



Research article

On coupled snap system with integral boundary conditions in the \mathbb{G} -Caputo sense

Sabri T. M. Thabet^{1,2}, Mohammed M. Matar³, Mohammed Abdullah Salman⁴, Mohammad Esmael Samei⁵, Miguel Vivas-Cortez^{6,*} and Imed Kedim⁷

¹ Department of Mathematics, University of Aden, Aden, Yemen

² Department of Mathematics, University of Lahej, Lahej, Yemen

³ Department of Mathematics, Al-Azhar University-Gaza, Gaza Strip, Palestine

⁴ Department of Mathematics and Statistics, Amran University, Amran, Yemen

⁵ Department of Mathematics, Faculty of Basic Science, Bu-Ali Sina University, Hamedan 65178-38695, Iran

⁶ Faculty of Exact and Natural Sciences, School of Physical Sciences and Mathematics, Pontifical Catholic University of Ecuador, Av. 12 de octubre 1076 y Roca, Apartado Postal 17-01-2184, Sede Quito, Ecuador

⁷ Department of Mathematics, College of Science and Humanities in Al-Kharj, Prince Sattam Bin Abdulaziz University, Al-Kharj 11942, Saudi Arabia

* **Correspondence:** Email: mjvivas@puce.edu.ec.

Abstract: In this paper, we consider a coupled snap system in a fractional \mathbb{G} -Caputo derivative sense with integral boundary conditions. Hyers-Ulam stability criterion is investigated, and a numerical simulation will be supplied to some applications. Some numerical simulations are presented to guarantee the theoretical results.

Keywords: snap problem; \mathbb{G} -Caputo fractional differential equation; boundary value problem; Ulam-Hyers-Rassias stability

Mathematics Subject Classification: 34A08, 34B18

1. Introduction

Over the past decades, the study of nonlinear problems has been the interest of many researchers [5, 10, 11, 14, 19, 24–26]. Also, study of fractional calculus has recently gained great momentum, and has emerged as a significant research area [5, 7, 15, 20, 21, 30]. Fractional derivatives provide an excellent

tool for the description of memory and hereditary properties of various materials and processes; see, for instance, the contribution [2–4, 6, 16, 22, 23, 28, 29] and references therein.

The authors in [8] focused on the study of nonlinear jerk problems due to its various physical applications, as form

$$\frac{d^3y}{dt^3} = \mathfrak{T}\left(y, \frac{dy}{dt}, \frac{d^2y}{dt^2}\right).$$

In 2020, the authors investigated the existence and uniqueness of solutions for the following nonlocal generalized fractional Sturm-Liouville and Langevin equations:

$$\begin{cases} {}^c\mathcal{D}_{t_1^+}^\alpha \left(\left[p(t) {}^c\mathcal{D}_{t_1^+}^\gamma + q(t) \right] y(t) \right) = \mathfrak{T}(t, y(t)), & t \in [0, T], \alpha, \gamma \in (0, 1], \\ y(0) + \kappa_1(y) = y_1 \in \mathbb{R}, \\ {}^c\mathcal{D}_{t_1^+}^\gamma y(T) + \kappa_2(y) = y_2 \in \mathbb{R}, \end{cases}$$

where ${}^c\mathcal{D}_{t_1^+}^\alpha$, ${}^c\mathcal{D}_{t_1^+}^\gamma$ are the Caputo fractional derivatives, $p, q \in C([0, T])$ with $|p| \geq K > 0$, $\kappa_1, \kappa_2 : C(J) \rightarrow \mathbb{R}$ are continuous functions and $\mathfrak{T} \in C([0, T] \times \mathbb{R})$ [27]. The second derivative of the acceleration (fourth derivative of position) is a physical quantity called a snap or jounce, which can be modeled as

$$\begin{cases} \frac{dy_1}{dt} = y_2(t), & \frac{dv_2}{dt} = y_3(t), & \frac{dy_3}{dt} = y_4(t), \\ \frac{dy_4}{dt} = \mathfrak{T}(y_1, y_2, y_3, y_4). \end{cases} \quad (1.1)$$

It is obvious that the model (1.1) can be reduced to the following equation:

$$\frac{d^4y_1}{dt^4} = \mathfrak{T}\left(y_1, \frac{dy_1}{dt}, \frac{d^2y_1}{dt^2}, \frac{d^3y_1}{dt^3}\right). \quad (1.2)$$

Scientifically, jerk and snap are the third and fourth derivatives of our position with regard to time, respectively. The Eq (1.1) contains a 4th-order derivative of the variable y_1 , and it describes a 4th-order dynamical vibration model.

The corresponding fractional model is achieved by using the fractional derivative (of order less than or equal 1) instead of the standard derivative $\frac{d}{dt}$. Many types of fractional derivatives can be used here, such as Riemann-Liouville, Caputo, Hadamard, etc. We prefer to use the generalized fractional derivative (GFD), with respect to differentiable increasing function \mathbb{G} . In 2020, Liu et al., developed two iterative algorithms to determine the periods, and then the periodic solutions of nonlinear jerk equations for two possible cases with initial values unknown and initial values given [13]. The authors in a recent article [23] considered the \mathbb{G} -fractional snap model (GFSM) with constant, initial conditions

$$\begin{cases} {}^c\mathcal{D}_{t_1^+}^{\alpha; \mathbb{G}} y(t) = y_1(t), & y(t_1) = v_0, \\ {}^c\mathcal{D}_{t_1^+}^{\beta; \mathbb{G}} y_1(t) = y_2(t), & y_1(t_1) = v_1, \\ {}^c\mathcal{D}_{t_1^+}^{\gamma; \mathbb{G}} y_2(t) = y_3(t), & y_2(t_1) = v_2, \\ {}^c\mathcal{D}_{t_1^+}^{\delta; \mathbb{G}} y_3(t) = \mathcal{T}(t, y, y_1, y_2, y_3), & y_3(t_1) = v_3, \end{cases} \quad (1.3)$$

where the \mathbb{G} -Caputo derivatives are illustrated by the symbol

$${}^c \mathcal{D}_{t_1^+}^{\eta; \mathbb{G}}, \quad \eta \in \{\alpha, \beta, \gamma, \delta\}, \quad 0 < \eta < 1,$$

here and the increasing function $\mathbb{G} \in C^1([t_1, t_2])$ is such that $\mathbb{G}'(t) \neq 0$, for each $t \in [t_1, t_2]$ and continuous function \mathcal{T} belongs to $C([t_1, t_2] \times \mathbb{R}^4)$ and $y_0, y_1, y_2, y_3 \in \mathbb{R}$. Abbas et al. studied the following coupled system of fractional differential equations:

$$\begin{cases} {}^{RL} \mathcal{D}_{t_1^+}^{\alpha_1; \varrho} y_1(t) = \mathfrak{T}_1(t, y_1(t), y_2(t)), \\ {}^{RL} \mathcal{D}_{t_1^+}^{\alpha_2; \varrho} y_2(t) = \mathfrak{T}_2(t, y_1(t), y_2(t)), \end{cases}$$

for $t \in [t_1, t_2]$ equipped with the generalized fractional integral boundary conditions

$$\begin{cases} y_1(\tau_1) = 0, & y_1(t_2) = \mathcal{I}_{t_1^+}^{\zeta_1; \varrho} y_1(\eta_1), \\ y_2(\tau_2) = 0, & y_2(t_2) = \mathcal{I}_{t_1^+}^{\zeta_2; \varrho} y_2(\eta_2), \end{cases}$$

where $\varrho \in (0, 1]$, ${}^{RL} \mathcal{D}_{t_1^+}^{\alpha_i; \varrho}$ denotes the generalized proportional fractional derivatives of Riemann-Liouville type of order $1 < \alpha_i \leq 2$, $\mathcal{I}_{t_1^+}^{\zeta_i; \varrho}$ that denotes the generalized proportional fractional integrals of order $0 < \zeta_i < 1$ and $\tau_i, \eta_i \in (t_1, t_2)$ and $\mathfrak{T}_i \in C([t_1, t_2] \times \mathbb{R}^2)$ [1].

We center our consideration on the problem of the existence and uniqueness along with the Hyers-Ulam stability (U-H-S) of solutions for fractional nonlinear couple snap system (CSS) in the \mathbb{G} -Caputo sense (\mathbb{G} C) with initial conditions

$$\begin{cases} {}^c \mathcal{D}_{t_1^+}^{q_1; \mathbb{G}} v_1(t) = u_1(t), & {}^c \mathcal{D}_{t_1^+}^{q_2; \mathbb{G}} v_2(t) = u_2(t), \\ {}^c \mathcal{D}_{t_1^+}^{p_1; \mathbb{G}} u_1(t) = w_1(t), & {}^c \mathcal{D}_{t_1^+}^{p_2; \mathbb{G}} u_2(t) = w_2(t), \\ {}^c \mathcal{D}_{t_1^+}^{r_1; \mathbb{G}} w_1(t) = x_1(t), & {}^c \mathcal{D}_{t_1^+}^{r_2; \mathbb{G}} w_2(t) = x_2(t), \\ {}^c \mathcal{D}_{t_1^+}^{s_1; \mathbb{G}} x_1(t) = h_1(t, v_1, v_2, u_1, u_2, w_1, w_2, x_1, x_2), \\ {}^c \mathcal{D}_{t_1^+}^{s_2; \mathbb{G}} x_2(t) = h_2(t, v_1, v_2, u_1, u_2, w_1, w_2, x_1, x_2), \end{cases} \quad (1.4)$$

subject to the following integral boundary conditions

$$\begin{aligned} v_1(t_1) &= \int_{t_1}^{t_2} g_{10}(s) ds, & v_2(t_1) &= \int_{t_1}^{t_2} g_{20}(s) ds, \\ u_1(t_1) &= \int_{t_1}^{t_2} g_{11}(s) ds, & u_2(t_1) &= \int_{t_1}^{t_2} g_{21}(s) ds, \\ w_1(t_1) &= \int_{t_1}^{t_2} g_{12}(s) ds, & w_2(t_1) &= \int_{t_1}^{t_2} g_{22}(s) ds, \\ x_1(t_1) &= \int_{t_1}^{t_2} g_{13}(s) ds, & x_2(t_1) &= \int_{t_1}^{t_2} g_{23}(s) ds, \end{aligned} \quad (1.5)$$

where the \mathbb{G} C derivatives are illustrated by symbol

$${}^c \mathcal{D}_{t_1^+}^{\eta; \mathbb{G}}, \quad \eta \in \{q_k, p_k, r_k, s_k\}, \quad 0 < q_k, p_k, r_k, s_k \leq 1,$$

here the function $\mathbb{G} \in C^1(\Sigma)$ is increasing with $\mathbb{G}'(t) \neq 0$, for all $t \in \Sigma = [\iota_1, \iota_2]$ and the functions $h_k \in C(\Sigma \times \mathbb{R}^8)$, ($k = 1, 2$) and $g_{kj} \in C(\Sigma, \mathbb{R})$, ($j = 0, 1, 2, 3$; $k = 1, 2$) are continuous functions. It is obvious that the CSS (1.4) and (1.5) can be rewritten as

$$\left\{ \begin{array}{l} {}^c \mathcal{D}_{\iota_1^+}^{s_k; \mathbb{G}} \left({}^c \mathcal{D}_{\iota_1^+}^{r_k; \mathbb{G}} \left({}^c \mathcal{D}_{\iota_1^+}^{p_k; \mathbb{G}} \left({}^c \mathcal{D}_{\iota_1^+}^{q_k; \mathbb{G}} v_k(t) \right) \right) \right) = h_k(t) \\ v_k(\iota_1) = \int_{\iota_1}^{\iota_2} g_{k0}(s) ds, \quad {}^c \mathcal{D}_{\iota_1^+}^{q_k; \mathbb{G}} v_k(t) \Big|_{t=\iota_1} = \int_{\iota_1}^{\iota_2} g_{k1}(s) ds, \\ {}^c \mathcal{D}_{\iota_1^+}^{p_k; \mathbb{G}} \left({}^c \mathcal{D}_{\iota_1^+}^{q_k; \mathbb{G}} v_k(t) \right) \Big|_{t=\iota_1} = \int_{\iota_1}^{\iota_2} g_{k2}(s) ds, \\ {}^c \mathcal{D}_{\iota_1^+}^{r_k; \mathbb{G}} \left({}^c \mathcal{D}_{\iota_1^+}^{p_k; \mathbb{G}} \left({}^c \mathcal{D}_{\iota_1^+}^{q_k; \mathbb{G}} v_k(t) \right) \right) \Big|_{t=\iota_1} = \int_{\iota_1}^{\iota_2} g_{k3}(s) ds, \quad k = 1, 2, \end{array} \right. \quad (1.6)$$

where

$$\begin{aligned} h_{v_1, v_2, k}(t) = & h_k \left(t, v_1(t), v_2(t), {}^c \mathcal{D}_{\iota_1^+}^{q_1; \mathbb{G}} v_1(t), {}^c \mathcal{D}_{\iota_1^+}^{q_2; \mathbb{G}} v_2(t), \right. \\ & {}^c \mathcal{D}_{\iota_1^+}^{p_1; \mathbb{G}} \left({}^c \mathcal{D}_{\iota_1^+}^{q_1; \mathbb{G}} v_1(t) \right), {}^c \mathcal{D}_{\iota_1^+}^{p_2; \mathbb{G}} \left({}^c \mathcal{D}_{\iota_1^+}^{q_2; \mathbb{G}} v_2(t) \right), \\ & \left. {}^c \mathcal{D}_{\iota_1^+}^{r_1; \mathbb{G}} \left({}^c \mathcal{D}_{\iota_1^+}^{p_1; \mathbb{G}} \left({}^c \mathcal{D}_{\iota_1^+}^{q_1; \mathbb{G}} v_1(t) \right) \right), {}^c \mathcal{D}_{\iota_1^+}^{r_2; \mathbb{G}} \left({}^c \mathcal{D}_{\iota_1^+}^{p_2; \mathbb{G}} \left({}^c \mathcal{D}_{\iota_1^+}^{q_2; \mathbb{G}} v_2(t) \right) \right) \right). \end{aligned}$$

The main novelty of this work is that we establish our results with the help of the technique of fixed point theorems for a fractional nonlinear CSS furnished with generalized operators, which leads to some general theoretical findings involving the following special cases: \mathbb{G} as $\mathbb{G}_1(\iota) = 2^\iota$, $\mathbb{G}_2(\iota) = \iota$ (Caputo derivative), $\mathbb{G}_3(\iota) = \ln \iota$ (Caputo-Hadamard derivative), $\mathbb{G}_4(\iota) = \sqrt{\iota}$ (Katugampola derivative).

This paper is organized as follows: In Section 2, we present some necessary definitions and lemmas that are needed in the subsequent sections. In Section 3, we adopt some fixed point theorems to prove the existence and uniqueness of solutions for problem (1.4). The stability results are extensively discussed in Section 3.2. An illustrative example is presented in Section 4.

2. Preliminaries

Some primitive notions, definitions and notations, which will be utilized throughout the manuscript, are recalled here. Consider the function \mathbb{G} with assumptions in system (1.4). We start this part by defining \mathbb{G} -Riemann-Liouville fractional (\mathbb{G} FR-RL) integrals and derivatives [17]. For $\eta > 0$, the η^{th} - \mathbb{G} FR-RL integral for an integrable function $v : \Sigma \rightarrow \mathbb{R}$ w.r.t \mathbb{G} is illustrated as follows

$$\mathcal{I}_{\iota_1^+}^{\eta; \mathbb{G}} v(t) = \frac{1}{\Gamma(\eta)} \int_{\iota_1}^t (\mathbb{G}(t) - \mathbb{G}(\sigma))^{\eta-1} \mathbb{G}'(\sigma) v(\sigma) d\sigma, \quad (2.1)$$

where $\Gamma(\eta) = \int_0^{+\infty} e^{-t} t^{\eta-1} dt$, $\eta > 0$. Let $n \in \mathbb{N}$ and $\mathbb{G}, v \in C^n(\Sigma)$ be such that \mathbb{G} has the same properties mentioned above. The η^{th} - \mathbb{G} FR-RL derivative of v is defined by

$$\begin{aligned} \mathcal{D}_{\iota_1^+}^{\eta; \mathbb{G}} v(t) &= A^{(n)} \mathcal{I}_{\iota_1^+}^{n-\eta; \mathbb{G}} v(t) \\ &= \frac{1}{\Gamma(n-\eta)} A^{(n)} \int_{\iota_1}^t (\mathbb{G}(t) - \mathbb{G}(\sigma))^{n-\eta-1} \mathbb{G}'(\sigma) v(\sigma) d\sigma, \end{aligned}$$

in which $n = [\eta] + 1$, where $A = \frac{1}{\mathbb{G}'(t)} \frac{d}{dt}$. The η^{th} - \mathbb{G} -fractional-Caputo derivative of v is defined by ${}^c \mathcal{D}_{t_1^+}^{\eta; \mathbb{G}} v(t) = \mathcal{I}_{t_1^+}^{n-\eta; \mathbb{G}} A^{(n)} v(t)$, in which $n = [\eta] + 1$, ($\eta \notin \mathbb{N}$), $n = \eta$ for $\eta \in \mathbb{N}$ [17]. In other words,

$${}^c \mathcal{D}_{t_1^+}^{\eta; \mathbb{G}} v(t) = \begin{cases} \int_{t_1}^t \frac{(\mathbb{G}(t) - \mathbb{G}(\xi))^{n-\eta-1}}{\Gamma(n-\eta)} \mathbb{G}'^{(n)} v(\xi) d\xi, & \eta \notin \mathbb{N}, \\ A^n v(t), & \eta = n \in \mathbb{N}. \end{cases} \quad (2.2)$$

This extension (2.2) gives the Caputo derivative when $\mathbb{G}(t) = t$ [17]. Also, in the case $\mathbb{G}(t) = \ln t$, it yields the Caputo-Hadamard derivative. If $v \in C^n(\Sigma)$, the η^{th} - \mathbb{G} -fractional-Caputo derivative of v is specified as [18]

$${}^c \mathcal{D}_{t_1^+}^{\eta; \mathbb{G}} v(t) = \mathcal{D}_{t_1^+}^{\eta; \mathbb{G}} \left(v(t) - \sum_{j=0}^{n-1} \frac{A^{(j)} v(t_1)}{j!} (\mathbb{G}(t) - \mathbb{G}(t_1))^j \right).$$

The composition rules for above \mathbb{G} -operators are recalled in this lemma.

Lemma 2.1. [18] Let $n - 1 < \eta < n$ and $v \in C^n(\Sigma)$. Then the following holds

$$\mathcal{I}_{t_1^+}^{\eta; \mathbb{G}} {}^c \mathcal{D}_{t_1^+}^{\eta; \mathbb{G}} v(t) = v(t) - \sum_{j=0}^{n-1} \frac{A^{(j)} v(t_1)}{j!} [\mathbb{G}(t) - \mathbb{G}(t_1)]^j,$$

for all $t \in \Sigma$. Moreover, if $m \in \mathbb{N}$ and $v \in C^{n+m}(\Sigma)$, then, the following holds

$$A^{(m)} \left({}^c \mathcal{D}_{t_1^+}^{\eta; \mathbb{G}} v \right) (t) = {}^c \mathcal{D}_{t_1^+}^{\eta+m; \mathbb{G}} v(t) + \sum_{j=0}^{m-1} \frac{[\mathbb{G}(t) - \mathbb{G}(t_1)]^{j+n-\eta-m}}{\Gamma(j+n-\eta-m+1)} A^{(j+n)} v(t_1). \quad (2.3)$$

Observe that from Eq (2.3) if $A^{(j)} v(t_1) = 0$, for $j = n, n+1, \dots, n+m-1$, we can get the following relation

$$A^{(m)} \left({}^c \mathcal{D}_{t_1^+}^{\eta; \mathbb{G}} v \right) (t) = {}^c \mathcal{D}_{t_1^+}^{\eta+m; \mathbb{G}} v(t), \quad t \in \Sigma.$$

Lemma 2.2. [12] Let $\eta, \nu > 0$, and $v \in C(\Sigma)$. Then for each $t \in \Sigma$ and by assuming

$$F_{t_1}(t) = \mathbb{G}(t) - \mathbb{G}(t_1), \quad (2.4)$$

we have

$$(1) \mathcal{I}_{t_1^+}^{\eta; \mathbb{G}} \left(\mathcal{I}_{t_1^+}^{\nu; \mathbb{G}} v \right) (t) = \mathcal{I}_{t_1^+}^{\eta+\nu; \mathbb{G}} v(t);$$

$$(2) {}^c \mathcal{D}_{t_1^+}^{\eta; \mathbb{G}} \left(\mathcal{I}_{t_1^+}^{\eta; \mathbb{G}} v \right) (t) = v(t);$$

$$(3) \mathcal{I}_{t_1^+}^{\eta; \mathbb{G}} (F_{t_1}(t))^{\nu-1} = \frac{\Gamma(\nu)}{\Gamma(\nu+\eta)} (F_{t_1}(t))^{\nu+\eta-1};$$

$$(4) {}^c \mathcal{D}_{t_1^+}^{\eta; \mathbb{G}} (F_{t_1}(t))^{\nu-1} = \frac{\Gamma(\nu)}{\Gamma(\nu-\eta)} (F_{t_1}(t))^{\nu-\eta-1};$$

$$(5) {}^c \mathcal{D}_{t_1^+}^{\eta; \mathbb{G}} (F_{t_1}(t))^j = 0, \quad n-1 \leq \eta \leq n, n \in \mathbb{N}, j = 0, 1, \dots, n-1.$$

Theorem 2.3. [9] (Banach's fixed point theorem) Consider $\Pi : \mathcal{Y} \rightarrow \mathcal{Y}$ to be a contraction operator, such that \mathcal{Y} is a Banach space. Then, there are only one $y^* \in \mathcal{Y}$, such that $\Pi(y^*) = y^*$.

Lemma 2.4. [9] (Krasnoselskii's fixed point theorem) Assume that $\mathcal{B} \subset X$ is a closed convex and nonempty, and $\mathcal{Q}_1, \mathcal{Q}_2 : \mathcal{B} \rightarrow X$ nonlinear operators, such that:

- (i) $\mathcal{Q}_1 u + \mathcal{Q}_2 v \in \mathcal{B}$ whenever $u, v \in \mathcal{B}$;
- (ii) \mathcal{Q}_1 is a contraction mapping;
- (iii) \mathcal{Q}_2 is compact and continuous.

Then, there exists $w \in \mathcal{B}$, such that $w = \mathcal{Q}_1 w + \mathcal{Q}_2 w$.

Definition 2.5. [29] Let X_1, X_2 be Banach spaces and $\Lambda_1, \Lambda_2 : X_1 \times X_2 \rightarrow X_1 \times X_2$ be two operators. Then, the operational equations system provided by

$$\begin{cases} u_1(t) = \Lambda_1(u_1, u_2)(t), \\ u_2(t) = \Lambda_2(u_1, u_2)(t), \end{cases} \quad (2.5)$$

is called U-H- \mathbb{S} , if there exist $\alpha_i > 0$, ($i = 1, \dots, 4$), such that, $\forall \rho_1, \rho_2 > 0$, and each solution $(u_1^*, u_2^*) \in X_1 \times X_2$ of the identities

$$\begin{cases} \|u_1^* - \Lambda_1(u_1^*, u_2^*)\| \leq \rho_1, \\ \|u_2^* - \Lambda_2(u_1^*, u_2^*)\| \leq \rho_2, \end{cases}$$

there exists $(v_1^*, v_2^*) \in X_1 \times X_2$ a solution of system (2.5), such that

$$\begin{cases} \|u_1^* - v_1^*\| \leq \alpha_1 \rho_1 + \alpha_2 \rho_2, \\ \|u_2^* - v_2^*\| \leq \alpha_3 \rho_1 + \alpha_4 \rho_2. \end{cases}$$

Theorem 2.6. [29] Let X_1, X_2 be Banach spaces and $\Lambda_1, \Lambda_2 : X_1 \times X_2 \rightarrow X_1 \times X_2$ be two operators that satisfy

$$\begin{cases} \|\Lambda_1(u_1, u_2) - \Lambda_1(u_1^*, u_2^*)\| \leq \alpha_1 \|u_1 - u_1^*\| + \alpha_2 \|u_2 - u_2^*\|, \\ \|\Lambda_2(u_1, u_2) - \Lambda_2(u_1^*, u_2^*)\| \leq \alpha_3 \|u_1 - u_1^*\| + \alpha_4 \|u_2 - u_2^*\|, \end{cases} \quad (2.6)$$

for each $(u_1, u_2), (u_1^*, u_2^*) \in X_1 \times X_2$ and if the matrix

$$\mathcal{E} = \begin{pmatrix} \alpha_1 & \alpha_2 \\ \alpha_3 & \alpha_4 \end{pmatrix},$$

it converges to zero. Then, the system (2.6) is U-H- \mathbb{S} .

3. Main results

Here, we analyze the existence properties of solutions, and their uniqueness for the proposed fractional \mathbb{G} -CSS (1.6) using Krasnoselskii and Banach fixed point theorems. We need after lemma, which indicate the corresponding integral equation.

Lemma 3.1. For given continuous mappings h, g_k ($k = 0, 1, 2, 3$) belongs to $C(\Sigma)$, and the solution of the linear \mathbb{G} -snap problem is

$$\begin{cases} {}^c \mathcal{D}_{t_1^+}^{s;\mathbb{G}} \left({}^c \mathcal{D}_{t_1^+}^{r;\mathbb{G}} \left({}^c \mathcal{D}_{t_1^+}^{p;\mathbb{G}} \left({}^c \mathcal{D}_{t_1^+}^{q;\mathbb{G}} v(t) \right) \right) \right) = h(t), \\ v(t_1) = \int_{t_1}^b g_0(\xi) d\xi, \quad {}^c \mathcal{D}_{t_1^+}^{q;\mathbb{G}} v(t_1) = \int_{t_1}^b g_1(\xi) d\xi, \\ {}^c \mathcal{D}_{t_1^+}^{p;\mathbb{G}} \left({}^c \mathcal{D}_{t_1^+}^{q;\mathbb{G}} v(t_1) \right) = \int_{t_1}^{t_2} g_2(\xi) d\xi, \\ {}^c \mathcal{D}_{t_1^+}^{r;\mathbb{G}} \left({}^c \mathcal{D}_{t_1^+}^{p;\mathbb{G}} \left({}^c \mathcal{D}_{t_1^+}^{q;\mathbb{G}} v(t_1) \right) \right) = \int_{t_1}^{t_2} g_3(\xi) d\xi, \end{cases} \quad (3.1)$$

where $q, p, r, s \in (0, 1]$, are formulated by

$$\begin{aligned} v(t) = & \int_{t_1}^{t_2} g_0(\xi) d\xi + \int_{t_1}^{t_2} \frac{(F_{t_1}(t))^q g_1(\xi)}{\Gamma(q+1)} d\xi + \int_{t_1}^{t_2} \frac{(F_{t_1}(t))^{q+p} g_2(\xi)}{\Gamma(q+p+1)} d\xi \\ & + \int_{t_1}^{t_2} \frac{(F_{t_1}(t))^{q+p+r} g_3(\xi)}{\Gamma(q+p+r+1)} d\xi + \int_{t_1}^t \mathbb{G}'(\xi) \frac{(F_\xi(t))^{q+p+r+s-1}}{\Gamma(q+p+r+k)} h(\xi) d\xi. \end{aligned}$$

Define the vector space

$$X_k = \left\{ v_k \in C(\Sigma, \mathbb{R}) : {}^c \mathcal{D}_{t_1^+}^{q_k;\mathbb{G}} v_k, {}^c \mathcal{D}_{t_1^+}^{p_k;\mathbb{G}} \left({}^c \mathcal{D}_{t_1^+}^{q_k;\mathbb{G}} v_k \right), {}^c \mathcal{D}_{t_1^+}^{r_k;\mathbb{G}} \left({}^c \mathcal{D}_{t_1^+}^{p_k;\mathbb{G}} \left({}^c \mathcal{D}_{t_1^+}^{q_k;\mathbb{G}} v_k(t) \right) \right) \in C(\Sigma, \mathbb{R}) \right\}.$$

Then, X_k , $k = 1, 2$, are Banach spaces via the norm

$$\begin{aligned} \|v_k\| = & \sup_{t \in \Sigma} |v_k(t)| + \sup_{t \in \Sigma} \left| {}^c \mathcal{D}_{t_1^+}^{q_k;\mathbb{G}} v_k(t) \right| + \sup_{t \in \Sigma} \left| {}^c \mathcal{D}_{t_1^+}^{p_k;\mathbb{G}} \left({}^c \mathcal{D}_{t_1^+}^{q_k;\mathbb{G}} v_k(t) \right) \right| \\ & + \sup_{t \in \Sigma} \left| {}^c \mathcal{D}_{t_1^+}^{r_k;\mathbb{G}} \left({}^c \mathcal{D}_{t_1^+}^{p_k;\mathbb{G}} \left({}^c \mathcal{D}_{t_1^+}^{q_k;\mathbb{G}} v_k(t) \right) \right) \right|. \end{aligned}$$

Hence, the product space $X_1 \times X_2$ is a Banach space with the norm

$$\|(v_1, v_2)\| = \max \{ \|v_1\|, \|v_2\| \}.$$

3.1. Existence and uniqueness

In view of Lemma 3.1, the solution of the coupled system (1.6) can be given as

$$\begin{aligned} v_k(t) = & \int_{t_1}^{t_2} g_{k0}(\xi) d\xi + \int_{t_1}^{t_2} \frac{(F_{t_1}(t))^{q_k} g_{k1}(\xi)}{\Gamma(q_k+1)} d\xi \\ & + \int_{t_1}^{t_2} \frac{(F_{t_1}(t))^{q_k+p_k} g_{k2}(\xi)}{\Gamma(q_k+p_k+1)} d\xi + \int_{t_1}^{t_2} \frac{v_{k3}(F_{t_1}(t))^{q_k+p_k+r_k} g_{k3}(\xi)}{\Gamma(q_k+p_k+r_k+1)} d\xi \\ & + \int_{t_1}^t \mathbb{G}'(\xi) \frac{(F_\xi(t))^{q_k+p_k+r_k+s_k-1}}{\Gamma(q_k+p_k+r_k+s_k)} h_{v_1, v_2, k}(\xi) d\xi. \end{aligned}$$

Define the functional $\Lambda_k : X_k \rightarrow \mathbb{R}$, such that

$$\begin{aligned} (\Lambda_k v_k)(t) = & \int_{t_1}^{t_2} g_{k0}(\xi) d\xi + \int_{t_1}^{t_2} \frac{(F_{t_1}(t))^{q_k} g_{k1}(\xi)}{\Gamma(q_k + 1)} d\xi + \int_{t_1}^{t_2} \frac{(F_{t_1}(t))^{q_k+p_k} g_{k2}(\xi)}{\Gamma(q_k + p_k + 1)} d\xi \\ & + \int_{t_1}^{t_2} \frac{(F_{t_1}(t))^{q_k+p_k+r_k} g_{k3}(\xi)}{\Gamma(q_k + p_k + r_k + 1)} d\xi + \int_{t_1}^t \mathbb{G}'(\xi) \frac{(F_{t_1}(\xi))^{q_k+p_k+r_k+s_k-1} h_{v_1, v_2, k}(\xi)}{\Gamma(q_k + p_k + r_k + s_k)} d\xi. \end{aligned} \quad (3.2)$$

Under some conditions, we show next that the functional $\Lambda : X_1 \times X_2 \rightarrow \mathbb{R}^2$ is a contraction, where Λ is given as

$$\Lambda(v_1, v_2) = (\Lambda_1(v_1, v_2), \Lambda_2(v_1, v_2)).$$

Theorem 3.2. Let $h_k \in C(\Sigma \times \mathbb{R}^8)$, ($k = 1, 2$) be continuous functions. Moreover, assume that

(H1) there exist real constants $\ell_k > 0$, ($k = 1, 2$), so that

$$|h_k(t, v_1, v_2, \dots, v_8) - h_k(t, v_1^*, v_2^*, \dots, v_8^*)| \leq \ell_k \sum_{i=1}^8 |v_i - v_i^*|, \quad (3.3)$$

for any $t \in \Sigma$, $v_i, v_i^* \in C([a, b])$ and $i = 1, 2, \dots, 8$.

Then, the fractional \mathbb{G} -CSS (1.6) admits a unique solution on Σ if $\Phi \ell < 1$, whenever $\ell = \max\{\ell_1, \ell_2\}$, $\Phi = \max\{\Phi_1, \Phi_2\}$ and

$$\begin{aligned} \Phi_k = & \frac{(F_{t_1}(t_2))^{q_k+p_k+r_k+s_k}}{\Gamma(q_k + p_k + r_k + s_k + 1)} + \frac{(F_{t_1}(t_2))^{p_k+r_k+s_k}}{\Gamma(p_k + r_k + s_k + 1)} \\ & + \frac{(F_{t_1}(t_2))^{r_k+s_k}}{\Gamma(r_k + s_k + 1)} + \frac{(F_{t_1}(t_2))^{s_k}}{\Gamma(s_k + 1)}, \end{aligned} \quad (3.4)$$

with $\Phi_k \ell_k < 1$.

Proof. First of all, we define a closed bounded ball

$$\mathbb{B}_\varepsilon = \{(v_1, v_2) \in X_1 \times X_2 : \|(v_1, v_2)\| \leq \varepsilon\},$$

satisfying

$$\varepsilon \geq \max \left\{ \frac{\Delta_1 + h_1^0 \Phi_1}{(1 - \ell_1 \Phi_1)}, \frac{\Delta_2 + h_2^0 \Phi_2}{(1 - \ell_2 \Phi_2)} \right\}, \quad (3.5)$$

where

$$\begin{aligned} \Delta_k = & M_{k0} + M_{k1} \left(1 + \frac{(F_{t_1}(t_2))^{q_k}}{\Gamma(q_k + 1)} \right) \\ & + M_{k2} \left(1 + \frac{(F_{t_1}(t_2))^{p_k}}{\Gamma(p_k + 1)} + \frac{(F_{t_1}(t_2))^{q_k+p_k}}{\Gamma(q_k + p_k + 1)} \right) \\ & + M_{k3} \left(1 + \frac{(F_{t_1}(t_2))^{r_k}}{\Gamma(r_k + 1)} + \frac{(F_{t_1}(t_2))^{p_k+r_k}}{\Gamma(p_k + r_k + 1)} + \frac{(F_{t_1}(t_2))^{q_k+p_k+r_k}}{\Gamma(q_k + p_k + r_k + 1)} \right), \end{aligned} \quad (3.6)$$

and

$$M_{kj} = \sup_{t \in \Sigma} \int_{t_1}^{t_2} |g_{kj}(\xi)| d\xi, \quad (j = 0, 1, 2, 3),$$

$$h_k^0 = \sup_{t \in \Sigma} |h_k(t, 0, 0, 0, 0, 0, 0, 0, 0)|, \quad (k = 1, 2). \quad (3.7)$$

Now, define the operator

$$\Lambda(v_1, v_2) = (\Lambda_1(v_1, v_2), \Lambda_2(v_1, v_2)), \quad \forall (v_1, v_2) \in X_1 \times X_2,$$

where Λ_k is given in (3.2). To show that $\Lambda(\mathbb{B}_\varepsilon) \subset \mathbb{B}_\varepsilon$, by using hypotheses (H1), for $(v_1, v_2) \in \mathbb{B}_\varepsilon$ and $t \in \Sigma$, we get

$$\begin{aligned} |\Lambda_k(v_1, v_2)(t)| &\leq \int_{t_1}^{t_2} |g_{k0}(\xi)| \, d\xi + \int_{t_1}^{t_2} \frac{(F_{t_1}(t))^{q_k} |g_{k1}(\xi)|}{\Gamma(q_k + 1)} \, d\xi \\ &\quad + \int_{t_1}^{t_2} \frac{(F_{t_1}(t))^{q_k + p_k} |g_{k2}(\xi)|}{\Gamma(q_k + p_k + 1)} \, d\xi + \int_{t_1}^{t_2} \frac{(F_{t_1}(t))^{q_k + p_k + r_k} |g_{k3}(\xi)|}{\Gamma(q_k + p_k + r_k + 1)} \, d\xi \\ &\quad + \mathcal{I}_{t_1^+}^{q_k + p_k + r_k + s_k; \mathbb{G}} \left(|h_{v_1, v_2, k}(t) - h_k(t, 0, 0, 0, 0, 0, 0, 0, 0)| \right. \\ &\quad \left. + |h_k(t, 0, 0, 0, 0, 0, 0, 0, 0)| \right) \\ &\leq \int_a^b |g_{k0}(\xi)| \, d\xi + \int_{t_1}^{t_2} \frac{(F_{t_1}(t))^{q_k} |g_{k1}(\xi)|}{\Gamma(q_k + 1)} \, d\xi \\ &\quad + \int_{t_1}^{t_2} \frac{(F_{t_1}(t))^{q_k + p_k} |g_{k2}(\xi)|}{\Gamma(q_k + p_k + 1)} \, d\xi + \int_{t_1}^{t_2} \frac{(F_{t_1}(t))^{q_k + p_k + r_k} |g_{k3}(\xi)|}{\Gamma(q_k + p_k + r_k + 1)} \, d\xi \\ &\quad + \mathcal{I}_{t_1^+}^{q_k + p_k + r_k + s_k; \mathbb{G}} \left(\ell_k (|v_1(t)| + |v_2(t)| \right. \\ &\quad \left. + \left| {}^c \mathcal{D}_{t_1^+}^{q_1; \mathbb{G}} v_1(t) \right| + \left| {}^c \mathcal{D}_{t_1^+}^{q_2; \mathbb{G}} v_2(t) \right| \right. \\ &\quad \left. + \left| {}^c \mathcal{D}_{t_1^+}^{p_1; \mathbb{G}} \left({}^c \mathcal{D}_{t_1^+}^{q_1; \mathbb{G}} v_1(t) \right) \right| + \left| {}^c \mathcal{D}_{t_1^+}^{p_2; \mathbb{G}} \left({}^c \mathcal{D}_{t_1^+}^{q_2; \mathbb{G}} v_2(t) \right) \right| \right. \\ &\quad \left. + \left| {}^c \mathcal{D}_{t_1^+}^{r_1; \mathbb{G}} \left({}^c \mathcal{D}_{t_1^+}^{p_1; \mathbb{G}} \left({}^c \mathcal{D}_{a^+}^{q_1; \mathbb{G}} v_1(t) \right) \right) \right| \right. \\ &\quad \left. + \left| {}^c \mathcal{D}_{t_1^+}^{r_2; \mathbb{G}} \left({}^c \mathcal{D}_{t_1^+}^{p_2; \mathbb{G}} \left({}^c \mathcal{D}_{t_1^+}^{q_2; \mathbb{G}} v_2(t) \right) \right) \right| \right) \\ &\quad \left. + |h_k(t, 0, 0, 0, 0, 0, 0, 0, 0)| \right) \\ &\leq M_{k0} + M_{k1} \frac{(F_{t_1}(t_2))^{q_k}}{\Gamma(q_k + 1)} + M_{k2} \frac{(F_{t_1}(t_2))^{q_k + p_k}}{\Gamma(q_k + p_k + 1)} \\ &\quad + M_{k3} \frac{(F_{t_1}(t_2))^{q_k + p_k + r_k}}{\Gamma(q_k + p_k + r_k + 1)} \\ &\quad + \frac{(F_{t_1}(t_2))^{q_k + p_k + r_k + s_k}}{\Gamma(q_k + p_k + r_k + s_k + 1)} \left(\ell_k (\|v_1\| + \|v_2\|) + h_k^0 \right). \end{aligned} \quad (3.8)$$

Also,

$$\begin{aligned} |{}^c \mathcal{D}_{t_1^+}^{q_k; \mathbb{G}} (\Lambda_k(v_1, v_2)(t))| &\leq \int_{t_1}^{t_2} |g_{k1}(\xi)| \, d\xi + \int_{t_1}^{t_2} \frac{(F_{t_1}(t))^{p_k} |g_{k2}(\xi)|}{\Gamma(p_k + 1)} \, d\xi \\ &\quad + \int_{t_1}^{t_2} \frac{(F_{t_1}(t))^{p_k + r_k} |g_{k3}(\xi)|}{\Gamma(p_k + r_k + 1)} \, d\xi \end{aligned}$$

$$\begin{aligned}
& + \mathcal{I}_{t_1^+}^{p_k+r_k+s_k;\mathbb{G}} \left(|h_{v_1, v_2, k}(t) - h_k(t, 0, 0, 0, 0, 0, 0, 0, 0)| \right. \\
& \left. + |h_k(t, 0, 0, 0, 0, 0, 0, 0, 0)| \right) \\
\leq & \int_{t_1}^{t_2} |g_{k1}(\xi)| d\xi + \int_{t_1}^{t_2} \frac{(F_{t_1}(t))^{p_k} |g_{k2}(\xi)|}{\Gamma(p_k + 1)} d\xi + \int_{t_1}^{t_2} \frac{(F_{t_1}(t))^{p_k+r_k} |g_{k3}(\xi)|}{\Gamma(p_k + r_k + 1)} d\xi \\
& + \mathcal{I}_{t_1^+}^{p_k+r_k+s_k;\mathbb{G}} \left(\ell_k (|v_1(t)| + |v_2(t)| + |{}^c\mathcal{D}_{t_1^+}^{q_1;\mathbb{G}} v_1(t)| + |{}^c\mathcal{D}_{t_1^+}^{q_2;\mathbb{G}} v_2(t)| \right. \\
& \left. + \left| {}^c\mathcal{D}_{t_1^+}^{p_1;\mathbb{G}} \left({}^c\mathcal{D}_{t_1^+}^{q_1;\mathbb{G}} v_1(t) \right) \right| + \left| {}^c\mathcal{D}_{t_1^+}^{p_2;\mathbb{G}} \left({}^c\mathcal{D}_{t_1^+}^{q_2;\mathbb{G}} v_2(t) \right) \right| \right. \\
& \left. + \left| {}^c\mathcal{D}_{t_1^+}^{r_1;\mathbb{G}} \left({}^c\mathcal{D}_{t_1^+}^{p_1;\mathbb{G}} \left({}^c\mathcal{D}_{t_1^+}^{q_1;\mathbb{G}} v_1(t) \right) \right) \right| \right. \\
& \left. + \left| {}^c\mathcal{D}_{t_1^+}^{r_2;\mathbb{G}} \left({}^c\mathcal{D}_{t_1^+}^{p_2;\mathbb{G}} \left({}^c\mathcal{D}_{t_1^+}^{q_2;\mathbb{G}} v_2(t) \right) \right) \right| \right) \\
& + |h_k(t, 0, 0, 0, 0, 0, 0, 0, 0)| \\
\leq & M_{k1} + M_{k2} \frac{(F_{t_1}(t_2))^{p_k}}{\Gamma(p_k + 1)} + M_{k3} \frac{(F_{t_1}(t_2))^{p_k+r_k}}{\Gamma(p_k + r_k + 1)} \\
& + \mathcal{I}_{t_1^+}^{p_k+r_k+s_k;\mathbb{G}} \left(\ell_k (\|v_1\| + \|v_2\|) + h_k^0 \right) \\
\leq & M_{k1} + M_{k2} \frac{(F_{t_1}(t_2))^{p_k}}{\Gamma(p_k + 1)} + M_{k3} \frac{(F_{t_1}(t_2))^{p_k+r_k}}{\Gamma(p_k + r_k + 1)} \\
& + \frac{(F_{t_1}(t_2))^{p_k+r_k+s_k}}{\Gamma(p_k + r_k + s_k + 1)} \left(\ell_k (\|v_1\| + \|v_2\|) + h_k^0 \right), \tag{3.9}
\end{aligned}$$

$$\begin{aligned}
\left| {}^c\mathcal{D}_{t_1^+}^{p_k;\mathbb{G}} \left({}^c\mathcal{D}_{t_1^+}^{q_k;\mathbb{G}} (\Lambda_k(v_1, v_2)(t)) \right) \right| & \leq M_{k2} + M_{k3} \frac{(F_{t_1}(t_2))^{r_k}}{\Gamma(r_k + 1)} \\
& + \frac{(F_{t_1}(t_2))^{r_k+s_k}}{\Gamma(r_k + s_k + 1)} \left(\ell_k (\|v_1\| + \|v_2\|) + h_k^0 \right), \tag{3.10}
\end{aligned}$$

and

$$\begin{aligned}
& \left| {}^c\mathcal{D}_{t_1^+}^{r_k;\mathbb{G}} \left({}^c\mathcal{D}_{t_1^+}^{p_k;\mathbb{G}} \left({}^c\mathcal{D}_{t_1^+}^{q_k;\mathbb{G}} (\Lambda_k(v_1, v_2)(t)) \right) \right) \right| \\
& \leq M_{k3} + \frac{(F_{t_1}(t_2))^{s_k}}{\Gamma(s_k + 1)} \left(\ell_k (\|v_1\| + \|v_2\|) + h_k^0 \right). \tag{3.11}
\end{aligned}$$

Thus, due to (3.8)–(3.11) and (3.5), we obtain

$$\begin{aligned}
\|\Lambda_k(v_1, v_2)\| & = \sup_{t \in \Sigma} |\Lambda_k(v_1, v_2)(t)| + \sup_{t \in \Sigma} \left| {}^c\mathcal{D}_{t_1^+}^{q_k;\mathbb{G}} (\Lambda_k(v_1, v_2))(t) \right| \\
& \quad + \sup_{t \in \Sigma} \left| {}^c\mathcal{D}_{t_1^+}^{p_k;\mathbb{G}} \left({}^c\mathcal{D}_{t_1^+}^{q_k;\mathbb{G}} (\Lambda_k(v_1, v_2))(t) \right) \right| \\
& \quad + \sup_{t \in \Sigma} \left| {}^c\mathcal{D}_{t_1^+}^{r_k;\mathbb{G}} \left({}^c\mathcal{D}_{t_1^+}^{p_k;\mathbb{G}} \left({}^c\mathcal{D}_{t_1^+}^{q_k;\mathbb{G}} (\Lambda_k(v_1, v_2))(t) \right) \right) \right| \\
& \leq \left[M_{k0} + M_{k1} \left(1 + \frac{(F_{t_1}(t_2))^{q_k}}{\Gamma(q_k + 1)} \right) \right]
\end{aligned}$$

$$\begin{aligned}
& + M_{k2} \left(1 + \frac{(F_{l_1}(t_2))^{p_k}}{\Gamma(p_k + 1)} + \frac{(F_{l_1}(t_2))^{q_k + p_k}}{\Gamma(q_k + p_k + 1)} \right) \\
& + M_{k3} \left(1 + \frac{(F_{l_1}(t_2))^{r_k}}{\Gamma(r_k + 1)} + \frac{(F_{l_1}(t_2))^{p_k + r_k}}{\Gamma(p_k + r_k + 1)} + \frac{(F_{l_1}(t_2))^{q_k + p_k + r_k}}{\Gamma(q_k + p_k + r_k + 1)} \right) \\
& + (\ell_k \| (v_1, v_2) \| + h_k^0) \left[\frac{(F_{l_1}(t_2))^{q_k + p_k + r_k + s_k}}{\Gamma(q_k + p_k + r_k + s_k + 1)} \right. \\
& \left. + \frac{(F_{l_1}(t_2))^{p_k + r_k + s_k}}{\Gamma(p_k + r_k + s_k + 1)} + \frac{(F_{l_1}(t_2))^{r_k + s_k}}{\Gamma(r_k + s_k + 1)} + \frac{(F_{l_1}(t_2))^{s_k}}{\Gamma(s_k + 1)} \right] \\
\leq & \left[M_{k0} + M_{k1} \left(1 + \frac{(F_{l_1}(t_2))^{q_k}}{\Gamma(q_k + 1)} \right) \right. \\
& + M_{k2} \left(1 + \frac{(F_{l_1}(t_2))^{p_k}}{\Gamma(p_k + 1)} + \frac{(F_{l_1}(t_2))^{q_k + p_k}}{\Gamma(q_k + p_k + 1)} \right) \\
& + M_{k3} \left(1 + \frac{(F_{l_1}(t_2))^{r_k}}{\Gamma(r_k + 1)} + \frac{(F_{l_1}(t_2))^{p_k + r_k}}{\Gamma(p_k + r_k + 1)} + \frac{(F_{l_1}(t_2))^{q_k + p_k + r_k}}{\Gamma(q_k + p_k + r_k + 1)} \right) \\
& \left. + (\ell_k \varepsilon + h_k^0) \left[\frac{(F_{l_1}(t_2))^{q_k + p_k + r_k + s_k}}{\Gamma(q_k + p_k + r_k + s_k + 1)} + \frac{(F_{l_1}(t_2))^{p_k + r_k + s_k}}{\Gamma(p_k + r_k + s_k + 1)} \right. \right. \\
& \left. \left. + \frac{(F_{l_1}(t_2))^{r_k + s_k}}{\Gamma(r_k + s_k + 1)} + \frac{(F_{l_1}(t_2))^{s_k}}{\Gamma(s_k + 1)} \right] \right] \\
\leq & \Delta_k + (\ell_k \varepsilon + h_k^0) \Phi_k \leq \varepsilon.
\end{aligned}$$

Hence, we deduce that $\|\Lambda(v_1, v_2)\| \leq \varepsilon$, for $(v_1, v_2) \in \mathbb{B}_\varepsilon$, so $\Lambda(\mathbb{B}_\varepsilon) \subset \mathbb{B}_\varepsilon$. Next, we prove that Λ is a contraction operator, by using (H1), for $(v_1, v_2), (u_1, u_2) \in \mathbb{B}_\varepsilon$ and $t \in \Sigma$, we have

$$\begin{aligned}
& |\Lambda_k(v_1, v_2)(t) - \Lambda_k(u_1, u_2)(t)| \\
& \leq \mathcal{I}_{t_1^+}^{q_k + p_k + r_k + s_k; \mathbb{G}} |h_{v_1, v_2, k}(t) - h_{u_1, u_2, k}(t)| \\
& \leq \mathcal{I}_{t_1^+}^{q_k + p_k + r_k + s_k; \mathbb{G}} \left(\ell_k (|v_1(t) - u_1(t)| + |v_2(t) - u_2(t)| \right. \\
& \quad + \left| {}^c \mathcal{D}_{t_1^+}^{q_1; \mathbb{G}} v_1(t) - {}^c \mathcal{D}_{t_1^+}^{q_1; \mathbb{G}} u_1(t) \right| + \left| {}^c \mathcal{D}_{t_1^+}^{q_2; \mathbb{G}} v_2(t) - {}^c \mathcal{D}_{t_1^+}^{q_2; \mathbb{G}} u_2(t) \right| \\
& \quad + \left| {}^c \mathcal{D}_{t_1^+}^{p_1; \mathbb{G}} \left({}^c \mathcal{D}_{t_1^+}^{q_1; \mathbb{G}} v_1(t) \right) - {}^c \mathcal{D}_{t_1^+}^{p_1; \mathbb{G}} \left({}^c \mathcal{D}_{t_1^+}^{q_1; \mathbb{G}} u_1(t) \right) \right| \\
& \quad + \left| {}^c \mathcal{D}_{t_1^+}^{p_2; \mathbb{G}} \left({}^c \mathcal{D}_{t_1^+}^{q_2; \mathbb{G}} v_2(t) \right) - {}^c \mathcal{D}_{t_1^+}^{p_2; \mathbb{G}} \left({}^c \mathcal{D}_{t_1^+}^{q_2; \mathbb{G}} u_2(t) \right) \right| \\
& \quad + \left| {}^c \mathcal{D}_{t_1^+}^{r_1; \mathbb{G}} \left({}^c \mathcal{D}_{t_1^+}^{p_1; \mathbb{G}} \left({}^c \mathcal{D}_{t_1^+}^{q_1; \mathbb{G}} v_1(t) \right) \right) \right. \\
& \quad \left. - {}^c \mathcal{D}_{t_1^+}^{r_1; \mathbb{G}} \left({}^c \mathcal{D}_{t_1^+}^{p_1; \mathbb{G}} \left({}^c \mathcal{D}_{t_1^+}^{q_1; \mathbb{G}} u_1(t) \right) \right) \right| \\
& \quad + \left| {}^c \mathcal{D}_{t_1^+}^{r_2; \mathbb{G}} \left({}^c \mathcal{D}_{t_1^+}^{p_2; \mathbb{G}} \left({}^c \mathcal{D}_{t_1^+}^{q_2; \mathbb{G}} v_2(t) \right) \right) \right. \\
& \quad \left. - {}^c \mathcal{D}_{t_1^+}^{r_2; \mathbb{G}} \left({}^c \mathcal{D}_{t_1^+}^{p_2; \mathbb{G}} \left({}^c \mathcal{D}_{t_1^+}^{q_2; \mathbb{G}} u_2(t) \right) \right) \right| \Big) \\
& \leq \mathcal{I}_{t_1^+}^{q_k + p_k + r_k + s_k; \mathbb{G}} (\ell_k (\|v_1 - u_1\| + \|v_2 - u_2\|))
\end{aligned}$$

$$\leq \frac{(F_{t_1}(t_2))^{q_k+p_k+r_k+s_k}}{\Gamma(q_k+p_k+r_k+s_k+1)} (\ell_k (\|v_1 - u_1\| + \|v_2 - u_2\|)), \quad (3.12)$$

$$\begin{aligned} & \left| {}^c \mathcal{D}_{t_1^+}^{q_k; \mathbb{G}} (\Lambda_k(v_1, v_2)) (t) - {}^c \mathcal{D}_{t_1^+}^{q_k; \mathbb{G}} (\Lambda_k(u_1, u_2)) (t) \right| \\ & \leq \mathcal{I}_{t_1^+}^{p_k+r_k+s_k; \mathbb{G}} \left| h_{v_1, v_2, k}(t) - h_{u_1, u_2, k}(t) \right| \\ & \leq \mathcal{I}_{t_1^+}^{p_k+r_k+s_k; \mathbb{G}} \left(\ell_k (|v_1(t) - u_1(t)| + |v_2(t) - u_2(t)| \right. \\ & \quad + \left| {}^c \mathcal{D}_{t_1^+}^{q_1; \mathbb{G}} v_1(t) - {}^c \mathcal{D}_{t_1^+}^{q_1; \mathbb{G}} u_1(t) \right| \\ & \quad + \left| {}^c \mathcal{D}_{t_1^+}^{q_2; \mathbb{G}} v_2(t) - {}^c \mathcal{D}_{t_1^+}^{q_2; \mathbb{G}} u_2(t) \right| \\ & \quad + \left| {}^c \mathcal{D}_{t_1^+}^{p_1; \mathbb{G}} \left({}^c \mathcal{D}_{t_1^+}^{q_1; \mathbb{G}} v_1(t) \right) - {}^c \mathcal{D}_{t_1^+}^{p_1; \mathbb{G}} \left({}^c \mathcal{D}_{t_1^+}^{q_1; \mathbb{G}} u_1(t) \right) \right| \\ & \quad + \left| {}^c \mathcal{D}_{t_1^+}^{p_2; \mathbb{G}} \left({}^c \mathcal{D}_{t_1^+}^{q_2; \mathbb{G}} v_2(t) \right) - {}^c \mathcal{D}_{t_1^+}^{p_2; \mathbb{G}} \left({}^c \mathcal{D}_{t_1^+}^{q_2; \mathbb{G}} u_2(t) \right) \right| \\ & \quad + \left| {}^c \mathcal{D}_{t_1^+}^{r_1; \mathbb{G}} \left({}^c \mathcal{D}_{t_1^+}^{p_1; \mathbb{G}} \left({}^c \mathcal{D}_{t_1^+}^{q_1; \mathbb{G}} v_1(t) \right) \right) \right. \\ & \quad \left. - {}^c \mathcal{D}_{t_1^+}^{r_1; \mathbb{G}} \left({}^c \mathcal{D}_{t_1^+}^{p_1; \mathbb{G}} \left({}^c \mathcal{D}_{t_1^+}^{q_1; \mathbb{G}} u_1(t) \right) \right) \right| \\ & \quad + \left| {}^c \mathcal{D}_{t_1^+}^{r_2; \mathbb{G}} \left({}^c \mathcal{D}_{t_1^+}^{p_2; \mathbb{G}} \left({}^c \mathcal{D}_{t_1^+}^{q_2; \mathbb{G}} v_2(t) \right) \right) \right. \\ & \quad \left. - {}^c \mathcal{D}_{t_1^+}^{r_2; \mathbb{G}} \left({}^c \mathcal{D}_{t_1^+}^{p_2; \mathbb{G}} \left({}^c \mathcal{D}_{t_1^+}^{q_2; \mathbb{G}} u_2(t) \right) \right) \right| \Big) \\ & \leq \mathcal{I}_{t_1^+}^{p_k+r_k+s_k; \mathbb{G}} (\ell_k (\|v_1 - u_1\| + \|v_2 - u_2\|)) \\ & \leq \frac{(F_{t_1}(t_2))^{p_k+r_k+s_k}}{\Gamma(p_k+r_k+s_k+1)} (\ell_k (\|v_1 - u_1\| + \|v_2 - u_2\|)), \quad (3.13) \end{aligned}$$

$$\begin{aligned} & \left| {}^c \mathcal{D}_{t_1^+}^{p_k; \mathbb{G}} \left({}^c \mathcal{D}_{t_1^+}^{q_k; \mathbb{G}} (\Lambda_k(v_1, v_2)) \right) (t) - {}^c \mathcal{D}_{t_1^+}^{p_k; \mathbb{G}} \left({}^c \mathcal{D}_{t_1^+}^{q_k; \mathbb{G}} (\Lambda_k(u_1, u_2)) \right) (t) \right| \\ & \leq \frac{(F_{t_1}(t_2))^{r_k+s_k}}{\Gamma(r_k+s_k+1)} (\ell_k (\|v_1 - u_1\| + \|v_2 - u_2\|)), \quad (3.14) \end{aligned}$$

and

$$\begin{aligned} & \left| {}^c \mathcal{D}_{t_1^+}^{r_k; \mathbb{G}} \left({}^c \mathcal{D}_{t_1^+}^{p_k; \mathbb{G}} \left({}^c \mathcal{D}_{t_1^+}^{q_k; \mathbb{G}} (\Lambda_k(v_1, v_2)) \right) \right) (t) - {}^c \mathcal{D}_{t_1^+}^{r_k; \mathbb{G}} \left({}^c \mathcal{D}_{t_1^+}^{p_k; \mathbb{G}} \left({}^c \mathcal{D}_{t_1^+}^{q_k; \mathbb{G}} (\Lambda_k(u_1, u_2)) \right) \right) (t) \right| \\ & \leq \frac{(F_{t_1}(t_2))^{s_k}}{\Gamma(s_k+1)} (\ell_k (\|v_1 - u_1\| + \|v_2 - u_2\|)). \quad (3.15) \end{aligned}$$

Therefore, due to (3.12)–(3.15), we get

$$\begin{aligned} & \|\Lambda_k(v_1, v_2) - \Lambda_k(u_1, u_2)\| \\ & \leq \left[\frac{(F_{t_1}(t_2))^{q_k+p_k+r_k+s_k}}{\Gamma(q_k+p_k+r_k+s_k+1)} + \frac{(F_{t_1}(t_2))^{p_k+r_k+s_k}}{\Gamma(p_k+r_k+s_k+1)} \right] \end{aligned}$$

$$\begin{aligned} & + \frac{(F_{t_1}(t_2))^{r_k+s_k}}{\Gamma(r_k+s_k+1)} + \frac{(F_{t_1}(t_2))^{s_k}}{\Gamma(s_k+1)} \left[(\ell_k (\|v_1 - u_1\| + \|v_2 - u_2\|)) \right. \\ & \left. \leq \Phi_k \ell_k (\|v_1 - u_1\| + \|v_2 - u_2\|). \right. \end{aligned}$$

Consequently,

$$\|\Lambda(v_1, v_2) - \Lambda(u_1, u_2)\| \leq \Phi \ell \| (v_1, u_1) - (v_2, u_2) \|.$$

Since $\Phi \ell < 1$, therefore, Λ is a contraction operator. Thus, by Banach's fixed point Theorem 2.3, the operator Λ has a unique fixed point, which is the unique solution of fractional G-snap system (1.6) and the proof is finished. \square

Next, we are ready to study the existence of solution of fractional \mathbb{G} -(CSS) (1.6). For this regard, we define the operators $\Omega, \Pi : X_1 \times X_2 \rightarrow \mathbb{R}^2$, $\Omega = (\Omega_1, \Omega_2)$, $\Pi = (\Pi_1, \Pi_2)$, such that $\Lambda_k = \Omega_k + \Pi_k$, where

$$(\Omega_k v_k)(t) = \int_{t_1}^t \mathbb{G}'(\xi) \frac{(F_{t_1}(t))^{q_k+p_k+r_k+s_k-1}}{\Gamma(q_k+p_k+r_k+s_k)} h_{v_1, v_2, k}(\xi) d\xi, \quad (3.16)$$

and

$$\begin{aligned} (\Pi_k v_k)(t) &= \int_{t_1}^{t_2} g_{k0}(\xi) d\xi + \frac{(F_{t_1}(t))^{q_k}}{\Gamma(q_k+1)} \int_{t_1}^{t_2} g_{k1}(\xi) d\xi \\ &+ \int_{t_1}^{t_2} \frac{(F_{t_1}(t))^{q_k+p_k} g_{k2}(\xi)}{\Gamma(q_k+p_k+1)} d\xi + \int_{t_1}^{t_2} \frac{(F_{t_1}(t))^{q_k+p_k+r_k} g_{k3}(\xi)}{\Gamma(q_k+p_k+r_k+1)} d\xi. \end{aligned} \quad (3.17)$$

Theorem 3.3. Let $h_k \in C(\Sigma \times \mathbb{R}^8)$, ($k = 1, 2$) be continuous functions. Moreover, assume that

(H2) there exist real constants $\lambda_k > 0$, ($k = 1, 2$), so that

$$|h_k(t, v_1, v_2, \dots, v_8)| \leq \lambda_k, \quad \forall t \in \Sigma \ \& \ v_i \in C(\Sigma), \ (i = 1, 2, \dots, 8).$$

Then, the fractional \mathbb{G} -CSS (1.6) has at least one solution on Σ .

Proof. At the beginning, we define a closed bounded ball

$$\mathbb{B}_r = \{(v_1, v_2) \in X_1 \times X_2 : \|(v_1, v_2)\| \leq r\},$$

which satisfying

$$r \geq \max \{r_1, r_2\}, \quad (3.18)$$

where

$$\begin{aligned} r_k &\geq M_{k0} + M_{k1} \left(1 + \frac{(F_{t_1}(t_2))^{q_k}}{\Gamma(q_k+1)} \right) \\ &+ M_{k2} \left(1 + \frac{(F_{t_1}(t_2))^{p_k}}{\Gamma(p_k+1)} + \frac{(F_{t_1}(t_2))^{q_k+p_k}}{\Gamma(q_k+p_k+1)} \right) \\ &+ M_{k3} \left(1 + \frac{(F_{t_1}(t_2))^{r_k}}{\Gamma(r_k+1)} + \frac{(F_{t_1}(t_2))^{p_k+r_k}}{\Gamma(p_k+r_k+1)} + \frac{(F_{t_1}(t_2))^{q_k+p_k+r_k}}{\Gamma(q_k+p_k+r_k+1)} \right) \end{aligned}$$

$$+ \frac{(F_{t_1}(t_2))^{q_k+p_k+r_k+s_k}}{\Gamma(q_k+p_k+r_k+s_k+1)} \lambda_k.$$

Firstly, we will prove $\Omega v + \Pi u \in \mathbb{B}_r$. By using (H2), for $v = (v_1, v_2), u = (u_1, u_2) \in \mathbb{B}_r$ and $t \in [a, b]$, we have

$$\|\Omega_k(v_1, v_2)\| \leq \frac{(F_{t_1}(t_2))^{q_k+p_k+r_k+s_k}}{\Gamma(q_k+p_k+r_k+s_k+1)} \lambda_k, \quad (3.19)$$

and

$$\begin{aligned} \|\Pi_k(u_1, u_2)\| &\leq M_{k0} + M_{k1} \left(1 + \frac{(F_{t_1}(t_2))^{q_k}}{\Gamma(q_k+1)} \right) \\ &+ M_{k2} \left(1 + \frac{(F_{t_1}(t_2))^{p_k}}{\Gamma(p_k+1)} + \frac{(F_{t_1}(t_2))^{q_k+p_k}}{\Gamma(q_k+p_k+1)} \right) \\ &+ M_{k3} \left(1 + \frac{(F_{t_1}(t_2))^{r_k}}{\Gamma(r_k+1)} + \frac{(F_{t_1}(t_2))^{p_k+r_k}}{\Gamma(p_k+r_k+1)} + \frac{(F_{t_1}(t_2))^{q_k+p_k+r_k}}{\Gamma(q_k+p_k+r_k+1)} \right). \end{aligned} \quad (3.20)$$

Hence, from (3.19) and (3.20), we have

$$\begin{aligned} &\|\Omega_k(v_1, v_2) + \Pi_k(u_1, u_2)\| \\ &\leq M_{k0} + M_{k1} \left(1 + \frac{(F_{t_1}(t_2))^{q_k}}{\Gamma(q_k+1)} \right) \\ &+ M_{k2} \left(1 + \frac{(F_{t_1}(t_2))^{p_k}}{\Gamma(p_k+1)} + \frac{(F_{t_1}(t_2))^{q_k+p_k}}{\Gamma(q_k+p_k+1)} \right) \\ &+ M_{k3} \left(1 + \frac{(F_{t_1}(t_2))^{r_k}}{\Gamma(r_k+1)} + \frac{(F_{t_1}(t_2))^{p_k+r_k}}{\Gamma(p_k+r_k+1)} + \frac{(F_{t_1}(t_2))^{q_k+p_k+r_k}}{\Gamma(q_k+p_k+r_k+1)} \right) \\ &+ \frac{(F_{t_1}(t_2))^{q_k+p_k+r_k+s_k}}{\Gamma(q_k+p_k+r_k+s_k+1)} \lambda_k \leq r. \end{aligned}$$

Then,

$$\|\Omega(v_1, v_2) + \Pi(u_1, u_2)\| \leq r,$$

this implying that $\Omega v + \Pi u \in \mathbb{B}_r$.

Secondly, we will prove that the operator Π is a contraction mapping. It is clearly that Π_k is a contraction with the constant zero. Thus, Π is a contraction operator.

Third, we will prove that the operator Ω is a continuous. Let $(v_{n,1}, v_{n,2})$ be a sequence of a bounded ball \mathbb{B}_r , such that $(v_{n,1}, v_{n,2}) \rightarrow (v_1, v_2)$ as $n \rightarrow \infty$ in \mathbb{B}_r , we find that

$$\begin{aligned} &|(\Omega_k(v_{n,1}, v_{n,2}))(t) - (\Omega_k(v_1, v_2))(t)| \\ &\leq \int_{t_1}^t \frac{\mathbb{G}'(\xi)(F_{t_1}(t))^{q_k+p_k+r_k+s_k-1}}{\Gamma(q_k+p_k+r_k+s_k)} |h_{v_{n,1}, v_{n,2}, k}(\xi) - h_{v_1, v_2, k}(\xi)| d\xi \\ &\leq \frac{(F_{t_1}(t_2))^{q_k+p_k+r_k+s_k}}{\Gamma(q_k+p_k+r_k+s_k+1)} \|h_{v_{n,1}, v_{n,2}, k}(\cdot) - h_{v_1, v_2, k}(\cdot)\|. \end{aligned}$$

By continuity of $h_{v_1, v_2, k}$, we have

$$\|\Omega_k(v_{n,1}, v_{n,2}) - \Omega_k(v_1, v_2)\| \rightarrow 0,$$

as $n \rightarrow \infty$. So, Ω is a continuous operator.

Fourth, we will prove that the operator Ω is a compact operator. By using (H2), for $v = (v_1, v_2) \in \mathbb{B}_r$ and $t_g, t_y \in \Sigma$ with $t_g < t_y$, we have

$$\begin{aligned}
 & |(\Omega_k(v_1, v_2))(t_y) - (\Omega_k(v_1, v_2))(t_g)| \\
 & \leq \left| \int_{t_1}^{t_y} \frac{\mathbb{G}'(\xi)(F_{t_1}(t_2))^{q_k+p_k+r_k+s_k-1}}{\Gamma(q_k+p_k+r_k+s_k)} h_{v_1, v_2, k}(\xi) d\xi \right. \\
 & \quad \left. - \int_{t_1}^{t_g} \frac{\mathbb{G}'(\xi)(F_{t_1}(t_1))^{q_k+p_k+r_k+s_k-1}}{\Gamma(q_k+p_k+r_k+s_k)} h_{v_1, v_2, k}(\xi) d\xi \right| \\
 & \leq \left| \int_{t_1}^{t_g} \frac{\mathbb{G}'(\xi)(F_{t_1}(t_2))^{q_k+p_k+r_k+s_k-1}}{\Gamma(q_k+p_k+r_k+s_k)} h_{v_1, v_2, k}(\xi) d\xi \right. \\
 & \quad \left. - \int_{t_1}^{t_g} \frac{\mathbb{G}'(\xi)(F_{t_1}(t_1))^{q_k+p_k+r_k+s_k-1}}{\Gamma(q_k+p_k+r_k+s_k)} h_{v_1, v_2, k}(\xi) d\xi \right| \\
 & \quad + \left| \int_{t_g}^{t_y} \frac{\mathbb{G}'(\xi)(F_{t_1}(t_2))^{q_k+p_k+r_k+s_k-1}}{\Gamma(q_k+p_k+r_k+s_k)} h_{v_1, v_2, k}(\xi) d\xi \right| \\
 & \leq \lambda_k \left[\frac{(F_{t_1}(t_2))^{q_k+p_k+r_k+s_k}}{\Gamma(q_k+p_k+r_k+s_k+1)} - \frac{(F_{t_1}(t_1))^{q_k+p_k+r_k+s_k}}{\Gamma(q_k+p_k+r_k+s_k+1)} \right] \\
 & \quad + \lambda_k \frac{(F_{t_1}(t_2))^{q_k+p_k+r_k+s_k}}{\Gamma(q_k+p_k+r_k+s_k+1)}.
 \end{aligned}$$

As $t_g \rightarrow t_y$, we obtain

$$|(\Omega_k(v_1, v_2))(t_y) - (\Omega_k(v_1, v_2))(t_g)| \rightarrow 0,$$

implying that Ω is equicontinuous. Furthermore, in view of (3.19), Ω is uniformly bounded. Hence, due to the Arzelá-Ascoli theorem, we deduce that Ω is a compact operator. Then, all the conditions of Theorem 2.4 are holding. Thus, fractional \mathbb{G} -CSS (1.6) has at least one solution $(v_1, v_2) \in \mathbb{B}_r$. The proof is completed. \square

3.2. Ulam-Hyers stability

In this part, we review the stability criterion in the context of the U-H-S for solutions of the fractional \mathbb{G} -CSS (1.6).

Theorem 3.4. *Let (H1) and $\Phi_k \ell_k < 1$, ($k = 1, 2$) hold. Then, the fractional \mathbb{G} -CSS (1.6) is U-H-S.*

Proof. According to Theorem 3.2, we have

$$\|\Lambda_k(v_1, v_2) - \Lambda_k(u_1, u_2)\| \leq \Phi_k \ell_k \|v_1 - u_1\| + \Phi_k \ell_k \|v_2 - u_2\|,$$

which yields that

$$\|\Lambda(v_1, v_2) - \Lambda(u_1, u_2)\| \leq \Xi \times \begin{pmatrix} \|v_1 - u_1\| \\ \|v_2 - u_2\| \end{pmatrix},$$

where

$$\Xi = \begin{pmatrix} \Phi_1 \ell_1 & \Phi_1 \ell_1 \\ \Phi_2 \ell_2 & \Phi_2 \ell_2 \end{pmatrix}.$$

Since $\Phi_k \ell_k < 1$ and each geometric sequences $(\Phi_k \ell_k)^n \rightarrow 0$, hence $\mathcal{E}^n \rightarrow 0$ as $n \rightarrow \infty$. Therefore, due to Theorem 2.6, the fractional \mathbb{G} -CSS (1.6) is U-H - \mathbb{S} . \square

4. Application

We allow here a few illustrations of the fractional \mathbb{G} -CSS, based on numerical recreation to analyze their solutions. In these cases, we consider distinctive cases of the function \mathbb{G} to cover the Caputo, Caputo-Hadamard and Katugampola adaptations.

Example 4.1. Based on the system (1.6), by assuming $\Sigma = [0.05, 0.95]$,

$$q_1 = 0.73 \in (0, 1], \quad q_2 = 0.36 \in (0, 1], \quad p_1 = 0.92 \in (0, 1], \quad p_2 = 0.45 \in (0, 1],$$

$$r_1 = 0.12 \in (0, 1], \quad r_2 = 0.87 \in (0, 1], \quad s_1 = 0.54 \in (0, 1], \quad s_2 = 0.27 \in (0, 1],$$

we consider a fractional CSS as

$$\left\{ \begin{array}{l} {}^c \mathcal{D}_{t_1^+}^{0.73; \mathbb{G}} v_1(t) = u_1(t), \quad {}^c \mathcal{D}_{t_1^+}^{0.36; \mathbb{G}} v_2(t) = u_2(t), \\ {}^c \mathcal{D}_{t_1^+}^{0.92; \mathbb{G}} u_1(t) = w_1(t), \quad {}^c \mathcal{D}_{t_1^+}^{0.45; \mathbb{G}} u_2(t) = w_2(t), \\ {}^c \mathcal{D}_{t_1^+}^{0.12; \mathbb{G}} w_1(t) = x_1(t), \quad {}^c \mathcal{D}_{t_1^+}^{0.87; \mathbb{G}} w_2(t) = x_2(t), \\ {}^c \mathcal{D}_{t_1^+}^{0.54; \mathbb{G}} x_1(t) = \frac{5t}{36(\sqrt{15} + t^2)} + \frac{\arctan^2(v_1)}{36(7 + \arctan^2(v_1))} \\ + \frac{\exp(|v_2| + 1)}{36(\sqrt{15} + \exp(|v_2|))} + \frac{1}{72} \arcsin \frac{u_1}{\sqrt[3]{36 + u_1}} \\ + \frac{t \sin |u_2|}{36(15 + \sin |u_2|)} + \frac{\exp(w_1)}{36(\sqrt{7} + \exp(w_1))} + \frac{w_2^2}{108(w_2 + 3)^2} \\ + \frac{(x_1 x_2)^2}{54(x_1 x_2 + 21)^2}, \\ {}^c \mathcal{D}_{t_1^+}^{0.27; \mathbb{G}} x_2(t) = \frac{t^2}{2\sqrt{3}(t^2 + 49)} + \frac{\tan^2(v_1)}{1.5(7 + \tan^2(v_1))} \\ + \frac{\cos^2(|v_2| + 1)}{36(\sqrt{15} + \cos^2(|v_2|))} + \frac{1}{25} \arctan \frac{3u_1}{\sqrt[5]{6 + u_1}} \\ + \frac{\arctan |u_2|}{45 + \arctan |u_2|} + \frac{|w_1| + 3}{48(|w_1| + 5)^2} + \frac{\exp(w_2)}{45(\sqrt{12} + \exp(w_2))} \\ + \frac{(x_1 + x_2)^2}{\sqrt{10}(x_1 + x_2 + 21)^2}, \end{array} \right. \quad (4.1)$$

for $t \in \Sigma$ and

$$v_1(t_1) = \int_{t_1}^{t_2} \frac{s}{2} ds = 0.2250, \quad v_2(t_1) = \int_{t_1}^{t_2} \sqrt{s} ds = 0.6098,$$

$$u_1(t_1) = \int_{t_1}^{t_2} \frac{s^2}{5} ds = 0.0571, \quad u_2(t_1) = \int_{t_1}^{t_2} \frac{3}{2} s ds = 0.6750,$$

$$\begin{aligned}
 w_1(t_1) &= \int_{t_1}^{t_2} \frac{s}{\sqrt{2}} ds = 0.3181, & w_2(t_1) &= \int_{t_1}^{t_2} \frac{\sqrt{s}}{7} ds = 0.0871, \\
 x_1(t_1) &= \int_{t_1}^{t_2} \sin(\pi s) ds = 0.6287, & x_2(t_1) &= \int_{t_1}^{t_2} \cos(\pi s) ds = 0.
 \end{aligned}$$

Clearly,

$$\begin{aligned}
 &h_1(t, v_1, v_2, u_1, u_2, w_1, w_2, x_1, x_2) \\
 &= \frac{5t}{36(\sqrt{15} + t^2)} + \frac{\arctan^2(v_1)}{36(7 + \arctan^2(v_1))} + \frac{\exp(|v_2| + 1)}{36(\sqrt{15} + \exp(|v_2|))} \\
 &+ \frac{1}{72} \arcsin \frac{u_1}{\sqrt[3]{36 + u_1}} + \frac{t}{36} \frac{\sin |u_2|}{15 + \sin |u_2|} + \frac{\exp(w_1)}{36(\sqrt{7} + \exp(w_1))} \\
 &+ \frac{w_1^2}{108(w_1 + 3)^2} + \frac{(x_1 x_2)^2}{54(x_1 x_2 + 21)^2},
 \end{aligned}$$

and

$$\begin{aligned}
 &h_2(t, v_1, v_2, u_1, u_2, w_1, w_2, x_1, x_2) \\
 &= \frac{t^2}{2\sqrt{3}(t^2 + 49)} + \frac{\tan^2(v_1)}{1.5(7 + \tan^2(v_1))} \frac{\cos^2(|v_2| + 1)}{36(\sqrt{15} + \cos^2(|v_2|))} \\
 &+ \frac{1}{25} \arctan \frac{3u_1}{\sqrt[5]{6 + u_1}} + \frac{\arctan |u_2|}{45 + \arctan |u_2|} + \frac{|w_1| + 3}{48(|w_1| + 5)^2} \\
 &+ \frac{\exp(w_2)}{45(\sqrt{12} + \exp(w_2))} + \frac{(x_1 + x_2)^2}{\sqrt{10}(x_1 + x_2 + 21)^2}.
 \end{aligned}$$

Thus, we can rewrite the above system as Eq (1.6). At present, we will have

$$\begin{aligned}
 &|h_1(t, v_1, v_2, \dots, v_8) - h_1(t, v_1^*, v_2^*, \dots, v_8^*)| \\
 &= \left| \frac{5t}{36(\sqrt{15} + t^2)} + \frac{\arctan^2(v_1)}{36(7 + \arctan^2(v_1))} + \frac{\exp(|v_2| + 1)}{36(\sqrt{15} + \exp(|v_2|))} \right. \\
 &+ \frac{1}{72} \arcsin \frac{v_3}{\sqrt[3]{36 + v_3}} + \frac{t}{36} \frac{\sin |v_4|}{15 + \sin |v_4|} + \frac{\exp(v_5)}{36(\sqrt{7} + \exp(v_5))} \\
 &+ \frac{v_6^2}{108(v_6 + 3)^2} + \frac{(v_7 v_8)^2}{54(v_7 v_8 + 21)^2} \\
 &- \left(\frac{5t}{36(\sqrt{15} + t^2)} + \frac{\arctan^2(v_1^*)}{36(7 + \arctan^2(v_1^*))} + \frac{\exp(|v_2^*| + 1)}{36(\sqrt{15} + \exp(|v_2^*|))} \right. \\
 &+ \frac{1}{72} \arcsin \frac{v_3^*}{\sqrt[3]{36 + v_3^*}} + \frac{t}{36} \frac{\sin |v_4^*|}{15 + \sin |v_4^*|} + \frac{\exp(v_5^*)}{36(\sqrt{7} + \exp(v_5^*))} \\
 &\left. \left. + \frac{(v_6^*)^2}{108(v_6^* + 3)^2} + \frac{(v_7^* v_8^*)^2}{54(v_7^* v_8^* + 21)^2} \right) \right| \leq \frac{5}{36} \sum_{i=1}^8 |v_i - v_i^*|,
 \end{aligned}$$

with $\ell_1 = \frac{5}{36}$ and

$$\begin{aligned} & \left| h_2(t, v_1, v_2, \dots, v_8) - h_2(t, v_1^*, v_2^*, \dots, v_8^*) \right| \\ &= \left| \frac{t^2}{2\sqrt{3}(t^2 + 49)} + \frac{\tan^2(v_1)}{1.5(7 + \tan^2(v_1))} + \frac{\cos^2(|v_2| + 1)}{36(\sqrt{15} + \cos^2(|v_2|))} \right. \\ &+ \frac{1}{25} \arctan \frac{3v_3}{\sqrt[5]{6 + v_3}} + \frac{\arctan |v_4|}{45 + \arctan |v_4|} + \frac{|v_5| + 3}{48(|v_5| + 5)^2} \\ &+ \frac{\exp(v_6)}{45(\sqrt{12} + \exp(v_6))} + \frac{(v_7 + v_8)^2}{\sqrt{10}(v_7 + v_8 + 21)^2} \\ &- \left(\frac{t^2}{2\sqrt{3}(t^2 + 49)} + \frac{\tan^2(v_1^*)}{1.5(7 + \tan^2(v_1^*))} + \frac{\cos^2(|v_2^*| + 1)}{36(\sqrt{15} + \cos^2(|v_2^*|))} \right. \\ &+ \frac{1}{25} \arctan \frac{3v_3^*}{\sqrt[5]{6 + v_3^*}} + \frac{\arctan |v_4^*|}{45 + \arctan |v_4^*|} + \frac{|v_5^*| + 3}{48(|v_5^*| + 5)^2} \\ &\left. \left. + \frac{\exp(v_6^*)}{45(\sqrt{12} + \exp(v_6^*))} + \frac{(v_7^* + v_8^*)^2}{\sqrt{10}(v_7^* + v_8^* + 21)^2} \right) \right| \leq \frac{1}{2\sqrt{3}} \sum_{i=1}^8 |v_i - v_i^*|, \end{aligned}$$

with $\ell_2 = \frac{1}{2\sqrt{3}}$. So $\ell = \frac{1}{2\sqrt{3}}$. Now, from (3.6), we consider four cases for \mathbb{G} as:

- $\mathbb{G}_1(t) = 2^t$,
- $\mathbb{G}_2(t) = t$ (Caputo derivative),
- $\mathbb{G}_3(t) = \ln t$ (Caputo-Hadamard derivative),
- $\mathbb{G}_4(t) = \sqrt{t}$ (Katugampola derivative).

Thus,

$$\begin{aligned} \Phi_1 &= \frac{(F_{t_1}(t_2))^{q_1+p_1+r_1+s_1}}{\Gamma(q_1 + p_1 + r_1 + s_1 + 1)} + \frac{(F_{t_1}(t_2))^{p_1+r_1+s_1}}{\Gamma(p_k + r_1 + s_1 + 1)} \\ &+ \frac{(F_{t_1}(t_2))^{r_1+s_1}}{\Gamma(r_1 + s_1 + 1)} + \frac{(F_{t_1}(t_2))^{s_1}}{\Gamma(s_1 + 1)} \simeq \begin{cases} 0.4091, & \mathbb{G}_1(t) = 2^t, \\ 0.4106, & \mathbb{G}_2(t) = t, \\ 1.7597, & \mathbb{G}_3(t) = \ln t, \\ 0.3473, & \mathbb{G}_4(t) = \sqrt{t}, \end{cases} \end{aligned} \quad (4.2)$$

and

$$\begin{aligned} \Phi_2 &= \frac{(F_{t_1}(t_2))^{q_2+p_2+r_2+s_2}}{\Gamma(q_2 + p_2 + r_2 + s_2 + 1)} + \frac{(F_{t_1}(t_2))^{p_2+r_2+s_2}}{\Gamma(p_k + r_2 + s_2 + 1)} \\ &+ \frac{(F_{t_1}(t_2))^{r_2+s_2}}{\Gamma(r_2 + s_2 + 1)} + \frac{(F_{t_1}(t_2))^{s_2}}{\Gamma(s_2 + 1)} \simeq \begin{cases} 0.3370, & \mathbb{G}_1(t) = 2^t, \\ 0.3383, & \mathbb{G}_2(t) = t, \\ 1.4912, & \mathbb{G}_3(t) = \ln t, \\ 0.2826, & \mathbb{G}_4(t) = \sqrt{t}. \end{cases} \end{aligned} \quad (4.3)$$

Hence,

$$\Phi \simeq \begin{cases} 2.9461, & \mathbb{G}_1(\iota) = 2^\iota, \\ 2.9567, & \mathbb{G}_2(\iota) = \iota, \\ 12.9144, & \mathbb{G}_3(\iota) = \ln \iota, \\ 2.5009, & \mathbb{G}_4(\iota) = \sqrt{\iota}, \end{cases}$$

and we have

$$\Phi \ell \simeq \begin{cases} 0.4091 < 1, & \mathbb{G}_1(\iota) = 2^\iota, \\ 0.4106 < 1, & \mathbb{G}_2(\iota) = \iota, \\ 1.7936 \not< 1, & \mathbb{G}_3(\iota) = \ln \iota, \\ 0.3473 < 1, & \mathbb{G}_4(\iota) = \sqrt{\iota}. \end{cases}$$

On the other hand, by using equations in (3.7), we get

$$M_{1j} = \sup_{t \in \Sigma} \int_{t_1}^t |g_{1j}(\xi)| d\xi = 0.6328, \quad M_{2j} = \sup_{t \in \Sigma} \int_{t_1}^{t_2} |g_{1j}(\xi)| d\xi = 0.7632,$$

for $j = 0, 1, 2, 3$ and

$$h_1^0 = \sup_{t \in \Sigma} |h_1(t, 0, 0, 0, 0, 0, 0, 0)| \simeq \frac{5}{36} + \frac{1}{36(1 + \sqrt{7})},$$

$$h_2^0 = \sup_{t \in \Sigma} |h_2(t, 0, 0, 0, 0, 0, 0, 0)| \simeq \frac{1}{2\sqrt{3}} + \frac{1}{18(1 + \sqrt{15})},$$

for $k = 1, 2$. By employing Eq (3.6), we obtain

$$\begin{aligned} \Delta_1 &= M_{10} + M_{11} \left(1 + \frac{(F_{t_1}(t_2))^{q_1}}{\Gamma(q_1 + 1)} \right) + M_{12} \left(1 + \frac{(F_{t_1}(t_2))^{p_1}}{\Gamma(p_1 + 1)} + \frac{(F_{t_1}(t_2))^{q_1 + p_1}}{\Gamma(q_1 + p_1 + 1)} \right) \\ &\quad + M_{13} \left(1 + \frac{(F_{t_1}(t_2))^{r_1}}{\Gamma(r_1 + 1)} + \frac{(F_{t_1}(t_2))^{p_1 + r_1}}{\Gamma(p_1 + r_1 + 1)} + \frac{(F_{t_1}(t_2))^{q_1 + p_1 + r_1}}{\Gamma(q_1 + p_1 + r_1 + 1)} \right), \\ &\simeq \begin{cases} 3.4102, & \mathbb{G}_1(\iota) = 2^\iota, \\ 3.4173, & \mathbb{G}_2(\iota) = \iota, \\ 9.3326, & \mathbb{G}_3(\iota) = \ln \iota, \\ 3.1122, & \mathbb{G}_4(\iota) = \sqrt{\iota}, \end{cases} \\ \Delta_2 &= M_{20} + M_{21} \left(1 + \frac{(F_{t_1}(t_2))^{q_2}}{\Gamma(q_2 + 1)} \right) + M_{22} \left(1 + \frac{(F_{t_1}(t_2))^{p_2}}{\Gamma(p_2 + 1)} + \frac{(F_{t_1}(t_2))^{q_2 + p_2}}{\Gamma(q_2 + p_2 + 1)} \right) \\ &\quad + M_{23} \left(1 + \frac{(F_{t_1}(t_2))^{r_2}}{\Gamma(r_2 + 1)} + \frac{(F_{t_1}(t_2))^{p_2 + r_2}}{\Gamma(p_2 + r_2 + 1)} + \frac{(F_{t_1}(t_2))^{q_2 + p_2 + r_2}}{\Gamma(q_2 + p_2 + r_2 + 1)} \right) \\ &\simeq \begin{cases} 4.4208, & \mathbb{G}_1(\iota) = 2^\iota, \\ 4.4285, & \mathbb{G}_2(\iota) = \iota, \\ 9.8667, & \mathbb{G}_3(\iota) = \ln \iota, \\ 4.0927, & \mathbb{G}_4(\iota) = \sqrt{\iota}, \end{cases} \end{aligned}$$

and so we can choose

$$\varepsilon \geq \max \left\{ \frac{\Delta_1 + h_1^0 \Phi_1}{(1 - \ell_1 \Phi_1)}, \frac{\Delta_2 + h_2^0 \Phi_2}{(1 - \ell_2 \Phi_2)} \right\} \simeq \begin{cases} 7.2317, & \mathbb{G}_1(t) = 2^t, \\ 7.2597, & \mathbb{G}_2(t) = t, \\ -14.7276, & \mathbb{G}_3(t) = \ln t, \\ 6.1479, & \mathbb{G}_4(t) = \sqrt{t}. \end{cases}$$

We define the Algorithm 1 for obtaining the values of $\Phi\ell$, Δ_i and ε , which is shown in the MATLAB commands. One can check numerical results of $\Phi\ell$, Δ_i and ε in Tables 1 and 2 for $\iota \in [0.05, 0.95]$, and in Figure 1. Accordingly, all requirements of Theorem 3.2 hold, and so the fractional nonlinear couple snap system (CSS) in the \mathbb{G} -Caputo sense ($\mathbb{G}\mathbb{C}$) with initial conditions (4.1) has one unique solution on the $[0.05, 0.95]$.

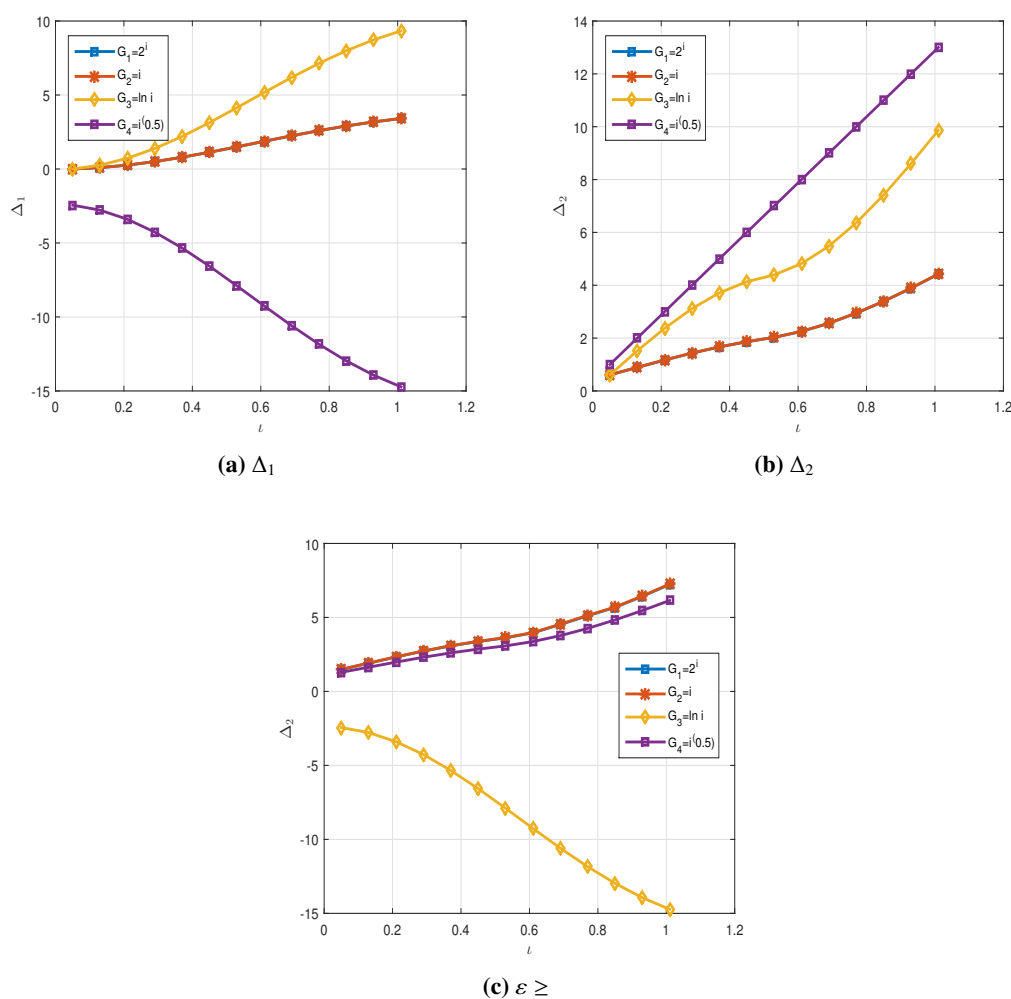


Figure 1. Graphical representation of Δ_1 , Δ_2 and ε for $t \in [0.05, 0.95]$ in Example 4.1.

Table 1. Numerical values of $\Phi\ell$, Δ_1 , Δ_2 and ε in Example 4.1 $\forall \iota \in [0.05, 0.95]$ when $\mathbb{G}_1 = 2^\iota$ and $\mathbb{G}_2 = \iota$.

ι	$\mathbb{G}_1(\iota) = 2^\iota$				$\mathbb{G}_2(\iota) = \iota$			
	$\Phi\ell$	Δ_1	Δ_2	$\varepsilon \geq$	$\Phi\ell$	Δ_1	Δ_2	$\varepsilon \geq$
0.05	0.4092	0.0000	0.6098	1.4836	0.4107	0.0000	0.6098	1.4886
0.13	0.4092	0.0916	0.8907	1.9071	0.4107	0.0918	0.8915	1.9142
0.21	0.4092	0.2602	1.1697	2.3280	0.4107	0.2608	1.1713	2.3371
0.29	0.4092	0.4976	1.4321	2.7238	0.4107	0.4986	1.4344	2.7347
0.37	0.4092	0.7921	1.6660	3.0766	0.4107	0.7938	1.6687	3.0888
0.45	0.4092	1.1297	1.8627	3.3733	0.4107	1.1321	1.8658	3.3867
0.53	0.4092	1.4944	2.0267	3.6206	0.4107	1.4976	2.0300	3.6348
0.61	0.4092	1.8697	2.2517	3.9599	0.4107	1.8736	2.2552	3.9752
0.69	0.4092	2.2394	2.5593	4.5209	0.4107	2.2441	2.5634	4.5429
0.77	0.4092	2.5889	2.9421	5.1124	0.4107	2.5943	2.9469	5.1371
0.85	0.4092	2.9058	3.3892	5.6758	0.4107	2.9119	3.3949	5.6977
0.93	0.4092	3.1810	3.8873	6.4269	0.4107	3.1877	3.8940	6.4518

Table 2. Numerical values of $\Phi\ell$, Δ_1 , Δ_2 and ε in Example 4.1 $\forall \iota \in [0.05, 0.95]$ when $\mathbb{G}_3(\iota) = \ln \iota$ and $\mathbb{G}_4(\iota) = \sqrt{\iota}$.

ι	$\mathbb{G}_3 = \ln \iota$				$\mathbb{G}_4 = \sqrt{\iota}$			
	$\Phi\ell$	Δ_1	Δ_2	$\varepsilon \geq$	$\Phi\ell$	Δ_1	Δ_2	$\varepsilon \geq$
0.05	1.7937	0.0000	0.6098	-2.4433	0.3474	0.0000	0.6098	1.2925
0.13	1.7937	0.2549	1.5187	-2.7789	0.3474	0.0835	0.8562	1.6360
0.21	1.7937	0.7237	2.3707	-3.3959	0.3474	0.2373	1.1034	1.9805
0.29	1.7937	1.3828	3.1158	-4.2635	0.3474	0.4537	1.3383	2.3081
0.37	1.7937	2.1996	3.7133	-5.3387	0.3474	0.7224	1.5507	2.6041
0.45	1.7937	3.1339	4.1339	-6.5685	0.3474	1.0303	1.7330	2.8582
0.53	1.7937	4.1410	4.3933	-7.8940	0.3474	1.3629	1.8890	3.0758
0.61	1.7937	5.1740	4.8174	-9.2538	0.3474	1.7053	2.1001	3.3700
0.69	1.7937	6.1876	5.4819	-10.5880	0.3474	2.0427	2.3850	3.7672
0.77	1.7937	7.1402	6.3609	-11.8418	0.3474	2.3617	2.7371	4.2581
0.85	1.7937	7.9969	7.4169	-12.9695	0.3474	2.6511	3.1472	4.8298
0.93	1.7937	8.7318	8.6033	-13.9368	0.3474	2.9026	3.6035	5.4660

5. Conclusions

In this paper, we defined a new fractional mathematical model of a BVP consisting of a coupled snap equation with integral boundary conditions in the framework of the generalized sequential \mathbb{G} -operators, and turned to the investigation of the qualitative behaviors of its solutions, including

existence, uniqueness, stability and inclusion version. To confirm the existence criterion, we used the Krasnoselskii theorem, and to confirm the uniqueness criterion, we utilized the Banach theorem. Different kinds of stability criteria were studied based on the standard definitions of these notions. In the final step, we designed examples, and, by assuming different cases for the function \mathbb{G} and order q , we obtained numerical results of these two suggested fractional coupled snap systems in some versions, such as Caputo, Caputo-Hadamard and Katugampola.

Conflict of interest

We declare that no competing interests.

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Appendix

Algorithm A1: MATLAB lines for Example 4.1.

```

1 clear;
2 format short;
3 syms v e;
4 q_1=0.83; q_2=0.36; p_1=0.92; p_2=0.45;
5 r_1=0.12; r_2=0.87; s_1=0.54; s_2=0.27;
6 iota_1=0.05; iota_2=0.95;
7 G1=2^v; G2=v; G3=log(v); G4=sqrt(v);
8 g_10=v/2; g_20=sqrt(v);
9 g_11=v^2/5; g_21=3*v/2;
10 g_12=v/sqrt(2); g_22=sqrt(v)/7;
11 g_13=sin(v*pi); g_23=cos(v*pi);
12 mathrmv_1=int(g_10, v, iota_1, iota_2);
13 mathrmv_2=int(g_20, v, iota_1, iota_2);
14 mathrmu_1=int(g_11, v, iota_1, iota_2);
15 mathrmu_2=int(g_21, v, iota_1, iota_2);
16 mathrmw_1=int(g_12, v, iota_1, iota_2);
17 mathrmw_2=int(g_22, v, iota_1, iota_2);
18 mathrmx_1=int(g_13, v, iota_1, iota_2);
19 mathrmx_2=int(g_23, v, iota_1, iota_2);
20 ell_1=5/36; ell_2=1/(5*sqrt(3));
21 ell=max(ell_1, ell_2);
22 h_1_0=5/36+1/(36*(1+sqrt(7)));
23 h_2_0=1/(5*sqrt(3))+1/(18*(1+sqrt(15)));
24 %G1
25 t=iota_1;
26 column=1;
27 nn=1;
28 while t<=iota_2+0.08
29     MI(nn, column) = nn;
30     MI(nn, column+1) = t;
31     Phi_1=(eval(subs(G1, {v}, {iota_2}))...
32         -eval(subs(G1, {v}, {iota_1})))^(q_1+p_1+r_1+s_1)...
33         /gamma(q_1+p_1+r_1+s_1+1)+(eval(subs(G1, {v}, {iota_2}))...
34         -eval(subs(G1, {v}, {iota_1})))^(p_1+r_1+s_1)...
35         /gamma(p_1+r_1+s_1+1)+(eval(subs(G1, {v}, {iota_2}))...
36         -eval(subs(G1, {v}, {iota_1})))^(r_1+s_1)...

```



```

37     /gamma(r_1+s_1+1)+(eval(subs(G1, {v}, {iota_2}))...
38     -eval(subs(G1, {v}, {iota_1})))^(s_1)/gamma(s_1+1);
39 MI(nn, column+2)=Phi_1*ell_1;
40 MI(nn, column+3)=Phi_1*ell_1<1;
41 Phi_2=(eval(subs(G1, {v}, {iota_2}))...
42     -eval(subs(G1, {v}, {iota_1})))^(q_2+p_2+r_2+s_2)...
43     /gamma(q_2+p_2+r_2+s_2+1)+(eval(subs(G1, {v}, {iota_2}))...
44     -eval(subs(G1, {v}, {iota_1})))^(p_2+r_2+s_2)...
45     /gamma(p_2+r_2+s_2+1)+(eval(subs(G1, {v}, {iota_2}))...
46     -eval(subs(G1, {v}, {iota_1})))^(r_2+s_2)...
47     /gamma(r_2+s_2+1)+(eval(subs(G1, {v}, {iota_2}))...
48     -eval(subs(G1, {v}, {iota_1})))^(s_2)/gamma(s_2+1);
49 MI(nn, column+4)=Phi_2*ell_2;
50 MI(nn, column+5)=Phi_2*ell_2<1;
51 Phi=max(Phi_1, Phi_2);
52 MI(nn, column+6)=Phi;
53 MI(nn, column+7)=Phi*ell;
54 MI(nn, column+8)=Phi*ell<1;
55 M_10=int(abs(g_10), v, iota_1, t);
56 MI(nn, column+9)=M_10;
57 M_11=int(abs(g_11), v, iota_1, t);
58 MI(nn, column+10)=M_11;
59 M_12=int(abs(g_12), v, iota_1, t);
60 MI(nn, column+11)=M_12;
61 M_13=int(abs(g_13), v, iota_1, t);
62 MI(nn, column+12)=M_13;
63 M_20=int(abs(g_20), v, iota_1, iota_2);
64 MI(nn, column+13)=M_20;
65 M_21=int(abs(g_21), v, iota_1, t);
66 MI(nn, column+14)=M_21;
67 M_22=int(abs(g_22), v, iota_1, t);
68 MI(nn, column+15)=M_22;
69 M_23=int(abs(g_23), v, iota_1, t);
70 MI(nn, column+16)=M_23;
71 M_1j=max(max(max(M_10, M_11), M_12), M_13);
72 MI(nn, column+17)=M_1j;
73 M_2j=max(max(max(M_20, M_21), M_22), M_23);
74 MI(nn, column+18)=M_2j;
75 Delta_1=M_10+M_11*(1+(eval(subs(G1, {v}, {iota_2}))...
76     -eval(subs(G1, {v}, {iota_1})))^(q_1)/gamma(q_1+1))...
77     +M_12*(1+(eval(subs(G1, {v}, {iota_2}))...
78     -eval(subs(G1, {v}, {iota_1})))^(p_1)/gamma(p_1+1)...
79     +(eval(subs(G1, {v}, {iota_2}))...
80     -eval(subs(G1, {v}, {iota_1})))^(q_1+p_1)/gamma(q_1+p_1+1))...
81     +M_13*(1+(eval(subs(G1, {v}, {iota_2}))...
82     -eval(subs(G1, {v}, {iota_1})))^(r_1)/gamma(r_1+1)...
83     +(eval(subs(G1, {v}, {iota_2}))...
84     -eval(subs(G1, {v}, {iota_1})))^(p_1+r_1)/gamma(p_1+r_1+1)...
85     +(eval(subs(G1, {v}, {iota_2}))...
86     -eval(subs(G1, {v}, {iota_1})))^(q_1+p_1+r_1)...
87     /gamma(q_1+p_1+r_1+1));
88 MI(nn, column+19)=Delta_1;
89 Delta_2=M_20+M_21*(1+(eval(subs(G1, {v}, {iota_2}))...
90     -eval(subs(G1, {v}, {iota_1})))^(q_2)/gamma(q_2+1))...
91     +M_22*(1+(eval(subs(G1, {v}, {iota_2}))...
92     -eval(subs(G1, {v}, {iota_1})))^(p_2)/gamma(p_2+1)...
93     +(eval(subs(G1, {v}, {iota_2}))...
94     -eval(subs(G1, {v}, {iota_1})))^(q_2+p_2)/gamma(q_2+p_2+1))...
95     +M_23*(1+(eval(subs(G1, {v}, {iota_2}))...

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96     -eval(subs(G1, {v}, {iota_1})))^(r_2)/gamma(r_2+1)...
97     +(eval(subs(G1, {v}, {iota_2})))...
98     -eval(subs(G1, {v}, {iota_1})))^(p_2+r_2)/gamma(p_2+r_2+1)...
99     +(eval(subs(G1, {v}, {iota_2})))...
100    -eval(subs(G1, {v}, {iota_1})))^(q_2+p_2+r_2)...
101    /gamma(q_2+p_2+r_2+1));
102    MI(nn,column+20)=Delta_2;
103    D1=(Delta_1+h_1_0*Phi_1)/(1-ell_1*Phi_1);
104    MI(nn,column+21)=D1;
105    D2=(Delta_2+h_2_0*Phi_1)/(1-ell_2*Phi_2);
106    MI(nn,column+22)=D2;
107    MI(nn,column+23)=max(D1, D2);
108    t=t+0.08;
109    nn=nn+1;
110 end;
111 %G2
112 t=iota_1;
113 column=25;
114 nn=1;
115 while t<=iota_2+0.08
116     MI(nn,column) = nn;
117     MI(nn,column+1) = t;
118     Phi_1=(eval(subs(G2, {v}, {iota_2})))...
119     -eval(subs(G2, {v}, {iota_1})))^(q_1+p_1+r_1+s_1)...
120     /gamma(q_1+p_1+r_1+s_1+1)+(eval(subs(G2, {v}, {iota_2})))...
121     -eval(subs(G2, {v}, {iota_1})))^(p_1+r_1+s_1)...
122     /gamma(p_1+r_1+s_1+1)+(eval(subs(G2, {v}, {iota_2})))...
123     -eval(subs(G2, {v}, {iota_1})))^(r_1+s_1)...
124     /gamma(r_1+s_1+1)+(eval(subs(G2, {v}, {iota_2})))...
125     -eval(subs(G2, {v}, {iota_1})))^(s_1)/gamma(s_1+1);
126     MI(nn,column+2)=Phi_1*ell_1;
127     MI(nn,column+3)=Phi_1*ell_1<1;
128     Phi_2=(eval(subs(G2, {v}, {iota_2})))...
129     -eval(subs(G2, {v}, {iota_1})))^(q_2+p_2+r_2+s_2)...
130     /gamma(q_2+p_2+r_2+s_2+1)+(eval(subs(G2, {v}, {iota_2})))...
131     -eval(subs(G2, {v}, {iota_1})))^(p_2+r_2+s_2)...
132     /gamma(p_2+r_2+s_2+1)+(eval(subs(G2, {v}, {iota_2})))...
133     -eval(subs(G2, {v}, {iota_1})))^(r_2+s_2)...
134     /gamma(r_2+s_2+1)+(eval(subs(G2, {v}, {iota_2})))...
135     -eval(subs(G2, {v}, {iota_1})))^(s_2)/gamma(s_2+1);
136     MI(nn,column+4)=Phi_2*ell_2;
137     MI(nn,column+5)=Phi_2*ell_2<1;
138     Phi=max(Phi_1, Phi_2);
139     MI(nn,column+6)=Phi;
140     MI(nn,column+7)=Phi*ell;
141     MI(nn,column+8)=Phi*ell<1;
142     M_10=int(abs(g_10), v, iota_1, t);
143     MI(nn,column+9)=M_10;
144     M_11=int(abs(g_11), v, iota_1, t);
145     MI(nn,column+10)=M_11;
146     M_12=int(abs(g_12), v, iota_1, t);
147     MI(nn,column+11)=M_12;
148     M_13=int(abs(g_13), v, iota_1, t);
149     MI(nn,column+12)=M_13;
150     M_20=int(abs(g_20), v, iota_1, iota_2);
151     MI(nn,column+13)=M_20;
152     M_21=int(abs(g_21), v, iota_1, t);
153     MI(nn,column+14)=M_21;
154     M_22=int(abs(g_22), v, iota_1, t);

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155 MI(nn, column+15)=M.22;
156 M.23=int(abs(g.23), v, iota_1, t);
157 MI(nn, column+16)=M.23;
158 M.1j=max(max(max(M.10, M.11), M.12), M.13);
159 MI(nn, column+17)=M.1j;
160 M.2j=max(max(max(M.20, M.21), M.22), M.23);
161 MI(nn, column+18)=M.2j;
162 Delta_1=M.10+M.11*(1+(eval(subs(G2, {v}, {iota_2})))...
163     -eval(subs(G2, {v}, {iota_1})))^(q-1)/gamma(q-1+1))...
164     +M.12*(1+(eval(subs(G2, {v}, {iota_2})))...
165     -eval(subs(G2, {v}, {iota_1})))^(p-1)/gamma(p-1+1)...
166     +(eval(subs(G2, {v}, {iota_2}))-eval(subs(G2, {v}, {iota_1})))^(q-1+p-1)...
167     /gamma(q-1+p-1+1))+M.13*(1+(eval(subs(G2, {v}, {iota_2})))...
168     -eval(subs(G2, {v}, {iota_1})))^(r-1)/gamma(r-1+1)...
169     +(eval(subs(G2, {v}, {iota_2}))-eval(subs(G2, {v}, {iota_1})))^(p-1+r-1)...
170     /gamma(p-1+r-1+1)+(eval(subs(G2, {v}, {iota_2})))...
171     -eval(subs(G2, {v}, {iota_1})))^(q-1+p-1+r-1)/gamma(q-1+p-1+r-1+1));
172 MI(nn, column+19)=Delta_1;
173 Delta_2=M.20+M.21*(1+(eval(subs(G2, {v}, {iota_2})))...
174     -eval(subs(G2, {v}, {iota_1})))^(q-2)/gamma(q-2+1))...
175     +M.22*(1+(eval(subs(G2, {v}, {iota_2})))...
176     -eval(subs(G2, {v}, {iota_1})))^(p-2)/gamma(p-2+1)...
177     +(eval(subs(G2, {v}, {iota_2})))...
178     -eval(subs(G2, {v}, {iota_1})))^(q-2+p-2)/gamma(q-2+p-2+1))...
179     +M.23*(1+(eval(subs(G2, {v}, {iota_2})))...
180     -eval(subs(G2, {v}, {iota_1})))^(r-2)/gamma(r-2+1)...
181     +(eval(subs(G2, {v}, {iota_2})))...
182     -eval(subs(G2, {v}, {iota_1})))^(p-2+r-2)/gamma(p-2+r-2+1)...
183     +(eval(subs(G2, {v}, {iota_2})))...
184     -eval(subs(G2, {v}, {iota_1})))^(q-2+p-2+r-2)...
185     /gamma(q-2+p-2+r-2+1));
186 MI(nn, column+20)=Delta_2;
187 D1=(Delta_1+h.1_0*Phi_1)/(1-ell.1*Phi_1);
188 MI(nn, column+21)=D1;
189 D2=(Delta_2+h.2_0*Phi_1)/(1-ell.2*Phi_2);
190 MI(nn, column+22)=D2;
191 MI(nn, column+23)=max(D1, D2);
192 t=t+0.08;
193 nn=nn+1;
194 end;
195 %G3
196 t=iota_1;
197 column=49;
198 nn=1;
199 while t<=iota_2+0.08
200     MI(nn, column) = nn;
201     MI(nn, column+1) = t;
202     Phi_1=(eval(subs(G3, {v}, {iota_2})))...
203         -eval(subs(G3, {v}, {iota_1})))^(q-1+p-1+r-1+s-1)...
204         /gamma(q-1+p-1+r-1+s-1+1)+(eval(subs(G3, {v}, {iota_2})))...
205         -eval(subs(G3, {v}, {iota_1})))^(p-1+r-1+s-1)...
206         /gamma(p-1+r-1+s-1+1)+(eval(subs(G3, {v}, {iota_2})))...
207         -eval(subs(G3, {v}, {iota_1})))^(r-1+s-1)...
208         /gamma(r-1+s-1+1)+(eval(subs(G3, {v}, {iota_2})))...
209         -eval(subs(G3, {v}, {iota_1})))^(s-1)/gamma(s-1+1);
210     MI(nn, column+2)=Phi_1*ell.1;
211     MI(nn, column+3)=Phi_1*ell.1<1;
212     Phi_2=(eval(subs(G3, {v}, {iota_2})))...
213         -eval(subs(G3, {v}, {iota_1})))^(q-2+p-2+r-2+s-2)...

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214     /gamma(q_2+p_2+r_2+s_2+1)+(eval(subs(G3, {v}, {iota_2})))...
215     -eval(subs(G3, {v}, {iota_1})))^(p_2+r_2+s_2)...
216     /gamma(p_2+r_2+s_2+1)+(eval(subs(G3, {v}, {iota_2})))...
217     -eval(subs(G3, {v}, {iota_1})))^(r_2+s_2)...
218     /gamma(r_2+s_2+1)+(eval(subs(G3, {v}, {iota_2})))...
219     -eval(subs(G3, {v}, {iota_1})))^(s_2)/gamma(s_2+1);
220 MI(nn,column+4)=Phi_2*ell_2;
221 MI(nn,column+5)=Phi_2*ell_2<1;
222 Phi=max(Phi_1, Phi_2);
223 MI(nn,column+6)=Phi;
224 MI(nn,column+7)=Phi*ell;
225 MI(nn,column+8)=Phi*ell<1;
226 M_10=int(abs(g_10), v, iota_1, t);
227 MI(nn,column+9)=M_10;
228 M_11=int(abs(g_11), v, iota_1, t);
229 MI(nn,column+10)=M_11;
230 M_12=int(abs(g_12), v, iota_1, t);
231 MI(nn,column+11)=M_12;
232 M_13=int(abs(g_13), v, iota_1, t);
233 MI(nn,column+12)=M_13;
234 M_20=int(abs(g_20), v, iota_1, iota_2);
235 MI(nn,column+13)=M_20;
236 M_21=int(abs(g_21), v, iota_1, t);
237 MI(nn,column+14)=M_21;
238 M_22=int(abs(g_22), v, iota_1, t);
239 MI(nn,column+15)=M_22;
240 M_23=int(abs(g_23), v, iota_1, t);
241 MI(nn,column+16)=M_23;
242 M_1j=max(max(max(M_10, M_11),M_12),M_13);
243 MI(nn,column+17)=M_1j;
244 M_2j=max(max(max(M_20, M_21),M_22),M_23);
245 MI(nn,column+18)=M_2j;
246 Delta_1=M_10+M_11*(1+(eval(subs(G3, {v}, {iota_2})))...
247     -eval(subs(G3, {v}, {iota_1})))^(q_1)/gamma(q_1+1))...
248     +M_12*(1+(eval(subs(G3, {v}, {iota_2})))...
249     -eval(subs(G3, {v}, {iota_1})))^(p_1)/gamma(p_1+1)...
250     +(eval(subs(G3, {v}, {iota_2})))...
251     -eval(subs(G3, {v}, {iota_1})))^(q_1+p_1)/gamma(q_1+p_1+1))...
252     +M_13*(1+(eval(subs(G3, {v}, {iota_2})))...
253     -eval(subs(G3, {v}, {iota_1})))^(r_1)/gamma(r_1+1)...
254     +(eval(subs(G3, {v}, {iota_2})))...
255     -eval(subs(G3, {v}, {iota_1})))^(p_1+r_1)/gamma(p_1+r_1+1)...
256     +(eval(subs(G3, {v}, {iota_2})))...
257     -eval(subs(G3, {v}, {iota_1})))^(q_1+p_1+r_1)...
258     /gamma(q_1+p_1+r_1+1));
259 MI(nn,column+19)=Delta_1;
260 Delta_2=M_20+M_21*(1+(eval(subs(G3, {v}, {iota_2})))...
261     -eval(subs(G3, {v}, {iota_1})))^(q_2)/gamma(q_2+1))...
262     +M_22*(1+(eval(subs(G3, {v}, {iota_2})))...
263     -eval(subs(G3, {v}, {iota_1})))^(p_2)/gamma(p_2+1)...
264     +(eval(subs(G3, {v}, {iota_2})))...
265     -eval(subs(G3, {v}, {iota_1})))^(q_2+p_2)/gamma(q_2+p_2+1))...
266     +M_23*(1+(eval(subs(G3, {v}, {iota_2})))...
267     -eval(subs(G3, {v}, {iota_1})))^(r_2)/gamma(r_2+1)...
268     +(eval(subs(G3, {v}, {iota_2})))...
269     -eval(subs(G3, {v}, {iota_1})))^(p_2+r_2)/gamma(p_2+r_2+1)...
270     +(eval(subs(G3, {v}, {iota_2})))...
271     -eval(subs(G3, {v}, {iota_1})))^(q_2+p_2+r_2)...
272     /gamma(q_2+p_2+r_2+1));

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273     MI(nn, column+20)=Delta_2;
274     D1=(Delta_1+h_1_0*Phi_1)/(1-ell_1*Phi_1);
275     MI(nn, column+21)=D1;
276     D2=(Delta_2+h_2_0*Phi_1)/(1-ell_2*Phi_2);
277     MI(nn, column+22)=D2;
278     MI(nn, column+23)=max(D1, D2);
279     t=t+0.08;
280     nn=nn+1;
281 end;
282 %G4
283 t=iota_1;
284 column=73;
285 nn=1;
286 while t<=iota_2+0.08
287     MI(nn, column) = nn;
288     MI(nn, column+1) = t;
289     Phi_1=(eval(subs(G4, {v}, {iota_2})))...
290         -eval(subs(G4, {v}, {iota_1})))^(q_1+p_1+r_1+s_1)...
291         /gamma(q_1+p_1+r_1+s_1+1)+(eval(subs(G4, {v}, {iota_2})))...
292         -eval(subs(G4, {v}, {iota_1})))^(p_1+r_1+s_1)...
293         /gamma(p_1+r_1+s_1+1)+(eval(subs(G4, {v}, {iota_2})))...
294         -eval(subs(G4, {v}, {iota_1})))^(r_1+s_1)...
295         /gamma(r_1+s_1+1)+(eval(subs(G4, {v}, {iota_2})))...
296         -eval(subs(G4, {v}, {iota_1})))^(s_1)/gamma(s_1+1);
297     MI(nn, column+2)=Phi_1*ell_1;
298     MI(nn, column+3)=Phi_1*ell_1<1;
299     Phi_2=(eval(subs(G4, {v}, {iota_2})))...
300         -eval(subs(G4, {v}, {iota_1})))^(q_2+p_2+r_2+s_2)...
301         /gamma(q_2+p_2+r_2+s_2+1)+(eval(subs(G4, {v}, {iota_2})))...
302         -eval(subs(G4, {v}, {iota_1})))^(p_2+r_2+s_2)...
303         /gamma(p_2+r_2+s_2+1)+(eval(subs(G4, {v}, {iota_2})))...
304         -eval(subs(G4, {v}, {iota_1})))^(r_2+s_2)...
305         /gamma(r_2+s_2+1)+(eval(subs(G4, {v}, {iota_2})))...
306         -eval(subs(G4, {v}, {iota_1})))^(s_2)/gamma(s_2+1);
307     MI(nn, column+4)=Phi_2*ell_2;
308     MI(nn, column+5)=Phi_2*ell_2<1;
309     Phi=max(Phi_1, Phi_2);
310     MI(nn, column+6)=Phi;
311     MI(nn, column+7)=Phi*ell;
312     MI(nn, column+8)=Phi*ell<1;
313     M_10=int(abs(g_10), v, iota_1, t);
314     MI(nn, column+9)=M_10;
315     M_11=int(abs(g_11), v, iota_1, t);
316     MI(nn, column+10)=M_11;
317     M_12=int(abs(g_12), v, iota_1, t);
318     MI(nn, column+11)=M_12;
319     M_13=int(abs(g_13), v, iota_1, t);
320     MI(nn, column+12)=M_13;
321     M_20=int(abs(g_20), v, iota_1, iota_2);
322     MI(nn, column+13)=M_20;
323     M_21=int(abs(g_21), v, iota_1, t);
324     MI(nn, column+14)=M_21;
325     M_22=int(abs(g_22), v, iota_1, t);
326     MI(nn, column+15)=M_22;
327     M_23=int(abs(g_23), v, iota_1, t);
328     MI(nn, column+16)=M_23;
329     M_1j=max(max(max(M_10, M_11), M_12), M_13);
330     MI(nn, column+17)=M_1j;
331     M_2j=max(max(max(M_20, M_21), M_22), M_23);

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332 MI(nn, column+18)=M_2j;
333 Delta_1=M_10+M_11*(1+(eval(subs(G4, {v}, {iota_2}))...
334 -eval(subs(G4, {v}, {iota_1})))^(q_1)/gamma(q_1+1))...
335 +M_12*(1+(eval(subs(G4, {v}, {iota_2}))...
336 -eval(subs(G4, {v}, {iota_1})))^(p_1)/gamma(p_1+1))...
337 +eval(subs(G4, {v}, {iota_2}))...
338 -eval(subs(G4, {v}, {iota_1})))^(q_1+p_1)/gamma(q_1+p_1+1))...
339 +M_13*(1+(eval(subs(G4, {v}, {iota_2}))...
340 -eval(subs(G4, {v}, {iota_1})))^(r_1)/gamma(r_1+1))...
341 +(eval(subs(G4, {v}, {iota_2}))...
342 -eval(subs(G4, {v}, {iota_1})))^(p_1+r_1)/gamma(p_1+r_1+1))...
343 +(eval(subs(G4, {v}, {iota_2}))...
344 -eval(subs(G4, {v}, {iota_1})))^(q_1+p_1+r_1))...
345 /gamma(q_1+p_1+r_1+1));
346 MI(nn, column+19)=Delta_1;
347 Delta_2=M_20+M_21*(1+(eval(subs(G4, {v}, {iota_2}))...
348 -eval(subs(G4, {v}, {iota_1})))^(q_2)/gamma(q_2+1))...
349 +M_22*(1+(eval(subs(G4, {v}, {iota_2}))...
350 -eval(subs(G4, {v}, {iota_1})))^(p_2)/gamma(p_2+1))...
351 +(eval(subs(G4, {v}, {iota_2}))...
352 -eval(subs(G4, {v}, {iota_1})))^(q_2+p_2)/gamma(q_2+p_2+1))...
353 +M_23*(1+(eval(subs(G4, {v}, {iota_2}))...
354 -eval(subs(G4, {v}, {iota_1})))^(r_2)/gamma(r_2+1))...
355 +(eval(subs(G4, {v}, {iota_2}))...
356 -eval(subs(G4, {v}, {iota_1})))^(p_2+r_2)/gamma(p_2+r_2+1))...
357 +(eval(subs(G4, {v}, {iota_2}))...
358 -eval(subs(G4, {v}, {iota_1})))^(q_2+p_2+r_2))...
359 /gamma(q_2+p_2+r_2+1));
360 MI(nn, column+20)=Delta_2;
361 D1=(Delta_1+h_1_0*Phi_1)/(1-e11_1*Phi_1);
362 MI(nn, column+21)=D1;
363 D2=(Delta_2+h_2_0*Phi_1)/(1-e11_2*Phi_2);
364 MI(nn, column+22)=D2;
365 MI(nn, column+23)=max(D1, D2);
366 t=t+0.08;
367 nn=nn+1;
368 end;

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