## Research article

# Categorification of VB-Lie algebroids and VB-Courant algebroids 

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#### Abstract

In this paper, first we introduce the notion of a VB-Lie 2-algebroid, which can be viewed as the categorification of a VB-Lie algebroid. The tangent prolongation of a Lie 2-algebroid is a VB-Lie 2-algebroid naturally. We show that after choosing a splitting, there is a one-to-one correspondence between VB-Lie 2-algebroids and flat superconnections of a Lie 2-algebroid on a 3-term complex of vector bundles. Then we introduce the notion of a VB-CLWX 2-algebroid, which can be viewed as the categorification of a VB-Courant algebroid. We show that there is a one-to-one correspondence between split Lie 3-algebroids and split VB-CLWX 2-algebroids. Finally, we introduce the notion of an $E$-CLWX 2-algebroid and show that associated to a VB-CLWX 2-algebroid, there is an E-CLWX 2-algebroid structure on the graded fat bundle naturally. By this result, we give a construction of a new Lie 3-algebra from a given Lie 3-algebra, which provides interesting examples of Lie 3-algebras including the higher analogue of the string Lie 2-algebra.


Keywords: Lie 3-algebroid; VB-Lie algebroid; VB-Courant algebroid; superconnection; VB-Lie
2-algebroid; VB-CLWX 2-algebroid; higher analogue of the string Lie 2-algebra
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## 1. Introduction

In this paper, we study the categorification of VB-Lie algebroids and VB-Courant algebroids, and establish the relations between these higher structures and super representations of Lie 2-algebroids, tangent prolongations of Lie 2-algebroids, N-manifolds of degree 3, tangent prolongations of CLWX 2-algebroids and higher analogues of the string Lie 2-algebra.

### 1.1. Lie n-algebroids, Courant algebroids and CLWX 2-algebroids

An NQ-manifold is an N -manifold $\mathcal{M}$ together with a degree 1 vector field $Q$ satisfying $[Q, Q]=0$. It is well known that a degree 1 NQ manifold corresponds to a Lie algebroid. Thus, people usually think that

## An NQ-manifold of degree $n$ corresponds to a Lie $n$-algebroid.

Some work in this direction appeared in [54]. Strictly speaking, a Lie $n$-algebroid gives arise to an NQ-manifold only after a degree 1 shift, just as a Lie algebroid $A$ corresponds to a degree 1 NQ manifold A[1]. To make the shifting manifest, and to present a Lie $n$-algebroid in a way more used to differential geometers, that is, to use the language of vector bundles, the authors introduced the notion of a split Lie $n$-algebroid in [52] to study the integration of a Courant algebroid. The equivalence between the category of split NQ manifolds and the category of split Lie $n$-Lie algebroids was proved in [5]. The language of split Lie $n$-algebroids has slowly become a useful tool for differential geometers to study problems related to NQ-manifolds ([14, 24, 25]). Since Lie 2-algebras are the categorification of Lie algebras ([4]), we will view Lie 2-algebroids as the categorification of Lie algebroids.

To study the double of a Lie bialgebroid ([42]), Liu, Weinstein and Xu introduced the notion of a Courant algebroid in [35]. See [44] for an alternative definition. There are many important applications of Courant algebroids, e.g. in generalized complex geometry ([8, 17, 22]), Poisson geometry ([33]), moment maps ([9]), Poisson-Lie T-duality ([47, 48]) and topological field theory ([46]). In [34], the authors introduced the notion of a CLWX 2-algebroid (named after Courant-Liu-Weinstein-Xu), which can be viewed as the categorification of a Courant algebroid. Furthermore, CLWX 2-algebroids are in one-to-one correspondence with QP-manifolds (symplectic NQ-manifolds) of degree 3, and have applications in the fields theory. See [23] for more details. The underlying algebraic structure of a CLWX 2-algebroid is a Leibniz 2-algebra, or a Lie 3-algebra. There is also a close relationship between CLWX 2-algebroids and the first Pontryagin classes of quadratic Lie 2-algebroids, which are represented by closed 5 -forms. More precisely, as the higher analogue of the results given in [6, 13], it was proved in [49] that the first Pontryagin class of a quadratic Lie algebroid is the obstruction of the existence of a CLWX-extension.

### 1.2. VB-Lie algebroids and VB-Courant algebroids

Double structures in geometry can be traced back to the work of Ehresmann on connection theory, and have been found many applications in Poisson geometry. See [40] for more details. We use the word "doublization" to indicate putting geometric structures on double vector bundles in the sequel. In [19], Gracia-Saz and Mehta introduced the notion of a VB-Lie algebroid, which is equivalent to Mackenzie's $\mathcal{L} \mathcal{A}$-vector bundle ([38]). A VB-Lie algebroid is a Lie algebroid object in the category of vector bundles and one important property is that it is closely related to superconnection (also called representation up to homotopy [1, 2]) of a Lie algebroid on a 2-term complex of vector bundles. Recently, the relation between VB-algebroid morphisms and representations up to homotopy were studied in [15].

In his PhD thesis [32], Li-Bland introduced the notion of a VB-Courant algebroid which is the doublization of a Courant algebroid [35], and established abstract correspondence between NQ-manifolds of degree 2 and VB-Courant algebroids. Then in [24], Jotz Lean provided a more concrete description of the equivalence between the category of split Lie 2-algebroids and the category of decomposed VB-Courant algebroids.

Double structures, such as double principle (vector) bundles ([12, 16, 26, 30]), double Lie algebroids ( $[18,37,38,39,41,55]$ ), double Lie groupoids ([43]), VB-Lie algebroids ([7, 19]) and VB-Lie groupoids ( $[7,20]$ ) became more and more important recently and are widely studied. In particular, the Lie theory relating VB-Lie algebroids and VB-Lie groupoids, i.e. their relation via differentiation and integration, is established in [7].

### 1.3. Summary of the results and outline of the paper

In this paper, we combine the aforementioned higher structures and double structures. First we introduce the notion of a VB-Lie 2-algebroid, which can be viewed as the categorification of a VB-Lie algebroid, or doublization of a Lie 2-algebroid:


We show that the tangent prolongation of a Lie 2-algebroid is a VB-Lie 2-algebroid and the graded fat bundle associated to a VB-Lie 2-algebroid is Lie 2-algebroid. Consequently, the graded jet bundle of a Lie 2-algebroid is also a Lie 2-algebroid. In [19], the authors showed that a VB-Lie algebroid is equivalent to a flat superconnection (representation up to homotopy ([1])) of a Lie algebroid on a 2-term complex of vector bundles after choosing a splitting. Now for a VB-Lie 2-algebroid, we establish a higher analogous result, namely, we show that after choosing a splitting, it is equivalent to a flat superconnection of a Lie 2-algebroid on a 3-term complex of vector bundles.

Then we introduce the notion of a VB-CLWX 2-algebroid, which can be viewed as both the doublization of a CLWX 2-algebroid and the categorification of a VB-Courant algebroid. More importantly, we show that after choosing a splitting, there is a one-to-one correspondence between VB-CLWX 2algebroids and split Lie 3-algebroids (NQ-manifolds of degree 3). The tangent prolongation of a CLWX 2-algebroid is a VB-CLWX 2-algebroid naturally. We go on defining $E$-CLWX 2-algebroid, which can be viewed as the categorification of an $E$-Courant algebroid introduced in [11]. As a higher analogue of the result that associated to a VB-Courant algebroid, there is an $E$-Courant algebroid [24, 31], we show that on the graded fat bundle associated to a VB-CLWX 2-algebroid, there is an $E$-CLWX 2-algebroid structure naturally. Similar to the case of a CLWX 2-algebroid, an E-CLWX 2-algebroid also gives rise to a Lie 3-algebra naturally. Thus through the following procedure:

$$
\underset{\text { 3-algebra }}{\text { Lie }} \longmapsto \underset{\text { 2-algebroid }}{\text { VB-CLWX }} \longmapsto \underset{\text { 2-algebroid }}{E \text {-CLWX }} \longmapsto \underset{\text { 3-algebra, }}{\text { Lie }}
$$

we can construct a Lie 3-algebra from a Lie 3-algebra. We obtain new interesting examples, including the higher analogue of the string Lie 2-algebra.

The paper is organized as follows. In Section 2, we recall double vector bundles, VB-Lie algebroids and VB-Courant algebroids. In Section 3, we introduce the notion of a VB-Lie 2-algebroid, and show that both the graded side bundle and the graded fat bundle are Lie 2-algebroids. The tangent prolongation of a Lie 2-algebroid is a VB-Lie 2-algebroid naturally. In Section 4, first we construct a strict Lie 3 -algebroid $\operatorname{End}(\mathcal{E})=\left(\operatorname{End}^{-2}(\mathcal{E}), \operatorname{End}^{-1}(\mathcal{E}), \mathcal{D}(\mathcal{E}), \mathfrak{p}, \mathrm{d},[\cdot, \cdot]_{C}\right)$ from a 3-term complex of vector bundles $\mathcal{E}: E_{-2} \xrightarrow{\pi} E_{-1} \xrightarrow{\pi} E_{0}$ and then we define a flat superconnection of a Lie 2-algebroid $\mathcal{A}=\left(A_{-1}, A_{0}, \mathfrak{a}, \mathrm{l}_{1}, \mathrm{l}_{2}, \mathrm{l}_{3}\right)$ on this 3 -term complex of vector bundles to be a morphism from $\mathcal{A}$ to $\operatorname{End}(\mathcal{E})$. We show that after choosing a splitting, VB-Lie 2 -algebroids one-to-one correspond to flat superconnections of a Lie 2-algebroid on a 3-term complex of vector bundles. In Section 5, we introduce the notion of a VB-CLWX 2-algebroid and show that after choosing a splitting, there is a one-to-one correspondence between VB-CLWX 2-algebroids and Lie 3-algebroids. In Section 6, we introduce
the notion of an $E$-CLWX 2-algebroid and show that the graded fat bundle associated to a VB-CLWX 2-algebroid is an E-CLWX 2-algebroid naturally. In particular, the graded jet bundle of a CLWX 2algebroid, which is the graded fat bundle of the tangent prolongation of this CLWX 2-algebroid, is a $T^{*} M$-CLWX 2-algebroid. We can also obtain a Lie 3-algebra from an $E$-CLWX 2-algebroid. In Section 7, we construct a Lie 3-algebra from a given Lie 3-algebra using the theories established in Section 5 and Section 6, and give interesting examples. In particular, we show that associated to a quadratic Lie 2-algebra, we can obtain a Lie 3-algebra, which can be viewed as the higher analogue of the string Lie 2-algebra.

## 2. Preliminaries

See [40, Definition 9.1.1] for the precise definition of a double vector bundle. We denote a double vector bundle

with core $C$ by $(D ; A, B ; M)$. We use $D^{B}$ and $D^{A}$ to denote vector bundles $D \longrightarrow B$ and $D \longrightarrow A$ respectively. For a vector bundle $A$, both the tangent bundle $T A$ and the cotangent bundle $T^{*} A$ are double vector bundles:


A morphism of double vector bundles

$$
\left(\varphi ; f_{A}, f_{B} ; f_{M}\right):(D ; A, B ; M) \rightarrow\left(D^{\prime} ; A^{\prime}, B^{\prime} ; M^{\prime}\right)
$$

consists of maps $\varphi: D \rightarrow D^{\prime}, f_{A}: A \rightarrow A^{\prime}, f_{B}: B \rightarrow B^{\prime}, f_{M}: M \rightarrow M^{\prime}$, such that each of $\left(\varphi, f_{B}\right),\left(\varphi, f_{A}\right)$, $\left(f_{A}, f_{M}\right)$ and $\left(f_{B}, f_{M}\right)$ is a morphism of the relevant vector bundles.

The space of sections $\Gamma_{B}(D)$ of the vector bundle $D^{B}$ is generated as a $C^{\infty}(B)$-module by core sections $\Gamma_{B}^{c}(D)$ and linear sections $\Gamma_{B}^{l}(D)$. See [41] for more details. For a section $c: M \rightarrow C$, the corresponding core section $c^{\dagger}: B \rightarrow D$ is defined as

$$
c^{\dagger}\left(b_{m}\right)=\tilde{0}_{b_{m}}+{ }_{A} \overline{c(m)}, \quad \forall m \in M, b_{m} \in B_{m}
$$

where ' means the inclusion $C \hookrightarrow D$. A section $\xi: B \rightarrow D$ is called linear if it is a bundle morphism from $B \rightarrow M$ to $D \rightarrow A$ over a section $X \in \Gamma(A)$. We will view $B^{*} \otimes C$ both as $\operatorname{Hom}(B, C)$ and $\operatorname{Hom}\left(C^{*}, B^{*}\right)$ depending on what it acts. Given $\psi \in \Gamma\left(B^{*} \otimes C\right)$, there is a linear section $\tilde{\psi}: B \rightarrow D$ over the zero section $0^{A}: M \rightarrow A$ given by

$$
\tilde{\psi}\left(b_{m}\right)=\tilde{0}_{b_{m}}+_{A} \overline{\psi\left(b_{m}\right)} .
$$

Note that $\Gamma_{B}^{l}(D)$ is locally free as a $C^{\infty}(M)$-module. Therefore, $\Gamma_{B}^{l}(D)$ is equal to $\Gamma(\hat{A})$ for some vector bundle $\hat{A} \rightarrow M$. The vector bundle $\hat{A}$ is called the fat bundle of the double vector bundle ( $D ; A, B ; M$ ). Moreover, we have the following short exact sequence of vector bundles over $M$

$$
\begin{equation*}
0 \rightarrow B^{*} \otimes C \longrightarrow \hat{A} \xrightarrow{\mathrm{pr}} A \rightarrow 0 \tag{2.1}
\end{equation*}
$$

Definition 2.1. ([19, Definition 3.4]) A VB-Lie algebroid is a double vector bundle ( $D ; A, B ; M$ ) equipped with a Lie algebroid structure ( $D^{B}, a,[\cdot, \cdot]_{D}$ ) such that the anchor $a: D \longrightarrow T B$ is linear, i.e. $a:(D ; A, B ; M) \longrightarrow(T B ; T M, B ; M)$ is a morphism of double vector bundles, and the Lie bracket $[\cdot, \cdot]_{D}$ is linear:

$$
\left[\Gamma_{B}^{l}(D), \Gamma_{B}^{l}(D)\right]_{D} \subset \Gamma_{B}^{l}(D),\left[\Gamma_{B}^{l}(D), \Gamma_{B}^{c}(D)\right]_{D} \subset \Gamma_{B}^{c}(D),\left[\Gamma_{B}^{c}(D), \Gamma_{B}^{c}(D)\right]_{D}=0 .
$$

The vector bundle $A \longrightarrow M$ is then also a Lie algebroid, with the anchor $\mathfrak{a}$ and the bracket $[\cdot, \cdot]_{A}$ defined as follows: if $\xi_{1}, \xi_{2}$ are linear over $X_{1}, X_{2} \in \Gamma(A)$, then the bracket $\left[\xi_{1}, \xi_{2}\right]_{D}$ is linear over $\left[X_{1}, X_{2}\right]_{A}$.

Definition 2.2. ([32, Definition 3.1.1]) A VB-Courant algebroid is a metric double vector bundle $(D ; A, B ; M)$ such that $\left(D^{B}, S, \llbracket \cdot, \rrbracket, \rho\right)$ is a Courant algebroid and the following conditions are satisfied:
(i) The anchor map $\rho: D \rightarrow T B$ is linear;
(ii) The Courant bracket is linear. That is

$$
\llbracket \Gamma_{B}^{l}(D), \Gamma_{B}^{l}(D) \rrbracket \subseteq \Gamma_{B}^{l}(D), \quad \llbracket \Gamma_{B}^{l}(D), \Gamma_{B}^{c}(D) \rrbracket \subseteq \Gamma_{B}^{c}(D), \quad \llbracket \Gamma_{B}^{c}(D), \Gamma_{B}^{c}(D) \rrbracket=0 .
$$

Theorem 2.3. ([32, Proposition 3.2.1]) There is a one-to-one correspondence between Lie 2-algebroids and VB-Courant algebroids.

## 3. VB-Lie 2-algebroids

In this section, we introduce the notion of a VB-Lie 2-algebroid, which can be viewed as the categorification of a VB-Lie algebroid introduced in [19]. First we recall the notion of a Lie $n$-algebroid. See [28,29] for more information of $L_{\infty}$-algebras.

Definition 3.1. ([52, Definition 2.1]) A split Lie $n$-algebroid is a non-positively graded vector bundle $\mathcal{A}=A_{0} \oplus A_{-1} \oplus \cdots \oplus A_{-n+1}$ over a manifold $M$ equipped with a bundle map $a: A_{0} \longrightarrow T M$ (called the anchor), and $n+1$ many brackets $l_{i}: \Gamma\left(\wedge^{i} \mathcal{A}\right) \longrightarrow \Gamma(\mathcal{A})$ with degree $2-i$ for $1 \leq i \leq n+1$, such that

1. $\Gamma(\mathcal{A})$ is an $n$-term $L_{\infty}$-algebra:

$$
\begin{array}{r}
\sum_{i+j=k+1}(-1)^{i(j-1)} \sum_{\sigma \in S h_{i, k-i}^{-1}} \operatorname{sgn}(\sigma) \operatorname{Ksgn}(\sigma) \\
l_{j}\left(l_{i}\left(X_{\sigma(1)}, \cdots, X_{\sigma(i)}\right), X_{\sigma(i+1)}, \cdots, X_{\sigma(k)}\right)=0,
\end{array}
$$

where the summation is taken over all $(i, k-i)$-unshuffles $S h_{i, k-i}^{-1}$ with $i \geq 1$ and " $\operatorname{Ksgn}(\sigma)$ " is the Koszul sign for a permutation $\sigma \in S_{k}$, i.e.

$$
X_{1} \wedge \cdots \wedge X_{k}=\operatorname{Ksgn}(\sigma) X_{\sigma(1)} \wedge \cdots \wedge X_{\sigma(k)} .
$$

2. $l_{2}$ satisfies the Leibniz rule with respect to the anchor $a$ :

$$
l_{2}\left(X^{0}, f X\right)=f l_{2}\left(X^{0}, X\right)+a\left(X^{0}\right)(f) X, \quad \forall X^{0} \in \Gamma\left(A_{0}\right), f \in C^{\infty}(M), X \in \Gamma(\mathcal{A}) .
$$

3. For $i \neq 2$, $l_{i}$ 's are $C^{\infty}(M)$-linear.

Denote a split Lie $n$-algebroid by $\left(A_{-n+1}, \cdots, A_{0}, a, l_{1}, \cdots, l_{n+1}\right)$, or simply by $\mathcal{A}$. We will only use a split Lie 2 -algebroid ( $A_{-1}, A_{0}, a, l_{1}, l_{2}, l_{3}$ ) and a split Lie 3-algebroid ( $A_{-2}, A_{-1}, A_{0}, a, l_{1}, l_{2}, l_{3}, l_{4}$ ). For a split Lie $n$-algebroid, we have a generalized Chevalley-Eilenberg complex $\left(\Gamma\left(\operatorname{Symm}(\mathcal{A}[1])^{*}\right), \delta\right)$. See [5,52] for more details. Then $\mathcal{A}[1]$ is an NQ-manifold of degree $n$. A split Lie $n$-algebroid morphism $\mathcal{A} \rightarrow \mathcal{A}^{\prime}$ can be defined to be a graded vector bundle morphism $f: \operatorname{Symm}(\mathcal{A}[1]) \rightarrow \operatorname{Symm}\left(\mathcal{A}^{\prime}[1]\right)$ such that the induced pull-back map $f^{*}: C\left(\mathcal{A}^{\prime}[1]\right) \rightarrow C(\mathcal{A}[1])$ between functions is a morphism of NQ manifolds. However it is rather complicated to write down a morphism between split Lie $n$-algebroids in terms of vector bundles, anchors and brackets, please see [5, Section 4.1] for such details. We only give explicit formulas of a morphism from a split Lie 2-algebroid to a strict split Lie 3-algebroid ( $l_{3}=0, l_{4}=0$ ) and this is what we will use in this paper to define flat superconnections.
Definition 3.2. Let $\mathcal{A}=\left(A_{-1}, A_{0}, a, l_{1}, l_{2}, l_{3}\right)$ be a split Lie 2 -algebroid and $\mathcal{A}^{\prime}=\left(A_{-2}^{\prime}, A_{-1}^{\prime}, A_{0}^{\prime}, a^{\prime}, l_{1}^{\prime}, l_{2}^{\prime}\right)$ a strict split Lie 3 -algebroid. A morphism $F$ from $\mathcal{A}$ to $\mathcal{F}^{\prime}$ consists of:

- a bundle map $F^{0}: A_{0} \longrightarrow A_{0}^{\prime}$,
- a bundle map $F^{1}: A_{-1} \longrightarrow A_{-1}^{\prime}$,
- a bundle map $F_{0}^{2}: \wedge^{2} A_{0} \longrightarrow A_{-1}^{\prime}$,
- a bundle map $F_{1}^{2}: A_{0} \wedge A_{-1} \longrightarrow A_{-2}^{\prime}$,
- a bundle map $F^{3}: \wedge^{3} A_{0} \longrightarrow A_{-2}^{\prime}$,
such that for all $X^{0}, Y^{0}, Z^{0}, X_{i}^{0} \in \Gamma\left(A_{0}\right), i=1,2,3,4, X^{1}, Y^{1} \in \Gamma\left(A_{-1}\right)$, we have

$$
\begin{aligned}
& a^{\prime} \circ F^{0}=a, \\
& l_{1}^{\prime} \circ F_{1}=F_{0} \circ l_{1}, \\
& F^{0} l_{2}\left(X^{0}, Y^{0}\right)-l_{2}^{\prime}\left(F^{0}\left(X^{0}\right), F^{0}\left(Y^{0}\right)\right)=l_{1}^{\prime} F_{0}^{2}\left(X^{0}, Y^{0}\right), \\
& F^{1} l_{2}\left(X^{0}, Y^{1}\right)-l_{2}^{\prime}\left(F^{0}\left(X^{0}\right), F^{1}\left(Y^{1}\right)\right)=F_{0}^{2}\left(X^{0}, l_{1}\left(Y^{1}\right)\right)-l_{1}^{\prime} F_{1}^{2}\left(X^{0}, Y^{1}\right), \\
& l_{2}^{\prime}\left(F^{1}\left(X^{1}\right), F^{1}\left(Y^{1}\right)\right)=F_{1}^{2}\left(l_{1}\left(X^{1}\right), Y^{1}\right)-F_{1}^{2}\left(X^{1}, l_{1}\left(Y^{1}\right)\right), \\
& l_{2}^{\prime}\left(F^{0}\left(X^{0}\right), F^{2}\left(Y^{0}, Z^{0}\right)\right)-F_{0}^{2}\left(l_{2}\left(X^{0}, Y^{0}\right), Z^{0}\right)+c . p .=F^{1}\left(l_{3}\left(X^{0}, Y^{0}, Z^{0}\right)\right) \\
& \quad \quad+l_{1}^{\prime} F^{3}\left(X^{0}, Y^{0}, Z^{0}\right), \\
& l_{2}^{\prime}\left(F^{0}\left(X^{0}\right), F_{1}^{2}\left(Y^{0}, Z^{1}\right)\right)+l_{2}^{\prime}\left(F^{0}\left(Y^{0}\right), F_{1}^{2}\left(Z^{1}, X^{0}\right)\right)+l_{2}^{\prime}\left(F^{1}\left(Z^{1}\right), F_{0}^{2}\left(X^{0}, Y^{0}\right)\right) \\
& =F_{1}^{2}\left(l_{2}\left(X^{0}, Y^{0}\right), Z^{1}\right)+c . p .+F^{3}\left(X^{0}, Y^{0}, l_{1}\left(Z^{1}\right)\right),
\end{aligned}
$$

and

$$
\begin{aligned}
& \sum_{i=1}^{4}(-1)^{i+1}\left(F_{1}^{2}\left(X_{i}^{0}, l_{3}\left(X_{1}^{0}, \cdots, \widehat{X_{i}^{0}}, \cdots X_{4}^{0}\right)\right)+l_{2}^{\prime}\left(F^{0}\left(X_{i}^{0}\right), F^{3}\left(X_{1}^{0}, \cdots, \widehat{X_{i}^{0}}, \cdots X_{4}^{0}\right)\right)\right) \\
& +\sum_{i<j}(-1)^{i+j}\left(F^{3}\left(l_{2}\left(X_{i}^{0}, X_{j}^{0}\right), X_{k}^{0}, X_{l}^{0}\right)+c \cdot p .-\frac{1}{2} l_{2}^{\prime}\left(F_{0}^{2}\left(X_{i}^{0}, X_{j}^{0}\right), F_{0}^{2}\left(X_{k}^{0}, X_{l}^{0}\right)\right)\right)=0
\end{aligned}
$$

where $k<l$ and $\{k, l\} \cap\{i, j\}=\emptyset$.

Let $\left(A_{-1}, A_{0}, a, l_{1}, l_{2}, l_{3}\right)$ be a split Lie 2 -algebroid. Then for all $X^{0}, Y^{0} \in \Gamma\left(A_{0}\right)$ and $X^{1} \in \Gamma\left(A_{-1}\right)$, Lie derivatives $L_{X^{0}}^{0}: \Gamma\left(A_{-i}^{*}\right) \longrightarrow \Gamma\left(A_{-i}^{*}\right), i=0,1, L_{X^{1}}^{1}: \Gamma\left(A_{-1}^{*}\right) \longrightarrow \Gamma\left(A_{0}^{*}\right)$ and $L_{X^{0}, Y^{0}}^{3}: \Gamma\left(A_{-1}^{*}\right) \longrightarrow \Gamma\left(A_{0}^{*}\right)$ are defined by

$$
\left\{\begin{array}{rl}
\left\langle L_{X 0}^{0} \alpha^{0}, Y^{0}\right\rangle & =\rho\left(X^{0}\right)\left\langle Y^{0}, \alpha^{0}\right\rangle-\left\langle\alpha^{0}, l_{2}\left(X^{0}, Y^{0}\right)\right\rangle,  \tag{3.1}\\
\left\langle L_{X^{0}}^{0} 0^{1}, Y^{1}\right\rangle & =\rho\left(X^{0}\right)\left\langle Y^{1}, \alpha^{1}\right\rangle-\left\langle\alpha^{1}, l_{2}\left(X^{0}, Y^{1}\right)\right\rangle, \\
\left\langle L_{X^{1}}^{1} \alpha^{1}, Y^{0}\right\rangle & =-\left\langle\alpha^{1}, l_{2}\left(X^{1}, Y^{0}\right)\right\rangle, \\
\left\langle L_{X^{0}, Y^{0}}^{3}\right.
\end{array}{ }^{1}, Z^{0}\right\rangle=-\left\langle\alpha^{1}, l_{3}\left(X^{0}, Y^{0}, Z^{0}\right)\right\rangle, ~=
$$

for all $\alpha^{0} \in \Gamma\left(A_{0}^{*}\right), \alpha^{1} \in \Gamma\left(A_{-1}^{*}\right), Y^{1} \in \Gamma\left(A_{-1}\right), Z^{0} \in \Gamma\left(A_{0}\right)$. If $\left(\mathcal{A}^{*}[1], \mathfrak{a}, \mathfrak{l}_{1}, \mathfrak{l}_{2}, \mathfrak{l}_{3}\right)$ is also a split Lie 2-algebroid, we denote by $\mathcal{L}^{0}, \mathcal{L}^{1}, \mathcal{L}^{3}, \delta_{*}$ the corresponding operations.

A graded double vector bundle consists of a double vector bundle of degree -1 and a double vector bundle of degree 0 :



We denote a graded double vector bundle by $\left(\begin{array}{ccc}D_{-1} ; & A_{-1}, B_{-1} ; & M_{-1} \\ D_{0} ; & A_{0}, B_{0} ; & M_{0}\end{array}\right)$. Morphisms between graded double vector bundles can be defined in an obvious way. We will denote by $\mathcal{D}$ and $\mathcal{A}$ the graded vector bundles $D_{0}^{B} \oplus D_{-1}^{B}$ and $A_{0} \oplus A_{-1}$ respectively. Now we are ready to introduce the main object in this section.

Definition 3.3. A VB-Lie 2-algebroid is a graded double vector bundle

$$
\left(\begin{array}{ccc}
D_{-1} ; & A_{-1}, B ; & M \\
D_{0} ; & A_{0}, B ; & M
\end{array}\right)
$$

equipped with a Lie 2 -algebroid structure $\left(D_{-1}^{B}, D_{0}^{B}, a, l_{1}, l_{2}, l_{3}\right)$ on $\mathcal{D}$ such that
(i) The anchor $a: D_{0} \longrightarrow T B$ is linear, i.e. we have a bundle map $\mathfrak{a}: A_{0} \longrightarrow T M$ such that ( $a ; a, \mathrm{id}_{\mathrm{B}} ; \mathrm{id}_{\mathrm{M}}$ ) is a double vector bundle morphism (see Diagram (i));
(ii) $l_{1}$ is linear, i.e. we have a bundle map $\mathrm{I}_{1}: A_{-1} \longrightarrow A_{0}$ such that $\left(l_{1} ; \mathrm{I}_{1}, \mathrm{id}_{\mathrm{B}} ; \mathrm{id}_{\mathrm{M}}\right)$ is a double vector bundle morphism (see Diagram (ii));
(iii) $l_{2}$ is linear, i.e.

$$
\begin{array}{ll}
l_{2}\left(\Gamma_{B}^{l}\left(D_{0}\right), \Gamma_{B}^{l}\left(D_{0}\right)\right) \subset \Gamma_{B}^{l}\left(D_{0}\right), & l_{2}\left(\Gamma_{B}^{l}\left(D_{0}\right), \Gamma_{B}^{c}\left(D_{0}\right)\right) \subset \Gamma_{B}^{c}\left(D_{0}\right), \\
l_{2}\left(\Gamma_{B}^{l}\left(D_{0}\right), \Gamma_{B}^{l}\left(D_{-1}\right)\right) \subset \Gamma_{B}^{l}\left(D_{-1}\right), & l_{2}\left(\Gamma_{B}^{l}\left(D_{0}\right), \Gamma_{B}^{c}\left(D_{-1}\right)\right) \subset \Gamma_{B}^{c}\left(D_{-1}\right), \\
l_{2}\left(\Gamma_{B}^{c}\left(D_{0}\right), \Gamma_{B}^{l}\left(D_{-1}\right)\right) \subset \Gamma_{B}^{c}\left(D_{-1}\right), & l_{2}\left(\Gamma_{B}^{c}\left(D_{0}\right), \Gamma_{B}^{c}\left(D_{-1}\right)\right)=0 ; \\
l_{2}\left(\Gamma_{B}^{c}\left(D_{0}\right), \Gamma_{B}^{c}\left(D_{0}\right)\right)=0 . &
\end{array}
$$

(iv) $l_{3}$ is linear, i.e.

$$
\begin{aligned}
& l_{3}\left(\Gamma_{B}^{l}\left(D_{0}\right), \Gamma_{B}^{l}\left(D_{0}\right), \Gamma_{B}^{l}\left(D_{0}\right)\right) \subset \Gamma_{B}^{l}\left(D_{-1}\right), \\
& l_{3}\left(\Gamma_{B}^{l}\left(D_{0}\right), \Gamma_{B}^{l}\left(D_{0}\right), \Gamma_{B}^{c}\left(D_{0}\right)\right) \subset \Gamma_{B}^{c}\left(D_{-1}\right), \\
& l_{3}\left(\Gamma_{B}^{c}\left(D_{0}\right), \Gamma_{B}^{c}\left(D_{0}\right), \cdot\right)=0 .
\end{aligned}
$$



Diagram (i)


Diagram (ii)

Since Lie 2-algebroids are the categorification of Lie algebroids, VB-Lie 2-algebroids can be viewed as the categorification of VB-Lie algebroids.

Recall that if ( $D ; A, B ; M$ ) is a VB-Lie algebroid, then $A$ is a Lie algebroid. The following result is its higher analogue.
Theorem 3.4. Let $\left(\begin{array}{ccc}D_{-1} ; & A_{-1}, B ; & M \\ D_{0} ; & A_{0}, B ; & M\end{array}\right)$ be a VB-Lie 2-algebroid. Then

$$
\left(A_{-1}, A_{0}, \mathfrak{a}, \mathfrak{l}_{1}, \mathfrak{l}_{2}, \mathfrak{l}_{3}\right)
$$

is a split Lie 2-algebroid, where $\mathfrak{l}_{2}$ is defined by the property that if $\xi_{1}^{0}, \xi_{2}^{0}, \xi^{0} \in \Gamma_{B}^{l}\left(D_{0}\right)$ are linear sections over $X_{1}^{0}, X_{2}^{0}, X^{0} \in \Gamma\left(A_{0}\right)$, and $\xi^{1} \in \Gamma_{B}^{l}\left(D_{-1}\right)$ is a linear section over $X^{1} \in \Gamma\left(A_{-1}\right)$, then $l_{2}\left(\xi_{1}^{0}, \xi_{2}^{0}\right) \in \Gamma_{B}^{l}\left(D_{0}\right)$ is a linear section over $I_{2}\left(X_{1}^{0}, X_{2}^{0}\right) \in \Gamma\left(A_{0}\right)$ and $l_{2}\left(\xi^{0}, \xi^{1}\right) \in \Gamma_{B}^{l}\left(D_{-1}\right)$ is a linear section over $I_{2}\left(X^{0}, X^{1}\right) \in \Gamma\left(A_{-1}\right)$. Similarly, $I_{3}$ is defined by the property that if $\xi_{1}^{0}, \xi_{2}^{0}, \xi_{3}^{0} \in \Gamma_{B}^{l}\left(D_{0}\right)$ are linear sections over $X_{1}^{0}, X_{2}^{0}, X_{3}^{0} \in \Gamma\left(A_{0}\right)$, then $l_{3}\left(\xi_{1}^{0}, \xi_{2}^{0}, \xi_{3}^{0}\right) \in \Gamma_{B}^{l}\left(D_{-1}\right)$ is a linear section over $I_{3}\left(X_{1}^{0}, X_{2}^{0}, X_{3}^{0}\right) \in \Gamma\left(A_{-1}\right)$.
Proof. Since $l_{2}$ is linear, for any $\xi^{i} \in \Gamma_{B}^{l}\left(D_{-i}\right)$ satisfying $\pi^{A_{-i}}\left(\xi^{i}\right)=0$, we have

$$
\pi^{A_{-(i+j)}}\left(l_{2}\left(\xi^{i}, \eta^{j}\right)\right)=0, \quad \forall \eta^{j} \in \Gamma_{B}^{l}\left(D_{-j}\right) .
$$

This implies that $\mathrm{I}_{2}$ is well-defined. Similarly, $\mathrm{I}_{3}$ is also well-defined.
By the fact that $l_{1}: D_{-1} \longrightarrow D_{0}$ is a double vector bundle morphism over $I_{1}: A_{-1} \longrightarrow A_{0}$, we can deduce that $\left(\Gamma\left(A_{-1}\right), \Gamma\left(A_{0}\right), \mathrm{I}_{1}, \mathrm{I}_{2}, \mathrm{I}_{3}\right)$ is a Lie 2-algebra. We only give a proof of the property

$$
\begin{equation*}
\mathfrak{I}_{1}\left(\mathrm{l}_{2}\left(X_{0}, X_{1}\right)\right)=\mathfrak{I}_{2}\left(X_{0}, \mathrm{I}_{1}\left(X_{1}\right)\right), \quad \forall X^{0} \in \Gamma\left(A_{0}\right), X^{1} \in \Gamma\left(A_{-1}\right) . \tag{3.2}
\end{equation*}
$$

The other conditions in the definition of a Lie 2-algebra can be proved similarly. In fact, let $\xi^{0} \in$ $\Gamma_{B}^{l}\left(D_{0}\right), \xi^{1} \in \Gamma_{B}^{l}\left(D_{-1}\right)$ be linear sections over $X^{0}, X^{1}$ respectively, then by the equality $l_{1}\left(l_{2}\left(\xi^{0}, \xi^{1}\right)\right)=$ $l_{2}\left(\xi^{0}, l_{1}\left(\xi^{1}\right)\right)$, we have

$$
\pi^{A_{0}} l_{1}\left(l_{2}\left(\xi^{0}, \xi^{1}\right)\right)=\pi^{A_{0}} l_{2}\left(\xi^{0}, l_{1}\left(\xi^{1}\right)\right)
$$

Since $l_{1}: D_{-1} \longrightarrow D_{0}$ is a double vector bundle morphism over $\mathrm{I}_{1}: A_{-1} \longrightarrow A_{0}$, the left hand side is equal to

$$
\pi^{A_{0}} l_{1}\left(l_{2}\left(\xi^{0}, \xi^{1}\right)\right)=\mathfrak{l}_{1} \pi^{A^{-1}} l_{2}\left(\xi^{0}, \xi^{1}\right)=\mathfrak{l}_{1} \mathfrak{l}_{2}\left(X^{0}, X^{1}\right)
$$

and the right hand side is equal to

$$
\pi^{A_{0}} l_{2}\left(\xi^{0}, l_{1}\left(\xi^{1}\right)\right)=\mathfrak{I}_{2}\left(\pi^{A_{0}}\left(\xi^{0}\right), \pi^{A_{0}}\left(l_{1}\left(\xi^{1}\right)\right)\right)=\mathfrak{I}_{2}\left(X_{0}, \mathrm{I}_{1}\left(X^{1}\right)\right)
$$

Thus, we deduce that (3.2) holds.
Finally, for all $X^{0} \in \Gamma\left(A_{0}\right), Y^{i} \in \Gamma\left(A_{-i}\right)$ and $f \in C^{\infty}(M)$, let $\xi^{0} \in \Gamma_{B}^{l}\left(D_{0}\right)$ and $\eta^{i} \in \Gamma_{B}^{l}\left(D_{-i}\right), i=0,1$ be linear sections over $X^{0}$ and $Y^{i}$. Then $q_{B}^{*}(f) \eta^{i}$ is a linear section over $f Y^{i}$. By the fact that $a$ is a double vector bundle morphism over $\mathfrak{a}$, we have

$$
\begin{aligned}
\mathrm{I}_{2}\left(X^{0}, f Y^{i}\right) & =\pi^{A-i} l_{2}\left(\xi^{0}, q_{B}^{*}(f) \eta^{i}\right)=\pi^{A-i}\left(q_{B}^{*}(f) l_{2}\left(\xi^{0}, \eta^{i}\right)+a\left(\xi^{0}\right)\left(q_{B}^{*}(f)\right) \eta^{i}\right) \\
& =f \mathrm{I}_{2}\left(X^{0}, Y^{i}\right)+\mathfrak{a}\left(X^{0}\right)(f) Y^{i} .
\end{aligned}
$$

Therefore, $\left(A_{-1}, A_{0}, \mathfrak{a}, \mathfrak{l}_{1}, \mathfrak{l}_{2}, \mathfrak{l}_{3}\right)$ is a Lie 2-algebroid.
Remark 1. By the above theorem, we can view a VB-Lie 2-algebroid as a Lie 2-algebroid object in the category of double vector bundles.

Consider the associated graded fat bundle $\hat{A}_{-1} \oplus \hat{A}_{0}$, obviously we have
Proposition 1. Let $\left(\begin{array}{ccc}D_{-1} ; & A_{-1}, B ; & M \\ D_{0} ; & A_{0}, B ; & M\end{array}\right)$ be a VB-Lie 2-algebroid. Then $\left(\hat{A}_{-1}, \hat{A}_{0}, \hat{a}, \hat{l}_{1}, \hat{l}_{2}, \hat{l}_{3}\right)$ is a split Lie 2-algebroid, where $\hat{a}=\mathfrak{a} \circ \mathrm{pr}$ and $\hat{l}_{1}, \hat{l}_{2}, \hat{l}_{3}$ are the restriction of $l_{1}, l_{2}, l_{3}$ on linear sections respectively.

Consequently, we have the following exact sequences of split Lie 2-algebroids:


It is helpful to give the split Lie 2-algebroid structure on $B^{*} \otimes C_{-1} \oplus B^{*} \otimes C_{0}$. Since $l_{1}$ is linear, it induces a bundle map $l_{1}^{C}: C_{-1} \longrightarrow C_{0}$. The restriction of $\hat{l}_{1}$ on $B^{*} \otimes C_{-1}$ is given by

$$
\begin{equation*}
\hat{l}_{1}\left(\phi^{1}\right)=l_{1}^{C} \circ \phi^{1}, \quad \forall \phi^{1} \in \Gamma\left(B^{*} \otimes C_{-1}\right)=\Gamma\left(\operatorname{Hom}\left(B, C_{-1}\right)\right) . \tag{3.4}
\end{equation*}
$$

Since the anchor $a: D_{0} \longrightarrow T B$ is a double vector bundle morphism, it induces a bundle map $\varrho: C_{0} \longrightarrow B$ via

$$
\begin{equation*}
\left\langle\varrho\left(c^{0}\right), \xi\right\rangle=-a\left(c^{0}\right)(\xi), \quad \forall c^{0} \in \Gamma\left(C_{0}\right), \xi \in \Gamma\left(B^{*}\right) \tag{3.5}
\end{equation*}
$$

Then by the Leibniz rule, we deduce that the restriction of $\hat{l}_{2}$ on $\Gamma\left(B^{*} \otimes C_{-1} \oplus B^{*} \otimes C_{0}\right)$ is given by

$$
\begin{align*}
& \hat{l}_{2}\left(\phi^{0}, \psi^{0}\right)=\phi^{0} \circ \varrho \circ \psi^{0}-\psi^{0} \circ \varrho \circ \phi^{0},  \tag{3.6}\\
& \hat{l}_{2}\left(\phi^{0}, \psi^{1}\right)=-\hat{l}_{2}\left(\psi^{1}, \phi^{0}\right)=-\psi^{1} \circ \varrho \circ \phi^{0}, \tag{3.7}
\end{align*}
$$

for all $\phi^{0}, \psi^{0} \in \Gamma\left(B^{*} \otimes C_{0}\right)=\Gamma\left(\operatorname{Hom}\left(B, C_{0}\right)\right), \psi^{1} \in \Gamma\left(B^{*} \otimes C_{-1}\right)=\Gamma\left(\operatorname{Hom}\left(B, C_{-1}\right)\right)$. Since $l_{3}$ is linear, the restriction of $l_{3}$ on $B^{*} \otimes C_{-1} \oplus B^{*} \otimes C_{0}$ vanishes. Obviously, the anchor is trivial. Thus, the split Lie 2-algebroid structure on $B^{*} \otimes C_{-1} \oplus B^{*} \otimes C_{0}$ is exactly given by (3.4), (3.6) and (3.7). Therefore, $B^{*} \otimes C_{-1} \oplus B^{*} \otimes C_{0}$ is a graded bundle of strict Lie 2-algebras.

An important example of VB-Lie algebroids is the tangent prolongation of a Lie algebroid. Now we explore the tangent prolongation of a Lie 2-algebroid. Recall that for a Lie algebroid $A \longrightarrow M, T A$ is a Lie algebroid over $T M$. A section $\sigma: M \longrightarrow A$ gives rise to a linear section $\sigma_{T} \triangleq d \sigma: T M \longrightarrow T A$
and a core section $\sigma_{C}: T M \longrightarrow T A$ by contraction. Any section of $T A$ over $T M$ is generated by such sections. A function $f \in C^{\infty}(M)$ induces two types of functions on $T M$ by

$$
f_{C}=q^{*} f, \quad f_{T}=d f,
$$

where $q: T M \longrightarrow M$ is the projection. We have the following relations about the module structure:

$$
\begin{equation*}
(f \sigma)_{C}=f_{C} \sigma_{C}, \quad(f \sigma)_{T}=f_{T} \sigma_{C}+f_{C} \sigma_{T} \tag{3.8}
\end{equation*}
$$

In particular, for $A=T M$, we have

$$
\begin{equation*}
X_{T}\left(f_{T}\right)=X(f)_{T}, \quad X_{T}\left(f_{C}\right)=X(f)_{C}, \quad X_{C}\left(f_{T}\right)=X(f)_{C}, \quad X_{C}\left(f_{C}\right)=0 \tag{3.9}
\end{equation*}
$$

for all $X \in \mathfrak{X}(M)$. See [32, Example 2.5.4] and [40] for more details.
Now for split Lie 2-algebroids, we have
Proposition 2. Let $\mathcal{A}=\left(A_{-1}, A_{0}, \mathfrak{a}, \mathfrak{l}_{1}, \mathfrak{l}_{2}, \mathfrak{l}_{3}\right)$ be a split Lie 2 -algebroid. Then

$$
\left(T A_{-1}, T A_{0}, a, l_{1}, l_{2}, l_{3}\right)
$$

is a split Lie 2-algebroid over $T M$, where $a: T A_{0} \longrightarrow T T M$ is given by

$$
\begin{equation*}
a\left(\sigma_{T}^{0}\right)=\mathfrak{a}\left(\sigma^{0}\right)_{T}, \quad a\left(\sigma_{C}^{0}\right)=\mathfrak{a}\left(\sigma^{0}\right)_{C} \tag{3.10}
\end{equation*}
$$

$l_{1}: \Gamma_{T M}\left(T A_{-1}\right) \longrightarrow \Gamma_{T M}\left(T A_{0}\right)$ is given by

$$
\begin{equation*}
l_{1}\left(\sigma_{T}^{1}\right)=\mathfrak{l}_{1}\left(\sigma^{1}\right)_{T}, \quad l_{1}\left(\sigma_{C}^{1}\right)=\mathfrak{l}_{1}\left(\sigma^{1}\right)_{C}, \tag{3.11}
\end{equation*}
$$

$l_{2}: \Gamma_{T M}\left(T A_{-i}\right) \times \Gamma_{T M}\left(T A_{-j}\right) \longrightarrow \Gamma_{T M}\left(T A_{-(i+j)}\right)$ is given by

$$
\begin{aligned}
l_{2}\left(\sigma_{T}^{0}, \tau_{T}^{0}\right) & =\mathfrak{I}_{2}\left(\sigma^{0}, \tau^{0}\right)_{T}, l_{2}\left(\sigma_{T}^{0}, \tau_{C}^{0}\right)=\mathfrak{I}_{2}\left(\sigma^{0}, \tau^{0}\right)_{C}, l_{2}\left(\sigma_{C}^{0}, \tau_{C}^{0}\right)=0 \\
l_{2}\left(\sigma_{T}^{0}, \tau_{T}^{1}\right) & =\mathfrak{I}_{2}\left(\sigma^{0}, \tau^{1}\right)_{T}, l_{2}\left(\sigma_{T}^{0}, \tau_{C}^{1}\right)=\mathfrak{I}_{2}\left(\sigma^{0}, \tau^{1}\right)_{C}, l_{2}\left(\sigma_{C}^{0}, \tau_{T}^{1}\right)=\mathfrak{I}_{2}\left(\sigma^{0}, \tau^{1}\right)_{C}, \\
l_{2}\left(\sigma_{C}^{0}, \tau_{C}^{1}\right) & =0
\end{aligned}
$$

and $l_{3}: \wedge^{3} \Gamma_{T M}\left(T A_{0}\right) \longrightarrow \Gamma_{T M}\left(T A_{-1}\right)$ is given by

$$
\begin{equation*}
l_{3}\left(\sigma_{T}^{0}, \tau_{T}^{0}, \varsigma_{T}^{0}\right)=\mathrm{I}_{3}\left(\sigma^{0}, \tau^{0}, \varsigma^{0}\right)_{T}, \quad l_{3}\left(\sigma_{T}^{0}, \tau_{T}^{0}, \varsigma_{C}^{0}\right)=\mathrm{I}_{3}\left(\sigma^{0}, \tau^{0}, \varsigma^{0}\right)_{C}, \tag{3.12}
\end{equation*}
$$

and $l_{3}\left(\sigma_{T}^{0}, \tau_{C}^{0}, \varsigma_{C}^{0}\right)=0$, for all $\sigma^{0}, \tau^{0}, \varsigma^{0} \in \Gamma\left(A_{0}\right)$ and $\sigma^{1}, \tau^{1} \in \Gamma\left(A_{-1}\right)$.
Moreover, we have the following VB-Lie 2-algebroid:


Proof. By the fact that $\mathcal{A}=\left(A_{-1}, A_{0}, \mathfrak{a}, l_{1}, l_{2}, l_{3}\right)$ is a split Lie 2-algebroid, it is straightforward to deduce that $\left(T A_{-1}, T A_{0}, a, l_{1}, l_{2}, l_{3}\right)$ is a split Lie 2 -algebroid over $T M$. Moreover, $a, l_{1}, l_{2}, l_{3}$ are all linear, which implies that it is a VB-Lie 2-algebroid.

The associated fat bundles of double vector bundles $\left(T A_{-1} ; A_{-1}, T M ; M\right)$ and $\left(T A_{0} ; A_{0}, T M ; M\right)$ are the jet bundles $\mathfrak{J} A_{-1}$ and $\mathfrak{J} A_{0}$ respectively. By Proposition 2 and Proposition 1, we obtain the following result, which is the higher analogue of the fact that the jet bundle of a Lie algebroid is a Lie algebroid.

Corollary 1. Let $\left(A_{-1}, A_{0}, \mathfrak{a}, \mathfrak{l}_{1}, l_{2}, \mathfrak{l}_{3}\right)$ be a split Lie 2-algebroid. Then we obtain that $\left(\mathfrak{J} A_{-1}, \mathfrak{J} A_{0}, \hat{a}, \hat{l}_{1}, \hat{l}_{2}, \hat{l}_{3}\right)$ is a split Lie 2-algebroid, where $\hat{a}, \hat{l}_{1}, \hat{l}_{2}, \hat{l}_{3}$ is given by

$$
\begin{aligned}
\hat{a}\left(\sigma_{T}^{0}\right) & =\mathfrak{a}\left(\sigma^{0}\right), \\
\hat{l}_{2}\left(\sigma_{T}^{0}, \tau_{T}^{0}\right) & =\mathfrak{l}_{2}\left(\sigma^{0}, \tau^{0}\right)_{T}, \\
\hat{l}_{2}\left(\sigma_{T}^{0}, \tau_{T}^{1}\right) & =\mathfrak{l}_{2}\left(\sigma^{0}, \tau^{1}\right)_{T}, \\
\hat{l}_{3}\left(\sigma_{T}^{0}, \tau_{T}^{0}, \zeta_{T}^{0}\right) & =\mathfrak{l}_{2}\left(\sigma^{0}, \tau^{0}, \zeta^{0}\right)_{T},
\end{aligned}
$$

for all $\sigma^{0}, \tau^{0}, \zeta^{0} \in \Gamma\left(A_{0}\right)$ and $\tau^{1} \in \Gamma\left(A_{-1}\right)$.

## 4. Superconnections of a split Lie 2-algebroid on a 3-term complex of vector bundles

In the section, we introduce the notion of a superconnection of a split Lie 2-algebroid on a 3-term complex of vector bundles, which generalizes the notion of a superconnection of a Lie algebroid on a 2 -term complex of vector bundles studied in [19]. We show that a VB-Lie 2-algebroid structure on a split graded double vector bundle is equivalent to a flat superconnection of a split Lie 2-algebroid on a 3-term complex of vector bundles.

Denote a 3-term complex of vector bundles $E_{-2} \xrightarrow{\pi} E_{-1} \xrightarrow{\pi} E_{0}$ by $\mathcal{E}$. Sections of the covariant differential operator bundle $\mathfrak{D}(\mathcal{E})$ are of the form $\mathfrak{D}=\left(\mathfrak{D}_{0}, \mathfrak{D}_{1}, \mathfrak{D}_{2}\right)$, where $\mathfrak{D}_{i}: \Gamma\left(E_{-i}\right) \longrightarrow \Gamma\left(E_{-i}\right)$ are $\mathbb{R}$-linear maps such that there exists $X \in \mathfrak{X}(M)$ satisfying

$$
\mathrm{D}_{i}\left(f e^{i}\right)=f \mathrm{D}_{i}\left(e^{i}\right)+X(f) e^{i}, \quad \forall f \in C^{\infty}(M), e^{i} \in \Gamma\left(E_{-i}\right) .
$$

Equivalently, $\mathfrak{D}(\mathcal{E})=\mathfrak{D}\left(E_{0}\right) \times_{T M} \mathfrak{D}\left(E_{-1}\right) \times_{T M} \mathfrak{D}\left(E_{-2}\right)$. Define $\mathfrak{p}: \mathfrak{D}(\mathcal{E}) \longrightarrow T M$ by

$$
\begin{equation*}
\mathfrak{p}\left(\mathrm{D}_{0}, \mathfrak{D}_{1}, \mathfrak{D}_{2}\right)=X . \tag{4.1}
\end{equation*}
$$

Then the covariant differential operator bundle $\mathfrak{D}(\mathcal{E})$ fits the following exact sequence:

$$
\begin{equation*}
0 \longrightarrow \operatorname{End}\left(E_{0}\right) \oplus \operatorname{End}\left(E_{-1}\right) \oplus \operatorname{End}\left(E_{-2}\right) \longrightarrow \mathfrak{D}(\mathcal{E}) \longrightarrow T M \longrightarrow 0 . \tag{4.2}
\end{equation*}
$$

Denote by $\operatorname{End}^{-1}(\mathcal{E})=\operatorname{Hom}\left(E_{0}, E_{-1}\right) \oplus \operatorname{Hom}\left(E_{-1}, E_{-2}\right)$. Denote by $\operatorname{End}^{-2}(\mathcal{E})=\operatorname{Hom}\left(E_{0}, E_{-2}\right)$. Define $\mathrm{d}: \operatorname{End}^{-2}(\mathcal{E}) \longrightarrow \operatorname{End}^{-1}(\mathcal{E})$ by

$$
\begin{equation*}
\mathrm{d}\left(\theta^{2}\right)=\pi \circ \theta^{2}-\theta^{2} \circ \pi, \quad \forall \theta^{2} \in \Gamma\left(\operatorname{Hom}\left(E_{0}, E_{-2}\right)\right), \tag{4.3}
\end{equation*}
$$

and define $\mathrm{d}: \operatorname{End}^{-1}(\mathcal{E}) \longrightarrow \mathcal{D}(\mathcal{E})$ by

$$
\begin{equation*}
\mathrm{d}\left(\theta^{1}\right)=\pi \circ \theta^{1}+\theta^{1} \circ \pi, \quad \forall \theta^{1} \in \Gamma\left(\operatorname{Hom}\left(E_{0}, E_{-1}\right) \oplus \operatorname{Hom}\left(E_{-1}, E_{-2}\right)\right) . \tag{4.4}
\end{equation*}
$$

Then we define a degree 0 graded symmetric bracket operation $[\cdot, \cdot]_{C}$ on the section space of the graded bundle $\operatorname{End}^{-2}(\mathcal{E}) \oplus \operatorname{End}^{-1}(\mathcal{E}) \oplus \mathcal{D}(\mathcal{E})$ by

$$
\begin{align*}
{[\mathfrak{D}, \mathrm{t}]_{C} } & =\mathfrak{D} \circ \mathrm{t}-\mathrm{t} \circ \mathfrak{D}, \quad \forall \mathfrak{D}, \mathrm{t} \in \Gamma(\mathfrak{D}(\mathcal{E})),  \tag{4.5}\\
{\left[\mathfrak{d}, \theta^{i}\right]_{C} } & =\mathfrak{D} \circ \theta^{i}-\theta^{i} \circ \mathfrak{d}, \quad \forall \mathfrak{D} \in \Gamma(\mathfrak{D}(\mathcal{E})), \theta^{i} \in \Gamma\left(\operatorname{End}^{-i}(\mathcal{E})\right),  \tag{4.6}\\
{\left[\theta^{1}, \vartheta^{1}\right]_{C} } & =\theta^{1} \circ \vartheta^{1}+\vartheta^{1} \circ \theta^{1}, \quad \forall \theta^{1}, \vartheta^{1} \in \Gamma\left(\operatorname{End}^{-1}(\mathcal{E})\right) . \tag{4.7}
\end{align*}
$$

Denote by $\mathfrak{D}_{\pi}(\mathcal{E}) \subset \mathfrak{D}(\mathcal{E})$ the subbundle of $\mathfrak{D}(\mathcal{E})$ whose section $\mathfrak{D} \in \Gamma\left(\mathfrak{D}_{\pi}(\mathcal{E})\right.$ ) satisfying $\pi \circ \mathfrak{D}=\mathfrak{D} \circ \pi$, or in term of components,

$$
\mathfrak{D}_{0} \circ \pi=\pi \circ \mathfrak{D}_{1}, \quad \mathfrak{D}_{1} \circ \pi=\pi \circ \mathfrak{D}_{2} .
$$

It is obvious that $\Gamma\left(\mathfrak{D}_{\pi}(\mathcal{E})\right)$ is closed under the bracket operation $[\cdot, \cdot]_{C}$ and

$$
\mathrm{d}\left(\operatorname{End}^{-1}(\mathcal{E})\right) \subset \mathfrak{D}_{\pi}(\mathcal{E})
$$

Then it is straightforward to verify that
Theorem 4.1. Let $E_{-2} \xrightarrow{\pi} E_{-1} \xrightarrow{\pi} E_{0}$ be a 3-term complex of vector bundles over $M$. Then $\left(\operatorname{End}^{-2}(\mathcal{E}), \operatorname{End}^{-1}(\mathcal{E}), \mathfrak{D}_{\pi}(\mathcal{E}), \mathfrak{p}, \mathrm{d},[\cdot, \cdot]_{C}\right)$ is a strict split Lie 3-algebroid.

With above preparations, we give the definition of a superconnection of a split Lie 2-algebroid on a 3-term complex of vector bundles as follows.

Definition 4.2. A superconnection of a split Lie 2-algebroid ( $A_{-1}, A_{0}, \mathfrak{a}, \mathrm{l}_{1}, \mathfrak{l}_{2}, \mathrm{l}_{3}$ ) on a 3-term complex of vector bundles $E_{-2} \xrightarrow{\pi} E_{-1} \xrightarrow{\pi} E_{0}$ consists of:

- a bundle morphism $F^{0}: A_{0} \longrightarrow \mathfrak{D}_{\pi}(\mathcal{E})$,
- a bundle morphism $F^{1}: A_{-1} \longrightarrow \operatorname{End}^{-1}(\mathcal{E})$,
- a bundle morphism $F_{0}^{2}: \wedge^{2} A_{0} \longrightarrow \operatorname{End}^{-1}(\mathcal{E})$,
- a bundle morphism $F_{1}^{2}: A_{0} \wedge A_{-1} \longrightarrow \operatorname{End}^{-2}(\mathcal{E})$,
- a bundle morphism $F^{3}: \wedge^{3} A_{0} \longrightarrow \operatorname{End}^{-2}(\mathcal{E})$.

A superconnection is called flat if $\left(F^{0}, F^{1}, F_{0}^{2}, F_{1}^{2}, F^{3}\right)$ is a Lie $n$-algebroid morphism from the split Lie 2-$\operatorname{algebroid}\left(A_{-1}, A_{0}, \mathfrak{a}, \mathfrak{I}_{1}, \mathfrak{I}_{2}, \mathfrak{I}_{3}\right)$ to the strict split Lie 3-algebroid $\left(\operatorname{End}^{-2}(\mathcal{E}), \operatorname{End}^{-1}(\mathcal{E}), \mathfrak{D}_{\pi}(\mathcal{E}), \mathfrak{p}, \mathrm{d},[\cdot, \cdot]_{C}\right)$.

Remark 2. If the split Lie 2-algebroid reduces to a Lie algebroid A and the 3-term complex reduces to a 2-term complex $E_{-1} \xrightarrow{\pi} E_{0}$, a superconnection will only consists of

- a bundle morphism $F^{0}=\left(F_{0}^{0}, F_{1}^{0}\right): A \longrightarrow \mathfrak{D}_{\pi}(\mathcal{E})$,
- a bundle morphism $F_{0}^{2}: \wedge^{2} A_{0} \longrightarrow \operatorname{Hom}\left(E_{0}, E_{-1}\right)$.

Thus, we recover the notion of a superconnection (also called representation up to homotopy if it is flat) of a Lie algebroid on a 2-term complex of vector bundles. See [1, 19] for more details.

Now we come back to VB-Lie 2-algebroids. Let ( $D_{-1}^{B}, D_{0}^{B}, a, l_{1}, l_{2}, l_{3}$ ) be a VB-Lie 2-algebroid structure on the graded double vector bundle $\left(\begin{array}{ccc}D_{-1} ; & A_{-1}, B ; & M \\ D_{0} ; & A_{0}, B ; & M\end{array}\right)$. Recall from Theorem 3.4 and Proposition 1 that both $\left(A_{-1}, A_{0}, \mathfrak{a}, l_{1}, l_{2}, l_{3}\right)$ and $\left(\hat{A}_{-1}, \hat{A}_{0}, \hat{a}, \hat{l}_{1}, \hat{l}_{2}, \hat{l}_{3}\right)$ are split Lie 2 -algebroids.

Choose a horizontal lift $s=\left(s_{0}, s_{1}\right): A_{0} \oplus A_{-1} \longrightarrow \hat{A}_{0} \oplus \hat{A}_{-1}$ of the short exact sequence of split Lie 2-algebroids (3.3). Define $\nabla^{B}: A_{0} \longrightarrow \mathfrak{D}(B)$ by

$$
\left\langle\nabla_{X^{0}}^{B} b, \xi\right\rangle=\mathfrak{a}\left(X^{0}\right)\langle\xi, b\rangle-\left\langle b, \hat{a}\left(s_{0}\left(X^{0}\right)\right)(\xi)\right\rangle, \quad \forall X^{0} \in \Gamma\left(A_{0}\right), b \in \Gamma(B), \xi \in \Gamma\left(B^{*}\right) .
$$

Since for all $\phi^{0} \in \Gamma\left(B^{*} \otimes C_{0}\right)$, we have $\hat{a}\left(\phi^{0}\right)=0$, it follows that $\nabla^{B}$ is well-defined.
We define $\nabla^{0}: A_{0} \longrightarrow \mathfrak{D}\left(C_{0}\right)$ and $\nabla^{1}: A_{0} \longrightarrow \mathfrak{D}\left(C_{-1}\right)$ by

$$
\begin{equation*}
\nabla_{X^{0}}^{0} c^{0}=l_{2}\left(s_{0}\left(X^{0}\right), c^{0}\right), \quad \nabla_{X^{0}}^{1} c^{1}=l_{2}\left(s_{0}\left(X^{0}\right), c^{1}\right), \tag{4.8}
\end{equation*}
$$

for all $X^{0} \in \Gamma\left(A_{0}\right), c^{0} \in \Gamma\left(C_{0}\right), c^{1} \in \Gamma\left(C_{-1}\right)$.
Define $\Upsilon^{1}: A_{-1} \longrightarrow \operatorname{Hom}\left(B, C_{0}\right)$ and $\Upsilon^{2}: A_{-1} \longrightarrow \operatorname{Hom}\left(C_{0}, C_{-1}\right)$ by

$$
\begin{equation*}
\Upsilon_{X^{1}}^{1}=s_{0}\left(\mathrm{l}_{1}\left(X^{1}\right)\right)-\hat{l}_{1}\left(s_{1}\left(X^{1}\right)\right), \quad \Upsilon_{X^{1}}^{2} c^{0}=l_{2}\left(s_{1}\left(X^{1}\right), c^{0}\right), \tag{4.9}
\end{equation*}
$$

for all $X^{1} \in \Gamma\left(A_{-1}\right), c^{0} \in \Gamma\left(C_{0}\right)$. Since $l_{2}$ is linear, $\nabla^{0}, \nabla^{1}$ and $\Upsilon$ are well-defined.
Define $R^{0}: \wedge^{2} \Gamma\left(A_{0}\right) \longrightarrow \Gamma\left(\operatorname{Hom}\left(B, C_{0}\right)\right), \Lambda: \wedge^{2} \Gamma\left(A_{0}\right) \longrightarrow \Gamma\left(\operatorname{Hom}\left(C_{0}, C_{-1}\right)\right)$ and $R^{1}: \Gamma\left(A_{0}\right) \wedge$ $\Gamma\left(A_{-1}\right) \longrightarrow \Gamma\left(\operatorname{Hom}\left(B, C_{-1}\right)\right)$ by

$$
\begin{align*}
R^{0}\left(X^{0}, Y^{0}\right) & =s_{0} \mathrm{I}_{2}\left(X^{0}, Y^{0}\right)-\hat{l}_{2}\left(s_{0}\left(X^{0}\right), s_{0}\left(Y^{0}\right)\right),  \tag{4.10}\\
\Lambda\left(X^{0}, Y^{0}\right)\left(c^{0}\right) & =-l_{3}\left(s_{0}\left(X^{0}\right), s_{0}\left(Y^{0}\right), c^{0}\right),  \tag{4.11}\\
R^{1}\left(X^{0}, Y^{1}\right) & =s_{1} l_{2}\left(X^{0}, Y^{1}\right)-\hat{l}_{2}\left(s_{0}\left(X^{0}\right), s_{1}\left(Y^{1}\right)\right), \tag{4.12}
\end{align*}
$$

for all $X^{0}, Y^{0} \in \Gamma\left(A_{0}\right)$ and $Y^{1} \in \Gamma\left(A_{-1}\right)$
Finally, define $\Xi: \wedge^{3} \Gamma\left(A_{0}\right) \longrightarrow \operatorname{Hom}\left(B, C_{-1}\right)$ by

$$
\begin{equation*}
\left.\Xi\left(X^{0}, Y^{0}, Z^{0}\right)\right)=s_{1} \mathrm{l}_{3}\left(X^{0}, Y^{0}, Z^{0}\right)-\hat{l}_{3}\left(s_{0}\left(X^{0}\right), s_{0}\left(Y^{0}\right), s_{0}\left(Z^{0}\right)\right) . \tag{4.13}
\end{equation*}
$$

By the equality $l_{1} l_{2}\left(s_{0}\left(X^{0}\right), c^{1}\right)=l_{2}\left(s_{0}\left(X^{0}\right), l_{1}^{C}\left(c^{1}\right)\right)$, we obtain

$$
\begin{equation*}
l_{1}^{C} \circ \nabla_{X^{0}}^{1}=\nabla_{X^{0}}^{0} \circ l_{1}^{C} \tag{4.14}
\end{equation*}
$$

By the fact that $a: D_{0} \longrightarrow T B$ preserves the bracket operation, we obtain

$$
\begin{aligned}
\left\langle\nabla_{X^{0}}^{B} \varrho\left(c^{0}\right), \xi\right\rangle & =\mathfrak{a}\left(X^{0}\right)\left\langle\varrho\left(c^{0}\right), \xi\right\rangle-\left\langle\varrho\left(c^{0}\right), a\left(s_{0}\left(X^{0}\right)\right)(\xi)\right\rangle \\
& =-\left[a\left(s_{0}\left(X^{0}\right)\right), a\left(c^{0}\right)\right]_{T B}(\xi)=-a\left(l_{2}\left(s_{0}\left(X^{0}\right), c^{0}\right)\right)(\xi) \\
& =\left\langle\varrho \nabla_{X^{0}}^{0} c^{0}, \xi\right\rangle,
\end{aligned}
$$

which implies that

$$
\begin{equation*}
\nabla_{X^{0}}^{B} \circ \varrho=\varrho \circ \nabla_{X^{0}}^{0} . \tag{4.15}
\end{equation*}
$$

By (4.14) and (4.15), we deduce that $\left(\nabla_{X^{0}}^{B}, \nabla_{X^{0}}^{0}, \nabla_{X^{0}}^{1}\right) \in \mathfrak{D}(\mathcal{E})$, where $\mathcal{E}$ is the 3-term complex of vector bundles $C_{-1} \xrightarrow{l_{1}^{c}} C_{0} \xrightarrow{\varrho} B$. Then we obtain a superconnection $\left(F^{0}, F^{1}, F_{0}^{2}, F_{1}^{2}, F^{3}\right)$ of the Lie 2-algebroid $\left(A_{-1}, A_{0}, \mathfrak{a}, \mathfrak{I}_{1}, \mathfrak{I}_{2}, \mathfrak{I}_{3}\right)$ on the 3-term complex of vector bundles $C_{-1} \xrightarrow{\iota_{1}^{c}} C_{0} \xrightarrow{\varrho} B$, where

$$
F^{0}=\left(\nabla^{B}, \nabla^{0}, \nabla^{1}\right), \quad F^{1}=\left(\Upsilon^{1}, \Upsilon^{2}\right), \quad F_{0}^{2}=\left(R^{0}, \Lambda\right), \quad F_{1}^{2}=R^{1}, \quad F^{3}=\Xi .
$$

Theorem 4.3. There is a one-to-one correspondence between VB-Lie 2-algebroids $\left(\begin{array}{ccc}D_{-1} ; & A_{-1}, B ; & M \\ D_{0} ; & A_{0}, B ; & M\end{array}\right)$ and flat superconnections $\left(F^{0}, F^{1}, F_{0}^{2}, F_{1}^{2}, F^{3}\right)$ of the split Lie 2-algebroid $\left(A_{-1}, A_{0}, \mathfrak{a}, \mathfrak{l}_{1}, \mathfrak{l}_{2}, \mathfrak{l}_{3}\right)$ on the 3-term complex of vector bundles $C_{-1} \xrightarrow{l_{1}^{c}} C_{0} \xrightarrow{\varrho} B$ by choosing a horizontal lift $s=\left(s_{0}, s_{1}\right): A_{0} \oplus A_{-1} \longrightarrow \hat{A}_{0} \oplus \hat{A}_{-1}$.

Proof. First it is obvious that

$$
\begin{equation*}
\mathfrak{p} \circ F^{0}=\mathfrak{a} . \tag{4.16}
\end{equation*}
$$

Using equalities $\mathfrak{a} \circ \mathrm{I}_{1}=0$ and $a \circ l_{1}=0$, we have

$$
\left\langle\nabla_{1_{1} X^{1}}^{B} b, \xi\right\rangle=\mathfrak{a}\left(\mathrm{I}_{1}\left(X^{1}\right)\right)\langle b, \xi\rangle-\left\langle b, a\left(s_{0}\left(\mathrm{I}_{1}\left(X^{1}\right)\right)\right)(\xi)\right\rangle=-\left\langle b, a\left(\Upsilon_{X^{1}}^{1}\right)(\xi)\right\rangle,
$$

which implies that

$$
\begin{equation*}
\nabla_{1_{1} X^{1}}^{B}=\varrho \circ \Upsilon_{X^{1}}^{1} . \tag{4.17}
\end{equation*}
$$

For $\nabla^{0}$, we can obtain

$$
\begin{align*}
\nabla_{\mathrm{I}_{1}\left(X^{1}\right)}^{0} & =\left.l_{2}\left(s_{0} \mathrm{I}_{1}\left(X^{1}\right), \cdot\right)\right|_{C_{0}}=\left.l_{2}\left(l_{1}\left(s_{1}\left(X^{1}\right)\right)+\Upsilon_{X^{1}}^{1}, \cdot\right)\right|_{C_{0}} \\
& =l_{1}^{C} \circ \Upsilon_{X^{1}}^{2}+\Upsilon_{X^{1}}^{1} \circ \varrho . \tag{4.18}
\end{align*}
$$

For $\nabla^{1}$, we have

$$
\begin{equation*}
\nabla_{1_{1}\left(X^{1}\right)}^{1}=\left.l_{2}\left(s_{0} \mathrm{l}_{1}\left(X^{1}\right), \cdot\right)\right|_{C_{1}}=\left.l_{2}\left(l_{1}\left(s_{1}\left(X^{1}\right)\right)+\Upsilon_{X^{1}}^{1}, \cdot\right)\right|_{C_{1}}=\Upsilon_{X^{1}}^{2} \circ l_{1}^{C} \tag{4.19}
\end{equation*}
$$

By (4.17), (4.18) and (4.19), we deduce that

$$
\begin{equation*}
F^{0} \circ \mathfrak{I}_{1}=\mathrm{d} \circ F^{1} . \tag{4.20}
\end{equation*}
$$

By straightforward computation, we have

$$
\begin{aligned}
& \left\langle\nabla_{\mathrm{t}_{2}\left(X^{0}, Y^{0}\right)}^{B} b-\nabla_{X^{0}}^{B} \nabla_{Y^{0}}^{B} b+\nabla_{Y^{0}}^{B} \nabla_{X^{0}}^{B} b, \xi\right\rangle \\
= & \left\langle b, a\left(\hat{l}_{2}\left(s_{0}\left(X^{0}\right), s_{0}\left(Y_{0}\right)\right)-s_{0} \mathrm{l}_{2}\left(X^{0}, Y^{0}\right)\right)(\xi)\right\rangle \\
= & \left\langle b,-a\left(R^{0}\left(X^{0}, Y^{0}\right)\right)(\xi)\right\rangle,
\end{aligned}
$$

which implies that

$$
\begin{equation*}
\nabla_{\mathrm{t}_{2}\left(X^{0}, Y^{0}\right)}^{B}-\nabla_{X^{0}}^{B} \nabla_{Y^{0}}^{B}+\nabla_{Y^{0}}^{B} \nabla_{X^{0}}^{B}=\varrho \circ R^{0}\left(X^{0}, Y^{0}\right) . \tag{4.21}
\end{equation*}
$$

Similarly, we have

$$
\begin{aligned}
& \nabla_{\mathrm{L}_{2}\left(X^{0}, Y^{0}\right)}^{0} c^{0}-\nabla_{X^{0}}^{0} \nabla_{Y^{0}}^{0} c^{0}+\nabla_{Y^{0}}^{0} \nabla_{X^{0}}^{0} c^{0} \\
= & l_{2}\left(s_{0} l_{2}\left(X^{0}, Y^{0}\right), c^{0}\right)-l_{2}\left(s_{0}\left(X^{0}\right), l_{2}\left(s_{0}\left(Y_{0}\right), c^{0}\right)\right)+l_{2}\left(s_{0}\left(Y^{0}\right), l_{2}\left(s_{0}\left(X_{0}\right), c^{0}\right)\right) \\
= & -l_{1} l_{3}\left(s_{0}\left(X^{0}\right), s_{0}\left(Y_{0}\right), c^{0}\right)+l_{2}\left(R^{0}\left(X^{0}, Y^{0}\right), c^{0}\right),
\end{aligned}
$$

which implies that

$$
\begin{equation*}
\nabla_{\mathrm{t}_{2}\left(X^{0}, Y^{0}\right)}^{0}-\nabla_{X^{0}}^{0} \nabla_{Y^{0}}^{0}+\nabla_{Y^{0}}^{0} \nabla_{X^{0}}^{0}=l_{1}^{C} \circ \Lambda\left(X^{0}, Y^{0}\right)+R^{0}\left(X^{0}, Y^{0}\right) \circ \varrho, \tag{4.22}
\end{equation*}
$$

and

$$
\begin{aligned}
& \nabla_{\mathrm{t}_{2}\left(X^{0}, Y^{0}\right)}^{1} c^{1}-\nabla_{X^{0}}^{1} \nabla_{Y^{0}}^{1} c^{1}+\nabla_{Y^{0}}^{1} \nabla_{X^{0}}^{1} c^{1} \\
= & l_{2}\left(s_{0} l_{2}\left(X^{0}, Y^{0}\right), c^{1}\right)-l_{2}\left(s_{0}\left(X^{0}\right), l_{2}\left(s_{0}\left(Y_{0}\right), c^{1}\right)\right)+l_{2}\left(s_{0}\left(Y^{0}\right), l_{2}\left(s_{0}\left(X_{0}\right), c^{1}\right)\right) \\
= & -l_{3}\left(s_{0}\left(X^{0}\right), s_{0}\left(Y^{0}\right), l_{1}\left(c^{1}\right)\right)+l_{2}\left(R^{0}\left(X^{0}, Y^{0}\right), c^{1}\right),
\end{aligned}
$$

which implies that

$$
\begin{equation*}
\nabla_{\mathrm{L}_{2}\left(X^{0}, Y^{0}\right)}^{1}-\nabla_{X^{0}}^{1} \nabla_{Y^{0}}^{1}+\nabla_{Y^{0}}^{1} \nabla_{X^{0}}^{1}=\Lambda\left(X^{0}, Y^{0}\right) \circ l_{1}^{C} . \tag{4.23}
\end{equation*}
$$

By (4.21), (4.22) and (4.23), we obtain

$$
\begin{equation*}
F^{0}\left(I_{2}\left(X^{0}, Y^{0}\right)\right)-\left[F^{0}\left(X^{0}\right), F^{0}\left(Y^{0}\right)\right]_{C}=\mathrm{d} F_{0}^{2}\left(X^{0}, Y^{0}\right) . \tag{4.24}
\end{equation*}
$$

By the equality

$$
l_{2}\left(s_{0}\left(X^{0}\right), l_{2}\left(s_{1}\left(Y^{1}\right), c^{0}\right)\right)+c . p .=\hat{l}_{3}\left(s_{0}\left(X^{0}\right), l_{1}\left(s_{1}\left(Y^{1}\right)\right), c^{0}\right),
$$

we obtain

$$
\begin{equation*}
\left[F^{0}\left(X^{0}\right), \Upsilon_{Y^{1}}^{2}\right]_{C}-\Upsilon_{1_{2}\left(X^{0}, Y^{1}\right)}^{2}=-\Lambda\left(X^{0}, 1_{1}\left(Y^{1}\right)\right)-R^{1}\left(X^{0}, Y^{1}\right) \circ \varrho . \tag{4.25}
\end{equation*}
$$

Furthermore, we have

$$
\begin{align*}
\Upsilon_{\mathrm{l}_{2}\left(X^{0}, Y^{1}\right)}^{1} & =s_{0} \mathrm{l}_{1}\left(\mathrm{I}_{2}\left(X^{0}, Y^{1}\right)\right)-\hat{l}_{1} s_{1}\left(\mathrm{I}_{2}\left(X^{0}, Y^{1}\right)\right) \\
& =s_{0} \mathrm{I}_{2}\left(X^{0}, \mathrm{l}_{1}\left(Y^{1}\right)\right)-\hat{l}_{1} \hat{l}_{2}\left(s_{0}\left(X^{0}\right), s_{1}\left(Y^{1}\right)\right)-\hat{l}_{1} R^{1}\left(X^{0}, Y^{1}\right) \\
& =s_{0} \mathrm{l}_{2}\left(X^{0}, \mathrm{l}_{1}\left(Y^{1}\right)\right)-\hat{l}_{2}\left(s_{0}\left(X^{0}\right), \hat{l}_{1} s_{1}\left(Y^{1}\right)\right)-l_{1}^{C} \circ R^{1}\left(X^{0}, Y^{1}\right) \\
& =s_{0} \mathrm{I}_{2}\left(X^{0}, \mathrm{l}_{1}\left(Y^{1}\right)\right)-\hat{l}_{2}\left(s_{0}\left(X^{0}\right), s_{0} \mathrm{I}_{1}\left(Y^{1}\right)-\Upsilon_{Y^{1}}^{1}\right)-l_{1}^{C} \circ R^{1}\left(X^{0}, Y^{1}\right) \\
& =\left[F^{0}\left(X^{0}\right), \Upsilon_{Y^{1}}^{1}\right]+R^{0}\left(X^{0}, \mathrm{l}_{1}\left(Y^{1}\right)\right)-l_{1}^{C} \circ R^{1}\left(X^{0}, Y^{1}\right) . \tag{4.26}
\end{align*}
$$

By (4.25) and (4.26), we deduce that

$$
\begin{equation*}
F^{1}\left(\mathrm{I}_{2}\left(X^{0}, Y^{1}\right)\right)-\left[F^{0}\left(X^{0}\right), F^{1}\left(Y^{1}\right)\right]_{C}=F_{0}^{2}\left(X^{0}, \mathrm{I}_{1}\left(Y^{1}\right)\right)-\mathrm{d} F_{1}^{2}\left(X^{0}, Y^{1}\right) . \tag{4.27}
\end{equation*}
$$

By straightforward computation, we have

$$
\begin{align*}
& R^{1}\left(\mathrm{I}_{1}\left(X^{1}\right), Y^{1}\right)-R^{1}\left(X^{1}, \mathrm{I}_{1}\left(Y^{1}\right)\right) \\
= & s_{1} \mathrm{l}_{2}\left(\mathrm{l}_{1}\left(X^{1}\right), Y^{1}\right)-\hat{l}_{2}\left(s_{0} \mathrm{I}_{1}\left(X^{1}\right), s_{1}\left(Y^{1}\right)\right) \\
& -s_{1} \mathrm{l}_{2}\left(X^{1}, \mathrm{I}_{1}\left(Y^{1}\right)\right)+\hat{l}_{2}\left(s_{1}\left(X^{1}\right), s_{0} \mathrm{l}_{1}\left(Y^{1}\right)\right) \\
= & \hat{l}_{2}\left(s_{1}\left(X^{1}\right), \hat{l}_{1} s_{1}\left(Y^{1}\right)\right)+\hat{l}_{2}\left(s_{1}\left(X^{1}\right), \Upsilon_{Y^{1}}^{1}\right)-\hat{l}_{2}\left(s_{0} \mathrm{I}_{1}\left(X^{1}\right), s_{1}\left(Y^{1}\right)\right) \\
= & -\hat{l}_{2}\left(\Upsilon_{X^{1}}^{1}, s_{1}\left(Y^{1}\right)\right)+\hat{l}_{2}\left(s_{1}\left(X^{1}\right), \Upsilon_{Y^{1}}^{1}\right) \\
= & {\left[\Upsilon_{X^{1}}^{1}+\Upsilon_{X^{1}}^{2}, \Upsilon_{Y^{1}}^{1}+\Upsilon_{Y^{1}}^{2}\right] . } \tag{4.28}
\end{align*}
$$

By the equality

$$
\hat{l}_{2}\left(s_{0}\left(X^{0}\right), \hat{l}_{2}\left(s_{0}\left(Y^{0}\right), s_{0}\left(Z^{0}\right)\right)\right)+c . p .=\hat{l}_{1} \hat{l}_{3}\left(s_{0}\left(X^{0}\right), s_{0}\left(Y^{0}\right), s_{0}\left(Z^{0}\right)\right),
$$

we deduce that

$$
\begin{align*}
& {\left[F^{0}\left(X^{0}\right), R^{0}\left(Y^{0}, Z^{0}\right)\right]_{C}+R^{0}\left(X^{0}, \mathrm{I}_{2}\left(Y^{0}, Z^{0}\right)\right)+\text { c.p. } } \\
= & \Upsilon_{1_{3}\left(X^{0}, Y^{0}, Z^{0}\right)}^{1}+l_{1}^{C} \circ \Xi\left(X^{0}, Y^{0}, Z^{0}\right) . \tag{4.29}
\end{align*}
$$

By the equality

$$
l_{2}\left(s_{0}\left(X^{0}\right), l_{3}\left(s_{0}\left(Y^{0}\right), s_{0}\left(Z^{0}\right), c^{0}\right)\right)-l_{3}\left(l_{2}\left(s_{0}\left(X^{0}\right), s_{0}\left(Y^{0}\right)\right), s_{0}\left(Z^{0}\right), c^{0}\right)+c . p .=0,
$$

we deduce that

$$
\begin{align*}
& -\left[F^{0}\left(X^{0}\right), \Lambda\left(Y^{0}, Z^{0}\right)\right]_{C}+\Lambda\left(\mathrm{I}_{2}\left(X^{0}, Y^{0}\right), Z^{0}\right)+c . p . \\
& \quad+\Upsilon_{1_{3}\left(X^{0}, Y^{0}, Z^{0}\right)}^{2}-\Xi\left(X^{0}, Y^{0}, Z^{0}\right) \circ \varrho=0 . \tag{4.30}
\end{align*}
$$

By (4.29) and (4.30), we obtain

$$
\begin{align*}
& {\left[F^{0}\left(X^{0}\right), F_{0}^{2}\left(Y^{0}, Z^{0}\right)\right]_{C}+F_{0}^{2}\left(X^{0}, \mathrm{I}_{2}\left(Y^{0}, Z^{0}\right)\right)+\text { c.p. } } \\
= & F^{1}\left(\mathrm{I}_{3}\left(X^{0}, Y^{0}, Z^{0}\right)\right)+\mathrm{d} F^{3}\left(X^{0}, Y^{0}, Z^{0}\right) . \tag{4.31}
\end{align*}
$$

Then by the equality

$$
\hat{l}_{2}\left(s_{0}\left(X^{0}\right), \hat{l}_{2}\left(s_{0}\left(Y^{0}\right), s_{1}\left(Z^{1}\right)\right)\right)+\text { c.p. }=\hat{l}_{3}\left(s_{0}\left(X^{0}\right), s_{0}\left(Y^{0}\right), \hat{l}_{1}\left(s_{1}\left(Z^{1}\right)\right)\right),
$$

we deduce that

$$
\begin{align*}
& {\left[F^{0}\left(X^{0}\right), R^{1}\left(Y^{0}, Z^{1}\right)\right]_{C}+\left[F^{0}\left(Y^{0}\right), R^{1}\left(Z^{1}, X^{0}\right)\right]_{C}+\left[\Upsilon_{Z^{1}}^{2}, R^{0}\left(X^{0}, Y^{0}\right)\right]_{C} } \\
& +R^{1}\left(X^{0}, \mathrm{I}_{2}\left(Y^{0}, Z^{1}\right)\right)+R^{1}\left(Y^{0}, \mathrm{I}_{2}\left(Z^{1}, X^{0}\right)\right)+R^{1}\left(Z^{1}, \mathrm{I}_{2}\left(X^{0}, Y^{0}\right)\right) \\
= & \Xi\left(X^{0}, Y^{0}, \mathrm{l}_{1}\left(Z^{1}\right)\right)-\left[\Lambda\left(X^{0}, Y^{0}\right), \Upsilon_{Z^{1}}^{1}\right]_{C} . \tag{4.32}
\end{align*}
$$

Finally, by the equality

$$
\begin{aligned}
& \left.\sum_{i=1}^{4}(-1)^{i+1} \hat{l}_{2}\left(s_{0}\left(X_{i}^{0}\right), \hat{l}_{3}\left(s_{0}\left(X_{1}^{0}\right), \cdots, \widehat{s_{0}\left(X_{i}^{0}\right.}\right), \cdots, s_{0}\left(X_{4}^{0}\right)\right)\right) \\
& +\sum_{i<j, k<l}(-1)^{i+j} \hat{l}_{3}\left(\hat{l}_{2}\left(s_{0}\left(X_{i}^{0}\right), s_{0}\left(X_{j}^{0}\right)\right), s_{0}\left(X_{k}^{0}\right), s_{0}\left(X_{l}^{0}\right)\right)=0,
\end{aligned}
$$

we deduce that

$$
\begin{align*}
& \sum_{i=1}^{4}(-1)^{i+1}\left(\left[F^{0}\left(X_{i}^{0}\right), \Xi\left(X_{1}^{0}, \cdots, \widehat{X_{i}^{0}}, \cdots, X_{4}^{0}\right)\right]_{C}\right. \\
& \left.+R^{1}\left(X_{i}^{0}, I_{3}\left(X_{1}^{0}, \cdots, \widehat{X_{i}^{0}}, \cdots, X_{4}^{0}\right)\right)\right) \\
& +\sum_{i<j}(-1)^{i+j}\left(\Xi\left(\mathrm{l}_{2}\left(X_{i}^{0}, X_{j}^{0}\right), X_{1}^{0}, \cdots, \widehat{X_{i}^{0}}, \cdots, \widehat{X_{j}^{0}}, \cdots, X_{4}^{0}\right)\right. \\
& \left.-\left[R^{0}\left(X_{i}^{0}, X_{j}^{0}\right), \Lambda\left(X_{1}^{0}, \cdots, \widehat{X_{i}^{0}}, \cdots, \widehat{X_{j}^{0}}, \cdots, X_{4}^{0}\right)\right]_{C}\right)=0 \tag{4.33}
\end{align*}
$$

By (4.16), (4.20), (4.24), (4.27), (4.28), (4.31)-(4.33), we deduce that $\left(F^{0}, F^{1}, F_{0}^{2}, F_{1}^{2}, F^{3}\right)$ is a morphism from the split Lie 2-algebroid ( $A_{-1}, A_{0}, \mathfrak{a}, \mathfrak{l}_{1}, \mathfrak{l}_{2}, \mathfrak{l}_{3}$ ) to the strict split Lie 3-algebroid

$$
\left(\operatorname{End}^{-2}(\mathcal{E}), \operatorname{End}^{-1}(\mathcal{E}), \mathfrak{D}_{\pi}(\mathcal{E}), \mathfrak{p}, \mathrm{d},[\cdot, \cdot]_{C}\right)
$$

Conversely, let $\left(A_{-1}, A_{0}, \mathfrak{a}, \mathrm{I}_{1}, \mathrm{I}_{2}, \mathrm{I}_{3}\right)$ be a split Lie 2-algebroid and $\left(F^{0}, F^{1}, F_{0}^{2}, F_{1}^{2}, F^{3}\right)$ a flat superconnection on the 3-term complex $C_{-1} \xrightarrow{l_{1}^{C}} C_{0} \xrightarrow{\varrho} B$. Then we can obtain a VB-Lie 2-algebroid structure on the split graded double vector bundle $\left(\begin{array}{cc}A_{-1} \oplus B \oplus C_{-1} ; & A_{-1}, B ; \\ A_{0} \oplus B \oplus C_{0} ; & A_{0}, B ;\end{array}\right)$ M . We leave the details to readers. The proof is finished.

## 5. VB-CLWX 2-algebroids

In this section, first we recall the notion of a CLWX 2-algebroid. Then we explore what is a metric graded double vector bundle, and introduce the notion of a VB-CLWX 2-algebroid, which can be viewed as the categorification of a VB-Courant algebroid introduced in [32].

As a model for "Leibniz algebras that satisfy Jacobi identity up to all higher homotopies", the notion of a strongly homotopy Leibniz algebra, or a $\operatorname{Lod}_{\infty}$-algebra was given in [36] by Livernet, which was further studied by Ammar and Poncin in [3]. In [50], the authors introduced the notion of a Leibniz 2-algebra, which is the categorification of a Leibniz algebra, and proved that the category of Leibniz 2-algebras and the category of 2-term $\operatorname{Lod}_{\infty}$-algebras are equivalent. Due to this reason, a 2 -term $\operatorname{Lod}_{\infty}$-algebra will be called a Leibniz 2-algebra directly in the sequel.

Definition 5.1. ([34]) A CLWX 2-algebroid is a graded vector bundle $\mathcal{E}=E_{-1} \oplus E_{0}$ over $M$ equipped with a non-degenerate graded symmetric bilinear form $S$ on $\mathcal{E}$, a bilinear operation $\diamond: \Gamma\left(E_{-i}\right) \times$ $\Gamma\left(E_{-j}\right) \longrightarrow \Gamma\left(E_{-(i+j)}\right), 0 \leq i+j \leq 1$, which is skewsymmetric on $\Gamma\left(E_{0}\right) \times \Gamma\left(E_{0}\right)$, an $E_{-1}$-valued 3-form $\Omega$ on $E_{0}$, two bundle maps $\partial: E_{-1} \longrightarrow E_{0}$ and $\rho: E_{0} \longrightarrow T M$, such that $E_{-1}$ and $E_{0}$ are isotropic and the following axioms are satisfied:
(i) $\left(\Gamma\left(E_{-1}\right), \Gamma\left(E_{0}\right), \partial, \diamond, \Omega\right)$ is a Leibniz 2-algebra;
(ii) for all $e \in \Gamma(\mathcal{E}), e \diamond e=\frac{1}{2} \mathcal{D} S(e, e)$, where $\mathcal{D}: C^{\infty}(M) \longrightarrow \Gamma\left(E_{-1}\right)$ is defined by

$$
\begin{equation*}
S\left(\mathcal{D} f, e^{0}\right)=\rho\left(e^{0}\right)(f), \quad \forall f \in C^{\infty}(M), e^{0} \in \Gamma\left(E_{0}\right) ; \tag{5.1}
\end{equation*}
$$

(iii) for all $e_{1}^{1}, e_{2}^{1} \in \Gamma\left(E_{-1}\right), S\left(\partial\left(e_{1}^{1}\right), e_{2}^{1}\right)=S\left(e_{1}^{1}, \partial\left(e_{2}^{1}\right)\right)$;
(iv) for all $e_{1}, e_{2}, e_{3} \in \Gamma(\mathcal{E}), \rho\left(e_{1}\right) S\left(e_{2}, e_{3}\right)=S\left(e_{1} \diamond e_{2}, e_{3}\right)+S\left(e_{2}, e_{1} \diamond e_{3}\right)$;
(v) for all $e_{1}^{0}, e_{2}^{0}, e_{3}^{0}, e_{4}^{0} \in \Gamma\left(E_{0}\right), S\left(\Omega\left(e_{1}^{0}, e_{2}^{0}, e_{3}^{0}\right), e_{4}^{0}\right)=-S\left(e_{3}^{0}, \Omega\left(e_{1}^{0}, e_{2}^{0}, e_{4}^{0}\right)\right)$.

Denote a CLWX 2-algebroid by ( $E_{-1}, E_{0}, \partial, \rho, S, \diamond, \Omega$ ), or simply by $\mathcal{E}$. Since the section space of a CLWX 2-algebroid is a Leibniz 2-algebra, the section space of a Courant algebroid is a Leibniz algebra and Leibniz 2-algebras are the categorification of Leibniz algebras, we can view CLWX 2-algebroids as the categorification of Courant algebroids.

As a higher analogue of Roytenberg's result about symplectic NQ manifolds of degree 2 and Courant algebroids ([45]), we have

Theorem 5.2. ([34]) Let $\left(T^{*}[3] A^{*}[2], \Theta\right)$ be a symplectic $N Q$ manifold of degree 3, where $A$ is an ordinary vector bundle and $\Theta$ is a degree 4 function on $T^{*}[3] A^{*}[2]$ satisfying $\{\Theta, \Theta\}=0$. Here $\{\cdot, \cdot\}$ is the canonical Poisson bracket on $T^{*}[3] A^{*}[2]$. Then ( $A^{*}[1], A, \partial, \rho, S, \diamond, \Omega$ ) is a CLWX 2-algebroid, where the bilinear form $S$ is given by

$$
S(X+\alpha, Y+\beta)=\langle X, \beta\rangle+\langle Y, \alpha\rangle, \quad \forall X, Y \in \Gamma(A), \alpha, \beta \in \Gamma\left(A^{*}\right),
$$

and $\partial, \rho, \diamond$ and $\Omega$ are given by derived brackets. More precisely, we have

$$
\begin{array}{rlrl}
\partial \alpha & =\{\alpha, \Theta\}, & & \forall \alpha \in \Gamma\left(A^{*}\right), \\
\rho(X)(f) & =\{f,\{X, \Theta\}\}, & & \forall X \in \Gamma(A), f \in C^{\infty}(M), \\
X \diamond Y & =\{Y,\{X, \Theta\}\}, & & \forall X, Y \in \Gamma(A), \\
X \diamond \alpha & =\{\alpha,\{X, \Theta\}\}, & & \forall X \in \Gamma(A), \alpha \in \Gamma\left(A^{*}\right), \\
\alpha \diamond X & =-\{X,\{\alpha, \Theta\}\}, & & \forall X \in \Gamma(A), \alpha \in \Gamma\left(A^{*}\right), \\
\Omega(X, Y, Z) & =\{Z,\{Y,\{X, \Theta\}\}\}, & \forall X, Y, Z \in \Gamma(A) .
\end{array}
$$

See [27,53] for more information of derived brackets. Note that various kinds of geometric structures were obtained in the study of QP manifolds of degree 3, e.g. Grutzmann's $H$-twisted Lie algebroids [21] and Ikeda-Uchino's Lie algebroids up to homotopy [23].
Definition 5.3. A metric graded double vector bundle is a graded double vector bundle $\left(\begin{array}{ccc}D_{-1} ; & A_{-1}, B ; & M \\ D_{0} ; & A_{0}, B ; & M\end{array}\right)$ equipped with a degree 1 nondegenerate graded symmetric bilinear form $S$ on the graded bundle $D_{-1}^{B} \oplus D_{0}^{B}$ such that it induces an isomorphism between graded double vector bundles

where $\star B$ means dual over $B$.
Given a metric graded double vector bundle, we have

$$
C_{0} \cong A_{-1}^{*}, \quad C_{-1} \cong A_{0}^{*} .
$$

In the sequel, we will always identify $C_{0}$ with $A_{-1}^{*}, C_{-1}$ with $A_{0}^{*}$. Thus, a metric graded double vector bundle is of the following form:


Now we are ready to put a CLWX 2-algebroid structure on a graded double vector bundle.

Definition 5.4. A VB-CLWX 2-algebroid is a metric graded double vector bundle

$$
\left(\left(\begin{array}{ccc}
D_{-1} ; & A_{-1}, B ; & M \\
D_{0} ; & A_{0}, B ; & M
\end{array}\right), S\right)
$$

equipped with a CLWX 2 -algebroid structure ( $D_{-1}^{B}, D_{0}^{B}, \partial, \rho, S, \diamond, \Omega$ ) such that
(i) $\partial$ is linear, i.e. there exists a unique bundle map $\bar{\partial}: A_{-1} \longrightarrow A_{0}$ such that $\partial: D_{-1} \longrightarrow D_{0}$ is a double vector bundle morphism over $\bar{\partial}: A_{-1} \longrightarrow A_{0}$ (see Diagram (iii));
(ii) the anchor $\rho$ is a linear, i.e. there exists a unique bundle map $\bar{\rho}: A_{0} \longrightarrow T M$ such that $\rho: D_{0} \longrightarrow$ $T B$ is a double vector bundle morphism over $\bar{\rho}: A_{0} \longrightarrow T M$ (see Diagram (iv));


Diagram (iii)


Diagram (iv)
(iii) the operation $\diamond$ is linear;
(iv) $\Omega$ is linear.

Since a CLWX 2-algebroid can be viewed as the categorification of a Courant algebroid, we can view a VB-CLWX 2-algebroid as the categorification of a VB-Courant algebroid.
Example 1. Let $\left(A_{-1}, A_{0}, a, l_{1}, l_{2}, l_{3}\right)$ be a Lie 2-algebroid. Let $E_{0}=A_{0} \oplus A_{-1}^{*}, E_{-1}=A_{-1} \oplus A_{0}^{*}$ and $\mathcal{E}=E_{0} \oplus E_{-1}$. Then $\left(E_{-1}, E_{0}, \partial, \rho, S, \diamond, \Omega\right)$ is a CLWX 2-algebroid, where $\partial: E_{-1} \longrightarrow E_{0}$ is given by

$$
\partial\left(X^{1}+\alpha^{0}\right)=l_{1}\left(X^{1}\right)+l_{1}^{*}\left(\alpha^{0}\right), \quad \forall X^{1} \in \Gamma\left(A_{-1}\right), \alpha^{0} \in \Gamma\left(A_{0}^{*}\right),
$$

$\rho: E_{0} \longrightarrow T M$ is given by

$$
\rho\left(X^{0}+\alpha^{1}\right)=a\left(X^{0}\right), \quad \forall X^{0} \in \Gamma\left(A_{0}\right), \alpha^{1} \in \Gamma\left(A_{-1}^{*}\right),
$$

the symmetric bilinear form $S=(\cdot, \cdot)_{+}$is given by

$$
\left(X^{0}+\alpha^{1}+X^{1}+\alpha^{0}, Y^{0}+\beta^{1}+Y^{1}+\beta^{0}\right)_{+}=\left\langle X^{0}, \beta^{0}\right\rangle+\left\langle Y^{0}, \alpha^{0}\right\rangle+\left\langle X^{1}, \beta^{1}\right\rangle+\left\langle Y^{1}, \alpha^{1}\right\rangle
$$

the operation $\diamond$ is given by

$$
\left\{\begin{array}{l}
\left(X^{0}+\alpha^{1}\right) \diamond\left(Y^{0}+\beta^{1}\right)=l_{2}\left(X^{0}, Y^{0}\right)+L_{X^{0}}^{0} \beta^{1}-L_{\gamma^{0}}^{0} \alpha^{1},  \tag{5.2}\\
\left(X^{0}+\alpha^{1}\right) \diamond\left(X^{1}+\alpha^{0}\right)=l_{2}\left(X^{0}, X^{1}\right)+L_{X^{0}}^{0} 0+\iota_{X^{1}} \delta\left(\alpha^{1}\right), \\
\left(X^{1}+\alpha^{0}\right) \diamond\left(X^{0}+\alpha^{1}\right)=l_{2}\left(X^{1}, X^{0}\right)+L_{X^{1}}^{1} 1^{1}-\iota_{X^{0}} \delta\left(\alpha^{0}\right),
\end{array}\right.
$$

and the $E_{-1}$-valued 3-form $\Omega$ is defined by

$$
\Omega\left(X^{0}+\alpha^{1}, Y^{0}+\beta^{1}, Z^{0}+\zeta^{1}\right)=l_{3}\left(X^{0}, Y^{0}, Z^{0}\right)+L_{X^{0}, Y^{0}}^{3} \zeta^{1}+L_{Z^{0}, X^{0}}^{3} \beta^{1}+L_{Y^{0}, Z^{0}}^{3} \alpha^{1},
$$

where $L^{0}, L^{1}, L^{3}$ are given by (3.1). It is straightforward to see that this CLWX 2-algebroid gives rise to a VB-CLWX 2-algebroid:


Example 2. For any manifold $M,\left(T^{*}[1] M, T M, \partial=0, \rho=\mathrm{id}, S, \diamond, \Omega=0\right)$ is a CLWX 2-algebroid, where $S$ is the natural symmetric pairing between $T M$ and $T^{*} M$, and $\diamond$ is the standard Dorfman bracket given by

$$
\begin{equation*}
(X+\alpha) \diamond(Y+\beta)=[X, Y]+L_{X} \beta-\iota_{Y} d \alpha, \quad \forall X, Y \in \mathfrak{X}(M), \alpha, \beta \in \Omega^{1}(M) . \tag{5.3}
\end{equation*}
$$

See [34, Remark 3.4] for more details. In particular, for any vector bundle $E$, $\left(T^{*} E^{*}, T E^{*}, \partial=0, \rho=\right.$ $\mathrm{id}, S, \diamond, \Omega=0$ ) is a CLWX 2-algebroid, which gives rise to a VB-CLWX 2-algebroid:


We have a higher analogue of Theorem 2.3:
Theorem 5.5. There is a one-to-one correspondence between split Lie 3-algebroids and split VB-CLWX 2-algebroids.
Proof. Let $\mathcal{A}=\left(A_{-2}, A_{-1}, A_{0}, a, l_{1}, l_{2}, l_{3}, l_{4}\right)$ be a split Lie 3-algebroid. Then $T^{*}[3] \mathcal{A}[1]$ is a symplectic NQ manifold of degree 3 . Note that

$$
T^{*}[3] \mathcal{A}[1]=T^{*}[3]\left(A_{0} \times_{M} A_{-1}^{*} \times_{M} A_{-2}^{*}\right)[1],
$$

where $A_{0} \times_{M} A_{-1}^{*} \times_{M} A_{-2}^{*}$ is viewed as a vector bundle over the base $A_{-2}^{*}$ and $A_{-1} \times_{M} A_{0}^{*} \times_{M} A_{-2}^{*}$ is its dual bundle. Denote by ( $x^{i}, \mu_{j}, \xi^{k}, \theta_{l}, p_{i}, \mu^{j}, \xi_{k}, \theta^{l}$ ) a canonical (Darboux) coordinate on $T^{*}[3]\left(A_{0} \times_{M} A_{-1}^{*} \times_{M}\right.$ $\left.A_{-2}^{*}\right)[1]$, where $x^{i}$ is a smooth coordinate on $M, \mu_{j} \in \Gamma\left(A_{-2}\right)$ is a fibre coordinate on $A_{-2}^{*}, \xi^{k} \in \Gamma\left(A_{0}^{*}\right)$ is a fibre coordinate on $A_{0}, \theta_{l} \in \Gamma\left(A_{-1}\right)$ is a fibre coordinate on $A_{-1}^{*}$ and ( $p_{i}, \mu^{j}, \xi_{k}, \theta^{l}$ ) are the momentum coordinates for $\left(x^{i}, \mu_{j}, \xi^{k}, \theta_{l}\right)$. About their degrees, we have

$$
\left(\begin{array}{cccccccc}
x^{i} & \mu_{j} & \xi^{k} & \theta_{l} & p_{i} & \mu^{j} & \xi_{k} & \theta^{l} \\
0 & 0 & 1 & 1 & 3 & 3 & 2 & 2
\end{array}\right)
$$

The symplectic structure is given by

$$
\omega=d x^{i} d p_{i}+d \mu_{j} d \mu^{j}+d \xi^{k} d \xi_{k}+d \theta_{l} d \theta^{l},
$$

which is degree 3. The Lie 3-algebroid structure gives rise to a degree 4 function $\Theta$ satisfying $\{\Theta, \Theta\}=0$. By Theorem 5.2, we obtain a CLWX 2-algebroid ( $D_{-1}, D_{0}, \partial, \rho, S, \diamond, \Omega$ ), where $D_{-1}=A_{-1} \times{ }_{M} A_{0}^{*} \times{ }_{M} A_{-2}^{*}$
and $D_{0}=A_{0} \times_{M} A_{-1}^{*} \times_{M} A_{-2}^{*}$ are vector bundles over $A_{-2}^{*}$. Obviously, they give the graded double vector bundle

$$
\left(\begin{array}{ccc}
A_{-1} \times_{M} A_{0}^{*} \times_{M} A_{-2}^{*} ; & A_{-1}, A_{-2}^{*} ; & M \\
A_{0} \times_{M} A_{-1}^{*} \times_{M} A_{-2}^{*} ; & A_{0}, A_{-2}^{*} ; & M
\end{array}\right) .
$$

The section space $\Gamma_{A_{-2}^{*}}\left(D_{0}\right)$ are generated by $\Gamma\left(A_{-1}^{*}\right)$ (the space of core sections) and $\Gamma\left(A_{-2} \otimes A_{-1}^{*}\right) \oplus \Gamma\left(A_{0}\right)$ (the space of linear sections) as $C^{\infty}\left(A_{-2}^{*}\right)$-module. Similarly, The section space $\Gamma_{A_{-2}^{*}}\left(D_{-1}\right)$ are generated by $\Gamma\left(A_{0}^{*}\right)$ and $\Gamma\left(A_{-2} \otimes A_{0}^{*}\right) \oplus \Gamma\left(A_{-1}\right)$ as $C^{\infty}\left(A_{-2}^{*}\right)$-module. Thus, in the sequel we only consider core sections and linear sections.

The graded symmetric bilinear form $S$ is given by

$$
\begin{aligned}
S\left(e^{0}, e^{1}\right) & =S\left(X^{0}+\psi^{1}+\alpha^{1}, X^{1}+\psi^{0}+\alpha^{0}\right) \\
& =\left\langle\alpha_{1}, X^{1}\right\rangle+\left\langle\alpha^{0}, X_{0}\right\rangle+\psi^{1}\left(X^{1}\right)+\psi^{0}\left(X^{0}\right),
\end{aligned}
$$

for all $e^{0}=X^{0}+\psi^{1}+\alpha^{1} \in \Gamma_{A_{-2}^{*}}\left(D_{0}\right)$ and $e^{1}=X^{1}+\psi^{0}+\alpha^{0} \in \Gamma_{A_{-2}^{*}}\left(D_{-1}\right)$, where $X^{i} \in \Gamma\left(A_{-i}\right)$, $\psi^{i} \in \Gamma\left(A_{-2} \otimes A_{-i}^{*}\right)$ and $\alpha^{i} \in \Gamma\left(A_{-i}^{*}\right)$. Then it is obvious that

$$
\left(\left(\begin{array}{ccc}
A_{-1} \times_{M} A_{0}^{*} \times_{M} A_{-2}^{*} ; & A_{-1}, A_{-2}^{*} ; & M \\
A_{0} \times_{M} A_{-1}^{*} \times_{M} A_{-2}^{*} ; & A_{0}, A_{-2}^{*} ; & M
\end{array}\right), S\right)
$$

is a metric graded double vector bundle.
The bundle map $\partial: D_{-1} \longrightarrow D_{0}$ is given by

$$
\partial\left(X^{1}+\psi^{0}+\alpha^{0}\right)=l_{1}\left(X^{1}\right)+\left.l_{2}\left(X^{1}, \cdot\right)\right|_{A_{-1}}+\psi^{0} \circ l_{1}+l_{1}^{*}\left(\alpha^{0}\right) .
$$

Thus, $\partial: D_{-1} \longrightarrow D_{0}$ is a double vector bundle morphism over $l_{1}: A_{-1} \longrightarrow A_{0}$.
Note that functions on $A_{-2}^{*}$ are generated by fibrewise constant functions $C^{\infty}(M)$ and fibrewise linear functions $\Gamma\left(A_{-2}\right)$. For all $f \in C^{\infty}(M)$ and $X^{2} \in \Gamma\left(A_{-2}\right)$, the anchor $\rho: D_{0} \longrightarrow T A_{-2}^{*}$ is given by

$$
\rho\left(X^{0}+\psi^{1}+\alpha^{1}\right)\left(f+X^{2}\right)=a\left(X^{0}\right)(f)+\left\langle\alpha^{1}, l_{1}\left(X^{2}\right)\right\rangle+l_{2}\left(X^{0}, X^{2}\right)+\psi^{1}\left(l_{1}\left(X^{2}\right)\right) .
$$

Therefore, for a linear section $X^{0}+\psi^{1} \in \Gamma_{A_{-2}^{*}}^{l}\left(D_{0}\right)$, the image $\rho\left(X^{0}+\psi^{1}\right)$ is a linear vector field and for a core section $\alpha^{1} \in \Gamma\left(A_{-1}^{*}\right)$, the image $\rho\left(\alpha^{1}\right)$ is a constant vector field. Thus, $\rho$ is linear.

The bracket operation $\diamond$ is given by

$$
\begin{aligned}
& \left(X^{0}+\psi^{1}+\alpha^{1}\right) \diamond\left(Y^{0}+\phi^{1}+\beta^{1}\right) \\
= & l_{2}\left(X^{0}, Y^{0}\right)+\left.l_{3}\left(X^{0}, Y^{0}, \cdot\right)\right|_{A_{-1}}+l_{2}\left(X^{0}, \phi^{1}(\cdot)\right)-\left.\phi^{1} \circ l_{2}\left(X^{0}, \cdot\right)\right|_{A_{-1}}+L_{X_{0}}^{0} \beta^{1} \\
& +\left.\psi^{1} \circ l_{2}\left(Y^{0}, \cdot\right)\right|_{A_{-1}}-l_{2}\left(Y^{0}, \psi^{1}(\cdot)\right)+\psi^{1} \circ l_{1} \circ \phi^{1}-\phi^{1} \circ l_{1} \circ \psi^{1}-\beta^{0} \circ l_{1} \circ \psi^{1} \\
& -L_{Y_{0}}^{0} \alpha^{1}+\alpha^{1} \circ l_{1} \circ \phi^{1}, \\
& \left(X^{0}+\psi^{1}+\alpha^{1}\right) \diamond\left(Y^{1}+\phi^{0}+\beta^{0}\right) \\
= & l_{2}\left(X^{0}, Y^{1}\right)+\left.l_{3}\left(X^{0}, \cdot, Y^{1}\right)\right|_{A_{0}}+l_{2}\left(X^{0}, \phi^{0}(\cdot)\right)-\left.\phi^{0} \circ l_{2}\left(X^{0}, \cdot\right)\right|_{A_{0}}+L_{X_{0}^{0}}^{0} \beta^{0} \\
& -\left.\psi^{1} l_{2}\left(\cdot, Y^{1}\right)\right|_{A_{0}}+\delta\left(\psi^{1}\left(Y^{1}\right)\right)+\psi^{1} \circ l_{1} \circ \phi^{0}+l_{Y_{1}} \delta \alpha^{1}+\alpha^{1} \circ l_{1} \circ \phi^{0}, \\
& \left(Y^{1}+\phi^{0}+\beta^{0} \diamond\left(X^{0}+\psi^{1}+\alpha^{1}\right)\right. \\
= & l_{2}\left(Y^{1}, X^{0}\right)-\left.l_{3}\left(X^{0}, \cdot, Y^{1}\right)\right|_{A_{0}}-l_{2}\left(X^{0}, \phi^{0}(\cdot)\right)+\left.\phi^{0} \circ l_{2}\left(X^{0}, \cdot\right)\right|_{A_{0}}+\delta\left(\phi^{0}\left(X^{0}\right)\right)
\end{aligned}
$$

$$
-\iota_{X^{0}} \delta \beta^{0}+\left.\psi^{1} l_{2}\left(\cdot, Y^{1}\right)\right|_{A_{0}}-\psi^{1} \circ l_{1} \circ \phi^{0}+L_{Y_{1}}^{1} \alpha^{1}-\alpha^{1} \circ l_{1} \circ \phi^{0} .
$$

Then it is straightforward to see that the operation $\diamond$ is linear.
Finally, $\Omega$ is given by

$$
\begin{aligned}
& \Omega\left(X^{0}+\psi^{1}+\alpha^{1}, Y^{0}+\phi^{1}+\beta^{1}, Z^{0}+\varphi^{1}+\gamma^{1}\right) \\
= & l_{3}\left(X^{0}, Y^{0}, Z^{0}\right)+l_{4}\left(X^{0}, Y^{0}, Z^{0}, \cdot\right) \\
& -\left.\varphi^{1} \circ l_{3}\left(X^{0}, Y^{0}, \cdot\right)\right|_{A_{0}}-\left.\phi^{1} \circ l_{3}\left(Z^{0}, X^{0}, \cdot\right)\right|_{A_{0}}-\left.\psi^{1} \circ l_{3}\left(Y^{0}, Z^{0}, \cdot\right)\right|_{A_{0}} \\
& +L_{X^{0}, Y^{0}}^{3} \gamma^{1}+L_{Y^{0}, Z^{0}}^{3} \alpha^{1}+L_{Z^{0}, X^{0}}^{3} \beta^{1},
\end{aligned}
$$

which implies that $\Omega$ is also linear.
Thus, a split Lie 3-algebroid gives rise to a split VB-CLWX 2-algebroid:


Conversely, given a split VB-CLWX 2-algebroid:

where $D_{-1}=A_{-1} \times_{M} A_{0}^{*} \times_{M} B$ and $D_{0}=A_{0} \times_{M} A_{-1}^{*} \times_{M} B$, then we can deduce that the corresponding symplectic NQ-manifold of degree 3 is $T^{*}[3] \mathcal{A}[1]$, where $\mathcal{A}=A_{0} \oplus A_{-1} \oplus B$ is a graded vector bundle in which $B$ is of degree -2 , and the $Q$-structure gives rise to a Lie 3 -algebroid structure on $\mathcal{A}$. We omit details.

Remark 3. Since every double vector bundle is splitable, every VB-CLWX 2-algebroid is isomorphic to a split one. Meanwhile, by choosing a splitting, we obtain a split Lie 3-algebroid from an NQ-manifold of degree 3 (Lie 3-algebroid). Thus, we can enhance the above result to be a one-to-one correspondence between Lie 3-algebroids and VB-CLWX 2-algebroids. We omit such details.

Recall that the tangent prolongation of a Courant algebroid is a VB-Courant algebroid ([32, Proposition 3.4.1]). Now we show that the tangent prolongation of a CLWX 2-algebroid is a VB-CLWX 2-algebroid. The notations used below is the same as the ones used in Section 3.

Proposition 3. Let $\left(E_{-1}, E_{0}, \partial, \rho, S, \diamond, \Omega\right)$ be a CLWX 2-algebroid. Then we obtain that $\left(T E_{-1}, T E_{0}, \widetilde{\partial}, \widetilde{\rho}, \widetilde{S}, \widetilde{\diamond}, \widetilde{\Omega}\right)$ is a CLWX 2-algebroid over $T M$, where the bundle map $\widetilde{\partial}: T E_{-1} \longrightarrow T E_{0}$ is given by

$$
\widetilde{\partial}\left(\sigma_{T}^{1}\right)=\partial\left(\sigma^{1}\right)_{T}, \quad \widetilde{\partial}\left(\sigma_{C}^{1}\right)=\partial\left(\sigma^{1}\right)_{C},
$$

the bundle map $\widetilde{\rho}: T E_{0} \longrightarrow T T M$ is given by

$$
\widetilde{\rho}\left(\sigma_{T}^{0}\right)=\rho\left(\sigma^{0}\right)_{T}, \quad \widetilde{\rho}\left(\sigma_{C}^{0}\right)=\rho\left(\sigma^{0}\right)_{C},
$$

the degree 1 bilinear form $\widetilde{S}$ is given by

$$
\begin{aligned}
& \widetilde{S}\left(\sigma_{T}^{0}, \tau_{T}^{1}\right)=S\left(\sigma^{0}, \tau^{1}\right)_{T}, \widetilde{S}\left(\sigma_{T}^{0}, \tau_{C}^{1}\right)=S\left(\sigma^{0}, \tau^{1}\right)_{C} \\
& \widetilde{S}\left(\sigma_{C}^{0}, \tau_{T}^{1}\right)=S\left(\sigma^{0}, \tau^{1}\right)_{C}, \widetilde{S}\left(\sigma_{C}^{0}, \tau_{C}^{1}\right)=0
\end{aligned}
$$

the bilinear operation $\widetilde{\diamond}$ is given by

$$
\begin{aligned}
& \sigma_{T}^{0} \widetilde{\diamond} \tau_{T}^{0}=\left(\sigma^{0} \diamond \tau^{0}\right)_{T}, \quad \sigma_{T}^{0} \stackrel{\rightharpoonup}{\diamond} \tau_{C}^{0}=-\tau_{C}^{0} \stackrel{\rightharpoonup}{\Delta} \sigma_{T}^{0}=\left(\sigma^{0} \diamond \tau^{0}\right)_{C}, \quad \sigma_{C}^{0} \widetilde{\diamond} \tau_{C}^{0}=0, \\
& \sigma_{T}^{0} \stackrel{\diamond}{\Delta} \tau_{T}^{1}=\left(\sigma^{0} \diamond \tau^{1}\right)_{T}, \quad \sigma_{T}^{0} \stackrel{\rightharpoonup}{\diamond} \tau_{C}^{1}=\sigma_{C}^{0} \stackrel{\rightharpoonup}{\diamond} \tau_{T}^{1}=\left(\sigma^{0} \diamond \tau^{1}\right)_{C}, \quad \sigma_{C}^{0} \stackrel{\rightharpoonup}{\diamond} \tau_{C}^{1}=0, \\
& \tau_{T}^{1} \widetilde{\diamond} \sigma_{T}^{0}=\left(\tau^{1} \diamond \sigma^{0}\right)_{T}, \quad \tau_{C}^{1} \widetilde{\diamond} \sigma_{T}^{0}=\tau_{T}^{1} \widetilde{\diamond} \sigma_{C}^{0}=\left(\tau^{1} \diamond \sigma^{0}\right)_{C}, \quad \tau_{C}^{1} \widetilde{\diamond} \sigma_{C}^{0}=0,
\end{aligned}
$$

and $\widetilde{\Omega}: \wedge^{3} T E_{0} \longrightarrow T E_{-1}$ is given by

$$
\widetilde{\Omega}\left(\sigma_{T}^{0}, \tau_{T}^{0}, \varsigma_{T}^{0}\right)=\Omega\left(\sigma^{0}, \tau^{0}, \varsigma^{0}\right)_{T}, \quad \widetilde{\Omega}\left(\sigma_{T}^{0}, \tau_{T}^{0}, \varsigma_{C}^{0}\right)=\Omega\left(\sigma^{0}, \tau^{0}, \varsigma^{0}\right)_{C}, \quad \widetilde{\Omega}\left(\sigma_{T}^{0}, \tau_{C}^{0}, \varsigma_{C}^{0}\right)=0,
$$

for all $\sigma^{0}, \tau^{0}, \varsigma^{0} \in \Gamma\left(E_{0}\right)$ and $\sigma^{1}, \tau^{1} \in \Gamma\left(E_{-1}\right)$.
Moreover, we have the following VB-CLWX 2-algebroid:


Proof. Since ( $E_{-1}, E_{0}, \partial, \rho, S, \diamond, \Omega$ ) is a CLWX 2-algebroid, it is straightforward to deduce that ( $T E_{-1}, T E_{0}, \widetilde{\partial}, \widetilde{\rho}, \widetilde{,}, \widetilde{\diamond}, \widetilde{\Omega}$ ) is a CLWX 2 -algebroid over $T M$. Moveover, it is obvious that $\widetilde{\partial}, \widetilde{\rho}, \widetilde{S}, \widetilde{\diamond}, \widetilde{\Omega}$ are all linear, which implies that we have a VB-CLWX 2-algebroid.

## 6. E-CLWX 2-algebroid

In this section, we introduce the notion of an E-CLWX 2-algebroid as the categorification of an $E$-Courant algebroid introduced in [11]. We show that associated to a VB-CLWX 2-algebroid, there is an $E$-CLWX 2-algebroid structure on the corresponding graded fat bundle.

There is an $E$-valued pairing $\langle\cdot, \cdot\rangle_{E}$ between the jet bundle $\mathfrak{J} E$ and the first order covariant differential operator bundle $\mathfrak{D} E$ defined by

$$
\langle\mu, \mathfrak{D}\rangle_{E} \triangleq \mathfrak{D}(u), \quad \forall \mathfrak{D} \in(\mathfrak{D} E)_{m}, \mu \in(\mathfrak{J} E)_{m}, u \in \Gamma(E) \text { statisfying } \mu=[u]_{m} .
$$

Definition 6.1. Let $E$ be a vector bundle. An $E$-CLWX 2 -algebroid is a 6 -tuple ( $\mathcal{K}, \partial, \rho, \mathcal{S}, \diamond, \Omega$ ), where $\mathcal{K}=K_{-1} \oplus K_{0}$ is a graded vector bundle over $M$ and

- $\partial: K_{-1} \longrightarrow K_{0}$ is a bundle map;
- $\mathcal{S}: \mathcal{K} \otimes \mathcal{K} \rightarrow E$ is a surjective graded symmetric nondegenerate $E$-valued pairing of degree 1 , which induces an embedding: $\mathcal{K} \hookrightarrow \operatorname{Hom}(\mathcal{K}, E)$;
- $\rho: K_{0} \rightarrow \mathfrak{D E}$ is a bundle map, called the anchor, such that $\rho^{\star}(\mathfrak{J} E) \subset K_{-1}$, i.e.

$$
\mathcal{S}\left(\rho^{\star}(\mu), e^{0}\right)=\left\langle\mu, \rho\left(e^{0}\right)\right\rangle_{E}, \forall \mu \in \Gamma(\mathfrak{J} E), e^{0} \in \Gamma\left(K_{0}\right)
$$

$\bullet \diamond: \Gamma\left(K_{-i}\right) \times \Gamma\left(K_{-j}\right) \longrightarrow \Gamma\left(K_{-(i+j)}\right), 0 \leq i+j \leq 1$ is an $\mathbb{R}$-bilinear operation;

- $\Omega: \wedge^{3} K_{0} \longrightarrow K_{-1}$ is a bundle map,
such that the following properties hold:
(E1) $(\Gamma(\mathcal{K}), \partial, \diamond, \Omega)$ is a Leibniz 2-algebra;
(E2) for all $e \in \Gamma(\mathcal{K}), e \diamond e=\frac{1}{2} \mathcal{D S}(e, e)$, where $\mathcal{D}: \Gamma(E) \longrightarrow \Gamma\left(K_{-1}\right)$ is defined by

$$
\begin{equation*}
\mathcal{S}\left(\mathcal{D} u, e^{0}\right)=\rho\left(e^{0}\right)(u), \quad \forall u \in \Gamma(E), e^{0} \in \Gamma\left(K_{0}\right) ; \tag{6.1}
\end{equation*}
$$

(E3) for all $e_{1}^{1}, e_{2}^{1} \in \Gamma\left(K_{-1}\right), \mathcal{S}\left(\partial\left(e_{1}^{1}\right), e_{2}^{1}\right)=\mathcal{S}\left(e_{1}^{1}, \partial\left(e_{2}^{1}\right)\right)$;
(E4) for all $e_{1}, e_{2}, e_{3} \in \Gamma(\mathcal{K}), \rho\left(e_{1}\right) \mathcal{S}\left(e_{2}, e_{3}\right)=\mathcal{S}\left(e_{1} \diamond e_{2}, e_{3}\right)+\mathcal{S}\left(e_{2}, e_{1} \diamond e_{3}\right)$;
(E5) for all $e_{1}^{0}, e_{2}^{0}, e_{3}^{0}, e_{4}^{0} \in \Gamma\left(K_{0}\right), \mathcal{S}\left(\Omega\left(e_{1}^{0}, e_{2}^{0}, e_{3}^{0}\right), e_{4}^{0}\right)=-\mathcal{S}\left(e_{3}^{0}, \Omega\left(e_{1}^{0}, e_{2}^{0}, e_{4}^{0}\right)\right)$;
(E6) for all $e_{1}^{0}, e_{2}^{0} \in \Gamma\left(K_{0}\right), \rho\left(e_{1}^{0} \diamond e_{2}^{0}\right)=\left[\rho\left(e_{1}^{0}\right), \rho\left(e_{2}^{0}\right)\right]_{\mathfrak{D}}$, where $[\cdot, \cdot]_{\mathfrak{D}}$ is the commutator bracket on $\Gamma(\mathfrak{D E})$.
A CLWX 2-algebroid can give rise to a Lie 3-algebra ([34, Theorem 3.11]). Similarly, an E-CLWX 2-algebroid can also give rise to a Lie 3-algebra. Consider the graded vector space $\mathfrak{e}=\mathfrak{e}_{-2} \oplus \mathfrak{e}_{-1} \oplus \mathfrak{e}_{0}$, where $\mathrm{e}_{-2}=\Gamma(E), \mathrm{e}_{-1}=\Gamma\left(K_{-1}\right)$ and $\mathrm{e}_{0}=\Gamma\left(K_{0}\right)$. We introduce a skew-symmetric bracket on $\Gamma(\mathcal{K})$,

$$
\begin{equation*}
\llbracket e_{1}, e_{2} \rrbracket=\frac{1}{2}\left(e_{1} \diamond e_{2}-e_{2} \diamond e_{1}\right), \quad \forall e_{1}, e_{2} \in \Gamma(\mathcal{K}) \tag{6.2}
\end{equation*}
$$

which is the skew-symmetrization of $\diamond$.
Theorem 6.2. An E-CLWX 2-algebroid ( $\mathcal{K}, \partial, \rho, \mathcal{S}, \diamond, \Omega$ ) gives rise to a Lie 3-algebra $\left(\mathfrak{e}, \mathrm{I}_{1}, \mathrm{I}_{2}, \mathrm{I}_{3}, \mathrm{I}_{4}\right)$, where $\mathrm{I}_{i}$ are given by

$$
\begin{array}{rlrl}
\mathrm{I}_{1}(u) & =\mathcal{D}(u), & & \forall u \in \Gamma(E), \\
\mathrm{I}_{1}\left(e^{1}\right) & =\partial\left(e^{1}\right), & & \forall e^{1} \in \Gamma\left(K_{-1}\right), \\
\mathrm{I}_{2}\left(e_{1}^{0}, e_{2}^{0}\right) & =\llbracket e_{1}^{0}, e_{2}^{0} \rrbracket, & & \forall e_{1}^{0}, e_{2}^{0} \in \Gamma\left(K_{0}\right), \\
\mathrm{I}_{2}\left(e^{0}, e^{1}\right) & =\llbracket e^{0}, e^{1} \rrbracket, & & \forall e^{0} \in \Gamma\left(K_{0}\right), e^{1} \in \Gamma\left(K_{-1}\right), \\
\mathrm{I}_{2}\left(e^{0}, f\right) & =\frac{1}{2} \mathcal{S}\left(e^{0}, \mathcal{D} f\right), & & \forall e^{0} \in \Gamma\left(K_{0}\right), f \in \Gamma(E), \\
\mathrm{I}_{2}\left(e_{1}^{1}, e_{2}^{1}\right) & =0, & & \forall e_{1}^{1}, e_{2}^{1} \in \Gamma\left(K_{-1}\right), \\
\mathrm{I}_{3}\left(e_{1}^{0}, e_{2}^{0}, e_{3}^{0}\right) & =\Omega\left(e_{1}^{0}, e_{2}^{0}, e_{3}^{0}\right), & & \forall e_{1}^{0}, e_{2}^{0}, e_{3}^{0} \in \Gamma\left(K_{0}\right), \\
\mathrm{I}_{3}\left(e_{1}^{0}, e_{2}^{0}, e^{1}\right) & =-T\left(e_{1}^{0}, e_{2}^{0}, e^{1}\right), & \forall e_{1}^{0}, e_{2}^{0} \in \Gamma\left(K_{0}\right), e^{1} \in \Gamma\left(K_{-1}\right), \\
\mathrm{I}_{4}\left(e_{1}^{0}, e_{2}^{0}, e_{3}^{0}, e_{4}^{0}\right) & =\bar{\Omega}\left(e_{1}^{0}, e_{2}^{0}, e_{3}^{0}, e_{4}^{0}\right), & \forall e_{1}^{0}, e_{2}^{0}, e_{3}^{0}, e_{4}^{0} \in \Gamma\left(K_{0}\right),
\end{array}
$$

where the totally skew-symmetric $T: \Gamma\left(K_{0}\right) \times \Gamma\left(K_{0}\right) \times \Gamma\left(K_{-1}\right) \longrightarrow \Gamma(E)$ is given by

$$
\begin{equation*}
T\left(e_{1}^{0}, e_{2}^{0}, e^{1}\right)=\frac{1}{6}\left(\mathcal{S}\left(e_{1}^{0}, \llbracket e_{2}^{0}, e^{1} \rrbracket\right)+\mathcal{S}\left(e^{1}, \llbracket e_{1}^{0}, e_{2}^{0} \rrbracket\right)+\mathcal{S}\left(e_{2}^{0}, \llbracket e^{1}, e_{1}^{0} \rrbracket\right)\right), \tag{6.3}
\end{equation*}
$$

and $\bar{\Omega}: \wedge^{4} \Gamma\left(K_{0}\right) \longrightarrow \Gamma(E)$ is given by

$$
\bar{\Omega}\left(e_{1}^{0}, e_{2}^{0}, e_{3}^{0}, e_{4}^{0}\right)=\mathcal{S}\left(\Omega\left(e_{1}^{0}, e_{2}^{0}, e_{3}^{0}\right), e_{4}^{0}\right)
$$

Proof. The proof is totally parallel to the proof of [34, Theorem 3.11], we omit the details.
Let $\left(D_{-1}^{B}, D_{0}^{B}, \partial, \rho, S, \diamond, \Omega\right)$ be a VB-CLWX 2-algebroid on the graded double vector bundle $\left(\begin{array}{ccc}D_{-1} ; & A_{-1}, B ; & M \\ D_{0} ; & A_{0}, B ; & M\end{array}\right)$. Then we have the associated graded fat bundles $\hat{A}_{-1} \oplus \hat{A}_{0}$, which fit the exact sequences:

$$
\begin{gathered}
0 \rightarrow B^{*} \otimes A_{0}^{*} \longrightarrow \hat{A}_{-1} \longrightarrow A_{-1} \rightarrow 0 \\
0 \rightarrow B^{*} \otimes A_{-1}^{*} \longrightarrow \hat{A}_{0} \longrightarrow A_{0} \rightarrow 0 .
\end{gathered}
$$

Since the bundle map $\partial$ is linear, it induces a bundle map $\hat{\partial}: \hat{A}_{-1} \longrightarrow \hat{A}_{0}$. Since the anchor $\rho$ is linear, it induces a bundle map $\hat{\rho}: \hat{A}_{0} \longrightarrow \mathfrak{D} B^{*}$, where sections of $\mathfrak{D} B^{*}$ are viewed as linear vector fields on $B$. Furthermore, the restriction of $S$ on linear sections will give rise to linear functions on $B$. Thus, we obtain a $B^{*}$-valued degree 1 graded symmetric bilinear form $\hat{S}$ on the graded fat bundle $\hat{A}_{-1} \oplus \hat{A}_{0}$. Since the operation $\diamond$ is linear, it induces an operation $\hat{\diamond}: \hat{A}_{-i} \times \hat{A}_{-j} \longrightarrow \hat{A}_{-(i+j)}, 0 \leq i+j \leq 1$. Finally, since $\Omega$ is linear, it induces an $\hat{\Omega}: \Gamma\left(\wedge^{3} \hat{A}_{0}\right) \longrightarrow \hat{A}_{-1}$. Then we obtain:

Theorem 6.3. A VB-CLWX 2-algebroid gives rise to a $B^{*}$-CLWX 2-algebroid structure on the corresponding graded fat bundle. More precisely, let $\left(D_{-1}^{B}, D_{0}^{B}, \partial, \rho, S, \diamond, \Omega\right)$ be a VB-CLWX 2-algebroid on the graded double vector bundle $\left(\begin{array}{ccc}D_{-1} ; & A_{-1}, B ; & M \\ D_{0} ; & A_{0}, B ; & M\end{array}\right)$ with the associated graded fat bundle $\hat{A}_{-1} \oplus \hat{A}_{0}$. Then $\left(\hat{A}_{-1}, \hat{A}_{0}, \hat{\partial}, \hat{\rho}, \hat{S}, \hat{\diamond}, \hat{\Omega}\right)$ is a $B^{*}$-CLWX 2-algebroid.
Proof. Since all the structures defined on the graded fat bundle $\hat{A}_{-1} \oplus \hat{A}_{0}$ are the restriction of the structures in the VB-CLWX 2-algebroid, it is straightforward to see that all the axioms in Definition 6.1 hold.

Example 3. Consider the VB-CLWX 2-algebroid given in Example 2, the corresponding E-CLWX 2-algebroid is $\left((\Im E)[1], \mathfrak{D} E, \partial=0, \rho=\mathrm{id}, \mathcal{S}=(\cdot, \cdot)_{E}, \diamond, \Omega=0\right)$, where the graded symmetric nondegenerate $E$-valued pairing $(\cdot, \cdot)_{E}$ is given by

$$
(\mathfrak{D}+\mu, \mathfrak{t}+v)_{E}=\langle\mu, \mathfrak{t}\rangle_{E}+\langle v, \mathfrak{D}\rangle_{E}, \quad \forall \mathfrak{D}+\mu, \mathfrak{t}+v \in \mathfrak{D} E \oplus \mathfrak{I} E,
$$

and $\diamond$ is given by

$$
(\mathfrak{D}+\mu) \diamond(\mathfrak{r}+v)=[\mathfrak{D}, \mathfrak{r}]_{\mathfrak{D}}+\mathfrak{Z}_{\mathrm{D}} v-\mathfrak{\Omega}_{\mathrm{r}} \mu+\mathbb{d}\langle\mu, \mathfrak{r}\rangle_{E} .
$$

See [10] for more details.
Example 4. Consider the VB-CLWX 2-algebroid given in Proposition 3. The graded fat bundle is $\mathfrak{J} E_{-1} \oplus \mathfrak{J} E_{0}$. It follows that the graded jet bundle associated to a CLWX 2-algebroid is a $T^{*} M$-CLWX 2-algebroid. This is the higher analogue of the result that the jet bundle of a Courant algebroid is $T^{*} M$-Courant algebroid given in [11]. See also [24] for more details.

## 7. Constructions of Lie 3-algebras

As applications of $E$-CLWX 2-algebroids introduced in the last section, we construct Lie 3-algebras from Lie 3-algebras in this section. Let $\left(\mathfrak{g}_{-2}, \mathfrak{g}_{-1}, \mathfrak{g}_{0}, l_{1}, l_{2}, l_{3}, l_{4}\right)$ be a Lie 3 -algebra. By Theorem 5.5, the corresponding VB-CLWX 2-algebroid is given by

where $D_{-1}=\mathfrak{g}_{-1} \oplus \mathfrak{g}_{0}^{*} \oplus \mathfrak{g}_{-2}^{*}$ and $D_{0}=\mathfrak{g}_{0} \oplus \mathfrak{g}_{-1}^{*} \oplus \mathfrak{g}_{-2}^{*}$.
By Theorem 6.3, we obtain:
Proposition 4. Let $\left(\mathfrak{g}_{-2}, \mathfrak{g}_{-1}, \mathfrak{g}_{0}, l_{1}, l_{2}, l_{3}, l_{4}\right)$ be a Lie 3-algebra. Then there is an E-CLWX 2algebroid $\left(\operatorname{Hom}\left(\mathfrak{g}_{0}, \mathfrak{g}_{-2}\right) \oplus \mathfrak{g}_{-1}, \operatorname{Hom}\left(\mathfrak{g}_{-1}, \mathfrak{g}_{-2}\right) \oplus \mathfrak{g}_{0}, \partial, \rho, \mathcal{S}, \diamond, \Omega\right)$, where for all $x^{i}, y^{i}, z^{i} \in \mathfrak{g}_{-i}, \phi^{i}, \psi^{i}, \varphi^{i} \in$ $\operatorname{Hom}\left(\mathfrak{g}_{-i}, \mathfrak{g}_{-2}\right), \partial: \operatorname{Hom}\left(\mathfrak{g}_{0}, \mathfrak{g}_{-2}\right) \oplus \mathfrak{g}_{-1} \longrightarrow \operatorname{Hom}\left(\mathfrak{g}_{-1}, \mathfrak{g}_{-2}\right) \oplus \mathfrak{g}_{0}$ is given by

$$
\begin{equation*}
\partial\left(\phi^{0}+x^{1}\right)=\phi^{0} \circ l_{1}+\left.l_{2}\left(x^{1}, \cdot\right)\right|_{g-1}+l_{1}\left(x^{1}\right), \tag{7.1}
\end{equation*}
$$

$\rho: \operatorname{Hom}\left(\mathfrak{g}_{-1}, \mathfrak{g}_{-2}\right) \oplus \mathfrak{g}_{0} \longrightarrow \mathfrak{g l}\left(\mathfrak{g}_{-2}\right)$ is given by

$$
\begin{equation*}
\rho\left(\phi^{1}+x^{0}\right)=\phi^{1} \circ l_{1}+\left.l_{2}\left(x^{0}, \cdot\right)\right|_{\mathrm{g}-2}, \tag{7.2}
\end{equation*}
$$

the $\mathfrak{g}_{-2}$-valued pairing $\mathcal{S}$ is given by

$$
\begin{equation*}
\mathcal{S}\left(\phi^{1}+x^{0}, \psi^{0}+y^{1}\right)=\phi^{1}\left(y^{1}\right)+\psi^{0}\left(x^{0}\right), \tag{7.3}
\end{equation*}
$$

the operation $\diamond$ is given by

$$
\left\{\begin{array}{l}
\left(x^{0}+\psi^{1}\right) \diamond\left(y^{0}+\phi^{1}\right)=l_{2}\left(x^{0}, y^{0}\right)+\left.l_{3}\left(x^{0}, y^{0}, \cdot\right)\right|_{g_{-1}}+l_{2}\left(x^{0}, \phi^{1}(\cdot)\right)-\phi^{1} \circ l_{1} \circ \psi^{1}  \tag{7.4}\\
\quad-\left.\phi^{1} \circ l_{2}\left(x^{0}, \cdot\right)\right|_{g_{-1}}+\left.\psi^{1} \circ l_{2}\left(y^{0}, \cdot\right)\right|_{\mathfrak{g}_{-1}}-l_{2}\left(y^{0}, \psi^{1}(\cdot)\right)+\psi^{1} \circ l_{1} \circ \phi^{1}, \\
\left(x^{0}+\psi^{1}\right) \diamond\left(y^{1}+\phi^{0}\right)=l_{2}\left(x^{0}, y^{1}\right)+\left.l_{3}\left(x^{0}, \cdot, y^{1}\right)\right|_{g_{0}}+l_{2}\left(x^{0}, \phi^{0}(\cdot)\right) \\
\quad-\left.\phi^{0} \circ l_{2}\left(x^{0}, \cdot\right)\right|_{g_{0}}-\left.\psi^{1} l_{2}\left(\cdot, y^{1}\right)\right|_{g_{0}}+\delta\left(\psi^{1}\left(y^{1}\right)\right)+\psi^{1} \circ l_{1} \circ \phi^{0}, \\
\left(y^{1}+\phi^{0}\right) \diamond\left(x^{0}+\psi^{1}\right)=l_{2}\left(y^{1}, x^{0}\right)-\left.l_{3}\left(x^{0} \cdot \cdot, y^{1}\right)\right|_{\mathfrak{g}_{0}}-l_{2}\left(x^{0}, \phi^{0}(\cdot)\right) \\
\quad+\left.\phi^{0} \circ l_{2}\left(x^{0}, \cdot\right)\right|_{g_{0}}+\delta\left(\phi^{0}\left(x^{0}\right)\right)+\left.\psi^{1} l_{2}\left(\cdot, \cdot y^{1}\right)\right|_{g_{0}}-\psi^{1} \circ l_{1} \circ \phi^{0},
\end{array}\right.
$$

and $\Omega$ is given by

$$
\begin{align*}
& \Omega\left(\phi^{1}+x^{0}, \psi^{1}+y^{0}+\varphi^{1}+z^{0}\right)=l_{3}\left(x^{0}, y^{0}, z^{0}\right)+l_{4}\left(x^{0}, y^{0}, z^{0}, \cdot\right) \\
& \quad-\left.\varphi^{1} \circ l_{3}\left(x^{0}, y^{0}, \cdot\right)\right|_{9_{0}}-\left.\phi^{1} \circ l_{3}\left(z^{0}, x^{0}, \cdot\right)\right|_{9_{0}}-\left.\psi^{1} \circ l_{3}\left(y^{0}, z^{0}, \cdot\right)\right|_{9_{0}} . \tag{7.5}
\end{align*}
$$

By (7.2), it is straightforward to deduce that the corresponding $\mathcal{D}: \mathfrak{g}_{-2} \longrightarrow \operatorname{Hom}\left(\mathfrak{g}_{0}, \mathfrak{g}_{-2}\right) \oplus \mathfrak{g}_{-1}$ is given by

$$
\begin{equation*}
\mathcal{D}\left(x^{2}\right)=l_{2}\left(\cdot, x^{2}\right)+l_{1}\left(x^{2}\right) \tag{7.6}
\end{equation*}
$$

Then by Theorem 6.2, we obtain:

Proposition 5. Let $\left(\mathfrak{g}_{-2}, \mathfrak{g}_{-1}, \mathfrak{g}_{0}, l_{1}, l_{2}, l_{3}, l_{4}\right)$ be a Lie 3-algebra. Then there is a Lie 3-algebra $\left(\overline{\mathfrak{g}}_{-2}, \overline{\mathfrak{g}}_{-1}, \overline{\mathfrak{g}}_{0}, \mathfrak{l}_{1}, \mathfrak{l}_{2}, \mathfrak{l}_{3}, \mathfrak{l}_{4}\right)$, where $\overline{\mathfrak{g}}_{-2}=\mathfrak{g}_{-2}, \overline{\mathfrak{g}}_{-1}=\operatorname{Hom}\left(\mathfrak{g}_{0}, \mathfrak{g}_{-2}\right) \oplus \mathfrak{g}_{-1}, \overline{\mathfrak{g}}_{0}=\operatorname{Hom}\left(\mathfrak{g}_{-1}, \mathfrak{g}_{-2}\right) \oplus \mathfrak{g}_{0}$, and $\mathrm{I}_{i}$ are given by

$$
\begin{aligned}
\mathrm{I}_{1}\left(x^{2}\right) & =\mathcal{D}\left(x^{2}\right), & & \forall x^{2} \in \mathfrak{g}_{-2}, \\
\mathrm{I}_{1}\left(\phi^{0}+x^{1}\right) & =\phi^{0} \circ l_{1}+\left.l_{2}\left(x^{1}, \cdot\right)\right|_{\mathfrak{g}_{-1}}+l_{1}\left(x^{1}\right), & & \forall \phi^{0}+x^{1} \in \overline{\mathfrak{g}}_{-1}, \\
\mathrm{I}_{2}\left(e_{1}^{0}, e_{2}^{0}\right) & =e_{1}^{0} \diamond e_{2}^{0}, & & \forall e_{1}^{0}, e_{2}^{0} \in \overline{\mathfrak{g}}_{0}, \\
\mathrm{I}_{2}\left(e^{0}, e^{1}\right) & =\frac{1}{2}\left(e^{0} \diamond e^{1}-e^{1} \diamond e^{0}\right), & & \forall e^{0} \in \overline{\mathfrak{g}}_{0}, e^{1} \in \overline{\mathfrak{g}}_{-1}, \\
\mathrm{I}_{2}\left(e^{0}, x^{2}\right) & =\frac{1}{2} \mathcal{S}\left(e^{0}, \mathcal{D} x^{2}\right), & & \forall e^{0} \in \overline{\mathfrak{g}}_{0}, x^{2}, e_{2}^{1} \in \overline{\mathfrak{g}}_{-1}, \\
\mathrm{I}_{2}\left(e_{1}^{1}, e_{2}^{1}\right) & =0, & & \forall e_{1}^{0}, e_{2}^{0}, e_{3}^{0} \in \overline{\mathfrak{g}}_{0}, \\
\mathrm{I}_{3}\left(e_{1}^{0}, e_{2}^{0}, e_{3}^{0}\right) & =\Omega\left(e_{1}^{0}, e_{2}^{0}, e_{3}^{0}\right), & & \forall e_{1}^{0}, e_{2}^{0} \in \overline{\mathfrak{g}}_{0}, e^{1} \in \overline{\mathfrak{g}}_{-1}, \\
\mathrm{I}_{3}\left(e_{1}^{0}, e_{2}^{0}, e^{1}\right) & =-T\left(e_{1}^{0}, e_{2}^{0}, e^{1}\right), & & \forall e_{1}^{0}, e_{2}^{0}, e_{3}^{0}, e_{4}^{0} \in \overline{\mathfrak{g}}_{0},
\end{aligned}
$$

where the operation $\mathcal{D}, \diamond, \Omega$ are given by (7.6), (7.4), (7.5) respectively, $T: \overline{\mathfrak{g}}_{0} \times \overline{\mathfrak{g}}_{0} \times \overline{\mathfrak{g}}_{-1} \longrightarrow \mathfrak{g}_{-2}$ is given by

$$
T\left(e_{1}^{0}, e_{2}^{0}, e^{1}\right)=\frac{1}{6}\left(\mathcal{S}\left(e_{1}^{0}, \mathrm{l}_{2}\left(e_{2}^{0}, e^{1}\right)\right)+\mathcal{S}\left(e^{1}, \mathrm{I}_{2}\left(e_{1}^{0}, e_{2}^{0}\right)\right)+\mathcal{S}\left(e_{2}^{0}, \mathrm{l}_{2}\left(e^{1}, e_{1}^{0}\right)\right)\right)
$$

and $\bar{\Omega}: \wedge^{4} \overline{\mathfrak{g}}_{0} \longrightarrow \mathfrak{g}_{-2}$ is given by

$$
\bar{\Omega}\left(e_{1}^{0}, e_{2}^{0}, e_{3}^{0}, e_{4}^{0}\right)=\mathcal{S}\left(\Omega\left(e_{1}^{0}, e_{2}^{0}, e_{3}^{0}\right), e_{4}^{0}\right)
$$

By Proposition 5, we can give interesting examples of Lie 3-algebras.
Example 5. We view a 3-term complex of vector spaces $V_{-2} \xrightarrow{l_{1}} V_{-1} \xrightarrow{l_{1}} V_{0}$ as an abelian Lie 3-algebra. By Proposition 5, we obtain the Lie 3-algebra

$$
\left(V_{-2}, \operatorname{Hom}\left(V_{0}, V_{-2}\right) \oplus V_{-1}, \operatorname{Hom}\left(V_{-1}, V_{-2}\right) \oplus V_{0}, \mathrm{I}_{1}, \mathrm{I}_{2}, \mathrm{I}_{3}, \mathrm{I}_{4}=0\right),
$$

where $\mathrm{I}_{i}, i=1,2,3$ are given by

$$
\begin{aligned}
\mathrm{I}_{1}\left(x^{2}\right)= & l_{1}\left(x^{2}\right), \\
\mathrm{I}_{1}\left(\phi^{0}+y^{1}\right)= & \phi^{0} \circ l_{1}+l_{1}\left(y^{1}\right), \\
\mathrm{I}_{2}\left(\psi^{1}+x^{0}, \phi^{1}+y^{0}\right)= & \psi^{1} \circ l_{1} \circ \phi^{1}-\phi^{1} \circ l_{1} \circ \psi^{1}, \\
\mathrm{I}_{2}\left(\psi^{1}+x^{0}, \phi^{0}+y^{1}\right)= & \frac{1}{2} l_{1}\left(\psi^{1}\left(y^{1}\right)-\phi^{0}\left(x^{0}\right)\right)+\psi^{1} \circ l_{1} \circ \phi^{0}, \\
\mathrm{I}_{2}\left(\psi^{1}+x^{0}, x^{2}\right)= & \frac{1}{2} \psi^{1}\left(l_{1}\left(x^{2}\right)\right), \\
\mathrm{I}_{2}\left(\psi^{0}+x^{1}, \phi^{0}+y^{1}\right)= & 0, \\
\mathrm{I}_{3}\left(\psi^{1}+x^{0}, \phi^{1}+y^{0}, \varphi^{1}+z^{0}\right)= & 0, \\
\mathrm{I}_{3}\left(\psi^{1}+x^{0}, \phi^{1}+y^{0}, \varphi^{0}+z^{1}\right)= & -\frac{1}{4}\left(\psi^{1} \circ l_{1} \circ \phi^{1}\left(z^{1}\right)-\phi^{1} \circ l_{1} \circ \psi^{1}\left(z^{1}\right)\right. \\
& \left.-\psi^{1} \circ l_{1} \circ \varphi^{0}\left(y^{0}\right)+\phi^{1} \circ l_{1} \circ \varphi^{0}\left(x^{0}\right)\right),
\end{aligned}
$$

for all $x^{2} \in V_{-2}, \psi^{0}+x^{1}, \phi^{0}+y^{1}, \varphi^{0}+z^{1} \in \operatorname{Hom}\left(V_{0}, V_{-2}\right) \oplus V_{-1}, \psi^{1}+x^{0}, \phi^{1}+y^{0}, \varphi^{1}+z^{0} \in \operatorname{Hom}\left(V_{-1}, V_{-2}\right) \oplus V_{0}$.

## Example 6. (Higher analogue of the Lie 2-algebra of string type )

A Lie 2-algebra ( $\mathfrak{g}_{-1}, \mathfrak{g}_{0}, \widetilde{l_{1}}, \widetilde{l_{2}}, \widetilde{l_{3}}$ ) gives rise to a Lie 3-algebra $\left(\mathbb{R}, \mathfrak{g}_{-1}, \mathfrak{g}_{0}, l_{1}, l_{2}, l_{3}, l_{4}=0\right)$ naturally, where $l_{i}, i=1,2,3$ is given by

$$
l_{1}(r)=0, \quad l_{1}\left(x^{1}\right)=\widetilde{l_{1}}\left(x^{1}\right)
$$

$$
\begin{aligned}
l_{2}\left(x^{0}, y^{0}\right) & =\widetilde{l_{2}}\left(x^{0}, y^{0}\right), l_{2}\left(x^{0}, y^{1}\right)=\widetilde{l_{2}}\left(x^{0}, y^{1}\right), l_{2}\left(x^{0}, r\right)=0, l_{2}\left(x^{1}, y^{1}\right)=0, \\
l_{3}\left(x^{0}, y^{0}, z^{0}\right) & =\widetilde{l_{3}}\left(x^{0}, y^{0}, z^{0}\right), \quad l_{3}\left(x^{0}, y^{0}, z^{1}\right)=0,
\end{aligned}
$$

for all $x^{0}, y^{0}, z^{0} \in \mathfrak{g}_{0}, x^{1}, y^{1}, z^{1} \in \mathfrak{g}_{-1}$, and $r, s \in \mathbb{R}$. By Proposition 5, we obtain the Lie 3-algebra $\left(\mathbb{R}, \mathfrak{g}_{-1} \oplus \mathfrak{g}_{0}^{*}, \mathfrak{g}_{0} \oplus \mathfrak{g}_{-1}^{*}, \mathrm{I}_{1}, \mathfrak{l}_{2}, \mathrm{I}_{3}, \mathrm{I}_{4}\right)$, where $\mathfrak{I}_{i}, i=1,2,3,4$ are given by

$$
\begin{aligned}
& \mathrm{l}_{1}(r)=0, \\
& \mathrm{I}_{1}\left(x^{1}+\alpha^{0}\right)=l_{1}\left(x^{1}\right)+l_{1}^{*}\left(\alpha^{0}\right), \\
& \mathrm{I}_{2}\left(x^{0}+\alpha^{1}, y^{0}+\beta^{1}\right)=l_{2}\left(x^{0}, y^{0}\right)+\operatorname{ad}_{x^{0}}^{0} \beta^{1}-\operatorname{ad}_{y^{0}}^{0} \alpha^{1}, \\
& \mathrm{I}_{2}\left(x^{0}+\alpha^{1}, y^{1}+\beta^{0}\right)=l_{2}\left(x^{0}, y^{1}\right)+\operatorname{ad}_{x^{0}}^{0} \beta^{0}-\operatorname{ad}_{y^{1}}{ }^{1} \alpha^{1} \text {, } \\
& \mathrm{I}_{2}\left(x^{1}+\alpha^{0}, y^{1}+\beta^{0}\right)=0, \\
& \mathrm{I}_{2}\left(x^{0}+\alpha^{1}, r\right)=0, \\
& \mathfrak{I}_{3}\left(x^{0}+\alpha^{1}, y^{0}+\beta^{1}, z^{0}+\zeta^{1}\right)=l_{3}\left(x^{0}, y^{0}, z^{0}\right)+\operatorname{ad}_{x^{0}, y^{0}}^{3^{*}} \zeta^{1}+\operatorname{ad}_{y^{0}, z^{0}}^{3^{*}} \alpha^{1} \\
& +\mathrm{ad}_{z^{0}, x^{0}}^{3} \beta^{1} \text {, } \\
& \mathfrak{I}_{3}\left(x^{0}+\alpha^{1}, y^{0}+\beta^{1}, z^{1}+\zeta^{0}\right)=\frac{1}{2}\left(\left\langle\alpha^{1}, l_{2}\left(y^{0}, z^{1}\right)\right\rangle+\left\langle\beta^{1}, l_{2}\left(z^{1}, x^{0}\right)\right\rangle\right. \\
& \left.+\left\langle\zeta^{0}, l_{2}\left(x^{0}, y^{0}\right)\right\rangle\right), \\
& \mathrm{I}_{4}\left(x^{0}+\alpha^{1}, y^{0}+\beta^{1}, z^{0}+\zeta^{1}, u^{0}+\gamma^{1}\right)=\left\langle\gamma^{1}, l_{3}\left(x^{0}, y^{0}, z^{0}\right)\right\rangle-\left\langle\zeta^{1}, l_{3}\left(x^{0}, y^{0}, u^{0}\right)\right\rangle \\
& -\left\langle\alpha^{1}, l_{3}\left(y^{0}, z^{0}, u^{0}\right)\right\rangle-\left\langle\beta^{1}, l_{3}\left(z^{0}, x^{0}, u^{0}\right)\right\rangle
\end{aligned}
$$

for all $x^{0}, y^{0}, z^{0}, u^{0} \in \mathfrak{g}_{0}, x^{1}, y^{1}, z^{1} \in \mathfrak{g}_{-1}, \alpha^{1}, \beta^{1}, \zeta^{1}, \gamma^{1} \in \mathfrak{g}_{-1}^{*}, \alpha^{0}, \beta^{0} \in \mathfrak{g}_{0}^{*}$, where ad ${ }_{x^{0}}^{0 *}: \mathfrak{g}_{-i}^{*} \longrightarrow \mathfrak{g}_{-i}^{*}$, $\operatorname{ad}^{1^{*}}{ }^{*}: \mathfrak{g}_{-1}^{*} \longrightarrow \mathfrak{g}_{0}^{*}$ and ad $^{3^{*}, y^{*}}: \mathfrak{g}_{-1}^{*} \longrightarrow \mathfrak{g}_{0}^{*}$ are defined respectively by

$$
\begin{aligned}
& \left\langle\operatorname{ad}^{0^{*}{ }^{0}} \alpha^{1}, x^{1}\right\rangle=-\left\langle\alpha^{1}, l_{2}\left(x^{0}, x^{1}\right)\right\rangle, \quad\left\langle\operatorname{ad}^{0^{*}}{ }_{x^{0}} \alpha^{0}, y^{0}\right\rangle=-\left\langle\alpha^{0}, l_{2}\left(x^{0}, y^{0}\right)\right\rangle, \\
& \left\langle\operatorname{ad}^{1^{*}}{ }_{x^{1}} \alpha^{1}, y^{0}\right\rangle=-\left\langle\alpha^{1}, l_{2}\left(x^{1}, y^{0}\right)\right\rangle,\left\langle\left\langle\operatorname{ad}^{3^{*}}{ }_{x^{0}, y^{0}} \alpha^{1}, z^{0}\right\rangle=-\left\langle\alpha^{1}, l_{3}\left(x^{0}, y^{0}, z^{0}\right)\right\rangle .\right.
\end{aligned}
$$

Remark 4. For any Lie algebra $\left(\mathfrak{h},[\cdot, \cdot]_{\mathfrak{h}}\right)$, we have the semidirect product Lie algebra $\left(\mathfrak{h} \ltimes_{\mathrm{ad}^{*}} \mathfrak{h}^{*},[\cdot, \cdot]_{\mathrm{ad}^{*}}\right)$, which is a quadratic Lie algebra naturally. Consequently, one can construct the corresponding Lie 2-algebra $\left(\mathbb{R}, \mathfrak{h} \ltimes_{\mathrm{ad}^{*}} \mathfrak{h}^{*}, l_{1}=0, l_{2}=[\cdot, \cdot]_{\mathrm{ad}^{*}}, l_{3}\right)$, where $l_{3}$ is given by

$$
l_{3}(x+\alpha, y+\beta, z+\gamma)=\left\langle\gamma,[x, y]_{\mathfrak{h}}\right\rangle+\left\langle\beta,[z, x]_{\mathfrak{h}}\right\rangle+\left\langle\alpha,[y, z]_{\mathfrak{h}}\right\rangle, \quad \forall x, y, z \in \mathfrak{h}, \alpha, \beta, \gamma \in \mathfrak{h}^{*} .
$$

This Lie 2-algebra is called the Lie 2-algebra of string type in [51]. On the other hand, associated to a Lie 2-algebra $\left(\mathfrak{g}_{-1}, \mathfrak{g}_{0}, \widetilde{l_{1}}, \widetilde{l_{2}}, \widetilde{l_{3}}\right)$, there is a naturally a quadratic Lie 2-algebra structure on $\left(\mathfrak{g}_{-1} \oplus \mathfrak{g}_{0}^{*}\right) \oplus\left(\mathfrak{g}_{0} \oplus \mathfrak{g}_{-1}^{*}\right)$ ([34, Example 4.8]). Thus, the Lie 3-algebra given in the above example can be viewed as the higher analogue of the Lie 2-algebra of string type.

Motivated by the above example, we show that one can obtain a Lie 3-algebra associated to a quadratic Lie 2-algebra in the sequel. This result is the higher analogue of the fact that there is a Lie 2-algebra, called the string Lie 2-algebra, associated to a quadratic Lie algebra.

A quadratic Lie 2-algebra is a Lie 2-algebra $\left(\mathfrak{g}_{-1}, \mathfrak{g}_{0}, l_{1}, l_{2}, l_{3}\right)$ equipped with a degree 1 graded symmetric nondegenerate bilinear form $S$ which induces an isomorphism between $\mathfrak{g}_{-1}$ and $\mathfrak{g}_{0}^{*}$, such that the following invariant conditions hold:

$$
\begin{equation*}
S\left(l_{1}\left(x^{1}\right), y^{1}\right)=S\left(l_{1}\left(y^{1}\right), x^{1}\right), \tag{7.7}
\end{equation*}
$$

$$
\begin{align*}
S\left(l_{2}\left(x^{0}, y^{0}\right), z^{1}\right) & =-S\left(l_{2}\left(x^{0}, z^{1}\right), y^{0}\right),  \tag{7.8}\\
S\left(l_{3}\left(x^{0}, y^{0}, z^{0}\right), u^{0}\right) & =-S\left(l_{3}\left(x^{0}, y^{0}, u^{0}\right), z^{0}\right), \tag{7.9}
\end{align*}
$$

for all $x^{0}, y^{0}, z^{0}, u^{0} \in \mathfrak{g}_{0}, x^{1}, y^{1} \in \mathfrak{g}_{-1}$.
Let $\left(g_{-1}, \mathfrak{g}_{0}, l_{1}, l_{2}, l_{3}, S\right)$ be a quadratic Lie 2 -algebra. On the 3-term complex of vector spaces $\mathbb{R} \oplus \mathfrak{g}_{-1} \oplus \mathfrak{g}_{0}$, where $\mathbb{R}$ is of degree -2 , we define $\mathfrak{I}_{i}, i=1,2,3,4$, by

$$
\left\{\begin{align*}
\mathfrak{I}_{1}(r) & =0, & \mathfrak{I}_{1}\left(x^{1}\right) & =l_{1}\left(x^{1}\right),  \tag{7.10}\\
\mathfrak{I}_{2}\left(x^{0}, y^{0}\right) & =l_{2}\left(x^{0}, y^{0}\right), & \mathfrak{I}_{2}\left(x^{0}, y^{1}\right) & =l_{2}\left(x^{0}, y^{1}\right), \\
\mathfrak{I}_{2}\left(x^{0}, r\right) & =0, & \mathfrak{I}_{2}\left(x^{1}, y^{1}\right) & =0, \\
\mathfrak{I}_{3}\left(x^{0}, y^{0}, z^{0}\right) & =l_{3}\left(x^{0}, y^{0}, z^{0}\right), & \mathfrak{I}_{3}\left(x^{0}, y^{0}, z^{1}\right) & =\frac{1}{2} S\left(z^{1}, l_{2}\left(x^{0}, y^{0}\right)\right), \\
\mathfrak{I}_{4}\left(x^{0}, y^{0}, z^{0}, u^{0}\right) & =S\left(l_{3}\left(x^{0}, y^{0}, z^{0}\right), u^{0}\right), & &
\end{align*}\right.
$$

for all $x^{0}, y^{0}, z^{0}, u^{0} \in \mathfrak{g}_{0}, x^{1}, y^{1}, z^{1} \in \mathfrak{g}_{-1}$ and $r \in \mathbb{R}$.
Theorem 7.1. With above notations, $\left(\mathbb{R}, \mathfrak{g}_{-1}, \mathfrak{g}_{0}, \mathfrak{l}_{1}, \mathfrak{l}_{2}, \mathfrak{l}_{3}, \mathrm{I}_{4}\right)$ is a Lie 3-algebra, called the higher analogue of the string Lie 2-algebra.

Proof. It follows from direct verification of the coherence conditions for $I_{3}$ and $\mathrm{I}_{4}$ using the invariant conditions (7.7)-(7.9). We omit details.

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