



Research article

A solution of a nonlinear Volterra integral equation with delay via a faster iteration method

Godwin Amechi Okeke^{1,2}, Austine Efut Ofem^{3,4}, Thabet Abdeljawad^{5,6,*}, Manar A. Alqudah⁷ and Aziz Khan⁵

¹ Department of Mathematics, College of Science and Technology, Covenant University, Canaanland, KM 10, Idiroko Road, Ota, Ogun State, Nigeria

² Department of Mathematics, School of Physical Sciences, Federal University of Technology Owerri, P.M.B. 1526 Owerri, Imo State, Nigeria

³ Department of Mathematics, University of Uyo, Uyo, Nigeria

⁴ Department of Mathematics, Statistics and Computer Science, University of KwaZulu-Natal, Durban, South Africa

⁵ Department of Mathematics and Sciences, Prince Sultan University, P.O. Box 66833, Riyadh 11586, Saudi Arabia

⁶ Department of Medical Research, China Medical University, Taichung 40402, Taiwan

⁷ Department of Mathematical Sciences, Princess Nourah Bint Abdulrahman University, P.O. Box 84428, Riyadh 11671, Saudi Arabia

* **Correspondence:** Email: tabdeljawad@psu.edu.sa.

Abstract: The purpose of this article is to study the convergence, stability and data dependence results of an iterative method for contractive-like mappings. The concept of stability considered in this study is known as w^2 -stability, which is larger than the simple notion of stability considered by several prominent authors. Some illustrative examples on w^2 -stability of the iterative method have been presented for different choices of parameters and initial guesses. As an application of our results, we establish the existence, uniqueness and approximation results for solutions of a nonlinear Volterra integral equation with delay. Finally, we provide an illustrative example to support the application of our results. The novel results of this article extend and generalize several well known results in existing literature.

Keywords: Banach space; data dependence; w^2 -stability; contractive-like mapping; nonlinear Volterra integral equation; fixed point

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1. Introduction

Let \mathcal{B} be a Banach space and \mathcal{A} a nonempty closed convex subset of \mathcal{B} . Let $\mathcal{F} : \mathcal{A} \rightarrow \mathcal{A}$ be a mapping. A member $m^* \in \mathcal{A}$ is called a fixed point of \mathcal{F} if $\mathcal{F}m^* = m^*$. We denote the set of all fixed points of \mathcal{F} by $F(\mathcal{F})$.

In [6], Berinde introduced a new class of mappings satisfying

$$\|\mathcal{F}m - \mathcal{F}q\| \leq \gamma\|m - q\| + L\|m - \mathcal{F}m\|, \quad (1.1)$$

for all $m, q \in \mathcal{A}$, $\gamma \in (0, 1)$ and $L \geq 0$.

The author established that the class of mappings satisfying (1.1) is larger than the class of mappings introduced and studied by Zamfirescu in [41].

In [15], Imoru and Olantiwo gave a definition of a mapping considered to be generalization of the classes of mappings considered by Berinde [6], Osilike et al. [33] and some other existing contraction-type mappings as follows:

Definition 1.1. [15] A mapping $\mathcal{F} : \mathcal{A} \rightarrow \mathcal{A}$ is called contractive-like if there exists a constant $\gamma \in [0, 1)$ and a strictly increasing continuous function $\psi : [0, \infty) \rightarrow [0, \infty)$ with $\psi(0) = 0$ such that

$$\|\mathcal{F}m - \mathcal{F}q\| \leq \gamma\|m - q\| + \psi(\|m - \mathcal{F}m\|), \quad (1.2)$$

for all $m, q \in \mathcal{A}$.

Remark 1.1. If $\psi(m) = Lm$, then (1.2) reduces to (1.1).

Problems in so many fields of mathematics and other subjects in sciences can be transformed into an equation for a suitable operator. Furthermore, the existence of a solution to this equation is tantamount to the existence of a fixed point of the suitable operator. Basically, fixed point theory is a nice mixture of functional analysis, topology and geometry. Translating the real-life or theoretical problem into the fixed point problem is a good approach to find the corresponding solution. In general, fixed point theory plays a vital role in almost all areas of applied sciences and engineering such as: economics, game theory, theoretical computer science, biology, chemistry, physics and many more, see e.g. [8, 19, 20, 24–31].

Proving the existence of a fixed point is an important step in finding a solution of a given problem, but it is also necessary to find the solution of a given problem when it exists. One valuable way of finding the desired fixed point is to utilize iterative method. For this reason, so many iterative methods for approximating the fixed points of different classes of operators have been introduced and studied by so many authors for the past two decades. Some widely used iterative methods in the literature are: Mann [21], Ishikawa [16], Noor [23], S [2], Abbas and Nazir [1], Tharkur [36] and many more.

Throughout this paper, the set of all natural numbers is denoted by \mathbb{N} and the set of real numbers is denoted by \mathbb{R} . For the sequences $\{\vartheta_n\}$, $\{\varpi_n\}$ and $\{\varrho_n\}$ in $[0, 1]$, the following iterative methods are known as Noor, S and M, respectively:

$$\begin{cases} m_1 \in \mathcal{A}, \\ p_n = (1 - \varrho_n)m_n + \varrho_n\mathcal{F}m_n, \\ q_n = (1 - \vartheta_n)m_n + \vartheta_n\mathcal{F}p_n, \\ m_{n+1} = (1 - \varpi_n)m_n + \varpi_n\mathcal{F}q_n, \end{cases} \quad \forall n \in \mathbb{N}, \quad (1.3)$$

$$\begin{cases} m_1 \in \mathcal{A}, \\ q_n = (1 - \vartheta_n)m_n + \vartheta_n \mathcal{F} m_n, \\ m_{n+1} = (1 - \varpi_n) \mathcal{F} m_n + \varpi_n \mathcal{F} q_n, \end{cases} \quad \forall n \in \mathbb{N}, \quad (1.4)$$

$$\begin{cases} m_1 \in \mathcal{A}, \\ p_n = (1 - \varpi_n)m_n + \varpi_n \mathcal{F} m_n, \\ q_n = \mathcal{F} p_n, \\ m_{n+1} = \mathcal{F} q_n, \end{cases} \quad \forall n \in \mathbb{N}. \quad (1.5)$$

Very recently, Akutsah et al. [4] introduced the following three steps iterative method:

$$\begin{cases} m_1 \in \mathcal{A}, \\ p_n = (1 - \vartheta_n)m_n + \vartheta_n \mathcal{F} m_n, \\ q_n = \mathcal{F} p_n, \\ m_{n+1} = \mathcal{F}((1 - \varpi_n)q_n + \varpi_n \mathcal{F} q_n), \end{cases} \quad \forall n \in \mathbb{N}, \quad (1.6)$$

where $\{\vartheta_n\}$ and $\{\varpi_n\}$ are sequences in $[0,1]$. The authors analytically and numerically showed that the iterative method (1.6) converges faster than those of Ullah and Arshad [39], Karakaya et al. [18] and Thakur et al. [37], respectively for contractive-like mappings.

The preference of an iterative method over another is based on some crucial criteria such as fastness, stability and dependence. Data dependency of fixed points iterative methods has become an area that has attracted many researchers for several decades now. There exists several recent results on data dependency of fixed point, see e.g. [3, 5, 10, 11, 14, 22, 25, 32].

Due to the importance of data dependency in fixed point theory, Akutsah et al. [4] raised the following question:

Open Question: Is it possible to obtain the data dependence result of the iterative method (1.6) for contractive-like mappings?

On other hand, a fixed point iterative method is said to be numerically stable if small modifications in the initial data involved in a computation process will produce a small impact on the computed value of the fixed point. The concept of stability was first considered by Ostrowski [34] for Banach contraction mappings. In 1988, Harder and Hicks [12, 13] illustrated the importance of studying the stability of various iterative methods.

Definition 1.2. [12, 13] Let $\{t_n\}$ be any sequence in \mathcal{A} . Then, an iterative method $t_{n+1} = f(\mathcal{F}, t_n)$, which converges to fixed point m^* , is said to be \mathcal{F} -stable or stable with respect to \mathcal{F} , if for $\varepsilon_n = \|t_{n+1} - f(\mathcal{F}, t_n)\|$, $\forall n \in \mathbb{N}$, we have

$$\lim_{n \rightarrow \infty} \varepsilon_n = 0 \Leftrightarrow \lim_{n \rightarrow \infty} t_n = m^*.$$

In the last few years, many authors have studied the stability of several iterative methods for different classes of operators (see e.g. [11, 17, 22, 25] and the references in them). Very recently, Akutsah et al. [4] established the following convergence and stability results for contractive-like mapping in Banach spaces.

Theorem 1.1. [4] Let \mathcal{A} be a nonempty closed convex subset of a uniformly convex Banach space \mathcal{B} . Let \mathcal{F} be a mapping satisfying (1.2). Let $\{m_n\}$ be the iterative method defined in (1.6) with sequences $\{\vartheta_n\}, \{\varpi_n\} \in [0, 1]$ such that $\sum_{n=0}^{\infty} \varpi_n = \infty$. Then, $\{m_n\}$ converges strongly to a unique fixed point of \mathcal{F} .

Theorem 1.2. [4] Let \mathcal{A} be a nonempty closed convex subset of a uniformly convex Banach space \mathcal{B} . Let \mathcal{F} be a mapping satisfying (1.2). Let $\{m_n\}$ be the iterative method defined by (1.6) with sequences $\{\vartheta_n\}$ and $\{\varpi_n\}$ in $[0,1]$ such that $\sum_{n=0}^{\infty} \varpi_n = \infty$. Then, $\{m_n\}$ is \mathcal{F} -stable.

In 2007, Berinde [8] showed throughout an example that taking an arbitrary sequence $\{t_n\}$ in Definition 1.2 led to an inconsistency. For this reason, Berinde [8] redefined the Definition 1.2 and gave a weaker, but more natural notion of stability known as weak stability. According the author, an approximate sequence of $\{m_n\}$ instead of arbitrary sequence $\{t_n\}$ in Definition 1.2 should be taken.

In 2012, Timi [38] introduced a wider concept of stability known as weak w^2 -stability by adopting equivalent sequences instead of arbitrary sequences in Definition 1.2.

Definition 1.3. [38] Let $\{m_n\}$ be an iterative sequence given by $m_{n+1} = f(\mathcal{F}, m_n)$. Assume that $\{m_n\}$ converges to an $m^* \in F(\mathcal{F})$. Set

$$\epsilon_n = \|t_{n+1} - f(\mathcal{F}, t_n)\|, \quad \forall n \in \mathbb{N}.$$

If for any equivalent sequence $\{t_n\} \subset \mathcal{A}$ of $\{m_n\}$,

$$\lim_{n \rightarrow \infty} \epsilon_n = 0 \text{ implies } \lim_{n \rightarrow \infty} t_n = m^*,$$

then the iterative sequence $\{m_n\}$ is said to be weak w^2 -stable with respect to \mathcal{F} .

Motivated by the above results, we prove the strong convergence theorem of the iterative method (1.6) for contractive-like mappings without the necessity of the assumption: $\sum_{n=0}^{\infty} \varpi_n = \infty$ as considered in [4]. Also, we demonstrate the numerical convergence of (1.6) using a nontrivial example in higher dimensional space. Further, we prove analytically that the iterative method (1.6) is w^2 -stable and the analytical proof is supported with some illustrative examples. Also, we give an affirmative answer to the open question above which was raised in [4] by showing that the iterative method (1.6) is data dependent for contractive-like mappings. Furthermore, by applying our main results, we establish the existence, uniqueness and approximation results for the solutions of a nonlinear Volterra integral equation with delay. We also provide an example which supports the application of our results.

This paper is organized as follows: In Section 2, we list some definitions and lemmas which will be used for further proof. In Section 3, we establish the convergence result of the iterative method (1.6) for contractive-like mappings. A supporting example is also provided. In Section 4, we show that the iterative algorithm (1.6) is weak w^2 -stable with respect to contractive-like mappings. The analytic result is supported with a numerical example. In Section 5, we prove the data dependence result of the iterative algorithm (1.6). In Section 6, we apply our main results to solve a nonlinear Volterra integral equation with delay and Section 7 gives the conclusion of our article.

2. Preliminaries

In this section, we give some definitions and lemmas that will be useful in proving our main results.

Definition 2.1. [8] Let $\{m_n\}$ and $\{t_n\}$ be sequences in \mathcal{A} . We say that $\{t_n\}$ is an approximate sequence of $\{m_n\}$, if for any $r \in \mathbb{N}$, there exists $\epsilon(r)$ such that

$$\|m_n - t_n\| \leq \epsilon(r), \quad \forall n \geq r.$$

Definition 2.2. [7] Let $\mathcal{F}, \tilde{\mathcal{F}} : \mathcal{A} \rightarrow \mathcal{A}$ be two operators. We say that $\tilde{\mathcal{F}}$ is an approximate operator for \mathcal{F} if for some $\varepsilon > 0$, we have

$$\|\mathcal{F}m - \tilde{\mathcal{F}}m\| \leq \varepsilon, \quad \forall m \in \mathcal{A}. \quad (2.1)$$

Definition 2.3. [9] Let $\{m_n\}$ and $\{t_n\}$ be sequences in \mathcal{A} . We say that these sequences are equivalent if

$$\lim_{n \rightarrow \infty} \|m_n - t_n\| = 0.$$

Lemma 2.1. [40] Let $\{\theta_n\}$ and $\{\lambda_n\}$ be nonnegative real sequences satisfying the following inequalities:

$$\theta_{n+1} \leq (1 - \sigma_n)\theta_n + \lambda_n,$$

where $\sigma_n \in (0, 1)$ for all $n \in \mathbb{N}$, $\sum_{n=0}^{\infty} \sigma_n = \infty$ and $\lim_{n \rightarrow \infty} \frac{\lambda_n}{\sigma_n} = 0$, then $\lim_{n \rightarrow \infty} \theta_n = 0$.

Lemma 2.2. [35] Let $\{\theta_n\}$ be a nonnegative real sequence such that for all $n \geq n_0 \in \mathbb{N}$, the following condition holds:

$$\theta_{n+1} \leq (1 - \sigma_n)\theta_n + \sigma_n\lambda_n,$$

where $\sigma_n \in (0, 1)$ for all $n \in \mathbb{N}$, $\sum_{n=0}^{\infty} \sigma_n = \infty$ and $\lambda_n \geq 0$ for all $n \in \mathbb{N}$, then

$$0 \leq \limsup_{n \rightarrow \infty} \theta_n \leq \limsup_{n \rightarrow \infty} \lambda_n.$$

3. Convergence result

In this section, we will prove a strong convergence result of the iterative method (1.6) for contractive-like mapping by weakening some conditions imposed on the control parameters by Akutsah et al. [4]. We also provide an example in three dimensional space to compare the convergence of various iterative methods.

Theorem 3.1. Let \mathcal{F} be a mapping satisfying (1.2) defined on a nonempty closed convex subset \mathcal{A} of a Banach space \mathcal{B} with $F(\mathcal{F}) \neq \emptyset$. Let $\{m_n\}$ be the iterative sequence defined by (1.6), then $\{m_n\}$ converges strongly to the unique fixed point of \mathcal{F} .

Proof. From (1.6), for any $m^* \in F(\mathcal{F})$, we have

$$\begin{aligned} \|p_n - m^*\| &\leq (1 - \vartheta_n)\|m_n - m^*\| + \vartheta_n\|\mathcal{F}m_n - m^*\| \\ &= (1 - \vartheta_n)\|m_n - m^*\| + \vartheta_n\|\mathcal{F}m^* - \mathcal{F}m_n\| \\ &\leq (1 - \vartheta_n)\|m_n - m^*\| + \gamma\vartheta_n\|m_n - m^*\| + \vartheta_n\psi(\|m^* - \mathcal{F}m^*\|) \\ &= (1 - (1 - \gamma)\vartheta_n)\|m_n - m^*\|. \end{aligned} \quad (3.1)$$

$$\|q_n - m^*\| = \|\mathcal{F} p_n - m^*\| \leq \gamma \|p_n - m^*\| \leq \gamma(1 - (1 - \gamma)\vartheta_n) \|m_n - m^*\|. \quad (3.2)$$

$$\begin{aligned} \|m_{n+1} - m^*\| &= \|\mathcal{F}((1 - \varpi_n)q_n + \varpi_n \mathcal{F} q_n) - m^*\| \\ &\leq \gamma \|(1 - \varpi_n)q_n + \varpi_n \mathcal{F} q_n - m^*\| \\ &\leq \gamma((1 - \varpi_n)\|q_n - m^*\| + \varpi_n \|\mathcal{F} q_n - m^*\|) \\ &\leq \gamma((1 - \varpi_n)\|q_n - m^*\| + \varpi_n \gamma \|q_n - m^*\|) \\ &= \gamma(1 - (1 - \gamma)\varpi_n) \|q_n - m^*\| \\ &\leq \gamma^2(1 - (1 - \gamma)\varpi_n)(1 - (1 - \gamma)\vartheta_n) \|m_n - m^*\|. \end{aligned} \quad (3.3)$$

Since $\{\vartheta_n\}, \{\varpi_n\} \in [0, 1]$ and $\gamma \in [0, 1)$, then it follows that $(1 - (1 - \gamma)\vartheta_n) < 1$ and $(1 - (1 - \gamma)\varpi_n) < 1$. Hence, (3.3) yields

$$\begin{aligned} \|m_{n+1} - m^*\| &\leq \gamma^2 \|m_n - m^*\| \\ &\vdots \\ &\leq \gamma^{2n} \|m_1 - m^*\|. \end{aligned} \quad (3.4)$$

Taking limit on both sides of the above inequality (3.4), we get $\lim_{n \rightarrow \infty} \|m_n - m^*\| = 0$. Indeed, $\gamma \in [0, 1)$ and so $\lim_{n \rightarrow \infty} \gamma^{2n} = 0$. \square

Remark 3.1. Clearly, the condition $\sum_{n=0}^{\infty} \varpi_n = \infty$ on the sequence $\{\varpi_n\} \in (0, 1)$ in Theorem 1.1 is *superfluous*.

Now we give the following example to validate the analytical proof in Theorem 6.1 and also carry out a numerical experiment to test the efficiency of the iterative method (1.6).

Example 3.1. Let $\mathcal{A} = [0, 8] \times [0, 8] \times [0, 8]$ be the subset of a Banach space $\mathcal{B} = \mathbb{R}^3$ with the taxicab norm. Let $\mathcal{F} : \mathcal{A} \rightarrow \mathcal{A}$ be defined by

$$\mathcal{F}(m_1, m_2, m_3) = \begin{cases} \left(\frac{m_1}{7}, \frac{m_2}{7}, \frac{m_3}{7}\right), & \text{if } (m_1, m_2, m_3) \in [0, 4) \times [0, 4) \times [0, 4), \\ \left(\frac{m_1}{14}, \frac{m_2}{14}, \frac{m_3}{14}\right), & \text{if } (m_1, m_2, m_3) \in [4, 8] \times [4, 8] \times [4, 8]. \end{cases}$$

Clearly, the only fixed point of \mathcal{F} is $(0, 0, 0)$. We will now show that \mathcal{F} is a contraction-like mapping. To see this, we define a function $\psi : \mathbb{R}^+ \rightarrow \mathbb{R}^+$ by $\psi(m) = \frac{m}{12}$. Clearly, ψ is a strictly increasing and continuous function satisfying $\psi(0) = 0$. We show that

$$\|\mathcal{F} m - \mathcal{F} q\| = \gamma \|m - q\| + \psi(\|m - \mathcal{F} m\|), \quad (3.5)$$

for all $p, q \in \mathcal{A}$ and $\gamma \in [0, 1)$. It will be useful to note the following. If $m = (m_1, m_2, m_3) \in [0, 4) \times [0, 4) \times [0, 4)$, then

$$\|m - \mathcal{F} m\| = \left\| (m_1, m_2, m_3) - \left(\frac{m_1}{7}, \frac{m_2}{7}, \frac{m_3}{7}\right) \right\| = \left\| \left(\frac{6m_1}{7}, \frac{6m_2}{7}, \frac{6m_3}{7}\right) \right\|$$

and

$$\begin{aligned}\psi(\|m - \mathcal{F}m\|) &= \psi\left(\left\|\left(\frac{6m_1}{7}, \frac{6m_2}{7}, \frac{6m_3}{7}\right)\right\|\right) \\ &= \left\|\left(\frac{m_1}{14}, \frac{m_2}{14}, \frac{m_3}{14}\right)\right\| = \left|\frac{m_1}{14}\right| + \left|\frac{m_2}{14}\right| + \left|\frac{m_3}{14}\right|.\end{aligned}\quad (3.6)$$

Similarly, if $m = (m_1, m_2, m_3) \in [4, 8] \times [4, 8] \times [4, 8]$, we have

$$\|m - \mathcal{F}m\| = \left\|(m_1, m_2, m_3) - \left(\frac{m_1}{14}, \frac{m_2}{14}, \frac{m_3}{14}\right)\right\| = \left\|\left(\frac{13m_1}{14}, \frac{13m_2}{14}, \frac{13m_3}{14}\right)\right\|$$

and

$$\begin{aligned}\psi(\|m - \mathcal{F}m\|) &= \psi\left(\left\|\left(\frac{13m_1}{14}, \frac{13m_2}{14}, \frac{13m_3}{14}\right)\right\|\right) \\ &= \left\|\left(\frac{13m_1}{168}, \frac{13m_2}{168}, \frac{13m_3}{168}\right)\right\| \\ &= \left|\frac{13m_1}{168}\right| + \left|\frac{13m_2}{168}\right| + \left|\frac{13m_3}{168}\right|.\end{aligned}\quad (3.7)$$

Next, we consider the following cases:

Case I: If $m = (m_1, m_2, m_3), q = (q_1, q_2, q_3) \in [0, 4) \times [0, 4) \times [0, 4)$, then using (3.6), we have

$$\begin{aligned}\|\mathcal{F}m - \mathcal{F}q\| &= \left\|\left(\frac{m_1}{7}, \frac{m_2}{7}, \frac{m_3}{7}\right) - \left(\frac{q_1}{7}, \frac{q_2}{7}, \frac{q_3}{7}\right)\right\| \\ &= \frac{1}{7}|m_1 - q_1| + \frac{1}{7}|m_2 - q_2| + \frac{1}{7}|m_3 - q_3| \\ &= \frac{1}{7}\|(m_1, m_2, m_3) - (q_1, q_2, q_3)\| \\ &\leq \frac{1}{7}\|m - q\| + \left|\frac{m_1}{14}\right| + \left|\frac{m_2}{14}\right| + \left|\frac{m_3}{14}\right| \\ &= \frac{1}{7}\|m - q\| + \psi(\|m - \mathcal{F}m\|).\end{aligned}$$

Case II: If $m = (m_1, m_2, m_3), q = (q_1, q_2, q_3) \in [4, 8] \times [4, 8] \times [4, 8]$, then using (3.7), we get

$$\begin{aligned}\|\mathcal{F}m - \mathcal{F}q\| &= \left\|\left(\frac{m_1}{14}, \frac{m_2}{14}, \frac{m_3}{14}\right) - \left(\frac{q_1}{14}, \frac{q_2}{14}, \frac{q_3}{14}\right)\right\| \\ &= \frac{1}{14}|m_1 - q_1| + \frac{1}{14}|m_2 - q_2| + \frac{1}{14}|m_3 - q_3| \\ &= \frac{1}{14}\|(m_1, m_2, m_3) - (q_1, q_2, q_3)\| \\ &\leq \frac{1}{7}\|m - q\| + \left|\frac{13m_1}{168}\right| + \left|\frac{13m_2}{168}\right| + \left|\frac{13m_3}{168}\right| \\ &= \frac{1}{7}\|m - q\| + \psi(\|m - \mathcal{F}m\|).\end{aligned}$$

Case III: If $m = (m_1, m_2, m_3) \in [0, 4) \times [0, 4) \times [0, 4)$ and $q = (q_1, q_2, q_3) \in [4, 8] \times [4, 8] \times [4, 8]$, then using (3.6), we have

$$\begin{aligned}
 \|\mathcal{F}m - \mathcal{F}q\| &= \left\| \left(\frac{m_1}{7}, \frac{m_2}{7}, \frac{m_3}{7} \right) - \left(\frac{m_1}{14}, \frac{m_2}{14}, \frac{m_3}{14} \right) \right\| \\
 &= \left\| \left(\frac{m_1}{7} - \frac{q_1}{14}, \frac{m_2}{7} - \frac{q_2}{14}, \frac{m_3}{7} - \frac{q_3}{14} \right) \right\| \\
 &= \left\| \left(\frac{m_1}{14} + \frac{m_1}{14} - \frac{q_1}{14}, \frac{m_2}{14} + \frac{m_2}{14} - \frac{q_2}{14}, \frac{m_3}{14} + \frac{m_3}{14} - \frac{q_3}{14} \right) \right\| \\
 &= \left| \frac{m_1}{14} + \frac{m_1}{14} - \frac{q_1}{14} \right| + \left| \frac{m_2}{14} + \frac{m_2}{14} - \frac{q_2}{14} \right| + \left| \frac{m_3}{14} + \frac{m_3}{14} - \frac{q_3}{14} \right| \\
 &\leq \left| \frac{m_1}{14} \right| + \left| \frac{m_2}{14} \right| + \left| \frac{m_3}{14} \right| + \left| \frac{m_1}{14} - \frac{q_1}{14} \right| + \left| \frac{m_2}{14} - \frac{q_2}{14} \right| + \left| \frac{m_3}{14} - \frac{q_3}{14} \right| \\
 &= \frac{1}{14} (|m_1 - q_1| + |m_2 - q_2| + |m_3 - q_3|) + \psi(\|m - \mathcal{F}m\|) \\
 &\leq \frac{1}{7} \|(m_1, m_2, m_3) - (q_1, q_2, q_3)\| + \psi(\|m - \mathcal{F}m\|) \\
 &= \frac{1}{7} \|m - q\| + \psi(\|m - \mathcal{F}m\|).
 \end{aligned}$$

Case IV: If $m = (m_1, m_2, m_3) \in [4, 8] \times [4, 8] \times [4, 8]$ and $q = (q_1, q_2, q_3) \in [0, 4) \times [0, 4) \times [0, 4)$, then using (3.6), we get

$$\begin{aligned}
 \|\mathcal{F}m - \mathcal{F}q\| &= \left\| \left(\frac{m_1}{14}, \frac{m_2}{14}, \frac{m_3}{14} \right) - \left(\frac{m_1}{7}, \frac{m_2}{7}, \frac{m_3}{7} \right) \right\| \\
 &= \left\| \left(\frac{m_1}{14} - \frac{q_1}{7}, \frac{m_2}{14} - \frac{q_2}{7}, \frac{m_3}{14} - \frac{q_3}{7} \right) \right\| \\
 &= \left\| \left(\frac{m_1}{7} - \frac{m_1}{14} - \frac{q_1}{7}, \frac{m_2}{7} - \frac{m_2}{14} - \frac{q_2}{7}, \frac{m_3}{7} - \frac{m_3}{14} - \frac{q_3}{7} \right) \right\| \\
 &= \left| \frac{m_1}{7} - \frac{m_1}{14} - \frac{q_1}{7} \right| + \left| \frac{m_2}{7} - \frac{m_2}{14} - \frac{q_2}{7} \right| + \left| \frac{m_3}{7} - \frac{m_3}{14} - \frac{q_3}{7} \right| \\
 &\leq \left| \frac{m_1}{14} \right| + \left| \frac{m_2}{14} \right| + \left| \frac{m_3}{14} \right| + \left| \frac{m_1}{7} - \frac{q_1}{7} \right| + \left| \frac{m_2}{7} - \frac{q_2}{7} \right| + \left| \frac{m_3}{7} - \frac{q_3}{7} \right| \\
 &= \frac{1}{7} (|m_1 - q_1| + |m_2 - q_2| + |m_3 - q_3|) + \psi(\|m - \mathcal{F}m\|) \\
 &= \frac{1}{7} \|(m_1, m_2, m_3) - (q_1, q_2, q_3)\| + \psi(\|m - \mathcal{F}m\|) \\
 &= \frac{1}{7} \|m - q\| + \psi(\|m - \mathcal{F}m\|).
 \end{aligned}$$

So, (3.5) is fulfilled with $\gamma = \frac{1}{7}$. Thus, \mathcal{F} is a contractive-like mapping.

It is worthy mentioning that the above example is more interesting and not as simple as that of Akutsah et al. [4].

Using MATLAB R2015a, we obtain the following Tables 1–3 and Figures 1–3. Clearly, for control sequences $\varpi_n = \vartheta_n = \varrho_n = 0.8$ and starting value $m_0 = (2, 2.5, 3.5)$, the iterative method (1.6) converges faster than a number of iterative methods. We also notice that M, Thakur and Karakaya iterative methods converge almost at the same rate.

Table 1. Convergence behavior of various iterative methods.

Step	Noor	Akutsah
1	(2.000000, 2.500000, 3.500000)	(2.000000, 2.500000, 3.500000)
2	(0.453924, 0.567405, 0.794367)	(0.004032, 0.005040, 0.007055)
3	(0.103024, 0.128779, 0.180291)	(0.000008, 0.000010, 0.000014)
4	(0.023382, 0.029228, 0.040919)	(0.000000, 0.000000, 0.000000)
5	(0.005307, 0.006634, 0.009287)	(0.000000, 0.000000, 0.000000)
6	(0.001204, 0.001506, 0.002108)	(0.000000, 0.000000, 0.000000)
7	(0.000273, 0.000342, 0.000478)	(0.000000, 0.000000, 0.000000)
8	(0.000062, 0.000078, 0.000109)	(0.000000, 0.000000, 0.000000)
9	(0.000014, 0.000018, 0.000025)	(0.000000, 0.000000, 0.000000)
10	(0.000003, 0.000004, 0.000006)	(0.000000, 0.000000, 0.000000)
11	(0.000001, 0.000001, 0.000001)	(0.000000, 0.000000, 0.000000)
12	(0.000000, 0.000000, 0.000000)	(0.000000, 0.000000, 0.000000)

Table 2. Convergence behavior of various iterative methods.

Step	S	Akutsah
1	(2.000000, 2.500000, 3.500000)	(2.000000, 2.500000, 3.500000)
2	(0.128980, 0.161224, 0.225714)	(0.004032, 0.005040, 0.007055)
3	(0.008318, 0.010397, 0.014556)	(0.000008, 0.000010, 0.000014)
4	(0.000536, 0.000671, 0.000939)	(0.000000, 0.000000, 0.000000)
5	(0.000035, 0.000043, 0.000061)	(0.000000, 0.000000, 0.000000)
6	(0.000002, 0.000003, 0.000004)	(0.000000, 0.000000, 0.000000)
7	(0.000000, 0.000000, 0.000000)	(0.000000, 0.000000, 0.000000)

Table 3. Convergence behavior of various iterative methods.

Step	Noor	M
1	(2.000000, 2.500000, 3.500000)	(2.000000, 2.500000, 3.500000)
2	(0.012828, 0.016035, 0.022449)	(0.004032, 0.005040, 0.007055)
3	(0.000082, 0.000103, 0.000144)	(0.000008, 0.000010, 0.000014)
4	(0.000001, 0.000001, 0.000001)	(0.000000, 0.000000, 0.000000)
5	(0.000000, 0.000000, 0.000000)	(0.000000, 0.000000, 0.000000)

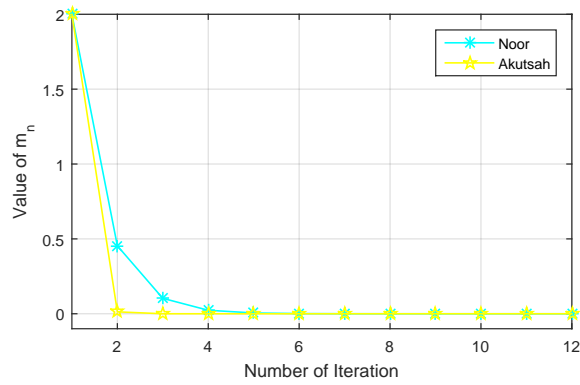


Figure 1. Graph corresponding to Table 1.

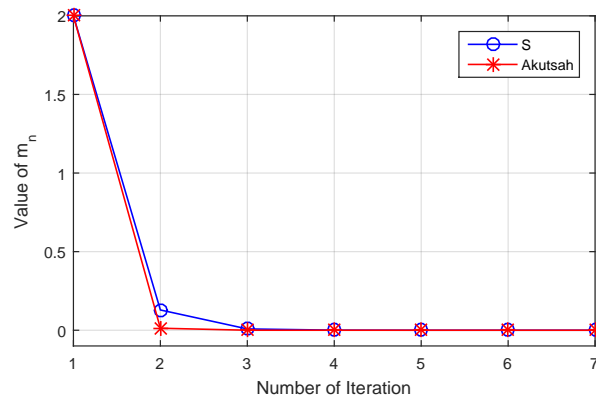


Figure 2. Graph corresponding to Table 2.

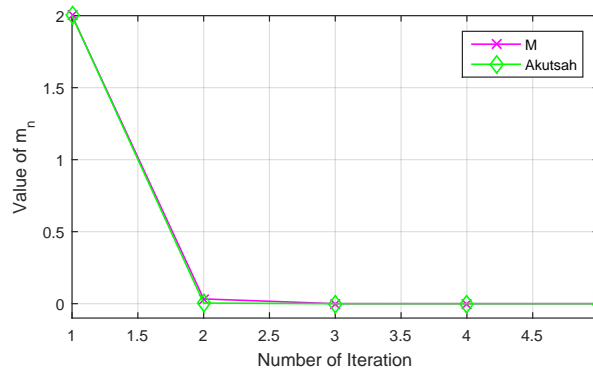


Figure 3. Graph corresponding to Table 3.

4. Stability result

In this section, we prove a stability result and provide some numerical examples to support our analytical proof.

Theorem 4.1. *Let \mathcal{F} be a mapping satisfying (1.2) defined on a nonempty closed convex subset \mathcal{A} of a Banach space \mathcal{B} with $F(\mathcal{F}) \neq 0$. Let $\{m_n\}$ be the iterative sequence defined by (1.6), then $\{m_n\}$ is weak w^2 -stable with respect to \mathcal{F} .*

Proof. Let $\{t_n\} \in \mathcal{A}$ be an equivalent sequence of $\{m_n\}$. Define a sequence $\{\epsilon_n\}$ in \mathbb{R}^+ by

$$\begin{cases} \epsilon_n = \|t_{n+1} - \mathcal{F}((1 - \varpi_n)r_n + \varpi_n\mathcal{F}r_n)\|, \\ r_n = \mathcal{F}d_n, \\ d_n = (1 - \vartheta_n)t_n + \vartheta_n\mathcal{F}t_n, \end{cases} \quad \forall n \in \mathbb{N}, \quad (4.1)$$

where $\{\vartheta_n\}$ and $\{\varpi_n\}$ are sequences in $[0, 1]$. Let $\lim_{n \rightarrow \infty} \epsilon_n = 0$, then from (1.2), (1.6) and (4.1), we have

$$\begin{aligned} \|t_{n+1} - m^*\| &\leq \|t_{n+1} - m_{n+1}\| + \|m_{n+1} - m^*\| \\ &\leq \|t_{n+1} - \mathcal{F}((1 - \varpi_n)r_n + \varpi_n\mathcal{F}r_n)\| \\ &\quad + \|\mathcal{F}((1 - \varpi_n)r_n + \varpi_n\mathcal{F}r_n) - m_{n+1}\| + \|m_{n+1} - m^*\| \\ &= \epsilon_n + \|\mathcal{F}((1 - \varpi_n)q_n + \varpi_n\mathcal{F}q_n) - \mathcal{F}((1 - \varpi_n)r_n + \varpi_n\mathcal{F}r_n)\| + \|m_{n+1} - m^*\| \\ &\leq \epsilon_n + \gamma\|(1 - \varpi_n)q_n + \varpi_n\mathcal{F}q_n - (1 - \varpi_n)r_n - \varpi_n\mathcal{F}r_n\| \\ &\quad + \psi(\|(1 - \varpi_n)q_n + \varpi_n\mathcal{F}q_n - \mathcal{F}((1 - \varpi_n)q_n + \varpi_n\mathcal{F}q_n)\|) + \|m_{n+1} - m^*\| \\ &\leq \epsilon_n + \gamma(1 - \varpi_n)\|q_n - r_n\| + \gamma\varpi_n\|\mathcal{F}q_n - \mathcal{F}r_n\| \\ &\quad + \psi(\|(1 - \varpi_n)q_n + \varpi_n\mathcal{F}q_n - \mathcal{F}((1 - \varpi_n)q_n + \varpi_n\mathcal{F}q_n)\|) + \|m_{n+1} - m^*\| \\ &\leq \epsilon_n + \gamma(1 - \varpi_n)\|q_n - r_n\| + \gamma^2\varpi_n\|q_n - r_n\| + \gamma\varpi_n\psi(\|q_n - \mathcal{F}q_n\|) \\ &\quad + \psi(\|(1 - \varpi_n)q_n + \varpi_n\mathcal{F}q_n - \mathcal{F}((1 - \varpi_n)q_n + \varpi_n\mathcal{F}q_n)\|) + \|m_{n+1} - m^*\| \\ &= \epsilon_n + \gamma(1 - (1 - \gamma)\varpi_n)\|q_n - r_n\| + \gamma\varpi_n\psi(\|q_n - \mathcal{F}q_n\|) \\ &\quad + \psi(\|(1 - \varpi_n)q_n + \varpi_n\mathcal{F}q_n - \mathcal{F}((1 - \varpi_n)q_n + \varpi_n\mathcal{F}q_n)\|) + \|m_{n+1} - m^*\|. \end{aligned} \quad (4.2)$$

$$\|q_n - r_n\| = \|\mathcal{F}p_n - \mathcal{F}d_n\| \leq \gamma\|p_n - d_n\| + \psi(\|p_n - \mathcal{F}p_n\|). \quad (4.3)$$

$$\begin{aligned} \|p_n - d_n\| &= \|(1 - \vartheta_n)m_n + \vartheta_n\mathcal{F}m_n - (1 - \vartheta_n)t_n - \vartheta_n\mathcal{F}t_n\| \\ &\leq (1 - \vartheta_n)\|m_n - t_n\| + \vartheta_n\|\mathcal{F}m_n - \mathcal{F}t_n\| \\ &\leq (1 - \vartheta_n)\|m_n - t_n\| + \gamma\vartheta_n\|m_n - t_n\| + \vartheta_n(\|m_n - \mathcal{F}m_n\|) \\ &= (1 - (1 - \gamma)\vartheta_n)\|m_n - t_n\| + \vartheta_n\psi(\|m_n - \mathcal{F}m_n\|). \end{aligned} \quad (4.4)$$

Using (4.2)–(4.4), we have

$$\begin{aligned}
\|t_{n+1} - m^*\| &\leq \epsilon_n + \gamma^2(1 - (1 - \gamma)\varpi_n)(1 - (1 - \gamma)\vartheta_n)\|m_n - t_n\| \\
&\quad + \gamma(1 - (1 - \gamma)\varpi_n)\vartheta_n\psi(\|m_n - \mathcal{F}m_n\|) \\
&\quad + (1 - (1 - \gamma)\varpi_n)\psi(\|p_n - \mathcal{F}p_n\|) + \gamma\varpi_n\psi(\|q_n - \mathcal{F}q_n\|) \\
&\quad + \psi(\|(1 - \varpi_n)q_n + \varpi_n\mathcal{F}q_n - \mathcal{F}((1 - \varpi_n)q_n + \varpi_n\mathcal{F}q_n)\|) \\
&\quad + \|m_{n+1} - m^*\|.
\end{aligned} \tag{4.5}$$

Since $\{t_n\} \in \mathcal{A}$ and its equivalence to $\{m_n\}$ yields $\lim_{n \rightarrow \infty} \|m_n - t_n\| = 0$. We have shown in Theorem 3.1 that $\|m_n - m^*\| = 0$, consequently $\lim_{n \rightarrow \infty} \|m_{n+1} - m^*\| = 0$. This implies that

$$\begin{aligned}
\|m_n - \mathcal{F}m_n\| &\leq \|m_n - m^*\| + \|\mathcal{F}m^* - \mathcal{F}m_n\| \\
&\leq (1 + \gamma)\|m_n - m^*\| \rightarrow 0, \text{ as } n \rightarrow \infty.
\end{aligned}$$

Following similar argument as above, we have that

$$\lim_{n \rightarrow \infty} \|m_n - \mathcal{F}m_n\| = \lim_{n \rightarrow \infty} \|p_n - \mathcal{F}p_n\| = \lim_{n \rightarrow \infty} \|q_n - \mathcal{F}q_n\| = 0. \tag{4.6}$$

Since $\lim_{n \rightarrow \infty} \|m_n - \mathcal{F}m_n\| = \psi(\lim_{n \rightarrow \infty} \|m_n - \mathcal{F}m_n\|) = 0$. It follows that

$$\begin{aligned}
\lim_{n \rightarrow \infty} \|m_n - \mathcal{F}m_n\| &= \psi(\lim_{n \rightarrow \infty} \|m_n - \mathcal{F}m_n\|) = \lim_{n \rightarrow \infty} \|p_n - \mathcal{F}p_n\| \\
&= \psi(\lim_{n \rightarrow \infty} \lim_{n \rightarrow \infty} \|p_n - \mathcal{F}p_n\|) = \lim_{n \rightarrow \infty} \|q_n - \mathcal{F}q_n\| \\
&= \psi(\lim_{n \rightarrow \infty} \|q_n - \mathcal{F}q_n\|) = 0.
\end{aligned} \tag{4.7}$$

Also,

$$\begin{aligned}
&\|(1 - \varpi_n)q_n + \varpi_n\mathcal{F}q_n - \mathcal{F}((1 - \varpi_n)q_n + \varpi_n\mathcal{F}q_n)\| \\
&\leq \|(1 - \varpi_n)q_n + \varpi_n\mathcal{F}q_n - \mathcal{F}m^*\| + \|\mathcal{F}m^* - \mathcal{F}((1 - \varpi_n)q_n + \varpi_n\mathcal{F}q_n)\| \\
&\leq (1 - \varpi_n)\|q_n - m^*\| + \gamma\varpi_n\|q_n - m^*\| + \varpi_n\psi(\|q_n - \mathcal{F}q_n\|) \\
&\quad + \gamma\|m^* - ((1 - \varpi_n)q_n + \varpi_n\mathcal{F}q_n)\| \\
&\leq (1 - \varpi_n)\|q_n - m^*\| + \gamma\varpi_n\|q_n - m^*\| + \varpi_n\psi(\|q_n - \mathcal{F}q_n\|) \\
&\quad + \gamma\|m^* - ((1 - \varpi_n)q_n + \varpi_n\mathcal{F}q_n)\| \\
&\leq (1 - \varpi_n)\|q_n - m^*\| + \gamma\varpi_n\|q_n - m^*\| + \varpi_n\psi(\|q_n - \mathcal{F}q_n\|) \\
&\quad + \gamma(1 - \varpi_n)\|q_n - m^*\| + \gamma^2\varpi_n\|q_n - m^*\| + \gamma\varpi_n\psi(\|q_n - \mathcal{F}q_n\|) \\
&= (1 + \gamma)(1 - (1 - \gamma)\varpi_n)\|q_n - m^*\| \\
&\quad + \varpi_n(1 + \gamma)\psi(\|q_n - \mathcal{F}q_n\|) \rightarrow 0, \text{ as } n \rightarrow \infty.
\end{aligned} \tag{4.8}$$

Therefore, from (4.8), we have

$$\lim_{n \rightarrow \infty} \psi(\|(1 - \varpi_n)q_n + \varpi_n\mathcal{F}q_n - \mathcal{F}((1 - \varpi_n)q_n + \varpi_n\mathcal{F}q_n)\|) = 0. \tag{4.9}$$

Thus, taking the limit on both sides of (4.5), we get

$$\lim_{n \rightarrow \infty} \|t_n - m^*\| = 0. \tag{4.10}$$

Hence, $\{m_n\}$ is weak w^2 -stable with respect to \mathcal{F} . \square

Now, we furnish the following examples in support of the above claim.

Example 4.1. Let $\mathcal{B} = \mathbb{R}$ with the usual norm and $\mathcal{A} = [0, 1]$ be a subset of \mathcal{B} . Define a mapping $\mathcal{F} : \mathcal{A} \rightarrow \mathcal{A}$ by

$$\mathcal{F}m = \frac{1}{2} \sin m. \quad (4.11)$$

Clearly, zero is the fixed point of \mathcal{F} . Now we show that \mathcal{F} is a weak contractive-like mapping satisfying (1.2). For this, let $\gamma = \frac{1}{2}$ and given as increasing function $\psi : [0, \infty) \rightarrow [0, \infty)$ with $\psi(0) = 0$, then we obtain

$$\begin{aligned} & |\mathcal{F}m - \mathcal{F}q| - \gamma|m - q| - \psi(|m - \mathcal{F}m|) \\ &= \frac{1}{2}|\sin m - \sin q| - \frac{1}{2}|m - q| - \psi\left(\left|m - \frac{1}{2} \sin m\right|\right) \\ &\leq \frac{1}{2}|m - q| - \frac{1}{2}|m - q| - \psi\left(\left|\frac{2m - \sin m}{2}\right|\right) \\ &= -\psi\left(\left|\frac{2m - \sin m}{2}\right|\right) \leq 0. \end{aligned}$$

The iterative method (1.6) corresponding to the operator \mathcal{F} in (4.11) is defined as follows:

$$\begin{cases} m_1 \in \mathcal{A}, \\ p_n = (1 - \vartheta_n)m_n + \vartheta_n \frac{1}{2} \sin(m_n), \\ q_n = \frac{1}{2} \sin(p_n), \\ m_{n+1} = \frac{1}{2} \sin((1 - \varpi_n)q_n + \varpi_n \frac{1}{2} \sin(q_n)), \end{cases} \quad \forall n \in \mathbb{N}, \quad (4.12)$$

where $\{\vartheta_n\}$ and $\{\varpi_n\}$ are sequences in $[0, 1]$.

Let $\vartheta_n = \varpi_n = \frac{1}{n+2}$. Using MATLAB R2015a, the following Table 4 and Figure 4 are obtained. They show that the iterative method $\{m_n\}$ in (4.12) converges to $m^* = 0$ for different choices of starting point $m_1 \in [0, 1]$.

Table 4. Convergence behavior of iterative method (1.6) for different choices of starting value m_1 in $[0, 1]$.

Step/IV	0.2	0.4	0.6	0.8
1	0.2000000000	0.4000000000	0.6000000000	0.8000000000
2	0.0344808485	0.0675512472	0.0979783982	0.1248374991
3	0.0059850135	0.0117182915	0.0169816155	0.0216142376
4	0.0010390583	0.0020343767	0.0029480484	0.0037521651
5	0.0001803920	0.0003531901	0.0005118132	0.0006514160
6	0.0000313181	0.0000613177	0.0000888565	0.0001130930
7	0.0000054372	0.0000106454	0.0000154265	0.0000196342
8	0.0000009440	0.0000018482	0.0000026782	0.0000034087
9	0.0000001639	0.0000003209	0.0000004650	0.0000005918
10	0.0000000285	0.0000000557	0.0000000807	0.0000001027

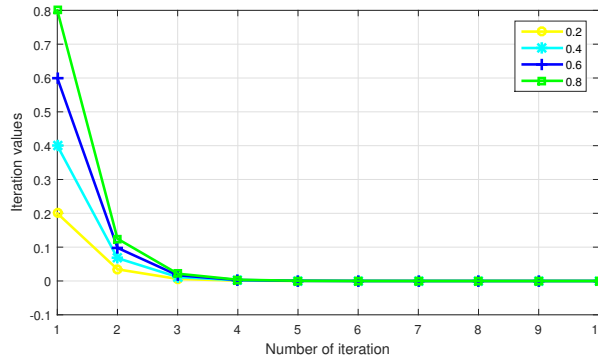


Figure 4. Graph corresponding to Table 4.

From the above table and graph, it is evident that $\lim_{n \rightarrow \infty} m_n = 0 = m^* \in F(\mathcal{F})$. On the other hand, we obtain $\lim_{n \rightarrow \infty} \|m_n\| = \|\lim_{n \rightarrow \infty} m_n\| = 0$. If we take the sequence $\{t_n\}$ as $t_n = \frac{1}{n+3}$ for all $n \in \mathbb{N}$, then we have

$$0 \leq \lim_{n \rightarrow \infty} \|m_n - t_n\| \leq \lim_{n \rightarrow \infty} \|m_n\| + \lim_{n \rightarrow \infty} \|t_n\| = 0,$$

which yields $\lim_{n \rightarrow \infty} \|m_n - t_n\| = 0$. This implies that the sequences $\{m_n\}$ and $\{t_n\}$ are equivalent.

Now, we show that (1.6) is weak w^2 -stable with respect to \mathcal{F} .

$$\begin{aligned} \epsilon_n &= |t_{n+1} - f(\mathcal{F}, t_n)| \\ &= \left| \frac{1}{n+4} - \left(\frac{1}{2} \sin \left\{ \frac{n+1}{n+2} \frac{1}{2} \sin \left(\left(\frac{n+1}{n+2} \right) \left(\frac{1}{n+3} \right) + \frac{1}{n+2} \frac{1}{2} \sin \left(\frac{1}{n+3} \right) \right) + \frac{1}{n+2} \frac{1}{2} \sin \left(\frac{1}{n+3} \right) \right\} \right) \right|. \end{aligned}$$

Clearly, $\lim_{n \rightarrow \infty} \epsilon_n = 0$. Therefore, the iterative method $\{m_n\}$ is weak w^2 -stable with respect to \mathcal{F} .

Example 4.2. Let $\mathcal{B} = \mathbb{R}$ with the usual norm and $\mathcal{A} = [0, 1]$ be a subset of \mathcal{B} . Define a mapping $\mathcal{F} : \mathcal{A} \rightarrow \mathcal{A}$ by

$$\mathcal{F} m = \frac{m}{5}. \tag{4.13}$$

Apparently, zero is the fixed point of \mathcal{F} and \mathcal{F} satisfies (1.2) with $\gamma = \frac{1}{5}$.

Now, we show that the iterative sequence $\{m_n\}_{n=0}^\infty$ in (1.6) converges to $p = 0 \in F(\mathcal{F})$ for different choices of real sequences in $\{\varpi_n\}, \{\vartheta_n\}$ in $[0, 1]$. Let $\{m_n^{(1)}\}_{n=0}^\infty, \{m_n^{(2)}\}_{n=0}^\infty, \{m_n^{(3)}\}_{n=0}^\infty$ be the iterative method (1.6) with control parameters $(\varpi_n = \vartheta_n = \frac{1}{n+1}), (\varpi_n = \vartheta_n = \frac{1}{2n+1})$ and $(\varpi_n = \frac{1}{n+2}, \vartheta_n = \frac{n+1}{2n+1})$ for all $n \in \mathbb{N}$, respectively.

For arbitrary $x_1 \in [0, 1]$, it follows that

$$\begin{aligned} p_n^{(1)} &= \left(1 - \frac{4}{5(n+1)} \right) m_n, \\ q_n^{(1)} &= \frac{1}{5} \left(1 - \frac{4}{5(n+1)} \right) m_n, \end{aligned}$$

$$\begin{aligned}
m_{n+1}^{(1)} &= \frac{1}{25} \left(1 - \frac{8}{5(n+1)} + \frac{16}{25(n+1)^2} \right) m_n \\
&= \left[1 - \left(\frac{24}{5^2} + \frac{8}{5^3(n+1)} - \frac{16}{5^4(n+1)^2} \right) \right] m_n.
\end{aligned} \tag{4.14}$$

Also,

$$\begin{aligned}
p_n^{(2)} &= \left(1 - \frac{4}{5(2n+1)} \right) m_n, \\
q_n^{(2)} &= \frac{1}{5} \left(1 - \frac{4}{5(2n+1)} \right) m_n, \\
m_{n+1}^{(2)} &= \frac{1}{25} \left(1 - \frac{8}{5(2n+1)} + \frac{16}{25(2n+1)^2} \right) m_n \\
&= \left[1 - \left(\frac{24}{5^2} + \frac{8}{5^3(2n+1)} - \frac{16}{5^4(2n+1)^2} \right) \right] m_n.
\end{aligned} \tag{4.15}$$

Finally,

$$\begin{aligned}
p_n^{(3)} &= \left(1 - \frac{4(n+1)}{5(2n+1)} \right) m_n, \\
q_n^{(3)} &= \frac{1}{5} \left(1 - \frac{4(n+1)}{5(2n+1)} \right) m_n, \\
m_{n+1}^{(3)} &= \frac{1}{25} \left(1 - \frac{4}{5(n+2)} - \frac{4(n+1)}{5(2n+1)} + \frac{16(n+1)}{25(n+2)(2n+1)} \right) m_n \\
&= \left[1 - \left(\frac{24}{5^2} + \frac{4}{5^3(n+2)} + \frac{4(n+1)}{5^3(2n+1)} - \frac{16(n+1)}{5^4(n+2)(2n+1)} \right) \right] m_n.
\end{aligned} \tag{4.16}$$

From (4.14)–(4.16), set

$$\begin{aligned}
\sigma_n^{(1)} &= \left[1 - \left(\frac{24}{5^2} + \frac{8}{5^3(n+1)} - \frac{16}{5^4(n+1)^2} \right) \right] m_n, \\
\sigma_n^{(2)} &= \left[1 - \left(\frac{24}{5^2} + \frac{8}{5^3(2n+1)} - \frac{16}{5^4(2n+1)^2} \right) \right] m_n, \\
\sigma_n^{(3)} &= \left[1 - \left(\frac{24}{5^2} + \frac{4}{5^3(n+2)} + \frac{4(n+1)}{5^3(2n+1)} - \frac{16(n+1)}{5^4(n+2)(2n+1)} \right) \right] m_n.
\end{aligned}$$

Then clearly, $\sigma_n^{(i)} \in (0, 1)$ for each $i \in \{1, 2, 3\}$ and $\sum_n \sigma_n^{(i)} = \infty$ for each $i \in \{1, 2, 3\}$. Thus, by Lemma 2.1, we have that $\lim_{n \rightarrow \infty} m_n^{(i)} = p = 0 \in F(\mathcal{F})$ for each $i \in \{1, 2, 3\}$.

On the other hand, we have $\lim_{n \rightarrow \infty} \|m^{(i)}\| = \left\| \lim_{n \rightarrow \infty} m^{(i)} \right\| = 0$ for each $i \in \{1, 2, 3\}$. Taking the sequence $\{t_n\}_{n=0}^\infty$ to be $t_n = \frac{1}{n+4}$ for all $n \in \mathbb{N}$, then we get

$$0 \leq \lim_{n \rightarrow \infty} \|m^{(i)} - t_n\| \leq \lim_{n \rightarrow \infty} \|m^{(i)}\| + \lim_{n \rightarrow \infty} \|t_n\| = 0, \text{ for each } i \in \{1, 2, 3\},$$

which shows that $\lim_{n \rightarrow \infty} \|m^{(i)} - t_n\| = 0$ for each $i \in \{1, 2, 3\}$, in other words, each of $\{m_n^{(i)}\}_{n=0}^{\infty}$, $i \in \{1, 2, 3\}$ and $\{t_n\}_{n=0}^{\infty} = \left\{\frac{1}{n+4}\right\}_{n=0}^{\infty}$ are equivalent sequences.

Let $\epsilon_n^{(1)}$, $\epsilon_n^{(2)}$ and $\epsilon_n^{(3)}$ be the corresponding sequences to the iterative algorithms $\{m_n^{(1)}\}_{n=0}^{\infty}$, $\{m_n^{(2)}\}_{n=0}^{\infty}$ and $\{m_n^{(3)}\}_{n=0}^{\infty}$, respectively. Then we have

$$\begin{aligned}\epsilon_n^{(1)} &= \left| \frac{1}{n+5} - \frac{1}{5^2(n+4)} + \frac{8}{5^3(n+1)(n+4)} - \frac{16}{5^4(n+1)^2(n+4)} \right|, \\ \epsilon_n^{(2)} &= \left| \frac{1}{n+5} - \frac{1}{5^2(n+4)} + \frac{8}{5^3(2n+1)(n+4)} - \frac{16}{5^4(2n+1)^2(n+4)} \right|, \\ \epsilon_n^{(3)} &= \left| \frac{1}{5} - \frac{1}{5^2(n+4)} + \frac{4}{5^3(n+2)(n+4)} + \frac{4(n+1)}{5^3(2n+1)(n+4)} - \frac{16(n+1)}{5^4(n+2)(2n+1)(n+4)} \right|.\end{aligned}$$

Obviously, $\lim_{n \rightarrow \infty} \epsilon_n^{(i)} = 0$ for each $i \in \{1, 2, 3\}$. Hence, all the iterative sequences $\{m_n^{(i)}\}_{n=0}^{\infty}$, $i \in \{1, 2, 3\}$ are w^2 -stable with respect to \mathcal{F} .

5. Data dependence result

In this section, the data dependence result of (1.6) for contractive-like mapping is obtained, hence, giving an affirmative answer to the above open question raised by Akutsah et al. [4].

Theorem 5.1. *Let $\tilde{\mathcal{F}}$ be an approximate operator of a mapping \mathcal{F} satisfying (1.2). Let $\{m_n\}$ be an iterative method generated by (1.6) for \mathcal{F} and define an iterative method as follows:*

$$\begin{cases} \tilde{m}_1 \in \mathcal{A}, \\ \tilde{p}_n = (1 - \vartheta_n)\tilde{m}_n + \vartheta_n \tilde{\mathcal{F}} \tilde{m}_n, \\ \tilde{q}_n = \tilde{\mathcal{F}} \tilde{p}_n, \\ \tilde{m}_{n+1} = \tilde{\mathcal{F}}((1 - \varpi_n)\tilde{q}_n + \varpi_n \tilde{\mathcal{F}} \tilde{q}_n), \end{cases} \quad \forall n \in \mathbb{N}, \quad (5.1)$$

where $\{\vartheta_n\}$ and $\{\varpi_n\}$ are sequences in $[0, 1]$ satisfying the following conditions:

(i) $\frac{1}{2} \leq \varpi_n, \forall n \in \mathbb{N}$,

(ii) $\sum_{n=0}^{\infty} \varpi_n = \infty$.

If $\mathcal{F}m^* = m^*$ and $\tilde{\mathcal{F}}\tilde{m}^* = \tilde{m}^*$ such that $\lim_{n \rightarrow \infty} \tilde{m}_n = \tilde{m}^*$, we have

$$\|m^* - \tilde{m}^*\| \leq \frac{7\epsilon}{1 - \gamma}, \quad (5.2)$$

where $\epsilon > 0$ is a fixed number.

Proof. Using (1.2), (1.6) and (5.1), we obtain

$$\begin{aligned}\|p_n - \tilde{p}_n\| &\leq (1 - \vartheta_n)\|m_n - \tilde{m}_n\| + \vartheta_n\|\mathcal{F}m_n - \tilde{\mathcal{F}}\tilde{m}_n\| \\ &\leq (1 - \vartheta_n)\|m_n - \tilde{m}_n\| + \vartheta_n\{\|\mathcal{F}m_n - \mathcal{F}\tilde{m}_n\| + \|\mathcal{F}\tilde{m}_n - \tilde{\mathcal{F}}\tilde{m}_n\|\} \\ &\leq (1 - \vartheta_n)\|m_n - \tilde{m}_n\| + \vartheta_n\{\gamma\|m_n - \tilde{m}_n\| + \psi(\|m_n - \mathcal{F}m_n\|) + \epsilon\} \\ &= [1 - (1 - \gamma)\vartheta_n]\|m_n - \tilde{m}_n\| + \vartheta_n\psi(\|m_n - \mathcal{F}m_n\|) + \vartheta_n\epsilon.\end{aligned} \quad (5.3)$$

$$\begin{aligned}
\|q_n - \tilde{q}_n\| &= \|\mathcal{F} p_n - \tilde{\mathcal{F}} \tilde{p}_n\| = \|\mathcal{F} p_n - \mathcal{F} \tilde{p}_n + \mathcal{F} \tilde{p}_n - \tilde{\mathcal{F}} \tilde{p}_n\| \\
&\leq \|\mathcal{F} p_n - \mathcal{F} \tilde{p}_n\| + \|\mathcal{F} \tilde{p}_n - \tilde{\mathcal{F}} \tilde{p}_n\| \\
&\leq \gamma \|p_n - \tilde{p}_n\| + \psi(\|p_n - \mathcal{F} p_n\|) + \epsilon.
\end{aligned} \tag{5.4}$$

Using (5.3) and (5.4),

$$\begin{aligned}
\|q_n - \tilde{q}_n\| &= \gamma(1 - (1 - \gamma)\vartheta_n)\|m_n - \tilde{m}_n\| + \gamma\vartheta_n\psi(\|m_n - \mathcal{F} m_n\|) \\
&\quad + \gamma\vartheta_n\epsilon + \psi(\|p_n - \mathcal{F} p_n\|) + \epsilon.
\end{aligned} \tag{5.5}$$

$$\begin{aligned}
\|m_{n+1} - \tilde{m}_{n+1}\| &= \|\mathcal{F}((1 - \varpi_n)q_n + \varpi_n\mathcal{F}q_n) - \tilde{\mathcal{F}}((1 - \varpi_n)\tilde{q}_n + \varpi_n\tilde{\mathcal{F}}\tilde{q}_n)\| \\
&\leq \|\mathcal{F}((1 - \varpi_n)q_n + \varpi_n\mathcal{F}q_n) - \mathcal{F}((1 - \varpi_n)\tilde{q}_n + \varpi_n\tilde{\mathcal{F}}\tilde{q}_n)\| \\
&\quad + \|\mathcal{F}((1 - \varpi_n)\tilde{q}_n + \varpi_n\tilde{\mathcal{F}}\tilde{q}_n) - \tilde{\mathcal{F}}((1 - \varpi_n)\tilde{q}_n + \varpi_n\tilde{\mathcal{F}}\tilde{q}_n)\| \\
&\leq \gamma((1 - \varpi_n)\|q_n - \tilde{q}_n\| + \varpi_n\|\mathcal{F}q_n - \tilde{\mathcal{F}}\tilde{q}_n\|) \\
&\quad + \psi(\|(1 - \varpi_n)q_n + \varpi_n\mathcal{F}q_n - \mathcal{F}((1 - \varpi_n)q_n + \varpi_n\mathcal{F}q_n)\|) + \epsilon \\
&\leq \gamma((1 - \varpi_n)\|q_n - \tilde{q}_n\| + \varpi_n(\|\mathcal{F}q_n - \mathcal{F}\tilde{q}_n\| + \|\mathcal{F}\tilde{q}_n - \tilde{\mathcal{F}}\tilde{q}_n\|)) \\
&\quad + \psi(\|(1 - \varpi_n)q_n + \varpi_n\mathcal{F}q_n - \mathcal{F}((1 - \varpi_n)q_n + \varpi_n\mathcal{F}q_n)\|) + \epsilon \\
&\leq \gamma((1 - \varpi_n)\|q_n - \tilde{q}_n\| + \gamma\varpi_n\|q_n - \tilde{q}_n\| + \varpi_n\psi(\|q_n - \mathcal{F}q_n\|) + \varpi_n\epsilon) \\
&\quad + \psi(\|(1 - \varpi_n)q_n + \varpi_n\mathcal{F}q_n - \mathcal{F}((1 - \varpi_n)q_n + \varpi_n\mathcal{F}q_n)\|) + \epsilon \\
&\leq \gamma(1 - (1 - \gamma)\varpi_n)\|q_n - \tilde{q}_n\| + \gamma\varpi_n\psi(\|q_n - \mathcal{F}q_n\|) + \gamma\varpi_n\epsilon \\
&\quad + \psi(\|(1 - \varpi_n)q_n + \varpi_n\mathcal{F}q_n - \mathcal{F}((1 - \varpi_n)q_n + \varpi_n\mathcal{F}q_n)\|) + \epsilon.
\end{aligned} \tag{5.6}$$

Putting (5.5) into (5.6), we obtain

$$\begin{aligned}
\|m_{n+1} - \tilde{m}_{n+1}\| &\leq \gamma^2(1 - (1 - \gamma)\varpi_n)(1 - (1 - \gamma)\vartheta_n)\|m_n - \tilde{m}_n\| \\
&\quad + \gamma^2(1 - (1 - \gamma)\varpi_n)\vartheta_n\psi(\|m_n - \mathcal{F} m_n\|) \\
&\quad + \gamma^2\vartheta_n\epsilon - \gamma^2\varpi_n\vartheta_n\epsilon + \gamma^3\varpi_n\vartheta_n\epsilon + (1 - (1 - \gamma)\varpi_n)\psi(\|p_n - \mathcal{F} p_n\|) \\
&\quad + \gamma\epsilon - \gamma\varpi_n\epsilon + \gamma^2\varpi_n\epsilon + \gamma\varpi_n\psi(\|q_n - \mathcal{F} q_n\|) + \gamma\varpi_n\epsilon \\
&\quad + \psi(\|(1 - \varpi_n)q_n + \varpi_n\mathcal{F} q_n - \mathcal{F}((1 - \varpi_n)q_n + \varpi_n\mathcal{F} q_n)\|) + \epsilon \\
&= \gamma^2(1 - (1 - \gamma)\varpi_n)(1 - (1 - \gamma)\vartheta_n)\|m_n - \tilde{m}_n\| \\
&\quad + \gamma^2(1 - (1 - \gamma)\varpi_n)\vartheta_n\psi(\|m_n - \mathcal{F} m_n\|) \\
&\quad + \gamma^2\vartheta_n\epsilon + \gamma^2\varpi_n\vartheta_n\epsilon(\gamma - 1) + (1 - (1 - \gamma)\varpi_n)\psi(\|p_n - \mathcal{F} p_n\|) \\
&\quad + \gamma\epsilon + \gamma^2\varpi_n\epsilon + \gamma\varpi_n\psi(\|q_n - \mathcal{F} q_n\|) \\
&\quad + \psi(\|(1 - \varpi_n)q_n + \varpi_n\mathcal{F} q_n - \mathcal{F}((1 - \varpi_n)q_n + \varpi_n\mathcal{F} q_n)\|) + \epsilon.
\end{aligned} \tag{5.7}$$

Since $\varpi_n, \vartheta_n \in [0, 1]$ and $\gamma \in [0, 1)$, it follows that

$$\begin{cases} (1 - (1 - \gamma)\varpi_n) < 1, \\ (1 - (1 - \gamma)\vartheta_n) < 1, \\ \gamma - 1 < 0, \\ \gamma^2 < 1, \\ \gamma^2\varpi_n, \gamma^2\varpi_n < 1. \end{cases} \tag{5.8}$$

From (5.7) and (5.8), we have

$$\begin{aligned} \|m_{n+1} - \tilde{m}_{n+1}\| &\leq (1 - (1 - \gamma)\varpi_n)\|m_n - \tilde{m}_n\| + \psi(\|m_n - \mathcal{F}m_n\|) + \psi(\|p_n - \mathcal{F}p_n\|) \\ &\quad + \psi(\|(1 - \varpi_n)q_n + \varpi_n\mathcal{F}q_n - \mathcal{F}((1 - \varpi_n)q_n + \varpi_n\mathcal{F}q_n)\|) \\ &\quad + \varpi_n\psi(\|q_n - \mathcal{F}q_n\|) + \varpi_n\epsilon + 3\epsilon. \end{aligned} \quad (5.9)$$

By our assumption (i), we have

$$1 - \varpi_n \leq \varpi_n \Rightarrow 1 = 1 - \varpi_n + \varpi_n \leq \varpi_n + \varpi_n = 2\varpi_n.$$

This yields

$$\|m_{n+1} - \tilde{m}_{n+1}\| \leq (1 - (1 - \gamma)\varpi_n)\|m_n - \tilde{m}_n\| + (1 - \gamma) \times \left\{ \begin{array}{l} \frac{2\varpi_n\psi(\|m_n - \mathcal{F}m_n\|) + 2\varpi_n\psi(\|p_n - \mathcal{F}p_n\|)}{(1-\gamma)} \\ + \frac{\varpi_n\psi(\|q_n - \mathcal{F}q_n\|) + 7\epsilon}{(1-\gamma)} \\ + \frac{2\varpi_n\psi(\|(1-\varpi_n)q_n + \varpi_n\mathcal{F}q_n - \mathcal{F}((1-\varpi_n)q_n + \varpi_n\mathcal{F}q_n)\|)}{(1-\gamma)} \end{array} \right\}. \quad (5.10)$$

Set

$$\begin{aligned} \theta_n &= \|m_n - \tilde{m}_n\|, \\ \sigma_n &= (1 - \gamma)\varpi_n \in (0, 1), \\ \lambda_n &= \left\{ \begin{array}{l} \frac{2\varpi_n\psi(\|m_n - \mathcal{F}m_n\|) + 2\varpi_n\psi(\|p_n - \mathcal{F}p_n\|)}{(1-\gamma)} \\ + \frac{\varpi_n\psi(\|q_n - \mathcal{F}q_n\|) + 7\epsilon}{(1-\gamma)} \\ + \frac{2\varpi_n\psi(\|(1-\varpi_n)q_n + \varpi_n\mathcal{F}q_n - \mathcal{F}((1-\varpi_n)q_n + \varpi_n\mathcal{F}q_n)\|)}{(1-\gamma)} \end{array} \right\}. \end{aligned}$$

From Theorem 3.1, we know that $\lim_{n \rightarrow \infty} m_n = m^*$ and since $\mathcal{F}m^* = m^*$, then from (4.7), (4.9) and Lemma 2.2, we obtain

$$0 \leq \limsup_{n \rightarrow \infty} \|m_n - \tilde{m}_n\| \leq \limsup_{n \rightarrow \infty} \frac{7\epsilon}{(1 - \gamma)}. \quad (5.11)$$

Since by Theorem 3.1, we have that $\lim_{n \rightarrow \infty} m_n = m^*$ and using the hypothesis $\lim_{n \rightarrow \infty} \tilde{m}_n = \tilde{m}^*$, it follows from (5.11) that

$$\|m - \tilde{m}\| \leq \frac{7\epsilon}{(1 - \gamma)}.$$

□

6. Application

In this section, we discuss an application to nonlinear Volterra integral equation with delay. Consider the integral equation

$$m(t) = g(t) + \lambda \int_a^t f(t, s, m(s), m(s - \tau)) ds \quad t \in I = [a, b], \quad (6.1)$$

with initial function

$$m(t) = \phi(t), \quad t \in [a - \tau, a], \quad (6.2)$$

where $\phi \in C[a - \tau, a], \mathbb{R}$, $a, b \in \mathbb{R}$ and $\tau > 0$.

Let $C[a, b]$ denote the set all of continuous functions defined on $[a, b]$ endowed with infinity norm $\|m - p\|_\infty = \max_{a \leq t \leq b} \|m(t) - p(t)\|$. It is well known that $(C[a, b], \mathbb{R}, \|\cdot\|_\infty)$ is a Banach space.

Theorem 6.1. Let \mathcal{K} be a nonempty closed convex subset of a Banach space $\mathcal{M} = (C([a, b], \mathbb{R}), \|\cdot\|_\infty)$. Let $\{m_n\}$ be the iterative method (1.6) with $\varpi_n, \vartheta_n \in [0, 1]$. Let $\mathcal{F} : \mathcal{K} \rightarrow \mathcal{K}$ be the operator defined by

$$\begin{aligned} \mathcal{F}m(t) &= g(t) + \lambda \int_a^t f(t, s, m(s), m(s - \tau)) ds \quad t \in I = [a, b], \quad \lambda \geq 0. \\ \mathcal{F}m(t) &= \phi(t), \quad t \in [a - \tau, a]. \end{aligned}$$

Suppose the following assumptions hold:

- (a) $g : I \rightarrow \mathbb{R}$ is continuous;
 (b) $f : I \times I \times \mathbb{R} \times \mathbb{R} \rightarrow \mathbb{R}$ is continuous in the sense that there exists a constant $L_f > 0$ such that

$$|f(t, s, u_1, u_2) - f(t, s, v_1, v_2)| \leq L_f(|u_1 - v_1| + |u_2 - v_2|),$$

for all $t, s \in I$, $u_i, v_i \in \mathbb{R}$ ($i = 1, 2$);

- (d) $2\lambda L_f(b - a) < 1$.

Then, the problem (6.1) with (6.2) has a unique solution, say $m^* \in C[a, b]$. Moreover, if \mathcal{F} is a mapping satisfying (1.2). Then, $\{m_n\}$ converges strongly to m^* .

Proof. Now, using the contraction principle, we show that \mathcal{F} has a fixed point. Note that

$$|\mathcal{F}m(t) - \mathcal{F}p(t)| = 0, \quad m, p \in C([a - \tau, a], \mathbb{R}), \quad t \in [a - \tau, b].$$

Next, for any $t \in I$, we have

$$\begin{aligned} |\mathcal{F}m(t) - \mathcal{F}p(t)| &= |g(t) + \lambda \int_a^t f(t, s, m(s), m(s - \tau)) ds - g(t) - \lambda \int_a^t f(t, s, p(s), p(s - \tau)) ds| \\ &\leq \lambda \int_a^t L_f \{|m(s) - p(s)| + |m(s - \tau) - p(s - \tau)|\} ds \\ &\leq \lambda \int_a^t L_f \left\{ \max_{a - \tau \leq s \leq b} |m(s) - p(s)| + \max_{a - \tau \leq s \leq b} |m(s - \tau) - p(s - \tau)| \right\} ds \\ &= \lambda \int_a^t L_f \{\|m - p\|_\infty + \|m - p\|_\infty\} ds \\ &\leq 2\lambda L_f(b - a)\|m - p\|_\infty, \end{aligned}$$

therefore,

$$\|\mathcal{F}m - \mathcal{F}p\|_\infty \leq 2\lambda L_f(b - a)\|m - p\|_\infty.$$

From condition (d), the operator \mathcal{F} is a contraction and using the contraction principle we deduce that the operator \mathcal{F} has a unique fixed point, $F(\mathcal{F}) = \{m^*\}$, i.e. the problem (6.1) with (6.2) has a unique solution $m^* \in C[a, b]$.

Next, we show that $\{m_n\}$ converges strongly to m^* . For $m, p \in \mathcal{A}$, we have

$$\begin{aligned}
|\mathcal{F}m(t) - \mathcal{F}p(t)| &\leq |\mathcal{F}m(t) - m(t)| + |m(t) - \mathcal{F}p(t)| \\
&= |\mathcal{F}m(t) - m(t)| + |g(t) + \lambda \int_a^t f(t, s, m(s), m(s - \tau))ds \\
&\quad - g(t) - \lambda \int_a^t f(t, s, p(s), p(s - \tau))ds| \\
&\leq |\mathcal{F}m(t) - m(t)| + \lambda \int_a^t L_f \{|m(s) - p(s)| + |m(s - \tau) - p(s - \tau)|\} ds \\
&\leq \max_{a-\tau \leq t \leq b} |\mathcal{F}m(t) - m(t)| \\
&\quad + \lambda \int_a^t L_f \left\{ \max_{a-\tau \leq s \leq b} |m(s) - p(s)| + \max_{a-\tau \leq s \leq b} |m(\alpha(s)) - p(\alpha(s))| \right\} ds \\
&\leq \max_{a-\tau \leq t \leq b} |\mathcal{F}m(t) - m(t)| \\
&\quad + \lambda \int_a^t L_f \left\{ \max_{a-\tau \leq d_1 \leq b} |m(d_1) - p(d_1)| + \max_{a-\tau \leq r_1 \leq b} |m(r_1) - p(r_1)| \right\} ds \\
&= \|\mathcal{F}m - m\|_\infty + \lambda \int_a^t L_f \{\|m - p\|_\infty + \|m - p\|_\infty\} ds \\
&\leq \|\mathcal{F}m - m\|_\infty + 2\lambda L_f(b - a)\|m - p\|_\infty, \tag{6.3}
\end{aligned}$$

therefore,

$$\|\mathcal{F}m - \mathcal{F}p\|_\infty \leq \|\mathcal{F}m - m\|_\infty + 2\lambda L_f(b - a)\|m - p\|_\infty. \tag{6.4}$$

From (6.4), it is clear that \mathcal{F} is a mapping satisfying (1.1). Set $\gamma = 2\lambda L_f(b - a)$, and by assumption (d), we have $\gamma < 1$. Thus, the operator \mathcal{F} is a contractive-like mapping satisfying (1.2) on \mathcal{K} with $L = 1$ since for $\psi(m) = Lm$, (1.2) reduces to (1.1). Taking $\mathcal{A} = \mathcal{K}$ and $\mathcal{B} = \mathcal{M}$, then all the assumptions of Theorem 3.1 are satisfied. Therefore, the sequence $\{m_n\}$ defined by the iterative algorithm (1.6) converges strongly to the unique solution of the problem (6.1) with (6.2). \square

7. Conclusions

In this study, we have proved the strong convergence results of the iterative scheme (1.6) for fixed points of contractive-like mapping under mild conditions. We have presented some interesting and nontrivial examples in three dimensional space to compare the efficiency of the iterative method (1.6) with some existing iterative methods. Also, we have shown analytically and numerically that the iterative method (1.6) is w^2 -stable for different choices of parameters and initial guesses. Again, our data dependence result gives an affirmative answer to the open question raised by Akutsah et al [4]. As an application of our results, we have established the existence, uniqueness and approximation results for the solutions of a nonlinear Volterra integral equation with delay (6.1) with (6.2).

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Conflict of interest

The authors declare no conflicts of interest.

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