



Research article

Investigation of the global dynamics of two exponential-form difference equations systems

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Abstract: In this study, we investigate the boundedness, persistence of positive solutions, local and global stability of the unique positive equilibrium point and rate of convergence of positive solutions of the following difference equations systems of exponential forms:

$$\begin{aligned}\Upsilon_{n+1} &= \frac{\Gamma_1 + \delta_1 e^{-\Psi_{n-1}}}{\Theta_1 + \Psi_n}, \quad \Psi_{n+1} = \frac{\Gamma_2 + \delta_2 e^{-\Omega_{n-1}}}{\Theta_2 + \Omega_n}, \quad \Omega_{n+1} = \frac{\Gamma_3 + \delta_3 e^{-\Upsilon_{n-1}}}{\Theta_3 + \Upsilon_n}, \\ \Upsilon_{n+1} &= \frac{\Gamma_1 + \delta_1 e^{-\Psi_{n-1}}}{\Theta_1 + \Upsilon_n}, \quad \Psi_{n+1} = \frac{\Gamma_2 + \delta_2 e^{-\Omega_{n-1}}}{\Theta_2 + \Psi_n}, \quad \Omega_{n+1} = \frac{\Gamma_3 + \delta_3 e^{-\Upsilon_{n-1}}}{\Theta_3 + \Omega_n},\end{aligned}$$

for $n \in \mathbb{N}_0$, where the initial conditions Υ_{-j} , Ψ_{-j} , Ω_{-j} , for $j \in \{0, 1\}$ and the parameters Γ_i , δ_i , Θ_i for $i \in \{1, 2, 3\}$ are positive constants.

Keywords: boundedness; system of difference equations; persistence; stability

1. Introduction and preliminaries

First of all, it is important to keep in mind that \mathbb{N}_0 , \mathbb{Z} , \mathbb{R} , \mathbb{R}^+ and $\mathbb{R}^+ \cup \{0\}$, refer to the non-negative integer set, integer set, real set, positive real set and non-negative real set, respectively. If $\Phi, \Psi \in \mathbb{Z}$ and $\Phi \leq \Psi$, the notation $k = \overline{\Phi, \Psi}$ stands for $\{k \in \mathbb{Z} : \Phi \leq k \leq \Psi\}$.

It is of utmost importance to use different branches of science in tandem. Mathematics can also be deployed in research fields of other scientific areas. Especially, mathematical models of many sorts have been developed for many areas of study, such as ecology, medicine, population biology, biostatistics and molecular biology in [1]. In order to apply mathematical modeling in biology, both mathematical and biological information are required. As such, multidisciplinary or interdisciplinary research studies are very popular these days (see [2–15]).

Difference equations, which represent a topic of applied mathematics, can also be used in mathematical modeling. In addition, difference equations are used to define real discrete models in different areas of advanced science, such as control theory, biology, physics, economics and psychology. One of the applications of difference equations in biology is the population model. Some population models involve exponential-form difference equations. Difference equations of the mentioned type attract the attention of mathematicians. But, their stability analysis process can be complex. Therefore, studying these difference equations and systems is worthwhile. To date, a significant number of papers concerning difference equations have been published (see [16–27]).

As a model in the field of mathematical biology, several difference equations of the exponential-type were studied. For example, the following single-species population model

$$U_{n+1} = \kappa + \epsilon U_{n-1} e^{-U_n}, \quad n \in \mathbb{N}_0, \quad (1.1)$$

where $\kappa, \epsilon \in \mathbb{R}^+$ and $U_{-1}, U_0 \in \mathbb{R}^+ \cup \{0\}$, was investigated by El-Metwally et al. in [28]. κ was used as the migration rate and ϵ was taken as the population growth rate in Eq (1.1).

There is another example, in which the authors of [29] changed Eq (1.1) to a newer version as;

$$U_{n+1} = \kappa + \epsilon U_n e^{-U_{n-1}}, \quad n \in \mathbb{N}_0, \quad (1.2)$$

where $U_{-1}, U_0 \in \mathbb{R}^+ \cup \{0\}$ and $\kappa, \epsilon \in \mathbb{R}^+$. As a model in the field of mathematical biology, Eq (1.2) was investigated. In Eq (1.2), κ is the migration rate and ϵ is the population growth rate.

The authors of [30] researched the dynamical properties of the next exponential-type difference equation:

$$U_{n+1} = \frac{\kappa + \epsilon e^{-U_n}}{\zeta + U_{n-1}}, \quad n \in \mathbb{N}_0, \quad (1.3)$$

where $U_{-1}, U_0 \in \mathbb{R}^+ \cup \{0\}$ and $\kappa, \epsilon, \zeta \in \mathbb{R}^+$. Equation (1.3) represent a mathematical biology-purposed model, where κ is the migration rate, ϵ is the population growth proportion and ζ is the carrying capacity.

Comert et al. in [31], explored the global behavior of the next exponential-type difference equation:

$$U_{n+1} = \frac{\delta + \epsilon e^{-U_n}}{\zeta + U_{n-k}}, \quad n \in \mathbb{N}_0, \quad (1.4)$$

where k is an even number, the initial values $U_{-k}, U_{-k+1}, \dots, U_0 \in \mathbb{R}^+ \cup \{0\}$ and the parameters $\delta, \epsilon, \zeta \in \mathbb{R}^+$. Moreover, there are numerous studies that can be viewed as a model for difference equations of the exponential-type in the literature [32–35].

Some authors extended Eq (1.3) to the two-dimensional exponential-type difference equations systems. For instance, Papaschinopoulos et al. examined the following systems of two-dimensional exponential-form difference equations:

$$\begin{aligned} T_{n+1} &= \frac{\kappa + \epsilon e^{-R_n}}{\zeta + R_{n-1}}, & R_{n+1} &= \frac{\delta + \lambda e^{-T_n}}{\mu + T_{n-1}}, \\ T_{n+1} &= \frac{\kappa + \epsilon e^{-R_n}}{\zeta + T_{n-1}}, & R_{n+1} &= \frac{\delta + \lambda e^{-T_n}}{\mu + R_{n-1}}, \\ T_{n+1} &= \frac{\kappa + \epsilon e^{-T_n}}{\zeta + R_{n-1}}, & R_{n+1} &= \frac{\delta + \lambda e^{-R_n}}{\mu + T_{n-1}}, \end{aligned} \quad (1.5)$$

for $n \in \mathbb{N}_0$, where $T_{-1}, T_0, R_{-1}, R_0 \in \mathbb{R}^+$ and $\kappa, \epsilon, \zeta, \delta, \lambda, \mu \in \mathbb{R}^+$ in [36]. The systems given by in (1.5) are two-species population models.

In addition, Thai et al. in [37], studied the dynamical properties of the following systems:

$$\begin{aligned} T_{n+1} &= \frac{\alpha_1 + \beta_1 e^{-T_{n-1}}}{\gamma_1 + R_n}, \quad R_{n+1} = \frac{\alpha_2 + \beta_2 e^{-R_{n-1}}}{\gamma_2 + T_n}, \\ T_{n+1} &= \frac{\alpha_1 + \beta_1 e^{-R_{n-1}}}{\gamma_1 + T_n}, \quad R_{n+1} = \frac{\alpha_2 + \beta_2 e^{-T_{n-1}}}{\gamma_2 + R_n}, \end{aligned} \quad (1.6)$$

for $n \in \mathbb{N}_0$, where the parameters $\alpha_k, \beta_k, \gamma_k \in \mathbb{R}^+$, for $k \in \{1, 2\}$ and $T_{-1}, T_0, R_{-1}, R_0 \in \mathbb{R}^+$. Two-dimensional exponential-form difference equations systems have been studied by many authors in recent years (see [38–44]).

Our aim in this paper is to generalize the systems given by (1.6) to the following three-dimensional system of difference equations of exponential-form:

$$\Upsilon_{n+1} = \frac{\Gamma_1 + \delta_1 e^{-\Psi_{n-1}}}{\Theta_1 + \Psi_n}, \quad \Psi_{n+1} = \frac{\Gamma_2 + \delta_2 e^{-\Omega_{n-1}}}{\Theta_2 + \Omega_n}, \quad \Omega_{n+1} = \frac{\Gamma_3 + \delta_3 e^{-\Upsilon_{n-1}}}{\Theta_3 + \Upsilon_n}, \quad (1.7)$$

$$\Upsilon_{n+1} = \frac{\Gamma_1 + \delta_1 e^{-\Psi_{n-1}}}{\Theta_1 + \Upsilon_n}, \quad \Psi_{n+1} = \frac{\Gamma_2 + \delta_2 e^{-\Omega_{n-1}}}{\Theta_2 + \Psi_n}, \quad \Omega_{n+1} = \frac{\Gamma_3 + \delta_3 e^{-\Upsilon_{n-1}}}{\Theta_3 + \Omega_n}, \quad (1.8)$$

for $n \in \mathbb{N}_0$, where the parameters $\Gamma_k, \delta_k, \Theta_k$ for $k = \overline{1, 3}$ and the initial values $\Upsilon_{-v}, \Psi_{-v}, \Omega_{-v}$, for $v \in \{0, 1\}$ are positive constants. Another goal of this study is to contribute to the literature, since there are few studies on systems of three-dimensional exponential-form difference equations in the literature (see [45, 46]).

In mathematical biology, the systems given by (1.7) and (1.8) can be viewed as three-species population models. Also, the biological parameters of systems (1.7) and (1.8) are shown in Table 1.

Table 1. Biological presentations in systems (1.7) and (1.8).

Parameters	Biological presentations
Γ_1	Migration rate of species Υ_n
δ_1	Population growth rate of species Υ_n
Θ_1	The carrying capacity of species Υ_n
Γ_2	Migration rate of species Ψ_n
δ_2	Population growth rate of species Ψ_n
Θ_2	The carrying capacity of species Ψ_n
Γ_3	Migration rate of species Ω_n
δ_3	Population growth rate of species Ω_n
Θ_3	The carrying capacity of species Ω_n

Our paper is organized as follows: In the following section, we study the boundedness, local and global stability of the unique positive equilibrium point and rate of convergence of system (1.7). In the third section, we study the boundedness, local and global stability of the unique positive equilibrium point and rate of convergence of system (1.8). The conclusion is given in the last section.

Before we start our analysis, recall some lemmas and definitions which are used throughout this work. For more particulars, one can refer to the references [47–50].

$$\begin{aligned}\mathbf{U}_{n+1} &= f(\mathbf{U}_n, \mathbf{U}_{n-1}, \rho_n, \rho_{n-1}, \sigma_n, \sigma_{n-1}), \\ \rho_{n+1} &= g(\mathbf{U}_n, \mathbf{U}_{n-1}, \rho_n, \rho_{n-1}, \sigma_n, \sigma_{n-1}), \quad n \in \mathbb{N}_0, \\ \sigma_{n+1} &= h(\mathbf{U}_n, \mathbf{U}_{n-1}, \rho_n, \rho_{n-1}, \sigma_n, \sigma_{n-1}),\end{aligned}\tag{1.9}$$

where $f : U^2 \times V^2 \times W^2 \rightarrow U$, $g : U^2 \times V^2 \times W^2 \rightarrow V$, $h : U^2 \times V^2 \times W^2 \rightarrow W$ are continuous differentiable functions and U, V, W are some intervals of real numbers. Also, a solution $\{\mathbf{U}_n, \rho_n, \sigma_n\}_{n=-1}^{\infty}$ of system (1.9) is uniquely defined by the initial values $(\mathbf{U}_{-\mu}, \rho_{-\mu}, \sigma_{-\mu}) \in U \times V \times W$ for $\mu \in \{0, 1\}$. Along with system (1.9), we take into account the suitable vector map $\mathbb{F} = (f, \mathbf{U}_n, g, \rho_n, h, \sigma_n)$. An equilibrium point of system (1.9) is a point $(\bar{\mathbf{U}}, \bar{\rho}, \bar{\sigma})$ that supplies

$$\bar{\mathbf{U}} = f(\bar{\mathbf{U}}, \bar{\mathbf{U}}, \bar{\rho}, \bar{\rho}, \bar{\sigma}, \bar{\sigma}), \quad \bar{\rho} = g(\bar{\mathbf{U}}, \bar{\mathbf{U}}, \bar{\rho}, \bar{\rho}, \bar{\sigma}, \bar{\sigma}), \quad \bar{\sigma} = h(\bar{\mathbf{U}}, \bar{\mathbf{U}}, \bar{\rho}, \bar{\rho}, \bar{\sigma}, \bar{\sigma}).$$

The point $(\bar{\mathbf{U}}, \bar{\mathbf{U}}, \bar{\rho}, \bar{\rho}, \bar{\sigma}, \bar{\sigma})$ is named a fixed point of the vector map \mathbb{F} .

Definition 1. Assume that $(\bar{\mathbf{U}}, \bar{\mathbf{U}}, \bar{\rho}, \bar{\rho}, \bar{\sigma}, \bar{\sigma})$ is a fixed point of the vector map $\mathbb{F} = (f, \mathbf{U}_n, g, \rho_n, h, \sigma_n)$, where f, g and h are continuous differentiable functions at $(\bar{\mathbf{U}}, \bar{\rho}, \bar{\sigma})$. The linearized system given by system (1.9) about the equilibrium point $(\bar{\mathbf{U}}, \bar{\rho}, \bar{\sigma})$ is

$$K_{n+1} = J_{\mathbb{F}} K_n,$$

where $K_n = \begin{pmatrix} \mathbf{U}_n \\ \mathbf{U}_{n-1} \\ \rho_n \\ \rho_{n-1} \\ \sigma_n \\ \sigma_{n-1} \end{pmatrix}$ and $J_{\mathbb{F}}$ is the Jacobian matrix of system (1.9) about the equilibrium point $(\bar{\mathbf{U}}, \bar{\rho}, \bar{\sigma})$.

Lemma 1. Let $K_{n+1} = \mathbb{F}(K_n)$, $n \in \mathbb{N}_0$, be a system of difference equations where \bar{K} is a fixed point of \mathbb{F} . If all eigenvalues of the Jacobian matrix $J_{\mathbb{F}}$ about \bar{K} lie inside the open unit disk $|\lambda| < 1$, then \bar{K} is locally asymptotically stable. If one of them has a modulus greater than one, then \bar{K} is unstable.

Definition 2. If there exist positive constants t and T and an integer $N \geq -1$, the positive solution $\{\mathbf{U}_n, \rho_n, \sigma_n\}_{n=-1}^{\infty}$ of system (1.9) is bounded and persists such that

$$t \leq \mathbf{U}_n, \rho_n, \sigma_n \leq T, \quad n \geq N.$$

The following lemma gives the rate of convergence of solutions of the systems of difference equations.

Lemma 2. ([37])

$$X_{n+1} = [\alpha + \beta(n)] X_n, \tag{1.10}$$

where X_n is a k -dimensional vector, $\alpha \in \mathbb{C}^{k \times k}$ is a constant matrix and $\beta : \mathbb{Z}^+ \rightarrow \mathbb{C}^{k \times k}$ is a matrix function satisfying

$$\|\beta_n\| \rightarrow 0, \text{ when } n \rightarrow \infty, \tag{1.11}$$

where $\|\cdot\|$ denotes any matrix norm which is associated with the vector norm

$$\|(x, y)\| = \sqrt{x^2 + y^2}.$$

2. Global behavior of system (1.7)

Lemma 3. *Every positive solution of system (1.7) is bounded and persists.*

Proof. Suppose that $\{(\Upsilon_n, \Psi_n, \Omega_n)\}$ is an arbitrary solution of system (1.7). We get

$$\Upsilon_n \leq \frac{\Gamma_1 + \delta_1}{\Theta_1} = \Pi_1, \quad \Psi_n \leq \frac{\Gamma_2 + \delta_2}{\Theta_2} = \Pi_2, \quad \Omega_n \leq \frac{\Gamma_3 + \delta_3}{\Theta_3} = \Pi_3, \quad n \in \mathbb{N}. \quad (2.1)$$

Then, from system (1.7) and Eq (2.1), we have

$$\begin{aligned} \Upsilon_n &\geq \frac{\Gamma_1 + \delta_1 e^{-\left(\frac{\Gamma_2 + \delta_2}{\Theta_2}\right)}}{\Theta_1 + \left(\frac{\Gamma_2 + \delta_2}{\Theta_2}\right)} = \Lambda_1, \\ \Psi_n &\geq \frac{\Gamma_2 + \delta_2 e^{-\left(\frac{\Gamma_3 + \delta_3}{\Theta_3}\right)}}{\Theta_2 + \left(\frac{\Gamma_3 + \delta_3}{\Theta_3}\right)} = \Lambda_2, \\ \Omega_n &\geq \frac{\Gamma_3 + \delta_3 e^{-\left(\frac{\Gamma_1 + \delta_1}{\Theta_1}\right)}}{\Theta_3 + \left(\frac{\Gamma_1 + \delta_1}{\Theta_1}\right)} = \Lambda_3, \end{aligned} \quad (2.2)$$

for $n \in \mathbb{N}$.

Therefore, from Eqs (2.1) and (2.2), the proof of the lemma is complete. \square

We can indicate the following lemma, which is useful for our study of system (1.7). We consider the following general system of difference equations:

$$x_{n+1} = f(y_n, y_{n-1}), \quad y_{n+1} = g(z_n, z_{n-1}), \quad z_{n+1} = h(x_n, x_{n-1}), \quad (2.3)$$

where f, g and h are continuous functions and the initial conditions $x_{-1}, x_0, y_{-1}, y_0, z_{-1}$ and z_0 are positive numbers.

Lemma 4. *Let $f, g, h : \mathbb{R}^+ \rightarrow \mathbb{R}^+$, $g : \mathbb{R}^+ \rightarrow \mathbb{R}^+$ and $h : \mathbb{R}^+ \rightarrow \mathbb{R}^+$ be continuous functions. Let a_1, b_1, a_2, b_2, a_3 and b_3 be positive numbers such that $a_1 < b_1, a_2 < b_2, a_3 < b_3$ and*

$$f : [a_2, b_2] \times [a_2, b_2] \rightarrow [a_1, b_1], \quad g : [a_3, b_3] \times [a_3, b_3] \rightarrow [a_2, b_2], \quad h : [a_1, b_1] \times [a_1, b_1] \rightarrow [a_3, b_3].$$

Suppose that the function $f(u, v)$ is a decreasing function with respect to u (resp. v) for every v (resp. u), $g(w, t)$ is a decreasing function with respect to w (resp. t) for all t (resp. w) and $h(p, s)$ is a decreasing function with respect to p (resp. s) for every s (resp. p). Finally, suppose that, if m, M, r, R, t and T are real numbers such that, if

$$M = f(r, r), \quad m = f(R, R), \quad R = g(t, t), \quad r = g(T, T), \quad T = h(m, m), \quad t = h(M, M), \quad (2.4)$$

then $m = M, r = R$ and $t = T$. Then, system (2.3) has a unique positive equilibrium $(\bar{x}, \bar{y}, \bar{z})$ and every positive solution of system (2.3) that satisfies

$$x_{n_0} \in [a_1, b_1], \quad x_{n_0+1} \in [a_1, b_1], \quad y_{n_0} \in [a_2, b_2], \quad y_{n_0+1} \in [a_2, b_2], \quad z_{n_0} \in [a_3, b_3], \quad z_{n_0+1} \in [a_3, b_3], \quad n_0 \in \mathbb{N},$$

tends to the unique positive equilibrium of system (2.3).

Proof. System (2.3) is equivalent to the following system of separated equations:

$$\begin{aligned}
 x_{n+1} &= f(y_n, y_{n-1}) = f(g(z_{n-1}, z_{n-2}), g(z_{n-2}, z_{n-3})) \\
 &= f(g(h(x_{n-2}, x_{n-3}), h(x_{n-3}, x_{n-4})), g(h(x_{n-3}, x_{n-4}), h(x_{n-4}, x_{n-5}))) \\
 &= F(x_{n-2}, x_{n-3}, x_{n-4}, x_{n-5}), n \geq 4, \\
 y_{n+1} &= g(z_n, z_{n-1}) = g(h(x_{n-1}, x_{n-2}), h(x_{n-2}, x_{n-3})) \\
 &= g(h(f(y_{n-2}, y_{n-3}), f(y_{n-3}, y_{n-4})), h(f(y_{n-3}, y_{n-4}), f(y_{n-4}, y_{n-5}))) \\
 &= G(y_{n-2}, y_{n-3}, y_{n-4}, y_{n-5}), n \geq 4, \\
 z_{n+1} &= h(x_n, x_{n-1}) = h(f(y_{n-1}, y_{n-2}), f(y_{n-2}, y_{n-3})) \\
 &= h(f(g(z_{n-2}, z_{n-3}), g(z_{n-3}, z_{n-4})), f(g(z_{n-3}, z_{n-4}), g(z_{n-4}, z_{n-5}))) \\
 &= H(z_{n-2}, z_{n-3}, z_{n-4}, z_{n-5}), n \geq 4.
 \end{aligned}$$

We consider the equation

$$x_{n+1} = F(x_{n-2}, x_{n-3}, x_{n-4}, x_{n-5}). \quad (2.5)$$

From the conditions of f, g, h , we have that $F : [a_1, b_1] \times [a_1, b_1] \times [a_1, b_1] \rightarrow [a_1, b_1]$ and $F(\alpha, \beta, \gamma, \delta)$ is increasing in α for all β, γ, δ ; increasing in β for all α, γ, δ ; increasing in γ for all α, β, δ ; increasing in δ for all α, β, γ . Now, let us take m and M as positive numbers so that

$$\begin{aligned}
 M &= F(M, M, M, M) = f(g(h(M, M), h(M, M)), g(h(M, M), h(M, M))), \\
 m &= F(m, m, m, m) = f(g(h(m, m), h(m, m)), g(h(m, m), h(m, m))).
 \end{aligned}$$

By setting $h(m, m) = T$ and $h(M, M) = t$, we get

$$\begin{aligned}
 M &= f(g(t, t), g(t, t)), \\
 m &= f(g(T, T), g(T, T)).
 \end{aligned}$$

By setting $g(t, t) = R$ and $g(T, T) = r$, we have that the relations given by Eq (2.4) are satisfied. Then, from a hypothesis of Lemma 4, we have that $m = M$. Equation (2.5) has a unique positive equilibrium \bar{x} , and every positive solution of Eq (2.5) tends to the unique positive equilibrium \bar{x} . Similarly, we can prove that the equation

$$y_{n+1} = G(y_{n-2}, y_{n-3}, y_{n-4}, y_{n-5}), \quad (2.6)$$

has a unique positive equilibrium \bar{y} and every positive solution of Eq (2.6) tends to the unique positive equilibrium \bar{y} . Similarly, we can prove that the equation

$$z_{n+1} = H(z_{n-2}, z_{n-3}, z_{n-4}, z_{n-5}), \quad (2.7)$$

has a unique positive equilibrium \bar{z} and every positive solution of Eq (2.7) tends to the unique positive equilibrium \bar{z} . This completes the proof of the lemma. \square

2.1. Local and global asymptotic stability

Theorem 3. For the local stability about $(\bar{\Upsilon}, \bar{\Psi}, \bar{\Omega}) \in [\Lambda_1, \Pi_1] \times [\Lambda_2, \Pi_2] \times [\Lambda_3, \Pi_3]$, i.e., the equilibrium point of system (1.7), the next declarations are valid:

(i) $(\bar{\Upsilon}, \bar{\Psi}, \bar{\Omega})$ is locally asymptotically stable if $L_1 < 1$,

(ii) $(\bar{\Upsilon}, \bar{\Psi}, \bar{\Omega})$ is unstable if $U_1 > 1$,

where

$$L_1 = \frac{1}{\Theta_1 \Theta_2 \Theta_3} \left(\Lambda_1 \Lambda_2 \Lambda_3 + e^{-1} \left(\delta_1 (\Lambda_3 + \delta_2 e^{-\Lambda_2}) + \delta_2 (\Lambda_1 + \delta_3 e^{-\Lambda_3}) \right. \right. \\ \left. \left. + \delta_3 (\Lambda_2 + \delta_1 e^{-\Lambda_1}) \right) + \delta_1 \delta_2 \delta_3 \right), \quad (2.8)$$

$$U_1 = \frac{1}{(\Theta_1 + \Pi_2)(\Theta_2 + \Pi_3)(\Theta_3 + \Pi_1)} \left(\frac{(\Gamma_1 + \delta_1 e^{-\Pi_2})(\Gamma_2 + \delta_2 e^{-\Pi_3})(\Gamma_3 + \delta_3 e^{-\Pi_1})}{(\Theta_1 + \Pi_2)(\Theta_2 + \Pi_3)(\Theta_3 + \Pi_1)} + \delta_1 \delta_2 \delta_3 e^{-\Pi_1 - \Pi_2 - \Pi_3} \right) \\ + \frac{(\Gamma_2 + \delta_2 e^{-\Pi_3})}{(\Theta_1 + \Pi_2)(\Theta_2 + \Pi_3)^2(\Theta_3 + \Pi_1)} \left(\frac{(\Gamma_1 + \delta_1 e^{-\Pi_2}) \delta_3 e^{-\Pi_1}}{(\Theta_1 + \Pi_2)} + \frac{(\Gamma_3 + \delta_3 e^{-\Pi_1}) \delta_1 e^{-\Pi_2}}{(\Theta_3 + \Pi_1)} \right) \\ + \frac{(\Gamma_1 + \delta_1 e^{-\Pi_2}) \delta_2 e^{-\Pi_3}}{(\Theta_1 + \Pi_2)(\Theta_2 + \Pi_3)(\Theta_3 + \Pi_1)} \left(\frac{(\Gamma_3 + \delta_3 e^{-\Pi_1})}{(\Theta_1 + \Pi_2)(\Theta_3 + \Pi_1)} + \frac{\delta_3 e^{-\Pi_1}}{(\Theta_1 + \Pi_2)} \right) \\ + \frac{\delta_1 e^{-\Pi_2}}{(\Theta_1 + \Pi_2)(\Theta_2 + \Pi_3)(\Theta_3 + \Pi_1)} \left(\frac{(\Gamma_2 + \delta_2 e^{-\Pi_3}) \delta_3 e^{-\Pi_1}}{(\Theta_2 + \Pi_3)} + \frac{(\Gamma_3 + \delta_3 e^{-\Pi_1}) \delta_2 e^{-\Pi_3}}{(\Theta_3 + \Pi_1)} \right). \quad (2.9)$$

Proof. (i) From system (1.7), we obtain

$$\bar{\Upsilon} = \frac{\Gamma_1 + \delta_1 e^{-\bar{\Psi}}}{\Theta_1 + \bar{\Psi}}, \quad \bar{\Psi} = \frac{\Gamma_2 + \delta_2 e^{-\bar{\Omega}}}{\Theta_2 + \bar{\Omega}}, \quad \bar{\Omega} = \frac{\Gamma_3 + \delta_3 e^{-\bar{\Upsilon}}}{\Theta_3 + \bar{\Upsilon}}. \quad (2.10)$$

In order to construct the corresponding linearized form of system (1.7), we consider the following transformation:

$$(\Upsilon_{n+1}, \Psi_n, \Omega_n, \Upsilon_n, \Psi_n, \Omega_n) \rightarrow (f, f_1, g, g_1, h, h_1), \quad (2.11)$$

where

$$f = \frac{\Gamma_1 + \delta_1 e^{-\Psi_{n-1}}}{\Theta_1 + \Psi_n}, \quad f_1 = \Upsilon_n, \\ g = \frac{\Gamma_2 + \delta_2 e^{-\Omega_{n-1}}}{\Theta_2 + \Omega_n}, \quad g_1 = \Psi_n, \\ h = \frac{\Gamma_3 + \delta_3 e^{-\Upsilon_{n-1}}}{\Theta_3 + \Upsilon_n}, \quad h_1 = \Omega_n. \quad (2.12)$$

By using the transformation given by Eq (2.11), we obtain

$$F_J(\bar{\Upsilon}, \bar{\Psi}, \bar{\Omega}) = \begin{pmatrix} 0 & 0 & s_1 & t_1 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & s_2 & t_2 \\ 0 & 0 & 1 & 0 & 0 & 0 \\ s_3 & t_3 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 \end{pmatrix}, \quad (2.13)$$

where

$$\begin{aligned} s_1 &= -\frac{\Gamma_1 + \delta_1 e^{-\bar{\Psi}}}{(\Theta_1 + \bar{\Psi})^2}, \quad t_1 = -\frac{\delta_1 e^{-\bar{\Psi}}}{\Theta_1 + \bar{\Psi}}, \\ s_2 &= -\frac{\Gamma_2 + \delta_2 e^{-\bar{\Omega}}}{(\Theta_2 + \bar{\Omega})^2}, \quad t_2 = -\frac{\delta_2 e^{-\bar{\Omega}}}{\Theta_2 + \bar{\Omega}}, \\ s_3 &= -\frac{\Gamma_3 + \delta_3 e^{-\bar{\Upsilon}}}{(\Theta_3 + \bar{\Upsilon})^2}, \quad t_3 = -\frac{\delta_3 e^{-\bar{\Upsilon}}}{\Theta_3 + \bar{\Upsilon}}. \end{aligned} \quad (2.14)$$

The characteristic equation of $F_J(\bar{\Upsilon}, \bar{\Psi}, \bar{\Omega})$ is below:

$$\lambda^6 + m_1 \lambda^3 + m_2 \lambda^2 + m_3 \lambda + m_4 = 0, \quad (2.15)$$

where

$$\begin{aligned} m_1 &= -s_1 s_2 s_3, \\ m_2 &= -(s_1 s_2 t_3 + s_1 t_2 s_3 + t_1 s_2 s_3), \\ m_3 &= -(s_1 t_2 t_3 + t_1 s_2 t_3 + t_1 t_2 s_3), \\ m_4 &= -t_1 t_2 t_3. \end{aligned} \quad (2.16)$$

Because $x e^{-x} < e^{-1}$, for $x > 0$, we have

$$\begin{aligned} \sum_{i=1}^4 |m_i| &= \frac{(\Gamma_1 + \delta_1 e^{-\bar{\Psi}})(\Gamma_2 + \delta_2 e^{-\bar{\Omega}})(\Gamma_3 + \delta_3 e^{-\bar{\Upsilon}})}{(\Theta_1 + \bar{\Psi})^2 (\Theta_2 + \bar{\Omega})^2 (\Theta_3 + \bar{\Upsilon})^2} \\ &\quad + \frac{(\Gamma_1 + \delta_1 e^{-\bar{\Psi}})(\Gamma_2 + \delta_2 e^{-\bar{\Omega}})\delta_3 e^{-\bar{\Upsilon}}}{(\Theta_1 + \bar{\Psi})^2 (\Theta_2 + \bar{\Omega})^2 (\Theta_3 + \bar{\Upsilon})} + \frac{(\Gamma_1 + \delta_1 e^{-\bar{\Psi}})\delta_2 e^{-\bar{\Omega}}(\Gamma_3 + \delta_3 e^{-\bar{\Upsilon}})}{(\Theta_1 + \bar{\Psi})^2 (\Theta_2 + \bar{\Omega})(\Theta_3 + \bar{\Upsilon})^2} \\ &\quad + \frac{\delta_1 e^{-\bar{\Psi}}(\Gamma_2 + \delta_2 e^{-\bar{\Omega}})(\Gamma_3 + \delta_3 e^{-\bar{\Upsilon}})}{(\Theta_1 + \bar{\Psi})(\Theta_2 + \bar{\Omega})^2 (\Theta_3 + \bar{\Upsilon})^2} + \frac{(\Gamma_1 + \delta_1 e^{-\bar{\Psi}})\delta_2 \delta_3 e^{-\bar{\Omega}-\bar{\Upsilon}}}{(\Theta_1 + \bar{\Psi})^2 (\Theta_2 + \bar{\Omega})(\Theta_3 + \bar{\Upsilon})} \\ &\quad + \frac{(\Gamma_2 + \delta_2 e^{-\bar{\Omega}})\delta_1 \delta_3 e^{-\bar{\Psi}-\bar{\Upsilon}}}{(\Theta_1 + \bar{\Psi})(\Theta_2 + \bar{\Omega})^2 (\Theta_3 + \bar{\Upsilon})} + \frac{(\Gamma_3 + \delta_3 e^{-\bar{\Upsilon}})\delta_1 \delta_2 e^{-\bar{\Psi}-\bar{\Omega}}}{(\Theta_1 + \bar{\Psi})(\Theta_2 + \bar{\Omega})(\Theta_3 + \bar{\Upsilon})^2} \end{aligned}$$

$$\begin{aligned}
& + \frac{\delta_1 \delta_2 \delta_3 e^{-\bar{\Upsilon} - \bar{\Psi} - \bar{\Omega}}}{(\Theta_1 + \bar{\Psi})(\Theta_2 + \bar{\Omega})(\Theta_3 + \bar{\Upsilon})} \\
& = \frac{\bar{\Upsilon} \bar{\Psi} \bar{\Omega}}{(\Theta_1 + \bar{\Psi})(\Theta_2 + \bar{\Omega})(\Theta_3 + \bar{\Upsilon})} + \frac{\bar{\Psi} \delta_3 e^{-\bar{\Upsilon} \bar{\Upsilon}}}{(\Theta_1 + \bar{\Psi})(\Theta_2 + \bar{\Omega})(\Theta_3 + \bar{\Upsilon})} \\
& + \frac{\bar{\Upsilon} \delta_2 e^{-\bar{\Omega} \bar{\Omega}}}{(\Theta_1 + \bar{\Psi})(\Theta_2 + \bar{\Omega})(\Theta_3 + \bar{\Upsilon})} + \frac{\bar{\Omega} \delta_1 e^{-\bar{\Psi} \bar{\Psi}}}{(\Theta_1 + \bar{\Psi})(\Theta_2 + \bar{\Omega})(\Theta_3 + \bar{\Upsilon})} \\
& + \frac{\delta_3 e^{-\bar{\Upsilon} \bar{\Upsilon}} \delta_2 e^{-\bar{\Omega}}}{(\Theta_1 + \bar{\Psi})(\Theta_2 + \bar{\Omega})(\Theta_3 + \bar{\Upsilon})} + \frac{\delta_1 e^{-\bar{\Psi} \bar{\Psi}} \delta_3 e^{-\bar{\Upsilon}}}{(\Theta_1 + \bar{\Psi})(\Theta_2 + \bar{\Omega})(\Theta_3 + \bar{\Upsilon})} \\
& + \frac{\delta_2 e^{-\bar{\Omega} \bar{\Omega}} \delta_1 e^{-\bar{\Psi}}}{(\Theta_1 + \bar{\Psi})(\Theta_2 + \bar{\Omega})(\Theta_3 + \bar{\Upsilon})} + \frac{\delta_1 \delta_2 \delta_3 e^{-\bar{\Upsilon} - \bar{\Psi} - \bar{\Omega}}}{(\Theta_1 + \bar{\Psi})(\Theta_2 + \bar{\Omega})(\Theta_3 + \bar{\Upsilon})} \\
& < \frac{\bar{\Upsilon} \bar{\Psi} \bar{\Omega}}{\Theta_1 \Theta_2 \Theta_3} + \frac{e^{-1} (\delta_3 \bar{\Psi} + \delta_2 \bar{\Upsilon} + \delta_1 \bar{\Omega} + \delta_2 \delta_3 e^{-\bar{\Omega}} + \delta_1 \delta_3 e^{-\bar{\Upsilon}} + \delta_1 \delta_2 e^{-\bar{\Psi}})}{\Theta_1 \Theta_2 \Theta_3} \\
& + \frac{\delta_1 \delta_2 \delta_3}{\Theta_1 \Theta_2 \Theta_3} \\
& < \frac{1}{\Theta_1 \Theta_2 \Theta_3} \left(\Lambda_1 \Lambda_2 \Lambda_3 + e^{-1} (\delta_1 (\Lambda_3 + \delta_2 e^{-\Lambda_2}) + \delta_2 (\Lambda_1 + \delta_3 e^{-\Lambda_3}) + \delta_3 (\Lambda_2 + \delta_1 e^{-\Lambda_1})) \right) \\
& \quad + \delta_1 \delta_2 \delta_3 \Big) < 1.
\end{aligned} \tag{2.17}$$

By supposing that $L_1 < 1$, from Eq (2.17), we have that $\sum_{i=1}^4 |m_i| < 1$. According to the Rouche theorem, $(\bar{\Upsilon}, \bar{\Psi}, \bar{\Omega})$ is locally asymptotically stable.

(ii) We get

$$\begin{aligned}
\sum_{i=1}^4 |m_i| &= \frac{(\Gamma_1 + \delta_1 e^{-\bar{\Psi}})(\Gamma_2 + \delta_2 e^{-\bar{\Omega}})(\Gamma_3 + \delta_3 e^{-\bar{\Upsilon}})}{(\Theta_1 + \bar{\Psi})^2 (\Theta_2 + \bar{\Omega})^2 (\Theta_3 + \bar{\Upsilon})^2} \\
&+ \frac{(\Gamma_1 + \delta_1 e^{-\bar{\Psi}})(\Gamma_2 + \delta_2 e^{-\bar{\Omega}}) \delta_3 e^{-\bar{\Upsilon}}}{(\Theta_1 + \bar{\Psi})^2 (\Theta_2 + \bar{\Omega})^2 (\Theta_3 + \bar{\Upsilon})} + \frac{(\Gamma_1 + \delta_1 e^{-\bar{\Psi}}) \delta_2 e^{-\bar{\Omega}} (\Gamma_3 + \delta_3 e^{-\bar{\Upsilon}})}{(\Theta_1 + \bar{\Psi})^2 (\Theta_2 + \bar{\Omega}) (\Theta_3 + \bar{\Upsilon})^2} \\
&+ \frac{\delta_1 e^{-\bar{\Psi}} (\Gamma_2 + \delta_2 e^{-\bar{\Omega}}) (\Gamma_3 + \delta_3 e^{-\bar{\Upsilon}})}{(\Theta_1 + \bar{\Psi}) (\Theta_2 + \bar{\Omega})^2 (\Theta_3 + \bar{\Upsilon})^2} + \frac{(\Gamma_1 + \delta_1 e^{-\bar{\Psi}}) \delta_2 \delta_3 e^{-\bar{\Omega} - \bar{\Upsilon}}}{(\Theta_1 + \bar{\Psi})^2 (\Theta_2 + \bar{\Omega}) (\Theta_3 + \bar{\Upsilon})} \\
&+ \frac{(\Gamma_2 + \delta_2 e^{-\bar{\Omega}}) \delta_1 \delta_3 e^{-\bar{\Psi} - \bar{\Upsilon}}}{(\Theta_1 + \bar{\Psi}) (\Theta_2 + \bar{\Omega})^2 (\Theta_3 + \bar{\Upsilon})} + \frac{(\Gamma_3 + \delta_3 e^{-\bar{\Upsilon}}) \delta_1 \delta_2 e^{-\bar{\Psi} - \bar{\Omega}}}{(\Theta_1 + \bar{\Psi}) (\Theta_2 + \bar{\Omega}) (\Theta_3 + \bar{\Upsilon})^2} \\
&+ \frac{\delta_1 \delta_2 \delta_3 e^{-\bar{\Upsilon} - \bar{\Psi} - \bar{\Omega}}}{(\Theta_1 + \bar{\Psi}) (\Theta_2 + \bar{\Omega}) (\Theta_3 + \bar{\Upsilon})}
\end{aligned}$$

$$\begin{aligned}
&\geq \frac{(\Gamma_1 + \delta_1 e^{-\Pi_2})(\Gamma_2 + \delta_2 e^{-\Pi_3})(\Gamma_3 + \delta_3 e^{-\Pi_1})}{(\Theta_1 + \Pi_2)^2 (\Theta_2 + \Pi_3)^2 (\Theta_3 + \Pi_1)^2} \\
&+ \frac{(\Gamma_1 + \delta_1 e^{-\Pi_2})(\Gamma_2 + \delta_2 e^{-\Pi_3})\delta_3 e^{-\Pi_1}}{(\Theta_1 + \Pi_2)^2 (\Theta_2 + \Pi_3)^2 (\Theta_3 + \Pi_1)} + \frac{(\Gamma_1 + \delta_1 e^{-\Pi_2})\delta_2 e^{-\Pi_3}(\Gamma_3 + \delta_3 e^{-\Pi_1})}{(\Theta_1 + \Pi_2)^2 (\Theta_2 + \Pi_3) (\Theta_3 + \Pi_1)^2} \\
&+ \frac{\delta_1 e^{-\Pi_2}(\Gamma_2 + \delta_2 e^{-\Pi_3})(\Gamma_3 + \delta_3 e^{-\Pi_1})}{(\Theta_1 + \Pi_2)(\Theta_2 + \Pi_3)^2 (\Theta_3 + \Pi_1)^2} + \frac{(\Gamma_1 + \delta_1 e^{-\Pi_2})\delta_2 \delta_3 e^{-\Pi_3 - \Pi_1}}{(\Theta_1 + \Pi_2)^2 (\Theta_2 + \Pi_3) (\Theta_3 + \Pi_1)} \\
&+ \frac{(\Gamma_2 + \delta_2 e^{-\Pi_3})\delta_1 \delta_3 e^{-\Pi_2 - \Pi_1}}{(\Theta_1 + \Pi_2)(\Theta_2 + \Pi_3)^2 (\Theta_3 + \Pi_1)} + \frac{(\Gamma_3 + \delta_3 e^{-\Pi_1})\delta_1 \delta_2 e^{-\Pi_2 - \Pi_3}}{(\Theta_1 + \Pi_2)(\Theta_2 + \Pi_3) (\Theta_3 + \Pi_1)^2} \\
&+ \frac{\delta_1 \delta_2 \delta_3 e^{-\Pi_1 - \Pi_2 - \Pi_3}}{(\Theta_1 + \Pi_2)(\Theta_2 + \Pi_3)(\Theta_3 + \Pi_1)} \\
&= \frac{1}{(\Theta_1 + \Pi_2)(\Theta_2 + \Pi_3)(\Theta_3 + \Pi_1)} \left(\frac{(\Gamma_1 + \delta_1 e^{-\Pi_2})(\Gamma_2 + \delta_2 e^{-\Pi_3})(\Gamma_3 + \delta_3 e^{-\Pi_1})}{(\Theta_1 + \Pi_2)(\Theta_2 + \Pi_3)(\Theta_3 + \Pi_1)} + \delta_1 \delta_2 \delta_3 e^{-\Pi_1 - \Pi_2 - \Pi_3} \right) \\
&+ \frac{(\Gamma_2 + \delta_2 e^{-\Pi_3})}{(\Theta_1 + \Pi_2)(\Theta_2 + \Pi_3)^2 (\Theta_3 + \Pi_1)} \left(\frac{(\Gamma_1 + \delta_1 e^{-\Pi_2})\delta_3 e^{-\Pi_1}}{(\Theta_1 + \Pi_2)} + \frac{(\Gamma_3 + \delta_3 e^{-\Pi_1})\delta_1 e^{-\Pi_2}}{(\Theta_3 + \Pi_1)} \right) \\
&+ \frac{(\Gamma_1 + \delta_1 e^{-\Pi_2})\delta_2 e^{-\Pi_3}}{(\Theta_1 + \Pi_2)(\Theta_2 + \Pi_3)(\Theta_3 + \Pi_1)} \left(\frac{(\Gamma_3 + \delta_3 e^{-\Pi_1})}{(\Theta_1 + \Pi_2)(\Theta_3 + \Pi_1)} + \frac{\delta_3 e^{-\Pi_1}}{(\Theta_1 + \Pi_2)} \right) \\
&+ \frac{\delta_1 e^{-\Pi_2}}{(\Theta_1 + \Pi_2)(\Theta_2 + \Pi_3)(\Theta_3 + \Pi_1)} \left(\frac{(\Gamma_2 + \delta_2 e^{-\Pi_3})\delta_3 e^{-\Pi_1}}{(\Theta_2 + \Pi_3)} + \frac{(\Gamma_3 + \delta_3 e^{-\Pi_1})\delta_2 e^{-\Pi_3}}{(\Theta_3 + \Pi_1)} \right) > 1.
\end{aligned} \tag{2.18}$$

By supposing that $U_1 > 1$, from Eq (2.18), we have that $\sum_{i=1}^4 |m_i| > 1$. According to the Rouche theorem, $(\bar{\Upsilon}, \bar{\Psi}, \bar{\Omega})$ is unstable. \square

Theorem 4. System (1.7) has a unique positive equilibrium $(\bar{\Upsilon}, \bar{\Psi}, \bar{\Omega})$, and every positive solution of system (1.7) tends to the unique positive equilibrium of system (1.7) as $n \rightarrow \infty$ if

$$\begin{aligned}
&\delta_1, \delta_3 < \Theta_2, \\
&\delta_1, \delta_2 < \Theta_3, \\
&\delta_2, \delta_3 < \Theta_1.
\end{aligned} \tag{2.19}$$

Proof. We consider the functions

$$f(u, v) = \frac{\Gamma_1 + \delta_1 e^{-u}}{\Theta_1 + v}, \quad g(w, t) = \frac{\Gamma_2 + \delta_2 e^{-w}}{\Theta_2 + t}, \quad h(k, l) = \frac{\Gamma_3 + \delta_3 e^{-k}}{\Theta_3 + l}, \tag{2.20}$$

where

$$\begin{aligned}
k, l \in [\Lambda_1, \Pi_1] &= \left[\frac{\Gamma_1 + \delta_1 e^{-\left(\frac{\Gamma_2 + \delta_2}{\Theta_2}\right)}}{\Theta_1 + \left(\frac{\Gamma_2 + \delta_2}{\Theta_2}\right)}, \frac{\Gamma_1 + \delta_1}{\Theta_1} \right], \\
u, v \in [\Lambda_2, \Pi_2] &= \left[\frac{\Gamma_2 + \delta_2 e^{-\left(\frac{\Gamma_3 + \delta_3}{\Theta_3}\right)}}{\Theta_2 + \left(\frac{\Gamma_3 + \delta_3}{\Theta_3}\right)}, \frac{\Gamma_2 + \delta_2}{\Theta_2} \right], \\
w, t \in [\Lambda_3, \Pi_3] &= \left[\frac{\Gamma_3 + \delta_3 e^{-\left(\frac{\Gamma_1 + \delta_1}{\Theta_1}\right)}}{\Theta_3 + \left(\frac{\Gamma_1 + \delta_1}{\Theta_1}\right)}, \frac{\Gamma_3 + \delta_3}{\Theta_3} \right].
\end{aligned} \tag{2.21}$$

From Eqs (2.20) and (2.21) we get the following relations for $k, l \in [\Lambda_1, \Pi_1]$, $u, v \in [\Lambda_2, \Pi_2]$ and $w, t \in [\Lambda_3, \Pi_3]$:

$$f(u, v) \in [\Lambda_1, \Pi_1], g(w, t) \in [\Lambda_2, \Pi_2], h(k, l) \in [\Lambda_3, \Pi_3];$$

thus, $f : [\Lambda_2, \Pi_2] \times [\Lambda_2, \Pi_2] \rightarrow [\Lambda_1, \Pi_1]$, $g : [\Lambda_3, \Pi_3] \times [\Lambda_3, \Pi_3] \rightarrow [\Lambda_2, \Pi_2]$ and $h : [\Lambda_1, \Pi_1] \times [\Lambda_1, \Pi_1] \rightarrow [\Lambda_3, \Pi_3]$. Let $\{(\Upsilon_n, \Psi_n, \Omega_n)\}$ be an arbitrary solution of system (1.7). Therefore, from Lemma 3, for $n \in \mathbb{N}$, we get

$$\Upsilon_n \in [\Lambda_1, \Pi_1], \Psi_n \in [\Lambda_2, \Pi_2], \Omega_n \in [\Lambda_3, \Pi_3].$$

Now, let m, M, r, R, t and T be positive numbers such that

$$\begin{aligned}
M &= \frac{\Gamma_1 + \delta_1 e^{-r}}{\Theta_1 + r}, \quad m = \frac{\Gamma_1 + \delta_1 e^{-R}}{\Theta_1 + R}, \\
R &= \frac{\Gamma_2 + \delta_2 e^{-t}}{\Theta_2 + t}, \quad r = \frac{\Gamma_2 + \delta_2 e^{-T}}{\Theta_2 + T}, \\
T &= \frac{\Gamma_3 + \delta_3 e^{-m}}{\Theta_3 + m}, \quad t = \frac{\Gamma_3 + \delta_3 e^{-M}}{\Theta_3 + M}.
\end{aligned} \tag{2.22}$$

Then, we consider the functions

$$F(x) = \frac{\Gamma_1 + \delta_1 e^{-q_1(x)}}{\Theta_1 + q_1(x)} - x, \quad q_1(x) = \frac{\Gamma_3 + \delta_3 e^{-x}}{\Theta_3 + x}, \quad x \in [\Lambda_1, \Pi_1], \tag{2.23}$$

$$G(y) = \frac{\Gamma_2 + \delta_2 e^{-q_2(y)}}{\Theta_2 + q_2(y)} - y, \quad q_2(y) = \frac{\Gamma_1 + \delta_1 e^{-y}}{\Theta_1 + y}, \quad y \in [\Lambda_2, \Pi_2], \tag{2.24}$$

$$H(z) = \frac{\Gamma_3 + \delta_3 e^{-q_3(z)}}{\Theta_3 + q_3(z)} - z, \quad q_3(z) = \frac{\Gamma_2 + \delta_2 e^{-z}}{\Theta_2 + z}, \quad z \in [\Lambda_3, \Pi_3]. \tag{2.25}$$

Note that F maps the interval $[\Lambda_1, \Pi_1]$ into itself. We claim that the equation $F(x) = 0$ has a unique solution in $[\Lambda_1, \Pi_1]$. From Eq (2.23), we get

$$\begin{aligned} F'(x) &= -q'_1(x) \frac{\delta_1 e^{-q_1(x)} (\Theta_1 + q_1(x)) + \Gamma_1 + \delta_1 e^{-q_1(x)}}{(\Theta_1 + q_1(x))^2} - 1, \\ q'_1(x) &= -\frac{\delta_3 e^{-x} (\Theta_3 + x) + (\Gamma_3 + \delta_3 e^{-x})}{(\Theta_3 + x)^2}, \quad x \in [\Lambda_1, \Pi_1]. \end{aligned} \quad (2.26)$$

Let $\bar{x}, \bar{x} \in [\Lambda_1, \Pi_1]$ be a solution of the equation $F(x) = 0$. Then, from Eq (2.23), we get

$$\bar{x}(\Theta_1 + q_1(\bar{x})) = \Gamma_1 + \delta_1 e^{-q_1(\bar{x})}, \quad q_1(\bar{x})(\Theta_3 + \bar{x}) = \Gamma_3 + \delta_3 e^{-\bar{x}}. \quad (2.27)$$

Now, observe that Eqs (2.26) and (2.27) imply that

$$q'_1(\bar{x}) = -\frac{\delta_3 e^{-\bar{x}} + q_1(\bar{x})}{\Theta_3 + \bar{x}}, \quad \frac{\delta_1 e^{-q_1(\bar{x})} (\Theta_1 + q_1(\bar{x})) + \Gamma_1 + \delta_1 e^{-q_1(\bar{x})}}{(\Theta_1 + q_1(\bar{x}))^2} = \frac{\delta_1 e^{-q_1(\bar{x})} + \bar{x}}{\Theta_1 + q_1(\bar{x})}. \quad (2.28)$$

Then, from Eqs (2.19), (2.26) and (2.28), we have

$$F'(\bar{x}) = \frac{\delta_3 e^{-\bar{x}} + q_1(\bar{x})}{\Theta_1 + q_1(\bar{x})} \times \frac{\delta_1 e^{-q_1(\bar{x})} + \bar{x}}{\Theta_3 + \bar{x}} - 1 < 0. \quad (2.29)$$

Therefore, from Eq (2.29), we see that the equation $F(x) = 0$ has a unique solution in $[\Lambda_1, \Pi_1]$.

Note that G maps the interval $[\Lambda_2, \Pi_2]$ into itself. We claim that the equation $G(y) = 0$ has a unique solution in $[\Lambda_2, \Pi_2]$. From Eq (2.24), we get

$$\begin{aligned} G'(y) &= -q'_2(y) \frac{\delta_2 e^{-q_2(y)} (\Theta_2 + q_2(y)) + \Gamma_2 + \delta_2 e^{-q_2(y)}}{(\Theta_2 + q_2(y))^2} - 1, \\ q'_2(y) &= -\frac{\delta_1 e^{-y} (\Theta_1 + y) + (\Gamma_1 + \delta_1 e^{-y})}{(\Theta_1 + y)^2}, \quad y \in [\Lambda_2, \Pi_2]. \end{aligned} \quad (2.30)$$

Let $\bar{y}, \bar{y} \in [\Lambda_2, \Pi_2]$ be a solution of the equation $G(y) = 0$. Then, from Eq (2.24), we get

$$\bar{y}(\Theta_2 + q_2(\bar{y})) = \Gamma_2 + \delta_2 e^{-q_2(\bar{y})}, \quad q_2(\bar{y})(\Theta_1 + \bar{y}) = \Gamma_1 + \delta_1 e^{-\bar{y}}. \quad (2.31)$$

Now, observe that Eqs (2.30) and (2.31) imply that

$$q'_2(\bar{y}) = -\frac{\delta_1 e^{-\bar{y}} + q_2(\bar{y})}{\Theta_1 + \bar{y}}, \quad \frac{\delta_2 e^{-q_2(\bar{y})} (\Theta_2 + q_2(\bar{y})) + \Gamma_2 + \delta_2 e^{-q_2(\bar{y})}}{(\Theta_2 + q_2(\bar{y}))^2} = \frac{\delta_2 e^{-q_2(\bar{y})} + \bar{y}}{\Theta_2 + q_2(\bar{y})}. \quad (2.32)$$

Then, from Eqs (2.19), (2.30) and (2.32), we have

$$G'(\bar{y}) = \frac{\delta_1 e^{-\bar{y}} + q_2(\bar{y})}{\Theta_2 + q_2(\bar{y})} \times \frac{\delta_2 e^{-q_2(\bar{y})} + \bar{y}}{\Theta_1 + \bar{y}} - 1 < 0. \quad (2.33)$$

Therefore, from Eq (2.33), we see that the equation $G(y) = 0$ has a unique solution in $[\Lambda_2, \Pi_2]$.

Note that H maps the interval $[\Lambda_3, \Pi_3]$ into itself. We claim that the equation $H(z) = 0$ has a unique solution in $[\Lambda_3, \Pi_3]$. From Eq (2.25), we get

$$\begin{aligned} H'(z) &= -q'_3(z) \frac{\delta_3 e^{-q_3(z)} (\Theta_3 + q_3(z)) + \Gamma_3 + \delta_3 e^{-q_3(z)}}{(\Theta_3 + q_3(z))^2} - 1, \\ q'_3(z) &= -\frac{\delta_2 e^{-z} (\Theta_2 + z) + (\Gamma_2 + \delta_2 e^{-z})}{(\Theta_2 + z)^2}, \quad z \in [\Lambda_3, \Pi_3]. \end{aligned} \quad (2.34)$$

Let $\bar{z}, \bar{z} \in [\Lambda_3, \Pi_3]$ be a solution of the equation $H(z) = 0$. Then, from Eq (2.25), we get

$$\bar{z}(\Theta_3 + q_3(\bar{z})) = \Gamma_3 + \delta_3 e^{-q_3(\bar{z})}, \quad q_3(\bar{z})(\Theta_2 + \bar{z}) = \Gamma_2 + \delta_2 e^{-\bar{z}}. \quad (2.35)$$

Now, observe that Eqs (2.34) and (2.35) imply that

$$q'_3(\bar{z}) = -\frac{\delta_2 e^{-\bar{z}} + q_3(\bar{z})}{\Theta_2 + \bar{z}}, \quad \frac{\delta_3 e^{-q_3(\bar{z})} (\Theta_3 + q_3(\bar{z})) + \Gamma_3 + \delta_3 e^{-q_3(\bar{z})}}{(\Theta_3 + q_3(\bar{z}))^2} = \frac{\delta_3 e^{-q_3(\bar{z})} + \bar{z}}{\Theta_3 + q_3(\bar{z})}. \quad (2.36)$$

Then, from Eqs (2.19), (2.34) and (2.36), we have

$$H'(\bar{z}) = \frac{\delta_2 e^{-\bar{z}} + q_3(\bar{z})}{\Theta_3 + q_3(\bar{z})} \times \frac{\delta_3 e^{-q_3(\bar{z})} + \bar{z}}{\Theta_2 + \bar{z}} - 1 < 0. \quad (2.37)$$

Therefore, from Eq (2.37) we see that the equation $H(z) = 0$ has a unique solution in $[\Lambda_3, \Pi_3]$.

In addition, Eq (2.22) implies that m and M are roots of $F(x) = 0$. Hence, we get that $m = M$. Similarly, Eq (2.22) implies that r and R are roots of $G(y) = 0$. Hence, we get that $r = R$. Finally, Eq (2.22) implies that t and T are roots of $H(z) = 0$. Hence, we get that $t = T$. From Lemma 4, system (1.7) has a unique positive equilibrium $(\bar{\Upsilon}, \bar{\Psi}, \bar{\Omega})$ and every positive solution of system (1.7) tends to the unique positive equilibrium as $n \rightarrow \infty$. This completes the proof of the theorem.

2.2. Rate of convergence

□

Theorem 5. If $\{(\Upsilon_n, \Psi_n, \Omega_n)\}_{n=-1}^\infty$ is a positive solution of system (1.7) such that

$$\lim_{n \rightarrow \infty} \Upsilon_n = \bar{\Upsilon}, \quad \lim_{n \rightarrow \infty} \Psi_n = \bar{\Psi}, \quad \lim_{n \rightarrow \infty} \Omega_n = \bar{\Omega}, \quad (2.38)$$

where

$$\bar{\Upsilon} \in [\Lambda_1, \Pi_1], \quad \bar{\Psi} \in [\Lambda_2, \Pi_2], \quad \bar{\Omega} \in [\Lambda_3, \Pi_3], \quad (2.39)$$

then the error vector $\Phi_n = (\Phi_n^1, \Phi_{n-1}^1, \Phi_n^2, \Phi_{n-1}^2, \Phi_n^3, \Phi_{n-1}^3)^T$ of every solution of system (1.7) supplies both of the following asymptotic relations:

$$\begin{aligned} \lim_{n \rightarrow \infty} (\|\Phi_n\|)^{\frac{1}{n}} &= \left| \lambda_{1,2,3,4,5,6} F_J(\bar{\Upsilon}, \bar{\Psi}, \bar{\Omega}) \right|, \\ \lim_{n \rightarrow \infty} \frac{\|\Phi_{n+1}\|}{\|\Phi_n\|} &= \left| \lambda_{1,2,3,4,5,6} F_J(\bar{\Upsilon}, \bar{\Psi}, \bar{\Omega}) \right|, \end{aligned} \quad (2.40)$$

where $\left| \lambda_{1,2,3,4,5,6} F_J(\bar{\Upsilon}, \bar{\Psi}, \bar{\Omega}) \right|$ denotes the characteristic root of $F_J(\bar{\Upsilon}, \bar{\Psi}, \bar{\Omega})$.

Proof. To find the error terms, from system (1.7), we obtain

$$\begin{aligned}
 \Upsilon_{n+1} - \bar{\Upsilon} &= \frac{\Gamma_1 + \delta_1 e^{-\Psi_{n-1}}}{\Theta_1 + \Psi_n} - \frac{\Gamma_1 + \delta_1 e^{-\bar{\Psi}}}{\Theta_1 + \bar{\Psi}} \\
 &= -\frac{\Gamma_1 + \delta_1 e^{-\bar{\Psi}}}{(\Theta_1 + \Psi_n)(\Theta_1 + \bar{\Psi})} (\Psi_n - \bar{\Psi}) + \frac{\delta_1 (e^{-\Psi_{n-1}} - e^{-\bar{\Psi}})}{(\Theta_1 + \Psi_n)(\Psi_{n-1} - \bar{\Psi})} (\Psi_{n-1} - \bar{\Psi}), \\
 \Psi_{n+1} - \bar{\Psi} &= \frac{\Gamma_2 + \delta_2 e^{-\Omega_{n-1}}}{\Theta_2 + \Omega_n} - \frac{\Gamma_2 + \delta_2 e^{-\bar{\Omega}}}{\Theta_2 + \bar{\Omega}} \\
 &= -\frac{\Gamma_2 + \delta_2 e^{-\bar{\Omega}}}{(\Theta_2 + \Omega_n)(\Theta_2 + \bar{\Omega})} (\Omega_n - \bar{\Omega}) + \frac{\delta_2 (e^{-\Omega_{n-1}} - e^{-\bar{\Omega}})}{(\Theta_2 + \Omega_n)(\Omega_{n-1} - \bar{\Omega})} (\Omega_{n-1} - \bar{\Omega}), \\
 \Omega_{n+1} - \bar{\Omega} &= \frac{\Gamma_3 + \delta_3 e^{-\Upsilon_{n-1}}}{\Theta_3 + \Upsilon_n} - \frac{\Gamma_3 + \delta_3 e^{-\bar{\Upsilon}}}{\Theta_3 + \bar{\Upsilon}} \\
 &= -\frac{\Gamma_3 + \delta_3 e^{-\bar{\Upsilon}}}{(\Theta_3 + \Upsilon_n)(\Theta_3 + \bar{\Upsilon})} (\Upsilon_n - \bar{\Upsilon}) + \frac{\delta_3 (e^{-\Upsilon_{n-1}} - e^{-\bar{\Upsilon}})}{(\Theta_3 + \Upsilon_n)(\Upsilon_{n-1} - \bar{\Upsilon})} (\Upsilon_{n-1} - \bar{\Upsilon}),
 \end{aligned} \tag{2.41}$$

that is,

$$\begin{aligned}
 \Upsilon_{n+1} - \bar{\Upsilon} &= -\frac{\Gamma_1 + \delta_1 e^{-\bar{\Psi}}}{(\Theta_1 + \Psi_n)(\Theta_1 + \bar{\Psi})} (\Psi_n - \bar{\Psi}) + \frac{\delta_1 (e^{-\Psi_{n-1}} - e^{-\bar{\Psi}})}{(\Theta_1 + \Psi_n)(\Psi_{n-1} - \bar{\Psi})} (\Psi_{n-1} - \bar{\Psi}), \\
 \Psi_{n+1} - \bar{\Psi} &= -\frac{\Gamma_2 + \delta_2 e^{-\bar{\Omega}}}{(\Theta_2 + \Omega_n)(\Theta_2 + \bar{\Omega})} (\Omega_n - \bar{\Omega}) + \frac{\delta_2 (e^{-\Omega_{n-1}} - e^{-\bar{\Omega}})}{(\Theta_2 + \Omega_n)(\Omega_{n-1} - \bar{\Omega})} (\Omega_{n-1} - \bar{\Omega}), \\
 \Omega_{n+1} - \bar{\Omega} &= -\frac{\Gamma_3 + \delta_3 e^{-\bar{\Upsilon}}}{(\Theta_3 + \Upsilon_n)(\Theta_3 + \bar{\Upsilon})} (\Upsilon_n - \bar{\Upsilon}) + \frac{\delta_3 (e^{-\Upsilon_{n-1}} - e^{-\bar{\Upsilon}})}{(\Theta_3 + \Upsilon_n)(\Upsilon_{n-1} - \bar{\Upsilon})} (\Upsilon_{n-1} - \bar{\Upsilon}).
 \end{aligned} \tag{2.42}$$

Set

$$\Phi_n^1 = \Upsilon_n - \bar{\Upsilon}, \quad \Phi_n^2 = \Psi_n - \bar{\Psi}, \quad \Phi_n^3 = \Omega_n - \bar{\Omega}. \tag{2.43}$$

By using Eq (2.43), Eq (2.42) can be written in the following form:

$$\begin{aligned}
 \Phi_{n+1}^1 &= d_n \Phi_n^2 + e_n \Phi_{n-1}^2, \\
 \Phi_{n+1}^2 &= f_n \Phi_n^3 + g_n \Phi_{n-1}^3, \\
 \Phi_{n+1}^3 &= h_n \Phi_n^1 + j_n \Phi_{n-1}^1,
 \end{aligned} \tag{2.44}$$

where

$$\begin{aligned} d_n &= -\frac{\Gamma_1 + \delta_1 e^{-\bar{\Psi}}}{(\Theta_1 + \Psi_n)(\Theta_1 + \bar{\Psi})}, \quad e_n = \frac{\delta_1 (e^{-\Psi_{n-1}} - e^{-\bar{\Psi}})}{(\Theta_1 + \Psi_n)(\Psi_{n-1} - \bar{\Psi})}, \\ f_n &= -\frac{\Gamma_2 + \delta_2 e^{-\bar{\Omega}}}{(\Theta_2 + \Omega_n)(\Theta_2 + \bar{\Omega})}, \quad g_n = \frac{\delta_2 (e^{-\Omega_{n-1}} - e^{-\bar{\Omega}})}{(\Theta_2 + \Omega_n)(\Omega_{n-1} - \bar{\Omega})}, \\ h_n &= -\frac{\Gamma_3 + \delta_3 e^{-\bar{\Upsilon}}}{(\Theta_3 + \Upsilon_n)(\Theta_3 + \bar{\Upsilon})}, \quad j_n = \frac{\delta_3 (e^{-\Upsilon_{n-1}} - e^{-\bar{\Upsilon}})}{(\Theta_3 + \Upsilon_n)(\Upsilon_{n-1} - \bar{\Upsilon})}. \end{aligned} \quad (2.45)$$

By taking the limits of d_n, e_n, f_n, g_n, h_n and j_n , we respectively obtain

$$\begin{aligned} \lim_{n \rightarrow \infty} d_n &= -\frac{\Gamma_1 + \delta_1 e^{-\bar{\Psi}}}{(\Theta_1 + \bar{\Psi})^2}, \quad \lim_{n \rightarrow \infty} e_n = -\frac{\delta_1 e^{-\bar{\Psi}}}{\Theta_1 + \bar{\Psi}}, \\ \lim_{n \rightarrow \infty} f_n &= -\frac{\Gamma_2 + \delta_2 e^{-\bar{\Omega}}}{(\Theta_2 + \bar{\Omega})^2}, \quad \lim_{n \rightarrow \infty} g_n = -\frac{\delta_2 e^{-\bar{\Omega}}}{\Theta_2 + \bar{\Omega}}, \\ \lim_{n \rightarrow \infty} h_n &= -\frac{\Gamma_3 + \delta_3 e^{-\bar{\Upsilon}}}{(\Theta_3 + \bar{\Upsilon})^2}, \quad \lim_{n \rightarrow \infty} j_n = -\frac{\delta_3 e^{-\bar{\Upsilon}}}{\Theta_3 + \bar{\Upsilon}}, \end{aligned} \quad (2.46)$$

that is,

$$\begin{aligned} d_n &= -\frac{\Gamma_1 + \delta_1 e^{-\bar{\Psi}}}{(\Theta_1 + \bar{\Psi})^2} + \xi 2_n, \quad e_n = -\frac{\delta_1 e^{-\bar{\Psi}}}{\Theta_1 + \bar{\Psi}} + \xi 2_{n-1}, \\ f_n &= -\frac{\Gamma_2 + \delta_2 e^{-\bar{\Omega}}}{(\Theta_2 + \bar{\Omega})^2} + \xi 3_n, \quad g_n = -\frac{\delta_2 e^{-\bar{\Omega}}}{\Theta_2 + \bar{\Omega}} + \xi 3_{n-1}, \\ h_n &= -\frac{\Gamma_3 + \delta_3 e^{-\bar{\Upsilon}}}{(\Theta_3 + \bar{\Upsilon})^2} + \xi 1_n, \quad j_n = -\frac{\delta_3 e^{-\bar{\Upsilon}}}{\Theta_3 + \bar{\Upsilon}} + \xi 1_{n-1}, \end{aligned} \quad (2.47)$$

where $\xi 1_n \rightarrow 0, \xi 1_{n-1} \rightarrow 0, \xi 2_n \rightarrow 0, \xi 2_{n-1} \rightarrow 0, \xi 3_n \rightarrow 0$ and $\xi 3_{n-1} \rightarrow 0$ as $n \rightarrow \infty$. Then, we get Poincare difference system (1.10) of [51], where

$$A = \begin{pmatrix} 0 & 0 & -\frac{\Gamma_1 + \delta_1 e^{-\bar{\Psi}}}{(\Theta_1 + \bar{\Psi})^2} & -\frac{\delta_1 e^{-\bar{\Psi}}}{\Theta_1 + \bar{\Psi}} & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & -\frac{\Gamma_2 + \delta_2 e^{-\bar{\Omega}}}{(\Theta_2 + \bar{\Omega})^2} & -\frac{\delta_2 e^{-\bar{\Omega}}}{\Theta_2 + \bar{\Omega}} \\ 0 & 0 & 1 & 0 & 0 & 0 \\ -\frac{\Gamma_3 + \delta_3 e^{-\bar{\Upsilon}}}{(\Theta_3 + \bar{\Upsilon})^2} & -\frac{\delta_3 e^{-\bar{\Upsilon}}}{\Theta_3 + \bar{\Upsilon}} & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 \end{pmatrix}, \quad (2.48)$$

and

$$B_n = \begin{pmatrix} 0 & 0 & \xi 2_n & \xi 2_{n-1} & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & \xi 3_n & \xi 3_{n-1} \\ 0 & 0 & 1 & 0 & 0 & 0 \\ \xi 1_n & \xi 1_{n-1} & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 \end{pmatrix}, \quad (2.49)$$

and $\|B_n\| \rightarrow 0$ as $n \rightarrow \infty$. Moreover, the limiting system of error terms turns into

$$\begin{pmatrix} \Phi_{n+1}^1 \\ \Phi_n^1 \\ \Phi_{n+1}^2 \\ \Phi_n^2 \\ \Phi_{n+1}^3 \\ \Phi_n^3 \end{pmatrix} = \begin{pmatrix} 0 & 0 & -\frac{\Gamma_1 + \delta_1 e^{-\bar{\Psi}}}{(\Theta_1 + \bar{\Psi})^2} & -\frac{\delta_1 e^{-\bar{\Psi}}}{\Theta_1 + \bar{\Psi}} & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & -\frac{\Gamma_2 + \delta_2 e^{-\bar{\Omega}}}{(\Theta_2 + \bar{\Omega})^2} & -\frac{\delta_2 e^{-\bar{\Omega}}}{\Theta_2 + \bar{\Omega}} \\ 0 & 0 & 1 & 0 & 0 & 0 \\ -\frac{\Gamma_3 + \delta_3 e^{-\bar{\Upsilon}}}{(\Theta_3 + \bar{\Upsilon})^2} & -\frac{\delta_3 e^{-\bar{\Upsilon}}}{\Theta_3 + \bar{\Upsilon}} & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 \end{pmatrix} \begin{pmatrix} \Phi_n^1 \\ \Phi_{n-1}^1 \\ \Phi_n^2 \\ \Phi_{n-1}^2 \\ \Phi_n^3 \\ \Phi_{n-1}^3 \end{pmatrix}, \quad (2.50)$$

which is similar to the linearized system (1.7) about the equilibrium $(\bar{\Upsilon}, \bar{\Psi}, \bar{\Omega})$. \square

3. Global behavior of system (1.8)

Lemma 5. *Every positive solution of system (1.8) is bounded and persists.*

Proof. Suppose that $\{(\Upsilon_n, \Psi_n, \Omega_n)\}$ is an arbitrary solution of system (1.8). From Lemma 3, by using induction and applying $n \in \mathbb{N}$, we obtain

$$\begin{aligned} \Upsilon_n \in I_4 &= \left[\frac{\Gamma_1 + \delta_1 e^{-\left(\frac{\Gamma_2 + \delta_2}{\Theta_2}\right)}}{\Theta_1 + \left(\frac{\Gamma_1 + \delta_1}{\Theta_1}\right)}, \frac{\Gamma_1 + \delta_1}{\Theta_1} \right] = [\Lambda_4, \Pi_4], \\ \Psi_n \in I_5 &= \left[\frac{\Gamma_2 + \delta_2 e^{-\left(\frac{\Gamma_3 + \delta_3}{\Theta_3}\right)}}{\Theta_2 + \left(\frac{\Gamma_2 + \delta_2}{\Theta_2}\right)}, \frac{\Gamma_2 + \delta_2}{\Theta_2} \right] = [\Lambda_5, \Pi_5], \\ \Omega_n \in I_6 &= \left[\frac{\Gamma_3 + \delta_3 e^{-\left(\frac{\Gamma_1 + \delta_1}{\Theta_1}\right)}}{\Theta_3 + \left(\frac{\Gamma_3 + \delta_3}{\Theta_3}\right)}, \frac{\Gamma_3 + \delta_3}{\Theta_3} \right] = [\Lambda_6, \Pi_6]. \end{aligned} \quad (3.1)$$

The proof of the lemma is similar to Lemma 3, so it is omitted. \square

3.1. Local and global asymptotic stability

Theorem 6. *For the local stability about $(\bar{\Upsilon}, \bar{\Psi}, \bar{\Omega}) \in [\Lambda_4, \Pi_4] \times [\Lambda_5, \Pi_5] \times [\Lambda_6, \Pi_6]$, i.e., the equilibrium point of system (1.8), the next declarations are valid:*

(i) $(\bar{\Upsilon}, \bar{\Psi}, \bar{\Omega})$ is locally asymptotically stable if $L_2 < 1$,

(ii) $(\bar{\Upsilon}, \bar{\Psi}, \bar{\Omega})$ is unstable if $U_2 > 1$,

where

$$\begin{aligned} L_2 = \frac{1}{\Theta_1 \Theta_2 \Theta_3} & \left(\Theta_2 \Lambda_4 (\Theta_3 + 2\Lambda_6) + \Theta_3 \Lambda_5 (\Theta_1 + 2\Lambda_4) + \Theta_1 \Lambda_6 (\Theta_2 + 2\Lambda_5) \right. \\ & \left. + \Lambda_4 \Lambda_5 \Lambda_6 + \delta_1 \delta_2 \delta_3 \right), \end{aligned} \quad (3.2)$$

$$\begin{aligned} U_2 = \frac{\Pi_4 (\Theta_2 + \Pi_5)}{(\Theta_1 + \Pi_4)(\Theta_2 + \Pi_5)(\Theta_3 + \Pi_6)} & (\Theta_3 + 2\Pi_6) + \frac{\Pi_5 (\Theta_3 + \Pi_6)}{(\Theta_1 + \Pi_4)(\Theta_2 + \Pi_5)(\Theta_3 + \Pi_6)} (\Theta_1 + 2\Pi_4) \\ & + \frac{\Pi_6 (\Theta_1 + \Pi_4)}{(\Theta_1 + \Pi_4)(\Theta_2 + \Pi_5)(\Theta_3 + \Pi_6)} (\Theta_2 + 2\Pi_5) + \frac{1}{(\Theta_1 + \Pi_4)(\Theta_2 + \Pi_5)(\Theta_3 + \Pi_6)} \left(\Pi_4 \Pi_5 \Pi_6 \right. \\ & \left. + \delta_1 \delta_2 \delta_3 e^{-\Pi_4 - \Pi_5 - \Pi_6} \right). \end{aligned} \quad (3.3)$$

Proof. (i) From system (1.8), we have

$$\bar{\Upsilon} = \frac{\Gamma_1 + \delta_1 e^{-\bar{\Psi}}}{\Theta_1 + \bar{\Upsilon}}, \bar{\Psi} = \frac{\Gamma_2 + \delta_2 e^{-\bar{\Omega}}}{\Theta_2 + \bar{\Psi}}, \bar{\Omega} = \frac{\Gamma_3 + \delta_3 e^{-\bar{\Gamma}}}{\Theta_3 + \bar{\Omega}}. \quad (3.4)$$

In order to construct the corresponding linearized form of system (1.8), we consider the following transformation:

$$(\Upsilon_{n+1}, \Upsilon_n, \Psi_{n+1}, \Psi_n, \Omega_{n+1}, \Omega_n) \rightarrow (f, f_1, g, g_1, h, h_1), \quad (3.5)$$

where

$$\begin{aligned} f &= \frac{\Gamma_1 + \delta_1 e^{-\Psi_{n-1}}}{\Theta_1 + \Upsilon_n}, f_1 = \Upsilon_n, \\ g &= \frac{\Gamma_2 + \delta_2 e^{-\Omega_{n-1}}}{\Theta_2 + \Psi_n}, g_1 = \Psi_n, \\ h &= \frac{\Gamma_3 + \delta_3 e^{-\Upsilon_{n-1}}}{\Theta_3 + \Omega_n}, h_1 = \Omega_n. \end{aligned} \quad (3.6)$$

By using the transformation given by Eq (3.5), we have

$$F_J(\bar{\Upsilon}, \bar{\Psi}, \bar{\Omega}) = \begin{pmatrix} s_4 & 0 & 0 & t_4 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & s_5 & 0 & 0 & t_5 \\ 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & s_6 & 0 & 0 & t_6 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 \end{pmatrix}, \quad (3.7)$$

where

$$\begin{aligned}
s_4 &= -\frac{\Gamma_1 + \delta_1 e^{-\bar{\Psi}}}{(\Theta_1 + \bar{\Upsilon})^2}, \quad t_4 = -\frac{\delta_1 e^{-\bar{\Psi}}}{\Theta_1 + \bar{\Upsilon}}, \\
s_5 &= -\frac{\Gamma_2 + \delta_2 e^{-\bar{\Omega}}}{(\Theta_2 + \bar{\Psi})^2}, \quad t_5 = -\frac{\delta_2 e^{-\bar{\Omega}}}{\Theta_2 + \bar{\Psi}}, \\
s_6 &= -\frac{\delta_3 e^{-\bar{\Upsilon}}}{\Theta_3 + \bar{\Omega}}, \quad t_6 = -\frac{\Gamma_3 + \delta_3 e^{-\bar{\Upsilon}}}{(\Theta_3 + \bar{\Omega})^2}.
\end{aligned} \tag{3.8}$$

The characteristic equation of $F_J(\bar{\Upsilon}, \bar{\Psi}, \bar{\Omega})$ is below:

$$\lambda^6 + \widehat{m}_1 \lambda^5 + \widehat{m}_2 \lambda^4 + \widehat{m}_3 \lambda^3 + \widehat{m}_4 = 0, \tag{3.9}$$

where

$$\begin{aligned}
\widehat{m}_1 &= -(s_4 + s_5 + t_6), \\
\widehat{m}_2 &= s_4 s_5 + s_4 t_6 + s_5 t_6, \\
\widehat{m}_3 &= -s_4 s_5 t_6, \\
\widehat{m}_4 &= -s_6 t_4 t_5.
\end{aligned} \tag{3.10}$$

Now, we can compute $\sum_{i=1}^4 |\widehat{m}_i|$ as follows:

$$\begin{aligned}
\sum_{i=1}^4 |\widehat{m}_i| &= \frac{(\Gamma_1 + \delta_1 e^{-\bar{\Psi}})}{(\Theta_1 + \bar{\Upsilon})^2} + \frac{(\Gamma_2 + \delta_2 e^{-\bar{\Omega}})}{(\Theta_2 + \bar{\Psi})^2} + \frac{(\Gamma_3 + \delta_3 e^{-\bar{\Upsilon}})}{(\Theta_3 + \bar{\Omega})^2} \\
&\quad + \frac{(\Gamma_1 + \delta_1 e^{-\bar{\Psi}})(\Gamma_2 + \delta_2 e^{-\bar{\Omega}})}{(\Theta_1 + \bar{\Upsilon})^2 (\Theta_2 + \bar{\Psi})^2} + \frac{(\Gamma_1 + \delta_1 e^{-\bar{\Psi}})(\Gamma_3 + \delta_3 e^{-\bar{\Upsilon}})}{(\Theta_1 + \bar{\Upsilon})^2 (\Theta_3 + \bar{\Omega})^2} \\
&\quad + \frac{(\Gamma_2 + \delta_2 e^{-\bar{\Omega}})(\Gamma_3 + \delta_3 e^{-\bar{\Upsilon}})}{(\Theta_2 + \bar{\Psi})^2 (\Theta_3 + \bar{\Omega})^2} + \frac{(\Gamma_1 + \delta_1 e^{-\bar{\Psi}})(\Gamma_2 + \delta_2 e^{-\bar{\Omega}})(\Gamma_3 + \delta_3 e^{-\bar{\Upsilon}})}{(\Theta_1 + \bar{\Upsilon})^2 (\Theta_2 + \bar{\Psi})^2 (\Theta_3 + \bar{\Omega})^2} \\
&\quad + \frac{\delta_1 \delta_2 \delta_3 e^{-\bar{\Upsilon} - \bar{\Psi} - \bar{\Omega}}}{(\Theta_1 + \bar{\Upsilon})(\Theta_2 + \bar{\Psi})(\Theta_3 + \bar{\Omega})} \\
&= \frac{\bar{\Upsilon}}{(\Theta_1 + \bar{\Upsilon})} + \frac{\bar{\Psi}}{(\Theta_2 + \bar{\Psi})} + \frac{\bar{\Omega}}{(\Theta_3 + \bar{\Omega})} + \frac{\bar{\Upsilon} \bar{\Psi}}{(\Theta_1 + \bar{\Upsilon})(\Theta_2 + \bar{\Psi})} + \frac{\bar{\Upsilon} \bar{\Omega}}{(\Theta_1 + \bar{\Upsilon})(\Theta_3 + \bar{\Omega})} \\
&\quad + \frac{\bar{\Psi} \bar{\Omega}}{(\Theta_2 + \bar{\Psi})(\Theta_3 + \bar{\Omega})} + \frac{\bar{\Upsilon} \bar{\Psi} \bar{\Omega}}{(\Theta_1 + \bar{\Upsilon})(\Theta_2 + \bar{\Psi})(\Theta_3 + \bar{\Omega})} \\
&\quad + \frac{\delta_1 \delta_2 \delta_3 e^{-\bar{\Upsilon} - \bar{\Psi} - \bar{\Omega}}}{(\Theta_1 + \bar{\Upsilon})(\Theta_2 + \bar{\Psi})(\Theta_3 + \bar{\Omega})}
\end{aligned} \tag{3.11}$$

$$\begin{aligned}
&= \frac{\bar{\Upsilon}}{(\Theta_1 + \bar{\Upsilon})(\Theta_3 + \bar{\Omega})} (\Theta_3 + 2\bar{\Omega}) + \frac{\bar{\Psi}}{(\Theta_1 + \bar{\Upsilon})(\Theta_2 + \bar{\Psi})} (\Theta_1 + 2\bar{\Upsilon}) \\
&+ \frac{\bar{\Omega}}{(\Theta_2 + \bar{\Psi})(\Theta_3 + \bar{\Omega})} (\Theta_2 + 2\bar{\Psi}) + \frac{1}{(\Theta_1 + \bar{\Upsilon})(\Theta_2 + \bar{\Psi})(\Theta_3 + \bar{\Omega})} (\bar{\Upsilon} \bar{\Psi} \bar{\Omega} + \delta_1 \delta_2 \delta_3 e^{-\bar{\Upsilon} - \bar{\Psi} - \bar{\Omega}}) \\
&< \frac{\bar{\Upsilon}}{\Theta_1 \Theta_3} (\Theta_3 + 2\bar{\Omega}) + \frac{\bar{\Psi}}{\Theta_1 \Theta_2} (\Theta_1 + 2\bar{\Upsilon}) + \frac{\bar{\Omega}}{\Theta_2 \Theta_3} (\Theta_2 + 2\bar{\Psi}) + \frac{1}{\Theta_1 \Theta_2 \Theta_3} (\bar{\Upsilon} \bar{\Psi} \bar{\Omega} + \delta_1 \delta_2 \delta_3) \\
&= \frac{1}{\Theta_1 \Theta_2 \Theta_3} (\Theta_2 \bar{\Upsilon} (\Theta_3 + 2\bar{\Omega}) + \Theta_3 \bar{\Psi} (\Theta_1 + 2\bar{\Upsilon}) + \Theta_1 \bar{\Omega} (\Theta_2 + 2\bar{\Psi}) + \bar{\Upsilon} \bar{\Psi} \bar{\Omega} + \delta_1 \delta_2 \delta_3) \\
&< \frac{1}{\Theta_1 \Theta_2 \Theta_3} \left(\Theta_2 \Lambda_4 (\Theta_3 + 2\Lambda_6) + \Theta_3 \Lambda_5 (\Theta_1 + 2\Lambda_4) + \Theta_1 \Lambda_6 (\Theta_2 + 2\Lambda_5) + \Lambda_4 \Lambda_5 \Lambda_6 \right. \\
&\quad \left. + \delta_1 \delta_2 \delta_3 \right) < 1.
\end{aligned}$$

By supposing that $L_2 < 1$, from Eq (3.11), we have that $\sum_{i=1}^4 |\widehat{m}_i| < 1$. According to the Rouche theorem, $(\bar{\Upsilon}, \bar{\Psi}, \bar{\Omega})$ is locally asymptotically stable.

(ii) We have

$$\begin{aligned}
\sum_{i=1}^4 |\widehat{m}_i| &= \frac{(\Gamma_1 + \delta_1 e^{-\bar{\Psi}})}{(\Theta_1 + \bar{\Upsilon})^2} + \frac{(\Gamma_2 + \delta_2 e^{-\bar{\Omega}})}{(\Theta_2 + \bar{\Psi})^2} + \frac{(\Gamma_3 + \delta_3 e^{-\bar{\Gamma}})}{(\Theta_3 + \bar{\Omega})^2} \\
&+ \frac{(\Gamma_1 + \delta_1 e^{-\bar{\Psi}})(\Gamma_2 + \delta_2 e^{-\bar{\Omega}})}{(\Theta_1 + \bar{\Upsilon})^2 (\Theta_2 + \bar{\Psi})^2} + \frac{(\Gamma_1 + \delta_1 e^{-\bar{\Psi}})(\Gamma_3 + \delta_3 e^{-\bar{\Gamma}})}{(\Theta_1 + \bar{\Upsilon})^2 (\Theta_3 + \bar{\Omega})^2} \\
&+ \frac{(\Gamma_2 + \delta_2 e^{-\bar{\Omega}})(\Gamma_3 + \delta_3 e^{-\bar{\Gamma}})}{(\Theta_2 + \bar{\Psi})^2 (\Theta_3 + \bar{\Omega})^2} + \frac{(\Gamma_1 + \delta_1 e^{-\bar{\Psi}})(\Gamma_2 + \delta_2 e^{-\bar{\Omega}})(\Gamma_3 + \delta_3 e^{-\bar{\Gamma}})}{(\Theta_1 + \bar{\Upsilon})^2 (\Theta_2 + \bar{\Psi})^2 (\Theta_3 + \bar{\Omega})^2} \\
&+ \frac{\delta_1 \delta_2 \delta_3 e^{-\bar{\Upsilon} - \bar{\Psi} - \bar{\Omega}}}{(\Theta_1 + \bar{\Upsilon})(\Theta_2 + \bar{\Psi})(\Theta_3 + \bar{\Omega})} \\
&= \frac{\bar{\Upsilon}}{(\Theta_1 + \bar{\Upsilon})(\Theta_3 + \bar{\Omega})} (\Theta_3 + 2\bar{\Omega}) + \frac{\bar{\Psi}}{(\Theta_1 + \bar{\Upsilon})(\Theta_2 + \bar{\Psi})} (\Theta_1 + 2\bar{\Upsilon}) \tag{3.12} \\
&+ \frac{\bar{\Omega}}{(\Theta_2 + \bar{\Psi})(\Theta_3 + \bar{\Omega})} (\Theta_2 + 2\bar{\Psi}) + \frac{1}{(\Theta_1 + \bar{\Upsilon})(\Theta_2 + \bar{\Psi})(\Theta_3 + \bar{\Omega})} (\bar{\Upsilon} \bar{\Psi} \bar{\Omega} + \delta_1 \delta_2 \delta_3 e^{-\bar{\Upsilon} - \bar{\Psi} - \bar{\Omega}}) \\
&\geq \frac{\Pi_4 (\Theta_2 + \Pi_5)}{(\Theta_1 + \Pi_4)(\Theta_2 + \Pi_5)(\Theta_3 + \Pi_6)} (\Theta_3 + 2\Pi_6) + \frac{\Pi_5 (\Theta_3 + \Pi_6)}{(\Theta_1 + \Pi_4)(\Theta_2 + \Pi_5)(\Theta_3 + \Pi_6)} (\Theta_1 + 2\Pi_4) \\
&+ \frac{\Pi_6 (\Theta_1 + \Pi_4)}{(\Theta_1 + \Pi_4)(\Theta_2 + \Pi_5)(\Theta_3 + \Pi_6)} (\Theta_2 + 2\Pi_5) + \frac{1}{(\Theta_1 + \Pi_4)(\Theta_2 + \Pi_5)(\Theta_3 + \Pi_6)} \left(\Pi_4 \Pi_5 \Pi_6 \right. \\
&\quad \left. + \delta_1 \delta_2 \delta_3 e^{-\Pi_4 - \Pi_5 - \Pi_6} \right) > 1.
\end{aligned}$$

By supposing that $U_2 > 1$, from Eq (3.12), we have that $\sum_{i=1}^4 |\widehat{m}_i| > 1$. According to the Rouche theorem, $(\bar{\Upsilon}, \bar{\Psi}, \bar{\Omega})$ is unstable. \square

Theorem 7. Consider system (1.8). Assume that the next relation is true:

$$\delta_1\delta_2\delta_3 < \Theta_1\Theta_2\Theta_3. \quad (3.13)$$

Moreover, system (1.8) has a unique positive equilibrium $(\bar{\Upsilon}, \bar{\Psi}, \bar{\Omega})$, and every positive solution of system (1.8) tends to the unique positive equilibrium of system (1.8) as $n \rightarrow \infty$.

Proof. We consider the functions

$$f_2(\Upsilon, \Psi) = \frac{\Gamma_1 + \delta_1 e^{-\Psi}}{\Theta_1 + \Upsilon}, \quad g_2(\Psi, \Omega) = \frac{\Gamma_2 + \delta_2 e^{-\Omega}}{\Theta_2 + \Psi}, \quad h_2(\Upsilon, \Omega) = \frac{\Gamma_3 + \delta_3 e^{-\Upsilon}}{\Theta_3 + \Omega}, \quad (3.14)$$

where

$$\Upsilon \in I_4, \Psi \in I_5, \Omega \in I_6, \quad (3.15)$$

and I_4, I_5, I_6 are defined in Eq (3.1). From Eqs (3.14) and (3.15), we see that, for $\Upsilon \in I_4, \Psi \in I_5$ and $\Omega \in I_6$,

$$f_2(\Upsilon, \Psi) \in I_4, \quad g_2(\Psi, \Omega) \in I_5, \quad h_2(\Upsilon, \Omega) \in I_6;$$

thus,

$$f_2 : I_4 \times I_5 \rightarrow I_4, \quad g_2 : I_5 \times I_6 \rightarrow I_5, \quad h_2 : I_4 \times I_6 \rightarrow I_6.$$

Let p, P, l, L, w and W be positive numbers such that

$$\begin{aligned} P &= \frac{\Gamma_1 + \delta_1 e^{-l}}{\Theta_1 + p}, \quad p = \frac{\Gamma_1 + \delta_1 e^{-L}}{\Theta_1 + P}, \\ L &= \frac{\Gamma_2 + \delta_2 e^{-w}}{\Theta_2 + l}, \quad l = \frac{\Gamma_2 + \delta_2 e^{-W}}{\Theta_2 + L}, \\ W &= \frac{\Gamma_3 + \delta_3 e^{-P}}{\Theta_3 + w}, \quad w = \frac{\Gamma_3 + \delta_3 e^{-P}}{\Theta_3 + W}. \end{aligned} \quad (3.16)$$

From Eq (3.16), we get

$$\begin{aligned} e^{-l} &= \frac{P(\Theta_1 + p) - \Gamma_1}{\delta_1}, \quad e^{-L} = \frac{p(\Theta_1 + P) - \Gamma_1}{\delta_1}, \\ e^{-w} &= \frac{L(\Theta_2 + l) - \Gamma_2}{\delta_2}, \quad e^{-W} = \frac{l(\Theta_2 + L) - \Gamma_2}{\delta_2}, \\ e^{-P} &= \frac{W(\Theta_3 + w) - \Gamma_3}{\delta_3}, \quad e^{-P} = \frac{w(\Theta_3 + W) - \Gamma_3}{\delta_3}, \end{aligned}$$

which imply that

$$\begin{aligned}
P - p &= \frac{\delta_1}{\Theta_1} (e^{-l} - e^{-L}) = \frac{\delta_1}{\Theta_1} e^{-l-L} (e^L - e^l), \\
L - l &= \frac{\delta_2}{\Theta_2} (e^{-w} - e^{-W}) = \frac{\delta_2}{\Theta_2} e^{-w-W} (e^W - e^w), \\
W - w &= \frac{\delta_3}{\Theta_3} (e^{-p} - e^{-P}) = \frac{\delta_3}{\Theta_3} e^{-p-P} (e^P - e^p).
\end{aligned} \tag{3.17}$$

Moreover, we get

$$\begin{aligned}
e^P - e^p &= e^{d_1} (P - p), \quad \min \{P, p\} \leq d_1 \leq \max \{P, p\}, \\
e^L - e^l &= e^{d_2} (L - l), \quad \min \{L, l\} \leq d_2 \leq \max \{L, l\}, \\
e^W - e^w &= e^{d_3} (W - w), \quad \min \{W, w\} \leq d_3 \leq \max \{W, w\}.
\end{aligned} \tag{3.18}$$

Then Eqs (3.17) and (3.18) imply that

$$\begin{aligned}
P - p &= \frac{\delta_1}{\Theta_1} e^{d_2-l-L} (L - l), \\
L - l &= \frac{\delta_2}{\Theta_2} e^{d_3-w-W} (W - w), \\
W - w &= \frac{\delta_3}{\Theta_3} e^{d_1-p-P} (P - p);
\end{aligned} \tag{3.19}$$

thus,

$$\begin{aligned}
|P - p| &\leq \frac{\delta_1}{\Theta_1} |L - l|, \\
|L - l| &\leq \frac{\delta_2}{\Theta_2} |W - w|, \\
|W - w| &\leq \frac{\delta_3}{\Theta_3} |P - p|.
\end{aligned} \tag{3.20}$$

In addition, observe that Eqs (3.13) and (3.20) imply that

$$\begin{aligned}
\left(1 - \frac{\delta_1 \delta_2 \delta_3}{\Theta_1 \Theta_2 \Theta_3}\right) |P - p| &\leq 0, \\
\left(1 - \frac{\delta_1 \delta_2 \delta_3}{\Theta_1 \Theta_2 \Theta_3}\right) |L - l| &\leq 0, \\
\left(1 - \frac{\delta_1 \delta_2 \delta_3}{\Theta_1 \Theta_2 \Theta_3}\right) |W - w| &\leq 0,
\end{aligned}$$

from which we have that $P = p$, $L = l$ and $W = w$. Thus from Eq (3.1), system (1.8) has a unique positive equilibrium $(\bar{\Upsilon}, \bar{\Psi}, \bar{\Omega})$, and every positive solution of system (1.8) tends to the unique positive equilibrium as $n \rightarrow \infty$.

□

3.2. Rate of convergence

Theorem 8. If $\{(\Upsilon_n, \Psi_n, \Omega_n,)\}_{n=1}^{\infty}$ is a positive solution of system (1.8) such that

$$\lim_{n \rightarrow \infty} \Upsilon_n = \bar{\Upsilon}, \quad \lim_{n \rightarrow \infty} \Psi_n = \bar{\Psi}, \quad \lim_{n \rightarrow \infty} \Omega_n = \bar{\Omega}, \quad (3.21)$$

where

$$\bar{\Upsilon} \in [\Lambda_4, \Pi_4], \quad \bar{\Psi} \in [\Lambda_5, \Pi_5], \quad \bar{\Omega} \in [\Lambda_6, \Pi_6], \quad (3.22)$$

then the error vector $\Phi_n = (\Phi_n^4, \Phi_{n-1}^4, \Phi_n^5, \Phi_{n-1}^5, \Phi_n^6, \Phi_{n-1}^6)^T$ of every solution of system (1.8) supplies both of the following asymptotic relations:

$$\begin{aligned} \lim_{n \rightarrow \infty} (\|\Phi_n\|)^{\frac{1}{n}} &= \left| \lambda_{1,2,3,4,5,6} F_J(\bar{\Upsilon}, \bar{\Psi}, \bar{\Omega}) \right|, \\ \lim_{n \rightarrow \infty} \frac{\|\Phi_{n+1}\|}{\|\Phi_n\|} &= \left| \lambda_{1,2,3,4,5,6} F_J(\bar{\Upsilon}, \bar{\Psi}, \bar{\Omega}) \right|, \end{aligned} \quad (3.23)$$

where $\left| \lambda_{1,2,3,4,5,6} F_J(\bar{\Upsilon}, \bar{\Psi}, \bar{\Omega}) \right|$ denotes the characteristic root of $F_J(\bar{\Upsilon}, \bar{\Psi}, \bar{\Omega})$.

Proof. To find the error terms, from system (1.8), we apply

$$\begin{aligned} \Upsilon_{n+1} - \bar{\Upsilon} &= \frac{\Gamma_1 + \delta_1 e^{-\Psi_{n-1}}}{\Theta_1 + \Upsilon_n} - \frac{\Gamma_1 + \delta_1 e^{-\bar{\Psi}}}{\Theta_1 + \bar{\Upsilon}} \\ &= - \frac{\Gamma_1 + \delta_1 e^{-\bar{\Psi}}}{(\Theta_1 + \Upsilon_n)(\Theta_1 + \bar{\Upsilon})} (\Upsilon_n - \bar{\Upsilon}) + \frac{\delta_1 (e^{-\Psi_{n-1}} - e^{-\bar{\Psi}})}{(\Theta_1 + \Upsilon_n)(\Psi_{n-1} - \bar{\Psi})} (\Psi_{n-1} - \bar{\Psi}), \\ \Psi_{n+1} - \bar{\Psi} &= \frac{\Gamma_2 + \delta_2 e^{-\Omega_{n-1}}}{\Theta_2 + \Psi_n} - \frac{\Gamma_2 + \delta_2 e^{-\bar{\Omega}}}{\Theta_2 + \bar{\Psi}} \\ &= - \frac{\Gamma_2 + \delta_2 e^{-\bar{\Omega}}}{(\Theta_2 + \Psi_n)(\Theta_2 + \bar{\Psi})} (\Psi_n - \bar{\Psi}) + \frac{\delta_2 (e^{-\Omega_{n-1}} - e^{-\bar{\Omega}})}{(\Theta_2 + \Psi_n)(\Omega_{n-1} - \bar{\Omega})} (\Omega_{n-1} - \bar{\Omega}), \\ \Omega_{n+1} - \bar{\Omega} &= \frac{\Gamma_3 + \delta_3 e^{-\Upsilon_{n-1}}}{\Theta_3 + \Omega_n} - \frac{\Gamma_3 + \delta_3 e^{-\bar{\Upsilon}}}{\Theta_3 + \bar{\Omega}} \\ &= - \frac{\Gamma_3 + \delta_3 e^{-\bar{\Upsilon}}}{(\Theta_3 + \Omega_n)(\Theta_3 + \bar{\Omega})} (\Omega_n - \bar{\Omega}) + \frac{\delta_3 (e^{-\Upsilon_{n-1}} - e^{-\bar{\Upsilon}})}{(\Theta_3 + \Omega_n)(\Upsilon_{n-1} - \bar{\Upsilon})} (\Upsilon_{n-1} - \bar{\Upsilon}), \end{aligned} \quad (3.24)$$

that is,

$$\begin{aligned} \Upsilon_{n+1} - \bar{\Upsilon} &= - \frac{\Gamma_1 + \delta_1 e^{-\bar{\Psi}}}{(\Theta_1 + \Upsilon_n)(\Theta_1 + \bar{\Upsilon})} (\Upsilon_n - \bar{\Upsilon}) + \frac{\delta_1 (e^{-\Psi_{n-1}} - e^{-\bar{\Psi}})}{(\Theta_1 + \Upsilon_n)(\Psi_{n-1} - \bar{\Psi})} (\Psi_{n-1} - \bar{\Psi}), \\ \Psi_{n+1} - \bar{\Psi} &= - \frac{\Gamma_2 + \delta_2 e^{-\bar{\Omega}}}{(\Theta_2 + \Psi_n)(\Theta_2 + \bar{\Psi})} (\Psi_n - \bar{\Psi}) + \frac{\delta_2 (e^{-\Omega_{n-1}} - e^{-\bar{\Omega}})}{(\Theta_2 + \Psi_n)(\Omega_{n-1} - \bar{\Omega})} (\Omega_{n-1} - \bar{\Omega}), \end{aligned} \quad (3.25)$$

$$\Omega_{n+1} - \bar{\Omega} = - \frac{\Gamma_3 + \delta_3 e^{-\bar{\Upsilon}}}{(\Theta_3 + \Omega_n)(\Theta_3 + \bar{\Omega})} (\Omega_n - \bar{\Omega}) + \frac{\delta_3 (e^{-\Upsilon_{n-1}} - e^{-\bar{\Upsilon}})}{(\Theta_3 + \Omega_n)(\Upsilon_{n-1} - \bar{\Upsilon})} (\Upsilon_{n-1} - \bar{\Upsilon}).$$

Set

$$\Phi_n^4 = \Upsilon_n - \bar{\Upsilon}, \quad \Phi_n^5 = \Psi_n - \bar{\Psi}, \quad \Phi_n^6 = \Omega_n - \bar{\Omega}. \quad (3.26)$$

By using Eq (3.26), Eq (3.25) can be written in the following form:

$$\begin{aligned} \Phi_{n+1}^4 &= \widehat{d}_n \Phi_n^4 + \widehat{e}_n \Phi_{n-1}^5, \\ \Phi_{n+1}^5 &= \widehat{f}_n \Phi_n^5 + \widehat{g}_n \Phi_{n-1}^6, \\ \Phi_{n+1}^6 &= \widehat{h}_n \Phi_n^6 + \widehat{j}_n \Phi_{n-1}^4, \end{aligned} \quad (3.27)$$

where

$$\begin{aligned} \widehat{d}_n &= - \frac{\Gamma_1 + \delta_1 e^{-\bar{\Psi}}}{(\Theta_1 + \Upsilon_n)(\Theta_1 + \bar{\Upsilon})}, \quad \widehat{e}_n = \frac{\delta_1 (e^{-\Psi_{n-1}} - e^{-\bar{\Psi}})}{(\Theta_1 + \Upsilon_n)(\Psi_{n-1} - \bar{\Psi})}, \\ \widehat{f}_n &= - \frac{\Gamma_2 + \delta_2 e^{-\bar{\Omega}}}{(\Theta_2 + \Psi_n)(\Theta_2 + \bar{\Omega})}, \quad \widehat{g}_n = \frac{\delta_2 (e^{-\Omega_{n-1}} - e^{-\bar{\Omega}})}{(\Theta_2 + \Psi_n)(\Omega_{n-1} - \bar{\Omega})}, \\ \widehat{h}_n &= - \frac{\Gamma_3 + \delta_3 e^{-\bar{\Upsilon}}}{(\Theta_3 + \Omega_n)(\Theta_3 + \bar{\Omega})}, \quad \widehat{j}_n = \frac{\delta_3 (e^{-\Upsilon_{n-1}} - e^{-\bar{\Upsilon}})}{(\Theta_3 + \Omega_n)(\Upsilon_{n-1} - \bar{\Upsilon})}. \end{aligned} \quad (3.28)$$

By taking the limits of $\widehat{d}_n, \widehat{e}_n, \widehat{f}_n, \widehat{g}_n, \widehat{h}_n$ and \widehat{j}_n , we respectively obtain

$$\begin{aligned} \lim_{n \rightarrow \infty} \widehat{d}_n &= - \frac{\Gamma_1 + \delta_1 e^{-\bar{\Psi}}}{(\Theta_1 + \bar{\Upsilon})^2}, \quad \lim_{n \rightarrow \infty} \widehat{e}_n = - \frac{\delta_1 e^{-\bar{\Psi}}}{\Theta_1 + \bar{\Upsilon}}, \\ \lim_{n \rightarrow \infty} \widehat{f}_n &= - \frac{\Gamma_2 + \delta_2 e^{-\bar{\Omega}}}{(\Theta_2 + \bar{\Psi})^2}, \quad \lim_{n \rightarrow \infty} \widehat{g}_n = - \frac{\delta_2 e^{-\bar{\Omega}}}{\Theta_2 + \bar{\Psi}}, \\ \lim_{n \rightarrow \infty} \widehat{h}_n &= - \frac{\Gamma_3 + \delta_3 e^{-\bar{\Upsilon}}}{(\Theta_3 + \bar{\Omega})^2}, \quad \lim_{n \rightarrow \infty} \widehat{j}_n = - \frac{\delta_3 e^{-\bar{\Upsilon}}}{\Theta_3 + \bar{\Omega}}, \end{aligned} \quad (3.29)$$

that is,

$$\begin{aligned} \widehat{d}_n &= - \frac{\Gamma_1 + \delta_1 e^{-\bar{\Psi}}}{(\Theta_1 + \bar{\Upsilon})^2} + \xi 4_n, \quad \widehat{e}_n = - \frac{\delta_1 e^{-\bar{\Psi}}}{\Theta_1 + \bar{\Upsilon}} + \xi 5_{n-1}, \\ \widehat{f}_n &= - \frac{\Gamma_2 + \delta_2 e^{-\bar{\Omega}}}{(\Theta_2 + \bar{\Psi})^2} + \xi 5_n, \quad \widehat{g}_n = - \frac{\delta_2 e^{-\bar{\Omega}}}{\Theta_2 + \bar{\Psi}} + \xi 6_{n-1}, \\ \widehat{h}_n &= - \frac{\Gamma_3 + \delta_3 e^{-\bar{\Upsilon}}}{(\Theta_3 + \bar{\Omega})^2} + \xi 6_n, \quad \widehat{j}_n = - \frac{\delta_3 e^{-\bar{\Upsilon}}}{\Theta_3 + \bar{\Omega}} + \xi 4_{n-1}, \end{aligned} \quad (3.30)$$

where $\xi 4_n \rightarrow 0$, $\xi 4_{n-1} \rightarrow 0$, $\xi 5_n \rightarrow 0$, $\xi 5_{n-1} \rightarrow 0$, $\xi 6_n \rightarrow 0$ and $\xi 6_{n-1} \rightarrow 0$ as $n \rightarrow \infty$. Then, we obtain Poincare difference system (1.10) of [51], where

$$\widehat{A} = \begin{pmatrix} -\frac{\Gamma_1 + \delta_1 e^{-\bar{\Psi}}}{(\Theta_1 + \bar{\Upsilon})^2} & 0 & 0 & -\frac{\delta_1 e^{-\bar{\Psi}}}{\Theta_1 + \bar{\Upsilon}} & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & -\frac{\Gamma_2 + \delta_2 e^{-\bar{\Omega}}}{(\Theta_2 + \bar{\Psi})^2} & 0 & 0 & -\frac{\delta_2 e^{-\bar{\Omega}}}{\Theta_2 + \bar{\Psi}} \\ 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & -\frac{\delta_3 e^{-\bar{\Upsilon}}}{\Theta_3 + \bar{\Omega}} & 0 & 0 & -\frac{\Gamma_3 + \delta_3 e^{-\bar{\Upsilon}}}{(\Theta_3 + \bar{\Omega})^2} & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 \end{pmatrix}, \quad (3.31)$$

and

$$\widehat{B}_n = \begin{pmatrix} \xi 4_n & 0 & 0 & \xi 5_{n-1} & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & \xi 5_n & 0 & 0 & \xi 6_{n-1} \\ 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & \xi 4_{n-1} & 0 & 0 & \xi 6_n & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 \end{pmatrix}, \quad (3.32)$$

and $\|\widehat{B}_n\| \rightarrow 0$ as $n \rightarrow \infty$. Moreover, the limiting system of error terms turns into

$$\begin{pmatrix} \Phi_{n+1}^4 \\ \Phi_n^4 \\ \Phi_{n+1}^5 \\ \Phi_n^5 \\ \Phi_{n+1}^6 \\ \Phi_n^6 \end{pmatrix} = \begin{pmatrix} -\frac{\Gamma_1 + \delta_1 e^{-\bar{\Psi}}}{(\Theta_1 + \bar{\Upsilon})^2} & 0 & 0 & -\frac{\delta_1 e^{-\bar{\Psi}}}{\Theta_1 + \bar{\Upsilon}} & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & -\frac{\Gamma_2 + \delta_2 e^{-\bar{\Omega}}}{(\Theta_2 + \bar{\Psi})^2} & 0 & 0 & -\frac{\delta_2 e^{-\bar{\Omega}}}{\Theta_2 + \bar{\Psi}} \\ 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & -\frac{\delta_3 e^{-\bar{\Upsilon}}}{\Theta_3 + \bar{\Omega}} & 0 & 0 & -\frac{\Gamma_3 + \delta_3 e^{-\bar{\Upsilon}}}{(\Theta_3 + \bar{\Omega})^2} & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 \end{pmatrix} \begin{pmatrix} \Phi_n^4 \\ \Phi_{n-1}^4 \\ \Phi_n^5 \\ \Phi_{n-1}^5 \\ \Phi_n^6 \\ \Phi_{n-1}^6 \end{pmatrix}, \quad (3.33)$$

which is similar to the linearized system (1.8) about the equilibrium $(\bar{\Upsilon}, \bar{\Psi}, \bar{\Omega})$. \square

4. Conclusions

In this paper, the global dynamics of two exponential-type systems of difference equations are investigated. The main results are as follows:

- (i) All positive solutions of systems (1.7) and (1.8) have been shown to persist and to be bounded.
- (ii) It has been shown that the equilibrium points of systems (1.7) and (1.8) are locally asymptotically stable or unstable based on the parameters L_1 , L_2 , U_1 and U_2 .
- (iii) It has been explained, by using both increasing and decreasing functions and a well-known mean-value theorem, that the equilibrium points of systems (1.7) and (1.8) are globally asymptotically stable when the conditions given by Eqs (2.19) and (3.13) are valid.
- (iv) Information has been given regarding the rates of convergence of systems (1.7) and (1.8).

Use of AI tools declarations

The author declares that she has not used artificial intelligence (AI) tools in the creation of this article.

Conflict of interest

The author declares no conflict of interest that may influence the publication of this paper.

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