_{n\Delta t}^k) \subset$

$B(0, R_{n,k})$ from point (ii) of Proposition 9. For all $t \in ((n + \frac{1}{2})\Delta t, (n+1)\Delta t]$, $\mu_t^k(x) = \mu_{(n+\frac{1}{2})\Delta t}^k(\Phi_{-2(t-(n+\frac{1}{2})\Delta t)}^{V[\mu_{n\Delta t}^k]}(x))$, so from Proposition 8,

$$\text{supp}(\mu_t^k) \subset B(0, R_{n,k} + \phi_{R_{n,k}}\Delta t) = B(0, R_{n,k} + (\phi_0 + 2L_\phi R_{n,k})\Delta t) = B(0, R_{n+1,k}),$$

with $R_{n+1,k} := \phi_0\Delta t + R_{n,k}(1 + 2L_\phi\Delta t)$. By induction, one can prove that for $t \in [(n-1)\Delta t, n\Delta t]$, $\text{supp}(\mu_t^k) \subset B(0, R_{n,k})$, with

$$R_{n,k} = \phi_0\Delta t \sum_{i=0}^n (1 + 2L_\phi\Delta t)^i + R(1 + 2L_\phi\Delta t)^n = (1 + 2L_\phi\Delta t)^n \left(\frac{\phi_0}{2L_\phi} + R \right) - \frac{\phi_0}{2L_\phi}.$$

Since $n \leq 2^k$, for all $n \in \{0, \dots, 2^k\}$, $R_{n,k} \leq (1 + 2L_\phi T 2^{-k})^{2^k} \left(\frac{\phi_0}{2L_\phi} + R \right) - \frac{\phi_0}{2L_\phi}$.

Moreover, $\lim_{k \rightarrow \infty} (1 + 2L_\phi T 2^{-k})^{2^k} = e^{2L_\phi T}$, so there exists R_T independent of k such that for all $t \in [0, T]$, $\text{supp}(\mu_t^k) \subset B(0, R_T)$. \square

Propositions 10 and 11 allow us to state the main result of this section.

Proposition 12. *Given V , h defined by (15) and (16) and $\mu_0 \in \mathcal{P}_c(\mathbb{R}^d)$, the sequence μ^k is a Cauchy sequence for the space $(C([0, T], \mathcal{P}(\mathbb{R}^d)), \mathcal{D})$, where*

$$\mathcal{D}(\mu, \nu) := \sup_{t \in [0, T]} \rho(\mu_t, \nu_t).$$

Proof. Let $k, n \in \mathbb{N}$, with $n \leq 2^k$. Let $\Delta t = 2^{-k}T$. Suppose that $\text{supp}(\mu_0) \subset B(0, R)$. Notice that from Propositions 8, 10 and 11, we have an L^∞ bound on $V[\mu_t^k]$ independent of t and k : for all $x \in B(0, R_T)$, for all $t \in [0, T]$, $|V[\mu_t^k](x)| \leq M_V := \phi_{R_T}$. We also have uniform Lipschitz constants for $V[\cdot]$ and $V[\mu_t^k](\cdot)$. For all $t, s \in [0, T]$, for all μ_t^k, μ_s^l solutions to \mathbb{S} with initial data μ_0 , it holds

$$|V[\mu_t^k](x) - V[\mu_t^k](z)| \leq L_\phi |x - z| \quad \text{and} \quad \|V[\mu_t^k] - V[\mu_s^l]\|_{L^\infty} \leq L_V \rho(\mu_t^k, \mu_s^l)$$

where $L_V := L_\phi + \phi_{R_T}$. We then estimate:

$$\begin{aligned} \rho(\mu_{n\Delta t}^k, \mu_{(n+1)\Delta t}^k) &\leq \rho(\mu_{n\Delta t}^k, \mu_{(n+\frac{1}{2})\Delta t}^k) + \rho(\mu_{(n+\frac{1}{2})\Delta t}^k, \mu_{(n+1)\Delta t}^k) \\ &\leq \rho(\mu_{n\Delta t}^k, \mu_{n\Delta t}^k + \Delta t h[\mu_{n\Delta t}^k]) + M_V \Delta t, \end{aligned} \quad (19)$$

from Proposition 4. Notice that $\mu_{n\Delta t}^k \in \mathcal{P}_c(\mathbb{R}^d)$ and $\mu_{n\Delta t}^k + \Delta t h[\mu_{n\Delta t}^k] \in \mathcal{M}^s(\mathbb{R}^d)$.

$$\rho(\mu_{n\Delta t}^k, \mu_{n\Delta t}^k + \Delta t h[\mu_{n\Delta t}^k]) = \Delta t \rho(0, h[\mu_{n\Delta t}^k]) \leq \Delta t |h[\mu_{n\Delta t}^k]| \leq \Delta t \bar{S}$$

from Equation (11), Proposition 3 and Proposition 9. Thus, coming back to (19), $\rho(\mu_{n\Delta t}^k, \mu_{(n+1)\Delta t}^k) \leq \Delta t (\bar{S} + M_V)$. It follows that for all $p \in \mathbb{N}$ such that $n+p \leq 2^k$, $\rho(\mu_{n\Delta t}^k, \mu_{(n+p)\Delta t}^k) \leq p\Delta t (\bar{S} + M_V)$. Generalizing for all $t, s \in [0, T]$, $t < s$, there exists $n, p \in \mathbb{N}$ such that $t = n\Delta t - \tilde{t}$ and $s = (n+p)\Delta t + \tilde{s}$, with $\tilde{t}, \tilde{s} \in [0, \Delta t)$. Then $\rho(\mu_t^k, \mu_s^k) \leq \rho(\mu_t^k, \mu_{n\Delta t}^k) + \rho(\mu_{n\Delta t}^k, \mu_{(n+p)\Delta t}^k) + \rho(\mu_{(n+p)\Delta t}^k, \mu_s^k)$.

If $\tilde{t} \leq \frac{1}{2}\Delta t$, $\rho(\mu_t^k, \mu_{n\Delta t}^k) \leq \bar{S}\tilde{t}$. If $\tilde{t} \geq \frac{1}{2}\Delta t$, $\rho(\mu_t^k, \mu_{n\Delta t}^k) \leq \bar{S}\frac{\Delta t}{2} + (\tilde{t} - \frac{\Delta t}{2})M_V \leq \bar{S}\tilde{t} + \tilde{t}M_V$. The same reasoning for \tilde{s} implies

$$\rho(\mu_t^k, \mu_s^k) \leq (\bar{S} + M_V)\tilde{t} + p(\bar{S} + M_V) + (\bar{S} + M_V)\tilde{s} = (\bar{S} + M_V)(s - t). \quad (20)$$

We also estimate:

$$\begin{aligned} \rho(\mu_{(n+\frac{1}{2})\Delta t}^{k+1}, \mu_{n\Delta t}^k) &\leq \rho(\mu_{(n+\frac{1}{2})\Delta t}^{k+1}, \mu_{n\Delta t}^{k+1}) + \rho(\mu_{n\Delta t}^{k+1}, \mu_{n\Delta t}^k) \\ &\leq \frac{\Delta t}{2}(\bar{S} + M_V) + \rho(\mu_{n\Delta t}^{k+1}, \mu_{n\Delta t}^k). \end{aligned} \quad (21)$$

We now aim to estimate $\rho(\mu_{(n+1)\Delta t}^k, \mu_{(n+1)\Delta t}^{k+1})$ as a function of $\rho(\mu_{n\Delta t}^k, \mu_{n\Delta t}^{k+1})$. Let $H_m^j := h[\mu_{m\Delta t}^j]$ and $\nu_m^j := \Phi_{\Delta t/2}^{V[\mu_{m\Delta t}^j]}$. Since

$$\begin{aligned}\mu_{(n+1)\Delta t}^k &= \Phi_{\Delta t}^{V[\mu_{n\Delta t}^k]} \# (\mu_{n\Delta t}^k + \Delta t h[\mu_{n\Delta t}^k]) = \nu_n^k \# \nu_n^k \# (\mu_{n\Delta t}^k + \Delta t H_n^k), \\ \mu_{(n+1)\Delta t}^{k+1} &= \Phi_{\Delta t/2}^{V[\mu_{(n+\frac{1}{2})\Delta t}^{k+1}]} \# \left(\mu_{(n+\frac{1}{2})\Delta t}^{k+1} + \frac{\Delta t}{2} h[\mu_{(n+\frac{1}{2})\Delta t}^{k+1}] \right) \\ &= \nu_{n+\frac{1}{2}}^{k+1} \# \left(\nu_n^{k+1} \# (\mu_{n\Delta t}^{k+1} + \frac{\Delta t}{2} H_n^{k+1}) + \frac{\Delta t}{2} H_{n+\frac{1}{2}}^{k+1} \right),\end{aligned}$$

it holds $\rho(\mu_{(n+1)\Delta t}^k, \mu_{(n+1)\Delta t}^{k+1}) \leq A_1 + \frac{\Delta t}{2} A_2 + \frac{\Delta t}{2} A_3$, where

$$\begin{cases} A_1 = \rho(\nu_n^k \# \nu_n^k \# \mu_{n\Delta t}^k, \nu_{n+\frac{1}{2}}^{k+1} \# \nu_n^{k+1} \# \mu_{n\Delta t}^{k+1}), \\ A_2 = \rho(\nu_n^k \# \nu_n^k \# H_n^k, \nu_{n+\frac{1}{2}}^{k+1} \# \nu_n^{k+1} \# H_n^{k+1}), \\ A_3 = \rho(\nu_n^k \# \nu_n^k \# H_n^k, \nu_{n+\frac{1}{2}}^{k+1} \# H_{n+\frac{1}{2}}^{k+1}). \end{cases}$$

We study independently the three terms of the inequality. According to Proposition 4 (see also [18] and [21]),

$$\begin{aligned}A_1 &\leq e^{L_\phi \frac{\Delta t}{2}} \rho(\nu_n^k \# \mu_{n\Delta t}^k, \nu_n^{k+1} \# \mu_{n\Delta t}^{k+1}) + \frac{e^{L_\phi \frac{\Delta t}{2}} - 1}{L_\phi} \|V[\mu_{n\Delta t}^k] - V[\mu_{(n+\frac{1}{2})\Delta t}^{k+1}]\|_{C^0} \\ &\leq (1 + L_\phi \Delta t) \rho(\nu_n^k \# \mu_{n\Delta t}^k, \nu_n^{k+1} \# \mu_{n\Delta t}^{k+1}) + \Delta t \|V[\mu_{n\Delta t}^k] - V[\mu_{(n+\frac{1}{2})\Delta t}^{k+1}]\|_{C^0}.\end{aligned}$$

According to Proposition 8 and equation (21),

$$\begin{aligned}\|V[\mu_{n\Delta t}^k] - V[\mu_{(n+\frac{1}{2})\Delta t}^{k+1}]\|_{C^0} &\leq L_V \rho(\mu_{n\Delta t}^k, \mu_{(n+\frac{1}{2})\Delta t}^{k+1}) \\ &\leq L_V \left(\frac{\Delta t}{2} (\bar{S} + M_V) + \rho(\mu_{n\Delta t}^{k+1}, \mu_{n\Delta t}^k) \right).\end{aligned}$$

Similarly,

$$\begin{aligned}\rho(\nu_n^k \# \mu_{n\Delta t}^k, \nu_n^{k+1} \# \mu_{n\Delta t}^{k+1}) &\leq (1 + L_\phi \Delta t) \rho(\mu_{n\Delta t}^k, \mu_{n\Delta t}^{k+1}) + \Delta t \|V[\mu_{n\Delta t}^k] - V[\mu_{n\Delta t}^{k+1}]\|_{C^0} \\ &\leq (1 + (L_\phi + L_V) \Delta t) \rho(\mu_{n\Delta t}^k, \mu_{n\Delta t}^{k+1}).\end{aligned}$$

Thus we obtain

$$\begin{aligned}A_1 &\leq (1 + L_\phi \Delta t) (1 + (L_\phi + L_V) \Delta t) \rho(\mu_{n\Delta t}^k, \mu_{n\Delta t}^{k+1}) \\ &\quad + \Delta t L_V \left(\frac{\Delta t}{2} (\bar{S} + M_V) + \rho(\mu_{n\Delta t}^{k+1}, \mu_{n\Delta t}^k) \right) \\ &\leq (1 + 2(L_\phi + L_V) \Delta t + L_\phi (L_\phi + L_V) \Delta t^2) \rho(\mu_{n\Delta t}^k, \mu_{n\Delta t}^{k+1}) + \frac{L_\phi}{2} (\bar{S} + M_V) \Delta t^2.\end{aligned}$$

We treat the second term in a similar way.

$$A_2 \leq (1 + L_\phi \Delta t) \rho(\nu_n^k \# H_n^k, \nu_n^{k+1} \# H_n^{k+1}) + \Delta t \|V[\mu_{n\Delta t}^k] - V[\mu_{(n+\frac{1}{2})\Delta t}^{k+1}]\|_{C^0}.$$

We have:

$$\begin{aligned}\rho(\nu_n^k \# H_n^k, \nu_n^{k+1} \# H_n^{k+1}) &\leq (1 + L_\phi \Delta t) \rho(H_n^k, H_n^{k+1}) + \Delta t \|V[\mu_{n\Delta t}^k] - V[\mu_{n\Delta t}^{k+1}]\|_{C^0} \\ &\leq (1 + (L_\phi L_h + L_V) \Delta t) \rho(\mu_{n\Delta t}^k, \mu_{n\Delta t}^{k+1}).\end{aligned}$$

Thus,

$$\begin{aligned}
A_2 &\leq (1 + L_\phi \Delta t)(1 + (L_\phi L_h + L_V) \Delta t) \rho(\mu_{n\Delta t}^k, \mu_{n\Delta t}^{k+1}) \\
&\quad + \Delta t L_V \left[\frac{\Delta t}{2} (2\bar{S} + M_V) + \rho(\mu_{n\Delta t}^{k+1}, \mu_{n\Delta t}^k) \right] \\
&\leq (1 + (L_\phi(L_h + 1) + 2L_V) \Delta t + L_\phi(L_\phi L_h + L_V) \Delta t^2) \rho(\mu_{n\Delta t}^{k+1}, \mu_{n\Delta t}^k) \\
&\quad + \frac{L_V}{2} (\bar{S} + M_V) \Delta t^2.
\end{aligned}$$

Lastly, for the third term we have:

$$\begin{aligned}
A_3 &\leq (1 + L_\phi \Delta t) \rho(\nu_n^k \# H_n^k, H_{n+\frac{1}{2}}^{k+1}) + \Delta t \|V[\mu_{n\Delta t}^k] - V[\mu_{(n+\frac{1}{2})\Delta t}^{k+1}]\|_{C^0} \\
&\leq (1 + L_\phi \Delta t) [\rho(\nu_n^k \# H_n^k, H_n^k) + \rho(H_n^k, H_{n+\frac{1}{2}}^{k+1})] + \Delta t L_V \rho(\mu_{n\Delta t}^k, \mu_{(n+\frac{1}{2})\Delta t}^{k+1}) \\
&\leq \frac{\Delta t}{2} (L_S + 2M_V) + O(\Delta t^2) + (1 + (L_\phi L_h + L_V) \Delta t) \rho(\mu_{n\Delta t}^{k+1}, \mu_{n\Delta t}^k).
\end{aligned}$$

Gathering the three terms together, we have the following estimate:

$$\rho(\mu_{(n+1)\Delta t}^k, \mu_{(n+1)\Delta t}^{k+1}) \leq (1 + C_1 \Delta t) \rho(\mu_{n\Delta t}^{k+1}, \mu_{n\Delta t}^k) + C_2 \Delta t^2$$

where C_1 and C_2 depend on the constants L_ϕ , L_V , L_h , M_V and \bar{S} . Thus, by induction on n ,

$$\rho(\mu_{n\Delta t}^k, \mu_{n\Delta t}^{k+1}) \leq C_2 \Delta t^2 \frac{(1 + C_1 \Delta t)^n - 1}{1 + C_1 \Delta t - 1} \leq 2nC_2 \Delta t.$$

This allows us to prove the convergence of μ_t^k for every $t \in [0, T]$. For instance, for $t = T$, i.e. $n = T/\Delta t$, we have $\rho(\mu_T^k, \mu_T^{k+1}) \leq 2C_2 \Delta t = 2TC_2 2^{-k}$, and for all $l, k \in \mathbb{N}$,

$$\rho(\mu_T^k, \mu_T^{k+l}) \leq 2C_2 \left(\frac{1}{2^k} + \frac{1}{2^{k+1}} + \cdots + \frac{1}{2^{k+l-1}} \right) \leq \frac{4C_2}{2^k}.$$

A similar estimation holds for any $t \in (0, T)$ (see [18]). This proves that the sequence μ^k is a Cauchy sequence for the space $(C([0, T], \mathcal{P}(\mathbb{R}^d)), \mathcal{D})$. \square

As an immediate consequence, since $(C([0, T], \mathcal{P}(\mathbb{R}^d)), \mathcal{D})$ is complete (see Proposition 5), it follows that there exists $\bar{\mu} \in (C([0, T], \mathcal{P}(\mathbb{R}^d)))$ such that

$$\lim_{k \rightarrow \infty} \mathcal{D}(\mu^k, \bar{\mu}) = 0.$$

4.3. Existence and uniqueness of the solution. Let $\bar{\mu}_t := \lim_{k \rightarrow \infty} \mu_t^k$ denote the limit of the sequence constructed with the numerical scheme defined in the previous section. We now prove that it is indeed a weak solution of (14). We aim to prove that for all $f \in C_c^\infty((0, T) \times \mathbb{R}^d)$, it holds

$$\int_0^T \left(\int_{\mathbb{R}^d} (\partial_t f + V[\bar{\mu}_t] \cdot \nabla f) d\bar{\mu}_t + \int_{\mathbb{R}^d} f dh[\bar{\mu}_t] \right) dt = 0.$$

We begin by proving the following result:

Lemma 4.2. *Let $\mu_0 \in \mathcal{P}_c(\mathbb{R}^d)$ and let $\mu^k \in C([0, T], \mathcal{P}_c(\mathbb{R}^d))$ denote the solution to the numerical scheme \mathbb{S} with initial data μ_0 . Let $\Delta t_k := 2^{-k}T$. For all $f \in C_c^\infty((0, T) \times \mathbb{R}^d)$, it holds:*

$$\lim_{k \rightarrow \infty} \sum_{n=0}^{2^k-1} \int_{n\Delta t_k}^{(n+1)\Delta t_k} \left(\int_{\mathbb{R}^d} (\partial_t f + V[\mu_{n\Delta t_k}^k] \cdot \nabla f) d\mu_t^k + \int_{\mathbb{R}^d} f dh[\mu_{n\Delta t_k}^k] \right) dt = 0.$$

Proof. Let $k \in \mathbb{N}$ and $\Delta t := \Delta t_k = 2^{-k}T$. From the definition of the numerical scheme, we have

$$\begin{aligned}
 & \int_{n\Delta t}^{(n+1)\Delta t} \left(\int_{\mathbb{R}^d} (\partial_t f + V[\mu_{n\Delta t}^k] \cdot \nabla f) d\mu_t^k + \int_{\mathbb{R}^d} f dh[\mu_{n\Delta t}^k] \right) dt \\
 &= \int_{n\Delta t}^{(n+\frac{1}{2})\Delta t} \left(\int_{\mathbb{R}^d} (\partial_t f + V[\mu_{n\Delta t}^k] \cdot \nabla f) d(\mu_{n\Delta t}^k + 2(t - n\Delta t)h[\mu_{n\Delta t}^k]) \right) dt \\
 & \quad + \int_{(n+\frac{1}{2})\Delta t}^{(n+1)\Delta t} \left(\int_{\mathbb{R}^d} (\partial_t f + V[\mu_{n\Delta t}^k] \cdot \nabla f) d(\Phi_{2(t-(n+\frac{1}{2})\Delta t)}^{V[\mu_{n\Delta t}^k]} \# \mu_{(n+\frac{1}{2})\Delta t}^k) \right) dt \quad (22) \\
 & \quad + \int_{n\Delta t}^{(n+1)\Delta t} \int_{\mathbb{R}^d} f dh[\mu_{n\Delta t}^k] dt \\
 &= A_1 + A_2 + A_3 + A_4
 \end{aligned}$$

where

$$\begin{cases}
 A_1 = \int_{n\Delta t}^{(n+\frac{1}{2})\Delta t} \left(\int_{\mathbb{R}^d} \partial_t f d(\mu_{n\Delta t}^k + 2(t - n\Delta t)h[\mu_{n\Delta t}^k]) \right) dt, \\
 A_2 = \int_{n\Delta t}^{(n+1)\Delta t} \int_{\mathbb{R}^d} f dh[\mu_{n\Delta t}^k] dt, \\
 A_3 = \int_{n\Delta t}^{(n+\frac{1}{2})\Delta t} \left(\int_{\mathbb{R}^d} (V[\mu_{n\Delta t}^k] \cdot \nabla f) d(\mu_{n\Delta t}^k + 2(t - n\Delta t)h[\mu_{n\Delta t}^k]) \right) dt, \\
 A_4 = \int_{(n+\frac{1}{2})\Delta t}^{(n+1)\Delta t} \left(\int_{\mathbb{R}^d} (\partial_t f + V[\mu_{n\Delta t}^k] \cdot \nabla f) d(\Phi_{2(t-(n+\frac{1}{2})\Delta t)}^{V[\mu_{n\Delta t}^k]} \# \mu_{(n+\frac{1}{2})\Delta t}^k) \right) dt.
 \end{cases}$$

We begin by noticing that $\mu_{n\Delta t}^k + 2(t - n\Delta t)h[\mu_{n\Delta t}^k]$ is a weak solution on $(n\Delta t, (n + \frac{1}{2})\Delta t)$ to $\partial_t \nu_t = 2h[\mu_{n\Delta t}^k]$, with the initial condition $\nu_{n\Delta t} = \mu_{n\Delta t}^k$, so it satisfies:

$$\begin{aligned}
 A_1 &= -2 \int_{n\Delta t}^{(n+\frac{1}{2})\Delta t} \int_{\mathbb{R}^d} f dh[\mu_{n\Delta t}^k] dt \\
 & \quad + \int_{\mathbb{R}^d} f((n + \frac{1}{2})\Delta t) d\mu_{(n+\frac{1}{2})\Delta t}^k - \int_{\mathbb{R}^d} f(n\Delta t) d\mu_{n\Delta t}^k. \quad (23)
 \end{aligned}$$

We go back to the first two term of (22). Notice that from (23), we have

$$\begin{aligned}
 A_1 + A_2 &= \int_{n\Delta t}^{(n+\frac{1}{2})\Delta t} \int_{\mathbb{R}^d} (f(t + \frac{\Delta t}{2}) - f(t)) dh[\mu_{n\Delta t}^k] dt \\
 & \quad + \int_{\mathbb{R}^d} f((n + \frac{1}{2})\Delta t) d\mu_{(n+\frac{1}{2})\Delta t}^k - \int_{\mathbb{R}^d} f(n\Delta t) d\mu_{n\Delta t}^k \\
 &= \int_{n\Delta t}^{(n+\frac{1}{2})\Delta t} \int_{\mathbb{R}^d} \left(\frac{\Delta t}{2} \partial_t f(t) + O(\Delta t^2) \right) dh[\mu_{n\Delta t}^k] dt \\
 & \quad + \int_{\mathbb{R}^d} f((n + \frac{1}{2})\Delta t) d\mu_{(n+\frac{1}{2})\Delta t}^k - \int_{\mathbb{R}^d} f(n\Delta t) d\mu_{n\Delta t}^k.
 \end{aligned}$$

Similarly, since $\Phi_{2(t-(n+\frac{1}{2})\Delta t)}^{V[\mu_{n\Delta t}^k]} \# \mu_{(n+\frac{1}{2})\Delta t}^k$ is solution to the transport equation $\partial_\tau \nu_\tau + \nabla \cdot (V[\mu_{n\Delta t}^k] \nu_\tau) = 0$ with the initial condition $\nu_0 = \mu_{(n+\frac{1}{2})\Delta t}^k$ at time $\tau = 2(t - (n + \frac{1}{2})\Delta t)$, it satisfies

$$\begin{aligned}
& \int_0^{\Delta t} \int_{\mathbb{R}^d} \partial_\tau f\left(\frac{\tau}{2} + \left(n + \frac{1}{2}\right)\Delta t\right) d\nu_\tau d\tau \\
& \quad + \int_0^{\Delta t} \int_{\mathbb{R}^d} \nabla f\left(\frac{\tau}{2} + \left(n + \frac{1}{2}\right)\Delta t\right) \cdot V[\mu_{n\Delta t}^k] d\nu_\tau d\tau \\
& = \int_{\mathbb{R}^d} f((n+1)\Delta t) d\nu_{\Delta t} - \int_{\mathbb{R}^d} f\left(\left(n + \frac{1}{2}\right)\Delta t\right) d\nu_0
\end{aligned}$$

After the change of variables $t = \frac{\tau}{2} + (n + \frac{1}{2})\Delta t$, we obtain

$$\begin{aligned}
& \int_{(n+\frac{1}{2})\Delta t}^{(n+1)\Delta t} \int_{\mathbb{R}^d} (\partial_t f(t) + 2\nabla f(t) \cdot V[\mu_{n\Delta t}^k]) d(\Phi_{2(t-(n+\frac{1}{2})\Delta t)}^{V[\mu_{n\Delta t}^k]} \# \mu_{(n+\frac{1}{2})\Delta t}^k) dt \\
& = \int_{\mathbb{R}^d} f((n+1)\Delta t) d\mu_{(n+1)\Delta t}^k - \int_{\mathbb{R}^d} f\left(\left(n + \frac{1}{2}\right)\Delta t\right) d\mu_{(n+\frac{1}{2})\Delta t}^k.
\end{aligned}$$

We now use this to evaluate the fourth term of (22). We have:

$$\begin{aligned}
A_4 = & - \int_{(n+\frac{1}{2})\Delta t}^{(n+1)\Delta t} \int_{\mathbb{R}^d} \nabla f \cdot V[\mu_{n\Delta t}^k] d(\Phi_{2(t-(n+\frac{1}{2})\Delta t)}^{V[\mu_{n\Delta t}^k]} \# \mu_{(n+\frac{1}{2})\Delta t}^k) dt \\
& + \int_{\mathbb{R}^d} f((n+1)\Delta t) d\mu_{(n+1)\Delta t}^k - \int_{\mathbb{R}^d} f\left(\left(n + \frac{1}{2}\right)\Delta t\right) d\mu_{(n+\frac{1}{2})\Delta t}^k.
\end{aligned} \tag{24}$$

Adding together the second and third terms of (22) and using (24), we obtain:

$$\begin{aligned}
A_3 + A_4 = & \int_{n\Delta t}^{(n+\frac{1}{2})\Delta t} \int_{\mathbb{R}^d} \nabla f \cdot V[\mu_{n\Delta t}^k] d\mu_t^k dt - \int_{(n+\frac{1}{2})\Delta t}^{(n+1)\Delta t} \int_{\mathbb{R}^d} \nabla f \cdot V[\mu_{n\Delta t}^k] d\mu_t^k dt \\
& + \int_{\mathbb{R}^d} f((n+1)\Delta t) d\mu_{(n+1)\Delta t}^k - \int_{\mathbb{R}^d} f\left(\left(n + \frac{1}{2}\right)\Delta t\right) d\mu_{(n+\frac{1}{2})\Delta t}^k.
\end{aligned}$$

Now,

$$\begin{aligned}
& \int_{n\Delta t}^{(n+\frac{1}{2})\Delta t} \int_{\mathbb{R}^d} \nabla f \cdot V[\mu_{n\Delta t}^k] d\mu_t^k dt - \int_{(n+\frac{1}{2})\Delta t}^{(n+1)\Delta t} \int_{\mathbb{R}^d} \nabla f \cdot V[\mu_{n\Delta t}^k] d\mu_t^k dt \\
& = \int_{n\Delta t}^{(n+\frac{1}{2})\Delta t} \int_{\mathbb{R}^d} \nabla f(t) \cdot V[\mu_{n\Delta t}^k] d\mu_t^k dt \\
& \quad - \int_{n\Delta t}^{(n+\frac{1}{2})\Delta t} \int_{\mathbb{R}^d} \nabla f\left(t + \frac{\Delta t}{2}\right) \cdot V[\mu_{n\Delta t}^k] d\mu_{t+\frac{\Delta t}{2}}^k dt \\
& = \int_{n\Delta t}^{(n+\frac{1}{2})\Delta t} \int_{\mathbb{R}^d} \nabla f(t) \cdot V[\mu_{n\Delta t}^k] d(\mu_t^k - \mu_{t+\frac{\Delta t}{2}}^k) dt \\
& \quad + \int_{n\Delta t}^{(n+\frac{1}{2})\Delta t} \int_{\mathbb{R}^d} (\nabla f(t) - \nabla f\left(t + \frac{\Delta t}{2}\right)) \cdot V[\mu_{n\Delta t}^k] d\mu_{t+\frac{\Delta t}{2}}^k dt \\
& = B_1 + B_2 + B_3
\end{aligned}$$

where

$$\begin{cases} B_1 := \int_{n\Delta t}^{(n+\frac{1}{2})\Delta t} \int_{\mathbb{R}^d} \nabla f(t) \cdot V[\mu_{n\Delta t}^k] d(\mu_t^k - \mu_{(n+\frac{1}{2})\Delta t}^k) dt, \\ B_2 := \int_{n\Delta t}^{(n+\frac{1}{2})\Delta t} \int_{\mathbb{R}^d} \nabla f(t) \cdot V[\mu_{n\Delta t}^k] d(\mu_{(n+\frac{1}{2})\Delta t}^k - \mu_{t+\frac{\Delta t}{2}}^k) dt, \\ B_3 := \int_{n\Delta t}^{(n+\frac{1}{2})\Delta t} \int_{\mathbb{R}^d} (\nabla f(t) - \nabla f\left(t + \frac{\Delta t}{2}\right)) \cdot V[\mu_{n\Delta t}^k] d\mu_{t+\frac{\Delta t}{2}}^k dt. \end{cases}$$

The first term gives:

$$\begin{aligned} |B_1| &= \left| \int_{n\Delta t}^{(n+\frac{1}{2})\Delta t} \int_{\mathbb{R}^d} \nabla f(t) \cdot V[\mu_{n\Delta t}^k] 2((n+\frac{1}{2})\Delta t - t) dh[\mu_{n\Delta t}^k] dt \right| \\ &\leq M_V \bar{S} \|\nabla f\|_{L^\infty} \Delta t^2. \end{aligned}$$

The second term gives:

$$\begin{aligned} |B_2| &\leq \left| \int_{n\Delta t}^{(n+\frac{1}{2})\Delta t} L_1 \rho(\mu_{(n+\frac{1}{2})\Delta t}^k, \mu_{t+\frac{\Delta t}{2}}^k) dt \right| \\ &\leq L_1 \int_{n\Delta t}^{(n+\frac{1}{2})\Delta t} M_V(t + \frac{\Delta t}{2} - (n + \frac{1}{2})\Delta t) dt \leq L_1 M_V \Delta t^2 \end{aligned}$$

where, denoting by $L_1(t)$ the Lipschitz constant of the function $x \mapsto \nabla f(t, x) \cdot V[\mu_{n\Delta t}^k](x)$, we define $L_1 := \sup_{t \in (0, T)} L_1(t)$. Notice that it is independent of n and k as seen in Proposition 8.

Lastly,

$$|B_3| \leq \int_{n\Delta t}^{(n+\frac{1}{2})\Delta t} \int_{\mathbb{R}^d} \frac{\Delta t}{2} |\partial_t(\nabla f(t))| |V[\mu_{n\Delta t}^k]| d\mu_{t+\frac{\Delta t}{2}}^k dt \leq M_V \|\partial_t \nabla f\|_{L^\infty} \frac{\Delta t^2}{4}.$$

We can finally go back to (22).

$$\begin{aligned} &\int_{n\Delta t}^{(n+1)\Delta t} \left(\int_{\mathbb{R}^d} (\partial_t f + V[\mu_{n\Delta t}^k] \cdot \nabla f) d\mu_t^k + \int_{\mathbb{R}^d} f dh[\mu_{n\Delta t}^k] \right) dt \\ &\leq \int_{n\Delta t}^{(n+\frac{1}{2})\Delta t} \int_{\mathbb{R}^d} \left(\frac{\Delta t}{2} \partial_t f(t) + O(\Delta t^2) \right) dh[\mu_{n\Delta t}^k] dt + \int_{\mathbb{R}^d} f((n+\frac{1}{2})\Delta t) d\mu_{(n+\frac{1}{2})\Delta t}^k \\ &\quad - \int_{\mathbb{R}^d} f(n\Delta t) d\mu_{n\Delta t}^k + \int_{\mathbb{R}^d} f((n+1)\Delta t) d\mu_{(n+1)\Delta t}^k \\ &\quad - \int_{\mathbb{R}^d} f((n+\frac{1}{2})\Delta t) d\mu_{(n+\frac{1}{2})\Delta t}^k + M_V(\bar{S} \|\nabla f\|_{L^\infty} + L_1 + \frac{1}{4} \|\partial_t \nabla f\|_{L^\infty}) \Delta t^2 \\ &\leq \int_{\mathbb{R}^d} f((n+1)\Delta t) d\mu_{(n+1)\Delta t}^k - \int_{\mathbb{R}^d} f(n\Delta t) dh[\mu_{n\Delta t}^k] + C \Delta t^2, \end{aligned}$$

with $C := 2\bar{S} \|\partial_t f\|_{L^\infty} + M_V(\bar{S} \|\nabla f\|_{L^\infty} + L_1 + \frac{1}{4} \|\partial_t \nabla f\|_{L^\infty})$. Thus,

$$\begin{aligned} &\lim_{k \rightarrow \infty} \left| \sum_{n=0}^{2^k-1} \int_{n\Delta t}^{(n+1)\Delta t} \left(\int_{\mathbb{R}^d} (\partial_t f + V[\mu_{n\Delta t}^k] \cdot \nabla f) d\mu_t^k + \int_{\mathbb{R}^d} f dh[\mu_{n\Delta t}^k] \right) dt \right| \\ &\leq \lim_{k \rightarrow \infty} C \sum_{n=0}^{2^k-1} \Delta t^2 = \lim_{k \rightarrow \infty} C T 2^{-k} = 0. \end{aligned}$$

□

We can now prove the following:

Proposition 13. *The limit measure $\bar{\mu}_t = \lim_{k \rightarrow \infty} \mu_t^k$ is a weak solution to (14). Moreover, $\bar{\mu}_t \in \mathcal{P}_c(\mathbb{R}^d)$ and for all $R > 0$, there exists $R_T > 0$ such that if $\text{supp}(\bar{\mu}_0) \subset B(0, R)$, for all $t \in [0, T]$, $\text{supp}(\bar{\mu}_t) \subset B(0, R_T)$.*

Proof. We will prove that for all $f \in C_c^\infty((0, T) \times \mathbb{R}^d)$,

$$\begin{aligned} \lim_{k \rightarrow \infty} \sum_{n=0}^{2^k-1} \int_{n\Delta t}^{(n+1)\Delta t} \left(\int_{\mathbb{R}^d} (\partial_t f + V[\mu_{n\Delta t}^k] \cdot \nabla f) d\mu_t^k + \int_{\mathbb{R}^d} f dh[\mu_{n\Delta t}^k] \right) dt \\ - \int_0^T \left(\int_{\mathbb{R}^d} (\partial_t f + V[\bar{\mu}_t] \cdot \nabla f) d\bar{\mu}_t + \int_{\mathbb{R}^d} f dh[\bar{\mu}_t] \right) dt = 0. \end{aligned} \quad (25)$$

First, denoting by $F_1 := \sup_{[0, T]} \|\partial_t f(t, \cdot)\|_{\text{Lip}} + \|\partial_t f\|_{L^\infty((0, T) \times \mathbb{R}^d)}$, observe that

$$\begin{aligned} \sum_{n=0}^{2^k-1} \int_{n\Delta t}^{(n+1)\Delta t} \int_{\mathbb{R}^d} \partial_t f d(\mu_t^k - \bar{\mu}_t) dt &= F_1 \sum_{n=0}^{2^k-1} \int_{n\Delta t}^{(n+1)\Delta t} \int_{\mathbb{R}^d} \frac{\partial_t f}{F_1} d(\mu_t^k - \bar{\mu}_t) dt \\ &\leq F_1 \sum_{n=0}^{2^k-1} \int_{n\Delta t}^{(n+1)\Delta t} \left(\sup_{f \in \mathcal{C}_c^{0, \text{Lip}}, \|f\|_{\text{Lip}} \leq 1, \|f\|_\infty \leq 1} \int_{\mathbb{R}^d} f d(\mu_t^k - \bar{\mu}_t) \right) dt \\ &\leq F_1 T \mathcal{D}(\mu^k, \bar{\mu}) \xrightarrow{k \rightarrow \infty} 0. \end{aligned}$$

Secondly, denoting by $F_2 := \sup_{[0, T]} \|f(t, \cdot)\|_{\text{Lip}} + \|f\|_{L^\infty((0, T) \times \mathbb{R}^d)}$,

$$\begin{aligned} \int_{\mathbb{R}^d} f d(h[\mu_{n\Delta t}^k] - h[\bar{\mu}_t]) &= F_2 \int_{\mathbb{R}^d} \frac{f}{F_2} d(h[\mu_{n\Delta t}^k] - h[\bar{\mu}_t]) \leq F_2 \rho(h[\mu_{n\Delta t}^k], h[\bar{\mu}_t]) \\ &\leq F_2 L_h \rho(\mu_{n\Delta t}^k, \bar{\mu}_t) \leq F_2 L_h (\rho(\mu_{n\Delta t}^k, \mu_t^k) + \rho(\mu_t^k, \bar{\mu}_t)) \\ &\leq F_2 L_h ((\bar{S} + M_V) \Delta t + \mathcal{D}(\mu_t^k, \bar{\mu}_t)) \end{aligned}$$

from Equation (19). Hence,

$$\begin{aligned} \sum_{n=0}^{2^k-1} \int_{n\Delta t}^{(n+1)\Delta t} \int_{\mathbb{R}^d} f d(h[\mu_{n\Delta t}^k] - h[\bar{\mu}_t]) dt \\ \leq F_2 L_h \sum_{n=0}^{2^k-1} \int_{n\Delta t}^{(n+1)\Delta t} ((\bar{S} + M_V) \Delta t + \mathcal{D}(\mu_t^k, \bar{\mu}_t)) dt \\ \leq (\bar{S} + M_V) \sum_{n=0}^{2^k-1} \Delta t^2 + T \mathcal{D}(\mu_t^k, \bar{\mu}_t) = 2^{-k} T (\bar{S} + M_V) + T \mathcal{D}(\mu_t^k, \bar{\mu}_t) \xrightarrow{k \rightarrow \infty} 0. \end{aligned}$$

Thirdly, denoting by $F_3 := \sup_{[0, T]} \|\nabla f(t, \cdot)\|_{\text{Lip}} + \|\nabla f\|_{L^\infty((0, T) \times \mathbb{R}^d)}$,

$$\begin{aligned} \int_{\mathbb{R}^d} V[\mu_{n\Delta t}^k] \cdot \nabla f d\mu_t^k - \int_{\mathbb{R}^d} V[\bar{\mu}_t] \cdot \nabla f d\bar{\mu}_t \\ = \int_{\mathbb{R}^d} V[\mu_{n\Delta t}^k] \cdot \nabla f d(\mu_t^k - \bar{\mu}_t) + \int_{\mathbb{R}^d} (V[\mu_{n\Delta t}^k] - V[\mu_t^k]) \cdot \nabla f d\bar{\mu}_t \\ + \int_{\mathbb{R}^d} (V[\mu_t^k] - V[\bar{\mu}_t]) \cdot \nabla f d\bar{\mu}_t \\ \leq F_3 (M_V + 2L_V) \rho(\mu_t^k, \bar{\mu}_t) + F_3 L_V (\bar{S} + M_V) \Delta t. \end{aligned}$$

Hence, $\sum_{n=0}^{2^k-1} \int_{n\Delta t}^{(n+1)\Delta t} \int_{\mathbb{R}^d} V[\mu_{n\Delta t}^k] \cdot \nabla f d\mu_t^k - \int_{\mathbb{R}^d} V[\bar{\mu}_t] \cdot \nabla f d\bar{\mu}_t dt \xrightarrow{k \rightarrow \infty} 0$. We conclude that (25) holds, and from Lemma 4.2, we obtain:

$$\int_0^T \left(\int_{\mathbb{R}^d} (\partial_t f + V[\bar{\mu}_t] \cdot \nabla f) d\bar{\mu}_t + \int_{\mathbb{R}^d} f dh[\bar{\mu}_t] \right) dt = 0.$$

As remarked in [21], this weak formulation is equivalent to the Definition 4.1. This proves that $\bar{\mu}_t$ is a weak solution to (14). The compactness of its support can be deduced from Proposition 11. \square

Proposition 14. *Let $\mu, \nu \in C([0, T], \mathcal{P}_c(\mathbb{R}^d))$ be two solutions to (14) with initial conditions μ_0, ν_0 . There exists a constant $C > 0$ such that for all $t \in [0, T]$,*

$$\rho(\mu_t, \nu_t) \leq e^{Ct} \rho(\mu_0, \nu_0).$$

In particular, this implies uniqueness of the solution to (14).

Proof. Let $\mu, \nu \in C([0, T], \mathcal{P}_c(\mathbb{R}^d))$ be two solutions to (14) with initial conditions μ_0, ν_0 . Let $\varepsilon(t) = \rho(\mu_t, \nu_t)$. Then

$$\varepsilon(t + \tau) = \rho(\mu_{t+\tau}, \nu_{t+\tau}) \leq A_1 + A_2 + A_3 \quad (26)$$

where $A_1 = \rho(\mu_{t+\tau}, \Phi_\tau^{V[\mu_t]} \# (\mu_t + \tau h[\mu_t]))$, $A_2 = \rho(\nu_{t+\tau}, \Phi_\tau^{V[\nu_t]} \# (\nu_t + \tau h[\nu_t]))$ and $A_3 = \rho(\Phi_\tau^{V[\mu_t]} \# (\mu_t + \tau h[\mu_t]), \Phi_\tau^{V[\nu_t]} \# (\nu_t + \tau h[\nu_t]))$. From Prop 4, it holds:

$$\begin{aligned} A_3 &\leq (1 + 2L\tau) \rho(\mu_t + \tau h[\mu_t], \nu_t + \tau h[\nu_t]) \\ &\quad + \min\{|\mu_t + \tau h[\mu_t]|, |\nu_t + \tau h[\nu_t]|\} 2\tau L_V \rho(\mu_t, \nu_t) \\ &\leq (1 + 2(2L_\phi + L_h + 2L_V)\tau) \rho(\mu_t, \nu_t). \end{aligned} \quad (27)$$

For A_1 and A_2 , we prove that any solution μ to (14) satisfies the operator-splitting estimate:

$$\forall (t, \tau) \in [0, T] \times [0, T - t], \quad \rho(\mu_{t+\tau}, \Phi_\tau^{V[\mu_t]} \# \mu_t + \tau h[\mu_t]) \leq K \tau^2. \quad (28)$$

We begin by proving (28) for solutions to the numerical scheme \mathbb{S} . Let $k \in \mathbb{N}$ and μ_t^k be the solution to \mathbb{S} with time-step $\Delta t = 2^{-k}T$ and initial condition μ_0 . For simplicity, we assume that $t = n\Delta t$ and $\tau = l\Delta t$, with $(n, l) \in \mathbb{N}^2$, and we study the distance

$$D_l := \rho(\mu_{(n+l)\Delta t}^k, \Phi_{l\Delta t}^{V[\mu_{n\Delta t}^k]} \# (\mu_{n\Delta t}^k + l\Delta t h[\mu_{n\Delta t}^k])).$$

Notice that by definition of the numerical scheme, for $l = 1$, $D_1 = 0$.

Let us now suppose that for some $l \in \mathbb{N}$, $D_l \leq K(l-1)^2 \Delta t^2$. We compute

$$\begin{aligned} D_{l+1} &= \rho(P_{n+l}^k \# (\mu_{(n+l)\Delta t}^k + \Delta t H_{n+l}^k), P_n^k \# \Phi_{l\Delta t}^{V[\mu_{n\Delta t}^k]} \# (\mu_{n\Delta t}^k + l\Delta t H_n^k + \Delta t H_n^k)) \\ &\leq \rho(P_{n+l}^k \# \mu_{(n+l)\Delta t}^k, P_n^k \# \Phi_{l\Delta t}^{V[\mu_{n\Delta t}^k]} \# (\mu_{n\Delta t}^k + l\Delta t H_n^k)) \\ &\quad + \Delta t \rho(P_{n+l}^k \# H_{n+l}^k, P_n^k \# \Phi_{l\Delta t}^{V[\mu_{n\Delta t}^k]} \# H_n^k) \\ &\leq (1 + 2L_\phi \Delta t) \rho(\mu_{(n+l)\Delta t}^k, \Phi_{l\Delta t}^{V[\mu_{n\Delta t}^k]} \# (\mu_{n\Delta t}^k + l\Delta t H_n^k)) + 2\Delta t L_V \rho(\mu_{(n+l)\Delta t}^k, \mu_{n\Delta t}^k) \\ &\quad + \Delta t (1 + 2L_\phi \Delta t) \rho(H_{n+l}^k, \Phi_{l\Delta t}^{V[\mu_{n\Delta t}^k]} \# H_n^k) + 2\Delta t^2 L_V \rho(\mu_{(n+l)\Delta t}^k, \mu_{n\Delta t}^k), \end{aligned}$$

where we used that from Proposition 10, for k large enough, $\Phi_{l\Delta t}^{V[\mu_{n\Delta t}^k]} \# (\mu_{n\Delta t}^k + l\Delta t H_n^k) \in \mathcal{P}(\mathbb{R}^d)$, thus $|\Phi_{l\Delta t}^{V[\mu_{n\Delta t}^k]} \# (\mu_{n\Delta t}^k + l\Delta t H_n^k)| = |\mu_{(n+l)\Delta t}^k| = 1$. Now since $\rho(\mu_{(n+l)\Delta t}^k, \mu_{n\Delta t}^k) \leq l\Delta t (M_V + \bar{S})$,

$$\begin{aligned} D_{l+1} &\leq (1 + 2L_\phi \Delta t) K((l-1)^2 \Delta t^2) + 2\Delta t L_V l\Delta t (M_V + \bar{S}) \\ &\quad + \Delta t (1 + 2L_\phi \Delta t) (L_h l\Delta t (M_V + \bar{S}) + l\Delta t M_V \bar{S}) + 2L_V \Delta t^2 l\Delta t (M_V + \bar{S}) \\ &\leq \Delta t^2 [K(l-1)^2 + l((2L_V + L_h)(M_V + \bar{S}) + M_V \bar{S})] + O(\Delta t^3) \\ &\leq \Delta t^2 [K(l-1)^2 + Kl] \leq Kl^2 \Delta t^2. \end{aligned}$$

Thus, by induction, $\rho(\mu_{(n+l)\Delta t}^k, \Phi_{l\Delta t}^{V[\mu_{n\Delta t}^k]}(\mu_{n\Delta t}^k + l\Delta t \ h[\mu_{n\Delta t}^k])) \leq K(l\Delta t)^2$ and similarly we can prove that for all $(t, \tau) \in [0, T] \times [0, T - t]$, $\rho(\mu_{t+\tau}^k, \Phi_\tau^{V[\mu_t^k]}(\mu_t^k + \tau h[\mu_t^k])) \leq K\tau^2$. Hence,

$$\begin{aligned} \rho(\mu_{t+\tau}, \Phi_\tau^{V[\mu_t]}(\mu_t + \tau h[\mu_t])) &\leq \rho(\mu_{t+\tau}^k, \Phi_\tau^{V[\mu_t^k]}(\mu_t^k + \tau h[\mu_t^k])) + \rho(\mu_{t+\tau}, \mu_{t+\tau}^k) \\ &\quad + \rho(\Phi_\tau^{V[\mu_t]}(\mu_t + \tau h[\mu_t]), \Phi_\tau^{V[\mu_t^k]}(\mu_t^k + \tau h[\mu_t^k])) \end{aligned}$$

and by taking the limit $k \rightarrow \infty$, $\rho(\mu_{t+\tau}, \Phi_\tau^{V[\mu_t]}(\mu_t + \tau h[\mu_t])) \leq K\tau^2$, which proves (28).

Coming back to (26), and using (27) and (28), it holds $\varepsilon(t + \tau) \leq (1 + 2(2L_\phi + 2L_V + L_h)\tau) \varepsilon(t) + 2K\tau^2$. Then $\frac{\varepsilon(t+\tau) - \varepsilon(t)}{\tau} \leq 2(2L_\phi + 2L_V + L_h)\varepsilon(t) + 2K\tau$, which proves that ε is differentiable and that $\varepsilon'(t) \leq 2(2L_\phi + 2L_V + L_h)\varepsilon(t)$. From Gronwall's lemma, $\varepsilon(t) \leq \varepsilon(0)e^{2(2L_\phi + 2L_V + L_h)t}$. This proves continuity with respect to the initial data, i.e. uniqueness of the solution. \square

We have thus proven Theorem 1.1: Existence was obtained as the limit of the numerical scheme \mathbb{S} in Proposition 13; Uniqueness comes from Proposition 14.

We saw in Section 3.2 that the Bounded Lipschitz distance and the 1-Wasserstein distance are equivalent on the set of probability measures with uniformly compact support. This allows us to state the following:

Corollary 1. *Let $\mu, \nu \in C([0, T], \mathcal{P}_c(\mathbb{R}^d))$ be two solutions to (14) with initial conditions μ_0, ν_0 satisfying $\text{supp}(\mu_0) \cup \text{supp}(\nu_0) \subset B(0, R)$. There exist constants $C > 0$ and $C_{R_T} > 0$ such that for all $t \in [0, T]$,*

$$W_1(\mu_t, \nu_t) \leq C_{R_T} e^{Ct} W_1(\mu_0, \nu_0).$$

Furthermore, for all $p \in \mathbb{N}^*$,

$$W_p(\mu_t, \nu_t) \leq (2R)^{\frac{p-1}{p}} C_{R_T}^{\frac{1}{p}} e^{\frac{C}{p}t} W_p(\mu_0, \nu_0)^{\frac{1}{p}}.$$

Proof. Let $R > 0$ such that $\text{supp}(\mu_0) \cup \text{supp}(\nu_0) \subset B(0, R)$. From Proposition 13, there exists $R_T > 0$ such that for all $t \in [0, T]$, $\text{supp}(\mu_t) \cup \text{supp}(\nu_t) \subset B(0, R_T)$. Putting together Proposition 14, equation (12) and Proposition 6,

$$W_1(\mu_t, \nu_t) \leq C_{R_T} \rho(\mu_t, \nu_t) \leq C_{R_T} e^{Ct} \rho(\mu_0, \nu_0) \leq C_{R_T} e^{Ct} W_1(\mu_0, \nu_0),$$

where $C_{R_T} = \max(1, R_T)$. Moreover, for all $p \in \mathbb{N}^*$, from equation (13) and Proposition 7, it holds

$$\begin{aligned} W_p(\mu_t^N, \mu_t) &\leq (2R)^{\frac{p-1}{p}} W_1(\mu_t^N, \mu_t)^{\frac{1}{p}} \leq (2R)^{\frac{p-1}{p}} C_{R_T}^{\frac{1}{p}} e^{\frac{C}{p}t} W_1(\mu_0^N, \mu_0)^{\frac{1}{p}} \\ &\leq (2R)^{\frac{p-1}{p}} C_{R_T}^{\frac{1}{p}} e^{\frac{C}{p}t} W_p(\mu_0^N, \mu_0)^{\frac{1}{p}}. \end{aligned}$$

\square

5. Convergence to the macroscopic model. Having proven the well-posedness of both the microscopic and macroscopic models, we are now in a position to prove the convergence result stated in Theorem 1.2 that is central to this paper. The proof, as for the now classical proof of convergence of the microscopic dynamics without weights (1) to the non-local transport PDE (2) (see [10]), relies on two ingredients: the fact that the empirical measure satisfies the PDE and the continuity of the solution with respect to the initial data. We begin by defining the empirical measure for our microscopic system with weight dynamics and prove that it does satisfy the PDE (14).

5.1. From microscopic to macroscopic via the empirical measure. The fact that (7) preserves indistinguishability allows us to define a generalized version of the empirical measure. For all $N \in \mathbb{N}$ and $(x, m) \in \mathcal{C}([0, T]; (\mathbb{R}^d)^N \times \mathbb{R}^N)$ solution to (7), let

$$\mu_t^N = \frac{1}{M} \sum_{i=1}^N m_i(t) \delta_{x_i(t)} \quad (29)$$

be the *generalized empirical measure*. From Proposition 1, we know that for all $t \in [0, T]$, $\mu_t \in \mathcal{P}(\mathbb{R}^d)$. We can prove the following:

Proposition 15. *Let $(x, m) \in \mathcal{C}([0, T]; (\mathbb{R}^d)^N \times \mathbb{R}^N)$ be a solution to (7), and let $\mu^N \in C([0, T]; \mathcal{P}(\mathbb{R}^d))$ denote the corresponding empirical measure, given by (29). Then, μ^N is a weak solution to (14).*

Proof. We show that μ_t^N satisfies (17). Let $f \in C_c^\infty(\mathbb{R}^d)$. Substituting μ by μ^N in the left-hand side of (17), we obtain

$$\frac{d}{dt} \int_{\mathbb{R}^d} f(x) d\mu_t^N(x) = \frac{1}{M} \sum_{i=1}^N \dot{m}_i(t) f(x_i(t)) + \frac{1}{M} \sum_{i=1}^N m_i(t) \nabla f(x_i(t)) \cdot \dot{x}_i(t). \quad (30)$$

The first part of the right-hand side of (17) gives

$$\begin{aligned} \int_{\mathbb{R}^d} V[\mu_t] \cdot \nabla f(x) d\mu_t^N(x) &= \frac{1}{M^2} \sum_{i=1}^N \sum_{j=1}^N m_i m_j \phi(x_j - x_i) \cdot \nabla f(x_i) \\ &= \frac{1}{M} \sum_{i=1}^N m_i \nabla f(x_i) \cdot \dot{x}_i. \end{aligned} \quad (31)$$

where the last equality comes from the fact that x is a solution to (7). The second part of the right-hand side of (17) gives:

$$\begin{aligned} \int_{\mathbb{R}^d} f(x) dh[\mu_t^N](x) &= \frac{1}{M} \sum_{i=1}^N m_i f(x_i) \frac{1}{M^q} \sum_{j_1=1}^N \cdots \sum_{j_q=1}^N m_{j_1} \cdots m_{j_q} S(x_i, x_{j_1}, \dots, x_{j_q}) \\ &= \frac{1}{M} \sum_{i=1}^N \dot{m}_i f(x_i). \end{aligned}$$

where the last equality comes from the fact that m is a solution to (7). Putting together this last equation with (30) and (31), we deduce that μ_t^N satisfies (17), thus it is a weak solution to (14). \square

5.2. Convergence. We are finally equipped to prove Theorem 1.2, that we state again here in its full form:

Theorem 2. *Let $T > 0$, $q \in \mathbb{N}$ and $M > 0$.*

For each $N \in \mathbb{N}$, let $(x_i^{N,0}, m_i^{N,0})_{i \in \{1, \dots, N\}} \in (\mathbb{R}^d)^N \times (\mathbb{R}^{+})^N$ such that $\sum_{i=1}^N m_i^{N,0} = M$. Let $\phi \in C(\mathbb{R}^d; \mathbb{R}^d)$ satisfying Hyp. 1 and let $S \in C((\mathbb{R}^d)^{q+1}; \mathbb{R})$ satisfying Hyp. 2. For all $t \in [0, T]$, let $t \mapsto (x_i^N(t), m_i^N(t))_{i \in \{1, \dots, N\}}$ be the solution*

to

$$\begin{cases} \dot{x}_i = \frac{1}{M} \sum_{j=1}^N m_j \phi(x_j - x_i), & x_i(0) = x_i^{N,0} \\ \dot{m}_i = m_i \frac{1}{M^q} \sum_{j_1=1}^N \cdots \sum_{j_q=1}^N m_{j_1} \cdots m_{j_q} S(x_i, x_{j_1}, \dots, x_{j_q}), & m_i(0) = m_i^{N,0}, \end{cases}$$

and let $\mu_t^N := \frac{1}{M} \sum_{i=1}^N m_i^N(t) \delta_{x_i^N(t)} \in \mathcal{P}_c(\mathbb{R}^d)$ be the corresponding empirical measure. Let $\mathcal{D}(\cdot, \cdot)$ denote either the Bounded Lipschitz distance $\rho(\cdot, \cdot)$ or any of the Wasserstein distances $W_p(\cdot, \cdot)$ for $p \in \mathbb{N}^*$. If there exists $\mu_0 \in \mathcal{P}_c(\mathbb{R}^d)$ such that

$$\lim_{N \rightarrow \infty} \mathcal{D}(\mu_0^N, \mu_0) = 0,$$

then for all $t \in [0, T]$,

$$\lim_{N \rightarrow \infty} \mathcal{D}(\mu_t^N, \mu_t) = 0,$$

where μ_t is the solution to the transport equation with source

$$\begin{aligned} \partial_t \mu_t(x) + \nabla \cdot \left(\int_{\mathbb{R}^d} \phi(x - y) d\mu_t(y) \mu_t(x) \right) \\ = \left(\int_{(\mathbb{R}^d)^q} S(x, y_1, \dots, y_q) d\mu_t(y_1) \cdots d\mu_t(y_q) \right) \mu_t(x), \end{aligned}$$

with initial data $\mu_{t=0} = \mu_0$.

Proof. Since μ_t^N and μ_t are both weak solutions to (14), from Proposition 14, there exists $C > 0$ such that $\rho(\mu_t^N, \mu_t) \leq e^{Ct} \rho(\mu_0^N, \mu_0)$ and the result follows immediately for $\mathcal{D} = \rho$.

Let $R < 0$ such that $\text{supp}(\mu_0) \cup \text{supp}(\mu_0^N) \subset B(0, R)$ for all $N \in \mathbb{N}$. From Corollary 1, there exists $C_{R,T} > 0$ depending on T and R such that for all $p \in \mathbb{N}^*$, $W_p(\mu_t^N, \mu_t) \leq (2R)^{\frac{p-1}{p}} C_{R,T}^{\frac{1}{p}} e^{\frac{C}{p}t} W_p(\mu_0^N, \mu_0)^{\frac{1}{p}}$ and the result follows for $\mathcal{D} = W_p$. \square

6. Numerical simulations. To illustrate our convergence result, we provide numerical simulations for a specific model. We also refer the reader to the paper [2] for numerical simulations with a different model.

We recall the first model (M1) proposed in [16], “increasing weight by pairwise competition”:

$$\begin{cases} \dot{x}_i(t) = \frac{1}{M} \sum_{j=1}^N m_j(t) \phi(x_j(t) - x_i(t)), & x_i(0) = x_i^0 \\ \dot{m}_i(t) = \frac{1}{M} m_i(t) \sum_{j=1}^N m_j(t) \beta \left\langle \frac{\dot{x}_i(t) + \dot{x}_j(t)}{2}, u_{ji} \right\rangle, & m_i(0) = m_i^0 \end{cases} \quad (32)$$

where u_{ji} is the unit vector in the direction $x_i - x_j$ and β is a constant.

With this choice of model, the evolution of each agent’s weight depends on the dynamics of the midpoints $(x_i + x_j)/2$ between x_i and each other agent at position x_j . More specifically, if the midpoint $(x_i + x_j)/2$ moves in the direction of x_i , i.e. $\langle \frac{\dot{x}_i + \dot{x}_j}{2}, u_{ji} \rangle > 0$, then the weight m_i increases proportionally to m_j . If, on the other hand, $(x_i + x_j)/2$ moves away from x_i and towards x_j , the weight m_i decreases by the same proportion.

In order to ensure continuity, we slightly modify the model and replace u_{ji} by a function $h(x_i - x_j)$, where $h \in \text{Lip}(\mathbb{R}^d; \mathbb{R}^d)$ is non-decreasing and satisfies the following properties:

- $h(y) = \tilde{h}(|y|)y$ for some $\tilde{h} \in C(\mathbb{R}^+; \mathbb{R}^+)$
- $h(y) \sim \frac{y}{|y|}$ when $|y| \rightarrow \infty$.

Then, by replacing \dot{x}_i and \dot{x}_j by their expressions, the second equation becomes:

$$\dot{m}_i = \frac{1}{M^2} m_i \sum_{j=1}^N \sum_{k=1}^N m_j m_k \beta \left\langle \frac{\phi(x_k - x_i) + \phi(x_k - x_j)}{2}, h(x_i - x_j) \right\rangle.$$

Notice that it is in the form of System (7), with $q = 2$ and $S \in C((\mathbb{R}^d)^3; \mathbb{R})$ defined by $S(x, y, z) = \beta \left\langle \frac{\phi(z-x) + \phi(z-y)}{2}, h(x-y) \right\rangle$. One easily sees that $S(x, y, z) = -S(y, x, z)$, thus S satisfies (10). Furthermore, for every $R_T > 0$, there exists \bar{S} such that for all $x, y, z \in B(0, R_T)$, $S(x, y, z) \leq \bar{S}$, hence condition (8) is satisfied in a relaxed form. Lastly, it is simple to check that as long as $\phi \in \text{Lip}(\mathbb{R}^d; \mathbb{R}^d)$, $S \in \text{Lip}((\mathbb{R}^d)^3; \mathbb{R})$ thus S satisfies (9).

We can then apply Theorem 1.2.

Consider $\mu_0 \in \mathcal{P}(\mathbb{R})$. For simplicity purposes, for the numerical simulations we take μ_0 supported on $[0, 1]$ and absolutely continuous with respect to the Lebesgue measure. For a given $N \in \mathbb{N}$, we define for each $i \in \{1, \dots, N\}$: $x_i^{N,0} := \frac{i}{N}$ and $m_i^{N,0} := \int_{\frac{i-1}{N}}^{\frac{i}{N}} d\mu_0$. We then have convergence of the empirical measures μ_0^N to μ_0 when N goes to infinity. According to Theorem 1.2, for all $t \in [0, T]$, $\mu_t^N \rightharpoonup \mu_t$, where μ_t is the solution to the transport equation with source

$$\partial_t \mu_t(x) + \partial_x \left(\int_{\mathbb{R}} \phi(y-x) d\mu_t(y) \mu_t(x) \right) = \left(\int_{\mathbb{R}^2} S(x, y, z) d\mu_t(y) d\mu_t(z) \right) \mu_t(x). \quad (33)$$

Figures 1, 2 and 3 illustrate this convergence for the specific choices : $\beta := 100$, $M := N$, and

- $\phi := \phi_{0.2}$, where for all $R > 0$, $\phi_R : \delta \mapsto \frac{\delta}{|\delta|} \sin^2(\frac{\pi}{R}|\delta|) \mathbb{1}_{|\delta| \leq R}$,
- $h : \delta \mapsto \arctan(|\delta|) \frac{\delta}{|\delta|}$,
- $d\mu_0(x) := \frac{f(x)}{F} dx$, with

$$f(x) := \left[\frac{3.5}{\sqrt{0.4\pi}} \exp\left(-\frac{5(x-0.25)^2}{4}\right) + \frac{1}{\sqrt{0.4\pi}} \exp\left(-\frac{5(x-0.90)^2}{4}\right) \right] \mathbb{1}_{[0,1]}(x)$$

$$\text{and } F := \int_{\mathbb{R}} f(x) dx.$$

Remark 5. The interaction function ϕ_R provides an example of a bounded-confidence model (see [15]): agents interact only if they are within distance R of one another. Furthermore, the force exerted by x_j on x_i is colinear to the vector $x_j - x_i$: this translates the fact that x_j attracts x_i . Since the seminal paper [15], bounded-confidence models have been extensively studied in opinion dynamics, and it is well-known that they can lead to various global phenomena such as consensus or clustering.

Figure 1 shows the evolution of $t \mapsto (x_i^N(t))_{i \in \{1, \dots, N\}}$ and Figure 2 shows the evolution of $t \mapsto (m_i^N(t))_{i \in \{1, \dots, N\}}$ for $N = 20$, $N = 50$ and $N = 100$. Due to the fact that the interaction function ϕ has compact support, we observe formation of clusters within the population. Note that as expected, the final number and

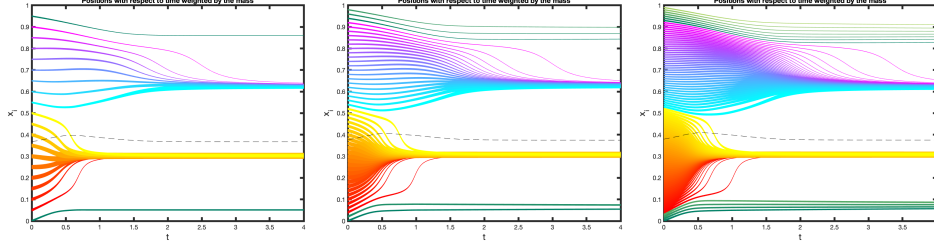


FIGURE 1. Evolution of the positions for $N = 20$, $N = 50$ and $N = 100$. The thickness of the lines is proportional to the agent's weight. The dotted line represents the barycenter $\bar{x} := \frac{1}{M} \sum_i m_i x_i$.

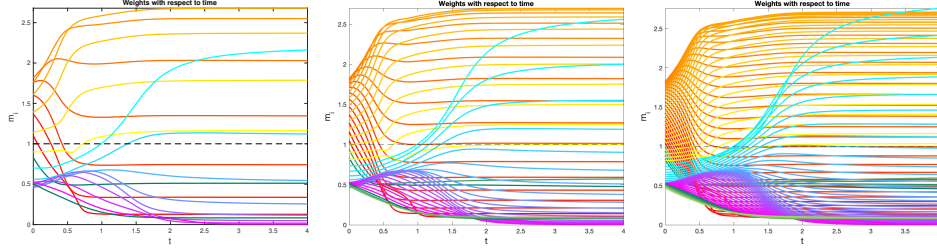


FIGURE 2. Evolution of the weights for $N = 20$, $N = 50$ and $N = 100$. The dotted line represents the average weight $\bar{m} := \frac{1}{M} \sum_i m_i$.

positions of clusters are the same for all values of N (N big enough). Within each cluster, the agents that are able to attract more agents gain influence (i.e. weight), while the followers tend to lose influence (weight).

Figure 3 compares the evolutions of $t \mapsto \mu_t$ and $t \mapsto \mu_t^N$ at four different times. For visualization, the empirical measure was represented by the piece-wise constant counting measure $\tilde{\mu}_t^N$ defined by: for all $x \in E_j$, $\tilde{\mu}_t^N(x) = \frac{p}{M} \sum_{i=1}^N m_i \mathbb{1}\{x_i \in E_j\}$, where for each $j \in \{1, \dots, p\}$, $E_j = [\frac{j-1}{p}, \frac{j}{p})$, so that $(E_j)_{j \in \{1, \dots, p\}}$ is a partition of $[0, 1]$. In Fig. 3, $p = 41$. We observe a good correspondence between the two solutions at all four time steps. Observe that the four clusters are formed at the same locations that in Figure 1, i.e. at $x = 0.07$, $x = 0.33$, $x = 0.66$ and $x = 0.9$. Convergence to the first and fourth clusters is slower than convergence to the second and third, due to the differences in the total weight of each cluster.

Appendix. We provide the proof of Proposition 2. It is modeled after the proof of existence and uniqueness of the Graph Limit equation provided in [2], but we write it fully here for self-containedness.

Proof. Let $(\tilde{x}_i)_{i \in \{1, \dots, N\}} \in C([0, T]; (\mathbb{R}^d)^N)$ and $(\tilde{m}_i)_{i \in \{1, \dots, N\}} \in C([0, T]; \mathbb{R}_+^N)$. Consider the following decoupled systems of ODE:

$$\begin{cases} \dot{x}_i(t) = \frac{1}{M} \sum_{j=1}^N \tilde{m}_j(t) \phi(x_j(t) - x_i(t)), \\ x_i(0) = x_i^{\text{in}}; \end{cases} \quad (34)$$

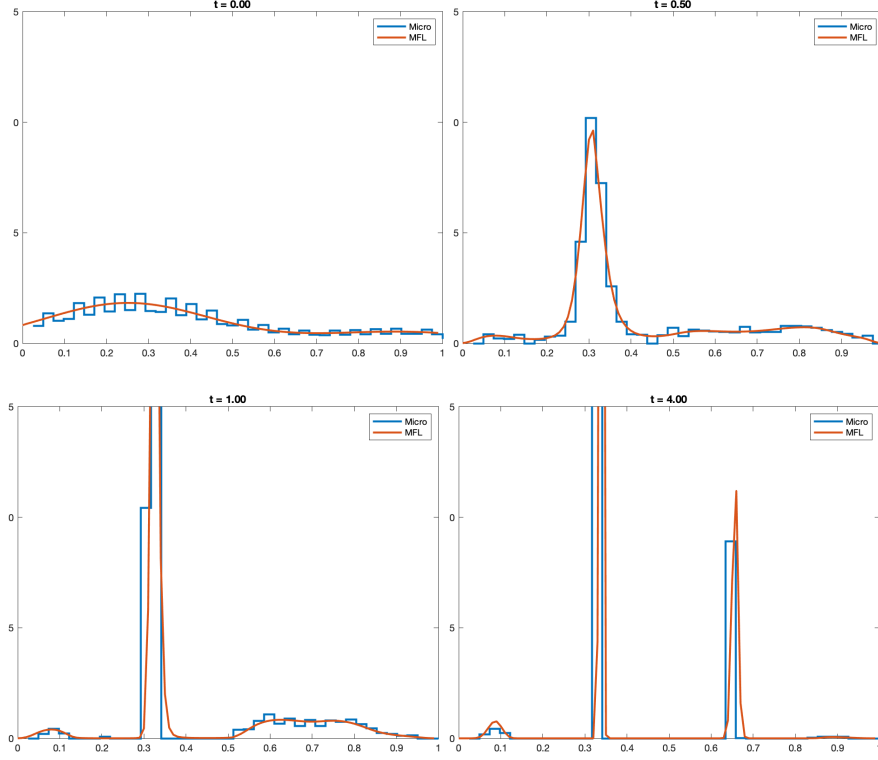


FIGURE 3. Comparison of μ_t (in red), solution to the macroscopic model (33) and $\tilde{\mu}_t^N$ (in blue), counting measure corresponding to the solution to the microscopic model (32) for $N = 100$.

$$\begin{cases} \dot{m}_i(t) = m_i(t) \frac{1}{M^q} \sum_{j_1=1}^N \cdots \sum_{j_q=1}^N m_{j_1}(t) \cdots m_{j_q}(t) S(\tilde{x}_i(t), \tilde{x}_{j_1}(t), \dots, \tilde{x}_{j_q}(t)), \\ m_i(0) = m_i^{\text{in}}. \end{cases} \quad (35)$$

Existence and uniqueness of the solution to the Cauchy problem given by (34) comes from a simple fixed-point argument.

We now show existence and uniqueness of the solution to the second decoupled system (35). Let $m^0 \in \mathbb{R}_+^N$ such that $\sum_{i=1}^N m_i^{\text{in}} = M$. Let $M_{m^{\text{in}}} := \{m \in C([0, \tilde{T}], \mathbb{R}_+^N) \mid m(t=0) = m^{\text{in}} \text{ and } \sum_{i=1}^N m_i \equiv M\}$. Consider the application $K_{m^{\text{in}}} : M_{m^{\text{in}}} \rightarrow M_{m^{\text{in}}}$ where

$$\begin{aligned} (K_{m^{\text{in}}} m)_i(t) &:= m_i^0 \\ &+ \int_0^t m_i(\tau) \frac{1}{M^q} \sum_{j_1=1}^N \cdots \sum_{j_q=1}^N m_{j_1}(\tau) \cdots m_{j_q}(\tau) S(\tilde{x}_i(\tau), \tilde{x}_{j_1}(\tau), \dots, \tilde{x}_{j_q}(\tau)) d\tau \end{aligned}$$

for all $t \in [0, \tilde{T}]$ and $i \in \{1, \dots, N\}$. We show that $K_{m^{\text{in}}}$ is contracting for the norm $\|m\|_{M_{m^{\text{in}}}} := \frac{1}{M} \sup_{t \in [0, \tilde{T}]} \sum_{i=1}^N |m_i(t)|$. Let $m, p \in M_{m^{\text{in}}}$. It holds:

$$\begin{aligned}
|(K_{m^{\text{in}}}m - K_{m^{\text{in}}}p)_i| &\leq \int_0^t \frac{1}{M^q} |m_i - p_i| \sum_{j_1 \cdots j_q} m_{j_1} \cdots m_{j_q} |S(\tilde{x}_i, \tilde{x}_{j_1}, \dots, \tilde{x}_{j_q})| d\tau \\
&+ \int_0^t \frac{1}{M^q} p_i \sum_{j_1 \cdots j_q} |m_{j_1} - p_{j_1}| m_{j_2} \cdots m_{j_q} |S(\tilde{x}_i, \tilde{x}_{j_1}, \dots, \tilde{x}_{j_q})| d\tau \\
&+ \cdots + \int_0^t \frac{1}{M^q} p_i \sum_{j_1 \cdots j_q} p_{j_1} \cdots p_{j_{q-1}} |m_{j_q} - p_{j_q}| |S(\tilde{x}_i, \tilde{x}_{j_1}, \dots, \tilde{x}_{j_q})| d\tau \\
&\leq \bar{S}\tilde{T} \sup_{[0, \tilde{T}]} |m_i - p_i| + q \bar{S}\tilde{T} \frac{1}{M} \sup_{[0, \tilde{T}]} (p_i \sum_{j=1}^N |m_j - p_j|) \\
&\leq \bar{S}\tilde{T} \sup_{[0, \tilde{T}]} |m_i - p_i| + q \bar{S}\tilde{T} \sup_{[0, \tilde{T}]} \sum_{j=1}^N |m_j - p_j|.
\end{aligned}$$

Thus, $\|K_{m^{\text{in}}}m - K_{m^{\text{in}}}p\|_{M_{m^{\text{in}}}} \leq (q+1) \bar{S}\tilde{T} \|m - p\|_{M_{m^{\text{in}}}}$. Taking $\tilde{T} \leq \frac{1}{2}((q-1)\bar{S})^{-1}$, the operator $K_{m^{\text{in}}}$ is contracting. Thus, there is a unique solution $m \in C^1([0, T], \mathbb{R}_+^N)$ to (35).

Let us define the sequences $(x^n)_{n \in \mathbb{N}}$ and $(m^n)_{n \in \mathbb{N}}$ by : $m^0(t) = m^{\text{in}}$ and $x^0(t) = x^{\text{in}}$ for all $t \in [0, T]$. For all $n \geq 1$, x^n and m^n are solutions to the system of ODEs

$$\begin{aligned}
\dot{x}_i^n &= \frac{1}{M} \sum_{j=1}^N m_j^{n-1} \phi(x_j^n - x_i^n), \\
\dot{m}_i^n &= m_i^n \frac{1}{M^q} \sum_{j_1=1}^N \cdots \sum_{j_q=1}^N m_{j_1}^n \cdots m_{j_q}^n S(x_i^{n-1}, x_{j_1}^{n-1}, \dots, x_{j_q}^{n-1})
\end{aligned}$$

with initial conditions $x_i^n(0) = x_i^{\text{in}}$ and $m_i^n(0) = m_i^{\text{in}}$. The results obtained above ensure that the sequences are well defined and that for all $n \in \mathbb{N}$, $(x^n, m^n) \in C([0, T]; (\mathbb{R}^d)^N \times \mathbb{R}_+^N)$. We begin by showing that x^n and m^n are bounded in L^∞ norm independently of n . It holds: $|m_i^n(t)| \leq |m_i^{\text{in}}| + \bar{S} \int_0^t |m_i^n(\tau)| d\tau$. From Gronwall's lemma, for all $t \in [0, T]$, $|m_i^n(t)| \leq m_i^{\text{in}} e^{\bar{S}t} \leq M_T$ where $M_T := \max_{i \in \{1, \dots, N\}} m_i^{\text{in}} e^{\bar{S}T}$.

Similarly, notice that for all $z \in \mathbb{R}^d$, $\|\phi(z)\| \leq \Phi_0 + L_\phi \|z\|$, where $\Phi_0 = \phi(0)$. Then $\|x_i^n(t)\| \leq \|x_i^{\text{in}}\| + \frac{M_T}{M} \int_0^t (\Phi_0 + 2L_\phi \max_{i \in \{1, \dots, N\}} \|x_i^n(\tau)\|) d\tau$. Thus

$$\max_{i \in \{1, \dots, N\}} \|x_i^n(t)\| \leq \max_{i \in \{1, \dots, N\}} \|x_i^{\text{in}}\| + \frac{M_T}{M} (\Phi_0 t + 2L_\phi \int_0^t \max_{i \in \{1, \dots, N\}} \|x_i^n(\tau)\| d\tau)$$

and from Gronwall's lemma, for all $t \in [0, T]$,

$$\max_{i \in \{1, \dots, N\}} \|x_i^n(t)\| \leq X_T := \left[\max_{i \in \{1, \dots, N\}} \|x_i^{\text{in}}\| + \frac{M_T}{M} \Phi_0 T \right] e^{2L_\phi \frac{M_T}{M} T}.$$

We prove that $(x^n)_{n \in \mathbb{N}}$ and $(m^n)_{n \in \mathbb{N}}$ are Cauchy sequences. For all $n \in \mathbb{N}$,

$$\begin{aligned}
&\|x_i^{n+1} - x_i^n\| \\
&= \left\| \int_0^t \frac{1}{M} \sum_{j=1}^N m_j^n \phi(x_j^{n+1} - x_i^{n+1}) d\tau - \int_0^t \frac{1}{M} \sum_{j=1}^N m_j^{n-1} \phi(x_j^n - x_i^n) d\tau \right\|
\end{aligned}$$

$$\begin{aligned} &\leq \frac{1}{M}(\Phi_0 + 2L_\phi X_T) \int_0^t \sum_{j=1}^N |m_j^n - m_j^{n-1}| d\tau \\ &\quad + \frac{M_T L_\phi}{M} \int_0^t \sum_{j=1}^N (\|x_j^{n+1} - x_j^n\| + \|x_i^{n+1} - x_i^n\|) d\tau. \end{aligned}$$

Thus

$$\begin{aligned} \sum_i \|x_i^{n+1} - x_i^n\| &\leq \frac{N}{M}(\Phi_0 + 2L_\phi X_T) \int_0^t \sum_i |m_i^n - m_i^{n-1}| d\tau \\ &\quad + 2N \frac{M_T L_\phi}{M} \int_0^t \sum_i \|x_i^{n+1} - x_i^n\| d\tau. \end{aligned}$$

A similar computation, for m gives

$$\begin{aligned} |m_i^{n+1} - m_i^n| &\leq \int_0^t |m_i^{n+1} - m_i^n| \frac{1}{M^q} \sum_{j_1 \dots j_q} m_{j_1}^{n+1} \dots m_{j_q}^{n+1} S(x_i^n \dots x_{j_q}^n) d\tau \\ &\quad + \int_0^t m_i^n \frac{1}{M^q} \sum_{j_1 \dots j_q} |m_{j_1}^{n+1} - m_{j_1}^n| m_{j_2}^{n+1} \dots m_{j_q}^{n+1} S(x_i^n \dots x_{j_q}^n) d\tau \\ &\quad + \dots + \int_0^t m_i^n \frac{1}{M^q} \sum_{j_1 \dots j_q} m_{j_1}^n \dots m_{j_{q-1}}^n |m_{j_q}^{n+1} - m_{j_q}^n| S(x_i^n \dots x_{j_q}^n) d\tau \\ &\quad + \int_0^t m_i^n \frac{1}{M^q} \sum_{j_1 \dots j_q} m_{j_1}^n \dots m_{j_q}^n |S(x_i^n \dots x_{j_q}^n) - S(x_i^{n-1} \dots x_{j_q}^{n-1})| d\tau. \end{aligned}$$

From (9), it holds $\int_0^t m_i^n \frac{1}{M^q} \sum_{j_1 \dots j_q} m_{j_1}^n \dots m_{j_q}^n |S(x_i^n \dots x_{j_q}^n) - S(x_i^{n-1} \dots x_{j_q}^{n-1})| d\tau \leq \int_0^t m_i^n L_S \|x_i^n - x_i^{n-1}\| d\tau + q \int_0^t \frac{1}{M} \sum_{j=1}^N m_j^n L_S \|x_j^n - x_j^{n-1}\| d\tau$.

Thus, $|m_i^{n+1} - m_i^n| \leq \bar{S} \int_0^t |m_i^{n+1} - m_i^n| d\tau + q \bar{S} \frac{M_T}{M} \int_0^t \sum_j |m_j^{n+1} - m_j^n| d\tau + M_T \int_0^t L_S \|x_i^n - x_i^{n-1}\| d\tau + q L_S \frac{M_T}{M} \int_0^t \sum_j \|x_j^n - x_j^{n-1}\| d\tau$. Summing the terms, it holds

$$\begin{aligned} \sum_{i=1}^N |m_i^{n+1} - m_i^n| &\leq \bar{S}(1 + qN \frac{M_T}{M}) \int_0^t \sum_{j=1}^N |m_j^{n+1} - m_j^n| d\tau \\ &\quad + M_T L_S (1 + q \frac{N}{M}) \int_0^t \sum_{i=1}^N \|x_i^n - x_i^{n-1}\| d\tau. \end{aligned}$$

Summarizing, we have

$$\begin{aligned} \sum_{i=1}^N \|x_i^{n+1} - x_i^n\| &\leq C_1 \int_0^t \sum_{i=1}^N \|x_i^{n+1} - x_i^n\| d\tau + C_2 \int_0^t \sum_{i=1}^N |m_i^n - m_i^{n-1}| d\tau; \\ \sum_{i=1}^N |m_i^{n+1} - m_i^n| &\leq C_3 \int_0^t \sum_{i=1}^N |m_i^{n+1} - m_i^n| d\tau + C_4 \int_0^t \sum_{i=1}^N \|x_i^n - x_i^{n-1}\| d\tau. \end{aligned}$$

where $C_1 = 2N \frac{M_T L_\phi}{M}$, $C_2 = \frac{N}{M}(\Phi_0 + 2L_\phi X_T)$, $C_3 = \bar{S}(1 + qN \frac{M_T}{M})$ and $C_4 = M_T L_S (1 + q \frac{N}{M})$. Let $u_n := \sum_{i=1}^N \|x_i^{n+1} - x_i^n\| + \sum_{i=1}^N |m_i^{n+1} - m_i^n|$ for all $n \in \mathbb{N}$. Then $u_n(t) \leq A_T \int_0^t u_n(\tau) d\tau + A_T \int_0^t u_{n-1}(\tau) d\tau$ where $A_T := \max(C_1, C_2, C_3, C_4)$. From Gronwall's lemma, for all $t \in [0, T]$, $u_n(t) \leq A_T e^{A_T T} \int_0^t u_{n-1}(\tau) d\tau$ which,

by recursion, implies $u_n(t) \leq \frac{(A_T e^{A_T T})^n}{n!} \sup_{[0,T]} u_0$. This is the general term of a convergent series. Thus, for all $n, p \in \mathbb{N}$,

$$\sum_{i=1}^N \|x_i^{n+p} - x_i^n\| \leq \sum_{k=n}^{n+p-1} \sum_{i=1}^N \|x_i^{k+1} - x_i^k\| \leq \sum_{k=n}^{n+p-1} u_k \xrightarrow[n, p \rightarrow +\infty]{} 0.$$

This proves that $(x^n)_{n \in \mathbb{N}}$ is a Cauchy sequence in the Banach space $C([0, T], (\mathbb{R}^d)^N)$ for the norm $x \mapsto \sup_{t \in [0, T]} \sum_{i=1}^N \|x_i^n(t)\|$. Similarly, $(m^n)_{n \in \mathbb{N}}$ is a Cauchy sequence in $C([0, T], \mathbb{R}_+^N)$ for the norm $m \mapsto \sup_{t \in [0, T]} \sum_{i=1}^N |m_i^n(t)|$. One can easily show that their limits (x, m) satisfy the system of ODEs (3). Furthermore, since the bounds X_T and M_T do not depend on n , it holds $\|x_i(t)\| \leq X_T$ and $|m_i(t)| \leq M_T$ for all $t \in [0, T]$ and every $i \in \{1, \dots, N\}$. This concludes the proof of existence.

Let us now deal with uniqueness. Suppose that (x, m) and (p, m) are two couples of solutions to the Cauchy problem (3) with the same initial conditions $(x^{\text{in}}, m^{\text{in}})$. As previously,

$$\begin{aligned} & \sum_{i=1}^N \|x_i(t) - y_i(t)\| + \sum_{i=1}^N |m_i(t) - p_i(t)| \\ & \leq A_T \int_0^t \left(\sum_{i=1}^N \|x_i(\tau) - y_i(\tau)\| + \sum_{i=1}^N |m_i(\tau) - p_i(\tau)| \right) d\tau. \end{aligned}$$

By Gronwall's lemma, $\sum_{i=1}^N \|x_i(t) - y_i(t)\| + \sum_{i=1}^N |m_i(t) - p_i(t)| = 0$, which concludes uniqueness. \square

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