



Research article

Error bounds for generalized vector inverse quasi-variational inequality Problems with point to set mappings

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Abstract: The goal of this paper is further to study a kind of generalized vector inverse quasi-variational inequality problems and to obtain error bounds in terms of the residual gap function, the regularized gap function, and the global gap function by utilizing the relaxed monotonicity and Hausdorff Lipschitz continuity. These error bounds provide effective estimated distances between an arbitrary feasible point and the solution set of generalized vector inverse quasi-variational inequality problems.

Keywords: generalized vector inverse quasi-variational inequality problems; strong monotonicity; relaxed monotonicity; Hausdorff Lipschitz continuity; residual gap function; regularized gap function; global gap function; bi-mapping; error bounds; generalized f -projection operator

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1. Introduction

In 2014, Li et al. [1] suggested a new class of inverse mixed variational inequality in Hilbert spaces that has simple problem of traffic network equilibrium control, market equilibrium issues as applications in economics and telecommunication network problems. The concept of gap function plays an important role in the development of iterative algorithms, an evaluation of their convergence properties and useful stopping rules for iterative algorithms, *see* [2–5]. Error bounds are very important and useful because they provide a measure of the distance between a solution set and a feasible arbitrary point. Solodov [6] developed some merit functions associated with a generalized mixed variational inequality, and used those functions to achieve mixed variational error limits. Aussel et al. [7] introduced a new inverse quasi-variational inequality (IQVI), obtained local (global) error bounds for IQVI in terms of certain gap functions to demonstrate the applicability of IQVI, and

provided an example of road pricing problems, also *see* [8, 9]. Sun and Chai [10] introduced regularized gap functions for generalized vector variation inequalities (GVVI) and obtained GVVI error bounds for regularized gap functions. Wu and Huang [11] implemented generalized f -projection operators to deal with mixed variational inequality. Using the generalized f -projection operator, Li and Li [12] investigated a restricted mixed set-valued variational inequality in Hilbert spaces and proposed four merit functions for the restricted mixed set valued variational inequality and obtained error bounds through these functions.

Our goal in this paper is to present a problem of generalized vector inverse quasi-variational inequality problems. They propose three gap functions, the residual gap function, the regularized gap function, and the global gap function, and obtain error bounds for generalized vector inverse quasi-variational inequality problem using these gap functions and generalized f -projection operator under the monotonicity and Lipschitz continuity of underlying mappings.

2. Preliminaries

Throughout this article, \mathbf{R}^+ denotes the set of non-negative real numbers, $\mathbf{0}$ denotes the origins of all finite dimensional spaces, $\|\cdot\|$ and $\langle \cdot, \cdot \rangle$ denotes the norms and the inner products in finite dimensional spaces, *respectively*. Let $\Omega, \mathbb{F}, \mathbb{P} : \mathbf{R}^n \rightarrow \mathbf{R}^n$ be the set-valued mappings with nonempty closed convex values, $\mathbb{N}_i : \mathbf{R}^n \times \mathbf{R}^n \rightarrow \mathbf{R}^n$ ($i = 1, 2, \dots, m$) be the bi-mappings, $\mathbb{B} : \mathbf{R}^n \rightarrow \mathbf{R}^n$ be the single-valued mappings, and $f_i : \mathbf{R}^n \rightarrow \mathcal{R}$ ($i = 1, 2, \dots, m$) be real-valued convex functions. We put

$$f = (f_1, f_2, \dots, f_m), \quad \mathbb{N}(\cdot, \cdot) = (\mathbb{N}_1(\cdot, \cdot), \mathbb{N}_2(\cdot, \cdot), \dots, \mathbb{N}_m(\cdot, \cdot)),$$

and for any $x, w \in \mathbf{R}^n$,

$$\langle \mathbb{N}(x, x), w \rangle = (\langle \mathbb{N}_1(x, x), w \rangle, \langle \mathbb{N}_2(x, x), w \rangle, \dots, \langle \mathbb{N}_n(x, x), w \rangle).$$

In this paper, we consider the following generalized vector inverse quasi-variational inequality for finding $\bar{x} \in \Omega(\bar{x})$, $\bar{u} \in \mathbb{F}(\bar{x})$ and $\bar{v} \in \mathbb{P}(\bar{x})$ such that

$$\langle \mathbb{N}(\bar{u}, \bar{v}), y - \mathbb{B}(\bar{x}) \rangle + f(y) - f(\mathbb{B}(\bar{x})) \notin -\text{int}\mathbf{R}_+^m, \quad \forall y \in \Omega(\bar{x}), \quad (2.1)$$

and solution set is denoted by \mathcal{U} .

Special cases:

- (i) If \mathbb{P} is a zero mapping and $\mathbb{N}(\cdot, \cdot) = \mathbb{N}(\cdot)$, then (2.1) reduces to the following problem for finding $\bar{x} \in \Omega(\bar{x})$ and $\bar{u} \in \mathbb{F}(\bar{x})$ such that

$$\langle \mathbb{N}(\bar{u}), y - \mathbb{B}(\bar{x}) \rangle + f(y) - f(\mathbb{B}(\bar{x})) \notin -\text{int}\mathbf{R}_+^m, \quad \forall y \in \Omega(\bar{x}), \quad (2.2)$$

studied in [13] and solution set is denoted by \mathcal{U}_1 .

- (ii) If \mathbb{F} is single valued mapping, then (2.2) reduces to the following vector inverse mixed quasi-variational inequality for finding $\bar{x} \in \Omega(\bar{x})$ such that

$$\langle \mathbb{N}(\bar{x}), y - \mathbb{B}(\bar{x}) \rangle + f(y) - f(\mathbb{B}(\bar{x})) \notin -\text{int}\mathbf{R}_+^m, \quad \forall y \in \Omega(\bar{x}), \quad (2.3)$$

studied in [14] and solution set is denoted by \mathcal{U}_2 .

- (iii) If $C \subset \mathbf{R}^n$ is a nonempty closed and convex subset, $\mathbb{B}(x) = x$ and $\Omega(x) = C$ for all $x \in \mathbf{R}^n$, then (2.3) collapses to the following generalized vector variational inequality for finding $\bar{x} \in C$ such that

$$\langle \mathbb{N}(\bar{x}), y - x \rangle + f(y) - f(\bar{x}) \notin -\text{int}\mathbf{R}_+^m, \quad \forall y \in C, \quad (2.4)$$

which is considered in [10].

- (iv) If $f(x) = 0$ for all $x \in \mathbf{R}^n$, then (2.4) reduces to vector variational inequality for finding $\bar{x} \in C$ such that

$$\langle \mathbb{N}(\bar{x}), y - x \rangle \notin -\text{int}\mathbf{R}_+^m, \quad \forall y \in C, \quad (2.5)$$

studied in [15].

- (v) If $\mathbf{R}_+^m = \mathcal{R}_+$ then (2.5) reduces to variational inequality for finding $\bar{x} \in C$ such that

$$\langle \mathbb{N}(\bar{x}), y - x \rangle \geq 0, \quad \forall y \in C, \quad (2.6)$$

studied in [16].

Definition 2.1 [7] Let $G : \mathbf{R}^n \rightarrow \mathbf{R}^n$ and $g : \mathbf{R}^n \rightarrow \mathbf{R}^n$ be two maps.

- (i) (G, g) is said to be a strongly monotone if there exists a constant $\mu^g > 0$ such that

$$\langle G(y) - G(x), g(y) - g(x) \rangle \geq \mu^g \|y - x\|^2, \quad \forall x, y \in \mathbf{R}^n;$$

- (ii) g is said to be \mathcal{L}^g -Lipschitz continuous if there exists a constant $\mathcal{L}^g > 0$ such that

$$\|g(x) - g(y)\| \leq \mathcal{L}^g \|x - y\|, \quad \forall x, y \in \mathbf{R}^n.$$

For any fixed $\gamma > 0$, let $G : \mathbf{R}^n \times \tilde{\Omega} \rightarrow (-\infty, +\infty]$ be a function defined as follows:

$$G(\varphi, x) = \|x\|^2 - 2\langle \varphi, x \rangle + \|\varphi\|^2 + 2\gamma f(x), \quad \forall \varphi \in \mathbf{R}^n, x \in \tilde{\Omega}, \quad (2.7)$$

where $\tilde{\Omega} \subset \mathbf{R}^n$ is a nonempty closed and convex subset, and $f : \mathbf{R}^n \rightarrow \mathcal{R}$ is convex.

Definition 2.2 [11] We say that $\mathfrak{J}_{\tilde{\Omega}}^f : \mathbf{R}^n \rightarrow 2^{\tilde{\Omega}}$ is a generalized f -projection operator if

$$\mathfrak{J}_{\tilde{\Omega}}^f \varphi = \{w \in \tilde{\Omega} : G(\varphi, w) = \inf_{y \in \tilde{\Omega}} G(\varphi, y)\}, \quad \forall \varphi \in \mathbf{R}^n.$$

Remark 2.3 If $f(x) = 0$ for all $x \in \tilde{\Omega}$, then the generalized f -projection operator $\mathfrak{J}_{\tilde{\Omega}}^f$ is equivalent to the following metric projection operator:

$$P_{\tilde{\Omega}}(\varphi) = \{w \in \tilde{\Omega} : \|w - \varphi\| = \inf_{y \in \tilde{\Omega}} \|y - \varphi\|\}, \quad \forall \varphi \in \mathbf{R}^n.$$

Lemma 2.4 [1, 11] The following statements hold:

- (i) For any given $\varphi \in \mathbf{R}^n$, $\mathfrak{J}_{\tilde{\Omega}}^f \varphi$ is nonempty and single-valued;
(ii) For any given $\varphi \in \mathbf{R}^n$, $x = \mathfrak{J}_{\tilde{\Omega}}^f \varphi$ if and only if

$$\langle x - \varphi, y - x \rangle + \gamma f(y) - \gamma f(x) \geq 0, \quad \forall y \in \tilde{\Omega};$$

(iii) $\mathfrak{J}_{\Omega}^f : \mathbf{R}^n \rightarrow \Omega$ is nonexpansive, that is,

$$\|\mathfrak{J}_{\Omega}^f x - \mathfrak{J}_{\Omega}^f y\| \leq \|x - y\|, \forall x, y \in \mathbf{R}^n.$$

Lemma 2.5 [17] Let m be a positive number, $B \subset \mathbf{R}^n$ be a nonempty subset such that

$$\|d\| \leq m \text{ for all } d \in B.$$

Let $\Omega : \mathbf{R}^n \rightarrow \mathbf{R}^n$ be a set-valued mapping such that, for each $x \in \mathbf{R}^n$, $\Omega(x)$ is a closed convex set, and let $f : \mathbf{R}^n \rightarrow \mathcal{R}$ be a convex function on \mathbf{R}^n . Assume that

(i) there exists a constant $\tau > 0$ such that

$$\mathcal{D}(\Omega(x), \Omega(y)) \leq \tau \|x - y\|, x, y \in \mathbf{R}^n,$$

where $\mathcal{D}(\cdot, \cdot)$ is a Hausdorff metric defined on \mathbf{R}^n ;

(ii) $0 \in \bigcap_{w \in \mathbf{R}^n} \Omega(w)$;

(iii) f is ℓ -Lipschitz continuous on \mathbf{R}^n . Then there exists a constant $\kappa = \sqrt{6\tau(m + \gamma\ell)}$ such that

$$\|\mathfrak{J}_{\Omega(x)}^f z - \mathfrak{J}_{\Omega(y)}^f z\| \leq \kappa \|x - y\|, \forall x, y \in \mathbf{R}^n, z \in B.$$

Lemma 2.6 A function $r : \mathbf{R}^n \rightarrow R$ is said to be a gap function for a generalized vector inverse quasi-variational inequality on a set $\tilde{\mathcal{S}} \subset \mathbf{R}^n$ if it satisfies the following properties:

- (i) $r(x) \geq 0$ for any $x \in \tilde{\mathcal{S}}$;
- (ii) $r(\bar{x}) = 0$, $\bar{x} \in \tilde{\mathcal{S}}$ if and only if \bar{x} is a solution of (2.1).

Definition 2.7 Let $\mathbb{B} : \mathbf{R}^n \rightarrow \mathbf{R}^n$ be the single-valued mapping and $\mathbb{N} : \mathbf{R}^n \times \mathbf{R}^n \rightarrow \mathbf{R}^n$ be a bi-mapping.

(i) (\mathbb{N}, \mathbb{B}) is said to be a strongly monotone with respect to the first argument of \mathbb{N} and \mathbb{B} , if there exists a constant $\mu^{\mathbb{B}} > 0$ such that

$$\langle \mathbb{N}(y, \cdot) - \mathbb{N}(x, \cdot), \mathbb{B}(y) - \mathbb{B}(x) \rangle \geq \mu^{\mathbb{B}} \|y - x\|^2, \forall x, y \in \mathbf{R}^n;$$

(ii) (\mathbb{N}, \mathbb{B}) is said to be a relaxed monotone with respect to the second argument of \mathbb{N} and \mathbb{B} , if there exists a constant $\zeta^{\mathbb{B}} > 0$ such that

$$\langle \mathbb{N}(\cdot, y) - \mathbb{N}(\cdot, x), \mathbb{B}(y) - \mathbb{B}(x) \rangle \geq -\zeta^{\mathbb{B}} \|y - x\|^2, \forall x, y \in \mathbf{R}^n;$$

(iii) \mathbb{N} is said to be σ -Lipschitz continuous with respect to the first argument with constant $\sigma > 0$ and \wp -Lipschitz continuous with respect to the second argument with constant $\wp > 0$ such that

$$\|\mathbb{N}(x, \bar{x}) - \mathbb{N}(y, \bar{y})\| \leq \sigma \|x - y\| + \wp \|\bar{x} - \bar{y}\|, \forall x, \bar{x}, y, \bar{y} \in \mathbf{R}^n.$$

(iv) \mathbb{B} is said to be ℓ -Lipschitz continuous if there exists a constant $\ell > 0$ such that

$$\|\mathbb{B}(x) - \mathbb{B}(y)\| \leq \ell \|x - y\|, \forall x, y \in \mathbf{R}^n.$$

Example 2.8 The variational inequality (2.6) can be solved by transforming it into an equivalent optimization problem for the so-called merit function $r(\cdot; \tau) : X = \mathbf{R}^n \rightarrow R \cup \{+\infty\}$ defined by

$$r(x; \tau) = \sup\{\langle \mathbb{N}(\bar{x}), y - x \rangle_X - \tau \|\bar{x} - x\|_X^2 \mid x \in C\} \text{ for } \bar{x} \in C,$$

where τ is a nonnegative parameter. If X is finite dimensional, the function $r(\cdot; 0)$ is usually called the gap function for $\tau = 0$, and the function $r(\cdot; \tau)$ for $\tau > 0$ is called the regularized gap function.

Example 2.9 Assume that $\mathbb{N} : \mathbf{R}^n \rightarrow \mathbf{R}^n$ be a given mapping and C a closed convex set in \mathbf{R}^n . Let \forall and \wedge be given scalar satisfying $\forall > \wedge > 0$ then (2.6) has a D -gap function if

$$\mathbb{N}_{\forall \wedge}(x) = \mathbb{N}_{\forall}(x) - \mathbb{N}_{\wedge}(x), \forall x \in \mathbf{R}^n$$

where D stands for difference.

3. The residual gap functions

In this section, we discuss the residual gap function for generalized vector inverse quasi-variational inequality problem by using the strong monotonicity, relaxed monotonicity, Hausdorff Lipschitz continuity and prove error bounds related to the residual gap function. We define the residual gap function for (2.1) as follows:

$$r_{\gamma}(x) = \min_{1 \leq i \leq m} \{ \|\mathbb{B}(x) - \mathfrak{J}_{\Omega(x)}^{f_i} [\mathbb{B}(x) - \gamma \mathbb{N}_i(u, v)]\| \}, \quad x \in \mathbf{R}^n, \quad u \in \mathbb{F}(x), \quad v \in \mathbb{P}(x), \quad \gamma > 0. \quad (3.1)$$

Theorem 3.1 Suppose that $\mathbb{F}, \mathbb{P} : \mathbf{R}^n \rightarrow \mathbf{R}^n$ are set-valued mappings and $\mathbb{N}_i : \mathbf{R}^n \times \mathbf{R}^n \rightarrow \mathbf{R}^n$ ($i = 1, 2, \dots, m$) are the bi-mappings. Assume that $\mathbb{B} : \mathbf{R}^n \rightarrow \mathbf{R}^n$ is single-valued mapping, then for any $\gamma > 0$, $r_{\gamma}(x)$ is a gap function for (2.1) on \mathbf{R}^n .

Proof. For any $x \in \mathbf{R}^n$,

$$r_{\gamma}(x) \geq 0.$$

On the other side, if

$$r_{\gamma}(\bar{x}) = 0,$$

then there exists $0 \leq i_0 \leq m$ such that

$$\mathbb{B}(\bar{x}) = \mathfrak{J}_{\Omega(\bar{x})}^{f_{i_0}} [\mathbb{B}(\bar{x}) - \gamma \mathbb{N}_{i_0}(\bar{u}, \bar{v})], \quad \forall \bar{u} \in \mathbb{F}(\bar{x}), \quad \bar{v} \in \mathbb{P}(\bar{x}).$$

From Lemma 2.4, we have

$$\langle \mathbb{B}(\bar{x}) - [\mathbb{B}(\bar{x}) - \gamma \mathbb{N}_{i_0}(\bar{u}, \bar{v})], y - \mathbb{B}(\bar{x}) \rangle + \gamma f(y) - \gamma f(\mathbb{B}(\bar{x})) \leq 0, \quad \forall y \in \Omega(\bar{x}), \quad \bar{u} \in \mathbb{F}(\bar{x}), \quad \bar{v} \in \mathbb{P}(\bar{x})$$

and

$$\langle \mathbb{N}_{i_0}(\bar{u}, \bar{v}), y - \mathbb{B}(\bar{x}) \rangle + f(y) - f(\mathbb{B}(\bar{x})) \leq 0, \quad \forall y \in \Omega(\bar{x}), \quad \bar{u} \in \mathbb{F}(\bar{x}), \quad \bar{v} \in \mathbb{P}(\bar{x}).$$

It gives that

$$\langle \mathbb{N}(\bar{u}, \bar{v}), y - \mathbb{B}(\bar{x}) \rangle + f(y) - f(\mathbb{B}(\bar{x})) \notin -\text{int}R_+^m, \quad \forall y \in \Omega(\bar{x}), \quad \bar{u} \in \mathbb{F}(\bar{x}), \quad \bar{v} \in \mathbb{P}(\bar{x}).$$

Thus, \bar{x} is a solution of (2.1).

Conversely, if \bar{x} is a solution of (2.1), there exists $1 \leq i_0 \leq m$ such that

$$\langle \mathbb{N}_{i_0}(\bar{u}, \bar{v}), y - \mathbb{B}(\bar{x}) \rangle + f_{i_0}(y) - f_{i_0}(\mathbb{B}(\bar{x})) \geq 0, \quad \forall y \in \Omega(\bar{x}), \bar{u} \in \mathbb{F}(\bar{x}), \bar{v} \in \mathbb{P}(\bar{x}).$$

By using the Lemma 2.4, we have

$$\mathbb{B}(\bar{x}) = \mathfrak{J}_{\Omega(\bar{x})}^{f_{i_0}}[\mathbb{B}(\bar{x}) - \gamma \mathbb{N}_{i_0}(\bar{u}, \bar{v})], \quad \forall \bar{u} \in \mathbb{F}(\bar{x}), \bar{v} \in \mathbb{P}(\bar{x}).$$

This means that

$$r_\gamma(\bar{x}) = \min_{1 \leq i \leq m} \{ \|\mathbb{B}(\bar{x}) - \mathfrak{J}_{\Omega(\bar{x})}^{f_i}[\mathbb{B}(\bar{x}) - \gamma \mathbb{N}_i(\bar{u}, \bar{v})]\| \} = 0.$$

The proof is completed. \square

Next we will give the residual gap function r_γ , error bounds for (2.1).

Theorem 3.2 Let $\mathbb{F}, \mathbb{P} : \mathbf{R}^n \rightarrow \mathbf{R}^n$ be \mathcal{D} - $\vartheta^{\mathbb{F}}$ -Lipschitz continuous and \mathcal{D} - $\varrho^{\mathbb{P}}$ -Lipschitz continuous mappings, respectively. Let $\mathbb{N}_i : \mathbf{R}^n \times \mathbf{R}^n \rightarrow \mathbf{R}^n$ ($i = 1, 2, \dots, m$) be σ_i -Lipschitz continuous with respect to the first argument and \wp_i -Lipschitz continuous with respect to the second argument, and $\mathbb{B} : \mathbf{R}^n \rightarrow \mathbf{R}^n$ be ℓ -Lipschitz continuous, and $(\mathbb{N}_i, \mathbb{B})$ be strongly monotone with respect to the first argument of \mathbb{N}_i and \mathbb{B} with positive constant $\mu_i^{\mathbb{B}}$, and relaxed monotone with respect to the second argument of \mathbb{N}_i and \mathbb{B} with positive constant $\zeta_i^{\mathbb{B}}$. Let

$$\bigcap_{i=1}^m (\mathcal{U}^i) \neq \emptyset.$$

Assume that there exists $\kappa_i \in \left(0, \frac{\mu_i^{\mathbb{B}} - \zeta_i^{\mathbb{B}}}{\sigma_i \vartheta^{\mathbb{F}} + \varrho^{\mathbb{P}} \wp_i}\right)$ such that

$$\begin{aligned} \|\mathfrak{J}_{\Omega(x)}^{f_i} z - \mathfrak{J}_{\Omega(y)}^{f_i} z\| &\leq \kappa_i \|x - y\|, \quad \forall x, y \in \mathbf{R}^n, u \in \mathbb{F}(x), v \in \mathbb{P}(x), \\ z &\in \{w \mid w = \mathbb{B}(x) - \gamma \mathbb{N}_i(u, v)\}. \end{aligned} \quad (3.2)$$

Then, for any $x \in \mathbf{R}^n$ and $\mu_i^{\mathbb{B}} > \zeta_i^{\mathbb{B}} + \kappa_i(\sigma_i \vartheta^{\mathbb{F}} + \varrho_i \varrho^{\mathbb{P}})$,

$$\gamma > \frac{\kappa_i \ell}{\mu_i^{\mathbb{B}} - \zeta_i^{\mathbb{B}} - \kappa_i(\sigma_i \vartheta^{\mathbb{F}} + \varrho_i \varrho^{\mathbb{P}})},$$

$$d(x, \mathcal{U}) \leq \frac{\gamma(\sigma_i \vartheta^{\mathbb{F}} - \varrho_i \varrho^{\mathbb{P}}) + \ell}{\gamma(\mu_i^{\mathbb{B}} - \zeta_i^{\mathbb{B}} - \kappa_i(\sigma_i \vartheta^{\mathbb{F}} + \varrho_i \varrho^{\mathbb{P}})) - \kappa_i \ell} r_\gamma(x),$$

where

$$d(x, \mathcal{U}) = \inf_{\bar{x} \in \mathcal{U}} \|x - \bar{x}\|$$

denotes the distance between the point x and the solution set \mathcal{U} .

Proof. Since

$$\bigcap_{i=1}^m (\mathcal{U}^i) \neq \emptyset.$$

Let $\bar{x} \in \Omega(\bar{x})$ be the solution of (2.1) and thus for any $i \in \{1, \dots, m\}$, we have

$$\langle \mathbb{N}_i(\bar{u}, \bar{v}), y - \mathbb{B}(\bar{x}) \rangle + f_i(y) - f_i(\mathbb{B}(\bar{x})) \geq 0, \quad \forall y \in \Omega(\bar{x}), \bar{u} \in \mathbb{F}(\bar{x}), \bar{v} \in \mathbb{P}(\bar{x}). \quad (3.3)$$

From the definition of $\mathfrak{J}_{\Omega(\bar{x})}^i[\mathbb{B}(x) - \gamma \mathbb{N}_i(u, v)]$, and Lemma 2.4, we have

$$\begin{aligned} & \langle \mathfrak{J}_{\Omega(\bar{x})}^i[\mathbb{B}(x) - \gamma \mathbb{N}_i(u, v)] - (\mathbb{B}(x) - \gamma \mathbb{N}_i(u, v)), y - \mathfrak{J}_{\Omega(\bar{x})}^i[\mathbb{B}(x) - \gamma \mathbb{N}_i(u, v)] \rangle \\ & + \gamma f_i(y) - \gamma f_i(\mathfrak{J}_{\Omega(\bar{x})}^i[\mathbb{B}(x) - \gamma \mathbb{N}_i(u, v)]) \geq 0, \quad \forall y \in \Omega(\bar{x}), u \in \mathbb{F}(x), v \in \mathbb{P}(x). \end{aligned} \quad (3.4)$$

Since

$$\bar{x} \in \bigcap_{i=1}^m (\mathcal{U}^i), \quad \text{and} \quad \mathbb{B}(\bar{x}) \in \Omega(\bar{x}).$$

Replacing y by $\mathbb{B}(\bar{x})$ in (3.4), we get

$$\begin{aligned} & \langle \mathfrak{J}_{\Omega(\bar{x})}^i[\mathbb{B}(x) - \gamma \mathbb{N}_i(u, v)] - (\mathbb{B}(x) - \gamma \mathbb{N}_i(u, v)), \mathbb{B}(\bar{x}) - \mathfrak{J}_{\Omega(\bar{x})}^i[\mathbb{B}(x) - \gamma \mathbb{N}_i(u, v)] \rangle \\ & + \gamma f_i(\mathbb{B}(\bar{x})) - \gamma f_i(\mathfrak{J}_{\Omega(\bar{x})}^i[\mathbb{B}(x) - \gamma \mathbb{N}_i(u, v)]) \geq 0, \quad \forall u \in \mathbb{F}(x), v \in \mathbb{P}(x). \end{aligned} \quad (3.5)$$

Since

$$\mathfrak{J}_{\Omega(\bar{x})}^i[\mathbb{B}(x) - \gamma \mathbb{N}_i(u, v)] \in \Omega(\bar{x}),$$

from (3.3), it follows that

$$\langle \gamma \mathbb{N}_i(\bar{u}, \bar{v}), \mathfrak{J}_{\Omega(\bar{x})}^i[\mathbb{B}(x) - \gamma \mathbb{N}_i(u, v)] - \mathbb{B}(\bar{x}) \rangle + \gamma f_i(\mathfrak{J}_{\Omega(\bar{x})}^i[\mathbb{B}(x) - \gamma \mathbb{N}_i(u, v)]) - \gamma f_i(\mathbb{B}(\bar{x})) \geq 0. \quad (3.6)$$

Utilizing (3.5) and (3.6), we have

$$\langle \gamma \mathbb{N}_i(\bar{u}, \bar{v}) - \gamma \mathbb{N}_i(u, v) - \mathfrak{J}_{\Omega(\bar{x})}^i[\mathbb{B}(x) - \gamma \mathbb{N}_i(u, v)] + \mathbb{B}(x), \mathfrak{J}_{\Omega(\bar{x})}^i[\mathbb{B}(x) - \gamma \mathbb{N}_i(u, v)] - \mathbb{B}(\bar{x}) \rangle \geq 0,$$

which implies that

$$\begin{aligned} & \langle \gamma \mathbb{N}_i(\bar{u}, \bar{v}) - \gamma \mathbb{N}_i(u, v), \mathfrak{J}_{\Omega(\bar{x})}^i[\mathbb{B}(x) - \gamma \mathbb{N}_i(u, v)] - \mathbb{B}(x) \rangle - \langle \gamma \mathbb{N}_i(\bar{u}, \bar{v}) - \gamma \mathbb{N}_i(u, v), \mathbb{B}(\bar{x}) - \mathbb{B}(x) \rangle \\ & + \langle \mathbb{B}(x) - \mathfrak{J}_{\Omega(\bar{x})}^i[\mathbb{B}(x) - \gamma \mathbb{N}_i(u, v)], \mathfrak{J}_{\Omega(\bar{x})}^i[\mathbb{B}(x) - \gamma \mathbb{N}_i(u, v)] - \mathbb{B}(x) \rangle \\ & + \langle \mathbb{B}(x) - \mathfrak{J}_{\Omega(\bar{x})}^i[\mathbb{B}(x) - \gamma \mathbb{N}_i(u, v)], \mathbb{B}(x) - \mathbb{B}(\bar{x}) \rangle \geq 0. \end{aligned}$$

Since \mathbb{F} is \mathcal{D} - $\theta^{\mathbb{F}}$ -Lipschitz continuous, \mathbb{P} is \mathcal{D} - $\varrho^{\mathbb{P}}$ -Lipschitz continuous and \mathbb{N}_i is σ_i -Lipschitz continuous with respect to the first argument and φ_i -Lipschitz continuous with respect to the second argument, we have

$$\begin{aligned}
\|\bar{u} - u\| &\leq \mathcal{D}(\mathbb{F}(\bar{x}), \mathbb{F}(x)) \leq \vartheta^{\mathbb{F}} \|\bar{x} - x\|; \\
\|\bar{v} - v\| &\leq \mathcal{D}(\mathbb{P}(\bar{x}), \mathbb{P}(x)) \leq \varrho^{\mathbb{P}} \|\bar{x} - x\|; \\
\|\mathbb{N}_i(\bar{u}, \bar{v}) - \mathbb{N}_i(u, v)\| &\leq \sigma_i \|\bar{u} - u\| + \wp_i \|\bar{v} - v\|.
\end{aligned} \tag{3.7}$$

Again, for $i = 1, 2, \dots, m$, $(\mathbb{N}_i, \mathbb{B})$ are strongly monotone with respect to the first argument of \mathbb{N}_i and \mathbb{B} with a positive constant $\mu_i^{\mathbb{B}}$, and relaxed monotone with respect to the second argument of \mathbb{N}_i and \mathbb{B} with a positive constant $\zeta_i^{\mathbb{B}}$, we have

$$\begin{aligned}
&\langle \gamma \mathbb{N}_i(\bar{u}, \bar{v}) - \gamma \mathbb{N}_i(u, v), \mathfrak{J}_{\Omega(\bar{x})}^{f_i} [\mathbb{B}(x) - \gamma \mathbb{N}_i(u, v)] - \mathbb{B}(x) \rangle - \|\mathbb{B}(x) - \mathfrak{J}_{\Omega(\bar{x})}^{f_i} [\mathbb{B}(x) - \gamma \mathbb{N}_i(u, v)]\|^2 \\
&+ \langle \mathbb{B}(x) - \mathfrak{J}_{\Omega(\bar{x})}^{f_i} [\mathbb{B}(x) - \gamma \mathbb{N}_i(u, v)], \mathbb{B}(x) - \mathbb{B}(\bar{x}) \rangle \geq \gamma \mu_i^{\mathbb{B}} \|x - \bar{x}\|^2 - \gamma \zeta_i^{\mathbb{B}} \|x - \bar{x}\|^2.
\end{aligned}$$

By adding $\mathfrak{J}_{\Omega(x)}^{f_i} [\mathbb{B}(x) - \gamma \mathbb{N}_i(u, v)]$ and using the Cauchy-Schwarz inequality along with the triangular inequality, we have

$$\begin{aligned}
&\|\gamma \mathbb{N}_i(\bar{u}, \bar{v}) - \gamma \mathbb{N}_i(u, v)\| \{ \|\mathfrak{J}_{\Omega(\bar{x})}^{f_i} [\mathbb{B}(x) - \gamma \mathbb{N}_i(u, v)] - \mathfrak{J}_{\Omega(x)}^{f_i} [\mathbb{B}(x) - \gamma \mathbb{N}_i(u, v)]\| \\
&+ \|\mathfrak{J}_{\Omega(x)}^{f_i} [\mathbb{B}(x) - \gamma \mathbb{N}_i(u, v)] - \mathbb{B}(x)\| \} \\
&+ \|\mathbb{B}(x) - \mathbb{B}(\bar{x})\| \{ \|\mathbb{B}(x) - \mathfrak{J}_{\Omega(x)}^{f_i} [\mathbb{B}(x) - \gamma \mathbb{N}_i(u, v)]\| + \|\mathfrak{J}_{\Omega(x)}^{f_i} [\mathbb{B}(x) - \gamma \mathbb{N}_i(u, v)] \\
&- \mathfrak{J}_{\Omega(\bar{x})}^{f_i} [\mathbb{B}(x) - \gamma \mathbb{N}_i(u, v)]\| \} \geq \gamma \mu_i^{\mathbb{B}} \|x - \bar{x}\|^2 - \gamma \zeta_i^{\mathbb{B}} \|x - \bar{x}\|^2.
\end{aligned}$$

Using the (3.7) and condition (3.2), we have

$$\begin{aligned}
&(\sigma_i \vartheta^{\mathbb{F}} + \wp_i \varrho^{\mathbb{P}}) \gamma \|\bar{x} - x\| \{ \kappa_i \|\bar{x} - x\| + \|\mathfrak{J}_{\Omega(x)}^{f_i} [\mathbb{B}(x) - \gamma \mathbb{N}_i(u, v)] - \mathbb{B}(x)\| \} \\
&+ \ell \|x - \bar{x}\| \{ \|\mathbb{B}(x) - \mathfrak{J}_{\Omega(x)}^{f_i} [\mathbb{B}(x) - \gamma \mathbb{N}_i(u, v)]\| + \kappa_i \|x - \bar{x}\| \} \geq \gamma (\mu_i^{\mathbb{B}} - \zeta_i^{\mathbb{B}}) \|x - \bar{x}\|^2.
\end{aligned}$$

Hence, for any $x \in \mathbf{R}^n$ and $i \in \{1, 2, \dots, m\}$, $\mu_i^{\mathbb{B}} > \zeta_i^{\mathbb{B}} + \kappa_i (\sigma_i \vartheta^{\mathbb{F}} + \wp_i \varrho^{\mathbb{P}})$,

$$\gamma > \frac{\kappa_i \ell}{\mu_i^{\mathbb{B}} - \zeta_i^{\mathbb{B}} - \kappa_i (\sigma_i \vartheta^{\mathbb{F}} + \wp_i \varrho^{\mathbb{P}})},$$

we have

$$\|x - \bar{x}\| \leq \frac{\gamma (\sigma_i \vartheta^{\mathbb{F}} + \wp_i \varrho^{\mathbb{P}}) + \ell}{\gamma (\mu_i^{\mathbb{B}} - \zeta_i^{\mathbb{B}} - \kappa_i (\sigma_i \vartheta^{\mathbb{F}} + \wp_i \varrho^{\mathbb{P}})) - \kappa_i \ell} \|\mathbb{B}(x) - \mathfrak{J}_{\Omega(x)}^{f_i} [\mathbb{B}(x) - \gamma \mathbb{N}_i(u, v)]\|, \quad \forall u \in \mathbb{F}(x), v \in \mathbb{P}(x).$$

This implies

$$\|x - \bar{x}\| \leq \frac{\gamma (\sigma_i \vartheta^{\mathbb{F}} + \wp_i \varrho^{\mathbb{P}}) + \ell}{\gamma (\mu_i^{\mathbb{B}} - \zeta_i^{\mathbb{B}} - \kappa_i (\sigma_i \vartheta^{\mathbb{F}} + \wp_i \varrho^{\mathbb{P}})) - \kappa_i \ell} \min_{1 \leq i \leq m} \{ \|\mathbb{B}(x) - \mathfrak{J}_{\Omega(x)}^{f_i} [\mathbb{B}(x) - \gamma \mathbb{N}_i(u, v)]\| \}$$

which means that

$$d(x, \mathbb{U}) \leq \|x - \bar{x}\| \leq \frac{\gamma (\sigma_i \vartheta^{\mathbb{F}} + \wp_i \varrho^{\mathbb{P}}) + \ell}{\gamma (\mu_i^{\mathbb{B}} - \zeta_i^{\mathbb{B}} - \kappa_i (\sigma_i \vartheta^{\mathbb{F}} + \wp_i \varrho^{\mathbb{P}})) - \kappa_i \ell} r_\gamma(x).$$

The proof is completed. \square

4. The regularized gap function

The regularized gap function for (2.1) is defined for all $x \in \mathbf{R}^n$ as follows:

$$\phi_\gamma(x) = \min_{1 \leq i \leq m} \sup_{\substack{y \in \Omega(x), \\ u \in \mathbb{F}(x), v \in \mathbb{P}(x)}} \{ \langle \mathbb{N}_i(u, v), \mathbb{B}(x) - y \rangle + f_i(\mathbb{B}(x)) - f_i(y) - \frac{1}{2\gamma} \|\mathbb{B}(x) - y\|^2 \}$$

where $\gamma > 0$ is a parameter.

Lemma 4.1 We have

$$\phi_\gamma(x) = \min_{1 \leq i \leq m} \{ \langle \mathbb{N}_i(u, v), \mathbf{R}_\gamma^i(x) \rangle + f_i(\mathbb{B}(x)) - f_i(\mathbb{B}(x) - \mathbf{R}_\gamma^i(x)) - \frac{1}{2\gamma} \|\mathbf{R}_\gamma^i(x)\|^2 \}, \quad (4.1)$$

where

$$\mathbf{R}_\gamma^i(x) = \mathbb{B}(x) - \mathfrak{J}_{\Omega(x)}^{f_i}[\mathbb{B}(x) - \gamma \mathbb{N}_i(u, v)], \quad \forall x \in \mathbf{R}^n, u \in \mathbb{F}(x), v \in \mathbb{P}(x)$$

and if

$$x \in \mathbb{B}^{-1}(\Omega)$$

and

$$\mathbb{B}^{-1}(\Omega) = \{ \xi \in \mathbf{R}^n \mid \mathbb{B}(\xi) \in \Omega(\xi) \},$$

then

$$\phi_\gamma(x) \geq \frac{1}{2\gamma} r_\gamma(x)^2. \quad (4.2)$$

Proof. For given $x \in \mathbf{R}^n$, $u \in \mathbb{F}(x)$, $v \in \mathbb{P}(x)$ and $i \in \{1, 2, \dots, m\}$, set

$$\psi_i(x, y) = \langle \mathbb{N}_i(u, v), \mathbb{B}(x) - y \rangle + f_i(\mathbb{B}(x)) - f_i(y) - \frac{1}{2\gamma} \|\mathbb{B}(x) - y\|^2, \quad y \in \mathbf{R}^n.$$

Consider the following problem:

$$g_i(x) = \max_{y \in \Omega(x)} \psi_i(x, y).$$

Since $\psi_i(x, \cdot)$ is a strongly concave function and $\Omega(x)$ is nonempty closed convex, the above optimization problem has a unique solution $z \in \Omega(x)$. Evoking the condition of optimality at z , we get

$$0 \in \mathbb{N}_i(u, v) + \partial f_i(z) + \frac{1}{\gamma}(z - \mathbb{B}(x)) + \mathcal{N}_{\Omega(x)}(z),$$

where $\mathcal{N}_{\Omega(x)}(z)$ is the normal cone at z to $\Omega(x)$ and $\partial f_i(z)$ denotes the subdifferential of f_i at z . Therefore,

$$\langle z - (\mathbb{B}(x) - \gamma \mathbb{N}_i(u, v)), y - z \rangle + \gamma f_i(y) - \gamma f_i(z) \geq 0, \quad \forall y \in \Omega(x), u \in \mathbb{F}(x), v \in \mathbb{P}(x)$$

and so

$$z = \mathfrak{J}_{\Omega(x)}^{f_i}[\mathbb{B}(x) - \gamma \mathbb{N}_i(u, v)], \quad \forall u \in \mathbb{F}(x), v \in \mathbb{P}(x).$$

Hence $g_i(x)$ can be rewritten as

$$g_i(x) = \langle \mathbb{N}_i(u, v), \mathbb{B}(x) - \mathfrak{J}_{\Omega(x)}^{f_i}[\mathbb{B}(x) - \gamma \mathbb{N}_i(u, v)] \rangle + f_i(\mathbb{B}(x)) - f_i(\mathfrak{J}_{\Omega(x)}^{f_i}[\mathbb{B}(x) - \gamma \mathbb{N}_i(u, v)]) \\ - \frac{1}{2\gamma} \|\mathbb{B}(x) - \mathfrak{J}_{\Omega(x)}^{f_i}[\mathbb{B}(x) - \gamma \mathbb{N}_i(u, v)]\|^2, \quad \forall u \in \mathbb{F}(x), v \in \mathbb{P}(x).$$

Letting

$$\mathbf{R}_\gamma^i(x) = \mathbb{B}(x) - \mathfrak{J}_{\Omega(x)}^{f_i}[\mathbb{B}(x) - \gamma \mathbb{N}_i(u, v)], \quad \forall u \in \mathbb{F}(x), v \in \mathbb{P}(x),$$

we get

$$g_i(x) = \langle \mathbb{N}_i(u, v), \mathbf{R}_\gamma^i(x) \rangle + f_i(\mathbb{B}(x)) - f_i(\mathbb{B}(x) - \mathbf{R}_\gamma^i(x)) \\ - \frac{1}{2\gamma} \|\mathbf{R}_\gamma^i(x)\|^2, \quad \forall u \in \mathbb{F}(x), v \in \mathbb{P}(x), \quad (4.3)$$

$$(4.4)$$

and so

$$\phi_\gamma(x) = \min_{1 \leq i \leq m} \{ \langle \mathbb{N}_i(u, v), \mathbf{R}_\gamma^i(x) \rangle + f_i(\mathbb{B}(x)) - f_i(\mathbb{B}(x) - \mathbf{R}_\gamma^i(x)) - \frac{1}{2\gamma} \|\mathbf{R}_\gamma^i(x)\|^2 \}.$$

From the definition of projection $\mathfrak{J}_{\Omega(x)}^{f_i}[\mathbb{B}(x) - \gamma \mathbb{N}_i(u, v)]$, we have

$$\langle \mathfrak{J}_{\Omega(x)}^{f_i}[\mathbb{B}(x) - \gamma \mathbb{N}_i(u, v)] - \mathbb{B}(x) + \gamma \mathbb{N}_i(u, v), y - \mathfrak{J}_{\Omega(x)}^{f_i}[\mathbb{B}(x) - \gamma \mathbb{N}_i(u, v)] \rangle \\ + \gamma f_i(y) - \gamma f_i(\mathfrak{J}_{\Omega(x)}^{f_i}[\mathbb{B}(x) - \gamma \mathbb{N}_i(u, v)]) \geq 0, \quad \forall u \in \mathbb{F}(x), v \in \mathbb{P}(x). \quad (4.5)$$

For any $x \in \mathbb{B}^{-1}(\Omega)$, we have

$$\mathbb{B}(x) \in \Omega(x).$$

Therefore, putting $y = \mathbb{B}(x)$ in (4.5), we get

$$\langle \gamma \mathbb{N}_i(u, v) - \mathbf{R}_\gamma^i(x), \mathbf{R}_\gamma^i(x) \rangle + \gamma f_i(\mathbb{B}(x)) - \gamma f_i(\mathbb{B}(x) - \mathbf{R}_\gamma^i(x)) \geq 0, \quad \forall u \in \mathbb{F}(x), v \in \mathbb{P}(x),$$

that is,

$$\langle \mathbb{N}_i(u, v), \mathbf{R}_\gamma^i(x) \rangle + f_i(\mathbb{B}(x)) - f_i(\mathbb{B}(x) - \mathbf{R}_\gamma^i(x)) \geq \frac{1}{\gamma} \langle \mathbf{R}_\gamma^i(x), \mathbf{R}_\gamma^i(x) \rangle \\ = \frac{1}{\gamma} \|\mathbf{R}_\gamma^i(x)\|^2. \quad (4.6)$$

From the definition of $r_\gamma(x)$ and (4.1), we get

$$\phi_\gamma(x) \geq \frac{1}{2\gamma} r_\gamma(x)^2.$$

The proof is completed. \square

Theorem 4.2 For $\gamma > 0$, ϕ_γ is a gap function for (2.1) on the set

$$\mathbb{B}^{-1}(\Omega) = \{ \xi \in \mathbf{R}^n \mid \mathbb{B}(\xi) \in \Omega(\xi) \}.$$

Proof. From the definition of ϕ_γ , we have

$$\phi_\gamma(x) \geq \min_{1 \leq i \leq m} \{ \langle \mathbb{N}_i(u, v), \mathbb{B}(x) - y \rangle + f_i(\mathbb{B}(x)) - f_i(y) - \frac{1}{2\gamma} \|\mathbb{B}(x) - y\|^2 \}, \quad (4.7)$$

for all $y \in \Omega(x), u \in \mathbb{F}(x), v \in \mathbb{P}(x)$.

Therefore, for any $x \in \mathbb{B}^{-1}(\Omega)$, putting $y = \mathbb{B}(x)$ in (4.7), we have

$$\phi_\gamma(x) \geq 0.$$

Suppose that $\bar{x} \in \mathbb{B}^{-1}(\xi)$ with $\phi_\gamma(\bar{x}) = 0$. From (4.2), it follows that

$$r_\gamma(\bar{x}) = 0,$$

which implies that \bar{x} is the solution of (2.1).

Conversely, if \bar{x} is a solution of (2.1), there exists $1 \leq i_0 \leq m$ such that

$$\langle \mathbb{N}_{i_0}(\bar{u}, \bar{v}), \mathbb{B}(\bar{x}) - y \rangle + f_{i_0}(\mathbb{B}(\bar{x})) - f_{i_0}(y) \leq 0, \quad \forall y \in \Omega(\bar{x}), \bar{u} \in \mathbb{F}(\bar{x}), \bar{v} \in \mathbb{P}(\bar{x}),$$

which means that

$$\min_{1 \leq i \leq m} \left\{ \sup_{\substack{y \in \Omega(\bar{x}), \\ \bar{u} \in \mathbb{F}(\bar{x}), \bar{v} \in \mathbb{P}(\bar{x})}} \{ \langle \mathbb{N}_i(\bar{u}, \bar{v}), \mathbb{B}(\bar{x}) - y \rangle + f_i(\mathbb{B}(\bar{x})) - f_i(y) - \frac{1}{2\gamma} \|\mathbb{B}(\bar{x}) - y\|^2 \} \right\} \leq 0.$$

Thus,

$$\phi_\gamma(\bar{x}) \leq 0.$$

The preceding claim leads to

$$\phi_\gamma(\bar{x}) \geq 0$$

and it implies that

$$\phi_\gamma(\bar{x}) = 0.$$

The proof is completed. \square

Since ϕ_γ can act as a gap function for (2.1), according to Theorem 4.2, investigating the error bound properties that can be obtained with ϕ_γ is interesting. The following corollary is obtained directly by Theorem 3.2 and (3.5).

Corollary 4.3 Let $\mathbb{F}, \mathbb{P} : \mathbf{R}^n \rightarrow \mathbf{R}^n$ be \mathcal{D} - $\vartheta^{\mathbb{F}}$ -Lipschitz continuous and \mathcal{D} - $\varrho^{\mathbb{P}}$ -Lipschitz continuous mappings, respectively. Let $\mathbb{N}_i : \mathbf{R}^n \times \mathbf{R}^n \rightarrow \mathbf{R}^n$ ($i = 1, 2, \dots, m$) be σ_i -Lipschitz continuous with respect to the first argument and φ_i -Lipschitz continuous with respect to the second argument, $\mathbb{B} : \mathbf{R}^n \rightarrow \mathbf{R}^n$ be ℓ -Lipschitz continuous, and $(\mathbb{N}_i, \mathbb{B})$ be strongly monotone with respect to the first argument of \mathbb{N} and \mathbb{B} with respect to the constant $\mu_i^{\mathbb{B}} > 0$, and relaxed monotone with respect to the second argument of \mathbb{N} and \mathbb{B} with respect to the constant $\zeta_i^{\mathbb{B}} > 0$. Let

$$\bigcap_{i=1}^m (\mathcal{U}^i) \neq \emptyset.$$

Assume that there exists $\kappa_i \in \left(0, \frac{\mu_i^{\mathbb{B}} - \zeta_i^{\mathbb{B}}}{\vartheta^{\mathbb{F}}\sigma_i + \wp_i\varrho^{\mathbb{P}}}\right)$ such that

$$\|\mathfrak{J}_{\Omega(x)}^{f_i} z - \mathfrak{J}_{\Omega(y)}^{f_i} z\| \leq \kappa_i \|x - y\|, \quad \forall x, y \in \mathbf{R}^n, u \in \mathbb{F}(x), v \in \mathbb{P}(x) \quad \forall z \in \{w \mid w = \mathbb{B}(x) - \gamma \mathbb{N}_i(u, v)\}.$$

Then, for any $x \in \mathbb{B}^{-1}(\Omega)$ and any

$$\gamma > \frac{\kappa_i \ell}{\mu_i^{\mathbb{B}} - \zeta_i^{\mathbb{B}} - \kappa_i(\vartheta^{\mathbb{F}}\sigma_i + \wp_i\varrho^{\mathbb{P}})},$$

$$d(x, \mathbb{U}) \leq \frac{\gamma(\vartheta^{\mathbb{F}}\sigma_i + \wp_i\varrho^{\mathbb{P}}) + \ell}{\gamma(\mu_i^{\mathbb{B}} - \zeta_i^{\mathbb{B}} - \kappa_i(\vartheta^{\mathbb{F}}\sigma_i + \wp_i\varrho^{\mathbb{P}})) - \kappa_i \ell} \sqrt{2\gamma\phi_\gamma(x)}.$$

5. The global gap functions

The regularized gap function ϕ_γ does not provide global error bounds for (2.1) on \mathbf{R}^n . In this section, we first discuss the D -gap function, see [6] for (2.1), which gives \mathbf{R}^n the global error bound for (2.1). For (2.1) with $\lambda > \gamma > 0$, the D -gap function is defined as follows:

$$G_{\lambda\gamma}(x) = \min_{1 \leq i \leq m} \left\{ \sup_{\substack{y \in \Omega(x), \\ u \in \mathbb{F}(x), v \in \mathbb{P}(x)}} \{ \langle \mathbb{N}_i(u, v), \mathbb{B}(x) - y \rangle + f_i(\mathbb{B}(x)) - f_i(y) - \frac{1}{2\lambda} \|\mathbb{B}(x) - y\|^2 \} \right. \\ \left. - \sup_{\substack{y \in \Omega(x), \\ u \in \mathbb{F}(x), v \in \mathbb{P}(x)}} \{ \langle \mathbb{N}_i(u, v), \mathbb{B}(x) - y \rangle + f_i(\mathbb{B}(x)) - f_i(y) - \frac{1}{2\gamma} \|\mathbb{B}(x) - y\|^2 \} \right\}.$$

From (4.1), we know $G_{\lambda\gamma}$ can be rewritten as

$$G_{\lambda\gamma}(x) = \min_{1 \leq i \leq m} \left\{ \langle \mathbb{N}_i(u, v), \mathbf{R}_\lambda^i(x) \rangle + f_i(\mathbb{B}(x)) - f_i(\mathbb{B}(x) - \mathbf{R}_\lambda^i(x)) - \frac{1}{2\lambda} \|\mathbf{R}_\lambda^i(x)\|^2 \right. \\ \left. - (\langle \mathbb{N}_i(u, v), \mathbf{R}_\gamma^i(x) \rangle + f_i(\mathbb{B}(x)) - f_i(\mathbb{B}(x) - \mathbf{R}_\gamma^i(x)) - \frac{1}{2\gamma} \|\mathbf{R}_\gamma^i(x)\|^2) \right\},$$

where

$$\mathbf{R}_\lambda^i(x) = \mathbb{B}(x) - \mathfrak{J}_{\Omega(x)}^{f_i} [\mathbb{B}(x) - \lambda \mathbb{N}_i(u, v)]$$

and

$$\mathbf{R}_\gamma^i(x) = \mathbb{B}(x) - \mathfrak{J}_{\Omega(x)}^{f_i} [\mathbb{B}(x) - \gamma \mathbb{N}_i(u, v)], \quad \forall x \in \mathbf{R}^n, u \in \mathbb{F}(x), v \in \mathbb{P}(x).$$

Theorem 5.1 For any $x \in \mathbf{R}^n$, $\lambda > \gamma > 0$, we have

$$\frac{1}{2} \left(\frac{1}{\gamma} - \frac{1}{\lambda} \right) r_\gamma^2(x) \leq G_{\lambda\gamma}(x) \leq \frac{1}{2} \left(\frac{1}{\gamma} - \frac{1}{\lambda} \right) r_\lambda^2(x). \quad (5.1)$$

Proof. From the definition of $G_{\lambda\gamma}(x)$, it follows that

$$G_{\lambda\gamma}(x) = \min_{1 \leq i \leq m} \left\{ \langle \mathbb{N}_i(u, v), \mathbf{R}_\lambda^i(x) - \mathbf{R}_\gamma^i(x) \rangle - f_i(\mathbb{B}(x) - \mathbf{R}_\lambda^i(x)) \right. \\ \left. - \frac{1}{2\lambda} \|\mathbf{R}_\lambda^i(x)\|^2 + f_i(\mathbb{B}(x) - \mathbf{R}_\gamma^i(x)) + \frac{1}{2\gamma} \|\mathbf{R}_\gamma^i(x)\|^2 \right\}, \quad \forall u \in \mathbb{F}(x), v \in \mathbb{P}(x).$$

For any given $i \in \{1, 2, \dots, m\}$, we set

$$\begin{aligned} g_{\lambda\vee}^i(x) &= \langle \mathbb{N}_i(u, v), \mathbf{R}_\lambda^i(x) - \mathbf{R}_\vee^i(x) \rangle - f_i(\mathbb{B}(x) - \mathbf{R}_\lambda^i(x)) - \frac{1}{2\lambda} \|\mathbf{R}_\lambda^i(x)\|^2 \\ &\quad + f_i(\mathbb{B}(x) - \mathbf{R}_\vee^i(x)) + \frac{1}{2\vee} \|\mathbf{R}_\vee^i(x)\|^2, \quad \forall u \in \mathbb{F}(x), v \in \mathbb{P}(x). \end{aligned} \quad (5.2)$$

From $\mathfrak{J}_{\Omega(x)}^{f_i}[\mathbb{B}(x) - \vee\mathbb{N}_i(u, v)] \in \Omega(x)$, by Lemma 2.4, we know

$$\begin{aligned} &\langle \mathfrak{J}_{\Omega(x)}^{f_i}[\mathbb{B}(x) - \lambda\mathbb{N}_i(u, v)] - (\mathbb{B}(x) - \lambda\mathbb{N}_i(u, v)), \mathfrak{J}_{\Omega(x)}^{f_i}[\mathbb{B}(x) - \vee\mathbb{N}_i(u, v)] - \mathfrak{J}_{\Omega(x)}^{f_i}[\mathbb{B}(x) - \lambda\mathbb{N}_i(u, v)] \rangle \\ &\quad + \lambda f_i(\mathfrak{J}_{\Omega(x)}^{f_i}[\mathbb{B}(x) - \vee\mathbb{N}_i(u, v)]) - \lambda f_i(\mathfrak{J}_{\Omega(x)}^{f_i}[\mathbb{B}(x) - \lambda\mathbb{N}_i(u, v)]) \geq 0, \quad \forall u \in \mathbb{F}(x), v \in \mathbb{P}(x) \end{aligned}$$

which means that

$$\langle \lambda\mathbb{N}_i(u, v) - \mathbf{R}_\lambda^i(x), \mathbf{R}_\lambda^i(x) - \mathbf{R}_\vee^i(x) \rangle + \lambda f_i(\mathbb{B}(x) - \mathbf{R}_\vee^i(x)) - \lambda f_i(\mathbb{B}(x) - \mathbf{R}_\lambda^i(x)) \geq 0. \quad (5.3)$$

Combining (5.2) and (5.3), we get

$$\begin{aligned} g_{\lambda\vee}^i(x) &\geq \frac{1}{\lambda} \langle \mathbf{R}_\lambda^i(x), \mathbf{R}_\lambda^i(x) - \mathbf{R}_\vee^i(x) \rangle - \frac{1}{2\lambda} \|\mathbf{R}_\lambda^i(x)\|^2 + \frac{1}{2\vee} \|\mathbf{R}_\vee^i(x)\|^2 \\ &= \frac{1}{2\lambda} \|\mathbf{R}_\lambda^i(x) - \mathbf{R}_\vee^i(x)\|^2 + \frac{1}{2} \left(\frac{1}{\vee} - \frac{1}{\lambda} \right) \|\mathbf{R}_\vee^i(x)\|^2. \end{aligned} \quad (5.4)$$

Since

$$\mathfrak{J}_{\Omega(x)}^{f_i}[\mathbb{B}(x) - \lambda\mathbb{N}_i(u, v)] \in \Omega(x),$$

from Lemma 2.4, we have

$$\begin{aligned} &\langle \mathfrak{J}_{\Omega(x)}^{f_i}[\mathbb{B}(x) - \vee\mathbb{N}_i(u, v)] - (\mathbb{B}(x) - \vee\mathbb{N}_i(u, v)), \mathfrak{J}_{\Omega(x)}^{f_i}[\mathbb{B}(x) - \lambda\mathbb{N}_i(u, v)] - \mathfrak{J}_{\Omega(x)}^{f_i}[\mathbb{B}(x) - \vee\mathbb{N}_i(u, v)] \rangle \\ &\quad + \vee f_i(\mathfrak{J}_{\Omega(x)}^{f_i}[\mathbb{B}(x) - \lambda\mathbb{N}_i(u, v)]) - \vee f_i(\mathfrak{J}_{\Omega(x)}^{f_i}[\mathbb{B}(x) - \vee\mathbb{N}_i(u, v)]) \geq 0, \quad \forall u \in \mathbb{F}(x), v \in \mathbb{P}(x). \end{aligned}$$

Hence

$$\begin{aligned} &\langle \vee\mathbb{N}_i(u, v) - \mathbf{R}_\vee^i(x), \mathbf{R}_\vee^i(x) - \mathbf{R}_\lambda^i(x) \rangle + \vee f_i(\mathbb{B}(x) - \mathbf{R}_\lambda^i(x)) \\ &\quad - \vee f_i(\mathbb{B}(x) - \mathbf{R}_\vee^i(x)) \geq 0, \quad \forall u \in \mathbb{F}(x), v \in \mathbb{P}(x) \end{aligned}$$

and so

$$\begin{aligned} \frac{1}{\vee} \langle \mathbf{R}_\vee^i(x), \mathbf{R}_\lambda^i(x) - \mathbf{R}_\vee^i(x) \rangle &\geq \langle \mathbb{N}_i(u, v), \mathbf{R}_\lambda^i(x) - \mathbf{R}_\vee^i(x) \rangle \\ &\quad - f_i(\mathbb{B}(x) - \mathbf{R}_\lambda^i(x)) + f_i(\mathbb{B}(x) - \mathbf{R}_\vee^i(x)). \end{aligned}$$

It will require and (5.3),

$$\begin{aligned} g_{\lambda\vee}^i(x) &\leq \frac{1}{\vee} \langle \mathbf{R}_\vee^i(x), \mathbf{R}_\lambda^i(x) - \mathbf{R}_\vee^i(x) \rangle - \frac{1}{2\lambda} \|\mathbf{R}_\lambda^i(x)\|^2 + \frac{1}{2\vee} \|\mathbf{R}_\vee^i(x)\|^2 \\ &= -\frac{1}{2\vee} \|\mathbf{R}_\lambda^i(x) - \mathbf{R}_\vee^i(x)\|^2 + \frac{1}{2} \left(\frac{1}{\vee} - \frac{1}{\lambda} \right) \|\mathbf{R}_\lambda^i(x)\|^2. \end{aligned} \quad (5.5)$$

From (5.4) and (5.5), for any $i \in \{1, 2, \dots, m\}$, we get

$$\frac{1}{2} \left(\frac{1}{\gamma} - \frac{1}{\lambda} \right) \|\mathbf{R}_\gamma^i(x)\|^2 \leq g_{\lambda\gamma}^i(x) \leq \frac{1}{2} \left(\frac{1}{\gamma} - \frac{1}{\lambda} \right) \|\mathbf{R}_\lambda^i(x)\|^2.$$

Hence

$$\frac{1}{2} \left(\frac{1}{\gamma} - \frac{1}{\lambda} \right) \min_{1 \leq i \leq m} \{\|\mathbf{R}_\gamma^i(x)\|^2\} \leq \min_{1 \leq i \leq m} \{g_{\lambda\gamma}^i(x)\} \leq \frac{1}{2} \left(\frac{1}{\gamma} - \frac{1}{\lambda} \right) \min_{1 \leq i \leq m} \{\|\mathbf{R}_\lambda^i(x)\|^2\},$$

and so

$$\frac{1}{2} \left(\frac{1}{\gamma} - \frac{1}{\lambda} \right) r_\gamma^2(x) \leq G_{\lambda\gamma}(x) \leq \frac{1}{2} \left(\frac{1}{\gamma} - \frac{1}{\lambda} \right) r_\lambda^2(x).$$

The proof is completed. \square

Now we are in position to prove that $G_{\lambda\gamma}$ in the set \mathbf{R}^n is a global gap function for (2.1).

Theorem 5.2 For $0 < \gamma < \lambda$, $G_{\lambda\gamma}$ is a gap function for (2.1) on \mathbf{R}^n .

Proof. From (5.2), we have

$$G_{\lambda\gamma}(x) \geq 0, \quad \forall x \in \mathbf{R}^n.$$

Suppose that $\bar{x} \in \mathbf{R}^n$ with

$$G_{\lambda\gamma}(\bar{x}) = 0,$$

then (5.2) implies that

$$r_\gamma(\bar{x}) = 0.$$

From Theorem 3.1, we know \bar{x} is a solution of (2.1).

Conversely, if \bar{x} is a solution of (2.1), then from Theorem 3.1, it follows that

$$r_\lambda(\bar{x}) = 0.$$

Obviously, (5.2) shows that

$$G_{\lambda\gamma}(\bar{x}) = 0.$$

The proof is completed. \square

Use Theorem 3.2 and (5.2), we immediately get a global error bound in the set \mathbf{R}^n for (2.1).

Corollary 5.3 Let $\mathbb{F}, \mathbb{P} : \mathbf{R}^n \rightarrow \mathbf{R}^n$ be \mathcal{D} - $\vartheta^{\mathbb{F}}$ -Lipschitz continuous and \mathcal{D} - $\varrho^{\mathbb{P}}$ -Lipschitz continuous mappings, respectively. Let $\mathbb{N}_i : \mathbf{R}^n \times \mathbf{R}^n \rightarrow \mathbf{R}^n$ ($i = 1, 2, \dots, m$) be σ_i -Lipschitz continuous with respect to the first argument and φ_i -Lipschitz continuous with respect to the second argument, and $\mathbb{B} : \mathbf{R}^n \rightarrow \mathbf{R}^n$ be ℓ -Lipschitz continuous. Let $(\mathbb{N}_i, \mathbb{B})$ be the strongly monotone with respect to the first argument of \mathbb{N}_i and \mathbb{B} with constant $\mu_i^{\mathbb{B}}$ and relaxed monotone with respect to the second argument of \mathbb{N}_i and \mathbb{B} with modulus $\zeta_i^{\mathbb{B}}$. Let

$$\bigcap_{i=1}^m (\mathcal{U}^i) \neq \emptyset.$$

Assume that there exists $\kappa_i \in \left(0, \frac{\mu_i^{\mathbb{B}} - \zeta_i^{\mathbb{B}}}{\vartheta^{\mathbb{F}} \sigma_i + \varphi_i \varrho^{\mathbb{P}}}\right)$ such that

$$\|\mathfrak{J}_{\Omega(x)}^{f_i} z - \mathfrak{J}_{\Omega(y)}^{f_i} z\| \leq \kappa_i \|x - y\|, \quad \forall x, y \in \mathbf{R}^n, u \in \mathbb{F}(x), v \in \mathbb{P}(x), z \in \{w \mid w = \mathbb{B}(x) - \gamma \mathbb{N}_i(u, v)\}.$$

Then, for any $x \in \mathbf{R}^n$ and

$$\gamma > \frac{\kappa_i \ell}{\mu_i^{\mathbb{B}} - \zeta_i^{\mathbb{B}} - \kappa_i(\vartheta^{\mathbb{R}} \sigma_i + \varphi_i \varrho^{\mathbb{P}})},$$

$$d(x, \mathcal{U}^i) \leq \frac{\gamma(\vartheta^{\mathbb{R}} \sigma_i + \varrho^{\mathbb{P}} \varphi_i) + \ell}{\gamma(\mu_i^{\mathbb{B}} - \zeta_i^{\mathbb{B}} - \kappa_i(\vartheta^{\mathbb{R}} \sigma_i + \varrho^{\mathbb{P}} \varphi_i)) - \kappa_i \ell} \sqrt{\frac{2 \lambda \gamma}{\lambda - \gamma} G_{\lambda \gamma}(x)}.$$

6. Conclusions

One of the traditional approaches to evaluating a variational inequality (VI) and its variants is to turn into an analogous optimization problem by notion of a gap function. In addition, gap functions play a pivotal role in deriving the so-called error bounds that provide a measure of the distances between the solution set and feasible arbitrary point. Motivated and inspired by the researches going on in this direction, the main purpose of this paper is to further study the generalized vector inverse quasi-variational inequality problem (1.2) and to obtain error bounds in terms of the residual gap function, the regularized gap function, and the global gap function by utilizing the relaxed monotonicity and Hausdorff Lipschitz continuity. These error bounds provide effective estimated distances between an arbitrary feasible point and the solution set of (1.2).

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Conflict of interest

The authors declare that they have no competing interests.

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