

AIMS Mathematics, 7(6): 10790–10806. DOI:10.3934/math.2022603 Received: 31 December 2021 Revised: 28 February 2022 Accepted: 15 March 2022 Published: 31 March 2022

http://www.aimspress.com/journal/Math

Research article

Normalized ground states for fractional Kirchhoff equations with critical or supercritical nonlinearity

Huanhuan Wang, Kexin Ouyang and Huiqin Lu*

School of Mathematics Statistics, Shandong Normal University, Jinan 250358, China

* Correspondence: Email: lhy0625@163.com.

Abstract: The aim of this paper is to study the existence of ground states for a class of fractional Kirchhoff type equations with critical or supercritical nonlinearity

$$(a+b\int_{\mathbb{R}^3} |(-\Delta)^{\frac{s}{2}}u|^2 dx)(-\Delta)^s u = \lambda u + |u|^{q-2}u + \mu |u|^{p-2}u, \ x \in \mathbb{R}^3,$$

with prescribed L^2 -norm mass

$$\int_{\mathbb{R}^3} u^2 dx = c^2$$

where $s \in (\frac{3}{4}, 1)$, a, b, c > 0, $\frac{6+8s}{3} < q < 2_s^*$, $p \ge 2_s^* (2_s^* = \frac{6}{3-2s})$, $\mu > 0$ and $\lambda \in \mathbb{R}$ as a Langrange multiplier. By combining an appropriate truncation argument with Moser iteration method, we prove that the existence of normalized solutions for the above equation when the parameter μ is sufficiently small.

Keywords: normalized solution; fractional Kirchhoff equation; Pohozaev manifold; Moser iteration method; supercritical growth

Mathematics Subject Classification: 35J65, 47J05, 47J30

1. Introduction

In this paper, we study mainly the existence of ground states to the Kirchhoff type problem with critical or supercritical nonlinearity

$$\begin{cases} (a+b\int_{\mathbb{R}^3} |(-\Delta)^{\frac{s}{2}} u|^2 dx)(-\Delta)^s u = \lambda u + |u|^{q-2} u + \mu |u|^{p-2} u, \ x \in \mathbb{R}^3, \\ \int_{\mathbb{R}^3} u^2 = c^2, \end{cases}$$
(1.1)

where $s \in (\frac{3}{4}, 1)$, a, b, c > 0, $\frac{6+8s}{3} < q < 2_s^*$, $p \ge 2_s^* (2_s^* = \frac{6}{3-2s})$, $\mu > 0$ is a real parameter, and $(-\Delta)^s$ denotes the fractional Laplacian operator.

The operator $(-\Delta)^s$ can be seen as the infinitesimal generators of Lévy stable diffusion processes, see [1,2] for example. This operator appears in several areas such as biology, chemistry and physics (see [3–6]). Problem (1.1) is viewed as being nonlocal because of the appearance of the term $b \int_{\mathbb{R}^3} |(-\Delta)^{\frac{s}{2}} u|^2$, which implies that Eq (1.1) is no longer a pointwise identity. This also results in lack of weak sequential continuity of the energy function associated to (1.1), so it make the study of (1.1) particularly interesting. Over the last decade, many mathematicians were particularly keen on the study of nonlinear equations involving nonlocal operators, we can look it up in [7–14] and the references therein.

It is well known that problem (1.1) arises from looking for the standing wave type solutions $\varphi(x, t) = e^{-i\lambda t}u(x)$, $\lambda \in \mathbb{R}$ for the following time-dependent nonlinear fractional Kirchhoff equation

$$i\frac{\partial\varphi}{\partial t} = (a+b\int_{\mathbb{R}^3} |(-\Delta)^{\frac{s}{2}}\varphi|^2 dx)(-\Delta)^s \varphi - f(|\varphi|)\varphi, \ x \in \mathbb{R}^3,$$
(1.2)

where 0 < s < 1, *i* denotes the imaginary unit. The stationary case of (1.2) is the following equation

$$(a+b\int_{\mathbb{R}^3} |(-\Delta)^{\frac{s}{2}}\varphi|^2 dx)(-\Delta)^s \varphi = f(|\varphi|)\varphi, \ x \in \mathbb{R}^3.$$
(1.3)

Clearly, φ solves (1.2) if and only if the stand wave u(x) satisfies (1.1) with $f(u) = |u|^{q-2} + \mu |u|^{p-2}$. Alternatively one can consider the existence of normalized solutions to (1.1), that is, solutions with prescribed L^2 -norm. Since solutions $\varphi \in C([0, 1], H^s(\mathbb{R}^3))$ to (1.2) maintain their mass along time (In fact, multiplying (1.2) by the conjugate $\overline{\varphi}$ of φ , integrating over \mathbb{R}^3 , and taking the imaginary part, we get $\frac{d}{dt}|\varphi(t)|_2^2 = 0$, $t \in [0, T]$.), it is natural and interesting, from a physical point view, to search for such solutions.

When s = 1, Problem (1.3) becomes the Kirchhoff equation. In the past several years, the Kirchhoff type equations has been studied extensively by many researchers(see [15–23]). For all we know, the existence results to problem (1.1) have been mostly available for the case where $p, q \in (2, 2_s^*)$ and λ is fixed and assigned. When a = 1, b = 0, s = 1 and $\mu = 0$, i.e., for the Laplacian operator, Jeanjean's [24] was the first paper to prove existence of normalized solutions in purely L^2 -supercritical case. Li and Ye in [25] considered problem (1.1) with $s = 1, \mu = 0, N = 3, \lambda = -1, q \in (3, 6)$ and proved that (1.1) has at least one least energy solution by dealing with a constrained minimization problem on a manifold of $H^1(\mathbb{R}^3)$, which is obtained by combining the Nehari manifold and the corresponding Pohozaev identity. Liu, Chen and Yang in [26] considered problem (1.1) with $2 < q < p < 2_s^*$ and proved some existence results about the normalized solutions. However, there is few literature concerned about the normalized solutions for fractional Kirchhoff equation with critical or supercritical nonlinearity. With regard to the point, we attempt to study this kind of problem in this paper.

It is well known that the fractional order Sobolev space $H := H^s(\mathbb{R}^3)$ can be defined as follows

$$H^{s}(\mathbb{R}^{3}) = \{ u \in L^{2}(\mathbb{R}^{3}) : \int \int_{\mathbb{R}^{6}} \frac{|u(x) - u(y)|^{2}}{|x - y|^{3 + 2s}} dx dy < +\infty \},\$$

endowed with the norm

$$||u||_{H} = \left(\int \int_{\mathbb{R}^{6}} \frac{|u(x) - u(y)|^{2}}{|x - y|^{3 + 2s}} dx dy + \int_{\mathbb{R}^{3}} |u|^{2} dx\right)^{\frac{1}{2}}$$

AIMS Mathematics

and the inner product is

$$(u,v)_{H} = \int \int_{\mathbb{R}^{6}} \frac{(u(x) - u(y))(v(x) - v(y))}{|x - y|^{3 + 2s}} dx dy + \int_{\mathbb{R}^{3}} uv dx.$$

According to [26], we know that

$$||u|| = \left(\int_{\mathbb{R}^3} (|(-\Delta)^{\frac{s}{2}}u|^2 dx + \int_{\mathbb{R}^3} |u|^2 dx\right)^{\frac{1}{2}}$$

is also a norm on $H^s(\mathbb{R}^3)$ which is equivalent to $||u||_H$. Moreover, we define $H^s_r(\mathbb{R}^3) := \{u \in H^s(\mathbb{R}^3) : u(x) = u(|x|), x \in \mathbb{R}^3\}$.

Let $\mathbb{H} = H \times \mathbb{R}$ with the scalar product

$$(\cdot, \cdot)_{\mathbb{H}} = (\cdot, \cdot)_{H} + (\cdot, \cdot)_{\mathbb{R}}$$

and the corresponding norm

$$\|\cdot\|_{\mathbb{H}}^2 = \|\cdot\|_{H}^2 + |\cdot|_{\mathbb{R}}^2$$

Let $\|\cdot\|_t$ be the usual norm of space $L^t(\mathbb{R}^3)$ where $2 \le t \le \infty$. *H* is continuously embedding into $L^t(\mathbb{R}^3)$ for $t \in [2, 2_s^*]$ and there exists a best constant S_s^* such that

$$S_{s}^{*} = \inf_{u \in H, u \neq 0} \frac{\int_{\mathbb{R}^{3}} |(-\Delta)^{\frac{s}{2}} u|^{2} dx}{||u||_{2^{*}}^{2}}.$$
(1.4)

The normalized weak solution for the problem (1.1) is obtained by looking for critical points of the following C^1 functional

$$\mathcal{J}_{\mu}(u) = \frac{a}{2} \int_{\mathbb{R}^{3}} |(-\Delta)^{\frac{s}{2}} u|^{2} + \frac{b}{4} (\int_{\mathbb{R}^{3}} |(-\Delta)^{\frac{s}{2}} u|^{2})^{2} - \frac{1}{q} \int_{\mathbb{R}^{3}} |u|^{q} - \frac{\mu}{p} \int_{\mathbb{R}^{3}} |u|^{p} du^{p} du^$$

constrained on the L^2 -spheres in H:

$$S(c) = \{ u \in H | ||u||_2 = c > 0 \}.$$

 u_c is called a ground state of (1.1) on S(c) if

$$d\mathcal{J}_{\mu}|_{S(c)}(u_c) = 0 \text{ and } \mathcal{J}_{\mu}(u_c) = \inf_{u \in S(c)} \{ \mathcal{J}_{\mu}(u) : d\mathcal{J}_{\mu}|_{S(c)}(u) = 0 \}.$$

Since $p \ge 2_s^*$, the functional \mathcal{J}_{μ} is not well defined on $H^s(\mathbb{R}^3)$ unless $p = 2_s^*$. Moreover, we need to overcome the lack of compactness in studying critical and supercritical growth. Hence, we cannot directly use variational methods to prove the existence of normalized solutions. To overcome these difficulties, we use a new method, which came from [14,18]. The main idea of this method is to reduce the supercritical problem into a subcritical one. In comparison with previous works, this paper has several new features. Firstly, we consider the nonlinear term with superifical growth. Secondly, we give the existence of normalized solution for the appropriate truncation problem of (1.1). Finally, the existence of a normalized ground state solution is obtained by Moser iteration method. The results in this paper extend the results in paper [4,24,26]. There have been no previous studies considering the

AIMS Mathematics

existence of normalized ground state solutions for problem (1.1) involving superitical growth to the best of our knowledge.

Our main result is the following:

Theorem 1.1. For any c > 0, there exists a $\mu^* > 0$ such that, problem (1.1) has a couple of solutions $(u_c, \lambda_c) \in H^s(\mathbb{R}^3) \times \mathbb{R}$ for any $\mu \in (0, \mu^*]$. Moreover, u_c is a positive ground state, radially symmetric function and $\lambda_c < 0$.

Remark 1.2. When $\frac{6+8s}{3} < q < 2_s^*$, \mathcal{J}_{μ} is not bounded from below on S(c), i.e., $\inf_{u \in S(c)} \mathcal{J}_{\mu}(u) = -\infty$. So, the minimization problem constrained on S(c) does not work. We try to look for a critical point with a minimax characterization. Although \mathcal{J}_{μ} has a mountain-pass geometry on S(c), the boundedness of the obtained Palais-Smale sequence is not yet clear. Motivated by [4], we try to construct an auxiliary map I_{μ} , which on $S(c) \times \mathbb{R}$ has the same type of geometric structure as \mathcal{J}_{μ} on S(c). Besides, the Palais-Smale sequence of I_{μ} satisfies the additional condition, which is the key point to obtain the boundedness of the Palais-Smale sequence.

2. Preliminaries

In this section, we give a truncation argument in order to overcome the lack of compactness in studying critical and supercritical growth. Let M > 0 be a constant. For fixed c > 0, $\mu > 0$, M > 0, we investigate the existence of ground state for the following truncation problem

$$\begin{cases} (a+b\int_{\mathbb{R}^{3}}|(-\Delta)^{\frac{s}{2}}u|^{2}dx)(-\Delta)^{s}u = \lambda u + |u|^{q-2}u + \mu d_{M}(u), \ x \in \mathbb{R}^{3}, \\ \int_{\mathbb{R}^{3}}u^{2} = c^{2}, \end{cases}$$
(2.1)

where $s \in (\frac{3}{4}, 1)$, a, b > 0, $\frac{6+8s}{3} < q < 2_s^*$, $p \ge 2_s^* (2_s^* = \frac{6}{3-2s})$, and

$$d_M(t) = \begin{cases} |t|^{p-2}t, & |t| \le M, \\ M^{p-q}|t|^{q-2}t, & |t| > M, \end{cases}$$

To investigate (2.1), we define the energy functional $E_{\mu}: H \to \mathbb{R}$ by

$$E_{\mu}(u) = \frac{a}{2} \int_{\mathbb{R}^3} |(-\Delta)^{\frac{s}{2}} u|^2 dx + \frac{b}{4} (\int_{\mathbb{R}^3} |(-\Delta)^{\frac{s}{2}} u|^2 dx)^2 - \frac{1}{q} \int_{\mathbb{R}^3} |u|^q dx - \mu \int_{\mathbb{R}^3} D_M(u) dx, \qquad (2.2)$$

where $D_M(t) \doteq \int_0^t d_M(\tau) d\tau$. It is easy to obtain that $E_\mu \in C^1(H, \mathbb{R})$ and

$$\langle E'_{\mu}(u), v \rangle = (a + b \int_{\mathbb{R}^3} |(-\Delta)^{\frac{s}{2}} u|^2 dx) \int_{\mathbb{R}^3} (-\Delta)^{\frac{s}{2}} u (-\Delta)^{\frac{s}{2}} v dx - \int_{\mathbb{R}^3} |u|^{q-2} u v dx - \mu \int_{\mathbb{R}^3} d_M(u) v dx \quad (2.3)$$

for all $u, v \in H$.

Theorem 2.1. For any c > 0 and M > 0, there exists a $\mu_1 > 0$, such that, problem (2.1) has a couple of solutions $(u_c, \lambda_c) \in H^s_r(\mathbb{R}^3) \times \mathbb{R}$ for any $\mu \in (0, \mu_1]$. Moreover, u_c is a positive ground state, $\lambda_c < 0$ and $E_{\mu}(u_c) = m_{c,\mu}$, where

$$m_{c,\mu} := \inf_{u \in V(c)} E_{\mu}(u)$$

AIMS Mathematics

and V(c) is the Pohozaev manifold defined in lemma 2.4.

Next, we give some useful preliminary lemmas to prove Theorem 2.1.

Lemma 2.1. [8] If $\alpha \in (2, 2_s^*)$, there exists an optimal constant $C(s, \alpha)$ such that for any $u \in H$,

$$\int_{\mathbb{R}^3} |u|^{\alpha} \le C(s,\alpha) \left(\int_{\mathbb{R}^3} |(-\Delta)^{\frac{s}{2}} u|^2 \right)^{\frac{\alpha\beta\alpha}{s}} \left(\int_{\mathbb{R}^3} |u|^2 \right)^{\alpha - \frac{\alpha\beta\alpha}{s}},\tag{2.4}$$

where $\beta_{\alpha} := \frac{3(\alpha-2)}{2\alpha}$.

Lemma 2.2. [19] $H_r^s(\mathbb{R}^3)$ is compactly embedding into $L^t(\mathbb{R}^3)$ for $t \in (2, 2_s^*)$.

As in [4], we introduce the useful fiber map preserving the L^2 -norm, that is,

$$(\tau \star u)(x) := e^{\frac{3}{2}\tau} u(e^{\tau}x), \text{ for a.e. } x \in \mathbb{R}^3.$$
 (2.5)

Define the auxiliary functional $I : \mathbb{H} \to \mathbb{R}$ by

$$I_{\mu}(u,\tau) := E_{\mu}(\tau \star u) = \frac{a}{2}e^{2s\tau} \int_{\mathbb{R}^{3}} |(-\Delta)^{\frac{s}{2}}u|^{2} + \frac{b}{4}e^{4s\tau} (\int_{\mathbb{R}^{3}} |(-\Delta)^{\frac{s}{2}}u|^{2})^{2} -\frac{1}{q}e^{q\beta_{q}\tau} \int_{\mathbb{R}^{3}} |u|^{q}dx - \mu e^{r\beta_{r}\tau} \int_{\mathbb{R}^{3}} D_{M}(u)dx,$$
(2.6)

where

$$r = \begin{cases} p, & |u| \le M, \\ q, & |u| > M, \end{cases}$$

$$(2.7)$$

then we can obtain that I_{μ} is a C^1 -functional.

Lemma 2.3. [13] The map $(u, \tau) \in \mathbb{H} \mapsto \tau \star u \in H$ is continuous.

Similar to Lemma 2.1 in [4], we can easily get the following lemma.

Lemma 2.4. Let $(u, \lambda) \in S(c) \times \mathbb{R}$ be a weak solution of Eq (2.2). Then *u* belongs to the set

$$V(c) := \{ u \in S(c) : P_{\mu}(u) = 0 \}$$

where

$$P_{\mu}(u) = a \int_{\mathbb{R}^3} |(-\Delta)^{\frac{s}{2}} u|^2 dx + b (\int_{\mathbb{R}^3} |(-\Delta)^{\frac{s}{2}} u|^2 dx)^2 - \frac{\beta_q}{s} \int_{\mathbb{R}^3} |u|^q dx - \frac{\mu \beta_r r}{s} \int_{\mathbb{R}^3} D_M(u) dx.$$
(2.8)

Lemma 2.5. For any $u \in S(c)$, $\tau \in \mathbb{R}$ is a critical point for $\Phi_u(\tau) := I_\mu(u, \tau)$ if and only if $\tau \star u \in V(c)$. *Proof.* For any $u \in S(c)$ and $\tau \in \mathbb{R}$, we have

$$\begin{aligned} &(\Phi_{u})'(\tau) \\ &= ase^{2s\tau} \int_{\mathbb{R}^{3}} |(-\Delta)^{\frac{s}{2}} u|^{2} + bse^{4s\tau} (\int_{\mathbb{R}^{3}} |(-\Delta)^{\frac{s}{2}} u|^{2})^{2} - \beta_{q} e^{\beta_{q}q\tau} \int_{\mathbb{R}^{3}} |u|^{q} - \mu\beta_{r} r e^{\beta_{r}r\tau} \int_{\mathbb{R}^{3}} D_{M}(u) \\ &= as \int_{\mathbb{R}^{3}} |(-\Delta)^{\frac{s}{2}} (\tau \star u)|^{2} + bs (\int_{\mathbb{R}^{3}} |(-\Delta)^{\frac{s}{2}} (\tau \star u)|^{2})^{2} - \beta_{q} \int_{\mathbb{R}^{3}} |(\tau \star u)|^{q} - \mu\beta_{r} r \int_{\mathbb{R}^{3}} D_{M}(\tau \star u) \\ &= sP_{\mu}(\tau \star u). \end{aligned}$$

$$(2.9)$$

It is easy to see that Lemma 2.5 holds.

AIMS Mathematics

Volume 7, Issue 6, 10790–10806.

Lemma 2.6. Let $u \in S(c)$ be arbitrary fixed, then

(1) $\int_{\mathbb{R}^3} |(-\Delta)^{\frac{s}{2}}(\tau \star u)|^2 \to 0$ and $I_{\mu}(u,\tau) \to 0$ as $\tau \to -\infty$; (2) $\int_{\mathbb{R}^3} |(-\Delta)^{\frac{s}{2}}(\tau \star u)|^2 \to +\infty$ and $I_{\mu}(u,\tau) \to -\infty$ as $\tau \to +\infty$. *Proof.* For fixed $u \in S(c)$, we can easily get the conclusions (1) and (2) from the facts

$$\int_{\mathbb{R}^{3}} |(-\Delta)^{\frac{s}{2}} (\tau \star u)|^{2} = e^{2s\tau} \int_{\mathbb{R}^{3}} |(-\Delta)^{\frac{s}{2}} u|^{2},$$

$$I_{\mu}(u,\tau) = \frac{a}{2} e^{2s\tau} \int_{\mathbb{R}^{3}} |(-\Delta)^{\frac{s}{2}} u|^{2} + \frac{b}{4} e^{4s\tau} (\int_{\mathbb{R}^{3}} |(-\Delta)^{\frac{s}{2}} u|^{2})^{2} - \frac{e^{\beta_{q}q\tau}}{q} \int_{\mathbb{R}^{3}} |u|^{q} - \mu e^{\beta_{r}r\tau} \int_{\mathbb{R}^{3}} D_{M}(u) dx$$

$$\beta_{r}r \ge \beta_{q}q > 4s.$$

and $\beta_r r \ge \beta_q q > 4s$.

Lemma 2.7. For every $u \in S(c)$, there exists a unique $\tau_u \in \mathbb{R}$ such that $\tau_u \star u \in V(c)$, where τ_u is a strict maximum point for $\Phi_u(\tau)$ and $\Phi_u(\tau_u) > 0$. *Proof.* For $u \in S(c)$ and $\tau \in \mathbb{R}$, by (2.9) we have

$$\begin{aligned} (\Phi_u)''(\tau) &= 2as^2 \int_{\mathbb{R}^3} |(-\Delta)^{\frac{s}{2}} (\tau \star u)|^2 + 4bs^2 (\int_{\mathbb{R}^3} |(-\Delta)^{\frac{s}{2}} (\tau \star u)|^2)^2 \\ &- q\beta_q^2 \int_{\mathbb{R}^3} |(\tau \star u)|^q - \mu(\beta_r r)^2 \int_{\mathbb{R}^3} D_M(\tau \star u). \end{aligned}$$

$$(2.10)$$

Since $r\beta_r \ge q\beta_q > 4s$, it is easy to see that $(\Phi_u)'(\tau) > 0$ as $\tau \to -\infty$, and $(\Phi_u)'(\tau) < 0$ as $\tau \to \infty$. So, there exists $\tau_u \in \mathbb{R}$ such that $(\Phi_u)'(\tau_u) = 0$. From Lemma 2.5, $\tau_u \star u \in V(c)$.

Combining with $(\Phi_u)'(\tau_u) = 0$, (2.9) and (2.10), we have

$$(\Phi_u)''(\tau_u) = -2as^2 \int_{\mathbb{R}^3} |(-\triangle)^{\frac{s}{2}}(\tau \star u)|^2 - \beta_q (q\beta_q - 4s) \int_{\mathbb{R}^3} |(\tau \star u)|^q - \mu r\beta_r (r\beta_r - 4s) \int_{\mathbb{R}^3} D_M(\tau \star u) < 0,$$

which together with Lemma 2.6 implies that τ_u is unique and it is a strict global maximum point for $\Phi_u(\tau)$ and $\Phi_u(\tau_u) > 0$.

3. Characterization of mountain pass level

As in [4], firstly, we prove that $E_{\mu}(u)$ has the mountain pass geometry on $S(c) \times \mathbb{R}$ in the following lemma.

Lemma 3.1. There exists $k_c > 0$ such that

$$P_{\mu}(u), E_{\mu}(u) > 0 \text{ for all } u \in \mathbb{A}_{c}, \text{ and } 0 < \sup_{u \in \mathbb{A}_{c}} E_{\mu}(u) < \inf_{u \in \mathbb{B}_{c}} E_{\mu}(u)$$

with

$$\mathbb{A}_{c} = \{ u \in S(c) : \int_{\mathbb{R}^{3}} |(-\Delta)^{\frac{s}{2}} u|^{2} \le k_{c} \}, \ \mathbb{B}_{c} = \{ u \in S(c) : \int_{\mathbb{R}^{3}} |(-\Delta)^{\frac{s}{2}} u|^{2} = 2k_{c} \}.$$

Proof. Let k > 0 be arbitrary fixed and suppose $u, v \in S(c)$ are such that

$$\int_{\mathbb{R}^3} |(-\Delta)^{\frac{s}{2}} u|^2 \le k, \text{ and } \int_{\mathbb{R}^3} |(-\Delta)^{\frac{s}{2}} v|^2 = 2k.$$

AIMS Mathematics

Then for k small enough, by (2.4) and $\frac{3(r-2)}{2s} \ge \frac{3(q-2)}{2s} > 4$, there exist constants C_1 and C_2 such that

$$P_{\mu}(u) \ge a \int_{\mathbb{R}^{3}} |(-\Delta)^{\frac{s}{2}} u|^{2} + b(\int_{\mathbb{R}^{3}} |(-\Delta)^{\frac{s}{2}} u|^{2})^{2} - C_{1}(\int_{\mathbb{R}^{3}} |(-\Delta)^{\frac{s}{2}} u|^{2})^{\frac{3(q-2)}{2s}} - C_{2}(\int_{\mathbb{R}^{3}} |(-\Delta)^{\frac{s}{2}} u|^{2})^{\frac{3(r-2)}{2s}},$$

$$E_{\mu}(u) \ge \frac{a}{2} \int_{\mathbb{R}^{3}} |(-\Delta)^{\frac{s}{2}} u|^{2} + \frac{b}{4} (\int_{\mathbb{R}^{3}} |(-\Delta)^{\frac{s}{2}} u|^{2})^{2} - C_{1}(\int_{\mathbb{R}^{3}} |(-\Delta)^{\frac{s}{2}} u|^{2})^{\frac{3(q-2)}{2s}} - C_{2}(\int_{\mathbb{R}^{3}} |(-\Delta)^{\frac{s}{2}} u|^{2})^{\frac{3(r-2)}{2s}},$$

and

$$\begin{split} E_{\mu}(v) - E_{\mu}(u) &\geq \frac{a}{2} \int_{\mathbb{R}^{3}} |(-\Delta)^{\frac{s}{2}} v|^{2} + \frac{b}{4} (\int_{\mathbb{R}^{3}} |(-\Delta)^{\frac{s}{2}} v|^{2})^{2} - \frac{1}{q} \int_{\mathbb{R}^{3}} |v|^{q} - \mu \int_{\mathbb{R}^{3}} D_{M}(v) \\ &- \frac{a}{2} \int_{\mathbb{R}^{3}} |(-\Delta)^{\frac{s}{2}} u|^{2} - \frac{b}{4} (\int_{\mathbb{R}^{3}} |(-\Delta)^{\frac{s}{2}} u|^{2})^{2} \\ &\geq ak + bk^{2} - \frac{a}{2}k - \frac{b}{4}k^{2} - C_{1} (\int_{\mathbb{R}^{3}} |(-\Delta)^{\frac{s}{2}} v|^{2})^{\frac{3(q-2)}{2s}} - C_{2} (\int_{\mathbb{R}^{3}} |(-\Delta)^{\frac{s}{2}} v|^{2})^{\frac{3(r-2)}{2s}} \\ &\geq \frac{ak}{2} + \frac{ak^{2}}{2} - C_{1}k^{\frac{3(q-2)}{2s}} - C_{2}k^{\frac{3(r-2)}{2s}}. \end{split}$$

By the above inequalities, we can obtain that there exists $k_c > 0$ sufficiently small such that Lemma 3.2 holds.

Next, we need to construct the minimax characterization of I_{μ} and E_{μ} .

Lemma 3.2. Let

$$\tilde{\gamma}_{c,\mu} := \inf_{\tilde{h} \in \tilde{\Gamma}_c} \max_{t \in [0,1]} I_{\mu}(\tilde{h}(t))$$

with

$$\tilde{\Gamma}_{c} = \{ \tilde{h} \in C([0,1], S(c) \times \mathbb{R}) : \tilde{h}(0) \in (\mathbb{A}_{c}, 0), \tilde{h}(1) \in (E^{0}_{\mu}, 0) \}, \ E^{0}_{\mu} := \{ u \in S(c) : \ E_{\mu}(u) \le 0 \}$$

and

$$\gamma_{c,\mu} := \inf_{h \in \Gamma_c} \max_{t \in [0,1]} E_{\mu}(h(t))$$

with

$$\Gamma_c = \{h \in C([0, 1], S(c)) : h(0) \in \mathbb{A}_c, \ h(1) \in E_u^0\},\$$

then we have

$$\tilde{\gamma}_{c,\mu} = \gamma_{c,\mu} = m_{c,\mu} > 0.$$

Proof. Firstly, we prove that $\tilde{\gamma}_{c,\mu} = \gamma_{c,\mu}$. For any $\tilde{h} \in \tilde{\Gamma}_c$, we can write it into

$$\tilde{h}(t) = (\tilde{h}_1(t), \tilde{h}_2(t)) \in S(c) \times \mathbb{R}.$$

We set $h(t) = \tilde{h}_2(t) \star \tilde{h}_1(t)$, then $h(t) \in \Gamma_c$, and

$$\max_{t \in [0,1]} I_{\mu}(\tilde{h}(t)) = \max_{t \in [0,1]} E_{\mu}(\tilde{h}_2(t) \star \tilde{h}_1(t)) = \max_{t \in [0,1]} E_{\mu}(h(t)),$$

AIMS Mathematics

which implies $\tilde{\gamma}_{c,\mu} \ge \gamma_{c,\mu}$. On the other hand, for any $h \in \Gamma_c$, if we set $\tilde{h}(t) = (h(t), 0)$, then we get $\tilde{h} \in \tilde{\Gamma}_c$ and

$$\max_{t \in [0,1]} I_{\mu}(\hat{h}(t)) = \max_{t \in [0,1]} E_{\mu}(h(t))$$

This infers that $\tilde{\gamma}_{c,\mu} \leq \gamma_{c,\mu}$. So, $\tilde{\gamma}_{c,\mu} = \gamma_{c,\mu}$.

Secondly, we claim that for $u \in S(c)$, $E_{\mu}(u) \le 0$ implies $P_{\mu}(u) < 0$.

For $u \in S(c)$, if $E_{\mu}(u) \le 0$, then $\Phi_u(0) \le 0$. By the proof of Lemma 2.7 and Lemma 2.6, we easily see that $\tau_u < 0$, so

$$P_{\mu}(u) = P_{\mu}(0 \star u) = \frac{1}{s}(\Phi_{u})'(0) < \frac{1}{s}(\Phi_{u})'(\tau_{u}) = 0$$

That is

$$E_{\mu}(u) \le 0 \Rightarrow P_{\mu}(u) < 0. \tag{3.1}$$

Next, we prove that $m_{c,\mu} = \gamma_{c,\mu}$.

For any $u \in V(c)$, by Lemma 2.6 and Lemma 2.3, there exists $t^- \ll -1$ and $t^+ \gg 1$ such that

$$h_u: \tau \in [0, 1] \rightarrow ((1 - \tau)t^- + \tau t^+) \star u \text{ and } h_u \in \Gamma_c$$

By Lemma 2.7, we have $\max_{\tau \in [0,1]} E_{\mu}(h_u(\tau)) = E_{\mu}(u)$. So we have $m_{c,\mu} \ge \gamma_{c,\mu}$. On the other hand, for any $\tilde{h}(\tau) = (\tilde{h}_1(\tau), \tilde{h}_2(\tau)) \in \tilde{\Gamma}_c$, we know that $\tilde{h}_2(0) \star \tilde{h}_1(0) = \tilde{h}_1(0) \in \mathbb{A}_c$, $\tilde{h}_2(1) \star \tilde{h}_1(1) = \tilde{h}_1(1) \in E^0_{\mu}$. Hence by Lemma 3.1, we can deduce that

$$P_{\mu}(\tilde{h}_2(0) \star \tilde{h}_1(0)) > 0,$$

and using (3.1),

$$P_{\mu}(\tilde{h}_2(1) \star \tilde{h}_1(1)) < 0.$$

From Lemma 2.3, the function $\tilde{P}_{\mu}(\tau) := P_{\mu}(\tilde{h}_2(\tau) \star \tilde{h}_1(\tau))$ is continuous in [0, 1]. Therefore, there exists $\bar{\tau} \in (0, 1)$ such that $\tilde{P}_{\mu}(\bar{\tau}) = 0$, which implies that $\tilde{h}_2(\bar{\tau}) \star \tilde{h}_1(\bar{\tau}) \in V(c)$, and

$$\max_{\tau \in [0,1]} I(\tilde{h}(\tau)) = \max_{\tau \in [0,1]} E_{\mu}(\tilde{h}_2(\tau) \star \tilde{h}_1(\tau)) \ge \inf_{u \in V(c)} E_{\mu}(u),$$

which implies that $\gamma_{c,\mu} = \tilde{\gamma}_{c,\mu} \ge m_{c,\mu}$. So, $m_{c,\mu} = \gamma_{c,\mu}$.

Finally, we prove that $m_{c,\mu} > 0$. For any $u \in V(c)$, then $P_{\mu}(u) = 0$. By (2.4), we have

$$a\int_{\mathbb{R}^{3}}|(-\Delta)^{\frac{s}{2}}u|^{2}dx+b(\int_{\mathbb{R}^{3}}|(-\Delta)^{\frac{s}{2}}u|^{2}dx)^{2}\leq C_{1}(\int_{\mathbb{R}^{3}}|(-\Delta)^{\frac{s}{2}}u|^{2}dx)^{\frac{q\beta_{q}}{s}}+C_{2}(\int_{\mathbb{R}^{3}}|(-\Delta)^{\frac{s}{2}}u|^{2}dx)^{\frac{r\beta_{r}}{s}},$$

noticing that $r\beta_r \ge q\beta_q > 4s$, there exists $\delta > 0$ such that $\inf_{u \in V(c)} \int_{\mathbb{R}^3} |(-\Delta)^{\frac{s}{2}} u|^2 dx \ge \delta$, and

$$E_{\mu}(u) = E_{\mu}(u) - \frac{1}{4}P_{\mu}(u) = \frac{a}{4} \int_{\mathbb{R}^{3}} |(-\Delta)^{\frac{s}{2}}u|^{2} dx + (\frac{\beta_{q}}{4s} - \frac{1}{q}) \int_{\mathbb{R}^{3}} |u|^{q} dx + \mu(\frac{r\beta_{r}}{4s} - 1) \int_{\mathbb{R}^{3}} D_{M}(u) dx + \frac{a}{4\delta} \delta$$

Thus, $m_{c,\mu} > 0$.

AIMS Mathematics

Volume 7, Issue 6, 10790-10806.

Remark 3.3. Let

$$\rho_c := \inf_{h \in \Gamma_c^0} \max_{t \in [0,1]} E_0(h(t))$$

with

$$\Gamma_c^0 = \{h \in C([0,1], S(c)) : h(0) \in \mathbb{A}_c, \ h(1) \in E^0\}, \ E^0 := \{u \in S(c) : \ E_0(u) \le 0\}.$$

Obviously, $\Gamma_c^0 \subset \Gamma_c$, $E_0(u) \ge E_{\mu}(u)$ for $u \in S(c)$. Thus we can deduce that ρ_c is independent of positive numbers μ , M and $\rho_c \ge \gamma_{c,\mu}$ for any $\mu > 0$.

In the following lemma, we give the relationship between the Palais-Smale sequence for I and that of E_{μ} .

Lemma 3.4. Let $\tilde{\gamma}_{c,\mu}$ and $\gamma_{c,\mu}$ be defined in Lemma 3.2. Then there exist a sequence $\{(v_n, \tau_n)\} \subset S(c) \times \mathbb{R}$ such that for $n \to \infty$, we have

(1) $I_{\mu}(v_n, \tau_n) \to \tilde{\gamma}_{c,\mu}$, (2) $(I_{\mu})'|_{S(c) \times \mathbb{R}}(v_n, \tau_n) \to 0$, i.e., it holds that

$$\partial_{\tau} I_{\mu}(v_n, \tau_n) \to 0$$

and

$$\langle \partial_u I_\mu(v_n, \tau_n), \tilde{\varphi} \rangle \to 0$$

with

$$\tilde{\varphi} \in T_{\nu_n} := \{ \varphi \in H : \int_{\mathbb{R}^3} \nu_n \varphi = 0 \}.$$

In addition, setting $u_n(x) = \tau_n \star v_n(x)$, then for $n \to \infty$, we get (i) $E_{\mu}(u_n) \to \gamma_{c,\mu}$, (ii) $P_{\mu}(u_n) \to 0$, (iii) $E'_{\mu}|_{S(c)}(u_n) \to 0$, i.e., it holds that

$$\langle E'_{\mu}(u_n), \varphi \rangle \to 0$$

with

$$\varphi \in T_{u_n} := \{ \varphi \in H : \int_{\mathbb{R}^3} u_n \varphi = 0 \}.$$

Proof. According to the construction of $\tilde{\gamma_{c,\mu}}$, we know that the conclusions (1) and (2) follow directly from the Ekeland's Variational Principle [8, Proposition 2.2]. Next we mainly show (i)–(iii).

For (i), by Lemma 3.2, $\tilde{\gamma}_{c,\mu} = \gamma_{c,\mu}$. we notice that

$$E_{\mu}(u_n) = E_{\mu}(\tau_n \star v_n) = I_{\mu}(v_n, \tau_n),$$

thus (i) holds.

By (2.9), we can get that $\partial_{\tau}I_{\mu}(v_n, \tau_n) = sP_{\mu}(\tau_n \star v_n)$. Thus, (ii) is a consequence of $\partial_{\tau}I_{\mu}(v_n, \tau_n) \to 0$ as $n \to \infty$.

For the proof of (iii), by the definition of I_{μ} , we have

$$\begin{aligned} \langle \partial_{u}I_{\mu}(v_{n},\tau_{n}),\tilde{\varphi} \rangle &= ae^{2s\tau_{n}} \int \int_{\mathbb{R}^{6}} \frac{(v_{n}(x)-v_{n}(y))(\tilde{\varphi}(x)-\tilde{\varphi}(y))}{|x-y|^{3+2s}dxdy} \\ &+ be^{4s\tau_{n}} \int \int_{\mathbb{R}^{6}} \frac{(v_{n}(x)-v_{n}(y))^{2}}{|x-y|^{3+2s}dxdy} \int \int_{\mathbb{R}^{6}} \frac{(v_{n}(x)-v_{n}(y))(\tilde{\varphi}(x)-\tilde{\varphi}(y))}{|x-y|^{3+2s}dxdy} \\ &- e^{\beta_{q}q\tau_{n}} \int_{\mathbb{R}^{3}} |v_{n}|^{q-2}v_{n}\tilde{\varphi} - \mu e^{\beta_{r}r\tau} \int_{\mathbb{R}^{3}} d_{M}(v_{n})\tilde{\varphi}, \end{aligned}$$

AIMS Mathematics

where $\tilde{\varphi} \in T_{\nu_n}$. On the other hand, for any φ with satisfying $\varphi \in T_{u_n}$, by using (2.3), we have

$$\begin{aligned} \langle E'_{\mu}(u_{n}),\varphi \rangle \\ &= a \int \int_{\mathbb{R}^{6}} \frac{(u_{n}(x) - u_{n}(y))(\varphi(x) - \varphi(y))}{|x - y|^{3 + 2s}} dx dy \\ &+ b \int \int_{\mathbb{R}^{6}} \frac{(u_{n}(x) - u_{n}(y))^{2}}{|x - y|^{3 + 2s}} dx dy \int \int_{\mathbb{R}^{6}} \frac{(u_{n}(x) - u_{n}(y))(\varphi(x) - \varphi(y))}{|x - y|^{3 + 2s}} dx dy \\ &- \int_{\mathbb{R}^{3}} |u_{n}|^{q - 2} u_{n}\varphi dx - \mu \int_{\mathbb{R}^{3}} d_{M}(u_{n})\varphi dx \\ &= a \int \int_{\mathbb{R}^{6}} \frac{e^{\frac{3}{2}\tau_{n}}(v_{n}(e^{\tau_{n}}x) - v_{n}(e^{\tau_{n}}y))(\varphi(x) - \varphi(y))}{|x - y|^{3 + 2s}} dx dy \int \int_{\mathbb{R}^{6}} \frac{e^{\frac{3}{2}\tau_{n}}(v_{n}(e^{\tau_{n}}x) - v_{n}(e^{\tau_{n}}y))(\varphi(x) - \varphi(y))}{|x - y|^{3 + 2s}} dx dy \\ &+ b \int \int_{\mathbb{R}^{6}} \frac{e^{3\tau_{n}}(v_{n}(e^{\tau_{n}}x) - v_{n}(e^{\tau_{n}}x))}{|x - y|^{3 + 2s}} dx dy \int \int_{\mathbb{R}^{6}} \frac{e^{\frac{3}{2}\tau_{n}}v_{n}(e^{\tau_{n}}x) - v_{n}(e^{\tau_{n}}y)}{|x - y|^{3 + 2s}} dx dy \\ &- \int_{\mathbb{R}^{3}} |e^{\frac{3}{2}\tau_{n}}v_{n}(e^{\tau_{n}}x)|^{q - 2}e^{\frac{3}{2}\tau_{n}}v_{n}(e^{\tau_{n}}x)\varphi(x) dx - \mu \int_{\mathbb{R}^{3}} d_{M}(e^{\frac{3}{2}\tau_{n}}v_{n}(e^{\tau_{n}}x))\varphi(x) dx \\ &= ae^{2s\tau_{n}} \int \int_{\mathbb{R}^{6}} \frac{(v_{n}(x) - v_{n}(y))(e^{-\frac{3}{2}\tau_{n}}\varphi(e^{-\tau_{n}}x) - e^{-\frac{3}{2}\tau_{n}}\varphi(e^{-\tau_{n}}y))}{|x - y|^{3 + 2s}} dx dy \\ &+ be^{4s\tau_{n}} \int \int_{\mathbb{R}^{6}} \frac{(v_{n}(x) - v_{n}(y))^{2}}{|x - y|^{3 + 2s}} dx dy \int \int_{\mathbb{R}^{6}} \frac{(v_{n}(x) - v_{n}(y))(e^{-\frac{3}{2}\tau_{n}}\varphi(e^{-\tau_{n}}x) - e^{-\frac{3}{2}\tau_{n}}\varphi(e^{-\tau_{n}}y)}{|x - y|^{3 + 2s}} dx dy \\ &- e^{q\beta_{q}\tau_{n}} \int_{\mathbb{R}^{3}} |v_{n}(x)|^{q - 2}v_{n}(x)e^{-\frac{3}{2}\tau_{n}}\varphi(e^{-\tau_{n}}x) dx - \mu e^{r\beta_{r}\tau_{n}} \int_{\mathbb{R}^{3}} d_{M}(v_{n})e^{-\frac{3}{2}\tau_{n}}\varphi(e^{-\tau_{n}}x) dx \end{aligned}$$

Setting

$$\tilde{\varphi}(x) = e^{-\frac{3}{2}\tau_n} \varphi(e^{-\tau_n} x),$$

we get (iii) if we could show that $\tilde{\varphi} \in T_{v_n}$. In fact, $\tilde{\varphi} \in T_{v_n}$ follows from the following equalities

$$0 = \int_{\mathbb{R}^3} u_n \varphi = \int_{\mathbb{R}^3} e^{\frac{3}{2}\tau_n} v_n(e^{\tau_n} x) \varphi(x)$$

=
$$\int_{\mathbb{R}^3} v_n(x) e^{-\frac{3}{2}\tau_n} \varphi(e^{-\tau_n} x) = \int_{\mathbb{R}^3} v_n \tilde{\varphi}.$$

4. Proof of Theorem 2.1

According to Lemma 3.4 and Lemma 3.2, there exist a Palais-Smale sequence $\{u_n\} \subset S(c)$ for $E_{\mu}|_{S(c)}$ at level $\gamma_{c,\mu} > 0$, and it satisfies $P_{\mu}(u_n) \to 0$ as $n \to \infty$. By applying the Lagrange multipliers rule there exists $\{\lambda_n\} \subset \mathbb{R}$ such that

$$(a+b\int_{\mathbb{R}^3} |(-\Delta)^{\frac{s}{2}} u_n|^2)(-\Delta)^s u_n - |u_n|^{q-2} u_n - \mu d_M(u) = \lambda_n u_n + o(1), \text{ as } n \to \infty.$$
(4.1)

(1). As $P_{\mu}(u_n) \rightarrow 0$, we have

$$a \int_{\mathbb{R}^3} |(-\Delta)^{\frac{s}{2}} u_n|^2 + b (\int_{\mathbb{R}^3} |(-\Delta)^{\frac{s}{2}} u_n|^2)^2 = \frac{\beta_q}{s} \int_{\mathbb{R}^3} |u_n|^q + \frac{\mu \beta_r r}{s} \int_{\mathbb{R}^3} D_M(u_n) + o(1) \text{ as } n \to \infty.$$
(4.2)

AIMS Mathematics

Thus, by (4.2) we deduce that

$$\begin{split} E_{\mu}(u_{n}) + o_{n}(1) &= \frac{a}{2} \int_{\mathbb{R}^{3}} |(-\Delta)^{\frac{s}{2}} u_{n}|^{2} + \frac{b}{4} (\int_{\mathbb{R}^{3}} |(-\Delta)^{\frac{s}{2}} u_{n}|^{2})^{2} - \mu \int_{\mathbb{R}^{3}} D_{M}(u_{n}) \\ &- \frac{1}{q} \frac{s}{\beta_{q}} [a \int_{\mathbb{R}^{3}} |(-\Delta)^{\frac{s}{2}} u_{n}|^{2} + b (\int_{\mathbb{R}^{3}} |(-\Delta)^{\frac{s}{2}} u_{n}|^{2})^{2} - \frac{\mu \beta_{r} r}{s} \int_{\mathbb{R}^{3}} D_{M}(u_{n})] + o(1) \\ &= a (\frac{1}{2} - \frac{s}{\beta_{q} q}) \int_{\mathbb{R}^{3}} |(-\Delta)^{\frac{s}{2}} u_{n}|^{2} + b (\frac{1}{4} - \frac{s}{\beta_{q} q}) (\int_{\mathbb{R}^{3}} |(-\Delta)^{\frac{s}{2}} u_{n}|^{2})^{2} \\ &+ \mu (\frac{\beta_{r} r}{\beta_{q} q} - 1) \int_{\mathbb{R}^{3}} D_{M}(u_{n}) \\ &\leq \gamma_{c,\mu} + 1 \end{split}$$

$$(4.3)$$

Since $\frac{6+8s}{3} < q < 2_s^*$ and (2.7), it implies that $\frac{s}{\beta_q q} < \frac{1}{4}$ and $\beta_r r \ge \beta_q q$. According to (4.3), we can deduce the boundedness of $\int_{\mathbb{R}^3} |(-\Delta)^{\frac{s}{2}} u_n|^2$, thus $\{u_n\}$ is bounded in *H*.

(2). According to Lemma 2.2, we know that the embedding $H_r^s(\mathbb{R}^3) \hookrightarrow L^t(\mathbb{R}^3)$ is compact for $t \in (2, 2_s^*)$, and we can deduce that there exists $u_c \in H_r^s(\mathbb{R}^3)$ such that, up to a subsequence, $u_n \rightharpoonup u_c$ weakly in $H, u_n \rightarrow u_c$ strongly in $L^q(\mathbb{R}^3)$ for $q \in (\frac{6+8s}{3}, 2_s^*)$. since $\{u_n\} \subset S(c)$ is bounded in H. By (4.1), we obtain that

$$\lambda_n c^2 = a \int_{\mathbb{R}^3} |(-\Delta)^{\frac{s}{2}} u_n|^2 + b (\int_{\mathbb{R}^3} |(-\Delta)^{\frac{s}{2}} u_n|^2)^2 - \int_{\mathbb{R}^3} |u_n|^q - \mu r \int_{\mathbb{R}^3} D_M(u_n) + o_n(1).$$
(4.4)

Using the fact that the boundedness of $\{u_n\}$ in H and (4.2), we can deduce that $\{\lambda_n\}$ is bounded. Hence, up to a subsequence $\lambda_n \to \lambda_c \in \mathbb{R}$.

(3). We claim that $u_c \neq 0$. We assume by contradiction that $u_c \equiv 0$, by (4.2) we deduce that $\int_{\mathbb{R}^3} |(-\Delta)^{\frac{s}{2}} u_n|^2 \to 0$. Recalling that $P_{\mu}(u_n) \to 0$, according to (4.3), we have $E_{\mu}(u_n) \to 0$, which is a contradiction to the assumption that $E_{\mu}(u_n) \to \gamma_{c,\mu} \neq 0$. Now, since $\lambda_n \to \lambda_c$ and $u_n \to u_c \neq 0$ weakly in *H*, together with (4.1), we know (u_c, λ_c) is a couple of solutions to (2.1). By the Pohozaev identity, we obtain

$$\frac{3-2s}{2}a\int_{\mathbb{R}^3}|(-\Delta)^{\frac{s}{2}}u_c|^2+\frac{3-2s}{2}b(\int_{\mathbb{R}^3}|(-\Delta)^{\frac{s}{2}}u_c|^2)^2=3(\int_{\mathbb{R}^3}\frac{1}{2}\lambda_c|u_c|^2+\frac{1}{q}|u_c|^q+\mu D_M(u_c)).$$

Combining with the (4.4) for u_c , we get

$$\lambda_c c^2 = \lambda_c |u_c|_2^2 = \frac{(3-2s)(q-2_s^*)}{3(q-2)} \left[a \int_{\mathbb{R}^3} |(-\Delta)^{\frac{s}{2}} u_c|^2 + b(\int_{\mathbb{R}^3} |(-\Delta)^{\frac{s}{2}} u_c|^2)^2\right] + \mu \frac{2(r-q)}{(q-2)} \int_{\mathbb{R}^3} D_M(u_c) \quad (4.5)$$

Since $\frac{6+8s}{3} < q < 2_s^*$ and (4.5), there exists $\mu_1 > 0$ such that $\lambda_c < 0$ for $\mu \in (0, \mu_1]$. (4). Testing (4.1) and (2.1) with $u_n - u_c$, we can obtain that

$$\langle E'_{\mu}(u_n) - E'_{\mu}(u_c), u_n - u_c \rangle - \lambda_c \int_{\mathbb{R}^3} |u_n - u_c|^2 = o_n(1).$$

Using the strong L^p convergence of u_n , we infer that

$$a\int_{\mathbb{R}^3} |(-\Delta)^{\frac{s}{2}} (u_n - u_c)|^2 + b(\int_{\mathbb{R}^3} |(-\Delta)^{\frac{s}{2}} (u_n - u_c)|^2)^2 - \lambda_c \int_{\mathbb{R}^3} |u_n - u_c|^2 = o_n(1),$$

which, being $\lambda_c < 0$, implies $u_n \to u_c$ strongly in H. Therefore, $E_{\mu}(u_n) \to E_{\mu}(u_c)$, as $n \to \infty$. From Lemma 2.4 and Lemma 3.2, we easily obtain that u_c is a ground state of (2.1) and $E_{\mu}(u_c) = m_{c,\mu}$.

AIMS Mathematics

5. Proof of main result

In this section, we devote to complete the proof of Theorem 1.1. From the truncation argument in Sections 2–4, we can see that if the ground state u_c of (2.1) satisfy $||u_c||_{\infty} \leq M$. Then $u_c \in H$ is a ground state of (1.1).

Lemma 5.1. Let(u_c , λ_c) be a couple of solutions of problem (2.1) for $\mu \in (0, \mu_1]$, then there exists a constant $K_c > 0$ independent of μ , M > 0 such that $||u_c|| \le K_c$. *Proof.* By Theorem 2.1 and Lemma 2.4, it is easy to see that

$$E_{\mu}(u_c) = \gamma_{c,\mu} \text{ and } P_{\mu}(u_c) = 0,$$
 (5.1)

It follows from (5.1) and Remark 3.3 that

$$\rho_c \ge \gamma_{c,\mu} \ge E_{\mu}(u_c) - \frac{1}{4}P_{\mu}(u_c) \ge \frac{a}{4}||u_c||^2$$

Consequently, there exists a constant $K_c > 0$ independent of μ , M > 0 such that $||u_c|| \le K_c$.

Lemma 5.2. If (u_c, λ_c) be a couple of solutions of problem (2.1) for $\mu \in (0, \mu_1]$, then $u_c \in L^{\infty}(\mathbb{R}^3)$, and there exists a constant $B_c > 0$ independent $\mu, M > 0$ such that

$$||u_c||_{\infty} \leq B_c(1+\mu^{\frac{1}{2^*_{s-q}}}M^{\frac{p-q}{2^*_{s-q}}}).$$

Proof. For convenience, we replace u_c with u in the following. Let L > 0 and $\beta > 1$, we first define the following functions:

$$\Upsilon(u) = u u_L^{2(\beta-1)} \in H,$$

where $u_L = min\{u, L\}$. Since Υ is an increasing function, we have

$$(x - y)[\Upsilon(x) - \Upsilon(y] \ge 0, \quad \forall x, y \in \mathbb{R}.$$

Let $\Phi(t) = \frac{1}{2}|t|^2$ and $\Psi(t) = \int_0^t (\Upsilon'(\tau))^{\frac{1}{2}} d\tau$. Then, if x > y, by Cauchy-Schwarz inequality, we have

$$\Phi'(x-y)[\Upsilon(x) - \Upsilon(y)] = (x-y)[\Upsilon(x) - \Upsilon(y)]$$

= $(x-y) \int_{y}^{x} \Upsilon'(t) dt$
= $(x-y) \int_{y}^{x} (\Psi'(t))^{2} dt$
 $\geq (\int_{y}^{x} \Psi'(t) dt)^{2}$
= $|\Psi(x) - \Psi(y)|^{2}$.

The same arguments hold for $x \le y$. Therefore,

$$\Phi'(x-y)[\Upsilon(x)-\Upsilon(y)] \ge |\Psi(x)-\Psi(y)|^2, \quad \forall x, y \in \mathbb{R}.$$
(5.2)

AIMS Mathematics

By the definition of u_L , it is easy to see that $|uu_L^{2(\beta-1)}| \le L^{2(\beta-1)}u$ and $\Upsilon(u) \in H$. Taking $\Upsilon(u)$ as a test function in Eq (2.1), and let $g_{\mu,M}(x,t) = |t|^{q-2}t + \mu d_M(t)$, we obtain

$$(a+b\int_{\mathbb{R}^{3}}|(-\Delta)^{\frac{s}{2}}u|^{2})\int\int_{\mathbb{R}^{3}\times\mathbb{R}^{3}}\frac{(u(x)-u(y))(uu_{L}^{2(\beta-1)}(x)-uu_{L}^{2(\beta-1)}(y))}{|x-y|^{3+2s}}dxdy$$

= $\lambda\int_{\mathbb{R}^{3}}u(x)uu_{L}^{2(\beta-1)}(x)dx + \int_{\mathbb{R}^{3}}g_{\mu,M}(x,u(x))uu_{L}^{2(\beta-1)}(x)dx.$ (5.3)

Since $\Psi(u) \ge \frac{1}{\beta}uu_L^{\beta-1}$ and (5.2), we get

$$a \int \int_{\mathbb{R}^{3} \times \mathbb{R}^{3}} \frac{(u(x) - u(y))(uu_{L}^{2(\beta-1)}(x) - uu_{L}^{2(\beta-1)}(y))}{|x - y|^{3+2s}} dxdy$$

$$\geq \frac{a}{\beta^{2}} \int \int_{\mathbb{R}^{3} \times \mathbb{R}^{3}} \frac{|uu_{L}^{\beta-1}(x) - uu_{L}^{\beta-1}(y)|^{2}}{|x - y|^{3+2s}} dxdy.$$
(5.4)

For any $\varepsilon > 0$, there exists $C_{\varepsilon} > 0$ such that

$$|g_{\mu,M}(x,t)| \le \varepsilon |t| + C_{\varepsilon} (1 + \mu M^{p-q}) |t|^{q-1}.$$
(5.5)

Let $\omega_L = u u_L^{\beta-1}$. By employing Hölder's inequality and (5.3)–(5.5), we have

$$\frac{a}{\beta^{2}} \int \int_{\mathbb{R}^{3} \times \mathbb{R}^{3}} \frac{|\omega_{L}(x) - \omega_{L}(y)|^{2}}{|x - y|^{3 + 2s}} dx dy$$

$$\leq \varepsilon \int_{\mathbb{R}^{3}} (\omega_{L})^{2} dx + C_{\varepsilon} (1 + \mu M^{p-q}) \int_{\mathbb{R}^{3}} |u(x)|^{q-2} (\omega_{L})^{2} dx$$

$$\leq \varepsilon \int_{\mathbb{R}^{3}} (\omega_{L})^{2} dx + C_{\varepsilon} (1 + \mu M^{p-q}) (\int_{\mathbb{R}^{3}} |u(x)|^{2^{*}_{s}} dx)^{\frac{q-2}{2^{*}_{s}}} ((\omega_{L})^{2t} dx)^{\frac{1}{t}},$$
(5.6)

where $\frac{q-2}{2_s^*} + \frac{1}{t} = 1$ and $2t \in (2, 2_s^*)$. Moreover, it follows from (1.4) that

$$S_{s}^{*} ||u||_{2_{s}^{*}}^{2} \leq \int_{\mathbb{R}^{3}} |(-\Delta)^{\frac{s}{2}} u|^{2}.$$
(5.7)

Therefore, we deduce from (5.6) and (5.7) that

$$\|\omega_L\|_{2_s^*}^2 \le C\beta^2 [\|\omega_L\|_2^2 + (1 + \mu M^{p-q})\|u\|_{2_s^*}^{q-2} \|\omega_L\|_{2_t}^2],$$

where C > 0 is a constant. From the definition of u_L , we have $u_L \le u$ in \mathbb{R}^3 . Letting $L \to +\infty$, using the Fatou's Lemma, one has

$$\|u\|_{\beta 2_{s}^{*}}^{2\beta} \leq C\beta^{2}[\|u\|_{2\beta}^{2\beta} + (1 + \mu M^{p-q})\|u\|_{2_{s}^{*}}^{q-2}\|u\|_{2\beta t}^{2\beta}].$$
(5.8)

By the interpolation inequality, we get $||u||_{2\beta} \le ||u||_2^{1-\sigma} ||u||_{2\beta t}^{\sigma}$, where $\sigma \in (0, 1)$ satisfies $\frac{1}{2\beta} = \frac{1-\sigma}{2} + \frac{\sigma}{2\beta t}$. Thus, $\sigma = \frac{t(\beta-1)}{t\beta-1}$, which shows that $\sigma \to 1$ as $\beta \to +\infty$. Since $2\beta(1-\sigma) = 2 + \frac{2(1-\beta)}{t\beta-1} < 2$, we get

$$\|u\|_{2\beta}^{2\beta} \le \|u\|_{2}^{2\beta(1-\sigma)} \|u\|_{2\beta t}^{2\beta\sigma} \le (1+\|u\|_{2})^{2} \|u\|_{2\beta t}^{2\beta\sigma},$$

which together with (5.8) yields

$$\|u\|_{\beta 2_s^*} \le C_1^{\frac{1}{2\beta}} \beta^{\frac{1}{\beta}} [1 + \|u\|_2^2 + (1 + \mu M^{p-q}) \|u\|_{2_s^*}^{q-2}]^{\frac{1}{2\beta}} \|u\|_{2\beta_t}^k.$$
(5.9)

AIMS Mathematics

where $k \in \{\sigma, 1\}$ and $C_1 > 0$ is a constant. Let $\theta := \frac{2^*_s}{2t}$, then $\theta > 1$. Taking $\beta = \theta$ in (3.13), we deduce that

$$\|u\|_{\theta 2_s^*} \le C_1^{\frac{1}{2\theta}} \theta^{\frac{1}{\theta}} [1 + \|u\|_2^2 + (1 + \mu M^{p-q}) \|u\|_{2_s^*}^{q-2}]^{\frac{1}{2\theta}} \|u\|_{2_s^*}^{k_1},$$
(5.10)

where $k_1 \in \{\sigma_1, 1\}$ and $\sigma_1 = \frac{t(\theta-1)}{t\theta-1}$. Taking $\beta = \theta^2$ in (5.9), we get

$$\|u\|_{\theta^{2}2_{s}^{*}} \leq C_{1}^{\frac{1}{2\theta^{2}}} \theta^{\frac{2}{\theta^{2}}} [1 + \|u\|_{2}^{2} + (1 + \mu M^{p-q}) \|u\|_{2_{s}^{*}}^{q-2}]^{\frac{1}{2\theta^{2}}} \|u\|_{2_{s}^{*}\theta}^{k_{2}},$$
(5.11)

where $k_2 \in \{\sigma_2, 1\}$ and $\sigma_2 = \frac{t(\theta^2 - 1)}{t\theta^2 - 1}$. Combining (5.10) with (5.11), we have

$$\|u\|_{\theta^{2}2_{s}^{*}} \leq C_{1}^{\frac{1}{2\theta} + \frac{1}{2\theta^{2}}} \theta^{\frac{1}{\theta} + \frac{2}{\theta^{2}}} [1 + \|u\|_{2}^{2} + (1 + \mu M^{p-q}) \|u\|_{2_{s}^{*}}^{q-2}]^{\frac{1}{2\theta} + \frac{1}{2\theta^{2}}} \|u\|_{2_{s}^{*}}^{k_{1}k_{2}}.$$

Taking $\beta = \theta^i, i \in \mathbb{N}$, one has

$$\|u\|_{\theta^{i}2_{s}^{*}} \leq C_{1}^{\sum_{m=1}^{i} \frac{1}{2\theta^{m}}} \theta^{\sum_{m=1}^{i} \frac{m}{\theta^{m}}} [1 + \|u\|_{2}^{2} + (1 + \mu M^{p-q}) \|u\|_{2_{s}^{*}}^{q-2} \int_{m=1}^{\sum_{m=1}^{i} \frac{1}{2\theta^{m}}} \|u\|_{2_{s}^{*}}^{k_{1}k_{2}\dots k_{i}}.$$
(5.12)

where $k_i \in \{\sigma_i, 1\}$ and $\sigma_i = \frac{t(\theta^i - 1)}{t\theta^i - 1}$. Next, we divide into two cases: $||u||_{2_s^*} \ge 1$ and $||u||_{2_s^*} < 1$.

(1) Assume that $||u||_{2_s^*} \ge 1$ is in force. In view of $k_1k_2 \dots k_i \le 1$, we have $||u||_{2_s^*}^{k_1k_2\dots k_i} \le ||u||_{2_s^*}$. Letting $i \to +\infty$ in (5.12), we can know that

$$\|u\|_{\infty} \leq C_{1}^{\frac{1}{2(\theta-1)}} \theta^{\frac{\theta}{(\theta-1)^{2}}} [1 + \|u\|_{2}^{2} + (1 + \mu M^{p-q}) \|u\|_{2_{s}^{*}}^{q-2}]^{\frac{1}{2(\theta-1)}} \|u\|_{2_{s}^{*}}.$$

(2) Assume that $||u||_{2_s^*} < 1$ is true. By $\sigma_i = \frac{t(\theta^i - 1)}{t\theta^i - 1} = 1 - \frac{t - 1}{t\theta^i - 1}$ and $k_i \in \sigma_i$, 1, we have $0 < \sigma_1 \sigma_2 \dots \sigma_i \le 1$ $k_1k_2...k_i \leq 1$, which shows that $\sum_{m=1}^{i} ln\sigma_m \leq \sum_{m=1}^{i} lnk_m \leq 0$. From the fact that $ln(1-s) \geq \frac{-s}{1-s}$ for all $s \in (0, 1)$, one has

$$\sum_{m=1}^{i} lnk_m \ge \sum_{m=1}^{i} ln\sigma_m = \sum_{m=1}^{i} ln(1 - \frac{t-1}{t\theta^m - 1}) \ge \frac{1-t}{t} \sum_{m=1}^{i} \frac{1}{\theta^m - 1} := A,$$

which implies that

 $k_1k_2\ldots k_i \geq e^A$ for all $i \in \mathbb{N}$.

By $||u||_{2^*_s} < 1$, we have $||u||_{2^*_s}^{k_1k_2...k_i} \le ||u||_{2^*_s}^{e^A}$. Similarly, letting $i \to +\infty$ in (3.16), we reach

$$\|u\|_{\infty} \leq C_{1}^{\frac{1}{2(\theta-1)}} \theta^{\frac{\theta}{(\theta-1)^{2}}} [1 + \|u\|_{2}^{2} + (1 + \mu M^{p-q}) \|u\|_{2_{s}^{*}}^{q-2}]^{\frac{1}{2(\theta-1)}} \|u\|_{2_{s}^{*}}^{e^{A}}.$$

Consequently, we have $u \in L^{\infty}(\mathbb{R}^3)$ and

$$\|u\|_{\infty} \le C_1^{\frac{1}{2(\theta-1)}} \theta^{\frac{\theta}{(\theta-1)^2}} [1 + c^2 + (1 + \mu M^{p-q}) \|u\|_{2_s^*}^{q-2}]^{\frac{1}{2(\theta-1)}} \|u\|_{2_s^*}^{\tau},$$
(5.13)

where $\tau = 1$ or $\tau = e^A \le 1$.

AIMS Mathematics

Finally, by (1.4) and Lemma 5.1, there exists $C_2 > 0$ such that $||u||_{2_s^*} \le C_2$. Therefore, it follows from (5.13) and $\theta = \frac{2_s^* - q + 2}{2}$, there exists a constant $B_c > 0$ independent μ , M > 0 such that

$$||u||_{\infty} \leq B_{c}(1+\mu^{\frac{1}{2^{*}_{s}-q}}M^{\frac{p-q}{2^{*}_{s}-q}}).$$

Proof of the Theorem 1.1. By Lemma 5.2, for any c > 0, there exists a constant $B_c > 0$ independent on μ and M such that

$$||u_c||_{\infty} \leq B_c(1+\mu^{\frac{1}{2^*_s-q}}M^{\frac{p-q}{2^*_s-q}}).$$

Thus, for large M > 0, we can choose small $\mu^* > 0$ with $\mu^* \le \mu_1$ such that $||u_c||_{\infty} \le M$ for all $\mu \in (0, \mu^*]$. By Theorem 2.1, problem (1.1) has a couple of solutions $(u_c, \lambda_c) \in H^s_r(\mathbb{R}^3) \times \mathbb{R}$ for any $\mu \in (0, \mu^*]$. Moreover, u_c is a positive ground state, radially symmetric function and $\lambda_c < 0$.

Acknowledgments

The authors would like to thank the anonymous referees for carefully reading this paper and making valuable comments and suggestions. This research was funded by the National Natural Science Foundation of China (61803236) and Natural Science Foundation of Shandong Province (ZR2018MA022).

Conflict of interest.

All authors declare no conflicts of interest in this paper.

References

- D. Applebaum, *Lévy processes and stochastic calculus*, 2 Eds., Cambridge: Cambridge University Press, 2009. https://doi.org/10.1017/CBO9780511809781
- 2. D. Applebaum, Lévy processes-from probability to finance and quantum groups, *Notices of the AMS*, **51** (2004), 1336–1347.
- 3. R. Servadei, E. Valdinoci, Fractional Laplacian equations with critivcal Sobolev exponent, *Rev. Mat. Complut.*, **28** (2015), 655–676. https://doi.org/10.1007/s13163-015-0170-1
- 4. H. Luo, Z. Zhang, Normalized solutions to the fractional Schrödinger equations with combined nonlinearities, *Calc. Var.*, **59** (2020), 143. https://doi.org/10.1007/s00526-020-01814-5
- 5. H. Lu, X. Zhang, Positive solution for a class of nonlocal elliptic equations, *Appl. Math. Lett.*, **88** (2019), 125–131. https://doi.org/10.1016/j.aml.2018.08.019
- Y. Liu, Bifurcation techniques for a class of boundary value problems of fractional impulsive differential equations, *J. Nonlinear Sci. Appl.*, 8 (2015), 340–353. http://doi.org/10.22436/jnsa.008.04.07
- 7. B. Yan, C. An, The sign-changing solutions for a class of nonlocal elliptic problem in an annulus, *Topol. Methods Nonlinear Anal.*, **55** (2020), 1–18. http://doi.org/10.12775/TMNA.2019.081

- 8. R. Frank, E. Lenzmann, L. Silvestre, Uniqueness of radial solutions for the fractional Laplacian, *Commun. Pure Appl. Math.*, **69** (2016), 1671–1726. https://doi.org/10.1002/cpa.21591
- 9. F. Jin, B. Yan, The sign-changing solutions for nonlinear elliptic problem with Carrier type, J. *Math. Anal. Appl.*, **487** (2020), 124002. https://doi.org/10.1016/j.jmaa.2020.124002
- M. Wang, X. Qu, H. Lu, Ground state sign-changing solutions for fractional Laplacian equations with critical nonlinearity, *AIMS Mathematics*, 6 (2021), 5028–5039. https://doi.org/10.3934/math.2021297
- H. Lu, X. Qu, J. Wang, Sign-changing and constant-sign solutions for elliptic problems involving nonlocal integro-differential operators, *SN Partial Differ. Equ. Appl.*, 1 (2020), 33. https://doi.org/10.1007/s42985-020-00028-w
- K. Teng, Multiple solutions for a class of fractional Schrödinger equations in ℝ^N, Nonlinear Anal. Real, 21 (2015), 76–86. https://doi.org/10.1016/j.nonrwa.2014.06.008
- 13. T. Bartsch, N. Soave, Multiple normalized solutions for a competing system of Schrödinger equations, *Calc. Var.*, **58** (2019), 22. https://doi.org/10.1007/s00526-018-1476-x
- 14. G. Gu, X. Tang, J. Shen, Multiple solutions for fractional Schrödinger-Poisson system with critical or supercritical nonlinearity, *Appl. Math. Lett.*, **111** (2021), 106605. https://doi.org/10.1016/j.aml.2020.106605
- 15. A. Mao, Z. Zhang, Sign-changing and multiple solutions of Kirchhoff type problems without the P.S. condition, *Nonlinear Anal. Theor.*, **70** (2009), 1275–1287. https://doi.org/10.1016/j.na.2008.02.011
- H. Ye, The sharp existence of constrained minimizers for a class of nonlinear Kirchhoff equations, *Math. Method. Appl. Sci.*, **38** (2015), 2663–2679. https://doi.org/10.1002/mma.3247
- M. Mu, H. Lu, Existence and multiplicity of positive solutions for Schrodinger-Kirchhoff-Poisson system with Singularity, J. Funct. Space., 2017 (2017), 5985962. https://doi.org/10.1155/2017/5985962
- L. Gao, C. Chen, C. Zhu, Existence of sign-changning solutions for Kirchhoff equations with critical or supercritical nonlinearity, *Appl. Math. Lett.*, **107** (2020), 106424. https://doi.org/10.1016/j.aml.2020.106424
- 19. P. L. Lions, Symétrie et compacité dans les espaces de Sobolev, *J. Funct. Anal.*, **3** (1982), 315–334. https://doi.org/10.1016/0022-1236(82)90072-6
- 20. B. Yan, D. Wang, The multiplicity of positive solutions for a class of nonlocal elliptic problem, *J. Math. Anal. Appl.*, **442** (2016), 72–102. https://doi.org/10.1016/j.jmaa.2016.04.023
- Z. Zhang, K. Perera, Sign changing solutions of Kirchhoff type problems via invariant sets of descent flow, *J. Math. Anal. Appl.*, **317** (2006), 456–463. https://doi.org/10.1016/j.jmaa.2005.06.102
- 22. Y. Wang, Y. Liu, Y. Cui, Multiple sign-changing solutions for nonlinear fractional Kirchhoff equations, *Bound. Value Probl.*, **2018** (2018), 193. https://doi.org/10.1186/s13661-018-1114-8
- 23. X. He, W. Zou, Ground state solutions for a class of fractional Kirchhoff equations with critical growth, *Sci. China Math.*, **62** (2019), 853–890. https://doi.org/10.1007/s11425-017-9399-6

- 24. L. Jeanjean, Existence of solutions with prescribed norm for semilinear elliptic equations, *Nonlinear Anal. Theor.*, **28** (1997), 1633–1659. https://doi.org/10.1016/S0362-546X(96)00021-1
- 25. G. Li, H. Ye, Existence of positive ground state solutions for the nonlinear Kirchhoff type equations in ℝ³, *J. Differ. Equations*, **257** (2014), 378–396. https://doi.org/10.1016/j.jde.2014.04.011
- 26. L. Liu, H. Chen, J. Yang, Normalized solutions to the fractional Kirchhoff equation with combined nonlinearities, 2021, arXiv:2104.06053v1.



 \bigcirc 2022 the Author(s), licensee AIMS Press. This is an open access article distributed under the terms of the Creative Commons Attribution License (http://creativecommons.org/licenses/by/4.0)