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# Research article

# Analysis and control of Aedes Aegypti mosquitoes using sterile-insect techniques with Wolbachia

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**Abstract:** Combining Sterile and Incompatible Insect techniques can significantly reduce mosquito populations and prevent the transmission of diseases between insects and humans. This paper describes impulsive differential equations for the control of a mosquito with Wolbachia. Several interesting conditions are created when sterile male mosquitoes are released impulsively, ensuring both open- and closed-loop control. To determine the wild mosquito population size in real-time, we propose an open-loop control system, which uses impulsive and constant releases of sterile mosquitoes. A closed-loop control scheme is also being investigated, which specifies the release of sterile mosquitoes according to the size of the wild mosquito population. To eliminate or reduce a mosquito population below a certain threshold, the Sterile insect technique involves mass releases of sterile insects. Numerical simulations verify the theoretical results.

**Keywords:** Aedes Aegypti mosquitoes; feedback control; stability; sterile insect technique; Wolbachia

# 1. Introduction

Dengue hemorrhagic fever is emerging as one of the most serious vector-borne diseases worldwide. The *Aedes Aegypti* mosquito is a major vector for the transmission of dengue and other arboviral infections from an infected individual to a susceptible individual. In recent decades, people have been paying more attention to the prevalence, mortality, and massive economic impact of diseases like malaria, chikungunya, dengue, etc, due to their morbidity burdens; see [1–4]. For a long time, there is no available vaccines for the mosquito-borne diseases, even though the researchers is trying to find an effective vaccine. Multerer et al. [5] discussed the dynamical behaviors of *Aedes Aegypti* mosquito

in terms of partial differential equations and also described an Allee effect to capture extinction events and optimal control analysis to identify the release strategy that eliminates the mosquitoes. Zheng et al. [6] investigated the existence and stability results for the mosquito and human populations model in which contains dengue serotype circulates, the delay terms capture the respective intrinsic and extrinsic incubation periods, as well as the maturation delay between mating and emergence of adult mosquitoes [7,8].

There are mainly two biological control techniques for mosquito populations: Incompatible Insect Techniques (IIT) and Sterile Insect Techniques (SIT). The IIT contains an intracellular bacterium, Wolbachia, commonly found in insects including mosquitoes. The technique of releasing mosquitoes carrying Wolbachia to replace the wild mosquito population is a type of population replacement strategy. If the females mosquitoes infected Wolbachia, then its produced offsprings will also be infected. If the females are uninfected, mate with male with infected Wolbachia, then the offsprings will be dead [9]. Ormaetxe et al. [10] reported the availability of different Wolbachia strains, which are successfully implanted to Aedes Aegypti mosquitoes. The important thing of such techniques is stopping the spread of mosquitoes and reducing the mosquitoes life span. The authors in [11], discussed the augmentation control strategies of Aedes Aegypti mosquitoes with infected Wolbachia. Li et al. [12] investigated the spread of Wolbachia in sex-structured mosquitoes model with birth pulse and studied the sufficient condition for stability of total replacement periodic solution. Zheng et al. [13] studied the qualitative properties of Aedes Aegypti mosquitoes with infected Wolbachia and maturation delay terms. Li et al. [14] introduced the stage-structured mosquitoes model with Wolbachia infection and key factors like, including male killing effect, cytoplasmic incompatibility (CI), fecundity cost due to fitness effect, different mortality rates for infected individuals and maternal transmission are discussed. The authors in [15] discussed the dynamical behaviours the Wolbachia infected mosquito model with delays and effective control techniques.

In the SIT system, natural mosquito reproduction is disrupted and modified by physical, chemical, and radical methods into male mosquitoes that are sterile. These sterile mosquitoes are then released into the environment to mate with wild mosquitoes that are present in the environment. Repeating the process of sterile mosquitoes releases may control or wipe out the wild mosquitoes population. The authors [16, 17] reported the mathematical modelling of SIT to Aedes albopictus, which transmits the Chikungunya diseases and discussed pulsed periodic releases, which is useful to prevent, eliminate, reduce the diseases. Almeida et al. [18] discussed the control techniques, SIT and IIT to the mosquitoes model and optimizing the dissemination protocol for each of these strategies, in order to get as close as possible to these objectives. Nowadays, some researchers focused on the dynamical results of SIT into mosquitoes models; see [19–22].

In the most recent literature, continuous dynamical models and continuous mosquito releases were discussed. Instantaneous releases are a key feature of sterile mosquito releases, and they should be repeated numerous times to bring the mosquito population under control. Generally, continuous dynamical models have disadvantages in defining such control analysis with the impulsiveness nature of releases. Impulsive sterile releases can be applied to make up for a lack of such capacity. Huang et al. [23] reported the dynamical behavior of the interaction of sterile and wild mosquitoes and also discussed the impact of periodic impulsive sterile mosquitoes releases. Zhang et al. [24] described the stroboscopic maps which used to define the numbers of mosquitoes with uninfected and infected *Wolbachia* immediately after each birth pulse at the discrete times. Li et al. [25] studied the dynamical terms and the stroboscopic maps when the term of the stroboscopic maps when the stroboscopic

ical behaviors of mosquitoes and *Wolbachia* model with impulsive general birth and death rate functions and the sufficient conditions of mosquito extinction are discussed. Bliman et al. [26] reported the open and closed-loop control strategies for releasing impulsive sterile male insect techniques in the wild mosquito population, and they studied the open-loop control technique. In cases where the size of the wild mosquito population cannot be determined in real-time, cyclical impulsive releases of sterile males with constant release sizes are used. A closed-loop control strategy is proposed if periodic assessments of wild population size (synchronized with releases or sparser) are available in real-time [27]. The authors in [28,29] described the modelling of sterile and incompatible insect techniques for the mosquitoes model and suppression of the population. Mosquitoes epidemic models described through the impulsive differential equations have received much attention from the researchers (see [30–32]).

Herein, we provide new models of *Aedes Aegypti* mosquitos with infected *Wolbachia* and impulsive discharges of sterile mosquitos, inspired by earlier studies. We investigate periodic impulsive sterile emissions and formulate parameters for effective eradication based on the magnitude and frequency of the releases. We use a combination of SIT and IIT approaches to produce high sterile male mosquitoes in these models. Periodic releases are calculated so as to maintain the mosquito-free equilibrium. In this environment, open-loop techniques can be designed that ensure mosquito eradication in a finite amount of time without estimating the size of the wild mosquito population. By using the open-loop control technique, sterile mosquitoes are released every  $\tau$  days in order to eliminate wild mosquitoes. We can also create closed-loop control qualities to determine the size of the wild population.

In this paper, we develop a *Wolbachia Aedes Aegypti* Mosquito model and examine the findings of local stability in Section 2. The open and closed loop control features of the underlying model are studied in Section 3. In Section 4, the numerical results are discussed in order to confirm the theoretical results. Section 5 ends with a conclusion.

### 2. Modeling of Aedes Aegypti mosquitoes with Wolbachia

Assume that  $M_u(t)$ ,  $M_w(t)$  and  $F_u(t)$ ,  $F_w(t)$  denote the population density of male and female Aedes Aegypti mosquitoes with uninfected, infected Wolbachia respectively. Consider a Aedes Aegypti Mosquitoes with Wolbachia model of the form

$$\dot{M}_{u} = r\rho_{u}F_{u}\frac{M_{u}}{M_{u} + \gamma_{w}M_{w}}e^{-\beta(M_{u} + F_{u} + M_{w} + F_{w})} - \mu_{M_{u}}M_{u},$$
  

$$\dot{F}_{u} = (1 - r)\rho_{u}F_{u}\frac{M_{u}}{M_{u} + \gamma_{w}M_{w}}e^{-\beta(M_{u} + F_{u} + M_{w} + F_{w})} - \mu_{F_{u}}F_{u},$$
  

$$\dot{M}_{w} = r\rho_{w}F_{w}e^{-\beta(M_{u} + F_{u} + M_{w} + F_{w})} - \mu_{M_{w}}M_{w},$$
  

$$\dot{F}_{w} = (1 - r)\rho_{w}F_{w}e^{-\beta(M_{u} + F_{u} + M_{w} + F_{w})} - \mu_{F_{w}}F_{w}.$$
(2.1)

This model assumes that all females mate equally. The parameter  $\beta$  includes direct or indirect effects of competition at different stages (larvae, pupae, adults). Let  $r \in (0, 1)$  define the primary sex ratio in offspring, and  $\rho_u, \rho_w$  represent the mean number of eggs produced by a single female (uninfected and infected *Wolbachia*) who can deposit on average per day.  $\gamma_w$  measures the competition between male mosquitoes with uninfected and infected *Wolbachia* for the female mates.  $\mu_{M_u}, \mu_{F_u}, \mu_{M_w}, \mu_{F_w}$  are mean death rates of adult mosquitoes with uninfected, infected *Wolbachia* respectively. The basic offspring numbers are described as  $N_{M_u} = \frac{r\rho_u}{\mu_{M_u}}$ ,  $N_{F_u} = \frac{(1-r)\rho_u}{\mu_{F_u}}$ ,  $N_{M_w} = \frac{r\rho_w}{\mu_{M_w}}$ , and  $N_{F_w} = \frac{(1-r)\rho_w}{\mu_{F_w}}$ . Generally, the male mortality is larger than female, so let us take  $\mu_{M_u} \ge \mu_{F_u}$ ,  $\mu_{M_w} \ge \mu_{F_w}$ .

**Table 1.** The maternal transmission and CI reproductive phenotype induced by *Wolbachia*.

Adults	Uninfected Male	Wolbachia infected Male
Uninfected Female	Uninfected	Inviable eggs
Wolbachia infected Female	Wolbachia Infected	Wolbachia Infected

Now, we discuss the local asymptotic stability of (2.1). The model (2.1) has four steady states:

- (i) Mosquito free equilibrium point  $\mathcal{E}_0 = (0, 0, 0, 0)$ .
- (i) If  $N_{F_u} > 1$ , Wolbachia free equilibrium point  $\mathcal{E}_0^{-1}$  (0, 0, 0). (ii) If  $N_{F_u} > 1$ , Wolbachia free equilibrium point  $\mathcal{E}_1 = (M_u^*, F_u^*, 0, 0)$ , where  $M_u^* = \frac{N_{M_u}}{N_{M_u} + N_{F_u}} \frac{1}{\beta} ln N_{F_u}$ ,  $F_u^* = \frac{N_{F_u}}{N_{M_u} + N_{F_u}} \frac{1}{\beta} ln N_{F_u}$  and  $M_u^* + F_u^* = \frac{1}{\beta} ln N_{F_u}$ . (iii) If  $N_{F_w} > 1$ , all Wolbachia infected equilibrium point  $\mathcal{E}_2 = (0, 0, M_w^*, F_w^*)$  where  $M_w^* = \frac{N_{M_w} + N_{F_w}}{N_{M_w} + N_{F_w}} \frac{1}{\beta} ln N_{F_w}$  and  $M_w^* + F_w^* = \frac{1}{\beta} ln N_{F_w}$ . (iv) If  $N_{F_u}, N_{F_w} > 1$ , the interior equilibrium point  $\mathcal{E}_3 = (M_u^*, F_u^*, M_w^*, F_w^*)$ , where

$$M_{u}^{*} = \frac{\gamma_{w}}{\beta Q_{c}} N_{M_{u}} N_{M_{w}} N_{F_{w}} ln N_{F_{w}},$$

$$F_{u}^{*} = \frac{\gamma_{w}}{\beta Q_{c}} N_{F_{u}} N_{M_{w}} N_{F_{w}} ln N_{F_{w}},$$

$$M_{w}^{*} = \frac{1}{\beta Q_{c}} N_{M_{u}} N_{M_{w}} (N_{F_{u}} - N_{F_{w}}) ln N_{F_{w}},$$

$$F_{w}^{*} = \frac{1}{\beta Q_{c}} N_{M_{u}} N_{F_{w}} (N_{F_{u}} - N_{F_{w}}) ln N_{F_{w}},$$
and
$$Q_{c} = N_{M_{u}} (N_{F_{u}} - N_{F_{w}}) (N_{M_{w}} + N_{F_{w}}) + \gamma_{w} N_{M_{w}} N_{F_{w}} (N_{M_{u}} + N_{F_{u}}).$$

The Jacobian matrix of the model (2.1) is described by

$$J = \begin{pmatrix} a_1 & a_2 & a_3 & a_4 \\ a_5 & a_6 & a_7 & a_8 \\ a_9 & a_9 & a_{10} & a_{11} \\ a_{12} & a_{12} & a_{12} & a_{13} \end{pmatrix}$$

where

$$\begin{aligned} a_{1} &= r\rho_{u}b_{2}c\left\{-\beta M_{u}^{*}+b_{6}\right\}-\mu_{M_{u}}, a_{2} = r\rho_{u}b_{1}(1-\beta F_{u}^{*})c, \\ a_{3} &= -r\rho_{u}F_{u}^{*}b_{1}c\frac{\gamma_{w}+\beta(M_{u}^{*}+\gamma_{w}M_{w}^{*})}{M_{u}^{*}+\gamma_{w}M_{w}^{*}}, \\ a_{4} &= -r\beta\rho_{u}F_{u}^{*}b_{1}c, a_{5} = (1-r)\rho_{u}b_{2}c(b_{6}-\beta M_{u}^{*}), \\ a_{6} &= (1-r)\rho_{u}b_{1}c(1-\beta F_{u}^{*})-\mu_{F_{u}}, a_{7} = b_{3}(\gamma_{w}+\beta(M_{u}^{*}+\gamma_{w}M_{w}^{*}))\frac{1}{M_{u}^{*}+\gamma_{w}M_{w}^{*}}, \\ a_{8} &= b_{3}\beta, a_{9} = -r\beta\rho_{w}F_{w}^{*}c, a_{10} = a_{9}-\mu_{M_{w}}, \end{aligned}$$

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$$\begin{aligned} a_{11} &= r\rho_w c(1 - \beta F_w^*), a_{12} = -(1 - r)\beta\rho_w F_w^* c, \\ a_{13} &= (1 - r)\rho_w c(1 - \beta F_w^*) - \mu_{F_w}, b_1 = \frac{M_u^*}{M_u^* + \gamma_w M_w^*}, b_2 = \frac{F_u^*}{M_u^* + \gamma_w M_w^*}, \\ b_3 &= -(1 - r)\rho_u M_u^* b_2 c, b_4 = -r\beta\rho_w F_w^* c, b_5 = -(1 - r)\beta\rho_w F_w^* c, \\ b_6 &= \frac{\gamma_w M_w^*}{M_u^* + \gamma_w M_w^*}, c = \frac{1}{N_{F_w}}. \end{aligned}$$

The Jacobian matrix at  $\mathcal{E}_0$  is

$$J(\mathcal{E}_0) = \begin{pmatrix} -\mu_{M_u} & 0 & 0 & 0 \\ 0 & -\mu_{F_u} & 0 & 0 \\ 0 & 0 & -\mu_{M_w} & r\rho_w \\ 0 & 0 & 0 & (1-r)\rho_w - \mu_{F_w} \end{pmatrix}.$$

Then, the trivial equilibrium point  $\mathcal{E}_0$  is locally stable if  $N_{F_w} < 1$ .

The characteristic equation at *Wolbachia* free equilibrium point  $\mathcal{E}_1$  is defined as

$$(\lambda + \mu_{M_w})(\lambda + \mu_{F_w} + (1 - r)\rho_w e^{-\beta(M_u^* + F_u^*)})(\lambda^2 + p_1\lambda + p_2) = 0,$$
  
$$\lambda_1 = -\mu_{M_w}, \lambda_2 = -(\mu_{F_w} + (1 - r)\rho_w e^{-\beta(M_u^* + F_u^*)}) \text{ and } (\lambda^2 + p_1\lambda + p_2) = 0,$$

where

$$p_{1} = \mu_{F_{u}} + \mu_{M_{u}} + \rho_{u}e^{-\beta(M_{u}^{*}+F_{u}^{*})}(r\beta F_{u}^{*} - (1-r)(1-\beta F_{u}^{*})),$$
  
$$p_{2} = \mu_{M_{u}}\mu_{F_{u}} + \rho_{u}e^{-\beta(M_{u}^{*}+F_{u}^{*})}(r\beta F_{u}^{*}\mu_{F_{u}} - \mu_{M_{u}}(1-r)(1-\beta F_{u}^{*})).$$

 $p_1 > 0$ ,  $p_2 > 0$  are necessary conditions for all roots in the characteristic equation  $\lambda^2 + p_1\lambda + p_2 = 0$  to have negative real parts.

**Lemma 1.** Suppose that  $N_{F_u} > 1$ . Then Wolbachia free equilibrium point  $\mathcal{E}_1$  is locally asymptotically stable if  $p_1 > 0$ ,  $p_2 > 0$ .

The characteristic equation at all Wolbachia infected equilibrium point  $\mathcal{E}_2$  is defined as

$$(\lambda + \mu_{M_u})(\lambda + \mu_{F_u})(\lambda^2 + r_1\lambda + r_2) = 0,$$
  
$$\lambda_1 = -\mu_{M_u}, \lambda_2 = -\mu_{F_u} \text{ and } (\lambda^2 + r_1\lambda + r_2) = 0,$$

where

$$r_{1} = \mu_{F_{w}} + \mu_{M_{w}} + \rho_{w}e^{-\beta(M_{w}^{*}+F_{w}^{*})}(r\beta F_{w}^{*} - (1-r)(1-\beta F_{w}^{*})),$$
  

$$r_{2} = \mu_{M_{w}}\mu_{F_{w}} + \rho_{w}e^{-\beta(M_{w}^{*}+F_{w}^{*})}(r\beta F_{w}^{*}\mu_{F_{w}} - \mu_{M_{w}}(1-r)(1-\beta F_{w}^{*})).$$

 $r_1 > 0, r_2 > 0$  are necessary conditions for all roots in the characteristic equation  $\lambda^2 + r_1\lambda + r_2 = 0$  to have negative real parts.

**Lemma 2.** Suppose that  $N_{F_w} > 1$ , then all Wolbachia infected equilibrium point  $\mathcal{E}_2$  is locally asymptotically stable if  $r_1 > 0, r_2 > 0$ .

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The characteristic equation at interior equilibrium point  $\mathcal{E}_3$  is defined as

$$\lambda^{4} + s_{1}\lambda^{3} + s_{2}\lambda^{2} + s_{3}\lambda + s_{4} = 0,$$

where

$$\begin{split} s_1 &= -(1 + a_{10}a_{13}), \\ s_2 &= a_2a_5 + (a_1 + a_6)(a_{10} + a_{13}) + a_{12}(a_4 - a_8 - a_{11}) - a_9(a_3 + a_7) + a_1a_6 + a_{10}a_{13}, \\ s_3 &= -a_2a_5(a_{10} + a_{13}) + a_2(a_7a_9 + a_8a_{12}) + a_3(a_5(a_{12} - a_9) - a_{11}a_{12}) + a_9(a_4a_{12} + a_7(a_1 + a_{13})) - a_1a_6(a_{10} + a_{13}) - a_{10}a_{13}(a_1 + a_6) + a_{12}(a_{11}(a_1 + a_6 - a_7)) \\ &+ a_8(a_1 - a_9 + a_{10}) + a_3a_9(a_6 + a_{13}) - a_4a_{12}(a_6 + a_{10}), \\ s_4 &= a_6a_{12}(a_3a_{11} - a_4a_9) + (a_1a_6 + a_2a_5)(a_{10}a_{13} - a_{11}a_{12}) + (a_4a_5 + a_1a_8)(a_{12}(a_9 - a_{10})) \\ &+ (a_9a_{13} - a_{11}a_{12})(a_3a_5 - a_7(a_1 + a_2)) + a_2a_8a_{12}(a_9 - a_{10}) + a_6(a_4a_{10}a_{12} - a_3a_{9}a_{13}). \end{split}$$

According to the Routh-Hurwitz criterion, all roots  $\lambda_{1,2,3,4}$  of the characteristic equation  $\lambda^4 + s_1\lambda^3 + s_2\lambda^2 + s_3\lambda + s_4 = 0$  must be negative real parts. The conditions are

$$s_1 > 0, s_3 > 0, s_4 > 0, s_1 s_2 s_3 > s_3^2 + s_1^2 s_4$$

We arrive at the following Lemma.

**Lemma 3.** The interior steady state  $\mathcal{E}_3$  is locally asymptotically stable if  $s_1 > 0$ ,  $s_3 > 0$ ,  $s_4 > 0$ ,  $s_1s_2s_3 > s_3^2 + s_1^2s_4$ .

## 2.1. Continuous releases of sterile male mosquitoes

Here, we incorporate continuous releases sterile male mosquitoes into model (2.1) and assume  $\gamma_w = 1$ , the revised model takes the form

$$\begin{split} \dot{M}_{u} &= r\rho_{u}F_{u}\frac{M_{u}}{M_{u}+M_{w}+\gamma_{s}M_{s}}e^{-\beta(M_{u}+F_{u}+M_{w}+F_{w})} - \mu_{M_{u}}M_{u}, \\ \dot{F}_{u} &= (1-r)\rho_{u}F_{u}\frac{M_{u}}{M_{u}+M_{w}+\gamma_{s}M_{s}}e^{-\beta(M_{u}+F_{u}+M_{w}+F_{w})} - \mu_{F_{u}}F_{u}, \\ \dot{M}_{w} &= r\rho_{w}F_{w}\frac{M_{u}+M_{w}}{M_{u}+M_{w}+\gamma_{s}M_{s}}e^{-\beta(M_{u}+F_{u}+M_{w}+F_{w})} - \mu_{M_{w}}M_{w}, \\ \dot{F}_{w} &= (1-r)\rho_{w}F_{w}\frac{M_{u}+M_{w}}{M_{u}+M_{w}+\gamma_{s}M_{s}}e^{-\beta(M_{u}+F_{u}+M_{w}+F_{w})} - \mu_{F_{w}}F_{w}, \\ \dot{M}_{s} &= \Lambda - \mu_{M_{s}}M_{s}. \end{split}$$

$$(2.2)$$

The sterile male population density at time *t* is  $M_s(t)$ . At the beginning of each release period,  $\Lambda$  is the number of sterile male mosquitoes released. The mean death rate of sterile mosquitoes is  $\mu_{M_s}$ .  $\gamma_s$  be a relative reproductive efficiency and the value is smaller than one. The recruitment terms in (2.2) only include the successful mating of uninfected females  $F_u$  and *Wolbachia* infected females  $F_w$ , i.e., those leading to viable offspring, that are detected with probabilities  $\frac{M_u}{M_u+M_w+\gamma_s M_s}$  and  $\frac{M_u+M_w}{M_u+M_w+\gamma_s M_s}$ , respectively. From (2.2), the equilibrium point  $M_s^* = \frac{\Lambda}{\mu_{M_s}}$ . Moreover,  $\mu_{M_s} \ge \mu_{M_u}$  and  $\mu_{M_s} \ge \mu_{M_w}$ .

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$$\Lambda^{crit} = \frac{\mu_{M_s}(N_{F_w}e^{-\beta\left(\frac{N_{M_u}}{N_{M_u}+N_{F_u}}+\frac{N_{F_u}}{N_{M_u}+N_{F_u}}+\frac{N_{M_w}}{N_{M_w}+N_{F_w}}+\frac{N_{F_w}}{N_{M_w}+N_{F_w}}\right) - 1)}{\gamma} \left(\frac{N_{M_u}}{N_{M_u}+N_{F_u}}+\frac{N_{M_w}}{N_{M_w}+N_{F_w}}\right)$$

**Proof:** From the model (2.2)

$$\begin{aligned} \frac{M_u^*}{M_u^* + M_w^* + \gamma_s M_s^*} e^{-\beta(M_u^* + F_u^* + M_w^* + F_w^*)} &= \frac{1}{N_{F_u}}, \\ \frac{M_u^* + M_w^*}{M_u^* + M_w^* + \gamma_s M_s^*} e^{-\beta(M_u^* + F_u^* + M_w^* + F_w^*)} &= \frac{1}{N_{F_w}}, \\ M_u^* &= \frac{N_{M_u}}{N_{M_u} + N_{F_u}}, \quad F_u^* &= \frac{N_{F_u}}{N_{M_u} + N_{F_u}}, \\ M_w^* &= \frac{N_{M_w}}{N_{M_w} + N_{F_w}}, \quad F_w^* &= \frac{N_{F_w}}{N_{M_w} + N_{F_w}}, \end{aligned}$$

and

$$(1-r)\rho_{w}\frac{M_{u}^{*}+M_{w}^{*}}{M_{u}^{*}+M_{w}^{*}+\gamma_{s}M_{s}^{*}}e^{-\beta(M_{u}^{*}+F_{u}^{*}+M_{w}^{*}+F_{w}^{*})} = \mu_{F_{w}},$$

$$N_{F_{w}}e^{-\beta(M_{u}^{*}+F_{u}^{*}+M_{w}^{*}+F_{w}^{*})} = 1 + \frac{\gamma_{s}M_{s}^{*}}{M_{u}^{*}+M_{w}^{*}},$$

$$\Lambda^{crit} = \frac{\mu_{M_{s}}\left(N_{F_{w}}e^{-\beta(M_{u}^{*}+F_{u}^{*}+M_{w}^{*}+F_{w}^{*})} - 1\right)}{\gamma_{s}}(M_{u}^{*}+M_{w}^{*}).$$

If  $N_{F_w} > 1$ , there exists  $\Lambda^{crit} > 0$  such that (2.2) have one non negative steady state at  $\Lambda = \Lambda^{crit}$  and no non negative steady state at  $\Lambda > \Lambda^{crit}$ . The asymptotic stability results of the model (2.2) are similar to those in the previous subsection, so it is omitted.

## 2.2. Impulsive releases of sterile male mosquitoes

Now, we incorporate periodic impulsive sterile male mosquitoes into model (2.2), the model be-

$$\begin{split} \dot{M}_{u} &= r\rho_{u}F_{u}\frac{M_{u}}{M_{u}+M_{w}+\gamma_{s}M_{s}}e^{-\beta(M_{u}+F_{u}+M_{w}+F_{w})} - \mu_{M_{u}}M_{u}, \\ \dot{F}_{u} &= (1-r)\rho_{u}F_{u}\frac{M_{u}}{M_{u}+M_{w}+\gamma_{s}M_{s}}e^{-\beta(M_{u}+F_{u}+M_{w}+F_{w})} - \mu_{F_{u}}F_{u}, \\ \dot{M}_{w} &= r\rho_{w}F_{w}\frac{M_{u}+M_{w}}{M_{u}+M_{w}+\gamma_{s}M_{s}}e^{-\beta(M_{u}+F_{u}+M_{w}+F_{w})} - \mu_{M_{w}}M_{w}, \\ \dot{F}_{w} &= (1-r)\rho_{w}F_{w}\frac{M_{u}+M_{w}}{M_{u}+M_{w}+\gamma_{s}M_{s}}e^{-\beta(M_{u}+F_{u}+M_{w}+F_{w})} - \mu_{F_{w}}F_{w}, \\ \dot{M}_{s} &= -\mu_{M_{s}}M_{s}, \quad \text{for any} \quad t \in \bigcup_{n \in \mathbb{N}} \left(n\tau, (n+1)\tau\right), \\ M_{s}(n\tau^{+}) &= \tau\Lambda_{n} + M_{s}(n\tau^{-}), \quad n = 1, 2, 3, \ldots. \end{split}$$

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Make  $\Lambda_n$  a constant and drop consequently the subindex *n*.  $M_s(n\tau^{\pm})$  represents the right and left limits of  $M_s(t)$  at  $t = n\tau$ . In other terms, model (2.3) evolves according first four equations of (2.3) on the union of open intervals  $(n\tau, (n + 1)\tau)$ . While  $M_s$  undergoes jumps at each  $n\tau$ , accounting for the released sterile male mosquitoes. For such release schedule, when  $t \to \infty$ , the function  $M_s$  converges towards the following periodic solution

$$M_{s}^{per}(t) = \frac{\tau \Lambda}{1 - e^{-\mu_{M_{s}}\tau}} e^{-\mu_{M_{s}}(t - n\tau^{+})}.$$

We define the periodic system

$$\begin{split} \dot{M}_{u} &= r\rho_{u}F_{u}\frac{M_{u}}{M_{u}+M_{w}+\gamma_{s}M_{s}^{per}}e^{-\beta(M_{u}+F_{u}+M_{w}+F_{w})} - \mu_{M_{u}}M_{u}, \\ \dot{F}_{u} &= (1-r)\rho_{u}F_{u}\frac{M_{u}}{M_{u}+M_{w}+\gamma_{s}M_{s}^{per}}e^{-\beta(M_{u}+F_{u}+M_{w}+F_{w})} - \mu_{F_{u}}F_{u}, \\ \dot{M}_{w} &= r\rho_{w}F_{w}\frac{M_{u}+M_{w}}{M_{u}+M_{w}+\gamma_{s}M_{s}^{per}}e^{-\beta(M_{u}+F_{u}+M_{w}+F_{w})} - \mu_{M_{w}}M_{w}, \\ \dot{F}_{w} &= (1-r)\rho_{w}F_{w}\frac{M_{u}+M_{w}}{M_{u}+M_{w}+\gamma_{s}M_{s}^{per}}e^{-\beta(M_{u}+F_{u}+M_{w}+F_{w})} - \mu_{F_{w}}F_{w}. \end{split}$$
(2.4)

The model (2.3) has the same mosquito free equilibrium point  $\mathcal{E}_0$ . Now, we are going to study the conditions under which mosquitoes free steady state is asymptomatically stable. For the such study, we find the mean value of  $\frac{1}{M_r^{per}}$ ,

$$\left\langle \frac{1}{M_s^{per}} \right\rangle := \frac{1}{\tau} \int_0^\tau \frac{1}{M_s^{per}(t)} dt = \frac{(1 - e^{-\mu_{M_s}\tau})}{\tau^2 \Lambda} \int_0^\tau e^{\mu_{M_s}t} dt = \frac{2(\cosh(\mu_{M_s}\tau) - 1)}{\mu_{M_s}\tau^2 \Lambda}.$$
 (2.5)

#### 3. Stability analysis and main results

**Theorem 2.** Assume that

$$\Lambda \ge \Lambda_{per}^{crit} = \frac{2(\cosh(\mu_{M_s}\tau) - 1)}{e\beta\gamma_s\mu_{M_s}\tau^2} \min\{N_{M_u}, N_{F_u}, N_{M_w}, N_{F_w}\}, \quad \tau > 0,$$
(3.1)

Therefore, the solution of (2.4) converges globally exponentially to the steady-state  $\mathcal{E}_0$ .

**Proof:** From (2.4),

$$\dot{F}_{u} = \left( (1-r)\rho_{u} \frac{M_{u}}{M_{u} + M_{w} + \gamma_{s} M_{s}^{per}} e^{-\beta(M_{u} + F_{u} + M_{w} + F_{w})} - \mu_{F_{u}} \right) F_{u}.$$

For any  $F_u \ge 0$  and  $t \ge 0$  and use  $\alpha = \{xe^{-\beta x}; x \ge 0\} = \frac{1}{e\beta}$ 

$$\frac{M_u}{M_u + M_w + \gamma_s M_s^{per}} e^{-\beta(M_u + F_u + M_w + F_w)} \leq \frac{M_u}{M_u + M_w + \gamma_s M_s^{per}} e^{-\beta(M_u)} \leq \frac{\alpha_1}{\gamma M_s^{per}}.$$

Integrate from  $n\tau$  to t with  $n\tau < t$ , we get

$$F_u(t) \leq F_u(n\tau) e^{\int_{n\tau}^t \left( (1-r)\rho_u \frac{\alpha_1}{\gamma_s M_s^{per}} - \mu_{F_u} \right) ds}.$$

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Taking 
$$t = (n+1)\tau$$
,  $n \in \mathbb{N}$ ,  
 $F_u((n+1)\tau) \le e^{\left((1-r)\rho_u \frac{\alpha_1}{\gamma_s}\left\langle\frac{1}{M_s^{per}}\right\rangle - \mu_{F_u}\right)\tau}F_u(n\tau).$ 

Thus, the sequence  $\{F_u(n\tau)\}_{n\in\mathbb{N}}$  approaches to 0,

$$(1-r)\rho_{u}\frac{\alpha_{1}}{\gamma_{s}}\left\langle\frac{1}{M_{s}^{per}}\right\rangle < \mu_{F_{u}},$$
$$\left\langle\frac{1}{M_{s}^{per}}\right\rangle < e\beta\gamma_{s}\frac{1}{N_{F_{u}}}.$$

From the first equation of (2.4), similarly, we can prove  $\left\langle \frac{1}{M_s^{per}} \right\rangle < e\beta \gamma_s \frac{1}{N_{M_u}}$ . Let us consider

$$\begin{split} \dot{F}_{w} &= ((1-r)\rho_{w}\frac{M_{u}+M_{w}}{M_{u}+M_{w}+\gamma_{s}M_{s}^{per}}e^{-\beta(M_{u}+F_{u}+M_{w}+F_{w})} - \mu_{F_{w}})F_{w}, \\ \frac{M_{u}+M_{w}}{M_{u}+M_{w}+\gamma_{s}M_{s}^{per}}e^{-\beta(M_{u}+F_{u}+M_{w}+F_{w})} \leq \frac{M_{u}+M_{w}}{M_{u}+M_{w}+\gamma_{s}M_{s}^{per}}e^{-\beta(M_{u}+M_{w})} \leq \frac{\alpha_{2}}{\gamma_{s}M_{s}^{per}}. \end{split}$$

Integrate from  $n\tau$  to *t* with  $n\tau < t$ ,

$$\begin{split} F_w(t) &\leq F_w(n\tau) e^{\int_{n\tau}^t \left( (1-r)\rho_w \frac{\alpha_2}{\gamma_s M_s^{per}} - \mu_{F_w} \right) ds}.\\ \text{Taking} \quad t = (n+1)\tau, \quad n \in \mathbb{N},\\ F_w((n+1)\tau) &\leq e^{\left( (1-r)\rho_w \frac{\alpha_2}{\gamma_s} < \frac{1}{M_s^{per}} > -\mu_{F_w} \right) \tau} F_w(n\tau). \end{split}$$

Thus, the sequence  $\{F_w(n\tau)\}_{n\in\mathbb{N}}$  decreases towards 0, provided that

$$\left\langle \frac{1}{M_s^{per}} \right\rangle < e\beta\gamma_s \frac{1}{N_{F_w}}.$$

Similarly, from (2.4), we have  $\left\langle \frac{1}{M_s^{per}} \right\rangle < e\beta \gamma_s \frac{1}{N_{M_w}}$ .

Providing the necessary conditions  $\left\langle \frac{1}{M_s^{per}} \right\rangle$  leads to sufficient conditions for asymptotic stability at  $\mathcal{E}_0$ ;

$$\left\langle \frac{1}{M_s^{per}} \right\rangle = \frac{2(\cosh(\mu_{M_s}\tau) - 1)}{\mu_{M_s}\tau^2 \Lambda} < e\beta\gamma_s \max\{\frac{1}{N_{M_u}}, \frac{1}{N_{F_u}}, \frac{1}{N_{M_w}}, \frac{1}{N_{F_w}}\},$$

$$\Lambda \ge \frac{2(\cosh(\mu_{M_s}\tau) - 1)}{e\beta\gamma_s\mu_{M_s}\tau^2} \min\{N_{M_u}, N_{F_u}, N_{M_w}, N_{F_w}\}.$$

**Lemma 4.** Let  $k_1, k_2$  be a real number such that  $0 < k_1 < \frac{1}{N_{F_u}}, 0 < k_2 < \frac{1}{N_{F_w}}$ . Then, every solution of (2.2) such that  $\frac{M_u}{M_u+M_w+\gamma M_s} \le k_1$  and  $\frac{M_u+M_w}{M_u+M_w+\gamma M_s} \le k_2, t \ge 0$ , converges exponentially to  $\mathcal{E}_0$ .

**Proof:** By using the assumptions  $\frac{M_u}{M_u + M_w + \gamma M_s} \le k_1$  and  $\frac{M_u + M_w}{M_u + M_w + \gamma M_s} \le k_2$ , the model (2.2) becomes

$$\dot{M}_{u} = r\rho_{u}F_{u}\frac{M_{u}}{M_{u} + M_{w} + \gamma_{s}M_{s}}e^{-\beta(M_{u} + F_{u} + M_{w} + F_{w})} - \mu_{M_{u}}M_{u}$$

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$$\leq r\rho_{u}F_{u}\frac{M_{u}}{M_{u}+M_{w}+\gamma_{s}M_{s}}-\mu_{M_{u}}M_{u},\\ \leq -\mu_{M_{u}}M_{u}+r\rho_{u}k_{1}F_{u},\\ \dot{F}_{u} \leq (1-r)\rho_{u}F_{u}\frac{M_{u}}{M_{u}+M_{w}+\gamma_{s}M_{s}}-\mu_{F_{u}}F_{u},\\ \leq (-\mu_{F_{u}}+(1-r)\rho_{u}k_{1})F_{u},\\ \dot{M}_{w} \leq -\mu_{M_{w}}M_{w}+r\rho_{w}k_{2}F_{w},\\ \dot{F}_{w} \leq (-\mu_{F_{w}}+(1-r)\rho_{w}k_{2})F_{w}.$$

The autonomous linear system

$$\begin{pmatrix} \dot{M}'_{u} \\ \dot{F}'_{u} \\ \dot{M}'_{w} \\ \dot{F}'_{w} \end{pmatrix} = \begin{pmatrix} -\mu_{M_{u}} & r\rho_{u}k_{1} & 0 & 0 \\ 0 & -\mu_{F_{u}} + (1-r)\rho_{u}k_{1} & 0 & 0 \\ 0 & 0 & -\mu_{M_{w}} & r\rho_{w}k_{2} \\ 0 & 0 & 0 & -\mu_{F_{w}} + (1-r)\rho_{w}k_{2} \end{pmatrix} \begin{pmatrix} M'_{u} \\ F'_{u} \\ M'_{w} \\ F'_{w} \end{pmatrix}$$
(3.2)

is monotone (Metzler matrix involved) (see [33]), and it can be used as a comparison system for the evolution of (2.2). Thus, it is deduced that

$$0 \le M_{u}(t) \le M_{u}^{'}(t), \quad 0 \le F_{u}(t) \le F_{u}^{'}(t), \quad 0 \le M_{w}(t) \le M_{w}^{'}(t), \quad 0 \le F_{w}(t) \le F_{w}^{'}(t), \quad t \ge 0.$$

Here,  $(M'_u, F'_u, M'_w, F'_w)$  be the solution of the linear system (3.2) obtained by same initial condition as the solution  $(M_u, F_u, M_w, F_w)$  of (2.2). Furthermore, the linear system (3.2) is asymptotically stable if  $0 < k_1 < \frac{1}{N_{F_u}}, 0 < k_2 < \frac{1}{N_{F_w}}$ , i.e.,  $(M'_u, F'_u, M'_w, F'_w)$  asymptotically converges to  $\mathcal{E}_0$ . Based on this,  $(M_u, F_u, M_w, F_w)$  also asymptotically converges to  $\mathcal{E}_0$ .

**Remark 1.** The upper bound of  $k_1$  and  $k_2$  are fixed on the ratio  $\frac{M_u}{M_u+M_w+\gamma M_s}$  and  $\frac{M_u+M_w}{M_u+M_w+\gamma M_s}$  respectively, in order to make the apparent basic offspring number  $k_1N_{F_u}$  and  $k_2N_{F_w}$  is smaller than 1.

Here, we want to verify the condition  $\frac{M_u+M_w}{M_u+M_w+\gamma M_s} \le k_2$ , based on the sufficient impulse sterile releases  $\Lambda_n$ . Before, the value of  $M_s$  on  $(n\tau, (n+1)\tau]$  is described as

$$M_{s}(t) = M_{s}(n\tau^{+})e^{-\mu_{M_{s}}(t-n\tau)} = (\tau\Lambda_{n} + M_{s}(n\tau))e^{-\mu_{M_{s}}(t-n\tau)}.$$
(3.3)

We impose the stronger condition instead of  $\frac{M_u+M_w}{M_u+M_w+\gamma M_s} \le k_2$ , on  $(n\tau, (n+1)\tau]$ 

$$\gamma M_s(t) \ge \left(\frac{1}{k_2} - 1\right) (M'_u(t) + M'_w(t)), \qquad t \ge 0, \tag{3.4}$$

where  $M'_{u}(t)$ ,  $M'_{w}(t)$  refers to super solution of  $M_{u}(t)$ ,  $M_{w}(t)$  (Lemma 4).

**Lemma 5.** The solution of (3.2) on  $(n\tau, (n + 1)\tau]$  with initial conditions  $(M'_u(n\tau), F'_u(n\tau), M'_w(n\tau), F'_w(n\tau)) = (M_u(n\tau), F_u(n\tau), M_w(n\tau), F_w(n\tau))$  is defined by

$$\begin{pmatrix} M'_{u}(n\tau) \\ F'_{u}(n\tau) \\ M'_{w}(n\tau) \\ F'_{w}(n\tau) \end{pmatrix} = \begin{pmatrix} p_{1} & d_{1} & 0 & 0 \\ 0 & p_{2} & 0 & 0 \\ 0 & 0 & p_{3} & d_{2} \\ 0 & 0 & 0 & p_{4} \end{pmatrix} \begin{pmatrix} M_{u}(n\tau) \\ F_{u}(n\tau) \\ M_{w}(n\tau) \\ F_{w}(n\tau) \end{pmatrix},$$
(3.5)

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Now, we define the feedback control analysis, on any  $(n\tau, (n + 1)\tau]$ , substitute the values of (3.3) and (3.5) into (3.4), we get

$$\begin{split} \gamma M_{s}(t) &\geq \Big(\frac{1}{k_{2}} - 1\Big)(M_{u}'(t) + M_{w}'(t)), \\ &\qquad \gamma \Big(\Lambda_{n}\tau + M_{s}(n\tau)\Big)e^{-\mu_{M_{s}}(t-n\tau)} \\ &\geq \frac{1 - k_{2}}{k_{2}}\Big(e^{-\mu_{M_{u}}(t-n\tau)}M_{u}(n\tau) + \frac{r\rho_{u}k_{1}}{\mu_{M_{u}} - \mu_{F_{u}} + (1-r)\rho_{u}k_{1}}(e^{-(\mu_{F_{u}} - (1-r)\rho_{u}k_{1})(t-n\tau)}) \\ &\quad - e^{-\mu_{M_{u}}(t-n\tau)})F_{u}(n\tau) + e^{-\mu_{M_{w}}(t-n\tau)}M_{w}(n\tau) + \frac{r\rho_{w}k_{2}}{\mu_{M_{w}} - \mu_{F_{w}} + (1-r)\rho_{w}k_{2}} \\ &\qquad \times (e^{-(\mu_{F_{w}} - (1-r)\rho_{w}k_{2})(t-n\tau)} - e^{-\mu_{M_{w}}(t-n\tau)})F_{w}(n\tau)\Big), \\ \Lambda_{n}\tau &\geq -M_{s}(n\tau) + \frac{1 - k_{2}}{\gamma k_{2}}e^{(\mu_{M_{s}} - \mu_{M_{u}})s}\Big(M_{u}(n\tau) + \frac{r\rho_{u}k_{1}}{\mu_{M_{u}} - \mu_{F_{u}} + (1-r)\rho_{u}k_{1}} \times \\ &\qquad (e^{(\mu_{M_{u}} - (\mu_{F_{u}} - (1-r)\rho_{u}k_{1}))s} - 1)F_{u}(n\tau) + M_{w}(n\tau) + \frac{r\rho_{w}k_{2}}{\mu_{M_{w}} - \mu_{F_{w}} + (1-r)\rho_{w}k_{2}} \\ &\qquad \times (e^{(\mu_{M_{w}} - (\mu_{F_{w}} - (1-r)\rho_{w}k_{2}))s} - 1)F_{w}(n\tau)\Big), \quad s \in [0, \tau]. \end{split}$$

We arrive the following theorem:

**Theorem 3.** For a given  $k_1 \in (0, \frac{1}{N_{F_u}}), k_2 \in (0, \frac{1}{N_{F_w}})$ , assuming, for  $n \in \mathbb{N}$ ,

$$\tau \Lambda_{n} \geq \left| \Gamma \begin{pmatrix} M_{u}(n\tau) \\ F_{u}(n\tau) \\ M_{w}(n\tau) \\ F_{w}(n\tau) \end{pmatrix} - M_{s}(n\tau) \right|_{+},$$

$$\Gamma = \begin{pmatrix} \frac{1-k_{2}}{k_{2}} e^{(\mu_{M_{s}}-\mu_{M_{u}})\tau} \\ \frac{(1-k_{2})}{k_{2}} \frac{r\rho_{u}k_{1}}{\gamma(\mu_{M_{u}}-\mu_{F_{u}}+(1-r)\rho_{u}k_{1})} (e^{(\mu_{M_{s}}-(\mu_{F_{u}}-(1-r)\rho_{u}k_{1}))\tau} - e^{(\mu_{M_{s}}-\mu_{M_{u}})\tau}) \\ \frac{1-k_{2}}{\gamma(\mu_{M_{w}}-\mu_{F_{w}}+(1-r)\rho_{w}k_{2})} (e^{(\mu_{M_{s}}-(\mu_{F_{w}}-(1-r)\rho_{w}k_{2}))\tau} - e^{(\mu_{M_{s}}-\mu_{M_{w}})\tau}) \end{pmatrix}^{T}$$

$$(3.6)$$

Then, every solution of (2.3) exponentially converges to  $\mathcal{E}_0$  with a rate of convergence restricted from below by a value unrelated to the initial value. Moreover,

$$\tau \Lambda_n \le \Gamma \begin{pmatrix} M_u(n\tau) \\ F_u(n\tau) \\ M_w(n\tau) \\ F_w(n\tau) \end{pmatrix},$$
(3.7)

then the series  $\sum_{n=0}^{+\infty} \Lambda_n$  also converges.

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**Proof:** Suppose  $(M_u(n\tau), F_u(n\tau), M_w(n\tau), F_w(n\tau)) = (0, 0, 0, 0)$ , there is no impulsion effect  $\Lambda_n$  on the evolution of  $(M_u, F_u, M_w, F_w)$ . Let us consider  $(M_u(n\tau), F_u(n\tau), M_w(n\tau), F_w(n\tau)) \neq (0, 0, 0, 0)$ . Case(i) Assume the strict inequality of (3.6), one can easily get

$$\gamma M_{s}(t) > \left(\frac{1-k_{2}}{k_{2}}\right) (M_{u}^{'}(t) + M_{w}^{'}(t)), \quad \text{for every} \quad t \in (n\tau, (n+1)\tau], \quad (3.8)$$

where the solution  $(M'_u, F'_u, M'_w, F'_w)$  of (3.2) starting from  $(M_u(n\tau), F_u(n\tau), M_w(n\tau), F_w(n\tau))$  at  $t = n\tau$ . Initially, we establishes like that

$$M_{u}(t) < M'_{u}(t), F_{u}(t) < F'_{u}(t), M_{w}(t) < M'_{w}(t), F_{w}(t) < F'_{w}(t), \text{ for every } t \in [n\tau, (n+1)\tau].$$
(3.9)

Let  $t_0 \in [n\tau, (n+1)\tau)$  such that  $M_u(t_0) \le M'_u(t_0)$ ,  $F_u(t_0) \le F'_u(t_0)$ ,  $M_w(t_0) \le M'_w(t_0)$ ,  $F_w(t_0) \le F'_w(t_0)$  with at least one equality. Let us show the existence of  $t_1$  such that  $t_0 < t_1 < (n+1)\tau$ ,

$$M_{u}(t) < M'_{u}(t), F_{u}(t) < F'_{u}(t), M_{w}(t) < M'_{w}(t), F_{w}(t) < F'_{w}(t), \text{ for every } t \in (t_{0}, t_{1}).$$
(3.10)

Based on (3.8) and the definition of  $t_0$ ,

$$\gamma M_s(t_0) > \Big(\frac{1-k_2}{k_2}\Big)(M'_u(t_0) + M'_w(t_0)) \ge \Big(\frac{1-k_2}{k_2}\Big)(M_u(t_0) + M_w(t_0)),$$

when  $t_0 = n\tau$ , and  $M_s(t_0) = M_s(n\tau^+)$ . The functions  $M_u(t)$ ,  $F_u(t)$ ,  $M_w(t)$ ,  $F_w(t)$  and  $M_s(t)$  are continuous on  $(n\tau, (n+1)\tau)$ , there exists  $t_1$  such that  $t_0 < t_1 < (n+1)\tau$ 

$$\gamma M_s(t) > \left(\frac{1-k_2}{k_2}\right) (M_u(t) + M_w(t)), \quad \text{for every} \quad t \in (t_0, t_1).$$

It can be shown as in Lemma 4 that  $(M'_u(t), F'_u(t), M'_w(t), F'_w(t)) \ge (M_u(t), F_u(t), M_w(t), F_w(t))$  for any  $t \in (t_0, t_1)$ , Also  $(M'_u(t), F'_u(t), M'_w(t), F'_w(t)) > (M_u(t), F_u(t), M_w(t), F_w(t))$  because the functions defining the right hand sides of (2.3) take on strictly smaller values than those defining the r.h.s of (3.2). Therefore, for any  $t_0 \in (n\tau^+) \cup (n\tau, (n+1)\tau)$ , there exists  $t_1 > t_0$  such that (3.10) holds. From (3.10) and the fact that  $(M_u(n\tau), F_u(n\tau), M_w(n\tau), F_w(n\tau)) = (M'_u(n\tau), F'_u(n\tau), M'_w(n\tau), F'_w(n\tau))$ , one deduces that (3.10) is true with  $t_1 = (n + 1)\tau$ , and (3.9) is true. Finally, putting together (3.8) and (3.9) yields

$$\gamma M_s(t) > \left(\frac{1-k_2}{k_2}\right) (M_u(t) + M_w(t)), \quad \text{for every} \quad t \in (n\tau, (n+1)\tau].$$
 (3.11)

Case(ii) Assume (3.6) holds, and instead of (3.11), considering the  $\Lambda_n$  values convergent from above to the quantity in the r.h.s of this inequality, and trust the flow's consistency with respect to  $\Lambda_n$ .

$$\gamma M_s(t) \ge \left(\frac{1-k_2}{k_2}\right) (M_u(t) + M_w(t)), \quad \text{for every} \quad t \in (n\tau, (n+1)\tau]. \quad (3.12)$$

From (3.12), for any  $t \in (n\tau, (n+1)\tau]$ ,  $\frac{M_u}{M_u + M_w + M_s} \le k_1$  and  $\frac{M_u + M_w}{M_u + M_w + M_s} \le k_2$ .

$$\dot{F}_{u} = (1-r)\rho_{u}F_{u}\frac{M_{u}}{M_{u}+M_{w}+\gamma_{s}M_{s}}e^{-\beta(M_{u}+F_{u}+M_{w}+F_{w})} - \mu_{F_{u}}F_{u},$$
  
$$\leq ((1-r)\rho_{u}k_{1}-\mu_{F_{u}})F_{u},$$

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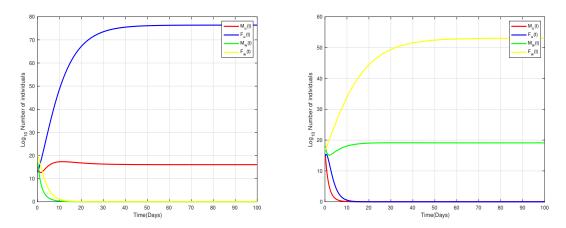
$$\begin{split} \dot{F}_{w} &= (1-r)\rho_{w}F_{w}\frac{M_{u}+M_{w}}{M_{u}+M_{w}+\gamma_{s}M_{s}}e^{-\beta(M_{u}+F_{u}+M_{w}+F_{w})} - \mu_{F_{w}}F_{w}, \\ &\leq ((1-r)\rho_{w}k_{2}-\mu_{F_{w}})F_{w}. \end{split}$$

From the values of  $\Gamma$ , there exists  $\epsilon_1, \epsilon_2 > 0$  such that  $\mu_{F_u} - (1 - r)\rho_u k_1 > \epsilon_1, \mu_{F_w} - (1 - r)\rho_w k_2 > \epsilon_2$ and then  $\dot{F}_u \leq -\epsilon_1 F_u, \dot{F}_w \leq -\epsilon_2 F_w$ . Therefore,  $F_u(t), F_w(t)$  exponentially converges to 0. It is then deduced from first and third equation of (2.3) that  $M_u(t), M_w(t)$  also exponentially converges to 0.  $(M_u(t), F_u(t), M_w(t), F_w(t))$  converges to  $\mathcal{E}_0$ .

Finally,  $\Lambda_n$  satisfies (3.6) and (3.7), based on exponentially stability concepts, there exist  $C, \epsilon > 0$  such that  $M_u(t) < Ce^{-\epsilon t}, F_u(t) < Ce^{-\epsilon t}, M_w(t) < Ce^{-\epsilon t}, F_w(t) < Ce^{-\epsilon t}, t \ge 0$ . We can easily obtain that

$$\begin{split} \Lambda_{n} &\leq \frac{(1-k_{2})}{\tau\gamma k_{2}} e^{(\mu_{M_{s}}-\mu_{M_{u}})\tau} M_{u}(n\tau) + \frac{r\rho_{u}k_{1}(1-k_{2})}{\tau\gamma k_{2}(\mu_{M_{u}}-\mu_{F_{u}}+(1-r)\rho_{u}k_{1})} (e^{(\mu_{M_{s}}-(\mu_{F_{u}}-(1-r)\rho_{u}k_{1}))\tau} \\ &- e^{(\mu_{M_{s}}-\mu_{M_{u}})\tau}) F_{u}(n\tau) + \frac{(1-k_{2})}{\tau\gamma k_{2}} e^{(\mu_{M_{s}}-\mu_{M_{w}})\tau} M_{w}(n\tau) + \frac{r\rho_{w}(1-k_{2})}{\tau\gamma(\mu_{M_{w}}-\mu_{F_{w}}+(1-r)\rho_{w}k_{2})} \\ &\times (e^{(\mu_{M_{s}}-(\mu_{F_{w}}-(1-r)\rho_{w}k_{2}))\tau} - e^{(\mu_{M_{s}}-\mu_{M_{w}})\tau}) F_{w}(n\tau), \\ &\leq \frac{C}{\gamma\tau} \Big( \frac{(1-k_{2})}{k_{2}} e^{(\mu_{M_{s}}-\mu_{M_{u}})\tau} + \frac{r\rho_{u}(1-k_{2})k_{1}}{k_{2}(\mu_{M_{u}}-\mu_{F_{u}}+(1-r)\rho_{u}k_{1})} (e^{(\mu_{M_{s}}-(\mu_{F_{u}}-(1-r)\rho_{w}k_{2}))\tau} - e^{(\mu_{M_{s}}-\mu_{M_{u}})\tau}) \\ &+ \frac{(1-k_{2})}{k_{2}} e^{(\mu_{M_{s}}-\mu_{M_{w}})\tau} + \frac{r\rho_{w}(1-k_{2})}{(\mu_{M_{w}}-\mu_{F_{w}}+(1-r)\rho_{w}k_{2})} (e^{(\mu_{M_{s}}-(\mu_{F_{u}}-(1-r)\rho_{w}k_{1}))\tau} - e^{(\mu_{M_{s}}-\mu_{M_{w}})\tau}) \Big) e^{-n\epsilon\tau}, \\ &\sum_{n=0}^{+\infty} \Lambda_{n} \leq \frac{C}{\gamma\tau} \Big( \frac{(1-k_{2})}{k_{2}} e^{(\mu_{M_{s}}-\mu_{M_{u}})\tau} + \frac{r\rho_{u}(1-k_{2})k_{1}}{k_{2}(\mu_{M_{u}}-\mu_{F_{u}}+(1-r)\rho_{u}k_{1})} (e^{(\mu_{M_{s}}-(\mu_{F_{u}}-(1-r)\rho_{w}k_{1}))\tau} \\ &- e^{(\mu_{M_{s}}-\mu_{M_{u}})\tau}) + \frac{(1-k_{2})}{k_{2}} e^{(\mu_{M_{s}}-\mu_{M_{w}})\tau} + \frac{r\rho_{w}(1-k_{2})}{(\mu_{M_{w}}-\mu_{F_{w}}+(1-r)\rho_{w}k_{2})} (e^{(\mu_{M_{s}}-(\mu_{F_{w}}-(1-r)\rho_{w}k_{2}))\tau} \\ &- e^{(\mu_{M_{s}}-\mu_{M_{u}})\tau}) \Big) \frac{1}{1-e^{-\epsilon t}}. \end{split}$$

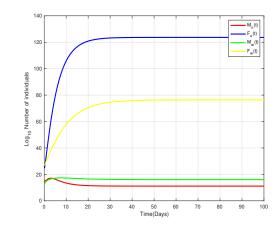
The above series is convergent.



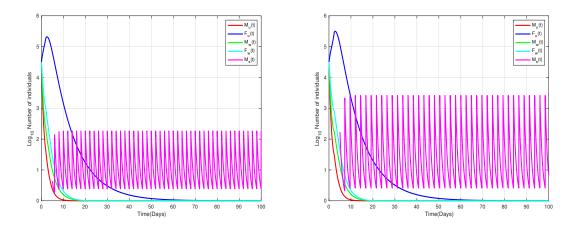
**Figure 1.** The *Wolbachia* free equilibrium point  $\mathcal{E}_1$ , which is asymptotically stable when  $N_{F_u} > 1$  (left) and *Wolbachia* infected equilibrium point  $\mathcal{E}_2$ , which is asymptotically stable when  $N_{F_w} > 1$  (right) for model (2.1).

## 4. Numerical simulations

We consider the parameter values of the model: r = 0.5,  $\rho_u = 6.4$ ,  $\rho_w = 3.5$ ,  $\gamma_s = 0.9$ ,  $\mu_{M_u} = 0.07$ ,  $\mu_{F_u} = 0.06$ ,  $\mu_{M_w} = 0.04$ ,  $\mu_{F_w} = 0.03$ ,  $\mu_{M_s} = 0.11$ ,  $\sigma = 0.05$ , K = 155,  $\beta = \frac{\sigma}{K} = 3.22 \times 10^{-4}$ . The basic offspring numbers:  $N_{M_u} \approx 45.71$ ,  $N_{F_u} \approx 53.33$ ,  $N_{M_w} \approx 43.75$ ,  $N_{F_w} \approx 58.33$ . The basic offspring figures show the average number of children produced over a person's lifespan. Figures 1 and 2 display the stable behaviour of the steady states  $\mathcal{E}_1, \mathcal{E}_2$  and  $\mathcal{E}_3$ , respectively. Let's starting with the regular rash discharges of sterile male mosquitoes. The releasing method derived in Theorem 2 is demonstrated. For open-loop periodic impulsive releases carried out every 7 and 14 days. Consider the smallest value in (3.1) to estimate the number of sterile male mosquitoes to release, i.e.,  $\Lambda_{per}^{crit} \times 7 = 1525 \times$ 7 = 10,675 and  $\Lambda_{per}^{crit} \times 14 = 1595 \times 14 = 22,330$ , sterile male mosquitoes per hectare and per two weeks, respectively. Figure 3 depicts the corresponding simulations.

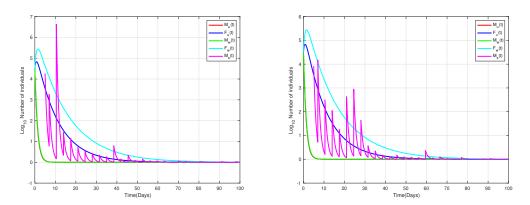


**Figure 2.** The interior equilibrium point  $\mathcal{E}_3$ , which is asymptotically stable when  $N_{F_u} > 1$  and  $N_{F_w} > 1$  for model (2.1).

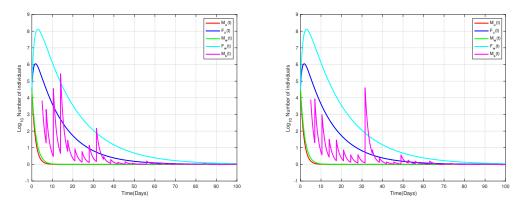


**Figure 3.** Open loop periodic impulsive control of (2.3) with  $\tau = 7$  days (left) and  $\tau = 14$  days (right).

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**Figure 4.** Closed loop periodic impulsive control of (2.3) with  $k_1N_{F_u} = 0.2$ ,  $k_2N_{F_w} = 0.25$ ,  $\tau = 7$  days (left) and  $k_1N_{F_u} = 0.2$ ,  $k_2N_{F_w} = 0.25$ ,  $\tau = 14$  days (right).



**Figure 5.** Closed loop periodic impulsive control of (2.3) with  $k_1 N_{F_u} = 0.7$ ,  $k_2 N_{F_w} = 0.8$ ,  $\tau = 7$  days (left) and  $k_1 N_{F_u} = 0.7$ ,  $k_2 N_{F_w} = 0.8$ ,  $\tau = 14$  days (right).

The closed-loop method can be utilized to reduce the total number of sterile insects released. Theorem 3 shows how the method can be used to lower the total number of sterile insects released. We consider the wild population every  $\tau$  days both here and in the examination of the feedback technique. We also look at the values of  $k_1$  and  $k_2$  to show the tradeoff between treatment duration and control effort. A small  $k_1$  and  $k_2$  results in a larger control effort and a faster convergence to  $\mathcal{E}_0$ . For  $k_1N_{F_u} = 0.2$ ,  $k_2N_{F_w} = 0.25$ ,  $\tau = 7$  and  $k_1N_{F_u} = 0.2$ ,  $k_2N_{F_w} = 0.25$ ,  $\tau = 14$ , the diagrams displayed in Figure 4 show that that the wild population is close to extinction with the help of SIT treatment. The control effort is smaller and convergence should be delayed for bigger values of  $k_1$  and  $k_2$ . For  $k_1N_{F_u} = 0.7$ ,  $k_2N_{F_w} = 0.8$ ,  $\tau = 7$  and  $k_1N_{F_u} = 0.7$ ,  $k_2N_{F_w} = 0.8$ ,  $\tau = 14$ , the diagrams are displayed in Figure 5. The size  $\Lambda_n$  of the  $n^{th}$  release is taken equal to the right-hand side of (3.6). As it can be clearly seen that  $k_1$ ,  $k_2$  and  $\tau$  have a significant impact on the mosquito population convergence to  $\mathcal{E}_0$ .

## 5. Concluding remarks

Our study utilized a *Wolbachia*-infected *Aedes Aegypti* mosquitoes model, followed by continuous and impulsive releases of sterile male mosquitoes. Mosquitoes can be controlled by releasing ster-

ile mosquitoes or by replacing the wild population with one that carries Wolbachia bacteria, which prevents the transmission of viruses from mosquitoes to humans. Our analysis suggests that despite the lower fitness of the *Wolbachia*-carrying population in comparison to the wild population, the CI-reproductive phenotype gives the system an advantage when shifting from a wild to a Wolbachia-carrying population. A number of interesting sufficient conditions have been derived for the model's local asymptotic stability. The conditions required for open-loop or closed-loop control systems were also assessed using sterile male mosquitoes released impulsively. Based on wild population estimates, release sizes are determined in closed-loop control. As shown by (3.6), the released volume is essentially proportional to the measured population. Using sterile insect techniques may lead to periodic outbreaks of mosquitoes due to a periodic oscillation in the system. The theoretical results confirm the numerical solution to the proposed model.

The use of control variables (open, closed-loop, and mixed control techniques) will be considered in future research to determine the best SIT technique, mixed control, and mosquito population elimination strategies.

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# **Conflict of interest**

The authors declare no conflicts of interest.

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